

1)  $G(s) = K \frac{1}{(s+1)^2} \Rightarrow 20 = 20 \log K$

~~K=10~~

$K = 10$

$G(s) = \frac{10}{(s+1)^2} = \frac{10}{s^2 + 2s + 1}$

$X = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$

$\hat{y}(s) = G(s) \hat{u}(s)$

$\begin{cases} \dot{X} = AX + BU \\ y = CX + DU \end{cases}$

$X = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} X + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$

$y = [10 \ 0] X + [0] u$

$y_1 = -y_1 - 2y_2 + u$

$y = 10y_1, \quad y_1 = \frac{y}{10}$

$\frac{y}{10} + 2\frac{y}{10} + \frac{1y}{10} = u$

b)  $\hat{U}(s) = \hat{r}(s) - K\hat{x}(s)$

~~$\begin{cases} \dot{X} = AX + B(\hat{r}(s) - KX) \\ y = CX \end{cases} \Rightarrow \begin{cases} \dot{X} = AX + B(r - KX) \\ \hat{y} = C\hat{x} \end{cases} X$~~

$\hat{U}(s) = \hat{r}(s) - K\hat{x}(s) \Rightarrow u(t) = r(t) - Kx(t)$

$\Rightarrow \begin{cases} \dot{X} = AX + B(r - KX) \\ y = CX + D(r - KX) \end{cases} \Rightarrow \begin{cases} \dot{X} = (A - BK)X + Br \\ y = (C - DK)X + Dr \end{cases}$

Impondo que  $r(t) = 0 \Rightarrow \lim_{t \rightarrow \infty} x(t) = 0$ , ou seja, queremos que

$\hat{y}(s) = \det(sI - (A - BK)) = \text{eq característica do sistema com malha fechada}$

$\begin{bmatrix} 0 & 1 \\ 6 & 5 \end{bmatrix}$

$\Rightarrow \text{polos que queremos}$

por integração

$K = [p_0 - a_0 \quad p_1 - a_1] = [0 - 1 \quad 5 - 2] = [5 \ 3]$

$A - BK = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 5 & 3 \end{bmatrix}$

c)  $F(s) = (C - DK)(sI - (A - BK))^{-1} B + D$

$= [10 \ 0] \begin{bmatrix} s & -1 \\ 6 & s+5 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = [10 \ 0] \cdot \frac{1}{s^2 + 5s + 6} \begin{bmatrix} 1 & 1 \\ 6 & 5 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 6 & 5 \end{bmatrix}$

$= \frac{1}{s^2 + 5s + 6} [10 \ 0] \begin{bmatrix} 1 \\ s \end{bmatrix} = \frac{10}{s^2 + 5s + 6} \Rightarrow \lim_{s \rightarrow 0} \frac{1}{s} \cdot \frac{10}{s^2 + 5s + 6} = \frac{10}{6} \Rightarrow \epsilon_{perm} = 1 - \frac{10}{6} = -\frac{4}{6}$

d) Temos que a eq característica é do tipo:

$F(s) = [10 \ 0] \begin{bmatrix} s & -1 \\ 1+k_1 & s+2+k_2 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{1}{s^2 + (2+k_2)s + (1+k_1)} \cdot [10 \ 0] \begin{bmatrix} s+2+k_2 & 1 \\ -1-k_1 & s \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1-k_1 & -2-k_2 \end{bmatrix}$

$= \frac{1}{s^2 + (2+k_2)s + (1+k_1)} \cdot 10 = \frac{10}{(s+2)(s+p)} \Rightarrow \text{para erro nulo, } F(0) = 1 \Rightarrow 1+k_1 = 10$

