

Local intraspecific aggregation in phytoplankton model communities: spatial scales of occurrence and implications for coexistence

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Abstract

The coexistence of multiple phytoplankton species despite their reliance on similar resources is often explained with mean-field models assuming mixed populations. In reality, observations of phytoplankton indicate spatial aggregation at all scales, including at the scale of a few individuals. Local spatial aggregation can hinder competitive exclusion since individuals then interact mostly with other individuals of their own species, rather than competitors from different species. To evaluate how microscale spatial aggregation could explain phytoplankton diversity maintenance, an individual-based, multispecific representation of cells in a realistic hydrodynamic environment is required. We therefore used as a starting point a mathematically tractable individual-based model of phytoplankton population dynamics in a viscous and turbulent environment, and generalize it here to multiple species and three dimensions. The model is studied through both simulations and the derivation of spatial moment equations, in connection with point process theory. The spatial moment equations show a good match between theory and simulations. We parameterized the model based on phytoplankters' ecological and physical characteristics, for both large and small phytoplankton. Defining a zone of potential interaction as the overlap between nutrient depletion volumes, we show that local species composition—within the range of possible interactions—depends on the size class of phytoplankton. In large phytoplankton, individuals are surrounded by cells from other species, while in small phytoplankton, individuals remain in mostly monospecific clusters. Spatial structure therefore favours intra- over inter-specific interactions for small phytoplankton, which likely contributes to coexistence mechanisms, while other factors behind diversity maintenance must be examined for large phytoplankton.

Keywords: aggregation; coexistence; individual-based model; phytoplankton; spatial moment equations; spatial point process

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Introduction

Phytoplankton communities are among the most important photosynthetic groups on Earth, being at the bottom of the marine food chain, and responsible for approximately half the global primary production (Field *et al.*, 1998). Their contribution to ecosystem functions is only matched by their contribution to biodiversity. Indeed, phytoplankton communities are characterized by a surprisingly high biodiversity, up to seventy species in volumes as small as a few mL (REPHY, 2017; Widdicombe & Harbour, 2021). This observation has led to the formulation of the so-called “paradox of the plankton” (Hutchinson, 1961), which refers to the conflict between the observed diversity of species competing for similar resources in a seemingly homogeneous environment, and theoretical expectations of a few species outcompeting the others. Phytoplankton models for coexistence are now almost as diverse as their model organisms (Record *et al.*, 2014) and some benefit from the support of coexistence theory, which proposes mechanisms to escape from competitive exclusion (Li & Chesson, 2016; Chesson, 2018). However, most of these models consider mean-field dynamics at the microscale. Such assumption needs to be challenged, as field observations themselves have revealed phytoplankton patchiness for more than a century (Bainbridge, 1957; Stocker, 2012), from the macro- to the micro-scale (Leonard *et al.*, 2001; Doubell *et al.*, 2006; Font-Muñoz *et al.*, 2017).

Phytoplankton patchiness can at least be partly explained by the hydrodynamics of their environment: the size of these organisms being mostly below the size of the smallest eddy (i.e., the Kolmogorov scale) in a typical environment such as the ocean, phytoplankton individuals are embedded in viscous micro-structures (Peters & Marrasé, 2000) while phytoplankton populations are being displaced by a turbulent flow at slightly larger scales (Martin, 2003; Prairie *et al.*, 2012). Phytoplankton organisms therefore live in an environment where fluid viscosity dominates at the scale of an individual but effects of turbulence can be seen as soon as one considers the volume required for a small population of those individuals (Estrada *et al.*, 1987; Prairie *et al.*, 2012).

This leads us to consider demography in the context of this environmental variation created by hydrodynamics processes. Individual-based models provide a convenient depiction of population dynamics and movement at the microscale (Hellweger & Bucci, 2009). In this framework, population growth is a result of individual births and deaths. Aggregation of particles can emerge from local reproduction coupled with limited dispersal, which can happen in a fluid where turbulence and diffusion are not too high to disperse kin aggregates (Young *et al.*, 2001). Such aggregation can affect the dynamics of the populations at the community level: even when interactions are identical between individuals of the same species (conspecifics) or between individuals of different species (heterospecifics), the combination of local reproduction and same-scale high dispersal limitation and strong interactions leads to stronger intraspecific interactions than interspecific interactions at the population level, a major stabilizing mechanism (Detto & Muller-Landau, 2016). Basically, a high intra-to-interspecific interaction strength ratio makes a species control its abundance more than it controls the abundance of other species, which is associated with coexistence in theoretical models (Levine & HilleRisLambers, 2009; Barabás *et al.*, 2017) and often observed in the field at the population level (Adler *et al.*, 2018; Picoche & Barraquand, 2020). Therefore, the microscale spatial

distribution of individuals likely affect the interaction structure within a community, and may sustain diversity.

Some models of phytoplankton populations already exist at the microscale, i.e. near the Kolmogorov scale, between 1 mm and 1 cm in an oceanic environment (Barton *et al.*, 2014). Most of these models focus on a single species and the clustering of its individuals (Young *et al.*, 2001; Birch *et al.*, 2007; Bouderbala *et al.*, 2018; Breier *et al.*, 2018). They share a similarity to dynamic point process models (Law *et al.*, 2003; Bolker & Pacala, 1999; Plank & Law, 2015) developed initially with larger organisms in mind. When phytoplankton individual-based models consider multiple types of organisms, they focus for now on how organisms with opposite characteristics (e.g., increase vs decrease in density with turbulence in Borgnino *et al.*, 2019; Arrieta *et al.*, 2020) segregate spatially, or on coexistence for species that have contrasted trait values (e.g., size in Benczik *et al.*, 2006). This is quite useful to understand how species with marked differences coexist. However, the difficulty of the coexistence problem is precisely that we have to explain how closely related species or genera (e.g., within diatoms), many of whom have similar size, buoyancy, chemical composition, etc., manage to coexist within a single trophic level. This requires to model *similar* species in spatially realistic environment and measure whether they aggregate or segregate in space.

To do so, we build a multispecific version of the Brownian Bug Model (BBM) of Young *et al.* (2001), an individual-based model which includes a chaotic advection process mimicking a turbulent fluid flow, passive diffusion of organisms, as well as stochastic birth and death processes. The initial version of this model (Young *et al.*, 2001) coupled limited dispersal and local reproduction with ocean-like microscale hydrodynamics, and showed spatial clusters of individuals of the same species. It was limited to a single species and a two-dimensional environment. Furthermore, the model was not strongly quantitative (Picoche *et al.*, 2022) in the sense that parameters were not informed by current knowledge on phytoplankton biology (numbers of cells per liter, diffusion characteristics, etc.). As phytoplankton organisms live in a three-dimensional environment, informing the model with realistic parameters required us to shift to three dimensions. We also extend the model to multiple species, and consider two size classes for our phytoplankton communities, which are either made of nanophytoplankton (3 μm diameter, $\approx 10^6$ C/L) or microphytoplankton (50 μm , $\approx 10^4$ C/L). We populate each community with 3 to 10 different species.

The Brownian Bug model (in its original single-species form as in the multispecies version considered here) is linked to spatial branching processes. Without advection, it combines a continuous-time, discrete-state model for population growth and a continuous-time, continuous-space Brownian motion for particle diffusion (Birch & Young, 2006). It is further complexified by the presence of a turbulent fluid flow in Young *et al.* (2001); Picoche *et al.* (2022) as well as here. In spite of this complexity, it remains possible to derive the dynamics of pair density functions, which quantify the degree of intra- and interspecific clustering of organisms, via correlations between positions of organisms (see Methods). This means that in addition to simulations, we can keep track analytically of spatial structure. Furthermore, because we do not consider direct interactions between particles, the multispecies spatial point process that represents the stable state of the Brownian Bug model is mathematically a random superposition of spatial point processes for each species (Illian *et al.*, 2008). This enables us to derive, in addition

to pair correlation functions, analytical formulas for the species composition of the neighbourhood of an individual, which are more readily ecologically interpreted than pair density or correlation functions.

Models and spatial statistics

Brownian bug model

The Brownian Bug Model (BBM) describes the dynamics of particles going through demographic processes in a turbulent and viscous environment, in continuous space and time. It has been developed in its two-dimension, monospecific version in Young *et al.* (2001), which we now extend to three dimensions and to S species.

In this model, we consider a community of particles, each individual being characterized by its species i and its position $\mathbf{x}^T = (x, y, z)$. Within a given community, all species are equivalent and share the same parameters. The population dynamics are modeled by a linear birth-death process with birth rate λ and death rate μ . Each particle independently follows a Brownian motion with diffusivity D , and is advected by a common stochastic flow modeling the turbulence with stretching parameter γ , meaning that the separation $s(t)$ between two points previously on top of each other follows $s(t) \propto e^{3\gamma t}$. We focus here on ecologically relevant quantities which can be extracted from this model, both analytically and numerically.

