

Predicting Real-valued outputs: an introduction to Regression

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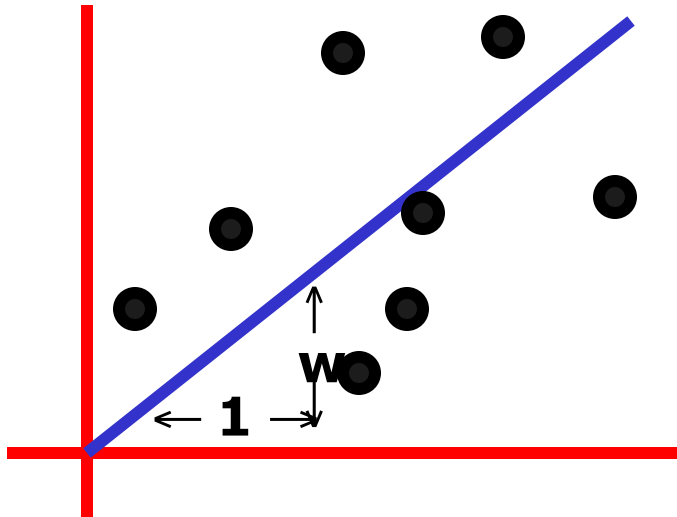
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This is reordered material
from the Neural Nets
lecture and the "Favorite
Regression Algorithms"
lecture

Single-Parameter Linear Regression

Linear Regression

DATASET



inputs	outputs
$x_1 = 1$	$y_1 = 1$
$x_2 = 3$	$y_2 = 2.2$
$x_3 = 2$	$y_3 = 2$
$x_4 = 1.5$	$y_4 = 1.9$
$x_5 = 4$	$y_5 = 3.1$

Linear regression assumes that the expected value of the output given an input, $E[y|x]$, is linear.

Simplest case: $\text{Out}(x) = wx$ for some unknown w .

Given the data, we can estimate w .

1-parameter linear regression

Assume that the data is formed by

$$y_i = wx_i + \text{noise}_i$$

where...

- the noise signals are independent
- the noise has a normal distribution with mean 0 and unknown variance σ^2

$p(y|w,x)$ has a normal distribution with

- mean wx
- variance σ^2

Bayesian Linear Regression

$$p(y|w,x) = \text{Normal}(\text{mean } wx, \text{var } \sigma^2)$$

We have a set of datapoints (x_1, y_1) (x_2, y_2) ... (x_n, y_n) which are **EVIDENCE** about w .

We want to infer w from the data.

$$p(w|x_1, x_2, x_3, \dots, x_n, y_1, y_2, \dots, y_n)$$

- You can use BAYES rule to work out a posterior distribution for w given the data.
- Or you could do Maximum Likelihood Estimation

Maximum likelihood estimation of w

Asks the question:

“For which value of w is this data most likely to have happened?”

\Leftrightarrow

For what w is

$p(y_1, y_2 \dots y_n \mid x_1, x_2, x_3, \dots x_n, w)$ maximized?

\Leftrightarrow

For what w is

$$\prod_{i=1}^n p(y_i \mid w, x_i) \text{ maximized?}$$

For what w is

$$\prod_{i=1}^n p(y_i | w, x_i) \text{ maximized?}$$

For what w is

$$\prod_{i=1}^n \exp\left(-\frac{1}{2}\left(\frac{y_i - wx_i}{\sigma}\right)^2\right) \text{ maximized?}$$

