

What is Independent Component Analysis (ICA)?

- ☐ Is a computational method used for separating a multivariate signal into subcomponents.
 - Multivariate signal: a signal that consists of distinguishable components.
 - Equation: dimension M consists of M scalar signals

$$[x_{I}(n), x_{2}(n),, x_{M}(n), n = 0,1,...N]$$

- Examples: images along the columns (rows)
- ☐ ICA simplifies complex data into manageable pieces

Abstract

Focus of are Group project:

☐ separate wave data made of various overlain waves using ICA

Scenario:

Group conversation among colleagues, differentiate individual voices

Plan:

☐ Use matrices, mathematical equations, and python code



List of Methodology

I. Center X

- subtracting the mean
- o center the data around o
- subtract the mean from each dimension
- add it back to the estimation of S at the end of the problem.

2. Whitening

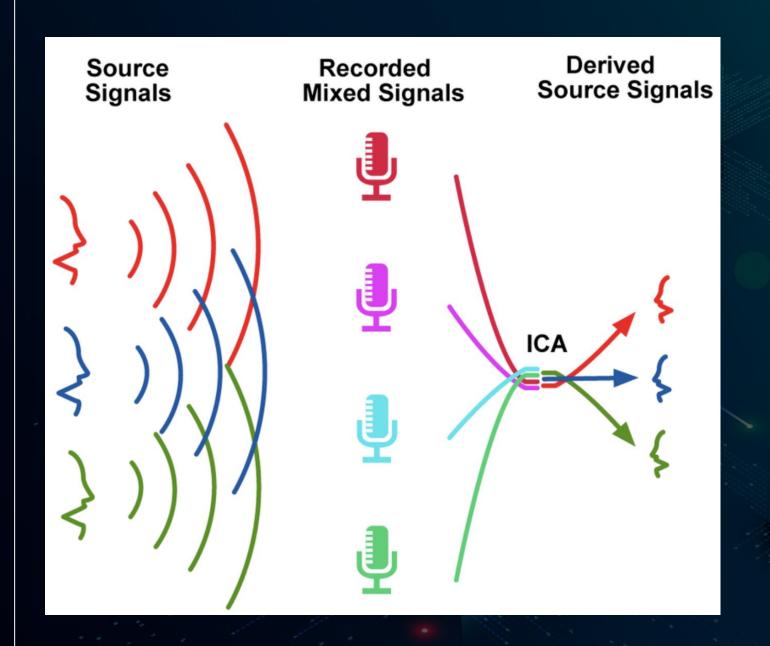
- transform data to remove any possible correlation
- transform X into X(hat).

3. Select a value

o select random initial value for the de-mixing matrix W.

4. Calculate

- o new value of W
- 5. Normalize
- $\sim W$
- 6. Check
- o If Algorithm has or has not converged
- 7. Dot Product
- after sufficient loops take the dot product of W and x to receive independent source signals



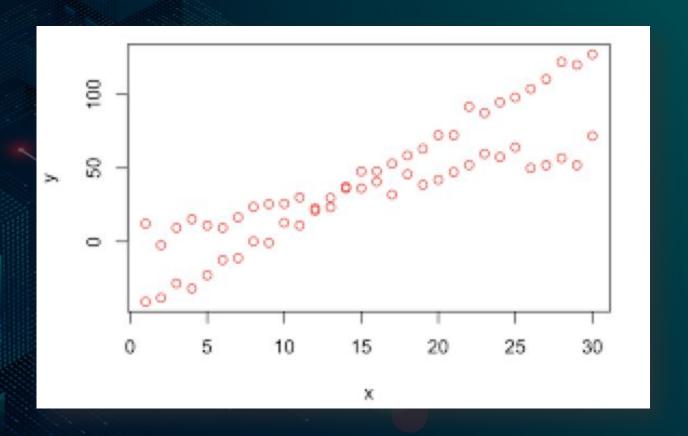
End Goal

separate the signals into individual components

Experiment

Step 1: Center X

☐ Select data source at the center that is around zero



Experiment

Step 2: Whitening

Whiten data to remove correlations.

- ☐ Transform X to X(hat)
- Whitened Signal of covariance matrix = identity matrix
- □ Decompose of CovarianceMatrix = eigenvalue of x-hat
- ☐ D = Diagonal matrix of eigenvalues

$$I_1 = [\, 1\,], \; I_2 = \left[egin{array}{cccc} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{array}
ight], \; \cdots, \; I_n = \left[egin{array}{cccc} 1 & 0 & 0 & \cdots & 0 \ 0 & 1 & 0 & \cdots & 0 \ 0 & 0 & 1 & \cdots & 0 \ \vdots & dots & dots & \ddots & dots \ 0 & 0 & 0 & \cdots & 1 \end{array}
ight].$$