For numerical simulations, this model needs to be discretized. During each time step of duration τ , events unroll as follow:

1. demography: each particle can either reproduce with probability $p = \lambda\tau$ (forming a new particle of the same species i at the same position \mathbf{x}), die with probability $q = \mu\tau$, or remain unchanged with probability $1 - p - q$.
2. diffusion: each particle moves to a new position $\mathbf{x}(t + t') = \mathbf{x}(t) + \delta\mathbf{x}(t)$ where each element of $\delta\mathbf{x}(t)$ follows a Gaussian distribution $\mathcal{N}(0, \Delta)$ with $D = \frac{\Delta^2}{2\tau}$ the diffusivity.
3. turbulence: each particle is displaced by a turbulent flow, following the Pierrehumbert map (Pierrehumbert, 1994), adapted in its three-dimension version (Ngan & Vanneste, 2011). The shift from continuous to discrete time is described in the Supplementary Information.

$$\begin{cases} x(t + \tau) &= x(t + t') + U\tau/3 \cos(ky(t + t') + \phi(t)) \\ y(t + \tau) &= y(t + t') + U\tau/3 \cos(kz(t + t') + \theta(t)) \\ z(t + \tau) &= z(t + t') + U\tau/3 \cos(kx(t + \tau) + \psi(t)) \end{cases}$$

where U is the maximum velocity of the particle, $k = 2\pi/L_s$ is the wavenumber for the flow at the length scale L_s (see below) and $\phi(t)$, $\theta(t)$, $\psi(t)$ are random phases uniformly distributed between 0 and 2π . Particles are distributed in a cube of side L , with periodic boundary conditions.

Characterization of the spatial distribution

Let W be the observation window (in our case, the whole cube, which we never subsample hereafter). The state of the system at time t can be described as a collection of S populations, where the population of species i is made of n_i particles randomly distributed in W , with positions $\mathbf{X}_i(t) = [\mathbf{x}_{1,i}(t), \mathbf{x}_{2,i}(t), \dots, \mathbf{x}_{n_i,i}(t)]$. $\mathbf{X}(t) = [\mathbf{X}_1(t), \dots, \mathbf{X}_S(t)]$ arises from a stochastic and spatial individual-based model changing through time, but can also be analyzed as a spatial point process at time t . We note that the point distributions remain the same for all transitions ξ (i.e., the point process described by the set $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k]$ is the same as $\mathbf{X}_\xi = [\mathbf{x}_1 + \xi, \mathbf{x}_2 + \xi, \dots, \mathbf{x}_k + \xi]$): the process is stationary.

One of the most common methods to describe a spatial point process is through its moment measures (hereafter, moments), that can be theoretically derived and allow us to check our simulations. However, the spatial moments of a process are merely statistical indicators which then need to be related to more easily interpretable quantities. This is the role of the dominance index, which we present below.

Spatial moments

The first-order moment is the intensity of the process, or mean concentration of particles $C_i = \frac{N_i(W)}{V(W)}$ where $N_i(W)$ is the number of particles of species i in the cube W and $V(W) = L^3$ is the volume of the cube; it does not give any information regarding the spatial distribution, and possibly spatial correlation between particles.

The second-order product density, or pair density $G(r, t)$, approximates the second-order moment. Let us first define $P(r, t) = \mathbb{E} \left(\sum_h^n \sum_{l, l \neq h}^n \mathbf{1}(\|\mathbf{x}_h(t) - \mathbf{x}_l(t)\| \leq r) \right) / (k(k-1))$, the distribution function of the distance between two randomly chosen particles, which can be expressed as a function of $G(r, t)$ (Illian *et al.*, 2008, p. 132, eq. 3.5.17-3.5.18).

$$P(r, t) = \int_W \int_W \mathbf{1}(\|\mathbf{x}_h(t) - \mathbf{x}_l(t)\| \leq r) G(r, t) d\mathbf{x}_h d\mathbf{x}_l \quad (1)$$

A similar characteristic can be used for marked spatial point process. In our case, the marks are the species, and we can define $G_{ij}(r, t)$, so that $G_{ij}(r, t) d\mathbf{x}_A d\mathbf{x}_B$ is the probability of finding an individual of species i in volume $d\mathbf{x}_A$ and an individual of species j in volume $d\mathbf{x}_B$, and the distance between the centers of $d\mathbf{x}_A$ and $d\mathbf{x}_B$ is equal to r . We can show that the intraspecific pair density $G_{ii}(r, t)$ is a solution of eq. 2 (see Picoche *et al.*, 2022 for a derivation).

$$\frac{\partial G_{ii}}{\partial t}(r, t) = \frac{2D}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial G_{ii}}{\partial r} \right) + \frac{\gamma}{r^2} \frac{\partial}{\partial r} \left(r^4 \frac{\partial G_{ii}}{\partial r} \right) + 2(\lambda - \mu) G_{ii} + 2\lambda C_i \delta(r) \quad (2)$$

The pair correlation function $g_{ij}(r, t)$, or pcf, which can be thought of as the mean number of points of species j at distance r of a particle of species i can be derived from the pair density (eq. 3).

$$g_{ij}(r, t) = \frac{G_{ij}(r, t)}{C_i C_j} \quad (3)$$

By integration of eq. 2, with $\lambda = \mu$ (population at equilibrium), the intraspecific pcf $g_{ii}(r, t)$ follows eq. 4 (see eqs. 13 to 27 in the Appendices). The system stabilizes in the presence of advection, but depends on time in its absence.

$$g_{ii}(r, t) = \begin{cases} 1 + \frac{\lambda}{4D\pi r C_i} \left\{ 1 - \operatorname{erf}\left(\frac{r}{\sqrt{8Dt}}\right) \right\} & \text{for } U = 0 \\ 1 + \frac{\lambda}{2\pi C_i} \left(\frac{\sqrt{\gamma} \arctan\left(\frac{\sqrt{\gamma} r}{\sqrt{2D}}\right)}{2^{3/2} D^{3/2}} + \frac{1}{2Dr} - \frac{\pi\sqrt{\gamma}}{2^{5/2} D^{3/2}} \right) & \forall U > 0 \end{cases} \quad (4)$$

As populations of different species do not directly interact, each population is an independent realization of a point process, which means that the distribution of all particles within the community constitutes a random superposition of stationary point processes and $g_{ij}(r, t) = 1 \forall i \neq j, \forall U$ (Illian *et al.*, 2008, p. 326, eq. 5.3.13).

Related to the pair correlation function is Ripley's K -function $K(r)$. Its marked version, $K_{ij}(r)$, is the average number of points of species j surrounding a particle of species i within a sphere of radius r (Illian *et al.*, 2008).

$$\forall r \geq 0, K_{ij}(r) = \frac{1}{C_j} \mathbb{E}_i (N_j(b(o, r))) \quad (5)$$

where \mathbb{E}_i is the mean with respect to points of species i and $N_j(b(o, r) \setminus \{o\})$ is the number of points of species j in the sphere of radius r centred on o , not counting o itself. The relationship between $K_{ij}(r)$ and $g_{ij}(r)$ is given in eq. 6.

$$g_{ij}(r) = \frac{K'_{ij}(r)}{4\pi r^2} \quad (6)$$

Combining eq. 4 and eq. 6 (see also eqs. 28 to 40 in the Appendices), we can show that:

$$K_{ii}(r, t) = \begin{cases} \frac{4}{3}\pi r^3 + \frac{\lambda}{C_i D} \left(\frac{r^2}{2} - \frac{1}{2} \operatorname{erf}\left(\frac{r}{\sqrt{8Dt}}\right) (r^2 - 4Dt) - \frac{\sqrt{2D}tr}{\sqrt{\pi}} e^{-r^2/8Dt} \right) & \text{for } U = 0 \\ \frac{4}{3}\pi r^3 + \frac{2\lambda}{C_i} \left(\frac{r^2}{6D} + \frac{\sqrt{\gamma} r^3 \arctan(\sqrt{\frac{\gamma}{2D}} r)}{6\sqrt{2} D^{3/2}} + \frac{\log\left(\gamma \frac{r^2}{2D} + 1\right)}{6\gamma} - \frac{\sqrt{\gamma} \pi r^3}{12\sqrt{2} D \sqrt{D}} \right) & \forall U > 0 \end{cases} \quad (7)$$

For random superposition of stationary point processes, $K_{ij}(r, t) = \frac{4}{3}\pi r^3$ whenever $i \neq j$ (Illian *et al.*, 2008, p. 324, eq. 5.3.5).

Dominance index

The dominance index (defined in Table S1 in the Supporting Information of Wiegand *et al.*, 2007) is the ratio between the number of conspecifics and the number of individuals of all species surrounding a given particle.

Let $M_{i.}(r)$ be the average number of individuals within a circle of radius r around an individual of species i , which can also be written with Ripley's K -function as $M_{i.}(r) = C K_i(r)$. $M_{ii}(r)$ corresponds to the conspecific

neighbourhood and $M_{io}(r)$ corresponds to individuals of all other species. We can then define D_i with eq. 8.

$$\begin{aligned} D_i(r) &= \frac{M_{ii}(r)}{M_{ii}(r) + M_{io}(r)} \\ &= \frac{C_i K_{ii}(r)}{\sum_{j=1}^S C_j K_{ij}(r)} \end{aligned} \quad (8)$$

When individuals of the same species i tend to cluster, $D_i(r)$ tends to 1 while it tends to the proportion of individuals of species i in the whole community when the distribution is uniform (see examples in the Supplementary Information).

