# RNP APCH procedures for OMAD Airport RWY 31

	NAME	POSITION	DATE	SIGNATURE
Designer		Flight Procedure Designer/Airspace Design		

# **Change Log**

Version	Date	Description	Ref. Paragraphs	Notes

#### **Summary**

#### Contents

1 Acronyms and Definitions	5
2 Input Data	7
3 Design Critera and Assumptions	8
4 Aeronautical Data	9
5 WAYPOINTS	9
6 P/R/D Zones	10
7 NOTAM	10
8 Procedure Overview	10
9 Design Report	11
9.1 Initial Transition TYRIO	11
9.1.1 Initial approach segment TYRIO to THEON	11
9.1.2 Intermediate approach segment THEON to KHALL	12
9.2 Initial Transition MIPIP	13
9.2.1 Initial approach segment MIPIP to THEON	13
9.2.2 Intermediate approach segment THEON to KHALL	13
9.3 Initial Transition ALB	14
9.3.1 Initial approach segment ALB to AD301	14
9.3.2 Initial approach segment AD301 to TYRIO	14
9.3.3 Initial approach segment TYRIO to THEON	15
9.3.4 Intermediate approach segment THEON to KHALL	15
9.4 LNAV_Minima	16
9.4.1 LNAV Final Segment	16
9.4.2 LNAV Missed Approach Segment	17
9.5 APV Baro Minima	18
9.5.1 APV Segment	18
9.5.2 VNAV Missed Approach Segment	19
9.6 SBAS Minima	19
9.6.1 Precision Segment	20
9.6.2 SBAS Missed Approach Segment	20
9.7 Missed Approach Holding	20
9.7.1 Holding on BORIM	20
9.8 Missed Approach Description	20
9.9 VSS	21
9.10 CIRCLING	22
10 Minima Table	23
11 Coding Table	24

# 1 Acronyms and Definitions

Acronym	Definition		
AIP	Aeronautical Information Publication		
ARP	Aerodrome Reference Point		
ATS	Air Traffic Services		
ATT	Along Track Tolerance		
Baro-VNAV	Barometric vertical navigation		
CTA	Con trol Area		
DA	Decision Altitude		
DB	Data Base		
DH	Decision Height		
ENR	Enroute		
FAF/P	Final Approach Fix/Point		
FPDAM	Flight Procedure Design and Airspace Manager		
FTA	Fix Tolerance Area		
HG	Height Gain		
Heq	Equivalent Height		
IAF	Initial Approach Fix		
IAS	Indicated Air Speed		
ICAO	International Civil Aviation Organization		
IF	Intermediate Fix		
ILS	Instrument Landing System		
KK'	Earliest TP tolerance. It is a main reference to evaluate a missed approach obstacle in the turn area, when a turn at a given fix is defined.		
Kt	Kno ts		
LDA	Localizer type Directional Aid		
	Lateral Navigation: The minima line on the chart for RNP Approaches without		
LNAV	vertical guidance		
	The minima line based on Baro-VNAV system performances that can be used by		
LNAV/VNAV	aircraft approved according to AMC 20-27 or equivalent. LNAV/VNAV minima can		
	also be used by SBAS capable aircraft		
	Localizer Performance with Vertical Guidance: the minima-line based on SBAS		
LPV	performances that can be used by aircraft approved according to AMC 20-28 or		
	equivalent		
MA	Missed Approach		
MAPt	Missed Approach Poin t		
MAF	Missed Approach Fix		
MAHF	Missed Approach Holding Fix		
MEA	Minimum En-Route Altitude		
MHA	Minimum Holding Altitude		
MOC	Minimum Obstacle Clearance		
MSD	Minimum Stabilization Distance		
NA NA	Nominal Altitude		
NM	Nautical Miles		
OAS	Obstacle Assessment Surface		
OCA/H	Obstacle Clearance Altitude/ Height		

PBN	Performance- Based Navigation. The PBN concept specifies Navigation Specifications in terms of navigation system performance accuracy, integrity and continuity along with the functionality required onboard an aircraft for the proposed operations
PT	Path & Terminator
RA	Required Altitude
RDH	Reference Datum Height (for APV or Precision Approaches)
RNAV	A rea Navigation
RNP	Required Navigation Performance
RWY	Run wa y
SBAS	Space Based Augmentation System
SDF	Step Down Fix
SOC	Start Of Climb
THR	Threshold
TMA	Terminal Control Area
WPT	Way poin t
XML	E xtensible Markup Language

# 2 Input Data

Software used for the design (Name and version)	
References for design criteria applied (ICAO Documentation)	
References for data criteria applied (ICAO Documentation)	
Data sources (Aeronautical Information Publications)	
Reference coordinate system (Datum)	
Unit of measure (Distance/High/Angle)	
Terrain data sources	
Obstacle data sources	

# 3 Design Critera and Assumptions

This chapter reports assumptions and criteria followed in the design of the instrument flight procedures described in this document.

