CS 5683: Algorithms & Methods for Big Data Analytics

Dimensionality Reduction Singular Value Decomposition

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Topics Overview

High. Dim. Data

Data Features

Dimension ality Reduction

Application
Rec.
Systems

Text Data

Clustering

Non-linear Dim. Reduction

<u>Application</u> IR **Graph Data**

PageRank

ML for Graphs

Community Detection

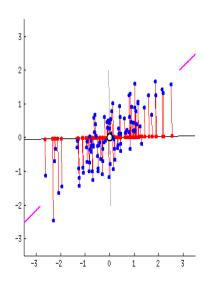
Others

Data Streams Mining

Intro. to Apache Spark

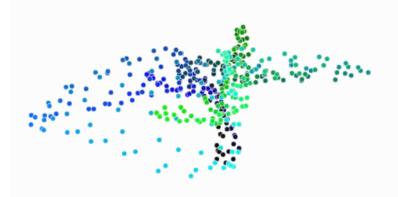
Dimensionality Reduction So Far... (1)

- Principal Component Analysis (PCA)
- Eigen Decomposition problem
 - Standardize the input data matrix
 - Extract Correlation or Covariance matrix
 - Extract Eigen values and Eigen vectors
 - Projection with top 'k' Eigen vectors
 - De-standardize and Reconstruction
 - Manually optimize with Reconstruction loss
- Linear problem



Dimensionality Reduction So Far... (2)

- T-distributed Stochastic Neighbor Embedding (tSNE)
- Non-linear method for visualization
- 2 types of input data projections
 - Projection-1 (P): with N dims. and Gaussian
 - Projection-2 (Q): with n dims. and t-distribution
 - Optimize Q to be as close as P with KL Divergence
 - Optimization with Gradient Descent
- Extremely slow algorithm
- No reconstruction



Rank of a Matrix

- Q: What is rank of a matrix A?
- A: Number of linearly independent rows of A

For example:

• Matrix
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix}$$
 has rank $\mathbf{r} = \mathbf{2}$

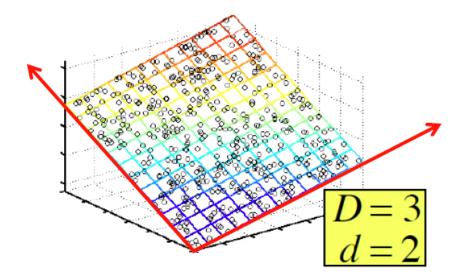
Why? The last two rows are linearly independent and the first row is addition of last two rows. So, the rank is 2

Rank is Dimensionality

Cloud of points 3D space:

■ Think of point positions as a matrix:

1 row per point:
$$\begin{bmatrix} 1 & 2 & 1 \\ -2 & -3 & 1 \\ 3 & 5 & 0 \end{bmatrix}$$
 A B C



We can rewrite coordinates more efficiently!

- Old basis vectors: [1 0 0] [0 1 0] [0 0 1]
- New basis vectors: [-2 -3 1] [3 5 0]
- Then **A** has new coordinates: [1 1]. **B**: [1 0], **C**: [0 1]
 - Notice: We reduced the number of coordinates!

Singular Value Decomposition

$$\mathbf{A}_{[m \times n]} = \mathbf{U}_{[m \times r]} \mathbf{\Sigma}_{[r \times r]} (\mathbf{V}_{[n \times r]})^{\mathsf{T}}$$

■ A: Input data matrix

■ *m* x *n* matrix (e.g., *m* documents, *n* terms)

U: Left singular vectors

■ *m* x *r* matrix (*m* documents, *r* concepts)

• Σ : Singular values

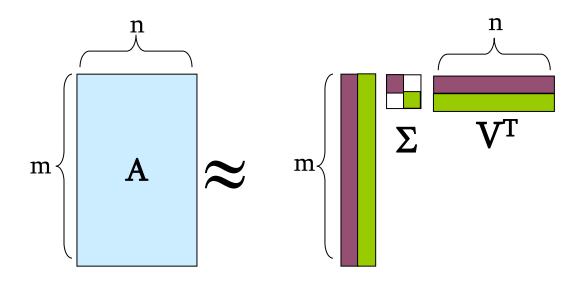
r x r diagonal matrix (strength of each 'concept')(r : rank of the matrix A)