Using eq. 7 and 8, we obtain a theoretical formula for the dominance index:

$$D_i(r, t) = \begin{cases} \frac{C_i \left[\frac{4}{3} \pi r^3 + \frac{\lambda}{C_i D} \left(\frac{r^2}{2} - \frac{1}{2} \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) (r^2 - 4Dt) - \frac{\sqrt{2Dt} r}{\sqrt{\pi}} e^{-r^2/8Dt} \right) \right]}{\sum_{j=1}^S C_j \frac{4}{3} \pi r^3 + \frac{\lambda}{D} \left(\frac{r^2}{2} - \frac{1}{2} \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) (r^2 - 4Dt) - \frac{\sqrt{2Dt} r}{\sqrt{\pi}} e^{-r^2/8Dt} \right)} & \text{for } U = 0 \\ \frac{C_i \left[\frac{4}{3} \pi r^3 + \frac{\lambda}{3C_i D} \left(r^2 + \frac{\sqrt{\gamma} r^3 \arctan(\sqrt{\frac{\gamma}{2D}} r)}{\sqrt{2D}} + \frac{D \log(\gamma \frac{r^2}{2D} + 1)}{\gamma} - \frac{\sqrt{\gamma} \pi r^3}{2\sqrt{2D}} \right) \right]}{\sum_{j=1}^S C_j \frac{4}{3} \pi r^3 + \frac{\lambda}{3D} \left(r^2 + \frac{\sqrt{\gamma} r^3 \arctan(\sqrt{\frac{\gamma}{2D}} r)}{\sqrt{2D}} + \frac{D \log(\gamma \frac{r^2}{2D} + 1)}{\gamma} - \frac{\sqrt{\gamma} \pi r^3}{2\sqrt{2D}} \right)} & \forall U > 0 \end{cases} \quad (9)$$

Parameters

We model two types of organisms: microphytoplankton (defined by a diameter between 20 and 200 μm , here 50 μm) and nanophytoplankton (defined by a diameter between 2 and 20 μm , here 3 μm). These two groups are characterized respectively by a low diffusivity, slow growth and lower concentration vs. high diffusivity, fast growth and higher concentration. Particles are displaced by a turbulent fluid whose velocity defines the time scale of the discretized model: we give here the reasoning behind parameter values, keeping in mind that our model can only be semi-quantitative. Main parameter definitions and values are given in Table 1.

Advection

We first consider the advection process, due to the turbulence of the environment. We only consider the Batchelor-Kolmogorov regime, i.e the size of the space is below the size of the smallest eddy, but above the smallest scale of fluctuations in nutrient concentrations. The defining scale of the environment therefore corresponds to a Reynolds number $Re \approx 1$.

$$Re = \frac{V}{k\nu} \approx 1$$

where $\nu = 10^{-6} \text{ m}^2 \cdot \text{s}^{-1}$ is the kinematic viscosity for water. The smallest wavenumber k corresponds to the largest length scale L_s (Kolmogorov scale), i.e. $k = 2\pi/L_s$, with $L_s \approx 1 \text{ cm}$ in the ocean (Barton *et al.*, 2014).

$$\begin{aligned} 1 &\approx \frac{VL_s}{2\pi\nu} \\ U &\approx \frac{2\pi\nu}{L_s} \end{aligned}$$

This means that $U = 6.3 \times 10^{-4} \text{ m.s}^{-1} = 5.4 \times 10^3 \text{ cm.d}^{-1}$. Using $U\tau/3 = 0.5 \text{ cm}$ as in Young *et al.* (2001), we have $\tau = 2.8 \times 10^{-4} \text{ d} = 24 \text{ s}$. When $U\tau/2 = 0$, i.e. the environment is only diffusive, we keep the same value for τ .

The advection parameter in continuous time, γ , is computed through simulations, based on $s(t) \propto e^{3\gamma t}$ the separation between pairs of particles before stabilization. γ is estimated as the slope of $1/3 \langle \ln(s(t)) \rangle = f(t)$ with $\langle \ln(s(t)) \rangle$ being the average separation between 800 pairs of particles. For $U\tau/3 = 0.5 \text{ cm}$, $\gamma = 1231 \text{ s}^{-1}$.

Diffusion

If we use the Stokes-Einstein equations (Einstein, 1905, cited from Dusenbery, 2009), diffusivity can be computed according to the formula:

$$D = \frac{RT}{N_A} \frac{1}{6\pi\eta a} \quad (10)$$

where $R = 8.314 \text{ J.K}^{-1}.\text{mol}^{-1}$ is the molar gas constant, $T = 293 \text{ K}$ is the temperature, $N_A = 6.0225 \times 10^{23}$ is Avogadro's number, $\eta = 10^{-3} \text{ m}^{-1}.\text{kg.s}^{-1}$ is the dynamic viscosity of water and a is the radius of the organism considered.

Using $D = \frac{\Delta^2}{2\tau}$,

$$\begin{aligned} \Delta &= \sqrt{2\tau D} \\ \Leftrightarrow \Delta &= \sqrt{\frac{RT}{N_A} \frac{\tau}{3\pi\eta a}} \end{aligned}$$

We consider $a_n = 1.5 \text{ }\mu\text{m}$ for nanophytoplankton particles and $a_d = 25 \text{ }\mu\text{m}$ for microphytoplankton particles, which allows us to compute Δ_n and Δ_d (see Table 1).

Ecological processes

We study the community at equilibrium, with the birth rate equal to the death rate, i.e. $p = q$. We use a diatom (microphytoplankton) doubling rate of 1 d^{-1} (Bissinger *et al.*, 2008) and consider the fastest-growing nanophytoplankton particles, corresponding to a diameter of $3 \text{ }\mu\text{m}$ (Bec *et al.*, 2008), for which the doubling rate is between 2 and 3 d^{-1} (set to 2.5 d^{-1} here).

Parameter	Definition	Value
p_d, q_d	Probability of reproducing/dying for diatom particles	2.8×10^{-4}
p_n, q_n	Probability of reproducing/dying for nanophytoplankton particles	6.9×10^{-4}
$U\tau/3$	Stretching parameter proxy	$\{0, 0.5\}$ cm
Δ_d	Diffusion parameter for diatoms	6.4×10^{-5} cm
Δ_n	Diffusion parameter for nanophytoplankton particles	2.6×10^{-4} cm

Table 1: Definitions and values of the main parameters used in the three-dimension Brownian Bug Model, assuming the duration of a time step τ is 24 seconds.

Range of interaction

As we examine particle aggregation or segregation and their potential effects on interactions between species, we have to ascertain the volume around which a particle can be affected by the presence of other particles, or affect other particles. We only consider here interactions due to competition for nutrients, and therefore need to define a nutrient depletion volume. We approximate this volume as the sphere of radius r where $C(r) \leq 90\%C_\infty$ with C_∞ the background concentration of the nutrient. The radius of this nutrient depletion volume is maximized when the particle is in stagnant water (diffusion is the only hydrodynamics process). In this case, it corresponds to 10 times the radius of the particle (Jumars *et al.*, 1993; Karp-Boss *et al.*, 1996). We define the maximum distance which allows for potential interactions (due to competition for resources) between two particles of radius a_i and a_j as $D_{\text{threshold}}$ (eq. 11), and the corresponding volume of potential interactions around an organism as $V_{\text{int}} = 4/3\pi D_{\text{threshold}}^3$.

$$D_{\text{threshold}} = 10a_i + 10a_j \quad (11)$$

We consider this maximum value as our baseline, keeping in mind that turbulence reduces the size of the nutrient depletion volume and increases the nutrient flux to the cell (Arnott *et al.*, 2021), but determination of the exact shape of the nutrient depletion volume in the presence of turbulence is too complex to be addressed here (Karp-Boss *et al.*, 1996).

We consider a total volume of 1000 cm^3 for diatoms and 10 cm^3 for nanophytoplankton (volumes are adapted to balance realistic concentrations and computation time) with periodic boundary conditions. Particles are uniformly distributed in the cube at the beginning of the simulation. We run an idealized simulation with 3 species with an even abundance distribution of about 10^4 C/L for diatoms (Picoche & Barraquand, 2020) and 10^6 C/L for nanophytoplankton particles (Edwards, 2019). We then model a more realistic community with 10 species having a skewed abundance distribution (between 55 000 and 400 particles C/L for microphytoplankton, according to observations of field abundance distributions in Picoche & Barraquand, 2020, and multiplied by 10^2 for nanophytoplankton). All simulations are run for 1000 time steps of duration τ .

Results

We show an example of nanophytoplankton spatial distributions with and without advection at the end of a simulation in Fig. 1: clustering is not visible to the naked eye, even when zooming in the observation volume, in the presence of advection, but removing turbulence helps visualising small aggregates of conspecifics. Microphytoplankton distributions are not so easy to analyse as no clusters can be detected from basic observations, whether advection is included or not (Fig. SX). Statistics are therefore needed to go further in detecting patterns of aggregation.