- 1) The flight procedures segments were designed in true degrees and converted in magnetic values by applying  $X.XX^{\circ}$  magnetic variation.
- 2) The study described in this report includes the construction of all the procedures elements involved in the STAR design and their respective protection areas.
- 3) Determination of Minimum Stabilization Distances and Minimum segment length have been assessed according to the provisions of ICAO Doc 8168, Part III, sec. 2, ch. 1, par. 1.4 (Minimum Stabilization Distance) and 1.5 (Determination of the minimum length of a RNAV segment limited by at least one waypoint which is not a turning point).
- 4) Vegetation applied: XXXFT
- 5) ....

# 4 Aeronautical Data

Aeronautical data reported in this section, considered as significant input to the procedures design activity, were provided by the XXX Authorities.

were provided by the 12221 runorities.			
Airport Information			
Airport Name ABU DHABI / AL BATEEN EXECUTIVE AIRPORT			
ICAO Identifier	OMAD		
A/D Elevation	16.00 FT		
ARP Latitude	242542.0000N		
ARP Longitude	0542729.0002E		
Magnetic Variation (year)	2.0° E (2017)		
Aircraft Categories	A/B/D/C		

Threshold Information				
Threshold Coordinates Elevation (FT)				
13	N 24 26 03.40	12.00		
15	E054 26 59.60	13.00		
21	N 24 25 18.90	12.00		
31	E054 28 01.80	13.00		

Approach and Runway Lighting Information (PAPI)		
MEHT	ANGLE	

# **5 WAYPOINTS**

In the table below, the waypoints used in the procedure design, both existing and new, are listed with their role, identification and coordinates.

ROLE	IDENT	Coordinates
LTP/FTP	AD005	N 24 25 18.90 E 054 28 01.80
OTHER	AD301	N 24 23 57.21 E 054 38 09.30
IAF	ALB	N 24 26 19.30 E 054 26 46.70
OTHER	BORIM	N 24 36 34.00 E 054 11 53.00
FAF	KHALL	N 24 19 58.29 E 054 35 29.29
IAF	MIPIP	N 24 14 15.00 E 054 43 28.00
MAPT	RWY31	N 24 25 18.90 E 054 28 01.80
IF	THEON	N 24 16 53.53 E 054 39 48.53
IAF	TYRIO	N 24 20 33.36 E 054 42 55.25
OTHER	TYRIO	N 24 20 33.36 E 054 42 55.25

# 6 P/R/D Zones

In the table below the P/R/D Zones (if present) taken into account in the project.

P/R/D Zone				
ID VERTICAL LIMITS REMARKS				

# 7 NOTAM

NOTAMs				
NOTAM ID	INTEGRATED		REMARKS	
			<report "n="" any="" if="" into<="" isn't="" notam="" notam"="" p="" take="" there="" to=""></report>	
			account>	

# **8 Procedure Overview**

H31

# 9 Design Report

# 9.1 Initial Transition TYRIO

#### 9.1.1 Initial approach segment TYRIO to THEON

	Segment Data								
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)				
TYRIO	THEON	A4000+	4.6	0.00	217.91				
		Turn Par	ameters						
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)				
NO	-	90.00	185.00	25.	00				
	CONTROLLING OBSTACLE								
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)				
TOP OF ETC TOWER	N 24 21 15.58 E054 42 44.32	469	984	1,453	A4000+				
Remarks									
Picture									

# 9.1.2 Intermediate approach segment THEON to KHALL

		Segmen	nt Data					
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)			
THEON	KHALL	A4000+	5	3.29	307.89			
		Turn Par	rameters					
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)			
NO	RIGHT	0.20	185.00	25.	.00			
	CONTROLLING OBSTACLE							
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)			
#DTM	N 24 16 35.64 E054 41 12.73	184	492	676	@A3000			
Remarks								
Picture								

