

Fitting a model to data

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1205.4446.

= fitting a straight line

= standard practice & the magic of Gaussians.

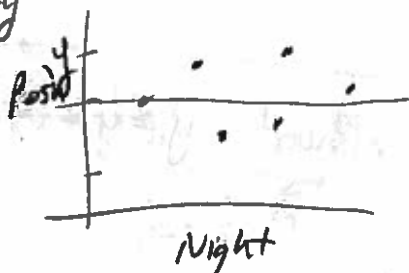
= uncertainties & likelihoods

Following lectures

= outliers & model selection

= MCMC

Night	Pos'n y	Uncertainty - ("Error")
1	6	
2	5	
3	8	
4		
5		
6		
Avg.		



$$y_{\text{avg}} = \frac{1}{N} \sum_i y_i$$

Model - position y is a constant

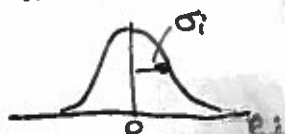
- measurements $y_i = y + e_i$

- e_i are drawn from a probability distribution.

- e_i are independent (of each other)

- prob. distribution is Gaussian with given σ_i and mean zero

prob.

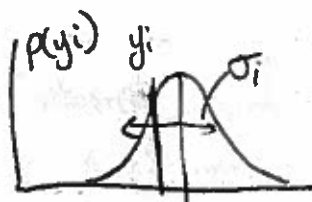
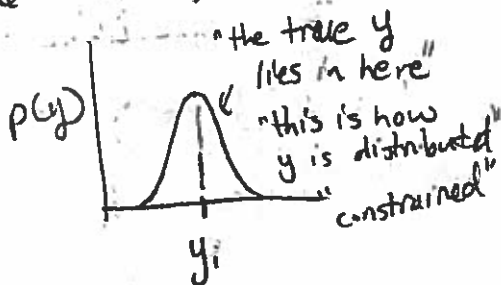


$$p(e_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{e_i^2}{\sigma_i^2}\right)$$

Aside:

experimentalist

data analyst



↓ y
"this is our model for how y_i is distributed given y "

- likelihood. $y_i = y + e_i$, $p(e_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{e_i^2}{\sigma_i^2}\right)$

$$y_i - y = e_i$$

$$p(y_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$

$$p(y_i | y) = \dots$$

- notation: Gaussian (Normal) distrib.

$$N(\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{\mu^2}{\sigma^2}\right)$$

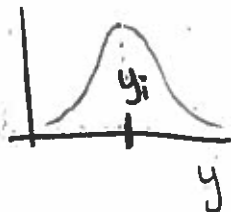
drawn from

$$e_i \sim N(\mu=0, \sigma^2=\sigma_i^2) \sim N(0, \sigma_i^2)$$

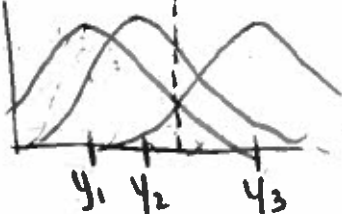
$$y_i \sim N(\mu=y, \sigma^2=\sigma_i^2) \sim N(y, \sigma_i^2)$$

likelihood \rightarrow constraint on y .

$p(y_i | y)$



$p(y_i | y)$

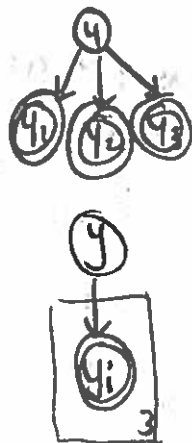


• y independent

$$p(y_1, y_2, y_3 | y) = p(y_1 | y) \cdot p(y_2 | y) \cdot p(y_3 | y)$$

$$p(\{y_i\} | y) = \prod_i p(y_i | y)$$

$$= \prod_i \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}\right)$$



Treat this as a function we're going to optimize by varying y .

