

RA: _____ Nome: _____

(1) (i) Sejam as coordenadas esféricas (r, θ, ϕ) dadas por

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta,$$

onde $0 \leq r < \infty$, $0 \leq \theta \leq \phi$ e $0 \leq \phi < 2\pi$.

(i) Mostre que os vetores tangentes unitários $\{\mathbf{e}_r, \mathbf{e}_\theta, \mathbf{e}_\phi\}$ são dados por

$$\mathbf{e}_r = \sin \theta \cos \phi \mathbf{i} + \sin \theta \sin \phi \mathbf{j} + \cos \theta \mathbf{k},$$

$$\mathbf{e}_\theta = \cos \theta \cos \phi \mathbf{i} + \cos \theta \sin \phi \mathbf{j} - \sin \theta \mathbf{k},$$

$$\mathbf{e}_\phi = -\sin \phi \mathbf{i} + \cos \phi \mathbf{j},$$

onde $\{\mathbf{i}, \mathbf{j}, \mathbf{k}\}$ são os vetores unitários cartesianos tais que $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.

(ii) Seja o campo vetorial \mathbf{V} dado por

$$\mathbf{V} = \frac{1}{\sqrt{x^2 + y^2 + z^2}} \left(\frac{yz}{x^2 + y^2} \mathbf{i} - \frac{xz}{x^2 + y^2} \mathbf{j} \right).$$

Mostre que em termos de coordenadas esféricas

$$\mathbf{V} = -\frac{\cot \theta}{r} \mathbf{e}_\phi.$$

(iii) Utilizando coordenadas esféricas, calcule o rotacional de \mathbf{V} .

(2) Seja a equação diferencial

$$x(1-x)y'' + (1-5x)y' - 4y = 0.$$

Ao utilizar o método de Frobenius para resolver essa equação diferencial encontramos que a equação indicial correspondente apresenta raízes iguais $r_1 = r_2 = 0$, e com isso obtemos que uma das soluções em forma de série dessa equação diferencial é

$$y_1(x) = \sum_{n=0}^{\infty} (n+1)^2 x^n.$$

Utilize o método de Frobenius para encontrar uma segunda solução $y_2(x)$ linearmente independente.

(3) Mostre que nenhuma solução não trivial da equação

$$z^2 y'' + zy' + y = 0$$

que é real no semieixo real positivo do plano complexo pode ser real no semieixo real negativo.

(4) Mostre que

$$\int_{-1}^1 \sqrt{\frac{1+x}{1-x}} dx = \pi.$$

FORMULÁRIO (EVENTUALMENTE ÚTIL)

$$\nabla f = \frac{1}{h_1} \frac{\partial f}{\partial q_1} \mathbf{e}_{q_1} + \frac{1}{h_2} \frac{\partial f}{\partial q_2} \mathbf{e}_{q_2} + \frac{1}{h_3} \frac{\partial f}{\partial q_3} \mathbf{e}_{q_3},$$

$$\nabla \cdot \mathbf{V} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial q_1} (h_2 h_3 V_1) + \frac{\partial}{\partial q_2} (h_3 h_1 V_2) + \frac{\partial}{\partial q_3} (h_1 h_2 V_3) \right],$$

$$\nabla \times \mathbf{V} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \mathbf{e}_{q_1} & h_2 \mathbf{e}_{q_2} & h_3 \mathbf{e}_{q_3} \\ \frac{\partial}{\partial q_1} & \frac{\partial}{\partial q_2} & \frac{\partial}{\partial q_3} \\ h_1 V_1 & h_2 V_2 & h_3 V_3 \end{vmatrix},$$

$$(\alpha)_n = \frac{\Gamma(\alpha + n)}{\Gamma(\alpha)}, \quad \Gamma(z) = \int_0^\infty e^{-t} t^{z-1} dt,$$

$$\Gamma(z)\Gamma(1-z) = \frac{\pi}{\sin \pi z}, \quad 2^{2z-1} \Gamma(z)\Gamma(z+1/2) = \sqrt{\pi} \Gamma(2z),$$

$$B(z, w) = \frac{\Gamma(z)\Gamma(w)}{\Gamma(z+w)}, \quad B(z, w) = \int_0^1 t^{z-1} (1-t)^{w-1} dt$$

$$B(z, w) = 2 \int_0^{\pi/2} \cos^{2z-1} \theta \sin^{2w-1} \theta d\theta,$$

$$\textcircled{1} \quad \vec{r} = (r \sin \theta \cos \phi) \vec{i} + (r \sin \theta \sin \phi) \vec{j} + (r \cos \theta) \vec{k}$$

