

1.

Figure 1: Rendering of the CAD model

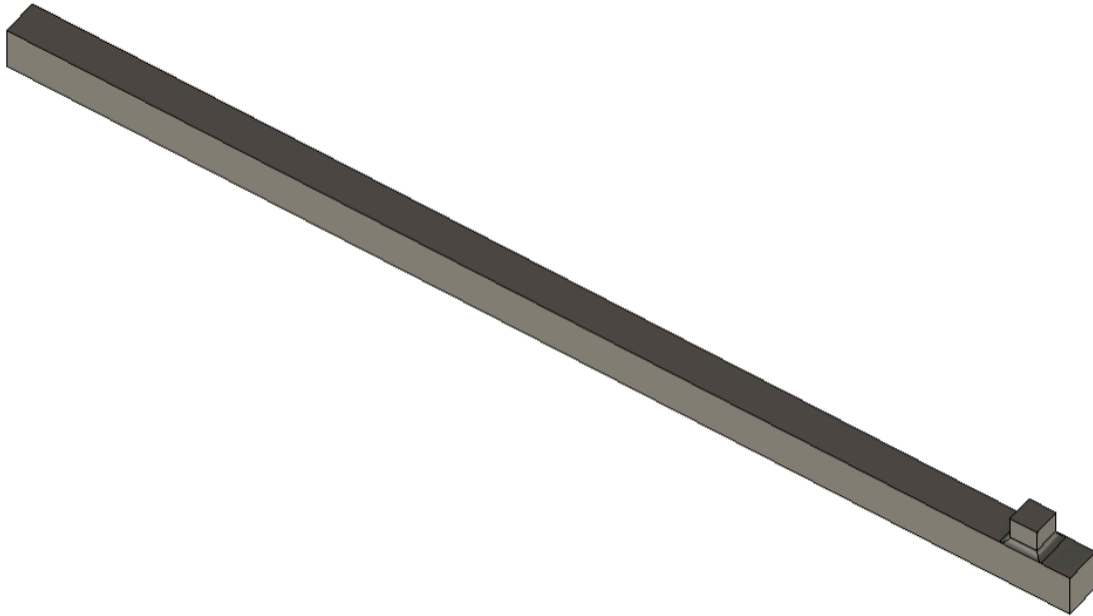


Figure 2: L=14 length of the torque wrench

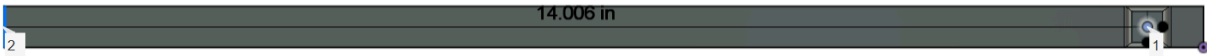