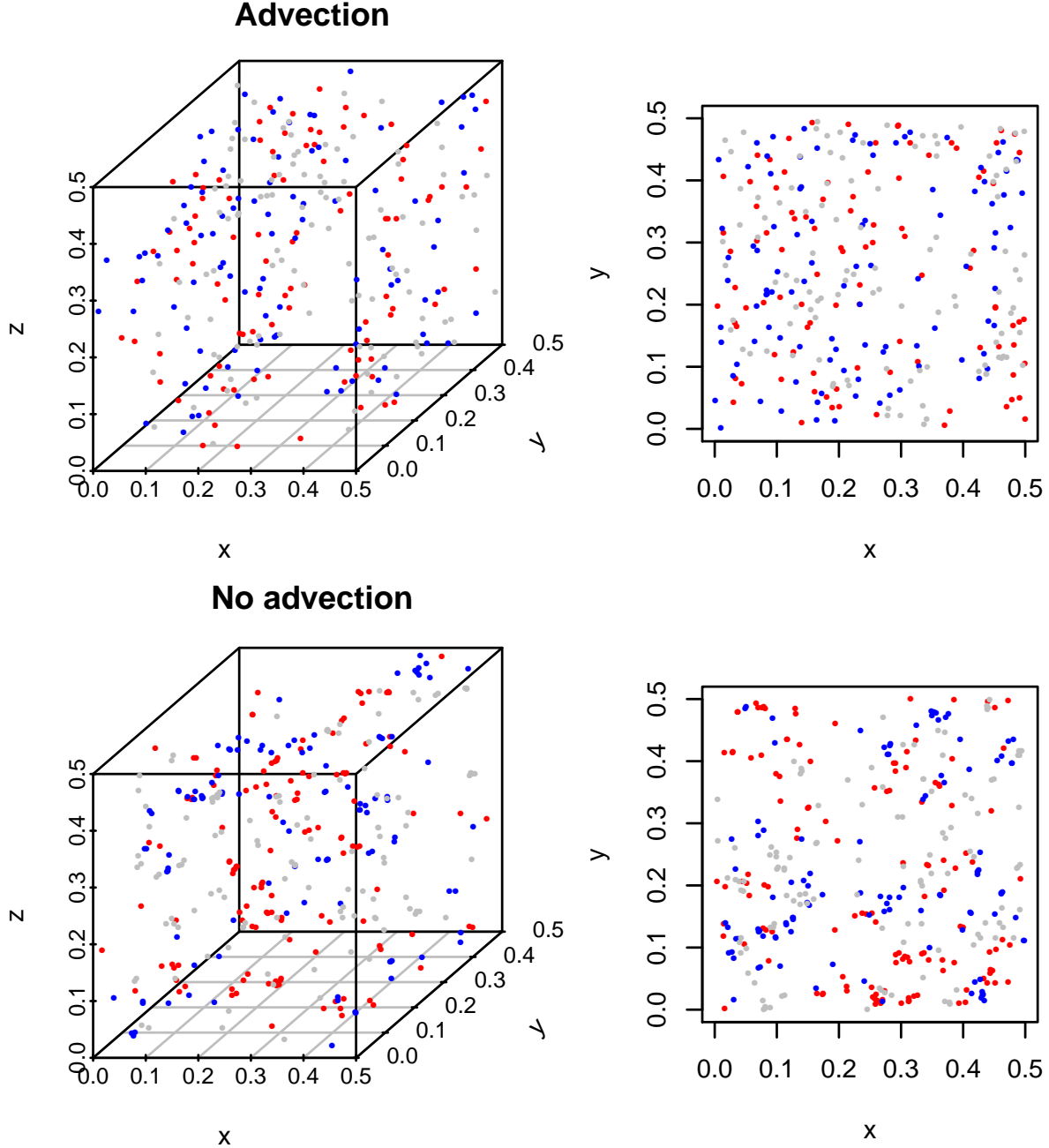


Figure 1: Spatial distributions of a 3-species community of nanophytoplankton with and without advection with density $\lambda = 10^3 \text{ cm}^{-3}$ after 1000 time steps. Each color corresponds to a different species. On the left-hand side, only a zoom on a $0.5 \times 0.5 \text{ cm}^2$ cube is shown, and its projection on the x-y plane is shown on the right hand-side.

Ripley's K -functions extracted from numerical simulations match theoretical formula (Fig. 2) for both types of particles, which also indicates that dominance indices extracted from the simulation match theoretical expectation.

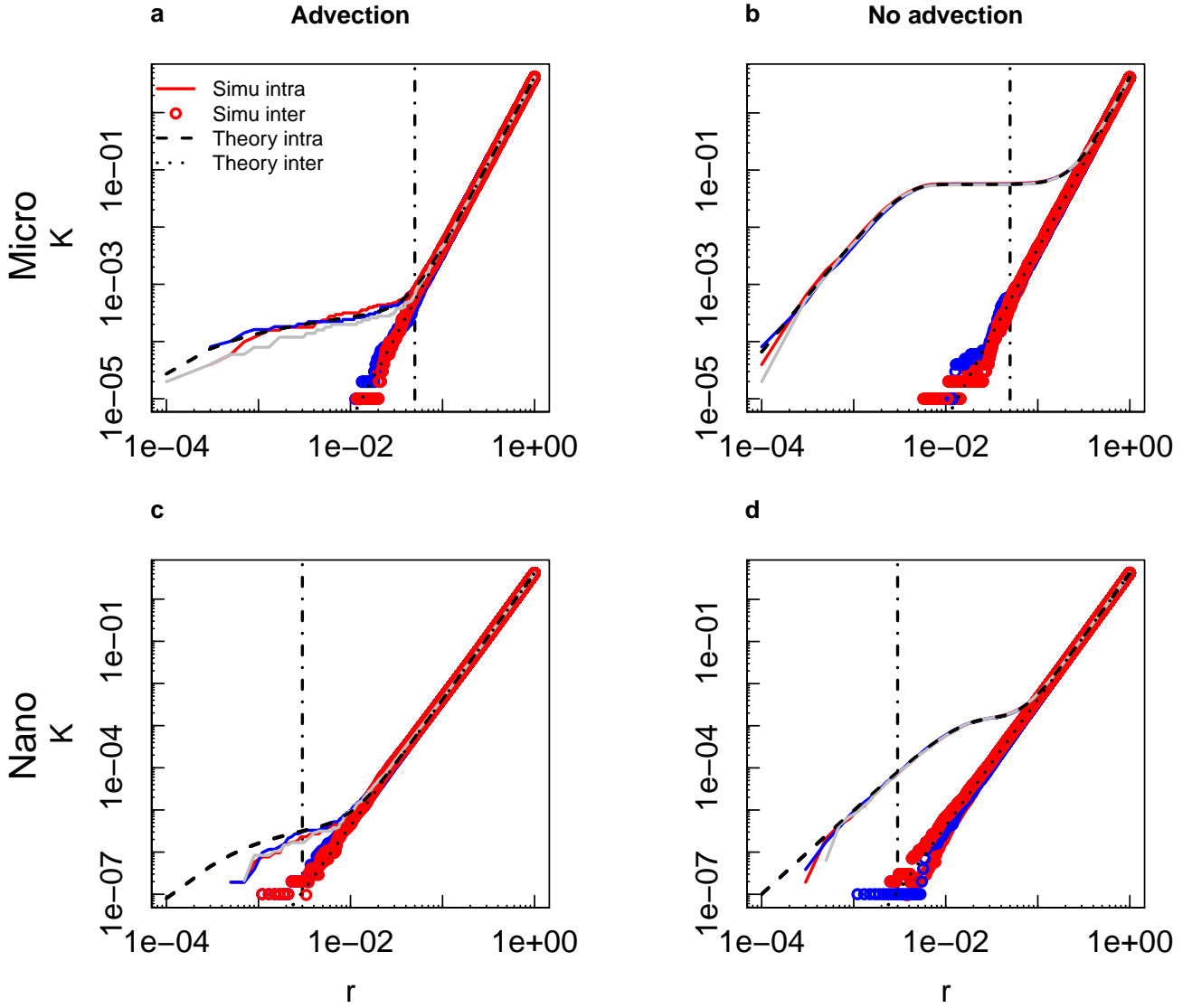


Figure 2: Ripley's K -function as a function of distance (in cm) for microphytoplankton (a-b) and nanophytoplankton (b-c) in a 3-species community with even distributions after 1000 timesteps, with (a, c) and without (b, d) advection. Each color represents a different species. The black dash-dotted line corresponds to the threshold considered as the maximum distance for nutrient-based competition.

Dominance indices all follow a similar pattern (Fig. 3 and 4). The dominance index is close to 1 for small distances: there is always a scale at which a particle is surrounded almost only by conspecifics. The index then decreases sharply to converge at large distances (close to 1 cm) to the proportion of the focus species in the whole community, as it would for a uniform distribution. Patterns differ at intermediate ranges of distances between particles.

In the presence of advection, the dominance index starts decreasing for a distance between 5 and 10 times lower

than when advection is absent, which indicates that organisms are closer to heterospecifics when their environment is turbulent. A quasi-uniform distribution is also reached for smaller distances with advection than without. Microphytoplankton species start mixing for distances larger than for nanophytoplankton species irrespective of the hydrodynamic regime surrounding them.

In a 3-species community with the same initial abundances, microphytoplankton dominance indices are between 0.37 and 0.47 at the distance threshold for potential interactions, while it is between 0.80 and 0.94 for nanophytoplankton species when advection is present. In the absence of turbulence, dominance indices are all above 0.98 when the distance threshold is reached (Fig. 3). Microphytoplankton organisms are therefore as likely to share their depletion volume with conspecifics as they are with heterospecifics, but only when turbulent advection is accounted for, whereas nanophytoplankton organisms have almost only conspecifics around them.