For what w is

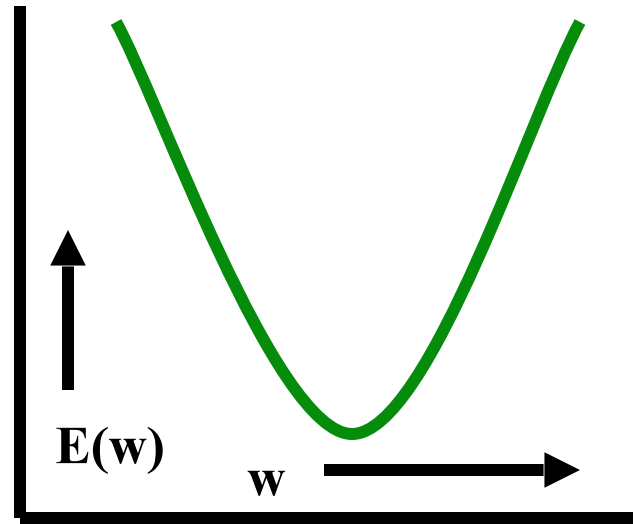
$$\sum_{i=1}^n -\frac{1}{2}\left(\frac{y_i - wx_i}{\sigma}\right)^2 \text{ maximized?}$$

For what w is

$$\sum_{i=1}^n (y_i - wx_i)^2 \text{ minimized?}$$

Linear Regression

The maximum likelihood w is the one that minimizes sum-of-squares of residuals



$$\begin{aligned} E &= \sum_i (y_i - wx_i)^2 \\ &= \sum_i y_i^2 - (2 \sum x_i y_i)w + \left(\sum x_i^2 \right) w^2 \end{aligned}$$

We want to minimize a quadratic function of w .

Linear Regression

Easy to show the sum of squares is minimized when

$$w = \frac{\sum x_i y_i}{\sum x_i^2}$$

The maximum likelihood model is $\text{Out}(x) = wx$

We can use it for prediction

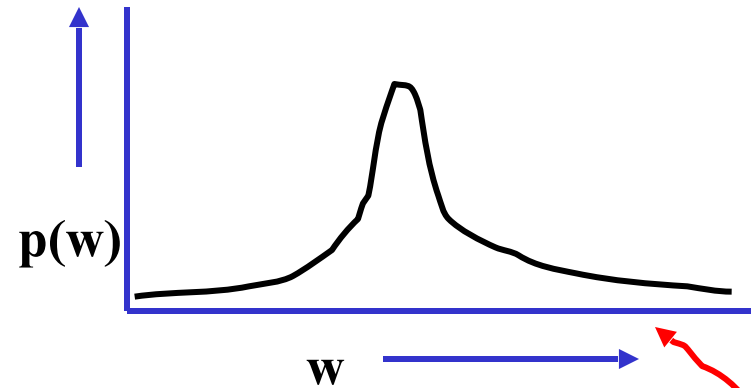
Linear Regression

Easy to show the sum of squares is minimized when

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The maximum likelihood model is $\text{Out}(x) = wx$

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Note: In Bayesian stats you'd have ended up with a prob dist of w

And predictions would have given a prob dist of expected output

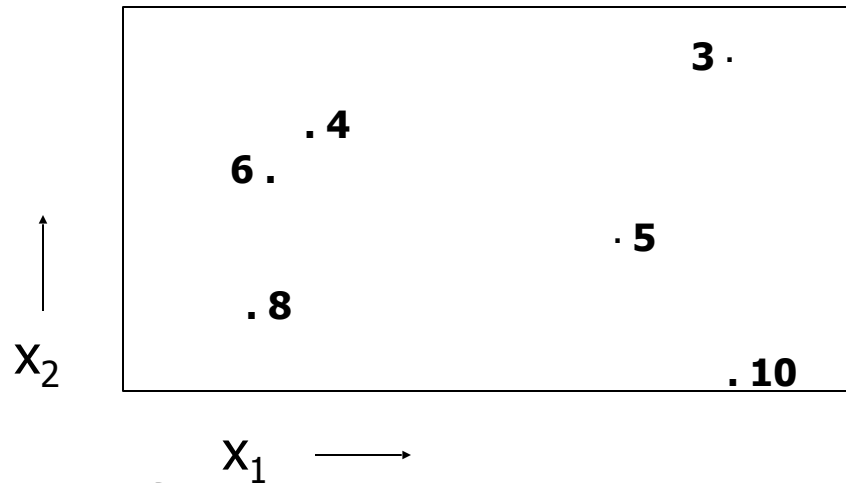
Often useful to know your confidence.

