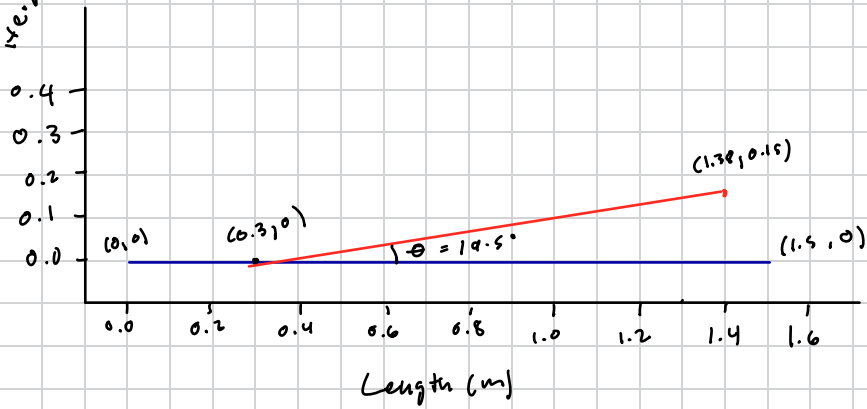


Portfolio sketch HW 4

Actuator:
Robotics IMASS R200



Discussion: The actuator I used was IMASS R200

The angle was $\theta = 19.5^\circ$