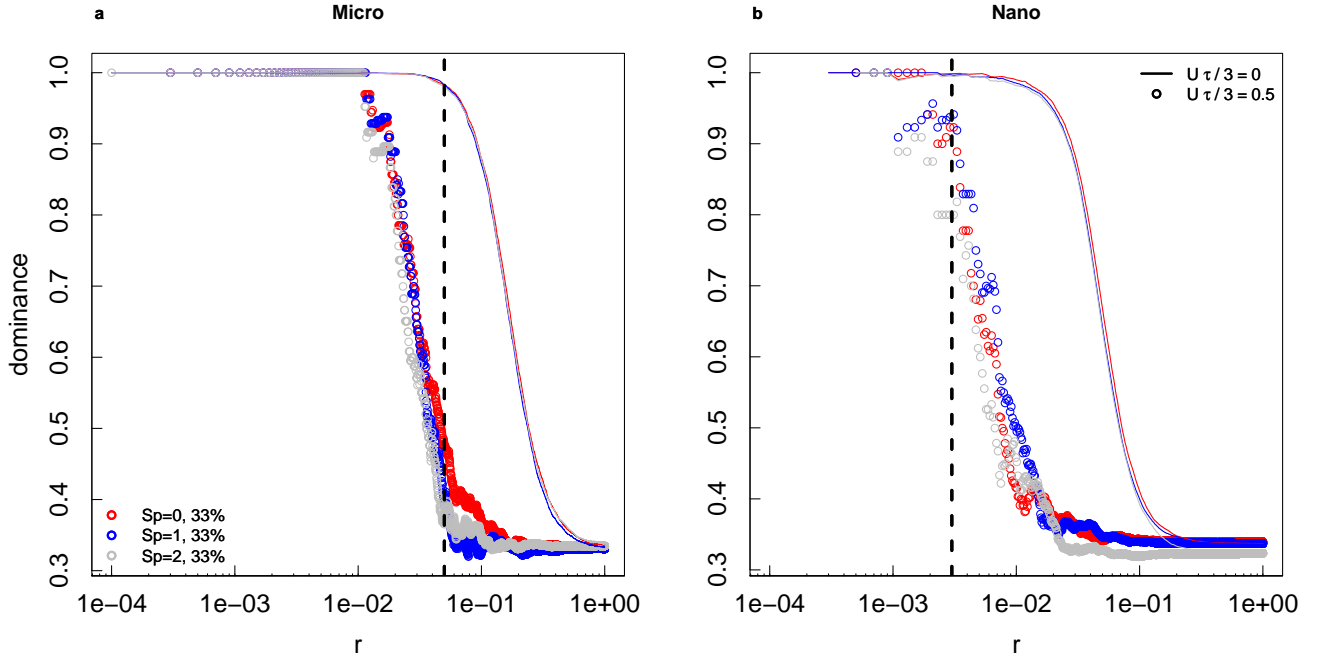


Figure 3: Dominance indices as a function of distance (in cm) for microphytoplankton (a) and nanophytoplankton (b) in a 3-species community with even distributions after 1000 timesteps, with (circles) and without (lines) advection. Each color represents a different species. The black dashed line corresponds to the threshold considered as the maximum distance for nutrient-based competition.

These differences between microphytoplankton and nanophytoplankton, and the role of advection, are even more pronounced when considering a 10 species-community with a skewed abundance distribution. (Fig. 4). In the presence of advection, microphytoplankton dominance indices at the distance threshold are between 0.34 (for the most abundant species) and 0.033 (for one of the least abundant species), while they are between 0.90 and 0.85 when advection is not taken into account. Nanophytoplankton species, too, are more mixed: dominance indices vary between 0.54 and 0.2 when the depletion-zone limit is reached (with an exception of 0 for one particular species which had no conspecific for radii below 10^{-2} cm) when particles are displaced by turbulence, while the

same quantity is between 1 and 0.97 when they are only subject to diffusion.

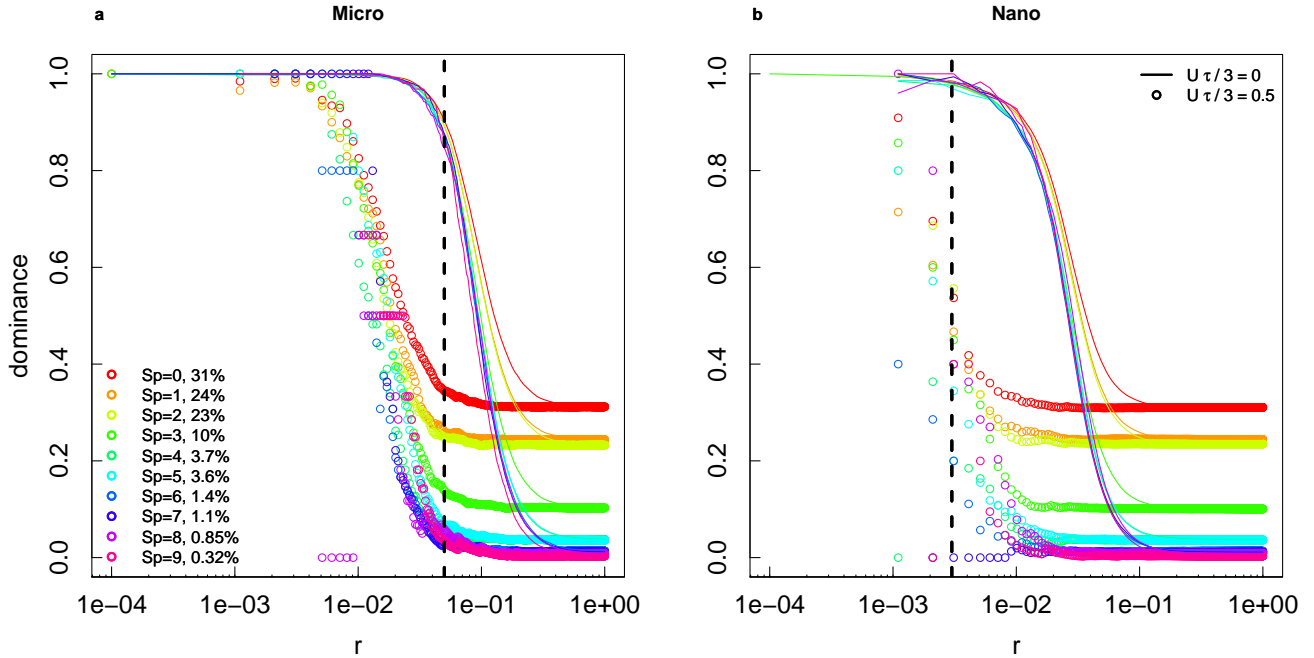


Figure 4: Dominance indices as a function of distance (in cm) for microphytoplankton (a) and nanophytoplankton (b) in a 10-species community with a skewed abundance distribution (final proportion in the community is indicated in the legend) after 1000 timesteps, with (circles) and without (lines) advection. Each color represents a different species. The black dashed line corresponds to the threshold considered as the maximum distance for nutrient-based competition.

Differences in spatial distributions are not only due to particle sizes which determine properties of demography and turbulence, but also to their abundances (here set through initial values). In the presence of turbulence, the dominance index decreases at lower distances for more abundant species (Fig. 5 a-b): as these species tend to be present nearly everywhere when they are mixed in the environment, they are also more likely to be close to a heterospecific, but still have more conspecifics close to them than the less abundant species. When turbulence is absent, the effect of abundance on the dominance index is reversed: a 5% dominance decrease is reached for a higher distance when species are more abundant for microphytoplankton, which may indicate that particle growth offsets diffusion in this case. The relationship is more complex for nanophytoplankton: the minimum distance for a 5% decrease in dominance is reached for intermediate abundances; there is possibly a trade-off between occupation of the space due to mixing by diffusion and growth of particles around their conspecifics. The effect of average abundances on the composition of a particle neighbourhood within its depletion zone is less marked for nanophytoplankton than for microphytoplankton (Fig. 5 c-d): a more abundant species of microphytoplankton will be more present in its depletion zone than a less abundant species, but the trend is less obvious for nanophytoplankton species. The lowest value of dominance is obtained for intermediate values of abundances, and is higher for less abundant species. However, the maximum value of dominance is still obtained by the most abundant species of nanophytoplankton.

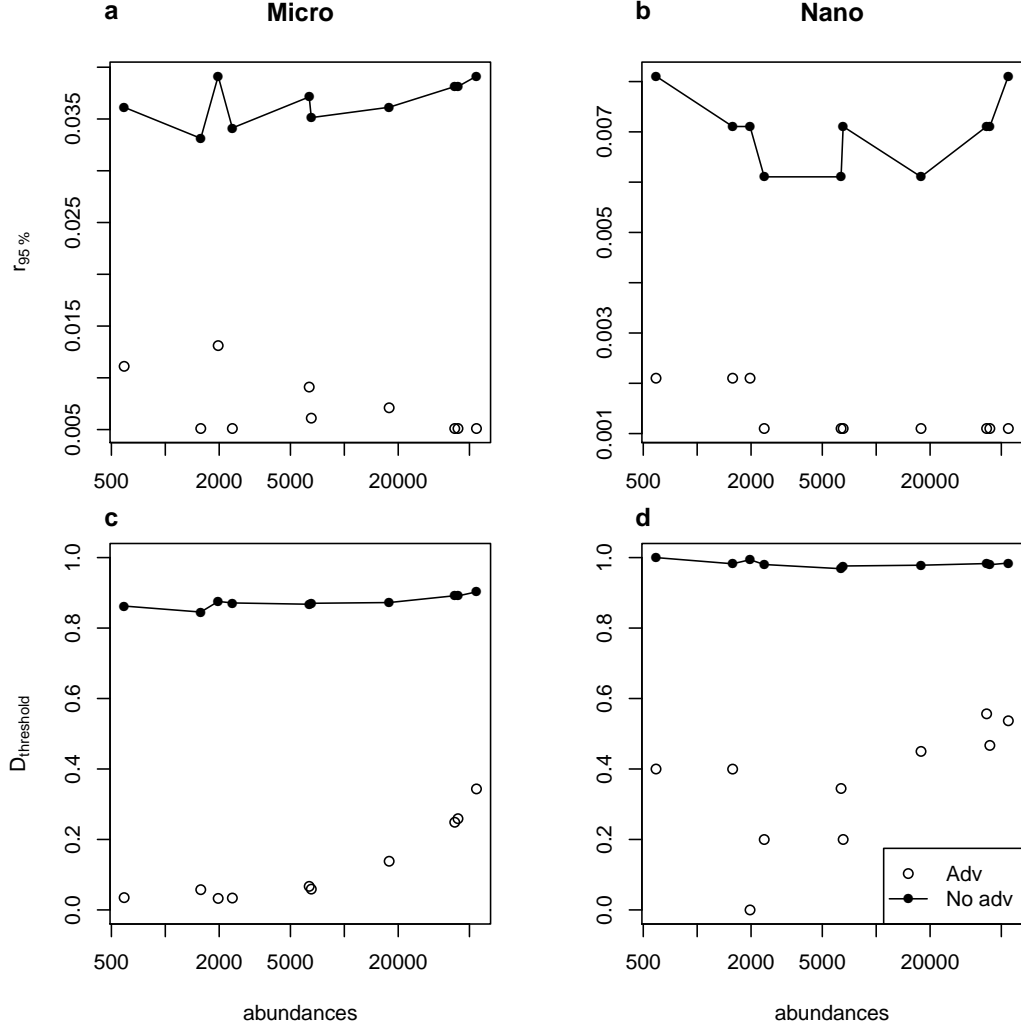


Figure 5: Minimum distances (in cm) between points for dominance to drop below 95% (a and b) and dominance at a distance corresponding to the threshold for competition (c and d) as a function of abundances (note the logarithmic scale on the x-axis) for microphytoplankton and nanophytoplankton. We consider cases with and without advection in a 10-species community with a skewed abundance distribution.

