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This document explains the function of the Solar Panel, its schematic level design, and its board level design

Solar Panel

Solar Panel Design

Revision: 2.1.1



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# Introduction

This document explains how the solar panel will fulfill the following Functions and conform to the following Requirements. This document refers to the Solar Panel version 2.0.

## Functions

The Solar Panel is responsible for the following:

* Harvest energy
* Providing power to charge the batteries located on the EPS

## Requirements

The system requirements and EPS design requirements can be found [here](https://github.com/CougsInSpace/CougSat1-Readme/blob/master/CougSat1-Requirements.pdf).

# Detailed Description

This section references the Solar Panel [schematic](https://github.com/CougsInSpace/CougSat1-Hardware/blob/master/CougSat1-PowerBoard/Documentation/SolarPanel.pdf)[[1]](#footnote-1). Page numbers will be listed and may have coordinates listed (number and letter combination found around the frame).

## Functional Block Diagram

The block diagram can be found on the first page of the schematic.

### Energy Collection

Energy is captured from the sun by the photovoltaic cells. There are two cells on each panel. Each PV is connected to its own battery charger with MPPT[[2]](#footnote-2).

### Power Output

Power is output via two current limited rails from the battery chargers, one from each battery charger.

### ADC

The ADC allows the PMIC to monitor temperature and power at various locations on the board. Sensor locations are indicated on the block diagram.

### Magnetorquer

The magnetorquer is controlled by the [ADCS](https://github.com/CougsInSpace/CougSat1-Hardware/tree/master/CougSat1-AvionicBoard/Documentation).

### Connector

The connector connects the solar panel to the EPS and the ADCS to the magnetorquer.

## Schematic

### Isolated Grounds

The four isolated grounds are found on page 2 of the schematic. Power ground *(PGND)* is connected to pins 6 and 7 of the connector. All other grounds are shorted to *PGND* with a resistor rated for up to . Digital ground *(DGND)* is connected to the digital components of the board. Analog ground *(AGND)* is connected to the analog components, including the ADC, its voltage reference, and the thermistors. Chassis ground *(CHASSIS)* is connected to the conductive mechanical components of the board, including the bolt holes.

### Battery Charger

Page 2 of the schematic contains the battery chargers[[3]](#footnote-3). Each battery charger has a single output, current limited to , contains MPPT technology as well as a boost converter. The batteries are capable of charging at up to , but by charging at the battery health can be preserved. The active low shutdown pin *(X\_SHUT)* is pulled up to the PV output by and resistors in series. output voltage and current are monitored by the ADC.

### ADC

Page 4 of the schematic contains the ADC[[4]](#footnote-4). The ADC has 16 single-ended inputs, or 8 differential inputs, or a combination of the two. The solar panel contains one ADC. The ADC’s address can be configured by selectively stuffing[[5]](#footnote-5) the resistors connected to the address pins. Each pin can be set to either high, low, or left floating. Specific addresses can be found in the [EPS design document](https://github.com/CougsInSpace/CougSat1-Hardware/blob/master/CougSat1-PowerBoard/Documentation/EPS-Design.pdf). The ADC measures differential for each PV input, and each output. Measured as single ended is the temperature at five different locations, the outputs from each battery charger, and the analog voltage rail *(AVDD).*

There is a voltage divider between the ADC’s *MUXOUT* and *ADCIN* pins that cuts the voltage by 80%. Each input also has a 5k series resistor to ensure that when the ADC is switched off, the ESD diodes will not short all the inputs to ground. The voltage divider and the input series resistors bring the input voltage to 83.3% of the original value, so that the ADC inputs will be within the range that it can measure. The total resistance of the voltage divider is , which is the resistance required by the thermistors to function properly.

### Magnetorquer

The magnetorquer can be found on page 3 of the schematic. The magnetorquer is directly connected to pins 8 and 9 on the connector. These will go directly to the ADCS. The magnetorquer shall only be installed on the +Z, -Y, and -X boards, as only three axes are necessary to control the orientation of the satellite.

