Project Planning of Software for a Writing Robot

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Software Description

This software is aimed to generate a G-code to the writing robot for writing the text which is read from a file. The G-code will be executed by the writing robot and draw the text on the paper.

The text which needs to be ‘draw out’ is input to the software by saving as a file. The output G-code will be sent to the control unit of the writing robot (Arduino in this case) using a virtual RS232 serial port.

In this software, some font data and open-source libraries will be used, for example, an additional font file contains the pre-defined G code for each character will be required. The RS232 serial port communication will be handled by a RS232 library.

For the serial port communication, before sending more G-code, the software will wait until receiving the acknowledge signal from the Arduino.

The software interface with user will be a console window. The communication code and possible errors during the process will be displayed on this console window.

Function Declarations

int generateFontIndex(FILE \*filepointer, int fontGcodeLineIndex[ ]);

Parameters:

filepointer: file pointer of the font g code file;

fontGcodeLineIndex: an array with size of 256 (equal to double size of ascii table), this stores the start line and end line number of each character G-code;

Return value: 1 for success, 0 for failed.

int WaitForWakeUp(void);

Parameters:

Return value: always 0.

int updateGcodeTargetPosition(int gcodeLineNum, int currentXOffset, int currentYOffset, char gCodeCommand[ ], int lastTimeReturnValue);

Parameters:

gcodeLineNum: current line number of fonts data;

currentXOffset: x axis start point of current character to the machine axes;

currentYOffset: y axis start point of current character to the machine axes;

gCodeCommand[ ]: return g code command for current step;

lastTimeReturnValue: determine if need to export Z axis move command;

Return value: 1 for no pen move up/down and head to next line, 0 for has pen move up/down and keep at same line

int WaitForReply(void);

Parameters:

Return value: always 0.

int updateCharactorOffsetPosition(int \*tempOffsetX, int \*tempOffsetY);

Parameters:

\*tempOffsetX: the offset position X needs to update;

\*tempOffsetY: the offset position Y needs to update;

Return value: 1 for success, 0 for failed.

Key Data Items

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| --- | --- | --- |
| Name | Data type | Rationale |
|  |  |  |
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|  |  |  |

Test Information

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| --- | --- | --- | --- |
| Function | Test Case | Test Data | Expected Output |
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|  |  |  |  |

Flowcharts

