Unit 6.1 – Numerical Differentiation

To fully appreciate the usefulness of numerical differentiation, we should start by considering the mathematical definition of a derivative.

$$\frac{df}{dx} = \lim_{\epsilon \to 0} \frac{f(x_0 + \epsilon) - f(x_0)}{\epsilon} \tag{6.1-1}$$

It's easy to show, for example how to do this for a polynomial, say

$$f(x) = ax^{2} + bx + c$$

$$\frac{df}{dx}$$

$$= \lim_{\epsilon \to 0} \frac{a(x+\epsilon)^{2} + b(x+\epsilon) + c - (ax^{2} + bx + c)}{\epsilon}$$

$$= \lim_{\epsilon \to 0} \frac{a(x^2 + 2x\epsilon + \epsilon^2) + b(x + \epsilon) + c}{\epsilon}$$
$$-\frac{(ax^2 + bx + c)}{\epsilon}$$

$$= \lim_{\epsilon \to 0} \frac{2ax\epsilon + \epsilon^2 + b\epsilon}{\epsilon}$$

$$= \lim_{\epsilon \to 0} 2ax + \epsilon + b$$

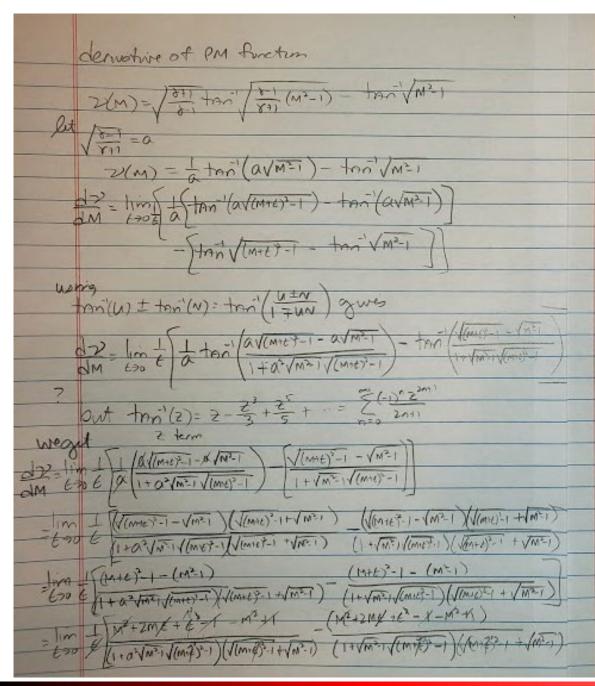
$$\frac{df}{dx} = 2ax + b \tag{6.1-2}$$

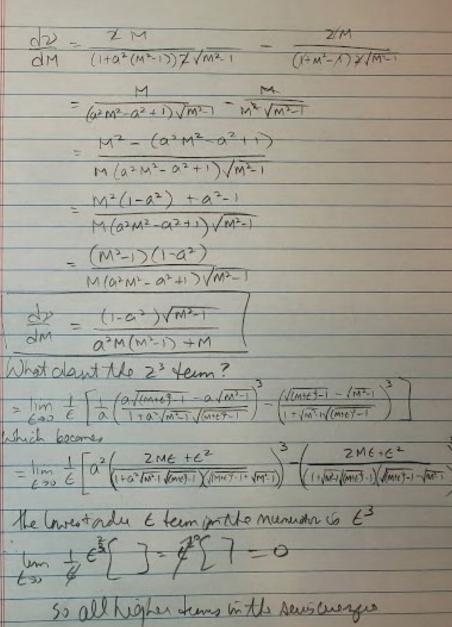
But what about for a more complicated case like the Prandtl-Meyer function from the exam?

$$\nu(M) = \sqrt{\frac{\gamma + 1}{\gamma - 1}} \tan^{-1} \sqrt{\frac{\gamma - 1}{\gamma + 1}} (M^2 - 1) - \tan^{-1} \sqrt{M^2 - 1}$$

Options:

- 1. Do by hand
- 2. Use Wolfram
- 3. Perform a numerical differentiation







Rocket science? Not a problem.







