```
2.5.3 Variance (\sigma_X^2 = V(X))
      ST2334 Finals Cheatsheet v1.0 (2019-05-08)
                                                                                                                                       Mutually Independent:
                                                                                                                                      Events A_1, A_2, ..., A_n are (mutually) independent iff for any subset g(x) = (x - \mu_X)^2, Let X be an R.V. with p.f. f(x)
      by Julius Putra Tanu Setiaji, page 1 of 2
                                                                                                                                      \{A_{i_1}, A_{i_2}, ..., A_{i_k}\}\ of A_1, A_2, ..., A_n,
    Basic Concepts of Probability
                                                                                                                                     \Pr(A_{i_1} \cap A_{i_2} \cap \dots \cap A_{i_k}) = \Pr(A_{i_1}) \Pr(A_{i_2}) \dots \Pr(A_{i_k})
     Sample space = sure event, subset of S = \emptyset = \text{null event}
    Mutually exclusive/disjoint if A \cap B = \emptyset
                                                                                                                                      A_1, A_2, ..., A_n are mutually independent \Leftrightarrow for any pair of events A_i, A_k
    Contained: A \subset B \equiv B \supset A.
     If A \subset B and B \supset A, then A = B
                                                                                                                                      where j \neq k, the multiplication rule holds, for any 3 distinct events, the multi-
 .1 Basic Properties
                                                                                                                                      plication rule holds, and so on Pr(A_1 \cap A_2 \cap ... \cap A_n) = Pr(A_1)Pr(A_2)...Pr(A_n)
                                                               • A \cap (B \cup C) = (A \cap B) \cup (A \cap C)
                                                                                                                                      In total there are 2^n - n - 1 diff cases.
   (A \cup B)' = A' \cap B'
                                                               • A \cup B = A \cup (B \cap A')
                                                                                                                                       Mutually indep ⇒ pairwise indep (not the converse)
    A \cup (B \cap C) = (A \cup B) \cap (A \cup C)
                                                               • A = (A \cap B) \cup (A \cap B')
                                                                                                                                      Suppose A_1, A_2, ..., A_n are mutually indep events, let B_i = A_i or A_i', i \in [1, n]. Definition: E(X^k), use g(x) = x^k in expectation of a fin
.2 De Morgan's Law
                                                                                                                                      Then B_1, B_2, \dots, B_n are also mutually indep events.
                                                              • (\bigcap_{r=1}^{n} A_r)' = \bigcup_{r=1}^{n} (A_r)'
    (\bigcup_{r=1}^{n} A_r)' = \bigcap_{r=1}^{n} (A_r)'
                                                                                                                                      Concepts of Random Variables
                                                                                                                                         Equivalent Events
1.3 Counting Methods
                                                                                                                                  2.1.1 Definition
1.3.1 Multiplication & Addition Principle
                                                                                                                                      Let E be an experiment in sample space S. Let X be an R.V. defined on S
1.3.2 Permutation
                                                                                                                                      and R_Y its range space, i.e. X: \overrightarrow{S} \to \mathbb{R}
   An arrangement of r objects from a set of n objects, r \le n, order taken into
                                                                                                                                      Let B be an event w.r.t. R_X, i.e. B \subset R_X
  n distinct objects taken r at a time = nP_r = \frac{n!}{(n-r)!}
                                                                                                                                      (A consists of all sample points s in S for which X(s) \in B)
  In a circle: (n-1)!
                                                                                                                                      A and B are equivalent events, and Pr(B) = Pr(A)
 Not all are distinct: \sum_{r=1}^{k} n_k = n, {}_{n}P_{n_1,n_2,...,n_k} = \frac{n!}{n_1!n_2!...n_k!}
                                                                                                                                  2.1.2 Example
                                                                                                                                      Consider tossing a coin twice, S = \{HH, HT, TH, TT\}
                                                                                                                                     Let X be no of heads, then R_X = \{0, 1, 2\}

    No of ways selecting r from n objects w/o regarding order

                                                                                                                                      A_1 = \{HH\} \text{ equiv } B_1 = \{2\}, A_2 = \{HT, TH\} \text{ equiv } B_2 = \{1\}, A_3 = \{TT\} \text{ equiv } B_1 = \{TT\} \text{ equiv } B_2 = \{TT\} \text{ equiv } B_1 = \{TT\} \text{ equiv } B_2 = \{TT\} \text{ eq
  \binom{n}{r} = {n \choose r} = \frac{n!}{r!(n-r)!}, \, {n \choose r} \times r! = {n \choose r}
                                                                                                                                      B_3 = \{0\}, A_4 = \{HH, HT, TH\} \text{ equiv } B_4 = \{2, 1\}
                                                                                                                                  2.2 Discrete Probability Distributions
   \binom{n}{r} = binom coeff of the term a^r b^{n-r} in binom expansion of (a+b)^n:
