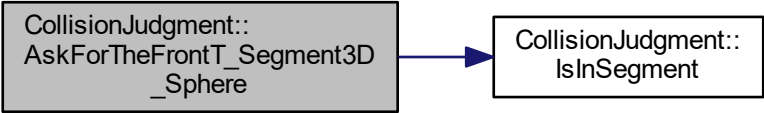


CollisionJudgment::
AskForTheFrontT_Segment3D
_Sphere



```
graph LR; A["CollisionJudgment::  
AskForTheFrontT_Segment3D  
_Sphere"] --> B["CollisionJudgment::  
IsInSegment"]
```

CollisionJudgment::
IsInSegment