$k_1 = 9$

$s^2 + (2+k_2)s + 10 = s^2 + (2+p)k_2 + 2p \quad 2p = 10, p = 5$

$2+k_2 = 2+p = 5$

$\Rightarrow K = [9 \ 5]$

$$(s^2 + 3s + 2)\hat{y} = (s + 3)\hat{u}$$

$$\Rightarrow G(s) = \frac{\hat{y}}{\hat{u}} = \frac{s+3}{s^2+3s+2}$$

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

$$A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$C = [3 \ 1]$$

$$D = [0]$$

$$\hat{y} = G(s)\hat{u}$$

b)  $u(t) = 1 \Rightarrow \hat{u}(s) = \frac{1}{s}$ ,  $\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} s \cdot \frac{1}{s} \cdot \frac{s+3}{s^2+3s+2} = \frac{3}{2} = 1,5$

c)  $u(t) = r(t) - Kx(t)$

$$\Rightarrow \dot{x} = Ax + Bu = Ax + B(r - Kx) = (A - BK)x + Br$$

$$y = Cx + Du = Cx + D(r - Kx) = (C - DK)x + Dr$$

$\xi = \sqrt{2}/2$   $\zeta_{critico} = 1 - \left(\frac{3}{4}\right) \rightarrow F(0)$

$$(A - BK) = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} - \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} K_1 & K_2 \end{bmatrix}$$

sendo  $F(s) = (C - DK)(sI - (A - BK))^{-1}B + D$

$$= [3 \ 1] \left( s \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \right)^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \\ -2K_1 & -3+K_2 \end{bmatrix}$$

$$= [3 \ 1] \begin{bmatrix} s & -1 \\ 2K_1 & s+3+K_2 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{1}{s^2 + (3+K_2)s + 2+K_1} \begin{bmatrix} 3 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} s+3+K_2 \\ -2K_1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \frac{1}{s^2 + (3+K_2)s + (2+K_1)} [3 \ 1] \begin{bmatrix} 1 \\ s \end{bmatrix} = \frac{s+3}{s^2 + (3+K_2)s + (2+K_1)}$$

Queremos  $\xi = \sqrt{2}/2$  e  $F(0) = \frac{3}{4} = \frac{3}{2+K_1} \Rightarrow 4 = 2 + K_1 \Rightarrow K_1 = 2$

$$\omega_N^2 = 4 \Rightarrow \omega_N = 2$$

$$(3 + K_2) = 2 \cdot \frac{\sqrt{2}}{2} \cdot 2 \Rightarrow K_2 = 2\sqrt{2} - 3 \approx 0$$

5) a)  $G(s) = K \cdot s \cdot \frac{1}{s+1} \cdot \frac{1}{(\frac{s}{2} + 1)} \Rightarrow \text{cm } 1 \Rightarrow 10 = K, K = 10$

$$G(s) = 20 \frac{s}{(s+1)(s+2)} = \frac{20s}{s^2+3s+2}$$

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$y = [0 \ 20] x + [0] u$$

b)  $u = r - Kx \Rightarrow \dot{x} = Ax + B(r - Kx) \Rightarrow \begin{cases} \dot{x} = (A - BK)x + Br \\ y = (C - DK)x + Dr \end{cases}$

sendo  $F(s) = (C - DK)(sI - (A - BK))^{-1}B + D = [0 \ 20] \frac{1}{s^2 + (3+K_2)s + (2+K_1)} \begin{bmatrix} s+3+K_2 \\ -2K_1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$= \frac{1}{s^2 + (3+K_2)s + (2+K_1)} [0 \ 20] \begin{bmatrix} 1 \\ s \end{bmatrix} = \frac{20s}{s^2 + (3+K_2)s + (2+K_1)} = \frac{20s}{(s+3)(s+3)} = \frac{20s}{s^2 + 6s + 9}$$

$z_0 = \frac{1}{3} \Rightarrow$  dois polos em  $s = -3$

$$2+K_1 = 9 \Rightarrow K_1 = 7$$

$$3+K_2 = 6 \Rightarrow K_2 = 3$$

$$K = \begin{bmatrix} 7 & 3 \end{bmatrix}$$

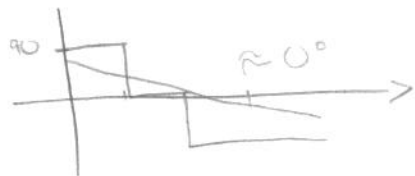
ou  $K = [p_0 - a_0 \ p_1 - a_1] = [7 \ 3]$

a) em  $y_3 \rightarrow$  CALCULAR A RESPOSTA EM FREQUÊNCIA P/FASE E MÓDULO

$$F(s) = \frac{20 \cdot s}{s^2 + 6s + 9} = \frac{20 \cdot s}{(s+3)(s+3)} = \frac{20 \cdot s}{\left(\frac{s}{3} + 1\right)\left(\frac{s}{3} + 1\right)} = \frac{20 \cdot s}{9 \left(\frac{s}{3} + 1\right)^2}$$

$$|F(j3)| = \frac{20 \cdot 3}{9} = \frac{20}{3}$$

$$\rightarrow y = |F(j3)| \cdot 6 \cdot \sin(3t + \phi) = \frac{20}{3} \cdot 6 \cdot \sin(3t) = 40 \sin 3t$$