$$\textcircled{i} \quad \frac{\partial \vec{r}}{\partial r} = \sin \theta \cos \phi \vec{i} + \sin \theta \sin \phi \vec{j} + \cos \theta \vec{k}$$

$$\therefore \vec{e}_r = \frac{\partial \vec{r}}{\partial r} \quad \checkmark$$

$$h_r = \sqrt{\underbrace{\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi}_{\sin^2 \theta} + \cos^2 \theta} = 1$$

$$\frac{\partial \vec{r}}{\partial \theta} = r \cos \theta \cos \phi \vec{i} + r \cos \theta \sin \phi \vec{j} - r \sin \theta \vec{k}$$

$$\therefore \vec{e}_\theta = \frac{1}{r} \frac{\partial \vec{r}}{\partial \theta} \quad \checkmark$$

$$h_\theta = \sqrt{\underbrace{r^2 \cos^2 \theta \cos^2 \phi + r^2 \cos^2 \theta \sin^2 \phi + r^2 \sin^2 \theta}_{r^2 \cos^2 \theta}} = r$$

$$\frac{\partial \vec{r}}{\partial \phi} = -r \sin \theta \sin \phi \vec{i} + r \sin \theta \cos \phi \vec{j}$$

$$\therefore \vec{e}_\phi = \frac{1}{r \sin \theta} \frac{\partial \vec{r}}{\partial \phi} \quad \checkmark$$

$$\therefore h_\phi = \sqrt{r^2 \sin^2 \theta \sin^2 \phi + r^2 \sin^2 \theta \cos^2 \phi} = r \sin \theta$$

$(+1, 0)$

$$\textcircled{ii} \quad \vec{i} = (\vec{i} \cdot \vec{e}_r) \vec{e}_r + (\vec{i} \cdot \vec{e}_\theta) \vec{e}_\theta + (\vec{i} \cdot \vec{e}_\phi) \vec{e}_\phi$$

$$\vec{i} = \sin \theta \cos \phi \vec{e}_r + \cos \theta \cos \phi \vec{e}_\theta - \sin \phi \vec{e}_\phi$$

$$\vec{j} = (\vec{j} \cdot \vec{e}_r) \vec{e}_r + (\vec{j} \cdot \vec{e}_\theta) \vec{e}_\theta + (\vec{j} \cdot \vec{e}_\phi) \vec{e}_\phi$$

$$\vec{j} = \sin \theta \sin \phi \vec{e}_r + \cos \theta \sin \phi \vec{e}_\theta + \cos \phi \vec{e}_\phi$$

$$\sqrt{x^2 + y^2 + z^2} = r$$

$$x^2 + y^2 = r^2 \sin^2 \theta$$

$$\begin{aligned} \therefore \vec{V} &= \frac{1}{r \cdot r^2 \sin^2 \theta} \left[r^2 \sin \theta \sin \phi \cos \theta (\sin \theta \cos \phi \vec{e}_r + \cos \theta \cos \phi \vec{e}_\theta - \sin \phi \vec{e}_\phi) \right. \\ &\quad \left. + r^2 \sin \theta \cos \phi \cos \theta (\sin \theta \sin \phi \vec{e}_r + \cos \theta \sin \phi \vec{e}_\theta + \cos \phi \vec{e}_\phi) \right] \end{aligned}$$

$$\begin{aligned}
 \vec{V} &= \frac{1}{r^3 \sin^2 \theta} \left[\underbrace{(r^2 \sin^2 \theta \cos \theta \sin \phi \cos \phi - r^2 \sin^2 \theta \cos \phi \sin \phi \cos \theta)}_{=0} \vec{e}_r \right. \\
 &\quad + \underbrace{(r^2 \sin \theta \cos^2 \theta \sin \phi \cos \phi - r^2 \sin \theta \cos^2 \theta \sin \phi \cos \phi)}_{=0} \vec{e}_\theta \\
 &\quad \left. - \underbrace{(r^2 \sin \theta \sin^2 \phi \cos \theta + r^2 \sin \theta \cos^2 \phi \cos \theta)}_{r^2 \sin \theta \cos \theta} \vec{e}_\phi \right] \\
 &= \frac{1}{r^3 \sin^2 \theta} (-r^2 \sin \theta \cos \theta) \vec{e}_\phi \quad \therefore \vec{V} = -\frac{\cot \theta}{r} \vec{e}_\phi
 \end{aligned}$$

(1, 0)

