ACTIVITY-BASED SCHEDULE

Project Name	Copy Waste		
Activity	**Duration**	**Start Date**	**End Date**
Getting setup with Prairie Robotics	14	Sept 17th	Oct 1st
Creating datasets for bin tip detector	14	Oct. 1st	Oct. 15th
Testing new models	14	Oct. 15th	Oct. 29th
Deploying model	14	Oct. 29th	Nov. 12th
Begin tracking real world performance	14	Nov 5th	Nov 19th
Collect various images of hazardous waste	7	Nov 19th	Nov 26th
Begin developing copy-paste pipeline	28	Nov 26th	Dec-Jan
Create test dataset	14	Jan 7th	Jan 21st
Train model	21	Jan 21st	Feb 11th
Evaluate Results	14	Feb 11th	Feb 25th

*Subject to change