

Review of Linear Algebra

Vectors

$$\vec{AB} = B - A$$

Length of a vector: $\|\vec{a}\|$

Normalisation: $\hat{a} = \vec{a} / \|\vec{a}\|$

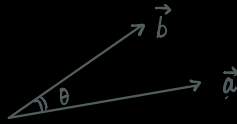
Cartesian Coordinates

$$A = \begin{pmatrix} x \\ y \end{pmatrix} \quad A^T = (x, y) \quad \|A\| = \sqrt{x^2 + y^2}$$

x, y can be any vectors

Vector Multiplication 乘法

Dot (Scalar) Product 点乘



$$\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$$

$$\text{UNIT VECTORS: } \cos \theta = \hat{a} \cdot \hat{b}$$

$$\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

$$\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$$

$$(k\vec{a}) \cdot \vec{b} = \vec{a} \cdot (k\vec{b}) = k(\vec{a} \cdot \vec{b})$$

Dot Product in Cartesian Coordinates

- Component-wise multiplication, then adding up

- In 2D

$$\vec{a} \cdot \vec{b} = \begin{pmatrix} x_a \\ y_a \end{pmatrix} \cdot \begin{pmatrix} x_b \\ y_b \end{pmatrix} = x_a x_b + y_a y_b$$

- In 3D

$$\vec{a} \cdot \vec{b} = \begin{pmatrix} x_a \\ y_a \\ z_a \end{pmatrix} \cdot \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix} = x_a x_b + y_a y_b + z_a z_b$$

用法 / 意义

① Find angle between two vectors

eg. cosine angle between light source and surface

② Find projection of one vector on another

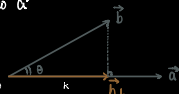
\vec{b}_L : projection of \vec{b} onto \vec{a}

- but

\vec{b}_L must be along \vec{a} or \hat{a}

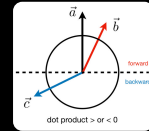
$$\vec{b}_L = k \hat{a}$$

$$k = \|\vec{b}_L\| = \|\vec{b}\| \cos \theta$$



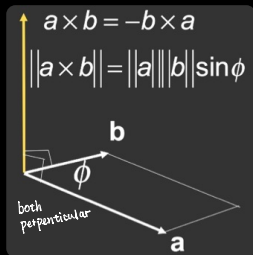
Dot Product in Graphics

- Measure how close two directions are
- Decompose a vector
- Determine forward / backward



$\cos \theta$ determines pos/neg

Cross Product 叉乘



- Cross product is orthogonal to two initial vectors
- Direction determined by right-hand rule
- Useful in constructing coordinate systems (later)

不满足交换律

$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$

$\vec{a} \times \vec{a} = \vec{0}$

$\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$

$\vec{a} \times (k\vec{b}) = k(\vec{a} \times \vec{b})$

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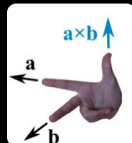
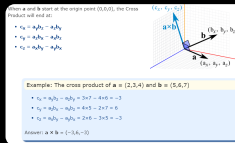
Cross Product: Cartesian Formula?

$$\vec{a} \times \vec{b} = \begin{pmatrix} y_a z_b - y_b z_a \\ z_a x_b - x_a z_b \\ x_a y_b - y_a x_b \end{pmatrix}$$

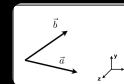
- Later in this lecture

$$\vec{a} \times \vec{b} = A^T b = \begin{pmatrix} 0 & -z_a & y_a \\ z_a & 0 & -x_a \\ -y_a & x_a & 0 \end{pmatrix} \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix}$$

check results of vector a



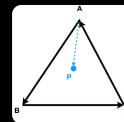
① determine left / right



$\vec{a} \times \vec{b} > 0$ \vec{b} 在 \vec{a} 左侧

$\vec{a} \times \vec{b} < 0$ \vec{b} 在 \vec{a} 右侧

② determine inside / outside



$\vec{AB} \times \vec{AP} > 0$ \vec{AP} 在 \vec{AB} 左侧

$\vec{BC} \times \vec{BP} > 0$ \vec{BP} 在 \vec{BC} 左侧

$\vec{CA} \times \vec{CP} > 0$ \vec{CP} 在 \vec{CA} 左侧

4 均在左侧内 $\rightarrow P$ 在三角形内

Coordinates

- Any set of 3 vectors (in 3D) that

$$\|\vec{u}\| = \|\vec{v}\| = \|\vec{w}\| = 1$$

$$\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{w} = \vec{u} \cdot \vec{w} = 0$$

互相垂直

$$\vec{w} = \vec{u} \times \vec{v} \quad (\text{right-handed})$$

$\vec{x} \quad \vec{x} \quad \vec{y}$

$$\vec{p} = (\vec{p} \cdot \vec{u})\vec{u} + (\vec{p} \cdot \vec{v})\vec{v} + (\vec{p} \cdot \vec{w})\vec{w}$$

(projection)

在三维上的投影

$$\|\vec{p}\| \cdot \|\vec{u}\| \cdot \cos \theta$$

1 单位向量

$$\vec{p}_1 = \|\vec{p}\| \cos \theta \vec{u}$$



Matrices

Multiplication

Matrix-Matrix Multiplication

- # (number of) columns in A must = # rows in B
(M x N) (N x P) = (M x P)

$$\begin{pmatrix} 1 & 3 \\ 5 & 2 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} 3 & 6 & 9 & 4 \\ 2 & 7 & 8 & 3 \end{pmatrix} = \begin{pmatrix} 9 & ? & 33 & 13 \\ 19 & 44 & 61 & 26 \\ 8 & 28 & 32 & ? \end{pmatrix}$$

- Element (i, j) in the product is the dot product of row i from A and column j from B

- Properties

- **Non-commutative**
(AB and BA are different in general)

- Associative and distributive
 - (AB)C = A(BC)
 - A(B+C) = AB + AC
 - (A+B)C = AC + BC

- Treat vector as a column matrix (m x 1)

- Key for transforming points (next lecture)

- Official spoiler: 2D reflection about y-axis

$$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -x \\ y \end{pmatrix}$$

矩阵的转置 transpose of matrix

Transpose of a Matrix

- Switch rows and columns (ij -> ji)

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}^T = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}$$

- Property

$$(AB)^T = B^T A^T$$

Identity Matrix and Inverses

$$I_{3 \times 3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{单位矩阵}$$

$$AA^{-1} = A^{-1}A = I \quad \text{逆矩阵}$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

Calculate Vector by Matrices

Vector multiplication in Matrix form

- Dot product?

$$\vec{a} \cdot \vec{b} = \vec{a}^T \vec{b}$$

$$= \begin{pmatrix} x_a & y_a & z_a \end{pmatrix} \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix} = x_a x_b + y_a y_b + z_a z_b$$

- Cross product?

$$\vec{a} \times \vec{b} = A^* \vec{b} = \begin{pmatrix} 0 & -z_a & y_a \\ z_a & 0 & -x_a \\ -y_a & x_a & 0 \end{pmatrix} \begin{pmatrix} x_b \\ y_b \\ z_b \end{pmatrix}$$

dual matrix of vector a

dual matrix