# 9.2 Initial Transition MIPIP

#### 9.2.1 Initial approach segment MIPIP to THEON

	Segment Data									
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)					
MIPIP	THEON	A3000+	4.3	0.00	308.25					
		Turn Par	rameters							
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)					
NO	-	0.33	250.00	25.	.00					
	CONTROLLING OBSTACLE									
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)					
#DTM	N 24 13 46.75 E054 43 21.00	322	984	1,306	A3000+					
Remarks										
Picture										

#### 9.2.2 Intermediate approach segment THEON to KHALL

	Segment Data									
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)					
THEON	KHALL	A3000+	5	0.00	307.89					
		Turn Par	rameters							
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)					
NO	-	0.20	185.00	25.	.00.					
		CONTROLLIN	G OBSTACLE							
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)					
#DTM	N 24 16 11.27 E054 39 04.87	171	492	663	@A3000					
Remarks										
Picture	Picture									

# 9.3 Initial Transition ALB

#### 9.3.1 Initial approach segment ALB to AD301

	Segment Data									
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)					
ALB	AD301	A4000+	10.6	0.00	102.77					
		Turn Par	rameters							
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)					
NO	-	25.03	250.00	25.	.00					
	CONTROLLING OBSTACLE									
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)					
BUILDING	N 24 25 18.20 E054 26 05.50	545	984	1,529	A4000+					
Remarks										
Picture										

#### 9.3.2 Initial approach segment AD301 to TYRIO

	Segment Data									
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)					
AD301	TYRIO	A4000+	5.5	0.00	127.87					
		Turn Par	rameters							
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)					
NO	-	90.00	185.00	25.	00					
		CONTROLLIN	G OBSTACLE							
OBST.	Coordinates	Coordinates Elev. (FT)		Calculated Altitude (FT)	WP Altitude (FT)					
TOP OF ETC TOWER	N 24 21 15.58 E054 42 44.32	469	984	1,453	A4000+					
Remarks										
Picture	C - OMAD				D 14					

#### 9.3.3 Initial approach segment TYRIO to THEON

Segment Data									
START POINT	END POINT	Initial Altitude (FT)							
TYRIO	THEON	A4000+	4.6	0.00	217.91				
		Turn Par	rameters						
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)				
NO	RIGHT	90.00	185.00	25.	.00				
	CONTROLLING OBSTACLE								
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)				
TOP OF ETC TOWER	N 24 21 15.58 E054 42 44.32	469	984	1,453	A4000+				
Remarks									
Picture									

# 9.3.4 Intermediate approach segment THEON to KHALL

Segment Data								
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	Course T (°)			
THEON	KHALL	A4000+	5	3.29	307.89			
		Turn Par	rameters					
Fly Over	<b>Turn Direction</b>	Turn Angle (°)	IAS (KT)	Bank A	ngle (°)			
NO	RIGHT	0.20	185.00	25.	00			
	CONTROLLING OBSTACLE							
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)			
#DTM	N 24 16 35.64 E054 41 12.73	184	492	676	@A3000			
Remarks								
Picture								

# 9.4 LNAV\_Minima

#### 9.4.1 LNAV Final Segment

#### 9.4.1.1 KHALL to AD005

	Segment Data										
START POINT	END POINT	Initial Altitude (FT)	Length (NM)	Descent Gradient (%)	TCH (FT)	Course T (°)					
KHALL	AD005	@A3000	8.6	5.59 50.00		308.06					
		CONTROL	LING OBSTA	CLE							
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Required Altitude (FT)		OCA (FT)					
BUILDING	N 24 24 51.90 E054 27 48.00	438	242	680		690.00					
Remarks											
Picture											