Figure 3: b=0.6 thickness of the torque wrench

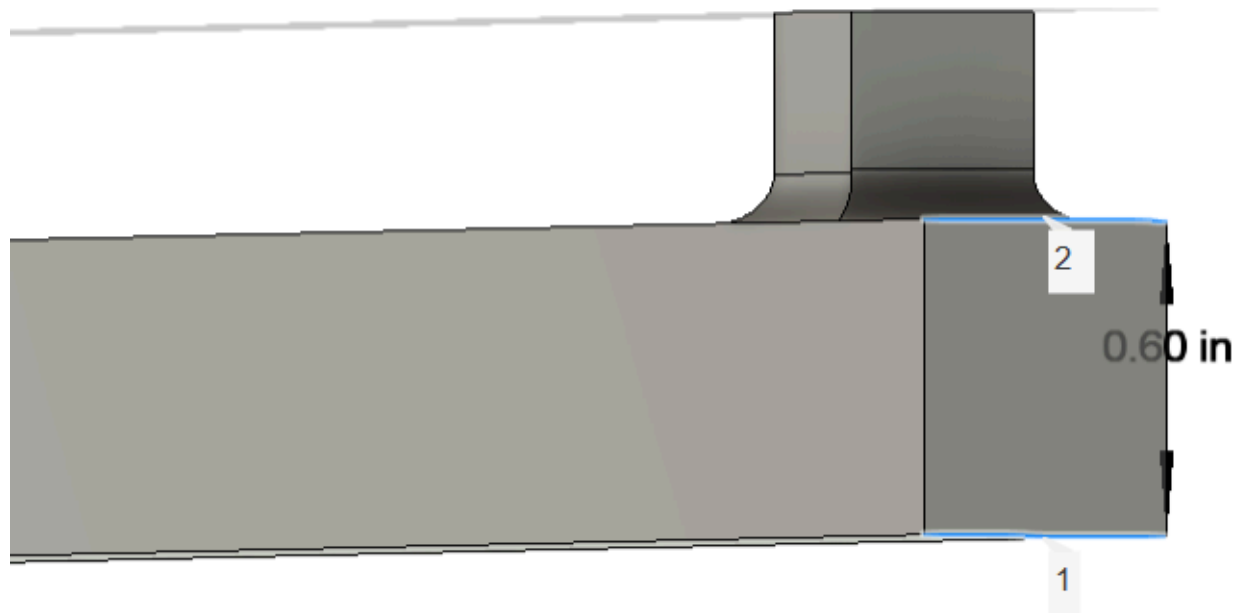


Figure 4: $h=0.5$ width of the torque wrench

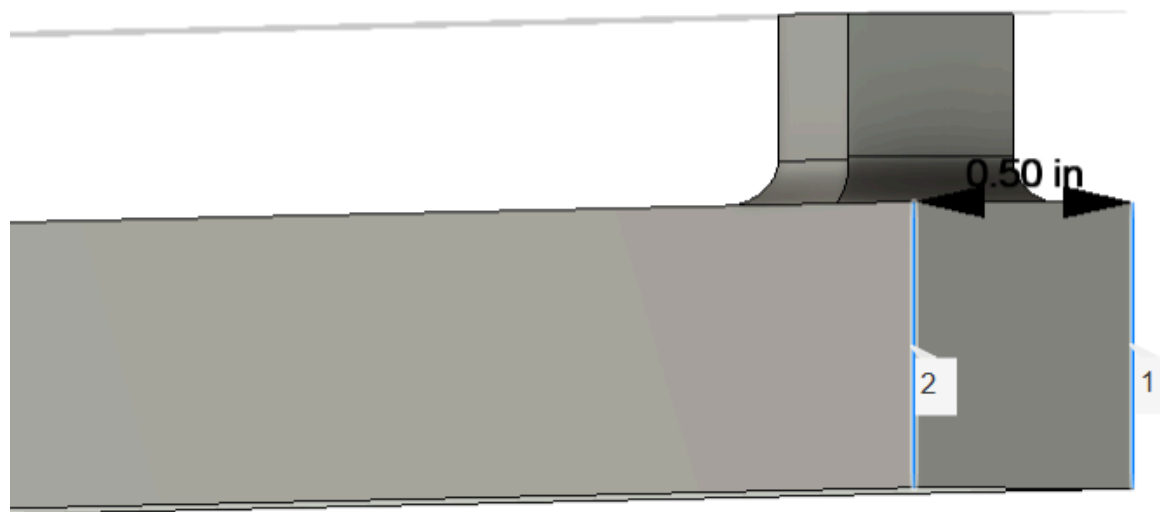
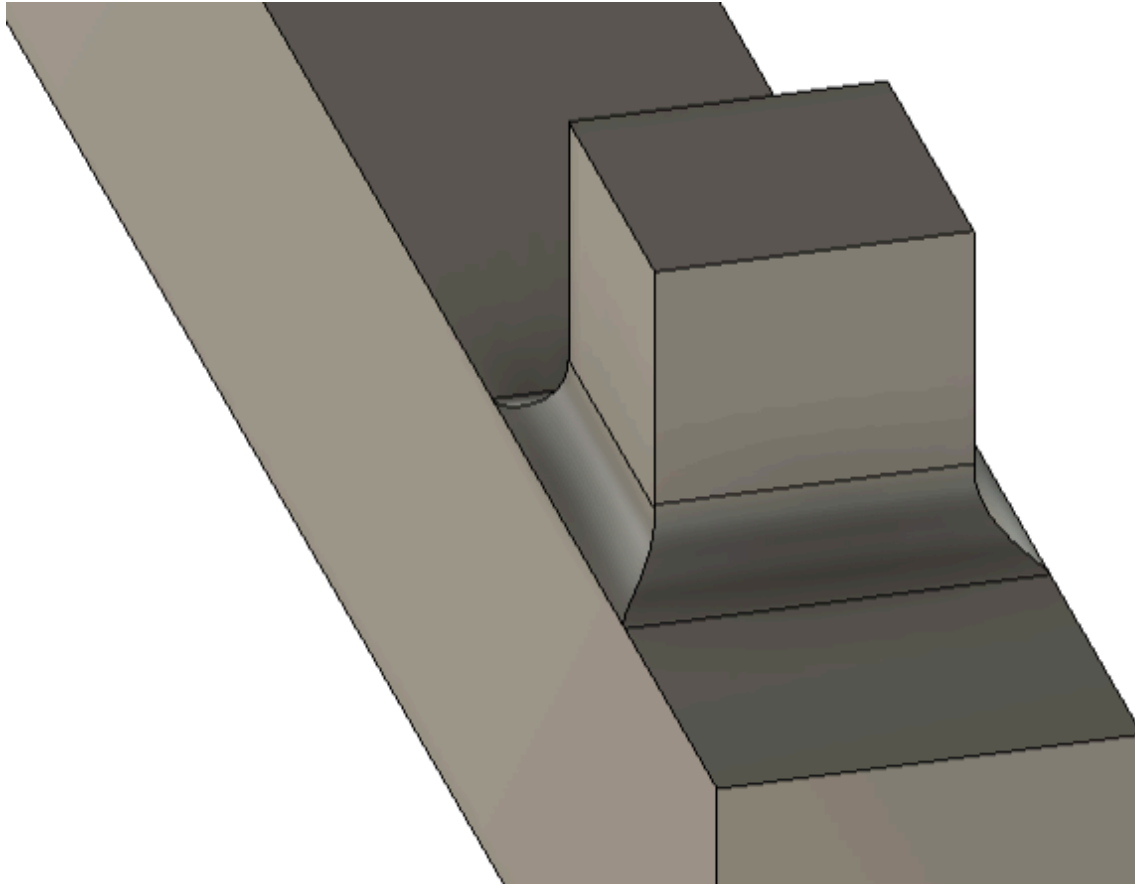