$$\tilde{x} = ED^{-1/2}E^T x$$

$$D = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots \\ 0 & \lambda_2 & 0 & \dots \\ 0 & 0 & \lambda_3 & \dots \\ \dots & \dots & \dots \end{pmatrix}$$

for 1 to the number of components:

repeat until $w_p^T w_{p+1} \approx 1$:

$$w_{p} = \frac{1}{n} \sum_{i}^{n} Xg(W^{T}X) - \frac{1}{n} \sum_{i}^{n} g'(W^{TX})W$$

$$w_p = w_p - \sum_{j=1}^{p-1} (w_p^T w_j) w_j$$

$$w_p = \frac{w_p}{\|w_p\|}$$

$$W = [w1, w2...]$$

$$g(u) = \tanh(u)$$

$$g'(u) = 1 - \tanh^2(u)$$

Experiment

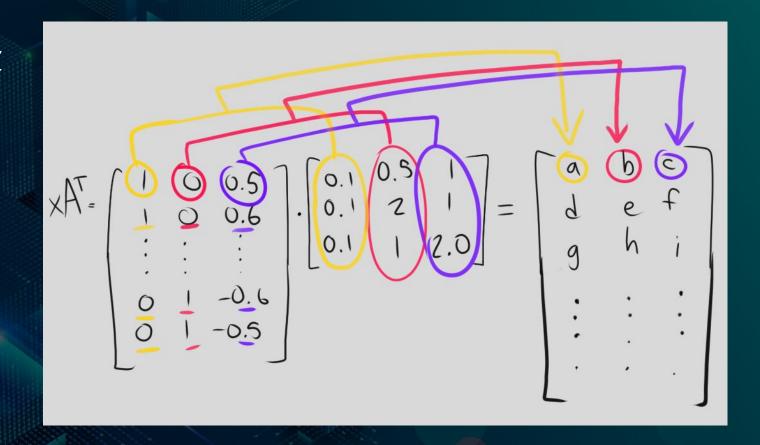
Step 3-6: Select value, Calculate, Normalize, & Check

- □Determine W
- □Calculate new value for W
- ■Normalize W
- □Check for convergence

Experiment

Step 7: Dot Product

- ☐ Take the Dot
 Product of W and X
- Results in independent signal sources





Code

201

202

203

204

205

207

208

209

210 211

212

213

214

215

216 217

218

219

220

221

222

224

225

227 228 229

230

231

233

235

236

237

238

- ☐ Code written in Python
- □ Output
 - >three wave signals
- ☐ Artificially mixes the wave signals together, to be later re-separated.

```
#Create the wave signals
sl = np.sin(2 * time) #sinusoidal
s2 = np.sign(np.sin(3 * time)) # square signal
s3 = signal.sawtooth(2 * np.pi * time) #saw tooth signal
print("sl = \n", sl)
print()
print("s2 = \n", s2)
print()
print("s3 = \n", s3)
print()
# Compute dot product of matrix A and the signals
# this will give us a combination of all three
# Then, use ICA to separate the mixed signal into the three
# original source signals
#np.c is a special type of np.r
#np.r Translates slice objects to concatenation along the first axis.
#np.c is a variation of that adds column vectors to each other, in first-to-last order.
#therefore, np.c [sl, s2, s3] means add the signals as columns to the matrix X!
X = np.c [s1, s2, s3]
print("X = ", X)
print()
#this A matrix is mostly arbitrary. Its only purpose is to mix up the X matrix data.
A = np.array(([[0.1, 0.1, 0.1], [1, 2, 1.0], [1, 1, 2.0]]))
#np.dot(X, A.T) means take the dot product of X and A.T (the transpose of A)
X = np.dot(X, A.T)
print("X*A.T = ", X)
print()
#X.T means get the transpose matrix of X
X = X.T
print ("X = X.T => ", X)
print()
```