Max likelihood can give some kinds of confidence too.

Multivariate Linear Regression

Multivariate Regression

What if the inputs are vectors?



**2-d input
example**

Dataset has form

$$\begin{array}{cc} \mathbf{x}_1 & y_1 \\ \mathbf{x}_2 & y_2 \\ \mathbf{x}_3 & y_3 \\ \vdots & \vdots \\ \mathbf{x}_R & y_R \end{array}$$

Multivariate Regression

Write matrix \mathbf{X} and \mathbf{Y} thus:

$$\mathbf{X} = \begin{bmatrix} \dots \mathbf{X}_1 \dots \\ \dots \mathbf{X}_2 \dots \\ \boxed{?} \\ \dots \mathbf{X}_R \dots \end{bmatrix} = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ & & \boxed{?} & \\ x_{R1} & x_{R2} & \dots & x_{Rm} \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \boxed{?} \\ y_R \end{bmatrix}$$

(there are R datapoints. Each input has m components)

The linear regression model assumes a vector \mathbf{w} such that

$$\text{Out}(\mathbf{x}) = \mathbf{w}^T \mathbf{x} = w_1 x[1] + w_2 x[2] + \dots w_m x[D]$$

The max. likelihood \mathbf{w} is $\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{Y})$

Multivariate Regression

Write matrix \mathbf{X} and \mathbf{Y} thus:

$$\mathbf{X} = \begin{bmatrix} \dots \mathbf{X}_1 \dots \\ \dots \mathbf{X}_2 \dots \\ \boxed{?} \\ \dots \mathbf{X}_R \dots \end{bmatrix} = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ \boxed{?} \\ x_{R1} & x_{R2} & \dots & x_{Rm} \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \boxed{?} \\ y_R \end{bmatrix}$$

(there are R datapoints. Each input

**IMPORTANT EXERCISE:
PROVE IT !!!!!**

The linear regression model assumes a vector \mathbf{w} such that

$$\text{Out}(\mathbf{x}) = \mathbf{w}^T \mathbf{x} = w_1 x[1] + w_2 x[2] + \dots w_m x[D]$$

The max. likelihood \mathbf{w} is $\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} (\mathbf{X}^T \mathbf{Y})$

Multivariate Regression (con't)