### Voltage Reference

The high-precision buffered voltage reference[[6]](#footnote-6) can be found on page 2 of the schematic. This chip produces a high precision reference voltage *(AVREF)*, nominally . *AVREF* is used as the absolute voltage reference for calibrating the ADC.

## Board

The board shall be double layered with copper and ENIG finish.

### Layout Constraints

Unless specified in the following subsections, all signals shall use the default parameters specified below. Signals in the following subsections do not include their sense signals unless specified. Trace width can be broken if a trace needs to bottleneck down to a pin, the bottleneck shall be minimized.

Trace width:

Vias: , unlimited count

Separation:

Length: unlimited

Devices with specific placement and Routing considerations are called out in the schematic, see “CAD Note”

#### I2C – I2C\_[SDA, SCL]

Length: Each node shall be length matched

Stubs: <

#### Solar Panel Outputs – PV\_IIN\_P-[A:B] , PV\_IIN\_P-[A:B] , PGND

PGND Applied between the solar panel and output connector

Trace width:

#### MPPT Inputs – MPPT\_LX-[A:B] , PGND

PGND applies between the battery charger and the output connector

Trace Width:

#### Power Outputs – MPPT\_VOUT-[A:B] , VOUT-[A:B]

Trace width:

#### Magnetorquer Inputs – MAGNETORQUER\_[P, N]

Trace width:

#### Input/Output Capacitors – PGND

PGND applies between the input/output capacitors and the output connector

Trace width:

# Testing

All tests shall be performed at room temperature and not under vacuum unless otherwise specified. If any modifications are performed, take note. Include enough information to understand circuit behavior and for others to replicate the results. Include any software written to execute the test and link it in the test notes section. Save all software, waveforms, etc. in a subfolder of the board’s test folder for each test. All tests shall be performed prior to attaching the solar cells to the solar panel.

* Waveforms shall be captured whenever appropriate.
* Have the event take fill the screen (for fast events, zoom in, for slow events, zoom out)
* Label each channel accurately
* Only have bandwidth limiting if necessary for the test (this applies to the oscilloscope and probe settings)
* If ringing or overshoot occurs, use a ground spring or differential probe

Results location: <https://github.com/CougsInSpace/CougSat1-Hardware/tree/master/CougSat1-PowerBoard/Testing/SolarPanel.2.0>

Common test instructions can be found on the [wiki](https://cis.vcea.wsu.edu/wiki/index.php/Cougs_in_Space_Wiki).

## Before First Power-On Check

This test is required to be executed before batteries are attached and before any external power is applied to the Solar Panel.

### Test Instructions

Measure the resistance of various points in reference to PGND located at the output connector.

### Test Data

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Node | Resistance |  | Node | Resistance |
| I2C\_SDA\_PMIC |  |  | VOUT-A |  |
| I2C\_SCL\_PMIC |  |  | VOUT-B |  |
| I2C\_SDA\_ADCS |  |  | AVDD |  |
| I2C\_SCL\_ADCS |  |  | AVREF |  |
| PV\_IIN\_P-A |  |  | 3.3V |  |
| PV\_IIN\_P-B |  |  |  |  |

### Test Notes

Delete me if no notes are required

## Battery Chargers

**Results: Pass / Fail**

This test evaluates the Battery Charger.

### Output Voltage

#### Test Instructions

Apply to the input connector before executing this test. Apply at the solar cell output and measure the voltages of VOUT-A and VOUT-B under no load and a resistive load.

#### Test Data

|  |  |  |  |
| --- | --- | --- | --- |
| Apply to PV\_IIN\_P-A and measure the voltage of VOUT-A at the output connector. | | | |
| Load | Measured Voltage VOUT-A | Passing Criteria | Pass / Fail |
| No Load |  |  |  |
| 300mA |  |  |  |

|  |  |  |  |
| --- | --- | --- | --- |
| Apply to PV\_IIN\_P-B and measure the voltage of VOUT-B at the output connector. | | | |
| Load | Measured Voltage VOUT-B | Passing Criteria | Pass / Fail |
| No Load |  |  |  |
| 300mA |  |  |  |

#### Test Notes

Delete me if no notes are required

### Output Efficiency

#### Test Instructions

Apply to the input connector before executing this test. Apply at the solar cell outputs. Measure the efficiency of the Battery Chargers under to resistive load.