(iii) $\vec{\nabla} \times \vec{V} = \frac{1}{r \cdot r \sin \theta} \begin{vmatrix} \vec{e}_r & r \vec{e}_\theta & r \sin \theta \vec{e}_\phi \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ 1 \cdot 0 & r \cdot 0 & \underbrace{r \sin \theta \left(-\frac{\cot \theta}{r} \right)}_{-\cos \theta} \end{vmatrix}$

$$= \frac{1}{r^2 \sin \theta} (-1) \frac{\partial}{\partial \theta} (\cos \theta) \vec{e}_r = \frac{1}{r^2} \vec{e}_r$$

$$\vec{\nabla} \times \vec{V} = \frac{1}{r^2} \vec{e}_r = \frac{\vec{F}}{r^3}$$

(1, 0)

2

$$y_2(x) = y_1(x) \ln x + x^0 \sum_{n=1}^{\infty} a_n x^n = y_1(x) \ln x + \sum_{n=1}^{\infty} a_n x^n$$

$$y_2'(x) = y_1' \ln x + y_1 \frac{1}{x} + \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y_2''(x) = y_1'' \ln x + 2y_1' \frac{1}{x} - y_1 \frac{1}{x^2} + \sum_{n=1}^{\infty} n(n-1) a_n x^{n-2}$$

$$(*) \Rightarrow \underbrace{[x(1-x)y_1'' + (1-5x)y_1' - 4y_1] \ln x}_{=0} + 2y_1' - \cancel{y_1 \frac{1}{x}} + \sum_{n=1}^{\infty} n(n-1) a_n x^{n-1} - 2xy_1' + y_1 - \sum_{n=1}^{\infty} n(n-1) a_n x^n + \cancel{y_1 \frac{1}{x}} + \sum_{n=1}^{\infty} n a_n x^{n-1} - 5y_1 - 5 \sum_{n=1}^{\infty} n a_n x^n - 4 \sum_{n=1}^{\infty} a_n x^n = 0$$

usando la expresi3n de $y_1(x)$:

$$2 \sum_{n=1}^{\infty} n(n+1)^2 x^{n-1} + \sum_{n=1}^{\infty} n(n-1) a_n x^{n-1} - 2 \sum_{n=1}^{\infty} n(n+1)^2 x^n - \sum_{n=1}^{\infty} n(n-1) a_n x^n + \sum_{n=1}^{\infty} n a_n x^{n-1} - 4 \sum_{n=0}^{\infty} (n+1)^2 x^n - 5 \sum_{n=1}^{\infty} n a_n x^n - 4 \sum_{n=1}^{\infty} a_n x^n = 0$$

$$\therefore 2 \cdot 1 \cdot 2^2 x^0 + 2 \sum_{n=1}^{\infty} (n+1)(n+2)^2 x^n + \sum_{n=1}^{\infty} (n+1) n a_{n+1} x^n - 2 \sum_{n=1}^{\infty} n(n+1)^2 x^n - \sum_{n=1}^{\infty} n(n-1) a_n x^n + 3 \cdot a_1 + \sum_{n=1}^{\infty} (n+1) a_{n+1} x^n - 4 - 4 \sum_{n=1}^{\infty} (n+1)^2 x^n - \sum_{n=1}^{\infty} (5n+4) a_n x^n = 0$$

0

$$\therefore \begin{cases} 8-4+a_1=0 \Rightarrow \boxed{a_1 = -4 = -2 \cdot 2} \\ 2(n+1)(n+2)^2 + (n+1)n a_{n+1} - 2n(n+1)^2 - n(n-1)a_n + (n+1)a_{n+1} \\ - 4(n+1)^2 - (5n+4)a_n = 0, \quad n=1, 2, 3, \dots \quad (*) \end{cases}$$

$$(*) (n+1) \left[\underbrace{2(n+2)^2 - 2n(n+1) - 4(n+1)}_{\substack{-2(n+2)(n+1) \\ (n+2)[2(n+2)-2(n+1)] \\ (n+2) \cdot 2}} \right] + (n+1)^2 a_{n+1} - \underbrace{[n(n-1) + 5n + 4]}_{\substack{n^2 + 4n + 4 \\ (n+2)^2}} a_n = 0$$

$$\therefore 2(n+1)(n+2) + (n+1)^2 a_{n+1} - (n+2)^2 a_n = 0$$

$$\therefore \boxed{a_{n+1} = \left(\frac{n+2}{n+1} \right) \left[\left(\frac{n+2}{n+1} \right) a_n - 2 \right]} \quad n=1, 2, 3, \dots$$

$$\underline{n=2} \quad a_2 = \frac{3}{2} \left[\frac{3}{2} a_1 - 2 \right] = \frac{3}{2} (-6 - 2) = -3 \cdot 4 = -3 \cdot 2 \cdot 2$$

$$\underline{n=3} \quad a_3 = \frac{4}{3} \left[\frac{4}{3} (-3 \cdot 4) - 2 \right] = \frac{4}{3} (-16 - 2) = -4 \cdot 3 \cdot 2$$