                                                                                                                                  2.2.1 Discrete R.V.
    \binom{n}{r} = \binom{n}{n-r} for r = 0, 1, ..., n
                                                                                                                                  Let X be an RV. If R_X is finite or countable infinite, X is discrete RV
  -\binom{n}{r} = \binom{n-1}{r} + \binom{n-1}{r-1} for 1 \le r \le n
                                                                                                                                  2.2.2 Probability Fn (p.f.) or Probability Mass Function (p.m.f.)
                                                                                                                                      For a discrete R.V., each value X has a certain probability f(x). Such a func-
  -\binom{n}{r} = 0 \text{ for } r < 0 \text{ pr } r > n
                                                                                                                                      tion f(x) is called the p.f.
1.4 Relative frequency (f_{\Delta})
                                                                                                                                      The collection of pairs (x_i, f(x_i)) is prob distribution of X
                                                                                                                                    The collection of pairs (x_i, f(x_i)) is prob distribution of X. The probability of X = x_i denoted by f(x_i) must satisfy: f(x_i) \ge 0 \ \forall x_i and 3.2.1 For Discrete RV
f_A = \frac{n_A}{n}, event A in n repetitions of experiment E, n_A = \text{no of times that event}.
\stackrel{\sim}{A} occurred among the n repetitions.
1.5 Axioms of Probability
                                                                                                                                  2.3 Continuous Probability Distributions

    If A<sub>1</sub>, A<sub>2</sub>,... are mutually exclusive (disjoint),

                                                                                                                                  2.3.1 Continuous R.V.
  i.e. A_i \cap A_j = \emptyset when i \neq j, then \Pr(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \Pr(A_i)
                                                                                                                                  Suppose that R_X is an interval or a collection of intervals, then X is a continu-
                                                                                                                                 ous R.V.
2.3.2 Probability Density Function (p.d.f.)
   If events A and B are mutually exclusive, then Pr(A \cup B) = Pr(A) + Pr(B)
.6 Properties of Probability
                                                                                                                                     Let X be a continuous R.V.
  If A_1, A_2, ..., A_n are mutually exclusive, then \Pr(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n \Pr(A_i)
                                                                                                                                      p.d.f. f(x) is a function satisfying:
   Pr(A) = Pr(A \cap B) + Pr(A \cap B')
                                                                                                                                      -f(x) \ge 0 \,\forall \, x \in R_X
                                                                                                                                     -\int_{R_{\mathbf{Y}}} f(x) dx = 1 \text{ or } \int_{-\infty}^{\infty} f(x) dx = 1 \text{ as } f(x) = 0 \,\forall x \notin R_{\mathbf{X}}
   Pr(A \cup B) = Pr(A) + Pr(B) - Pr(A \cap B)
  Pr(A \cup B \cup C) = Pr(A) + Pr(B) + Pr(C) - Pr(A \cap B) - Pr(B \cap C) - Pr(A \cap C) + Pr(A \cap B \cap C)
                                                                                                                                     - \forall c, d : c < d \text{ (i.e. } (c, d) \subset R_X), \Pr(c \le X \le d) = \int_c^d f(x) dx
   The Inclusion-Exclusion Principle
  \Pr(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n \Pr(A_i) - \sum_{i=1}^{n-1} \sum_{j=i+1}^n \Pr(A_i \cap A_j) + \sum_{i=1}^{n-2} \sum_{j=i+1}^{n-1} \sum_{k=j+1}^n \Pr(A_i \cap A_j \cap A_j)
                                                                                                                                      \Pr(c \le X \le d) = \int_{c}^{d} f(x) dx represents area under the graph of the p.d.f. f(x) | f_{X,Y}(x,y) | is called joint pdf if it satisfies:
                                                                                                                                     between x = c and x = d

Let x_0 be a fixed value, Pr(X = x_0) = 0

\leq and < can be used interchangeably in a prob statement.