V: Right singular vectors

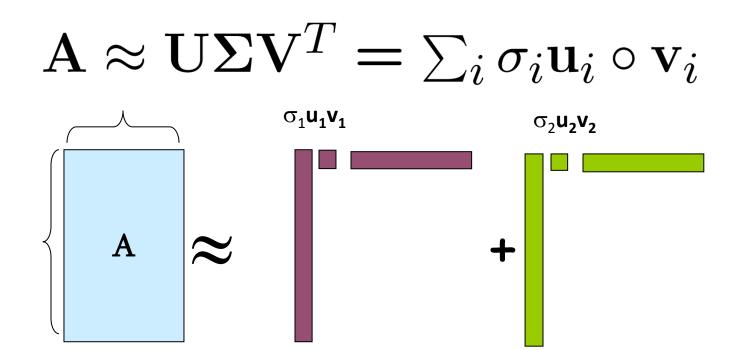
n x r matrix (n terms, r concepts)

SVD

$$\mathbf{A} \approx \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T = \sum_i \sigma_i \mathbf{u}_i \circ \mathbf{v}_i$$



SVD



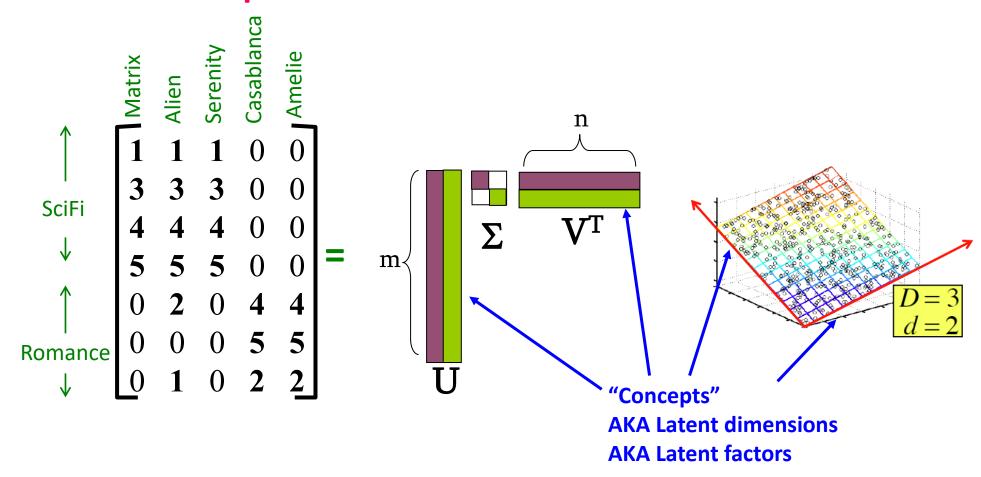
 σ_i ... scalar u_i ... vector v_i ... vector

SVD - Properties

It is **always** possible to decompose a real matrix ${\bf A}$ into ${\bf A}={\bf U}\; {\bf \Sigma}\; {\bf V}^{\rm T}$, where

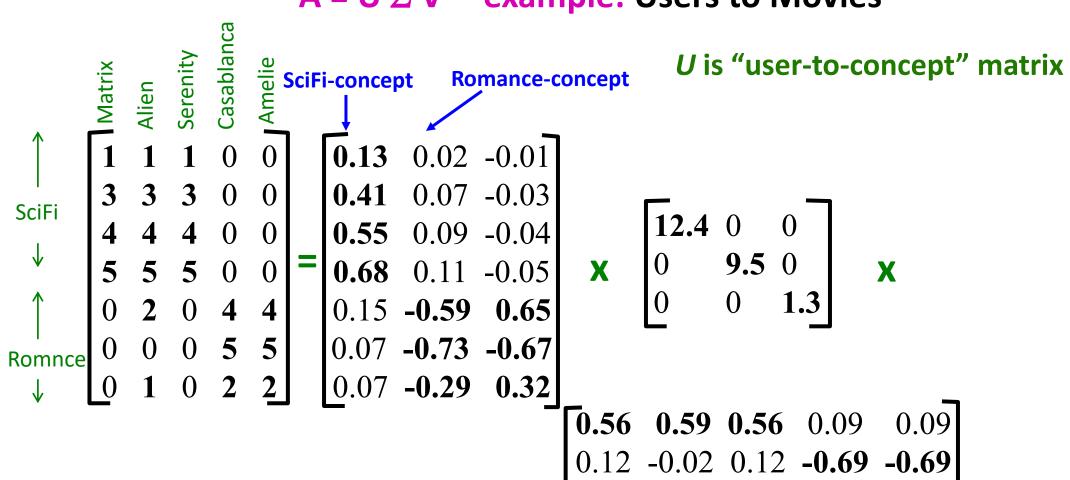
- **U**, Σ, *V*: unique
- *U*, *V*: column orthonormal
 - $U^T U = I$; $V^T V = I$ (I: identity matrix)
 - (Columns are orthogonal unit vectors)
- ullet Σ : diagonal
 - Entries (singular values) are positive, and sorted in decreasing order ($\sigma_1 \ge \sigma_2$ $\ge ... \ge 0$)