4) a)  $\dot{x} = \begin{bmatrix} 0 & 1 \\ -1 & 2 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$   $(L_2 \text{ e } L_1)$

$y = \begin{bmatrix} 1 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \end{bmatrix} u$   $\rightarrow$  CI novas

$x = \begin{bmatrix} y \\ \dot{y} \end{bmatrix}$

$$s^2 Y = s y(0) - \dot{y}(0) - 2sY - 2y(0) + Y$$

$$(s^2 - 2s + 1)Y = \hat{u} + 1$$

$$Y = \frac{\hat{u}}{s^2 - 2s + 1} + 1$$

~~$\det(A - LC)$~~   $P(s) = (s+2)^2 \Rightarrow$

$$A - \begin{bmatrix} L_1 \\ L_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} = \begin{bmatrix} -L_1 & 1 \\ -1-L_2 & 2 \end{bmatrix}$$

$$(sI - (A - LC)) = \begin{bmatrix} s+L_1 & -1 \\ 1+L_2 & s-2 \end{bmatrix}$$

$$\det(sI - (A - LC)) = P(s) = (s+L_1)(s-2) + (1+L_2)$$

$$= s^2 + (L_1 - 2)s + L_2 - 2L_1 + 1 = s^2 + 4s + 4$$

$$4 = L_1 - 2 \quad 4 = L_2 - 2 \cdot 6 + 1$$

$$L_1 = 6$$

$$L_2 = 4 + 11 = 15$$

b)  $\hat{e}_0 = (A - LC) \cdot e_0 \xrightarrow{L} s \hat{e}_0 - e_0(0) = (A - LC) \hat{e}_0 \Rightarrow (sI - (A - LC)) \hat{e}_0 = e_0(0)$

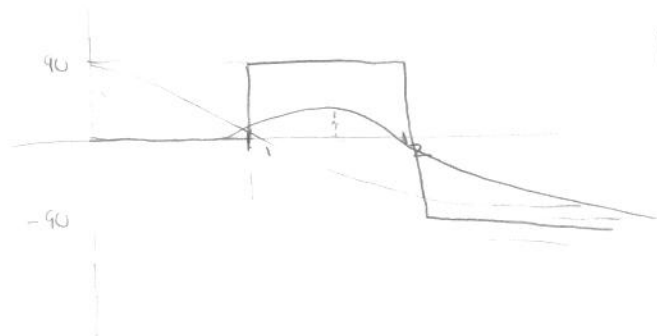
$$\hat{e}_0 = (sI - (A - LC))^{-1} e_0(0)$$

$$e_0(t) = x(t) - x_d(t)$$

5)  $G(s) = K(s+1) \cdot \frac{1}{(\frac{s}{2} + 1)^2} = \frac{10^{7/10} (s+1) \cdot 4}{(s^2 + 4s + 4)} = \frac{2 \cdot 10^{7/10} (s+1)}{s^2 + 4s + 4}$   $14 = 20 \log e$   
 $c = \frac{14}{20}$   
 $10$

$20 \log K + 20 \log 2 = 14 \Rightarrow 20 \log K = -20 \log 2 + 20 \log 10^{14/20}$

$20 \log K = 20 \log \frac{10^{7/10}}{2} \Rightarrow K = \frac{10^{7/10}}{2}$



$|G(s)| = 1 \Rightarrow$  (PUNTO CRÍTICO)

$y - y_0 = m(x - x_0)$

$0 - 14 = -20(\log \omega - \log 2)$

$\Rightarrow 20 \log \omega = 14 + 20 \log 2$

$\log \omega = \frac{14}{20} + \log 2$

$\log 10^{14/20}$

$\log \omega = \log 10^{13/20} \cdot 2$

$\omega = 2 \cdot 10^{7/10} \text{ rad/s} \gg 2 \text{ rad/s}$

$\Rightarrow$  FASE em  $\omega = 2 \cdot 10^{7/10} \text{ rad/s} \rightarrow -90^\circ \Rightarrow MF \approx 90^\circ$

b)  $\dot{X} = \begin{bmatrix} 0 & 1 \\ -4 & -4 \end{bmatrix} X + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$

