Servo-moteur :

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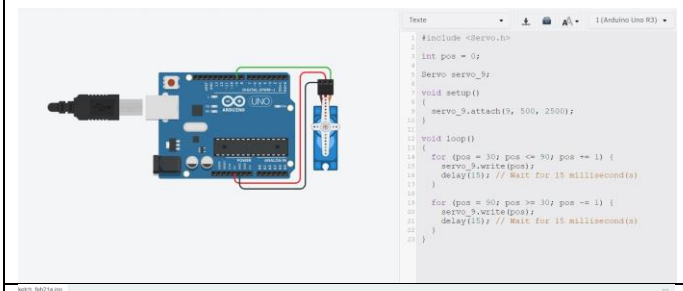
<td> 
</td>
<td>Dutrannois Esteban
Dubois Théo</td>
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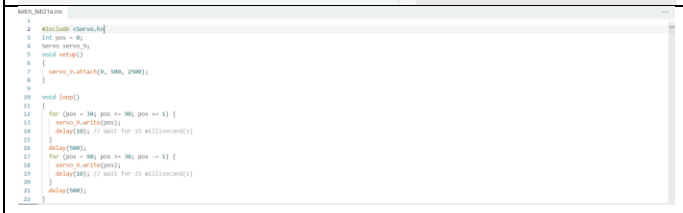
<td> 
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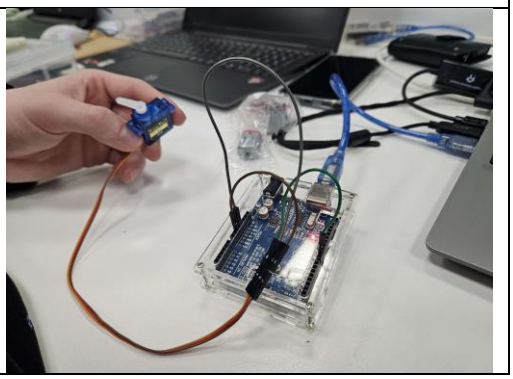
<td>  </td>
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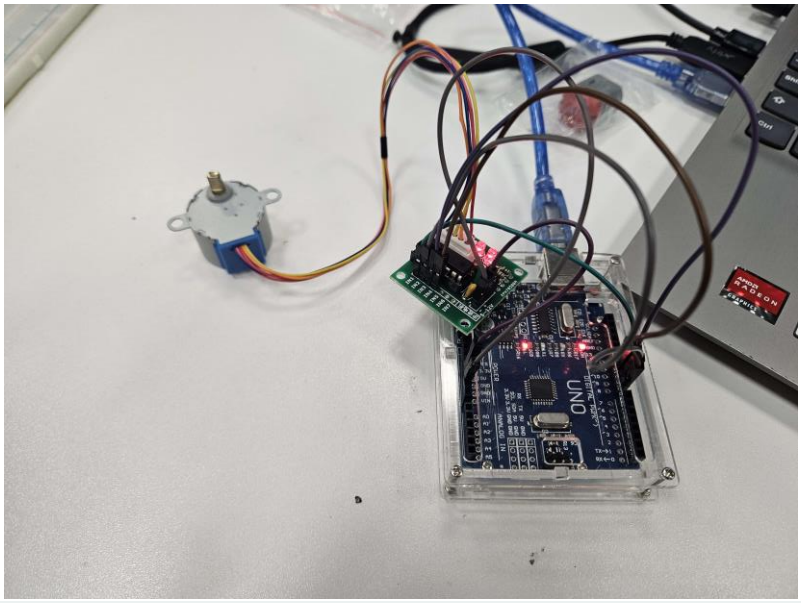
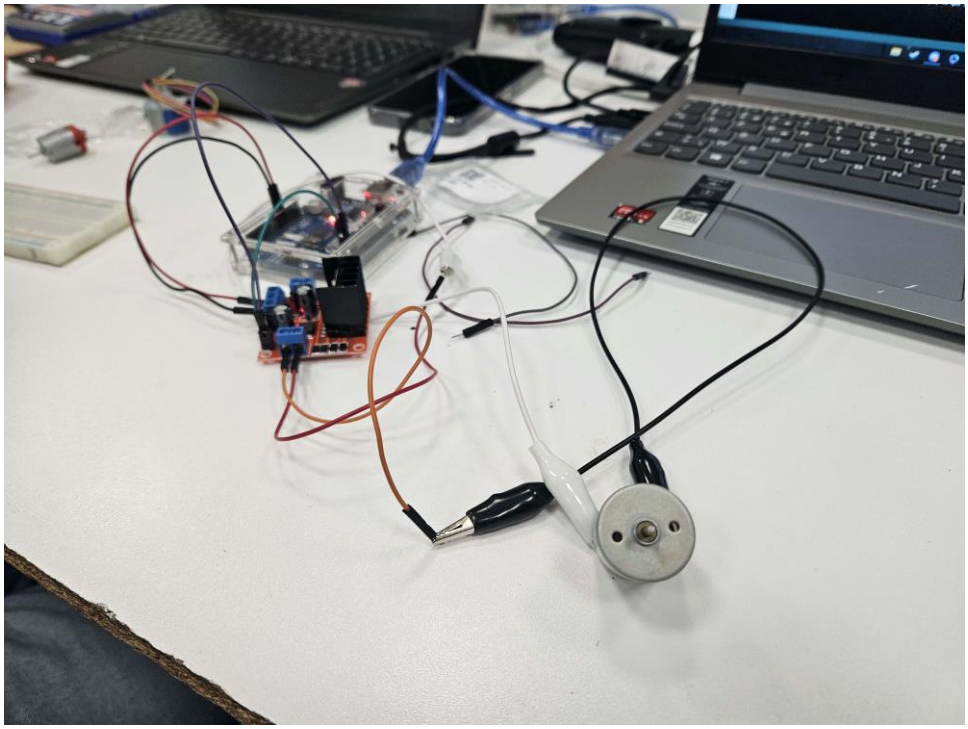
Moteur pas à pas :



```ino
#include <Stepper.h>

const int stepsPerRevolution = 200;  // change this to fit the number of steps per revolution
// for your motor

// initialize the stepper library on pins 8 through 11:
Stepper myStepper(stepsPerRevolution, 8, 9, 10, 11);

void setup() {
  // set the speed at 60 rpm:
  myStepper.setSpeed(1);
  // initialize the serial port:
  Serial.begin(9600);
}

void loop() {
  // step one revolution  in one direction:
  Serial.println("clockwise");
  myStepper.step(stepsPerRevolution);
  delay(500);

  // step one revolution in the other direction:
  Serial.println("counterclockwise");
  myStepper.step(-stepsPerRevolution);
  delay(500);
}
```

Moteur DC:



stepper_oneRevolution.ino

```ino
int motorPin = 3;
int motorPin2 = 4;


void setup() {

}

void loop() {
  digitalWrite(motorPin, HIGH);
  delay(500);
  digitalWrite(motorPin, LOW);
  digitalWrite(motorPin2, HIGH);
  delay(500);
  digitalWrite(motorPin2, LOW);


}
```