derivative with respect to M ((1/a)*arctan(a*sqrt(M**2-1))-arctan(sqrt(M**2-1)))



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Examples

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Assuming "M" is a variable | Use as a roman numeral instead

Derivative:

 $\frac{\partial}{\partial M} \left(\frac{\tan^{-1} \left(a \sqrt{M^2 - 1} \right)}{a} - \tan^{-1} \left(\sqrt{M^2 - 1} \right) \right) = -\frac{\left(a^2 - 1 \right) \sqrt{M^2 - 1}}{a^2 M \left(M^2 - 1 \right) + M}$

 $tan^{-1}(x)$ is the inverse tangent function

✓ Step-by-step solution



Clearly this one can be done, but at what cost and for how much trouble?

The numerical equivalent is found by doing just a little bit more math. Consider the Taylor series approximations:

We assume the series converges – terms shrink

$$f(x_0 + \Delta x) = f(x_0) + \Delta x \frac{df}{dx}(x_0) + \frac{\Delta x^2}{2} \frac{d^2 f}{dx^2}(x_0) + \frac{\Delta x^3}{6} \frac{d^3 f}{dx^3}(x_0) + \dots + \frac{\Delta x^n}{n!} \frac{d^n f}{dx^n}(x_0) + \dots$$
 (6.1-3)

$$f(x_0 - \Delta x) = f(x_0) - \Delta x \frac{df}{dx}(x_0) + \frac{\Delta x^2}{2} \frac{d^2 f}{dx^2}(x_0) - \frac{\Delta x^3}{6} \frac{d^3 f}{dx^3}(x_0) + (-1)^n \frac{\Delta x^n}{n!} \frac{d^n f}{dx^n}(x_0) + \cdots$$
 (6.1-4)

Subtracting 6.1-4 from 6.1-3 we get:

$$f(x_0 + \Delta x) - f(x_0 - \Delta x) = 2\Delta x \frac{df}{dx} (x_0) + \frac{\Delta x^3}{3} \frac{d^3 f}{dx^3} (x_0) + \cdots$$
 (6.1-5)

Or rearranging, gives the so-called first derivative central difference formula:

$$\frac{df}{dx}(x_0) = \frac{f(x_0 + \Delta x) - f(x_0 - \Delta x)}{2\Delta x} + \frac{\Delta x^2}{6} \frac{d^3 f}{dx^3}(x_0) + \cdots$$
 (6.1-6)

Or said another way:

$$\frac{df}{dx}(x_0) = \frac{f(x_0 + \Delta x) - f(x_0 - \Delta x)}{2\Delta x} + \mathcal{O}(\Delta x^2)$$
(6.1-7)

Similarly, subtracting $f(x_0)$ from 6.1-3 gives the first derivate forward difference formula:

$$\frac{df}{dx}(x_0) = \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} + \mathcal{O}(\Delta x) \tag{6.1-8}$$

The $O(\Delta x)$ and $O(\Delta x^2)$ terms represent the **truncation error** of the approximation. That is, the error incurred by a finite difference the extra terms are truncated off.

Similarly, subtracting 6.1-4 from $f(x_0)$ gives the first derivative backward difference formula:

$$\frac{df}{dx}(x_0) = \frac{f(x_0) - f(x_0 - \Delta x)}{\Delta x} + \mathcal{O}(\Delta x)$$
(6.1-9)

Adding 6.1-3 and 6.1-4 gives

Or rearranging, gives the **second derivative central difference formula**:

$$\frac{d^2f}{dx^2}(x_0) = \frac{f(x_0 + \Delta x) - 2f(x_0) + f(x_0 - \Delta x)}{\Delta x^2} + \mathcal{O}(\Delta x^2)$$
(6.1-10)

These so-called finite differences can be constructed at various orders by taking combinations of equations like 6.1-3 and 6.1-4. A full list of central and one-sided differences is given in the text.

Cautions:

- These formulae work so long as Δx is constant.
- Non-uniform grid formulas can also be constructed by using appropriate series and combining terms.
- One needs to determine the "best" Δx by balancing truncation and roundoff error.