$y = \begin{bmatrix} 2 \cdot 10^{7/10} & 2 \cdot 10^{7/10} \end{bmatrix} X + \begin{bmatrix} 0 \end{bmatrix} u$

c)  $\dot{X}_0 = A X_0 + B u + L(y - y_0)$

$y_0 = C X_0 + D u$

$\dot{X}_0 = A X_0 + B u + L(y - C X_0 - D u) \Rightarrow \dot{X}_0 = A X_0 + B u + L(C X_0 - C X_0 - D u)$

$\dot{X}_0 = (A - LC) X_0 + B u + LC X$   
 $\dot{X} = A X + B u$

$\dot{X} - \dot{X}_0 = \dot{e}_0 = A X + B u - (A - LC) X_0 - B u - LC X$

$= (A - LC) X - (A - LC) X_0$

$= (A - LC)(X - X_0) \Rightarrow \dot{e}_0 = (A - LC) e_0$

$\Rightarrow$  PARA O OBSERVADOR, PRECISAMOS ALOCAR OS POLOS DE  $\det(sI - (A - LC))$  em  $\tau_0 = 0,2$

$\tau_1 = 0,25s$

$A - LC = \begin{bmatrix} 0 & 1 \\ -4 & -4 \end{bmatrix} - \begin{bmatrix} L_1 \\ L_2 \end{bmatrix} \begin{bmatrix} 2 \cdot 10^{7/10} & 2 \cdot 10^{7/10} \end{bmatrix} = \begin{bmatrix} -L_1 \cdot 2 \cdot 10^{7/10} & 1 - L_1 \cdot 2 \cdot 10^{7/10} \\ -4 - L_2 \cdot 2 \cdot 10^{7/10} & -4 - L_2 \cdot 2 \cdot 10^{7/10} \end{bmatrix}$

$\det(sI - (A - LC)) = 0 \Rightarrow$  EQ CARACTERÍSTICA  $\Rightarrow \det \begin{bmatrix} s + L_1 \cdot 2 \cdot 10^{7/10} & -1 + L_1 \cdot 2 \cdot 10^{7/10} \\ 4 + L_2 \cdot 2 \cdot 10^{7/10} & s + 4 + L_2 \cdot 2 \cdot 10^{7/10} \end{bmatrix} = 0$

$s^2 + (4 + L_2 \cdot 2 \cdot 10^{7/10} + L_1 \cdot 2 \cdot 10^{7/10})s + (4 + L_2 \cdot 2 \cdot 10^{7/10})(4 + L_2 \cdot 2 \cdot 10^{7/10}) = 0$   
 $s^2 + (4 + L_2 \cdot 2 \cdot 10^{7/10} + L_1 \cdot 2 \cdot 10^{7/10})s + 4 \cdot L_2 \cdot 2 \cdot 10^{7/10} = P(s)$

$$P(s) = \left(\frac{1}{4}s + 1\right)\left(\frac{1}{5}s + 1\right) = \frac{1}{4} \cdot \frac{1}{5} (s+4)(s+5) = P(s) = 0 = s^2 + 9s + 20$$

$$+L_2 \cdot 10^{7/10} = 20^{10} \Rightarrow L_2 = \frac{10}{10^{7/10}} - \frac{2}{10^{7/10}} \approx 1,59 \dots$$

$$4 + L_2 \cdot 10^{7/10} + L_1 \cdot 10^{7/10} = 9 \Rightarrow L_1 = -1,09$$

$$L = \begin{bmatrix} -1,09 \\ 1,59 \end{bmatrix}$$

$$d) u(t) = 1 \Rightarrow u(s) = \frac{1}{s} \quad X(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\hat{e}_0 = (A - LC)e_0 \Rightarrow s e_0 - e_0(A - LC)e_0 = 0 \Rightarrow (sI - (A - LC))e_0 = e_0(0)$$