1.7 Conditional Probability, P(A \mid B)
  Pr(A \mid B) = \frac{Pr(A \cap B)}{Pr(B)}, if Pr(A) \neq 0
                                                                                                                                      Pr(A) = 0 does not necessarily imply A = \emptyset
                                                                                                                                      R_{\mathbf{Y}} \in [a,b] \Rightarrow f(x) = 0 \,\forall \, x \notin [a,b]
  For fixed A, Pr(B \mid A) satisfies the postulates of probability.
                                                                                                                                  2.4 Cumulative Distribution Function (c.d.f.)
   False positive: Pr(+ | condition)
                                                                                                                                  Let X be an R.V., disc or cont. F(x) is a cdf of X where F(x) = Pr(X \le x)
1.7.1 Multiplication rule
                                                                                                                                  2.4.1 c.d.f. for Discrete R.V.
   Pr(A \cap B) = Pr(A)Pr(B \mid A) = Pr(B)Pr(A \mid B), providing Pr(A) > 0, Pr(B) > 0
                                                                                                                                     F(x) = \sum_{t \le x} f(t) = \sum_{t \le x} \Pr(X = t)
c.d.f. of a discrete R.V. is a step function
   Pr(A \cap B \cap C) = Pr(A)Pr(B \mid A)Pr(C \mid A \cap B)
  Pr(A_1 \cap ... \cap A_n) = Pr(A_1)Pr(A_2 \mid A_1)Pr(A_3 \mid A_1 \cap A_2)...Pr(A_n \mid A_1 \cap ... \cap A_{n-1})
                                                                                                                                      \forall a, b \text{ s.t. } a \leq b, \Pr(a \leq X \leq b) = \Pr(X \leq b) - \Pr(X < a) = F(b) - F(a^{-}) \text{ where } a^{-}
1.7.2 The Law of Total Probability
                                                                                                                                      is the largest possible value of X strictly less than a
  Let A_1, A_2, ..., A_n be a partition of sample space S (mutually exclusive & ex-
                                                                                                                                      R_X \subset \mathbb{Z}, \tilde{a}, b \in \mathbb{Z} \Rightarrow
   haustive events s.t. A_i \cap A_j = \emptyset for i \neq j and \bigcup_{i=1}^n A_i = S).
                                                                                                                                      -\Pr(a \le X \le b) = \Pr(X = a \text{ or } a + 1 \text{ or ... or } b) = F(b) - F(a - 1)
                                                                                                                                     - Taking a = b, Pr(X = a) = F(a) - F(a - 1)
 Then Pr(B) = \sum_{i=1}^{n} Pr(B \cap A_i) = \sum_{i=1}^{n} Pr(A_i) Pr(B \mid A_i)
                                                                                                                                  2.4.2 c.d.f. for Continuous R.V.
                                                                                                                                     F(x) = \int_{-\infty}^{\infty} f(t) dt
   Let A_1, A_2, ..., A_n be a partition of S
                                                                                                                                      f(x) = \frac{dF(x)}{dx} if the derivative exists
  \Pr(A_k \mid B) = \frac{\Pr(A_k)\Pr(B \mid A_k)}{\sum_{i=1}^n \Pr(A_i)\Pr(B \mid A_i)} = \frac{\Pr(A_k)\Pr(B \mid A_k)}{\Pr(B)}, k \in [1, n]
                                                                                                                                      \Pr(a \le X \le b) = \Pr(a < X \le b) = F(b) - F(a)
                                                                                                                                      F(x) is a non-decreasing function: x_1 < x_2 \Rightarrow F(x_1) \le F(x_2); and 0 \le F(x) \le 1
1.8 Independent Events
  Definition: iff Pr(A \cap B) = Pr(A)Pr(B)