Figure 5: 0.05 fillet between the drive and the shaft

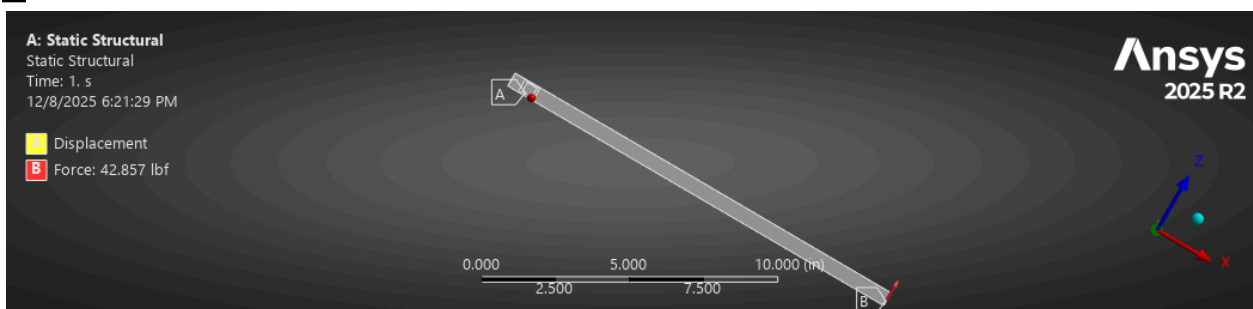


2.