$$\hat{e}_0 = (sI - (A - LC))^{-1} e_0(0)$$

$$X_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad X(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$e_0(0) = X(0) - X_0(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\rightarrow \text{ADOTANDO } 10^{7/10} \approx 10$$

$$\hat{e}_0 = \frac{1}{s^2 + 9s + 20} \begin{bmatrix} s+20 & 11 \\ -20 & s-11 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$(sI - (A - LC))^{-1} = \frac{1}{(s+4)(s+5)} \begin{bmatrix} s+20 & 11 \\ -20 & s-11 \end{bmatrix}$$

$$\hat{e}_0 = \frac{1}{(s+4)(s+5)} \begin{bmatrix} s+20 \\ -20 \end{bmatrix} \Rightarrow \begin{bmatrix} \hat{e}_{x_1} \\ \hat{e}_{x_2} \end{bmatrix} = \frac{1}{(s+4)(s+5)} \begin{bmatrix} s+20 \\ -20 \end{bmatrix}$$

$$\hat{e}_{x_2} = \frac{-20}{(s+4)(s+5)} = \frac{A}{s+4} + \frac{B}{s+5} \Rightarrow A(1) = -20 \quad B(-1) = -20 \Rightarrow B = 20$$

$$= \frac{-20}{s+4} + \frac{20}{s+5}$$

$$\mathcal{F}^{-1}\{\hat{e}_{x_2}(s)\} = -20e^{-4t} + 20e^{-5t}$$



$$X = \begin{bmatrix} x \\ \dot{x} \\ y \\ \dot{y} \end{bmatrix}$$

$$\left. \begin{aligned} m\ddot{x} + b(\dot{x} - \dot{y}) &= 0 & b(\dot{y} - \dot{x}) &= m\ddot{x} \\ K(y - x) + b(y - \dot{x}) + m\ddot{y} &= 0 & \Leftrightarrow & \\ K(x - y) = f(t) &\Rightarrow K(y - x) = -f(t) \end{aligned} \right\} \begin{aligned} m\ddot{x} + b\dot{x} - b\dot{y} &= 0 \Rightarrow \ddot{x} = -\frac{b}{m}\dot{x} + \frac{b}{m}\dot{y} \\ m\ddot{y} + b\dot{y} - b\dot{x} &= f(t) \Rightarrow \ddot{y} = -\frac{b}{m}\dot{y} + \frac{b}{m}\dot{x} + \frac{f(t)}{m} \end{aligned}$$

$$Kz - Ky = f(t) \Rightarrow z = y + \frac{1}{K}f(t)$$

6) CONT

$$\dot{X} = \begin{bmatrix} \dot{x} \\ \dot{x} \\ \dot{x} \\ \dot{x} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1/m \end{bmatrix} u(t)$$

$$y = \begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix} X + \begin{bmatrix} 1/k \end{bmatrix} u(t)$$

a) Não é possível atender a especificação pois o polo em baixa frequência mais rápido seria ainda maior que 2s  $\rightarrow$  não controlável

b) Não é possível pois não conseguimos alocar os polos a  $\infty$  devido a dinâmica do sistema ser mais ~~os polos de (A-BK) a alta frequência~~ de alta frequência da dinâmica do sistema em alta frequência

$\hookrightarrow$  não controlável de  $C_b = 0$

$$7) G(s) = \frac{2(s+4)}{(s+1)(s^2+9s+18)} = \frac{2s+8}{(s+1)(s^2+9s+18)} = \frac{2s+8}{s^3+10s^2+27s+18}$$

$$a) \dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & -27 & -10 \end{bmatrix} X + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 2 & 2 & 0 \end{bmatrix} X + \begin{bmatrix} 0 \end{bmatrix} u$$

$$P/ u = K(\hat{M} - x),$$

$$x = Ax + Bu \Rightarrow x = (A - BK)x + BKM\hat{M}$$

$$y = Cx + Du \Rightarrow y = (C - DK)x + DKM\hat{M}$$

$$F(s) = \frac{C - DK}{sI - (A - BK)} BKM + DKM$$

$$b) \psi(\xi) = e^{-\pi\xi/\sqrt{1-\xi^2}} \Rightarrow \xi > 0,4$$

$$\xi \omega_n \geq 4$$

$$\omega_n \leq 2\pi \cdot 50$$

$$Sendo a eq caract.  $\Rightarrow \det(sI - (A - BK)) = P(s)$$$

$\rightarrow$  onde iremos alocar os polos  
 em  $s = -4$ , por exemplo  
 $P(s) = (s+4)(s+4)(s+4) = s^3 + 12s^2 + 48s + 64$