                                                                                                                                  2.5 Mean and Variance of an R.V.
                                                                                                                                  2.5.1 Expected Value / Mean / Mathematical Expectation
   Suppose Pr(A) > 0, Pr(B) > 0, A and B are independent:
                                                                                                                                     Discrete: E(X) = \mu_X = \sum_i x_i f(x_i) = \sum_X x f(x)
   - Pr(B \mid A) = Pr(B) and Pr(A \mid B) = Pr(A)
                                                                                                                                     If f(x) = \frac{1}{N} for each of the N values of x, E(X) = \frac{1}{N} \sum_{i} x_{i}
   - A and B cannot be mutually exclusive (and vice versa)
                                                                                                                                     Continuous: E(X) = \mu_X = \int_{-\infty}^{\infty} x f(x) dx
   The sample space S and \emptyset are independent of any event
 If A \subseteq B, then A and B are dependent unless B = S
                                                                                                                                      Remark: The expected value exists if the sum/integral exists
Warning: Indep events can't be shown using Venn Diagram, so calc!!!
                                                                                                                                   2.5.2 Expectation of a function of an R.V.
1.8.2 Theorem
                                                                                                                                   g(X) with p.f. f_X(x)
If A, B are indep, then so are A and B', A' and B, A' and B'.
                                                                                                                                     Discrete: E[g(X)] = \sum_{X} g(x) f_{X}(x)
1.8.3 n Independent Events
                                                                                                                                      Continuous: E[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx
 Pairwise Independent Events:
   Events A_1, A_2, ..., A_n are pairwise indep iff Pr(A_i \cap A_i) = Pr(A_i)Pr(A_i)
                                                                                                                                      Provided the sum/integral exists.
```

```
\sigma_X^2 = V(X) = E[(X - \mu_X)^2]
          E[(X - \mu_X)^2] = \begin{cases} \sum_X (x - \mu_X)^2 f_X(x) & \text{if } X \text{ is discrete} \\ \int_{-\infty}^{\infty} (x - \mu_X)^2 f_X(X) dx & \text{if } X \text{ is continuous} \end{cases}
          Standard deviation = \sigma_V = \sqrt{V(X)}
    2.5.4 K-th moment of X
     2.5.5 Properties of Expectation
          E(aX + b) = aE(X) + b
         V(X) = E(X^2) - [E(X)]^2
    • V(aX + b) = a^2V(X)
    2.6 Chebyshev's Inequality
         Let X be an R.V. with E(X) = \mu, V(X) = \sigma^2
          \forall k > 0, \Pr(|X - \mu| > k\sigma) \le \frac{1}{k^2} \text{ OR } \Pr(|X - \mu| \le k\sigma) \ge 1 - \frac{1}{k^2}
          Holds for all distributions with finite mean and variance Gives a lower bound but not exact probability.
3 2D RV & Conditional Probability Distrubutions
3.1 2D RV Definition (Random Vector)

• Let E be experiment and S sample space assoc with E. Let X and Y be 2 discrete uniform distribution, and the probability function is f_X(x) = \frac{1}{k} \cdot x 
         functions each assigning a real number to each s \in S. (X, Y) is a 2D RV
            Range Space: R_{X,V} = \{(x,y) \mid x = X(s), y = Y(s), s \in S\}
           The definition can be extended to n-dimensional RV (or n-dimensional ran \mu = E(X) = \sum x f_X(x) = \frac{1}{k} \sum_{i=1}^k x_i
           dom vector) for X_1, X_2, ..., X_n.
          dom vector) for X_1, X_2, ..., X_n.

(X, Y) is a 2D discrete RV if the possible values of (X(s), Y(s)) are finite or \sigma^2 = V(X) = \sum_{i=1}^n (x_i - \mu)^2 f_X(x) = \frac{1}{k} \sum_{i=1}^k (x_i - \mu)^2 f_X(x) = \frac{1
           coutable infinite. (X, Y) is a 2D continuous RV if the possible values of (X(s), Y(s)) can assume \sigma^2 = E(X^2) - \mu^2 = \frac{1}{k} (\sum_{i=1}^k x_i^2) - \mu^2
           all values in some region of the Euclidean plane \mathbb{R}^2
 Let (X, Y) be a 2D discrete RV. With each possible value (x_i, y_j), we associate a 4.2.1 Bernoulli Distribution
   number f_{X,Y}(x_i,y_i) representing Pr(X=x_i,Y=y_i) and satisfying
         f_{X,Y}(x_i,y_i) \ge 0 \forall (x_i,y_i) \in R_{X,Y}
  • \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} f_{X,Y}(x_i, y_j) = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} \Pr(X = x_i, Y = y_j) = 1
The function f_{X,Y}(x,y) defined \forall (x_i, y_j) \in R_{X,Y} is called joint probability
  Let A be any set consisting of pairs of (x, y) values, then:
  \Pr((X,Y) \in A) = \sum \sum_{(x,v) \in A} f_{X,Y}(x,y)
  3.2.2 For Continuous RV
 Let (X,Y) be a 2D continuous RV assuming all values in some region R of the
 Euclidean plane \mathbb{R}^2.