The max. likelihood \mathbf{w} is $\mathbf{w} = (X^T X)^{-1} (X^T Y)$

$X^T X$ is an $m \times m$ matrix: i, j 'th elt is $\sum_{k=1}^R x_{ki} x_{kj}$

$X^T Y$ is an m -element vector: i 'th elt $\sum_{k=1}^R x_{ki} y_k$

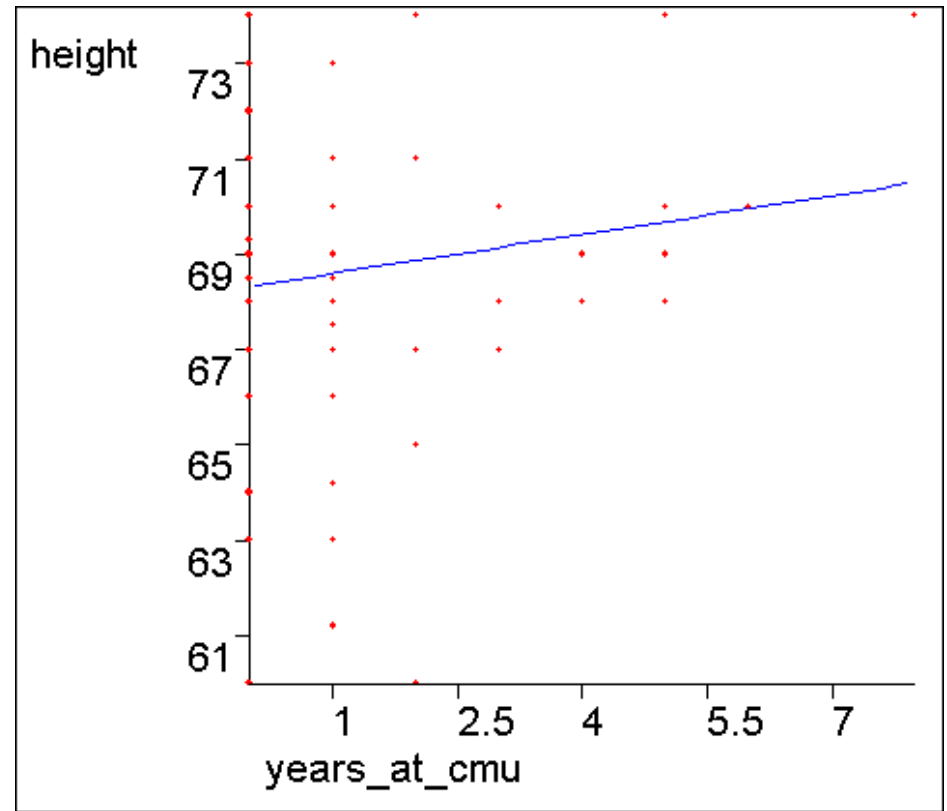
Constant Term in Linear Regression

What about a constant term?

We may expect linear data that does not go through the origin.

Statisticians and Neural Net Folks all agree on a simple obvious hack.

Can you guess??



The constant term

- The trick is to create a fake input “ X_0 ” that always takes the value 1

X_1	X_2	Y
2	4	16
3	4	17
5	5	20

Before:

$$Y = w_1 X_1 + w_2 X_2$$

...has to be a poor model

In this example,
You should be able
to see the MLE
 w_0 , w_1 and w_2 by
inspection

X_0	X_1	X_2	Y
1	2	4	16
1	3	4	17
1	5	5	20

After:

$$Y = w_0 X_0 + w_1 X_1 + w_2 X_2$$

$$= w_0 + w_1 X_1 + w_2 X_2$$

...has a fine constant term

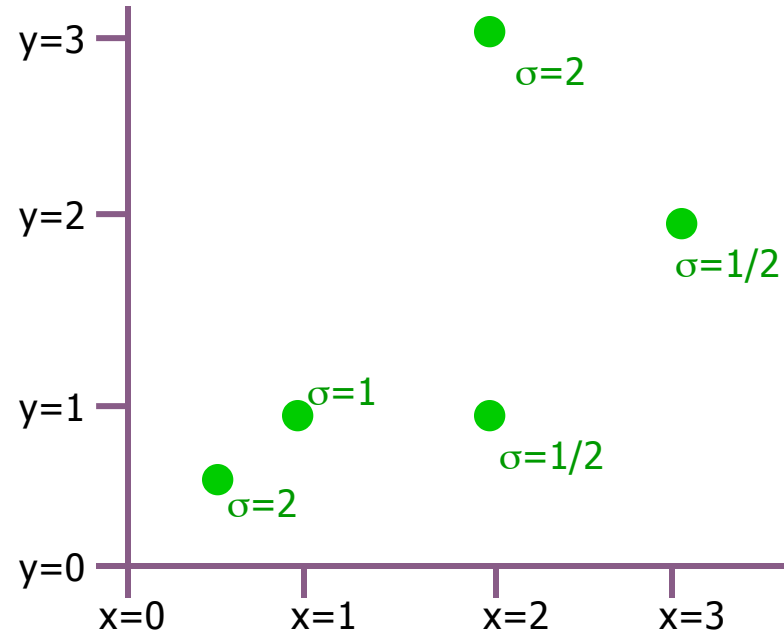
Heteroscedasticity...

Linear Regression with varying noise

Regression with varying noise

- Suppose you know the variance of the noise that was added to each datapoint.

x_i	y_i	σ_i^2
$1/2$	$1/2$	4
1	1	1
2	1	$1/4$
2	3	4
3	2	$1/4$



Assume $y_i \sim N(wx_i, \sigma_i^2)$

What's the MLE estimate of w ?