$$\log(p(\{y_i\} | y)) = \sum_i \log\left(\frac{1}{\sqrt{2\pi}\sigma_i}\right) + \sum_i \frac{1}{2} \frac{(y_i - y)^2}{\sigma_i^2}$$

$$\frac{d}{dy} \mathcal{L} = \sum_i -\frac{1}{2} \cdot 2 \frac{(y_i - y)}{\sigma_i^2} \cdot (-1)$$

talk about
chi-sq.
 \rightarrow

$$\frac{d}{dy} \mathcal{L} = 0 = \sum_i \frac{y_i - \hat{y}}{\sigma_i^2} = \sum_i \frac{y_i}{\sigma_i^2} - \hat{y} \sum_i \frac{1}{\sigma_i^2}$$

$$\boxed{\hat{y} = \frac{\sum_i \frac{y_i}{\sigma_i^2}}{\sum_i \frac{1}{\sigma_i^2}}}$$

$$\rightarrow \chi_i = \frac{y_i - \hat{y}}{\sigma_i}$$

$$\text{"chi-squared"} = \sum_i \chi_i^2 = \sum_i \frac{(y_i - \hat{y})^2}{\sigma_i^2}$$

we are going to find \hat{y} that maximizes the likelihood of observations $\{y_i\}$.

"Maximum likelihood analysis"

or Find \hat{y} to minimize chi-squared.

Result \hat{y} known as inverse-variance weighting.

Finally,	Night	Position y_i	Uncertainty σ_i
	1	6	1
	2	5	1
	3	8	1
	4		1
Avg.	$\hat{y} = 6\frac{1}{3}$		$\sigma = \frac{1}{\sqrt{3}} = 0.58$
ML			

From magic of Gaussians

$$\sum_i \frac{(y_i - \hat{y})^2}{\sigma_i^2} = \frac{(\hat{y} - y)^2}{\hat{\sigma}^2} + c$$

match up terms ^{containing} y^2

$$\sum_i \frac{y^2}{\sigma_i^2} = \frac{y^2}{\hat{\sigma}^2}$$

$$\hat{\sigma}^2 = \frac{1}{\sum_i \frac{1}{\sigma_i^2}}$$

What can we say about our uncertainty on \hat{y} ?

Frequentist vs Bayesian

↳ confidence interval

"In a poll of 300 voters, 30% said they would support X. The results are considered accurate to $\pm 5\%$, 19 times out of 20"

→ if you repeated this experiment, in 95% of the cases the reported confidence interval would contain the truth

→ NOT: there is a 95% chance that the true value lies within the confidence interval.

- not going to say more about Frequentist methods

Change σ_3 to $\frac{1}{2}$,

Night	y	σ
1	6	1
2	5	1
3	8	$\frac{1}{2}$
ML	$7\frac{1}{6}$	

Bayesian stats

starts from

$$P(A, B) = P(A)P(B|A) = P(B)P(A|B)$$

$$P(B|A) = \frac{P(A|B) P(B)}{P(A)}$$

B: y has value \hat{y}

A: we measure $\{y_i\}$

$$P(y = \hat{y} | \{y_i\}) = \frac{\overbrace{P(\{y_i\} | y = \hat{y})}^{\text{likelihood}} \overbrace{p(y = \hat{y})}^{\text{prior}}}{\underbrace{P(\{y_i\})}_{\text{evidence.}}}$$

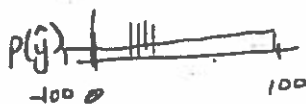
posterior probability

- evidence is constant here

- "uninformative" or "flat" prior:

$$P(y = \hat{y}) = p(\hat{y}) = C \quad (\text{"improper"})$$

$$\int_{\hat{y}=-\infty}^{+\infty} p(\hat{y}) = 1.$$



Then

$$p(\hat{y} | \{y_i\}) \propto P(\{y_i\} | \hat{y})$$

$$\propto \mathcal{L} = \prod_i N(y_i, \sigma_i^2)$$

$$P(\hat{y} | \{y_i\}) = N \left(\mu = \frac{\sum_i \frac{y_i}{\sigma_i^2}}{\sum_i \frac{1}{\sigma_i^2}}, \sigma^2 = \frac{1}{\sum_i \frac{1}{\sigma_i^2}} \right)$$

Night	Pos'n	Unc.
1	6	1
2	5	1
3	8	1
Model	$6\frac{1}{3}$	$\frac{1}{\sqrt{3}} \approx 0.58$

- assume a model μ
- assume a measurement process $y_i = \mu + e_i$
- noise $e_i \sim \text{Gaussian}(0, \sigma_i^2)$
- measurements stat, independent
- become Bayesian
- put a flat prior on y .