Discussion

We designed a stochastic, three-dimension, individual-based model of the spatial distribution of multiple species in a viscous and turbulent flow. We conducted both mathematical analyses and numerical simulations to quantify spatial correlations in particle distributions. We focused on the pair correlation function and Ripley's K -function, for which numerical and theoretical analyses showed a good agreement, and extracted a more ecologically-oriented metric from them, *i.e.* the dominance index. This statistic is the *local* average ratio of the number of organisms of a given species in the neighbourhood of a particle of the same species, compared to the total number of organisms, as a function of the distance from the particle. Intraspecific clustering corresponds to a dominance index close to 1, which decreases when interspecific mixing increases. The choice of this index was motivated by two reasons: it is at

its core a proportion of a focus species in a certain volume, i.e. a scale-dependent, localized metric bounded between 0 and 1 as opposed to other statistics whose values are less directly interpreted, and is easy to relate to coexistence theory as it describes the environment of a particle in terms of heterospecifics and conspecifics, which can, under certain hypotheses that we discuss below, be related to interspecific and intraspecific interactions. Comparing the distributions of organisms of different sizes and demography, we showed that the presence and intensity (Section SX) of turbulence always increased mixing, and that the species composition around a particle depended on its size, which mechanically determines its hydrodynamics properties (diffusivity), and is linked with its ecological characteristics (growth rate and density). Microphytoplankters (20 to 200 μm), larger cells with lower diffusivity, growth rate and abundance, were on average further away from other cells, due to their lower concentrations (Section SX), than nanophytoplankters (2 to 20 μm), but they were surrounded by more heterospecifics than conspecifics within a volume of potential interactions, whose radius is defined as the maximum distance for which nutrient depletion volumes of two different particles may overlap. Microphytoplankters were therefore more likely to interact with individuals from other species than with individuals of their own species. However, if we consider different distances within the volume of potential interactions, this affirmation needs to be nuanced: there was always a (potentially small) volume around a particle for which the community remained mostly monospecific. Variability in species composition of the neighbourhood only intervened for larger distances from the particle.

We first focus on the smallest distances between particles. The nearest neighbour of a particle was always a particle of the same species, and the minimum distance between conspecifics was always lower than expected for a uniform distribution (Section SX). The dominance index remained close to 1 for distances below 10^{-2} cm or 10^{-3} cm for microphytoplankton and nanophytoplankton respectively. There was therefore always *some* intraspecific aggregation, i.e. conspecifics were always closer than heterospecifics at the lowest distances. This is due to the prevalence of demographic processes at individual scales, because a particle acts as a source point for other organisms of the same species, and hydrodynamic processes do not separate conspecifics fast enough to prevent aggregation. If we consider that interaction strengths are a smoothly decaying function of distance, a common assumption in spatial coexistence models (e.g., Bolker & Pacala, 1999; Law *et al.*, 2003), this implies that population-level intraspecific interactions could be stronger than interspecific interactions due to intraspecific micro-scale aggregation. However, the mechanisms of competition at this scale are poorly known, likely relying on multiple types of resources with different distributions in the environment, effects on the cell, uptakes, etc. Rather than weighting much more heavily the potential interactions with the closest neighbour(s) through an interaction kernel, we therefore chose to define a maximum distance for two particles to possibly affect the concentrations of elements in the environment of each other. We consider that, at all distances below this threshold, interaction could happen between particles. We continue the discussion with that simplification in mind, and explicitly mention when it is relaxed.

Dominances began to decrease at distances above 10^{-3} cm, still below the maximum distance for interactions. At this distance and above, the balance between heterospecifics and conspecifics was much more sensitive to differ-

ent phytoplankton’s demographics and hydrodynamic traits. The species composition of a particle’s neighbourhood depended on its size: nanophytoplankton organisms mainly shared their volume of potential interactions with conspecifics (the dominance index remained close to 1, even near the distance threshold, i.e. the maximum distance for nutrient depletion volume overlap) while microphytoplankton organisms could affect both conspecifics and heterospecifics (the dominance index was often below 50% at the distance threshold, i.e. a particle’s depletion zone probably overlapped with more heterospecifics’ than conspecifics’). Microphytoplankters were therefore more likely to share their depletion volume with heterospecifics than nanophytoplankters. The rate of production of new microphytoplankton conspecifics was not sufficient to compensate for the separation velocity due to turbulence and diffusivity, even though the diffusion range of microphytoplankters was smaller than that of nanophytoplankters. There may therefore be different mechanisms at play at the community level for microphytoplankton and nanophytoplankton. For nanophytoplankton, the spatial structure likely leads to more interactions between conspecifics than between heterospecifics. The distribution of microphytoplankton species, on the contrary, encourages more interactions between heterospecifics. If we consider that local interaction strengths are equal within the volume of potential interactions, scaling to the population level, we would likely observe stronger intra- over interspecific interactions for nanophytoplankton (a key factor in coexistence theory, Barabás *et al.*, 2017). This is not so clear for microphytoplankton. If we consider that local interaction strengths are negatively correlated with distances between organisms, the balance between local interaction strength and frequency is unknown, and the structure of interactions at the population level that could emerge from the spatial structure remains obscure.

The dominance of heterospecifics in a microphytoplankter’s neighbourhood may however be debated. Indeed, when computing the volumes of potential interactions based on nutrient concentrations around a cell, we used maximum volumes, corresponding to a diffusive-only flow. When turbulence increases, uptake increases and the size of the depletion zone decreases (Karp-Boss *et al.*, 1996). The proportion of change in the depletion volume increases with the size of organism: a 10 μm -diameter organism might not experience any change, while the uptake of a 100 μm -diameter organism would increase by at least 50% (Karp-Boss *et al.*, 1996). Therefore the volume of potential interactions shrinks in the presence of turbulence for microphytoplankton, but not necessarily for nanophytoplankton. We know that there is always a volume around a particle in which conspecifics dominate: if this volume coincides with the (turbulence-reduced) volume of potential interactions, a microphytoplankter organism may interact predominantly with conspecifics, as a nanophytoplankter would. Computing the exact shape and size of the volume of potential interactions in the presence of turbulence could therefore indicate similar neighbourhood composition in terms of relative presences of conspecifics and heterospecifics for microphytoplankton and nanophytoplankton, and therefore a spatial distribution favouring intraspecific interactions over interspecific interactions, even for microphytoplankton.

Up to now, we have only focused on the dominance index, a localized ratio of average densities multiplied by the local average number of neighbours of a particle, therefore focusing on relative densities of the different

species. However, interactions also depend on the absolute numbers of individuals. Mechanically, when density decreases, the distances between neighbours increase, which explains that the distances between the low-abundance microphytoplankters tended to be greater than distances between the more abundant nanophytoplankters (Fig. SX). At low abundances, a particle may be only surrounded by its children, which are then advected too far to be able to share the same local resources. Interactions via resource depletion may therefore be scarce in both space and time. At the other end of the spectrum, high densities could have a paradoxical effect: a species with a high density is present nearly everywhere in space, which means that it has more heterospecifics in its neighbourhood than a low-density species, in absolute numbers, while still remaining dominant (less heterospecifics in relative numbers). We considered here annual averages of phytoplankton observed concentrations. If we were to model populations in a bloom, during which microphytoplankton particles can reach 10^6 C/L (2 orders of magnitude higher than here) and a single species can represent up to 90% of the abundance of the community (Hernandez-Fariñas *et al.*, 2014), we would likely see the dominance of the single blooming species: an organism of such species would be closer to its conspecifics than a low-abundance species, and have more conspecifics surrounding it than heterospecifics. The environment is also modified by a bloom: the competition can increase due to depletion of nutrients in the whole environment. If we wanted to make more general conclusions on interaction structure in different conditions (*e.g.*, blooms or not), we would therefore need a more mechanistic representation of the dynamics of resources affecting interactions between organisms.

