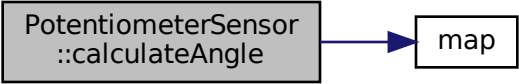


PotentiometerSensor  
::calculateAngle



```
graph LR; A[PotentiometerSensor::calculateAngle] --> B[map]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'PotentiometerSensor' on the top line and '::calculateAngle' on the bottom line. The right box is white with a black border and contains the text 'map'. A blue arrow points from the right side of the gray box to the left side of the white box.

map