Note: , measure the power across the input and output current shunt resistors.

#### Test Data

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Measure the efficiency of battery charger A under a to resistive load. | | | | | |
| Load | Power in | Power out | Efficiency | Passing Criteria | Pass / Fail |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |

#### Test Notes

Delete me if no notes are required.

### Output Current Limiting

#### Test Instructions

Apply to the input connector before executing this test. Apply at the solar panel output. Apply an increasing load to the Battery Charger output until the current no longer increases.

#### Test Data

|  |  |  |  |
| --- | --- | --- | --- |
| Apply an increasing load to the output until the current no longer increases. | | | |
| Output | Max Current | Passing Criteria | Pass / Fail |
| VOUT-A |  |  |  |
| VOUT-B |  |  |  |

#### Test Notes

Delete me if no notes are required.

## ADC

**Results: Pass / Fail**

### Current Monitoring

#### Test Instructions

Connect the EPS to the Solar Panel with a cable connecting only I2C and GND and charge or discharge the batteries to , and apply to the solar panel outputs before executing this test. Apply a to resistive load to the solar panel output and compare the currents measured by the EPS and a DMM.

Note:

#### Test Data

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Apply at the solar panel output and measure the current across VOUT-A for to resistive loads. | | | | | |
| Current | EPS current | DMM current | Error | Passing Criteria | Pass / Fail |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |

#### Test Notes

Delete me if no notes are required.

### Voltage Monitoring

#### Test Instructions

Connect the EPS to the Solar Panel with a cable connecting only I2C and GND and charge or discharge the batteries to , and apply to the solar panel outputs before executing this test. Apply a resistive load to the solar panel output and compare the output voltages measured by the EPS and a DMM.

Note:

#### Test Data

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Apply a resistive load to VOUT-A and measure the voltage at various signals. | | | | | |
| Signal | EPS Voltage | DMM Voltage | Error | Passing Criteria | Pass / Fail |
| VOUT-A |  |  |  |  |  |
| VOUT-B |  |  |  |  |  |

#### Test Notes

Delete me if no notes are required.

### Temperature Monitoring

#### Test Instructions

Connect the EPS to the Solar Panel and charge or discharge the batteries to before executing this test. Compare the temperature measured by the EPS and a thermometer at the following thermistors:

* FRONT\_TOP
* MPPT-A

Note:

#### Test Data

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Compare the temperature measured by the EPS and a thermometer | | | | | |
| Sensor | EPS Temperature | Thermometer  Temperature | Error | Passing Criteria | Pass / Fail |
| FRONT\_TOP |  |  |  |  |  |
| MPPT-A |  |  |  |  |  |

#### Test Notes

Delete me if no notes are required

1. <https://github.com/CougsInSpace/CougSat1-Hardware/blob/master/CougSat1-PowerBoard/Documentation/SolarPanel.pdf> [↑](#footnote-ref-1)
2. Maximum Power Point Tracking adjusts the output voltage and current to maximize the power taken from the solar cells [↑](#footnote-ref-2)
3. [SPV1040](https://github.com/CougsInSpace/Resources/blob/master/SupplierDocuments/ST/SPV1040.pdf) [↑](#footnote-ref-3)
4. [LTC2499](https://github.com/CougsInSpace/Resources/blob/master/SupplierDocuments/Linear/LTC2499_I2CADC-8DifferentialInputs.pdf) [↑](#footnote-ref-4)
5. Stuffing refers to populating a component during assembly [↑](#footnote-ref-5)
6. [MCP1501](https://github.com/CougsInSpace/Resources/blob/master/SupplierDocuments/Microchip/MCP1501_HighPrecisionVoltageReference.pdf) [↑](#footnote-ref-6)