■ A = U Σ V^T - example: Users to Movies



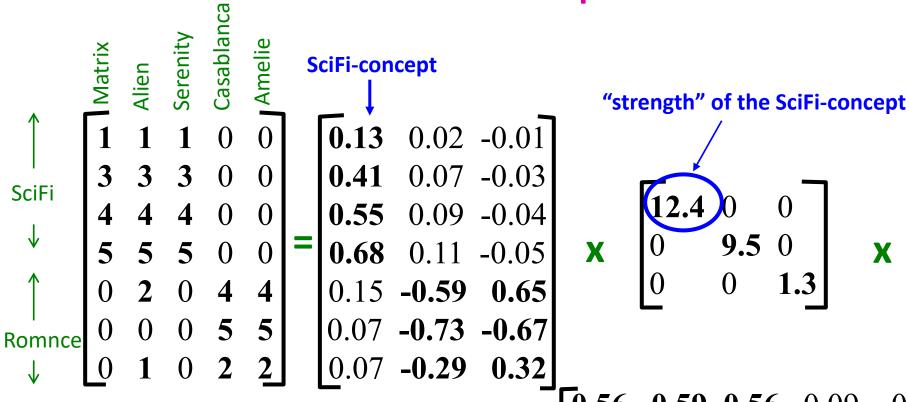
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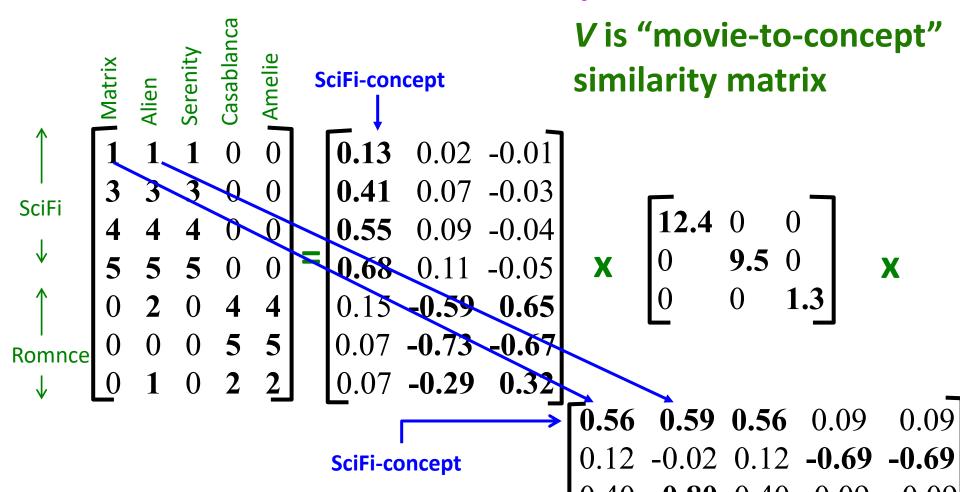


0.40 **-0.80** 0.40 0.09

■ A = U Σ V^T - example: Users to Movies



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SVD – Interpretation #1

'movies', 'users' and 'concepts':