$$F(0) = 1$$

$$K = [p_0 - a_0 \quad p_1 - a_1 \quad p_2 - a_2]$$

$$= [64 - 18 \quad 48 - 27 \quad 12 - 10] = [46 \quad 21 \quad 2]$$

$$A - BK = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & -27 & -10 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \begin{bmatrix} 46 & 21 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -64 & -48 & -12 \end{bmatrix}$$

$$F(s) = \begin{bmatrix} 2 & 2 & 0 \end{bmatrix} \frac{1}{s^3 + 12s^2 + 48s + 64} \begin{bmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 64 & 48 & s + 12 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} K \cdot M$$

7) CONTINUAÇÃO

$$\begin{bmatrix} \Delta_{11} & \Delta_{12} & \Delta_{13} \\ \Delta_{21} & \Delta_{22} & \Delta_{23} \\ \Delta_{31} & \Delta_{32} & \Delta_{33} \end{bmatrix} = \begin{bmatrix} s^2 + 12s + 48 & -64 & -64s \\ s + 12 & s^2 + 12s & -48s - 64 \\ 1 & s & s^2 \end{bmatrix}$$

$$\begin{bmatrix} \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{bmatrix}^t = \begin{bmatrix} s^2 + 12s + 48 & -64 & 1 \\ -64 & s^2 + 12s & s \\ -64s & -48s - 64 & s^2 \end{bmatrix}$$

$$F(s) = [8 \ 2 \ 0] \frac{1}{s^3 + 12s^2 + 48s + 64} \begin{bmatrix} 1 \\ s \\ s^2 \end{bmatrix} \text{ K M}$$

$$= \frac{2s + 8}{s^3 + 12s^2 + 48s + 64} \cdot \text{K M}$$

$$K K' = [46 \ 21 \ 2] \begin{bmatrix} 46 \\ 21 \\ 2 \end{bmatrix}$$

→ P/ERRO NULO

$$F(0) = 1 = S(0) \text{ K M} \Rightarrow 1 = \frac{8}{64} \cdot \text{K M}$$

$$M = S(0)^{-1} K' (K K')^{-1} = 8 \begin{bmatrix} 46 \\ 21 \\ 2 \end{bmatrix} \frac{1}{46^2 + 21^2 + 4} = \frac{8}{2561} \begin{bmatrix} 46 \\ 21 \\ 2 \end{bmatrix}$$

$$M = \begin{bmatrix} 0,1437 \\ 0,1656 \\ 0,0062 \end{bmatrix}$$

$$F(s) = \frac{2s + 8}{s^3 + 12s^2 + 48s + 64} \quad 8 = \frac{16s + 64}{s^3 + 12s^2 + 48s + 64}$$

c) SENDO ENTÃO  $U = -KX \Rightarrow U = -[46 \ 21 \ 2] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \Rightarrow$

DO QUE:  $\left. \begin{matrix} x_2 = \dot{x}_1 \\ x_3 = \dot{x}_2 \end{matrix} \right\} \begin{matrix} \hat{x}_2 = s \hat{x}_1 \\ \hat{x}_3 = s \hat{x}_2 \end{matrix}$

$$U = -[46 \ 21 \ 2] \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \\ s \hat{x}_2 \end{bmatrix} = -46 \frac{\hat{x}_2}{s} - 21 \hat{x}_2 - 2s \hat{x}_2$$

→ VARIÁVEL A SER MEDIDA

$$= -\hat{x}_2 \left( \frac{46}{s} + 21 + 2s \right)$$

$$C(s) = \frac{46}{s} + 21 + 2s$$

3

$$\begin{cases} \dot{x}_0 = Ax_0 + Bu + L(y - y_0) \\ y_0 = Cx_0 + Du \end{cases} \Rightarrow \begin{cases} \dot{x}_0 = Ax_0 + Bu + L(G + D - Cx_0 - Du) \\ \dot{x}_0 = (A - LC)x_0 + Bu + LCx \end{cases}$$

$$\dot{x} = Ax + Bu, \quad \dot{x} - \dot{x}_0 = Ax + Bu - (A - LC)x_0 - Bu - LCx$$

$$\Rightarrow \dot{x} - \dot{x}_0 = (A - LC)x - (A - LC)x_0 \Rightarrow \dot{e}_0 = (A - LC)e_0, \quad e_0 = x - x_0$$