MLE estimation with varying noise

$$\operatorname{argmax}_w \log p(y_1, y_2, \dots, y_R \mid x_1, x_2, \dots, x_R, \sigma_1^2, \sigma_2^2, \dots, \sigma_R^2, w) =$$

w

$$\operatorname{argmin}_w \sum_{i=1}^R \frac{(y_i - wx_i)^2}{\sigma_i^2} =$$

Assuming independence among noise and then plugging in equation for Gaussian and simplifying.

$$\left(w \text{ such that } \sum_{i=1}^R \frac{x_i(y_i - wx_i)}{\sigma_i^2} = 0 \right) =$$

Setting dLL/dw equal to zero

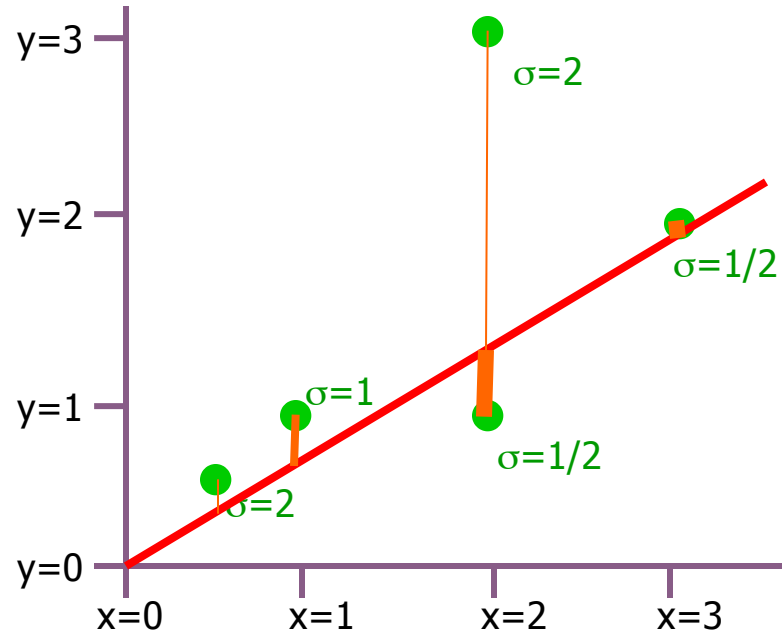
$$\frac{\left(\sum_{i=1}^R \frac{x_i y_i}{\sigma_i^2} \right)}{\left(\sum_{i=1}^R \frac{x_i^2}{\sigma_i^2} \right)}$$

Trivial algebra

This is Weighted Regression

- We are asking to minimize the weighted sum of squares

$$\operatorname{argmin}_w \sum_{i=1}^R \frac{(y_i - wx_i)^2}{\sigma_i^2}$$



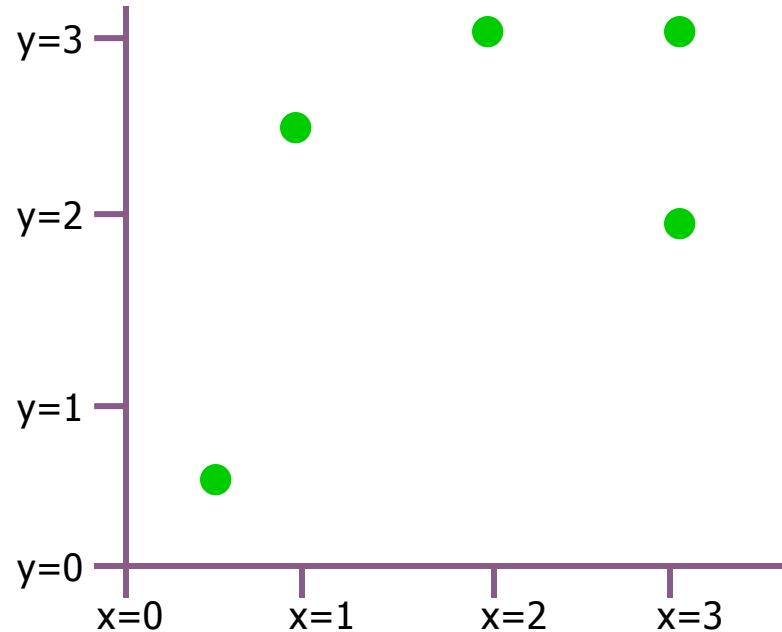
where weight for i'th datapoint is $\frac{1}{\sigma_i^2}$