- *U*: user-to-concept similarity matrix
- *V*: movie-to-concept similarity matrix
- \blacksquare Σ : its diagonal elements: 'strength' of each concept

Solving SVD

$$M = U\Sigma V^{T}$$

$$M^{T} = (U\Sigma V^{T})^{T} = (V^{T})^{T}\Sigma^{T}U^{T} = V\Sigma^{T}U^{T}$$

Transposing a diagonal matrix Σ will not have any effect \rightarrow $M^T = V\Sigma II^T$

$$\mathbf{M}^{\mathrm{T}}M = V\Sigma \ U^{\mathrm{T}}U\Sigma \ V^{\mathrm{T}} = \mathbf{V}\boldsymbol{\Sigma}^{\mathbf{2}}\mathbf{V}^{\mathbf{T}}$$

(since *U* is column orthonormal!)

$$M^{T}MV = V\Sigma^{2}V^{T}V = V\Sigma^{2}$$

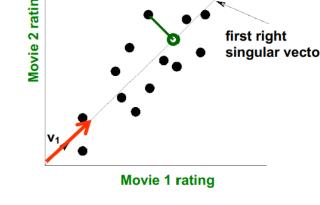
(looks very similar to $Mx = \lambda x!$)

Thus, V is an eigen vector of the correlation matrix M^TM Similarly, U is an eigen vector of the correlation matrix MM^T Σ^2 are eigen values $\Rightarrow \Sigma^2(MM^T) = \Sigma^2(M^TM)$

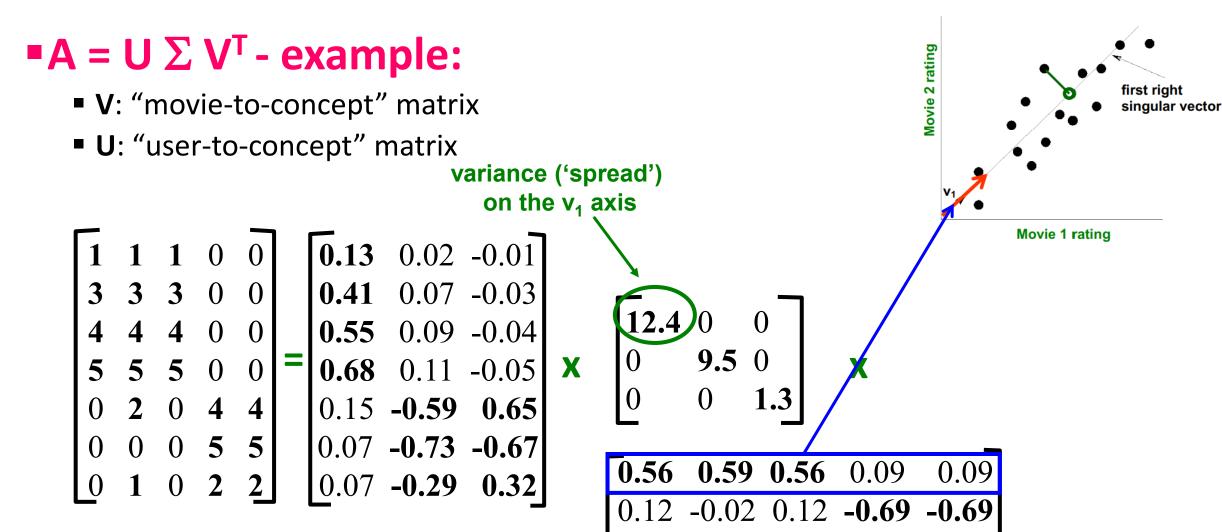
Goal: Minimize the sum of reconstruction errors:

$$\sum_{i=1}^{N} \sum_{j=1}^{D} ||x_{ij} - z_{ij}||^{2}$$

• where x_{ij} are the "old" and z_{ij} are the "new" coordinates



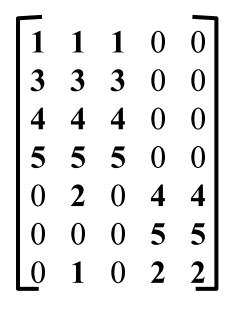
- SVD gives 'best' axis to project on:
 - 'best' = minimizing the reconstruction errors
- In other words, minimum reconstruction error