OS POLOS DO OBSERVADOR DEVEM SER MAIS RÁPIDOS DO QUE A DINÂMICA DO SISTEMA ORIGINAL:

OU SEJA, DEVE SER  $|s| > 6$

→ PÓLO MAIS RÁPIDO DO SISTEMA ORIGINAL

$$A - \begin{bmatrix} L_1 \\ L_2 \\ L_3 \end{bmatrix} \begin{bmatrix} 8 & 2 & 0 \end{bmatrix} = \begin{bmatrix} -8L_1 & 1-2L_1 & 0 \\ -8L_2 & -2L_2 & 1 \\ -8L_3 & -2L_3 & -10 \end{bmatrix}$$

$$Cq \text{ caract} \Rightarrow \det(sI - (A - LC)) = 0 = P(s) = (s + 7)^3$$

$$L = \begin{bmatrix} -1,75 \\ +2,5 \\ -45 \end{bmatrix}$$

$$8) G(s) = \frac{1}{s(s+1)} = \frac{1}{s^2 + s}$$

$$a) \dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \end{bmatrix} u$$

$$b) \text{ se } u = r - Kx,$$

$$\begin{cases} \dot{x} = Ax + B(r - Kx) \\ y = Cx + D(r - Kx) \end{cases} \Rightarrow \begin{cases} \dot{x} = (A - BK)x + Br \\ y = (C - DK)x + Dr \end{cases}$$

$$\begin{aligned} \hat{x} &= \hat{x} - (A - BK)\hat{x} = B\hat{r} \\ (sI - (A - BK))\hat{x} &= B\hat{r} \\ \hat{x} &= (sI - (A - BK))^{-1} B\hat{r} \end{aligned}$$

$$\hat{y} = \{(C - DK)(sI - (A - BK))^{-1} B + D\} \hat{r}$$

ONDE  $F(s) = (C - DK)(sI - (A - BK))^{-1} B + D$  é a eq. transferencial  $\hat{y} = F(s)\hat{r}$

$$\det(sI - (A - BK)) = 0$$

$$z_0 s + 1 \Rightarrow \text{PÓLOS em } -\frac{1}{z_0} = -2$$

$$\left. \begin{aligned} \zeta_{wn} &= 2 \\ \gamma &= 0,5 \end{aligned} \right\} \omega_n = \frac{2}{0,5} = 4 \Rightarrow P(s) = s^2 + 4s + 16$$

$$K = \begin{bmatrix} a_1 - a_0 & 0 & -a_0 \end{bmatrix} = \begin{bmatrix} 16 & 2 \end{bmatrix}$$



8) a) CONSIDERANDO  $U = -KX \Rightarrow U = -[16 \ 3] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -[16 \ 3] \begin{bmatrix} x_1 \\ -x_1 \end{bmatrix}$

$\dot{x}_1 = x_2 \xrightarrow{\Delta} x_1 = x_2$

$= -x_1 \frac{(16+3)}{C(s)}$

d) SENDO ①  $\dot{x}_0 = Ax_0 + Bu + L(y-y_0)$   
 $y_0 = Cx_0 + Du$

①  $\rightarrow \dot{x}_0 = Ax_0 + Bu + L(Cx + \cancel{Du} - Cx_0 - \cancel{Du})$

$\dot{x}_0 = (A-LC)x_0 + Bu + LCx$

$\dot{x} - \dot{x}_0 = Ax + \cancel{Bu} - (A-LC)x_0 - \cancel{Bu} - LCx \Rightarrow \dot{e}_0 = (A-LC)x - (A-LC)x_0$   
 $\Rightarrow \dot{e}_0 = (A-LC)e_0 \xrightarrow{\Delta} (sI - (A-LC))e_0 = e_0(0) \Rightarrow \frac{e_0}{e_0(0)} = (sI - (A-LC))^{-1}$