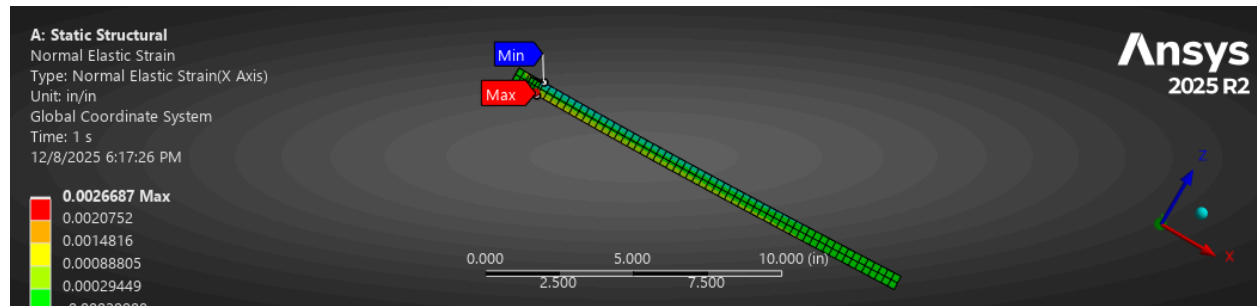
Ti-10V-2Fe-3Al is a premium titanium alloy with high tensile/yield strength, good ductility, good fatigue resistance, and high fracture toughness. In addition to all of these traits, it is significantly lighter per volume than steel. This is common in applications where weight, strength, fatigue, and toughness all matter especially in aerospace or high performance forged components. This material is a strong balance of properties. The material properties from GRANTA are:

- Young's modulus: 17.3×10^6 psi
- Poisson's ratio: 0.32
- Tensile strength: 157×10^3 psi
- Fatigue strength: 91×10^3 psi
- Fracture toughness: 115×10^3 psi·√in

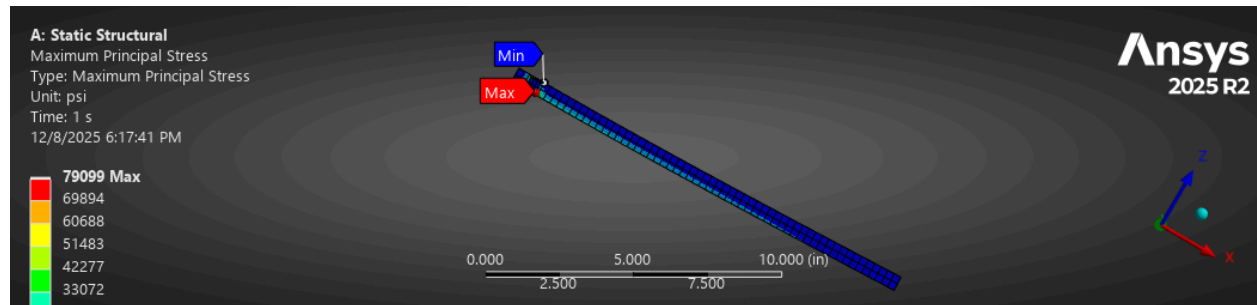
3.