Code

☐ Whitening

Calculation of W

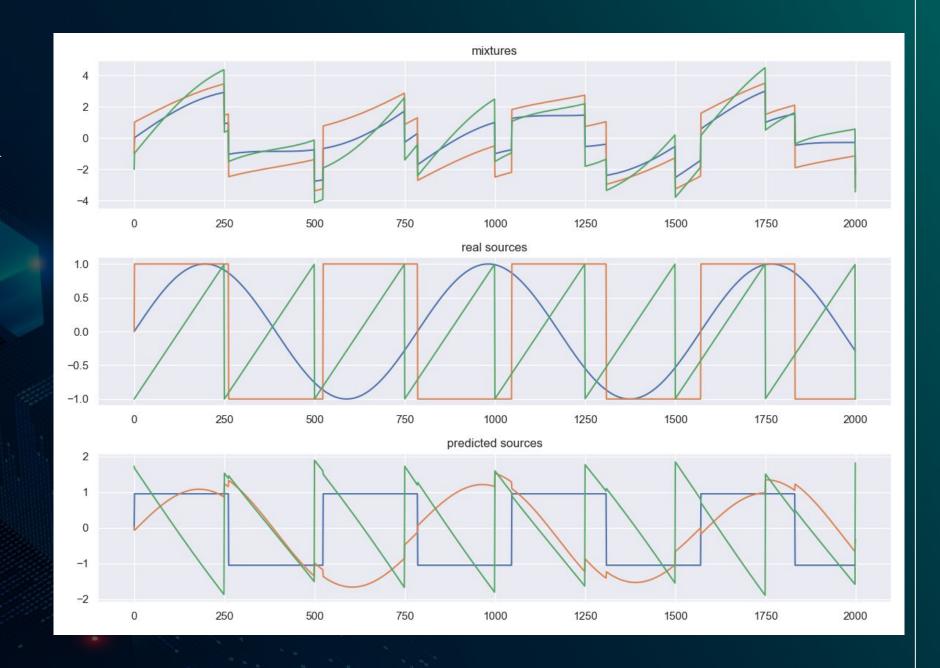
```
63
     def whitening (X):
64
           cov = np.cov(X)
65
66
           freturn to d, E these values:
67
           #d will receive the eigenvalues in ascending order, each repeated according to its multiplicity
           #multiplicity of an eigenvalue is the number of times it appears as a root of
69
           #the characteristic polynomial (ex.: the polynomial whose roots are the eigenvalues of a matrix)
           #polynomial being an expression such as: P(x) = 2x^2 - 6x + 12
71
           #meanwhile, E receives
73
74
           d, E = np.linalg.eigh(cov)
75
76
           #D shall be a diagonal matrix of eigenvalues (every lambda is an eigenvalue of the covariance matrix)
77
           D = np.diag(d)
78
79
           D inv = np.sqrt(np.linalg.inv(D))
80
81
           X whiten = np.dot(E, np.dot(D inv, np.dot(E.T, X)))
82
83
           return X whiten
84
85
       # update the de-mixing matrix W
86
87
     def calculate new w(w, X):
88
           w \text{ new} = (X * g(np.dot(w.T, X))).mean(axis=1) - g der(np.dot(w.T, X)).mean() * w
89
90
           w new /= np.sqrt((w new ** 2).sum())
92
           return w new
```

Results

```
PS C:\Users\corey\Desktop\CSE 5350 Final> python ./CSE_5350_Final_Project_v5_x.py
Running... Please wait...
s1 =
              0.00800392 0.01600732 ... -0.27253687 -0.28022907
 ΓΟ.
-0.287903321
s2 =
 [0. 1. 1. ... -1. -1. -1.]
s3 =
Γ-1.
           -0.991996 -0.983992 ... 0.983992 0.991996 -1.
X = [ ] 0.
  0.00800392 1.
                        -0.991996
  0.01600732 1.
                        -0.983992
 -0.27253687 -1.
                         0.983992
 -0.28022907 -1.
                         0.991996
 [-0.28790332 -1.
X*A.T = [[-1.00000000e-01 -1.00000000e+00 -2.00000000e+00]]
 [ 1.60079185e-03  1.01600792e+00 -9.75988079e-01]
 [-2.88544871e-02 -1.28854487e+00 6.95447125e-01]
 -2.88233070e-02 -1.28823307e+00 7.03762928e-011
 [-2.28790332e-01 -3.28790332e+00 -3.28790332e+00]]
X = X.T =  [-1.00000000e-01  1.60079185e-03  3.20153243e-03  ... -2.88544871e-02
  -2.88233070e-02 -2.28790332e-01]
 [-1.00000000e+00 1.01600792e+00 1.03201532e+00 ... -1.28854487e+00
  -1.28823307e+00 -3.28790332e+001
 [-2.00000000e+00 -9.75988079e-01 -9.51976672e-01 ... 6.95447125e-01
   7.03762928e-01 -3.28790332e+00]]
```

Results

- ☐ Graphs were plotted using Python Matplotlib library
- ☐ Three wave signals are generated
 - Sine wave
 - Square wave
 - Sawtooth wave
- ☐ Solved by ICA function
 - The three signals are re-separated



Conclusions

- x Matrix was our signal matrix
- After mixing and then de-mixing, Signals switched spots
- □ ICA algorithm successful, but produced signals in an unpredictable order
- ☐ Based on initial mixing matrix, S.
- ☐ Why did this happen?
- "Even when the sources are not independent, ICA finds a space where they are maximally independent." This could hint that ICA's primary focus is not on preserving signal order, or column order in the resulting de-mixed signal matrix, but rather, it focuses on maximizing the clarity and independence of each individual signal, regardless of the order they were initially in.
- ☐ Another algorithm would be needed after ICA to label all independent signals in the correct manner.

