

MA 214 Short notes

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1 Framework

1. A method approximates to t sig digits if $\left| \frac{x-x^*}{x} \right| \leq 5 \times 10^{-t}$
2. Relative error $\left| \frac{x-x^*}{x} \right| \approx \left| \frac{x-x^*}{x^*} \right|$
3. Loss of sig digits is caused by subtraction of nearly equal quantities, or division by small numbers
4. Condition: Sensitivity to changes in x , $\frac{\Delta f/f}{\Delta x/x} \approx \frac{f'(x)x}{f(x)}$
5. IVT for functions: $f[a, b] \rightarrow \mathbb{R}$, $\exists \xi \in [a, b] \mid \sum f(x_i)g_i = f(\xi) \sim g_i$
6. $\alpha_n = \mathcal{O}(\beta_n)$ if $\alpha_n \leq k\beta_n$ for large n
7. nested multiplication ... less round off error
8. Instability: Sensitivity to digital round off errors

2 Interpolation

1. Weierstraß approximation: $\forall \epsilon \exists P(x)$ such that $|f(x) - p(x)| < \epsilon$
2. Lagrange polynomial: $l_k(x) = \prod_{i \neq k} \frac{x-x_i}{x_k-x_i}$; $p_n(x) = \sum l_k(x)f(x_k)$
3. Divided diff: $P_n(x) = P_{n-1}(x) + a_n(x-x_0)(x-x_1)(\dots)$, $f[x_0, x_1, \dots, x_n] = a_n$
4. $f[x_0 \dots x_k] = \frac{f[x_1 \dots x_k] - f[x_0 \dots x_{k-1}]}{x_k - x_0}$

5. Error in estimating $f(\bar{x})$ is $e_n(\bar{x}) = f[x_0, x_1 \dots x_n, \bar{x}] \prod (\bar{x} - x_j)$
6. Osculatory: If derivatives at x_0 come n times, repeat x_0 , n times and say that $f[x_0, x_0 \dots n \text{ times}] = f^{(n)}(x)$
7. $\exists \xi \in [x_0, x_k] \mid f[x_0 \dots x_k] = \frac{f^{(k)}(\xi)}{k!}$
8. hermite (piecewise cubic) interpolation: Same as osculatory, but piecewise
9. Cubic spline: ?
10. $f[x_0 \dots x_k, x_{k+1}] = f[x_0 \dots x_{k+1}] + f[x_0, \dots]$

3 Integration

1. Error:
 - (a) If ψ_k is of one sign in interval, $E(f) = \frac{f^{(k+1)}(\xi)}{(k+1)!} \int \psi_k(x) dx$ where $\psi_k(x) = \prod (x - x_j)$
 - (b) If the integral is zero, $E(f) = \frac{f^{(k+2)}(\xi)}{(k+2)!} \int \psi_{k+1}(x) dx$

4 Matrices

4.1 LU factorization

To solve $Ax = b$, we first write $A = LU$, where the two matrices are l. triangular and u. triangular respectively. As there are ∞ solutions, set diagonal of L to 1 before proceeding.

Now solve $L(Ux) = b \implies Ly = b$, then solve $Ux = y$.