# Research Survival Handbook (**Unfinished**)

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# Chapter 1

# **Special Relativity**

#### **Conventions** 1.1

Metric in special relativity

$$\eta_{\mu\nu} = \begin{pmatrix}
-1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{pmatrix} 
\tag{1.1}$$

#### **Quantities and Operations** 1.2

d'Alembertian d'Alembert operator, or wave operator, is the Lapace operator in Minkowski space. 1

$$\Box \equiv \partial_{\mu} \partial^{\nu} = \eta_{\mu\nu} \partial^{\mu} \partial^{\nu} \tag{1.2}$$

In the usual t,x,y,z natural orthonormal basis,

$$\square = -\partial_t^2 + \partial_x^2 + \partial_y^2 + \partial_z^2 \tag{1.3}$$

$$= -\partial_t^2 + \Delta^2 \tag{1.4}$$

$$\Box = -\partial_t^2 + \partial_x^2 + \partial_y^2 + \partial_z^2 
= -\partial_t^2 + \Delta^2 
= -\partial_t^2 + \nabla$$
(1.3)
(1.4)
(1.5)

On wiki <sup>2</sup>, they give some applications to it.

**klein-Gordon equation**  $(\Box + m^2)\phi = 0$ 

wave equation for electromagnetic field in vacuum For the electromagnetic four-potential  $\Box A^{\mu} = 0^3$ 

<sup>&</sup>lt;sup>1</sup>Actually, there are more general definations for Lapacian, which includes this d'Alembertian of

<sup>&</sup>lt;sup>2</sup>wiki:D'Alembert operator

<sup>&</sup>lt;sup>3</sup>Gauge

wave equation for small vibrations  $\Box_c u(t,x) = 0 \rightarrow u_{tt} - c^2 u_{xx} = 0$ 

# **Chapter 2**

# **General Relativity**

# 2.1 Description of Space-time Manifold

How to describe space-time manifold?

- Metric (with a set of local coordinates), connection (Christoffel symbols).
- Metric (in the form of tetrads), connection (Ricci rotation coefficients).
- 1+3 covariantly defined variables.
- 2.2 Description of Space-time Manifold Coordinates
- 2.3 Description of Space-time Manifold Tetrads
- 2.4 Description of Space-time Manifold 1+3 Covariant Description

Physics in description is easier to understand.

#### 2.4.1 Definations

Definations of some physical quantities and operators are listed below. Here we have

- 1. geometrical variables: Volume
- Kinematical variables: Velocity, Expansion rate, Shear rate Thermaldynanmical variables: Energy density, Momentum density, Pressure, Equation of state

**Volume** To calculate volume, the volume element should be defined first in order to integrate. Before that, orientation on manifolds is to be figured out.

On an oriented manifold with metric, the defined volume element (a n-form) should be compatible with the orientation and also determined by the metric. <sup>1</sup>

Introducing those requirements, a compatible volume element is

$$\epsilon_{a_1\cdots a_n} = \pm \sqrt{|g|} (e^1)_{a_1} \wedge \cdots \wedge (e^n)_{a_n}$$
(2.1)

Alternatively, this can be expressed in the way Ellis used in arXiv:gr-qc/9812046v5.

$$\eta_{abcd} = \eta_{[abcd]}, \quad \text{with} \eta_{0123} = \sqrt{|\text{det}g_{ab}|}$$
(2.2)

Induced volume element  $\hat{\epsilon}_{a_1\cdots a_{n-1}}$  is defined use the normal vector  $u^a$  of the hypersurface,

$$\hat{\epsilon}_{a_1\cdots a_{n-1}} = u^b \epsilon_{ba_1\cdots a_{n-1}} \tag{2.3}$$

4-velocity 4-velocity of observed matter is

$$u^{\alpha} = \frac{\mathrm{d}x^{\alpha}}{\mathrm{d}\tau}$$

with  $u^{\alpha}u_{\alpha}=-1$ , au is the proper time along the worldlines of investaged matter.

**Projection Tensors** We can use 4-velocity to project variables to parts that is parallel to  $u^{\alpha}$  and parts that is orthogonal to  $u^{\alpha}$ .

$$U_b^a = -u^a u_b (2.4)$$

$$h_{ab} = g_{ab} + u_a u_b$$
, induced metric from  $g_{ab}$  (2.5)

Some properties of the two projections.

$$U^a_{\ b}U^b_{\ c} = U^a_{\ c}, U^a_{\ a} = 1, U_{ab} = g_{ac}U^c_{\ b}, U_{ab}u^b = -g_{ac}u^cu_bu^b = u_a$$
 (2.6)

$$h^{a}_{b} = g^{ac}h_{cb} = \delta^{a}_{b} + u^{a}u_{b} = \delta^{a}_{b} - U^{a}_{b}$$
(2.7)

$$h_{c}^{a}h_{b}^{c} = (\delta_{c}^{a} - U_{c}^{a})(\delta_{b}^{c} - U_{b}^{c}) = \delta_{b}^{a} - U_{b}^{a} = h_{b}^{a}$$
(2.8)

$$h^{a}_{a} = 4 - 1 = 3, h_{ab}u^{b} = 0 (2.9)$$

**Covariant time derivative ( ` )** This is the derivative along the fundamental worldlines (projection on the worldlines),

$$\dot{T}^{ab}_{\phantom{a}cd} = u^e \nabla_e T^{ab}_{\phantom{a}cd} \tag{2.10}$$

<sup>&</sup>lt;sup>1</sup>For more information, check out LIANG Canbin's book. Volume 1, page 115.