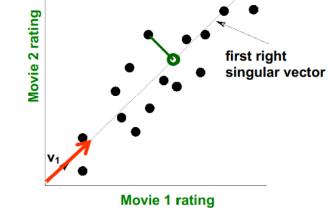


-0.80 0.40

\blacksquare A = U Σ V^T - example:

• U Σ: Gives the coordinates of the points in the projection axis





Projection of users on the "Sci-Fi" axis $(U \Sigma)^T$:

	_	_
1.61	0.19	-0.01
5.08	0.66	-0.03
6.82	0.85	-0.05
8.43	1.04	-0.06
1.86	-5.60	0.84
0.86	-6.93	-0.87
0.86	-2.75	0.41

More details

- Q: How exactly is dim. Reduction done?
- A: Set smaller singular values to zero

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 0.13 & 0.02 & -0.01 \\ 0.41 & 0.07 & -0.03 \\ 0.55 & 0.09 & -0.04 \\ 0.68 & 0.11 & -0.05 \\ 0.15 & -0.59 & 0.65 \\ 0.07 & -0.73 & -0.67 \\ 0.07 & -0.29 & 0.32 \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{12.4} & 0 & 0 \\ 0 & \mathbf{9.5} & 0 \\ 0 & 0 & \mathbf{3} \end{bmatrix} \mathbf{x}$$

$$\begin{bmatrix} \mathbf{0.56} & \mathbf{0.59} & \mathbf{0.56} & 0.09 & 0.09 \\ 0.12 & -0.02 & 0.12 & -\mathbf{0.69} & -\mathbf{0.69} \\ 0.40 & -\mathbf{0.80} & 0.40 & 0.09 & 0.09 \end{bmatrix}$$

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1	_	1	1	0	0		$\boxed{0.13}$	0.02	-(1)	.01						
3	3	3	3	0	0		0.41	0.07	-0	.03		_		_		
4	ļ	4	4	0	0		0.55	0.09	-0	.04		12.4				
5	•	5	5	0	0	2	0.68	0.11	-0	.05	X	$\begin{bmatrix} 0 \\ 0 \end{bmatrix}$	9.5		X	
C)	2	0	4	4		0.15	-0.59	0	65		\Box	0	(3)		
C								-0.73				Γn 56	0.50	0.56	0.00	0.00
)	1	0	2	2		0.07	-0.29	Ø	.32		0.30	_0.39	0.30	0.09 -0.69	-0.09
												0.12	-0.02 -0.80	0.12	-0.09 -0.09	-0.09 -0 ()C

More details

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								T _{12.4}	0	\neg		
							V	12.4			V	
							X		7.5		X	
								L				_
								$\boxed{0.56}$	0.59	0.56	0.09	0.09
			-			_	•	0.12	-0.02	0.12	-0.69	-0.69
3 4 5 2 0	3 3 4 4 5 5 2 0 0 0	3 3 0 4 4 0 5 5 0 2 0 4 0 0 5	3 3 0 0 4 4 0 0 5 5 0 0 2 0 4 4 0 0 5 5	3 3 0 0 4 4 0 0 5 5 0 0 2 0 4 4 0 0 5 5	3 3 0 0 0	3 3 0 0 0 4 4 0 0 0 5 5 0 0 0 2 0 4 4 0 0.55 0.09 0.68 0.11 0.15 -0.59 0.07 -0.73	3 3 0 0 0	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