The model presented here is one of the first microscale phytoplankton dynamic model focusing on spatial distributions of multiple species within a single trophic level, describing only basic hydrodynamics and demographics processes. Using this model, we were able to guesstimate the differences in potential intra vs interspecific interactions between species. Contrary to other models (*e.g.*, Birch & Young, 2006; Bouderbala *et al.*, 2018), we did not consider explicit effects of density dependence between individuals, as we cannot be sure that this kind of dependencies, more often observed at the population level and macroscale, applies similarly between individuals at the microscale, especially for the very short time scales that we consider. For instance, even if a species abundance is locally tripled, it does not necessarily mean that competition immediately ensues, if nutrient depletion has not had time to set in yet. Another, possibly more relevant, way of modeling interactions would be to introduce resource points in the cube, which could in turn change the reproduction or death rate of individuals. Such mechanism is mostly adequate for interactions due to competition for nutrients, but its adequacy is less clear-cut than may be thought. If the resource points risk being depleted, this entails a negative spatial correlation between organisms and their resources (Murrell, 2005). However, there are additional complexities in phytoplankton. For example, the phycosphere, a micro-environment at the periphery of a phytoplankton particle where communities of bacteria interact (Seymour *et al.*, 2017), can also impact phytoplankton fitness, both positively (cross-feeding) and negatively (algicidal activities of bacteria). As bacteria feed on compounds leaking from the phytoplankter, the gradient of resources is opposite to the gradient of nutrient: resources shared between phytoplankters and bacteria are maximum at the surface of

the phytoplankter and decrease with the distance from the organism. Volumes of potential interactions, and the types of interactions themselves, may therefore vary depending on the mechanism considered. Predation is another mechanism that can depend on the spatial distribution of organisms. Experiments show that predation depends on aggregation, even though patterns are not clear (e.g., increase in predation due to clustering, in Bjærke *et al.*, 2015, decrease in Boraas *et al.*, 1998), which creates a new balance between indirect interactions and spatial distributions. These trade-offs cannot be taken into account if explicit particles are not modeled, either representing elements necessary for plankton metabolism, or natural enemies.

Other interactions between microphytoplankton do not directly affect their survival, but their position: most phytoplankters are able to move willingly, whether in three-dimensions, or only along the vertical dimension when they can regulate their buoyancy. Models of attraction between motile mechanisms (Breier *et al.*, 2018) show that these mechanisms encourage cluster formation when length scales associated with interactions and turbulence are close. Such clustering would be even stronger if acknowledging another very common trait in microphytoplankton, coloniality (Kjørboe *et al.*, 1990). With independent and equivalent individuals, our model should therefore be taken as a first null model to which more complex, maybe more mechanistic models should be compared, likely leading to even more clustering.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Author contribution statement

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Appendices

Derivation of the spatial characteristics of the Brownian Bug Model

We show here how to compute the monospecific pair correlation function and Ripley's K -function of the Brownian Bug Model. Formula for standard processes are given in the Supplementary Information, for readers who want to familiarize with simpler models.

Proof of eq. 4

In three dimensions, when the birth rate λ is the same as the mortality rate μ , the pair density $G(r)$ is a solution of eq. 12 (see Young *et al.*, 2001 and Picoche *et al.*, 2022 for a detailed derivation).

$$\frac{\partial G}{\partial t} = \frac{2D}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial G}{\partial r} \right) + \frac{\gamma}{r^2} \frac{\partial}{\partial r} \left(r^4 \frac{\partial G}{\partial r} \right) + 2\lambda C \delta(\mathbf{r}) \quad (12)$$

With advection In the presence of advection ($\gamma \neq 0$), a steady-state solution can be found.

$$\begin{aligned} 0 &= \frac{2D}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial G}{\partial r} \right) + \frac{\gamma}{r^2} \frac{\partial}{\partial r} \left(r^4 \frac{\partial G}{\partial r} \right) + 2\lambda C \delta(\mathbf{r}) \\ \Leftrightarrow 0 &= 4\pi r^2 \left(\frac{2D}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial G}{\partial r} \right) + \frac{\gamma}{r^2} \frac{\partial}{\partial r} \left(r^4 \frac{\partial G}{\partial r} \right) + 2\lambda C \delta(\mathbf{r}) \right) \\ \Leftrightarrow 0 &= 4\pi \left(2D \frac{\partial}{\partial r} \left(r^2 \frac{\partial G}{\partial r} \right) + \gamma \frac{\partial}{\partial r} \left(r^4 \frac{\partial G}{\partial r} \right) \right) + 4\pi r^2 2\lambda C \delta(\mathbf{r}) \end{aligned} \quad (13)$$

We can then integrate Eq. (12) over a small sphere centered on a particle, with radius ρ . Let us first note that

$$\begin{aligned} \int_{\mathbb{R}^3} \delta(\mathbf{r}) d^3 \mathbf{r} &= 1 \\ \Leftrightarrow \int_0^{2\pi} \int_0^\pi \int_0^\rho \delta(\mathbf{r}') r'^2 \sin(\phi) dr' d\phi d\theta &= 1 \\ \Leftrightarrow 4\pi \int_0^\rho \delta(\mathbf{r}') r'^2 dr' &= 1 \end{aligned} \quad (14)$$

Using Eq. (13) and (14),

$$\begin{aligned} 0 &= 4\pi \left(2Dr^2 \frac{\partial G}{\partial r} + \gamma r^4 \frac{\partial G}{\partial r} \right) + 2\lambda C \\ \Leftrightarrow \frac{\partial G}{\partial r} &= - \frac{1}{4\pi} \frac{2\lambda C}{2Dr^2 + \gamma r^4} \end{aligned} \quad (15)$$

We can integrate between ρ and ∞ , knowing that $G(\infty) = C^2$.

$$C^2 - G(\rho) = - \frac{2\lambda C}{4\pi} \int_\rho^\infty \frac{1}{2Dr^2 + \gamma r^4} dr \quad (16)$$

We first compute the primitive $A = \int \frac{1}{2Dr^2 + \gamma r^4} dr$.

$$\begin{aligned} A &= \int \frac{1}{r^2(2D + \gamma r^2)} dr \\ &= \int \frac{1}{2Dr^2} - \frac{\gamma}{2D(2D + \gamma r^2)} dr \\ &= \frac{1}{2D} \int \frac{1}{r^2} dr - \frac{\gamma}{2D} \int \frac{1}{2D + \gamma r^2} dr \\ &= -\frac{1}{2Dr} - \frac{\gamma}{2D} \int \frac{1}{2D \left(1 + \left(\sqrt{\frac{\gamma}{2D}} r \right)^2 \right)} \end{aligned} \quad (17)$$

With a change of variable $u = \sqrt{\frac{\gamma}{2D}} r$, using $\int \frac{1}{1+u^2} = \arctan(u)$, we have:

$$A = -\frac{1}{2Dr} - \frac{\sqrt{\gamma} \arctan \left(\frac{\sqrt{\gamma} r}{\sqrt{2D}} \right)}{2\sqrt{2D}\sqrt{D}} + K \quad (18)$$

where K is a constant.

We can now compute $B = [A]_\rho^\infty$.

$$B = -\frac{\sqrt{\gamma}\pi}{4\sqrt{2D}\sqrt{D}} + \frac{1}{2D\rho} + \frac{\sqrt{\gamma}\arctan\left(\frac{\sqrt{\gamma}\rho}{\sqrt{2D}}\right)}{2\sqrt{2D}\sqrt{D}} \quad (19)$$

This leads to:

$$\begin{aligned} G(\rho) &= C^2 + \frac{2\lambda C}{4\pi} B \\ &= C^2 + \frac{\lambda C}{2\pi} \left[\frac{1}{2D\rho} + \frac{\sqrt{\gamma}\arctan\left(\frac{\sqrt{\gamma}\rho}{\sqrt{2D}}\right)}{2\sqrt{2D}\sqrt{D}} - \frac{\sqrt{\gamma}\pi}{4\sqrt{2D}\sqrt{D}} \right]. \end{aligned} \quad (20)$$

Finally, the pair correlation function $g = G/C^2$ is defined as

$$g(\rho) = \frac{\lambda}{4\pi CD} \left(\frac{\sqrt{\gamma}\arctan\left(\frac{\sqrt{\gamma}\rho}{\sqrt{2D}}\right)}{\sqrt{2D}} + \frac{1}{\rho} - \frac{\pi\sqrt{\gamma}}{2\sqrt{2D}} \right) + 1. \quad (21)$$

Without advection When $U = 0$, $\gamma = 0$ and there is no steady solution. We can get back to Eq. (12).

$$\frac{\partial G}{\partial t} = \frac{2D}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial G}{\partial r} \right) + 2\lambda C \delta(\mathbf{r}) \quad (22)$$

Assuming an isotropic environment, this means

$$\frac{\partial G}{\partial t} - 2D\Delta G = 2\lambda C \delta(\mathbf{r}) \quad (23)$$

where $\Delta = \nabla^2$ is the Laplacian operator.

We therefore have

$$\mathcal{L}G(\mathbf{r}, t) = 2\lambda C \delta(\mathbf{r}) \quad (24)$$

where \mathcal{L} is the linear differential operator $\partial_t - 2D\Delta$.

Using the Green's function theory, we know that $G(y) = \int H(y, s) 2\lambda C \delta(s) ds$ where $H(y, s) = H(y - s)$ is the Green kernel (heat kernel).

$$\begin{aligned} G(\mathbf{r}, t) &= 2\lambda C \int_{\mathbb{R}^3} \int_0^t H(\mathbf{r} - \mathbf{r}', t') \delta(\mathbf{r}') dr' dt' \\ \Leftrightarrow &= 2\lambda C \int_0^t H(\mathbf{r}, t') dt' \end{aligned}$$

A solution for the Green's function using $\mathcal{L} = \partial_t - 2D\Delta$ in 3 dimensions is $H(r, t) = \left(\frac{1}{4\pi 2Dt}\right)^{3/2} \exp\left(\frac{-r^2}{4 \times 2Dt}\right)$.