# 9.4.2 LNAV Missed Approach Segment

#### 9.4.2.1 AD005 to BORIM

		Segment 2	Data			
Initial Alt. (FT)	END POINT			Length (NM)	Climb Gradient (%)	Course T
A690+	BORIM	A33	10+	-	2.50	-
·		SOC Defin	nition			
ites		•	Tim	e (s)	IAS (KT)	Altitude (FT)
5.68 6.41	1.:	1.26			185.00	690
	CONT	TROLLING	OBSTACLI	E		
Coord	inates	Elev. (FT)	MOC (FT)	Altit	tude	OCA M.A. (FT)
		439.00	245	684		690.00
	(FT) A690+  tes 5.68 5.41  Coord	(FT) POINT  A690+ BORIM  tes Distance MAPt  5.68 5.41	Initial Alt.	(FT)         POINT         (FT)           A690+         BORIM         A3310+           SOC Definition           tes         Distance From MAPt (NM)         Tim           5.68         1.26           CONTROLLING OBSTACLI           Coordinates         Elev. (FT)         MOC (FT)           N 24 24 52.12         439 00         245	Initial Alt. (FT)	Initial Alt. (FT)

# 9.5 APV Baro Minima

#### 9.5.1 APV Segment

	Final Segment APV										
START POIN	T E	END P	OINT		Altitude (FT)	Length (	NM)		scent ient (%	Cours	se (°)
KHALL		AD(	005	@ /	@A3000 8.6		5.59		5.59	308.06	
ТСН		Pron	nulgated (°)	VPA	Tm	nin T correct		rection	(FT)	Min VPA	<b>\</b> (°)
50			3.2		C	)		156.86		3.03	
FAS angle (	(°)	X	K FAS (n	n)	Tm	ıax	Xz	CAT A	/B	Xz CAT	C/D
3.02			1513.45	i	-			-900m		-1100m/-1	400m
				N	Iissed App						
END PO	INT		END PO	OINT A	LT. (FT)		Climb lient (9	<b>%</b> )		Course (°)	ı
BORI	M			A3352	+		2.5			-	
					Min				,		
			(Only i	f turn i	is defined a	t Altitude	or On			NI	1 TNI A
OBST.	(	Coordi	inates	Ele	v. (FT)	MOC (	FT)		Required Nominal TNA (FT) (FT)		
-		-			-	-			-		,
		COI	NTROL	LING	OBSTACL	E (FAS+G	ROUN	ND PLA	NE)		
CAT		OBST	Γ.	Coo	oordinates Elev.		(FT)	HI	(FT)	OCA VNA	V (FT)
A	В	TOP ( UILDI CORN	ING	N 24 24 52.12 E054 27 45.85		43	39		132	572	
В	В	TOP ( UILDI CORN	ING		N 24 24 52.12 E054 27 45.85		439		145	585	
С	В	TOP ( UILDI CORN	OF ING		24 52.12 27 45.85	439			153	593	
D	В	TOP ( UILDI CORN:	ING		24 52.12 27 45.85	43	39		163	603	
	ı		CON	TROL	LING OB	STACLE (		- i			
CAT		OBS'	T.	Coo	rdinates	Elev. (FT	$\mathbf{Z}$		L (FT)	OCA VNA	V (FT)
A	Е	BUILD	ING	N 24 24 55.20 E054 26 54.60		446	25		133	397	
В	Е	UILD	ING		24 55.20 26 54.60	446	25	51	145	410	
С	Е	BUILD	ING	N 24	25 07.90	556	24	17	154	414	

CONTROLLING OBSTACLE (Z Surtface)									
CAT	OBST.	Coordinates	Elev. (FT)	<b>Z.eq</b> ( <b>FT</b> )	HL (FT)	OCA VNAV (FT)			
D	BUILDING	N 24 25 07.90 E054 26 04.10	556	264	164	441			
Remarks									
Picture									

# 9.5.2 VNAV Missed Approach Segment

#### 9.5.2.1 AD005 to BORIM

Segment Data										
START POINT	END POINT	Initial Altitude Length (FT) (NM)		Descent Gradient (%)	Course T (°)					
AD005	BORIM	A63+	-	2.50	-					
		Turn Par	ameters							
Fly Over	Fly Over   Turn Direction   Turn Angle (°)   IAS (KT)   Bank Angle (°)									
NO	-	0.00	265.00	15.	00					
CONTROLLING OBSTACLE										
OBST.	Coordinates	Elev. (FT)	MOC (FT)	Calculated Altitude (FT)	WP Altitude (FT)					
BUILDING	N 24 25 07.90 E054 26 04.10	556	32	441	A3352+					
Remarks										
Picture										