More details

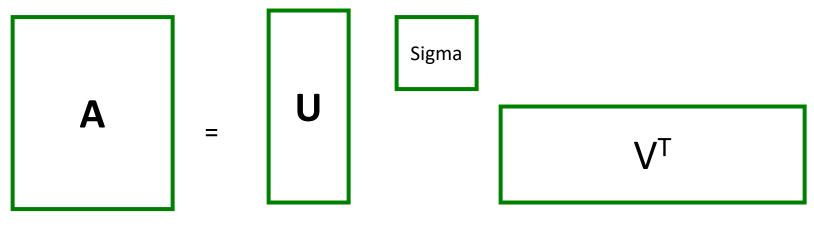
- Q: How exactly is dim. Reduction done?
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$$A \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 \\ 4 & 4 & 4 & 0 & 0 \\ 5 & 5 & 5 & 0 & 0 \\ 0 & 2 & 0 & 4 & 4 \\ 0 & 0 & 0 & 5 & 5 \\ 0 & 1 & 0 & 2 & 2 \end{bmatrix} \approx \begin{bmatrix} 0.92 & 0.95 & 0.92 & 0.01 & 0.01 \\ 2.91 & 3.01 & 2.91 & -0.01 & -0.01 \\ 3.90 & 4.04 & 3.90 & 0.01 & 0.01 \\ 4.82 & 5.00 & 4.82 & 0.03 & 0.03 \\ 0.70 & 0.53 & 0.70 & 4.11 & 4.11 \\ -0.69 & 1.34 & -0.69 & 4.78 & 4.78 \\ 0.32 & 0.23 & 0.32 & 2.01 & 2.01 \end{bmatrix}$$

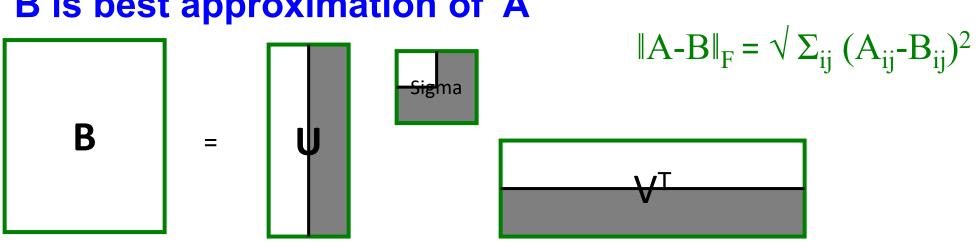
Frobenius norm:

$$\|\mathbf{M}\|_{\mathrm{F}} = \sqrt{\sum_{ij} M_{ij}^2}$$

$$\|\mathbf{A} - \mathbf{B}\|_{F} = \sqrt{\Sigma_{ij} (\mathbf{A}_{ij} - \mathbf{B}_{ij})^{2}}$$
 is "small"



B is best approximation of A



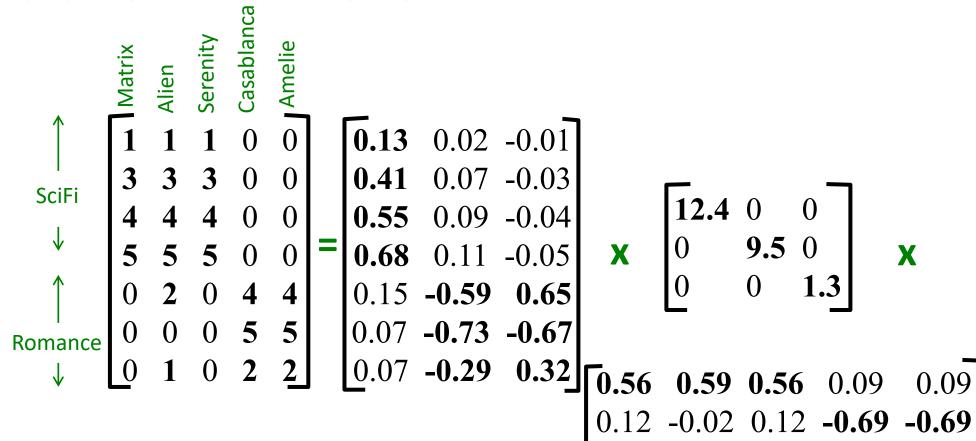
Q: How many σ_s to keep?

A: Rule-of-a thumb:

keep 80-90% of 'concepts'
$$\left(\frac{\sum_{i=1}^k \sigma_i^2}{\sum_{i=1}^r \sigma_i^2} = \mathbf{0.8}\right)$$

- To compute SVD:
 - O(nm²) or O(n²m) (whichever is less)
- But:
 - Less work, if we just want singular values
 - or if we want first k singular vectors
 - or if the matrix is sparse
- Implemented in linear algebra packages like
 - LINPACK, Matlab, SPlus, Mathematica ...