   • f_{X,Y}(x,y) \ge 0 \ \forall (x,y) \in R_{X,Y}
  • \iint_{(x,y)\in R_{X,Y}} f_{X,Y} dy dx = 1 \text{ or } \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy dx = 1
  3.3 Marginal and Conditional Probability Distributions
  3.3.1 Marginal Probability Distributions
  Let (X,Y) be a 2D RV with joint pdf f_{X,Y}(x,y). The marginal probability dis-
 tributions of X and Y are:
• Discrete: f_X(x) = \sum_y f_{X,Y}(x,y) and f_Y(y) = \sum_x f_{X,Y}(x,y)
• Cont: f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy and f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx
    3.3.2 Conditional Distribution
   Let (X,Y) be a 2D RV with joint pdf f_X y(x,y), let f_X(x) and f_Y(y) be the
   marginal probability functions of X and Y respectively.
   Then the conditional distribution of Y given that X = x:
f_{Y|X}(y \mid x) = \frac{f_{X,Y}(x,y)}{f_{X}(x)}, if f_{X}(x) > 0 for each x \in \text{range of } X
Similarly, the conditional distrubution of X given Y = y:
  f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_{Y}(y)}, if f_{Y}(y) > 0 for each y \in \text{range of } Y
   Remarks:
           The conditional pdf satisfy all the regs for a 1D pdf:
           - For a fixed y, f_{X|Y}(x|y) \ge 0, for a fixed x, f_{Y|X}(y|X) \ge 0
           - For discrete RV: \sum_{x} f_{X|Y}(x \mid y) = 1 and \sum_{y} f_{Y|X}(y \mid x) = 1
          - For cont RV: \int_{-\infty}^{\infty} f_{X|Y}(x|y) dx = 1 and \int_{-\infty}^{\infty} f_{Y|X}(y|x) dy = 1
For f_X(x) > 0, f_{X,Y}(x,y) = f_{Y|X}(y|x) f_X(x). For f_Y(y) > 0, f_{X,Y}(x,y) = f_{Y|X}(x) f_{X,Y}(x) f_{Y,Y}(x) = f_{Y|X}(x) f_{Y,Y}(x) f_{Y,Y}(x
           f_{X|Y}(x|y)f_Y(y)
   3.4 Independent RV
   RV X and Y are independent iff f_{X,Y}(x,y) = f_X(x)f_Y(y) \forall x,y
   This defin can be extended to RV X_1, X_2, ..., X_n
         The product of 2 positive functions f_X(x) and f_Y(y) means a function which 4.5 Continuous Uniform Distribution (U) or Rectangular Distribution
           is positive on a product space.
                                                                                                                                                                                                                                                                                                      RV has uniform distr over interval [a, b], -\infty < a < b < \infty, denoted by U(a, b)
           i.e. if f_X(x) > 0 for x \in A_1 and f_Y(y) > 0 for x \in A_2, then f_X(x)f_Y(y) > 0 for
                                                                                                                                                                                                                                                                                                      if its pdf is f_X(x) = \frac{1}{h-a} for a \le x \le b and 0 otherwise.
           (x,y) \in A_1 \times A_2
                                                                                                                                                                                                                                                                                                     E(X) = \frac{a+b}{2}, V(X) = \frac{1}{12}(b-a)^2
```

```
3.5 Expectation
E[g(X,Y)] = \begin{cases} \sum_{X} \sum_{y} g(x,y) f_{X,Y}(x,y) & \text{for Disc RV} \\ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) dx dy & \text{for Cont RV} \end{cases}
3.5.1 Covariance
Let g(X, Y) = (X - \mu_X)(Y - \mu_Y).