# 9.6 SBAS Minima

#### 9.6.1 Precision Segment

#### 9.6.2 SBAS Missed Approach Segment

# 9.7 Missed Approach Holding

# 9.7.1 Holding on BORIM

Segment Data								
<b>Holding Point</b>	MHA (FT)	Inbound/Outbo und Track (°)	IAS (KT)	` ′	niting Distance M)			
BORIM	A3000+	127/307	210.00	60				
<b>Turn Direction</b>	<b>Entry Sector</b>	RNAV Spo	ecification	Ту	<b>pe</b>			
RIGHT	ALL	RNA	AV 1	WITHOUT_HO	LDING_FUNCTI			
CONTROLLING OBSTACLE								
OBST.	Coordinates	Elev. (FT) MOC (FT)		Required Minima (FT)	Minimum Holding Altitude (FT)			
TOP OF BUILDING	N 24 28 50.64 E054 19 18.64	617	197	814	3,000			
Remarks								
Picture								

# 9.8 Missed Approach Description

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# 9.9 VSS

Segment Data									
RWY CODE	OCH LNAV (FT)	VSS Slope (°)	VSS Length (m)						
31	607	2.08	5094.1						
CONTROLLING OBSTACLE									
OBST.	Coordinates	Elev. (FT)	Penetration (FT)						
MOSQUE MINARET	N 24 24 46.80 E054 28 28.50	384	235						
Remarks									
Pictures									

# 9.10 CIRCLING

				Segment Da	ta				
	CAT		Radius (NM	<b>1</b> )	Limi	itation			
	A		1.7			-			
	В			2.69			-		
	C			4.27			-		
	D			5.36			-		
			CONTR	OLLING O	BSTACLI				
CAT	OBST. Coord		linates	Elev. (FT)	MOC (FT)	Required Minima (FT)	Nominal Altitude (FT)		
A	MOSQUE MINARET	N 24 24 43.10 E054 28 33.70		384	295	679	700		
В	MOSQUE MINARET		4 43.10 8 33.70	384	295	679	700		
С	TOP OF BUILDING ATC TOWER		9 36.55 4 30.38	812	394	1206	1300		
D			9 46.07 4 30.37	992	394	1386	1400		
Remarks									
Pictures									

# 10 Minima Table

OCA(H)	A	В	С	D						
LNAV		690 (674)								
LNAV/VNAV	590 (577)	600 (587)	610 (597)	620 (607)						

# 11 Coding Table

Serial Number	Path Terminator	Waypoint Identifier	Fly Over	Course °M (°T)	Distance (NM)	Turn Direction	Altitude (ft)	Speed Limit (kt)	Recommended Navaid	VPA/ TCH	Navigation Specification
010	IF	TYRIO	N	-	-	-	A4000+	185-	-	-	RNP APCH
020	TF	THEON	N	216 (217.9)	4.6	-	A4000+	185-	-	-	RNP APCH
030	TF	KHALL	N	306 (307.9)	5	R	@A3000	185-	-	-	RNP APCH
010	IF	MIPIP	N	-	-	-	A3000+	-	-	-	RNP APCH
020	TF	THEON	N	306 (308.2)	4.3	-	A3000+	-	-	-	RNP APCH
030	TF	KHALL	N	306 (307.9)	5	-	@A3000	-	-	-	RNP APCH
010	IF	ALB	N	-	-	-	A4000+	-	-	-	RNP APCH
020	TF	AD301	N	101 (102.8)	10.6	-	A4000+	-	-	-	RNP APCH
030	TF	TYRIO	N	126 (127.9)	5.5	-	A4000+	185-	-	-	RNP APCH
040	TF	THEON	N	216 (217.9)	4.6	R	A4000+	185-	-	-	RNP APCH
050	TF	KHALL	N	306 (307.9)	5	R	@A3000	185-	-	1	RNP APCH
010	IF	KHALL	N	-	-	-	@A3000	-	-	1	RNP APCH
020	TF	AD005	Y	306 (308.1)	8.6	-	-	-	-	-3.2/ 50	RNP APCH
010	IF	RWY31	Y	-	-	-	A690+	-	-	-	RNP APCH
020	DF	BORIM	Y	-	-	-	A3310+	-	-	-	RNP APCH
030	НМ	BORIM	Y	125 (127.0)	-	R	A3000+	210-	-	-	RNAV 1

# 12 Version Amendments

In this section all the changes, relative to the IFP design due to validation results, are reported