ALOCANDO AS RAÍZES DE  $\det(sI - (A-LC)) = 0$  em  $s = -5$ , POR EXEMPLO

$A-LC = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix} - \begin{bmatrix} L_1 \\ L_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \end{bmatrix} = \begin{bmatrix} -L_1 & 1 \\ -L_2 & -1 \end{bmatrix}$

$(sI - (A-LC)) = \det \begin{pmatrix} s+L_1 & -1 \\ -L_2 & s+1 \end{pmatrix} = s^2 + (L_1+1)s + L_1+L_2 = 0 = (s+5)^2$

$s^2 + (L_1+1)s + (L_1+L_2) = s^2 + 10s + 25 \Rightarrow L_1 = 9, L_2 = 16 \quad L = \begin{bmatrix} 9 \\ 16 \end{bmatrix}$

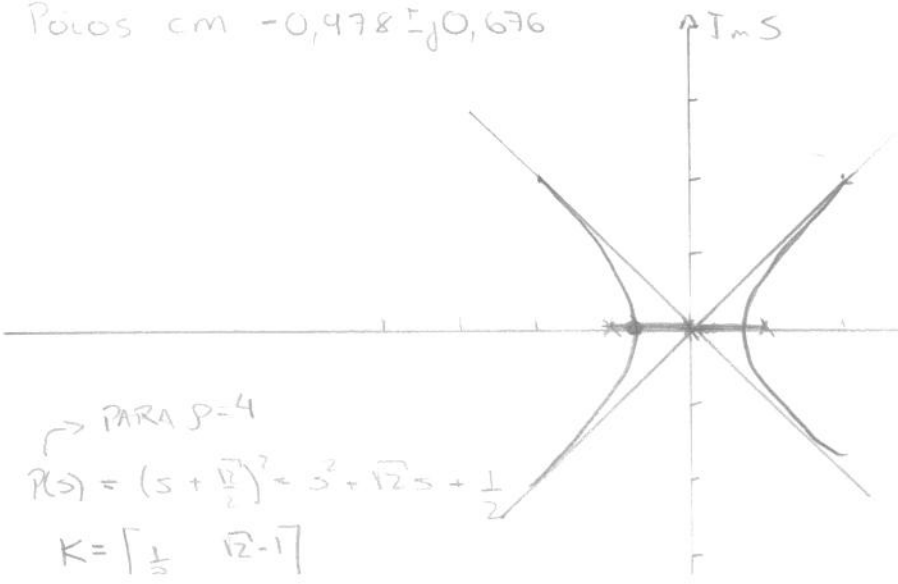
0,19  
1,7  
1,343  
4,9  
0,833  
0,3  
0,749a

e)  $g = 0,3 \quad V = [1 \ 0] = C = [1 \ 0]$

$\psi(s) = V(sI - A)^{-1}B = C(sI - A)^{-1}B = G(s) = \frac{1}{s^2 + s}$

$1 + g^{-1} \psi(s) \phi(s) = 0 \Rightarrow 1 + 2 \cdot \frac{1}{s^2 - s} \cdot \frac{1}{(s^2 + s)} = 1 + 2 \cdot \frac{1}{s^2(s-1)(s+1)} = \frac{1}{s^4 - s^2}$

Polos em  $-0,478 \pm j0,676$



$6 = \frac{\sum p_i - \sum z_i}{n-m} = \frac{-1+1}{4} = 0$

$G(s) = 0 = 4s^3 - 2s = 0$   
 $4s^2 = 2 \quad s^2 = \frac{2}{4} \Rightarrow s = \pm \frac{1}{\sqrt{2}} \cdot j$

$\frac{1}{K} = \frac{\prod |s - z_i|}{\prod |s - p_i|} \Rightarrow K = 0,3 \cdot 0,7 \cdot 0,7 \cdot 1,7$   
 $K \approx 0,23$   
 $g^{-1} = K$   
 $g = \frac{1}{K} = \frac{1}{0,23} = 4$

PARA  $g=4$

$P(s) = (s + \frac{\sqrt{2}}{2})^2 = s^2 + \sqrt{2}s + \frac{1}{2}$   
 $K = \begin{bmatrix} \frac{1}{2} & \sqrt{2} - 1 \end{bmatrix}$