$$\underline{n=4} \quad a_4 = \frac{5}{4} \left[\frac{5}{4} (-4 \cdot 6) - 2 \right] = \frac{5}{4} (-32) = -5 \cdot 4 \cdot 2$$

$$\therefore \boxed{a_n = -2n(n+1)} \quad n=1, 2, 3, \dots$$

$$\therefore y_2(x) = y_1(x) \ln x - 2 \sum_{n=1}^{\infty} n(n+1) x^n$$

$$\text{onde: } y_1(x) = \sum_{n=0}^{\infty} (n+1)^2 x^n$$

$$\textcircled{3} \quad \left. \begin{aligned} z^2 y'' + z y' + y &= 0 \\ y &= z^r \end{aligned} \right\} \Rightarrow r(r-1) + r + 1 = 0 \Rightarrow r^2 + 1 = 0 \quad r = \pm i$$

$$y = C_1 z^i + C_2 z^{-i} = C_1 e^{i \ln z} + C_2 e^{-i \ln z}, \text{ onde } C_1, C_2 \in \mathbb{C} + 0, i$$

Escrevendo $z = r e^{i\theta}$, $C_1 = \alpha_1 + i\beta_1$, $C_2 = \alpha_2 + i\beta_2$, temos

$$\begin{aligned} y &= (\alpha_1 + i\beta_1) e^{i \ln r} e^{-\theta} + (\alpha_2 + i\beta_2) e^{-i \ln r} e^{\theta} \\ &= (\alpha_1 + i\beta_1) e^{-\theta} [\cos(\ln r) + i \sin(\ln r)] + (\alpha_2 + i\beta_2) e^{\theta} [\cos(\ln r) - i \sin(\ln r)] \\ &= [(\alpha_1 e^{-\theta} + \alpha_2 e^{\theta}) \cos(\ln r) + (-\beta_1 e^{-\theta} + \beta_2 e^{\theta}) \sin(\ln r)] \\ &\quad + i [(\alpha_1 e^{-\theta} - \alpha_2 e^{\theta}) \sin(\ln r) + (\beta_1 e^{-\theta} + \beta_2 e^{\theta}) \cos(\ln r)] \quad (*) \end{aligned}$$

semieixo real positivo $\Rightarrow \theta = 0$

$$(*) \Rightarrow y_+ = (\alpha_1 + \alpha_2) \cos(\ln r) + (\beta_2 - \beta_1) \sin(\ln r) \\ + i [(\alpha_1 - \alpha_2) \sin(\ln r) + (\beta_1 + \beta_2) \cos(\ln r)]$$

$$y_+ \in \mathbb{R} \Leftrightarrow \boxed{\alpha_1 = \alpha_2, \beta_1 = -\beta_2} \quad \textcircled{I}$$

semieixo real negativo $\Rightarrow \theta = \pi$

$$(*) \Rightarrow y_- = (\alpha_1 e^{-\pi} + \alpha_2 e^{\pi}) \cos(\ln r) + (-\beta_1 e^{-\pi} + \beta_2 e^{\pi}) \sin(\ln r) \\ + i [(\alpha_1 e^{-\pi} - \alpha_2 e^{\pi}) \sin(\ln r) + (\beta_1 e^{-\pi} + \beta_2 e^{\pi}) \cos(\ln r)]$$

$$y_- \in \mathbb{R} \Leftrightarrow \boxed{\alpha_1 e^{-\pi} = \alpha_2 e^{\pi}, \beta_1 e^{-\pi} = -\beta_2 e^{\pi}} \quad \textcircled{II}$$

+1,5

MAS I e II NAO podem ser
satisfeitas ao mesmo tempo! +0,5

④ Escolhendo $\frac{x+1}{2} = t \Rightarrow x = 2t - 1$, temos

$$I = \int_{-1}^{+1} \sqrt{\frac{1+x}{1-x}} dx = \int_0^1 \sqrt{\frac{2t}{2(1-t)}} 2 dt = 2 \int_0^1 t^{1/2} (1-t)^{-1/2} dt$$

$$= 2 B\left(\frac{3}{2}, \frac{1}{2}\right) = \frac{2 \Gamma(\frac{3}{2}) \Gamma(\frac{1}{2})}{\Gamma(\frac{3}{2} + \frac{1}{2})} = 2 \cdot \frac{\frac{1}{2} \Gamma(\frac{1}{2}) \Gamma(\frac{1}{2})}{1 \cdot \Gamma(1)} =$$

$$= \Gamma(\frac{1}{2}) \Gamma(\frac{1}{2}) = \Gamma(\frac{1}{2}) \Gamma(1 - \frac{1}{2}) = \frac{\pi}{\sin \frac{\pi}{2}} = \pi$$

+1,5