Review of Linear Algebra

Vectors

$$\overrightarrow{AB} = B - A$$

Length of a vector. II all

Normalization: a= a/ 11 all

Cartesian Coordinates

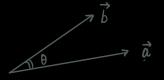
$$A = \begin{pmatrix} x \\ y \end{pmatrix}$$
 $A^T = (x, y)$

Vector Multiplication



/意义 用法

Dot (Scalar> Product 点乘



$$\vec{\alpha} \cdot \vec{b} = \|\vec{\alpha}\| \|\vec{b}\| \cos \theta$$

ZINIT VECTORS: $\cos \theta = \hat{\alpha} \cdot \hat{b}$

$$\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$
$$\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$$
$$(k\vec{a}) \cdot \vec{b} = \vec{a} \cdot (k\vec{b}) = k(\vec{a} \cdot \vec{b})$$

Dot Product in Cartesian Coordinates

- · Component-wise multiplication, then adding up

$$\vec{a} \cdot \vec{b} = \begin{pmatrix} x_a \\ y_a \end{pmatrix} \cdot \begin{pmatrix} x_b \\ y_b \end{pmatrix} = x_a x_b + y_a y_b$$

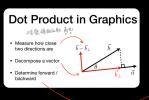
$$\vec{a} \cdot \vec{b} = \begin{pmatrix} x_a \\ y_a \\ z_a \end{pmatrix} \cdot \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix} = x_a x_b + y_a y_b + z_a z_b$$

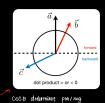
10 Find angle between two vectors

eg. cosine angle between light source and surface

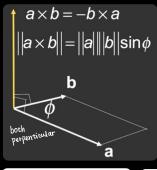
2) Find projection of one vector on another







CHOSE Product



- Direction determined by right-hand rule
- Useful in constructing coordinate systems (later)

不勒尼亥换率

$\vec{x} \times \vec{y} = +\vec{z}$ $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$ $\vec{u} \times \vec{x} = -\vec{z}$ $\vec{a} \times \vec{a} = \vec{0}$ obj $\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$ $\vec{a}\times(k\vec{b})=k(\vec{a}\times\vec{b})$

1 determine left/ Hight



determine inside/outside





• Later in this lecture
$$\vec{a}\times\vec{b}=A^*b=\begin{pmatrix}0&-z_a&y_a\\z_a&0&-x_a\\-y_a&x_a&0\\\text{dual matrix of vector }a&b\\\end{pmatrix}\begin{pmatrix}x_b\\y_b\\z_b\end{pmatrix}$$

Coordinates

Any set of 3 vectors (in 3D) that

$$\|\vec{u}\| = \|\vec{v}\| = \|\vec{w}\| = 1$$

$$\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{w} = \vec{u} \cdot \vec{w} = 0$$

$$\vec{w} = \vec{u} \times \vec{v} \qquad \text{(right-handed)}$$

$$\vec{p} = (\vec{p} \cdot \vec{u})\vec{u} + (\vec{p} \cdot \vec{v})\vec{v} + (\vec{p} \cdot \vec{w})\vec{w}$$
(projection)

在三轴上的抬剔

互相垂直





Matrices

Multiplication

Matrix-Matrix Multiplication

 # (number of) columns in A must = # rows in B (M x N) (N x P) = (M x P)

$$\begin{pmatrix} 1 & 3 \\ 5 & 2 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} 3 & 6 & 9 & 4 \\ 2 & 7 & 8 & 3 \end{pmatrix} = \begin{pmatrix} 9 & ? & 33 & 13 \\ 19 & 44 & 61 & 26 \\ 8 & 28 & 32 & ? \end{pmatrix}$$

• Element (i, j) in the product is the dot product of row i from A and column j from B

- Properties
- Non-commutative
 (AB and BA are different in general)
- Associative and distributive
- (AB)C=A(BC)
- A(B+C) = AB + AC - (A+B)C = AC + BC
- Treat vector as a column matrix (m×1)
- Key for transforming points (next lecture)
- Official spoiler: 2D reflection about y-axis

$$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -x \\ y \end{pmatrix}$$

矩阵的转置 transpose of matrix

Transpose of a Matrix

• Switch rows and columns (ij -> ji)

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}^T = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}$$

Property

$$(AB)^T = B^T A^T$$

Identity Matrix and Inverses

$$I_{3 imes 3} = egin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$AA^{-1} = A^{-1}A = I$$
 互换矩阵

$$(AB)^{-1} = B^{-1}A^{-1}$$

Calculate Vector by Matrices

Vector multiplication in Matrix form

• Dot product?

$$\vec{a} \cdot \vec{b} = \vec{a}^T \vec{b}$$

$$= \begin{pmatrix} x_a & y_a & z_a \end{pmatrix} \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix} = \begin{pmatrix} x_a x_b + y_a y_b + z_a z_b \end{pmatrix}$$

• Cross product?

$$\vec{a} \times \vec{b} = A^*b = \begin{pmatrix} 0 & -z_a & y_a \\ z_a & 0 & -x_a \\ -y_a & x_a & 0 \end{pmatrix} \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix}$$

dual matrix of vector a

dual matrix