$G(r, t)$ can then be computed:

$$G(r, t) = 2\lambda C \left(\frac{-\operatorname{erf}\left(\frac{r}{\sqrt{8tD}}\right)}{8\pi Dr} + K \right) \quad (25)$$

where erf is the error function. Using $G(r, 0) = C^2$ and $\lim_{x \rightarrow +\infty} \operatorname{erf}(x) = 1$ in Eq. (25),

$$\begin{aligned} C^2 &= 2\lambda C \left(\frac{1}{8\pi Dr} + K \right) \\ \Leftrightarrow \frac{C}{2\lambda} - \frac{1}{8\pi Dr} &= K \end{aligned} \quad (26)$$

We can finally compute $G(r, t)$:

$$\begin{aligned} G(r, t) &= 2\lambda C \left(-\frac{\operatorname{erf}\left(\frac{r}{\sqrt{8tD}}\right)}{8\pi Dr} + \frac{C}{2\lambda} + \frac{1}{8\pi Dr} \right) \\ &= \frac{\lambda C}{4\pi Dr} \left\{ 1 - \operatorname{erf}\left(\frac{r}{\sqrt{8tD}}\right) \right\} + C^2 \\ \Leftrightarrow g(r, t) &= \frac{\lambda}{4D\pi r C} \left\{ 1 - \operatorname{erf}\left(\frac{r}{\sqrt{8tD}}\right) \right\} + 1. \end{aligned} \quad (27)$$

Proof of eq. 7

We can integrate the pcf formula to compute Ripley's K -function, as $g(r) = \frac{K'(r)}{4\pi r^2}$.

With advection From eq. 21,

$$K(\rho) = 4\pi \int_0^\rho r^2 + \frac{\lambda}{2\pi C} \left[\frac{r}{2D} + \frac{\sqrt{\gamma} r^2 \arctan\left(\frac{\sqrt{\gamma} r}{\sqrt{2D}}\right)}{2\sqrt{2D}\sqrt{D}} - \frac{\sqrt{\gamma} \pi r^2}{4\sqrt{2D}\sqrt{D}} \right] dr. \quad (28)$$

We define $A = \int_0^\rho r^2 dr$, $B = \int_0^\rho \frac{r}{2D} dr$, $C = \int_0^\rho r^2 \arctan\left(\frac{\sqrt{\gamma} r}{\sqrt{2D}}\right) dr$ and $E = \int_0^\rho \frac{\sqrt{\gamma} \pi r^2}{4\sqrt{2D}\sqrt{D}} dr$.

$$\begin{aligned} A &= \frac{1}{3} \rho^3 \\ B &= \frac{\rho^2}{4D} \\ E &= \frac{\sqrt{\gamma} \pi \rho^3}{12\sqrt{2D}\sqrt{D}} \end{aligned} \quad (29)$$

We can also compute $C = \int_0^\rho r^2 \arctan\left(\frac{\sqrt{\gamma} r}{\sqrt{2D}}\right) dr$. We can first change variable, with $u = \frac{r}{\sqrt{2D}}$, $dr = \sqrt{2D} du$.

$$\begin{aligned} C &= \int_0^{\rho/\sqrt{2D}} (\sqrt{2D} u)^2 \arctan(\sqrt{\gamma} u) \sqrt{2D} du \\ &= (2D)^{3/2} \int_0^{\rho/\sqrt{2D}} u^2 \arctan(\sqrt{\gamma} u) du \end{aligned} \quad (30)$$

We can integrate by parts, with $f = \arctan(\sqrt{\gamma} u)$ and $g' = u^2$.

$$\begin{aligned} C &= (2D)^{3/2} \left(\frac{\rho^3}{3(2D)^{3/2}} \arctan(\sqrt{\frac{\gamma}{2D}} \rho) - \int_0^{\rho/\sqrt{2D}} \frac{\sqrt{\gamma} u^3}{3(\gamma u^2 + 1)} du \right) \\ &= (2D)^{3/2} \left(\frac{\rho^3}{3(2D)^{3/2}} \arctan(\sqrt{\frac{\gamma}{2D}} \rho) - \frac{\sqrt{\gamma}}{3} \int_0^{\rho/\sqrt{2D}} \frac{u^3}{(\gamma u^2 + 1)} du \right) \end{aligned} \quad (31)$$

We can substitute $v = \gamma u^2 + 1$, $du = \frac{1}{2\gamma u} dv$.

$$\begin{aligned}
\int_0^{\rho/\sqrt{2D}} \frac{u^3}{(\gamma u^2 + 1)} du &= \frac{1}{2\gamma^2} \int_1^{\gamma \rho^2/2D+1} \frac{v-1}{v} dv \\
&= \frac{1}{2\gamma^2} \int_1^{\gamma \rho^2/2D+1} 1 - \frac{1}{v} dv \\
&= \frac{1}{2\gamma^2} (\gamma \frac{\rho^2}{2D} - \log(\gamma \frac{\rho^2}{2D} + 1))
\end{aligned} \tag{32}$$

Going back to C, we obtain:

$$\begin{aligned}
C &= \frac{\rho^3 \arctan(\sqrt{\frac{\gamma}{2D}} \rho)}{3} - (2D)^{3/2} \frac{\sqrt{\gamma}}{3} \frac{1}{2\gamma^2} \left(\frac{\gamma}{2D} \rho^2 - \log(\gamma \frac{\rho^2}{2D} + 1) \right) \\
&= \frac{\rho^3 \arctan(\sqrt{\frac{\gamma}{2D}} \rho)}{3} - \frac{\sqrt{2D}}{6\sqrt{\gamma}} \rho^2 + \frac{\sqrt{2D}^{3/2}}{3\gamma^{3/2}} \log(\gamma \frac{\rho^2}{2D} + 1).
\end{aligned} \tag{33}$$

Combining all equations:

$$\begin{aligned}
K(\rho) &= \frac{4}{3} \pi \rho^3 + \frac{2\lambda}{C} \left(\frac{\rho^2}{4D} + \frac{\sqrt{\gamma} \rho^3 \arctan(\sqrt{\frac{\gamma}{2D}} \rho)}{6\sqrt{2D}^{3/2}} - \frac{\rho^2}{12D} + \frac{\log(\gamma \frac{\rho^2}{2D} + 1)}{6\gamma} - \frac{\sqrt{\gamma} \pi \rho^3}{12\sqrt{2D}\sqrt{D}} \right) \\
&= \frac{4}{3} \pi \rho^3 + \frac{2\lambda}{C} \left(\frac{\rho^2}{6D} + \frac{\sqrt{\gamma} \rho^3 \arctan(\sqrt{\frac{\gamma}{2D}} \rho)}{6\sqrt{2D}^{3/2}} + \frac{\log(\gamma \frac{\rho^2}{2D} + 1)}{6\gamma} - \frac{\sqrt{\gamma} \pi \rho^3}{12\sqrt{2D}\sqrt{D}} \right).
\end{aligned} \tag{34}$$

Without advection From eq. 27,

$$\begin{aligned}
K(\rho) &= \frac{\lambda}{DC} \int_0^\rho r \left\{ 1 - \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) \right\} + 4\pi r^2 dr \\
&= \frac{\lambda}{CD} \left(\frac{\rho^2}{2} - \int_0^\rho r \times \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) dr \right) + \frac{4}{3} \pi \rho^3
\end{aligned} \tag{35}$$

We first compute the primitive for $\int_0^\rho r \times \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) dr$. We define $u = \frac{r}{\sqrt{8Dt}}$, $dr = \sqrt{8Dt} du$.

$$\int_0^\rho r \times \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) dr = 8Dt \int_0^{\rho/\sqrt{8Dt}} u \times \operatorname{erf}(u) du \tag{36}$$

We can integrate by parts, with $f = \operatorname{erf}(u)$ and $g' = u$.

$$8Dt \int_0^{\rho/\sqrt{8Dt}} u \times \operatorname{erf}(u) du = 8Dt \left(\frac{\rho^2}{2} \frac{1}{8Dt} \operatorname{erf} \left(\frac{\rho}{\sqrt{8Dt}} \right) - \frac{1}{\sqrt{\pi}} \int_0^{\rho/\sqrt{8Dt}} u^2 e^{-u^2} du \right) \tag{37}$$

We integrate by parts again, this time with $f = u$ and $g' = u e^{-u^2}$, which leads to

$$\int u^2 e^{-u^2} du = -\frac{u e^{-u^2}}{2} + \frac{1}{2} \int e^{-u^2} du = -\frac{u e^{-u^2}}{2} + \frac{\sqrt{\pi} \operatorname{erf}(u)}{4} \tag{38}$$

If we use eq. 38 in eq. 37:

$$\begin{aligned}
8Dt \int_0^{\rho/\sqrt{8Dt}} u \times \operatorname{erf}(u) du &= 8Dt \left(\frac{\rho^2}{2} \frac{1}{8Dt} \operatorname{erf} \left(\frac{\rho}{\sqrt{8Dt}} \right) - \frac{\operatorname{erf}(\frac{\rho}{\sqrt{8Dt}})}{4} + \frac{1}{2\sqrt{\pi}} \frac{\rho}{\sqrt{8Dt}} e^{-\rho^2/8Dt} \right) \\
\Leftrightarrow \int_0^\rho r \times \operatorname{erf} \left(\frac{r}{\sqrt{8Dt}} \right) dr &= \frac{1}{2} \operatorname{erf} \left(\frac{\rho}{\sqrt{8Dt}} \right) (\rho^2 - 4Dt) + \frac{\sqrt{2Dt}}{\sqrt{\pi}} \rho e^{-\rho^2/8Dt}
\end{aligned} \tag{39}$$

We can now compute $K(\rho)$:

$$K(\rho) = \frac{\lambda}{CD} \left(\frac{\rho^2}{2} - \frac{1}{2} \operatorname{erf}\left(\frac{\rho}{\sqrt{8Dt}}\right)(\rho^2 - 4Dt) - \frac{\sqrt{2Dt}\rho}{\sqrt{\pi}} e^{-\rho^2/8Dt} \right) + \frac{4}{3}\pi\rho^3. \quad (40)$$

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