Let (X, Y) be a bivariate RV with joint pdf f_{X,Y}(x, y), then the covariance of X,
is Cov(X, Y) = E[(X - \mu_X)(Y - \mu_Y)]
   Discrete: Cov(X,Y) = \sum_{X} \sum_{Y} (x - \mu_X)(y - \mu_Y) f_{X,Y}(x,y)
   Cont: Cov(X,Y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y) f_{X,Y}(x,y) dx dy
   Cov(X,Y) = E(XY) - \mu_X \mu_Y
   If X, Y are independent, then Cov(X, Y) = 0.
   Cov(aX + b, cY + d) = acCov(X, Y)
   V(aX + bY) = a^{2}V(X) + b^{2}V(Y) + 2abCov(X, Y)
 3.5.2 Correlation Coefficient
 Cor(X,Y) = \rho_{X,Y} = \frac{Cov_{X,Y}}{\sqrt{V(X)}\sqrt{V(Y)}}
   \rho_{X,Y} = measure of degree of linear r/s b/w X and Y
   If X, Y are independent, then \rho_{X,Y} = 0.
4 Special Probability Distributions
4.1 Discrete Uniform Distribution
x_1, x_2, ..., x_k, and 0 otherwise.
4.1.1 Mean and Variance of Discrete Uniform Distribution
4.2 Bernoulli and Binomial Distribution
The collection of all probability distributions for different values of the param
is called a family of probability distributions.
   A random experiment with only 2 possible outcomes.
   RV X has a Bernoulli distribution if the probability function of X is f_X(s) =
   p^{X}(1-p)^{1-x}, x=0.1 where 0 , 0 for other X values, p is the param.
   Pr(X = 1) = p \text{ and } Pr(X = 0) = 1 - p = q
   \mu = E(X) = p, \sigma^2 = V(X) = p(1-p) = pq
 1.2.2 Binomial Distributions
   RV X has a Binomial distr with 2 params n and p (X \sim B(n, p)), if the prob fn
   of X is Pr(X = x) = f_X(x) = \binom{n}{x} p^x q^{n-x} for x = 0, 1, ..., n where 0 
   X is the no of successes in n independent Bernoulli trials.
   Bernoulli distribution is a special case of Binom distr when n = 1
   \mu = E(X) = np, \sigma^2 = V(X) = npq
   Conditions: (1) consists of n repeated Bernoulli trials, (2) Only 2 possible
   outcomes in each trial. (3) Pr(success) = p is constant in each trial. (4) trials
   are independent
 1.2.3 Negative Binomial Distribution
   Like binom, but trials will be repeated until a fixed no of successes occur
   (prob the k-th success occurs on the x-th trials vs prob x successes in n trials)
   Let X be a RV represents no of trials to produce k successes in a sequence of
   independent Bernoulli trials, B \sim NB(k, p)
   Pr(X = x) = f_X(x) = {x-1 \choose k-1} p^k q^{x-k} for x = k, k+1, k+2,...
   E(X) = \frac{k}{n}, V(X) = \frac{(1-p)k}{2}
   Special case: No of trials to the first success is Geometric distribution
   (X \sim NB(1,p) \equiv X \sim Geom(p))
4.3 Poisson Distribution

    RV X, no of successes during a given time interval/in a specified region

  \Pr(X = x) = f_X(x) = \frac{e^{-\lambda} \lambda^x}{x!} for x = 0, 1, 2, 3, ... where \lambda = average no of successes occurring in the given time interval/specified region
   E(X) = V(X) = \lambda
   Properties: (1) No of successes in one time interval/specified region are in
   dependent of those in any other disjoint time interval/region of space, (2)
   The prob of a single success during a short time interval/in a small region is
   proportional to length of time interval/size of region, and does not depend
   on no of successes outside this time interval/region, (3) The prob of more
   than one success in such a short time interval/falling in such a small region
   is neglibible
4.4 Poisson Approximation to the Binomial Distribution
   Let X \sim B(n, p), suppose that n \to \infty and p \to 0 such that \lambda = np remains a
   constant as n \to \infty, then X will have approx a Poisson distr with param np
  \lim_{p\to 0, n\to\infty} \Pr(X=x) = \frac{e^{-np}(np)^x}{x!}
• If p \to 1, can stil use by swapping success & failure s.t. p \to 0
```

