

Pfd
$$\int su \, \overline{U_r}^2 = -T + mg \cos \theta$$
 (a) $\int su \, \overline{U_\theta}^2 = -mg \sin \theta$ (b)

m
$$l \dot{\theta}(H) \dot{\theta}(H) = -mg \sin \theta(H) \cdot \dot{\theta}(H)$$

$$\frac{d}{dt} \left(\frac{1}{z} l \dot{\theta}(H)^2\right) = -d_t \left(-g \cos \theta(H)\right)$$

$$= \sum_{i=0}^{\infty} \left[\frac{1}{2} \theta \hat{l} \hat{t} \right]_{t=0}^{t} = \left[\frac{1}{2} \theta \hat{l$$

$$=) \cdot (\theta^2 = 2g \cos \theta - 2g + \frac{v_0^2}{e})$$

$$-2mg\cos\theta + 2mg - m\frac{Vo^2}{e} = -T + mg\cos\theta$$

$$= T = 3 \text{mgcos} \theta - 2 \text{mg} + \text{m} \frac{V_0^2}{\theta}$$

La corde seea toujours tendu si Test > 0 quand 0=T.

$$T(\theta=\pi)>0 \Rightarrow -3\text{ ong}-2\text{ ong}+\text{m}\frac{vo^2}{\rho}>0$$

$$= \frac{1}{2} \cdot \frac{$$