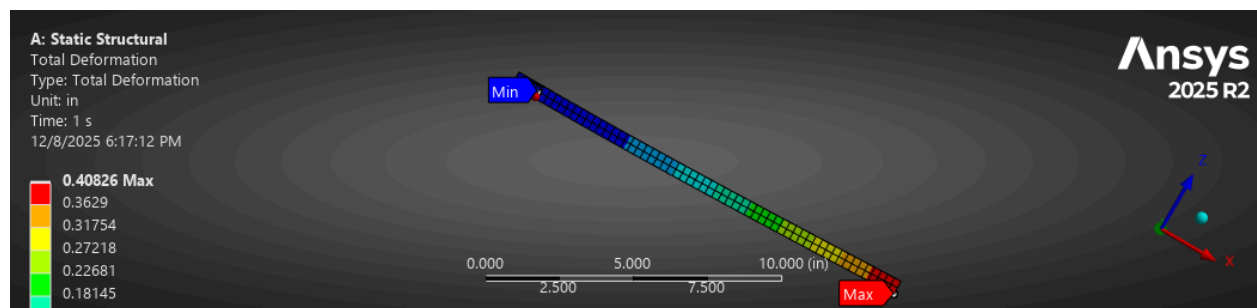
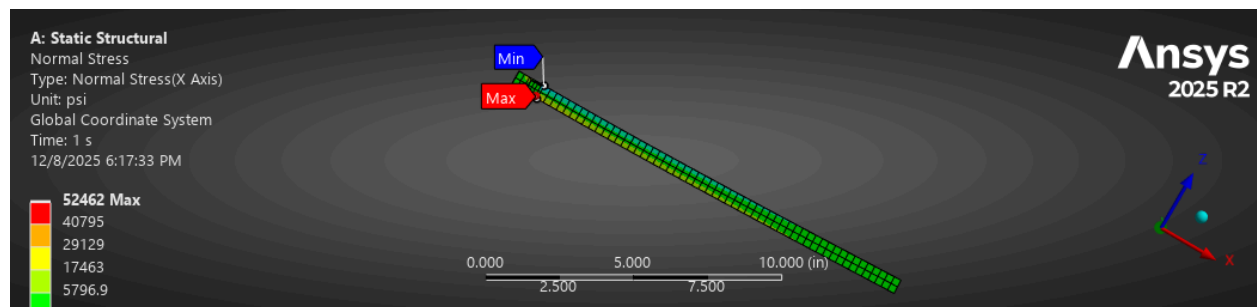
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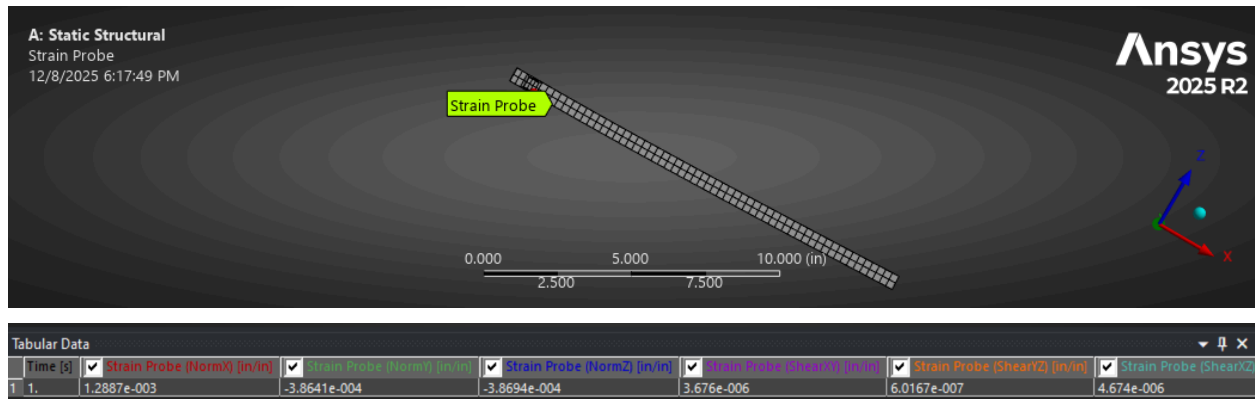


5.



6.





7. Torque Wrench Sensitivity: 1.2887

8.

The torque wrench uses a half-bridge strain gauge configuration, incorporating two active gauges in a Wheatstone bridge. Each strain gauge is positioned at a distance $c = 1$ in from the drive. The selected gauge is the Micro-Measurements CEA-XX-250UWA-120, a uniaxial linear pattern gauge with a $120\ \Omega$ nominal resistance and a 0.25 inch gauge length. Its compact package size (0.45 in long and 0.18 in wide) works for our design. It works to be bonded to the handle because of the 0.6 thickness.

```
material = 'Ti-10V-2Fe-3Al'
d = 0.3625
s_max = 2.4000e+04
X_o = 6.5417
X_s = 4.7917
X_K = 9.5501
sn_gauge = 0.0013
output = 0.0013
```