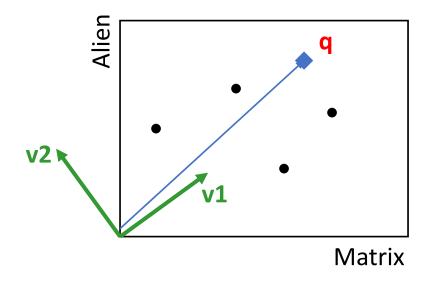
- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?



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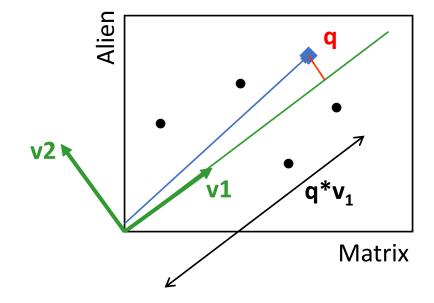
Project into concept space:

Inner product with each 'concept' vector $\mathbf{v_i}$

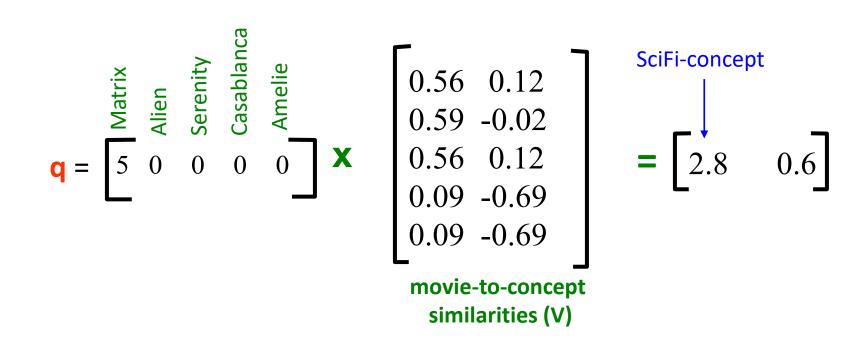


- Q: Find users that like 'Matrix'
- A: Map query into a 'concept space' how?

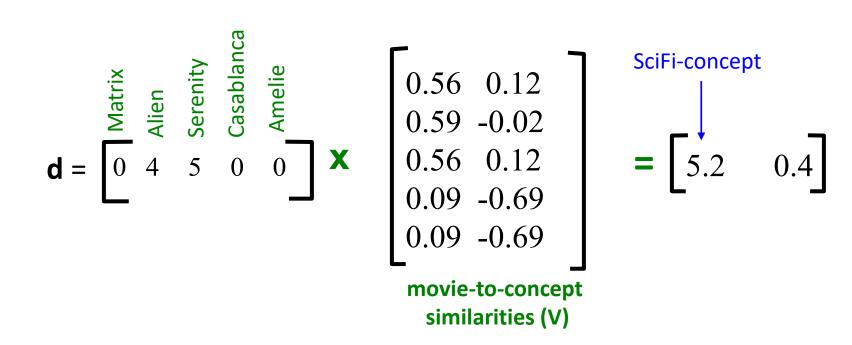
Project into concept space: Inner product with each 'concept' vector v_i



- The query is now mapped to a new compact space
- $q_{concept} = q.V$



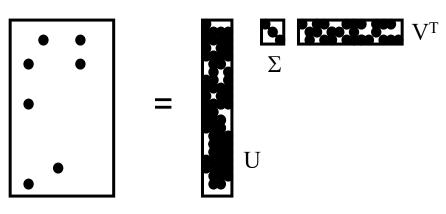
- How would the user d that rated ('Alien','Serenity') be handled?
- $d_{concept} = d.V$



 Observation: User d that rated ('Alien', 'Serenity') will be similar to user q that rated ('Matrix'), although d and q have zero ratings in common!

SVD Drawbacks

- +Optimal low-rank approximation in terms of Frobenius norm
- Interpretability problem:
 - A singular vector specifies a linear combination of all input columns or rows
- Lack of sparsity:
 - Singular vectors are dense!



0.13 0.02 -0.01 0.41 0.07 -0.03 0.55 0.09 -0.04 0.68 0.11 -0.05 0.15 -0.59 0.65 0.07 -0.73 -0.67 0.07 -0.29 0.32

Questions???



Acknowledgements

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Datasets course: http://www.mmds.org/