**Fully orthogonally projected covariant derivative** ( $\tilde{\nabla}$ ) This derivative is the project orghogonal to the normal vector of the hyperspace or orthogonal to the observer's 4-velocity or along the tagent of the hyperspace.

$$\tilde{\nabla}_{e} T^{ab}_{cd} = h_{f}^{a} h_{g}^{b} h_{c}^{p} h_{d}^{q} h_{e}^{r} \nabla_{r} T^{fg}_{pq}$$
(2.11)

Orthogonal projections of vectors Orthogonal projection of vectors

$$v^{\langle a\rangle} = h^a_{\ b} v^b \tag{2.12}$$

And the orthogonally projected symmetric trace-free part of tensors

$$T^{\langle ab\rangle} = [h^{(a}_{\ c}h^{b)}_{\ d} - \frac{1}{3}h^{ab}h_{cd}]T^{cd}$$
(2.13)

Othogonal projected covariant time derivatives along  $u^a$ 

$$\dot{v}^{\langle a\rangle} = h^a_{\ b}\dot{v}^b \tag{2.14}$$

$$\dot{T}^{\langle ab \rangle} = [h^{(a}_{\ b}h^{b)}_{\ d} - \frac{1}{3}h^{ab}h_{cd}]\dot{T}^{cd}$$
 (2.15)

# 2.4.2 Properties

• Projected time and space derivatives of  $U_{ab}$ ,  $h_{ab}$  and  $\eta_{abc}$  vanish.

# 2.5 Fields and Particles

# 2.5.1 Energy-Momentum Tensor for Particles

$$S_p \equiv -mc \int \int \mathrm{d}s \mathrm{d}\tau \sqrt{-\dot{x}^{\mu}g_{\mu\nu}\dot{x}^{\nu}} \delta^4(x^{\mu} - x^{\mu}(s)), \tag{2.16}$$

in which  $x^{\mu}(s)$  is the trajectory of the particle. Then the energy density  $\rho$  corresponds to  $m\delta^4(x^{\mu}-x^{\mu}(s))$ .

The Largrange density

$$\mathcal{L} = -\int \mathsf{d}smc\sqrt{-\dot{x}^{\mu}g_{\mu\nu}\dot{x}^{\nu}}\delta^{4}(x^{\mu} - x^{\mu}(s)) \tag{2.17}$$

Energy-momentum density is  $\mathcal{T}^{\mu\nu}=\sqrt{-g}T^{\mu\nu}$  is

$$\mathcal{T}^{\mu\nu} = -2\frac{\partial \mathcal{L}}{\partial g_{\mu\nu}} \tag{2.18}$$

Finally,

$$\mathcal{T}^{\mu\nu} = \int ds \frac{mc\dot{x}^{\mu}\dot{x}^{\nu}}{\sqrt{-\dot{x}^{\mu}g_{\mu\nu}\dot{x}^{\nu}}} \delta(t - t(s))\delta^{3}(\vec{x} - \vec{x}(t))$$
 (2.19)

$$= m\dot{x}^{\mu}\dot{x}^{\nu}\frac{\mathsf{d}s}{\mathsf{d}t}\delta^{3}(\vec{x}-\vec{x}(s(t))) \tag{2.20}$$

### 2.6 Theorems

## 2.6.1 Killing Vector Related

**2.1.**  $\xi^a$  is Killing vector field,  $T^a$  is the tangent vector of geodesic line. Then  $T^a \nabla_a (T^b \xi_b) = 0$ , that is  $T^b \xi_b$  is a constant on geodesics.

# 2.7 Specific Topics

#### 2.7.1 Redshift

In geometrical optics limit, the angular frequency  $\omega$  of a photon with a 4-vector  $K^a$ , measured by a observer with a 4-velocity  $Z^a$ , is  $\omega = -K_a Z^a$ .

## 2.7.2 Stationary vs Static

**Stationay** "A stationary spacetime admits a timelike Killing vector field. That a stationary spacetime is one in which you can find a family of observers who observe no changes in the gravitational field (or sources such as matter or electromagnetic fields) over time."

When we say a field is stationary, we only mean the field is time-independent.

**Static** "A static spacetime is a stationary spacetime in which the timelike Killing vector field has vanishing vorticity, or equivalently (by the Frobenius theorem) is hypersurface orthogonal. A static spacetime is one which admits a slicing into spacelike hypersurfaces which are everywhere orthogonal to the world lines of our 'bored observers'"

When we say a field is static, the field is both time-independent and symmetric in a time reversal process.