Non-linear Regression

Non-linear Regression

- Suppose you know that y is related to a function of x in such a way that the predicted values have a non-linear dependence on w , e.g:

x_i	y_i
$1/2$	$1/2$
1	2.5
2	3
3	2
3	3



Assume $y_i \sim N(\sqrt{w + x_i}, \sigma^2)$

What's the MLE estimate of w ?

Non-linear MLE estimation

$$\operatorname{argmax}_w \log p(y_1, y_2, \dots, y_R \mid x_1, x_2, \dots, x_R, \sigma, w) =$$

w

$$\operatorname{argmin}_w \sum_{i=1}^R \left(y_i - \sqrt{w + x_i} \right) =$$

Assuming i.i.d. and then plugging in equation for Gaussian and simplifying.

$$\left(w \text{ such that } \sum_{i=1}^R \frac{y_i - \sqrt{w + x_i}}{\sqrt{w + x_i}} = 0 \right) =$$

Setting dLL/dw equal to zero

Non-linear MLE estimation

$$\operatorname{argmax}_w \log p(y_1, y_2, \dots, y_R \mid x_1, x_2, \dots, x_R, \sigma, w) =$$

w

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$$\left(w \text{ such that } \sum_{i=1}^R \frac{y_i - \sqrt{w + x_i}}{\sqrt{w + x_i}} = 0 \right) =$$

Setting dLL/dw equal to zero



We're down the algebraic toilet

So guess what we do?

Non-linear MLE estimation

$$\operatorname{argmax}_w \log p(y_1, y_2, \dots, y_R \mid x_1, x_2, \dots, x_R, \sigma, w) =$$

w

Common (but not only) approach:
Numerical Solutions:

- Line Search
- Simulated Annealing
- Gradient Descent
- Conjugate Gradient
- Levenberg Marquart
- Newton's Method

Also, special purpose statistical-
optimization-specific tricks such as
E.M. (See Gaussian Mixtures lecture
for introduction)

$$\left. \frac{\partial}{\partial w} \log p(y_i \mid x_i, w) \right|_{w = w + x_i} =$$

Assuming i.i.d. and
then plugging in
equation for Gaussian
and simplifying.

$$\left. \frac{\partial}{\partial w} \log p(y_i \mid x_i, w) \right|_{w = w + x_i} = 0 \Bigg) =$$

Setting dLL/dw
equal to zero

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algebraic toilet



So guess what
we do?

Polynomial Regression

Polynomial Regression

So far we've mainly been dealing with linear regression

X_1	X_2	Y
3	2	7
1	1	3
\vdots	\vdots	\vdots

$\mathbf{X} =$	3	2
	1	1
	\vdots	\vdots

$\mathbf{y} =$	7
	3
	\vdots

$y_1 = 7..$

$\mathbf{z} =$	1	3	2
	1	1	1
	\vdots		\vdots

$\mathbf{y} =$	7
	3
	\vdots

$\mathbf{z}_1 = (1, 3, 2).. \quad y_1 = 7..$

$\mathbf{z}_k = (1, x_{k1}, x_{k2})$

$$\beta = (\mathbf{Z}^T \mathbf{Z})^{-1} (\mathbf{Z}^T \mathbf{y})$$

$$y^{\text{est}} = \beta_0 + \beta_1 x_1 + \beta_2 x_2$$

Quadratic Regression

It's trivial to do linear fits of fixed nonlinear basis functions

X_1	X_2	Y
3	2	7
1	1	3
\vdots	\vdots	\vdots

$\mathbf{X} =$	3	2
	1	1
	\vdots	\vdots

$\mathbf{y} =$	7
	3
	\vdots

$y_1 = 7..$

$\mathbf{Z} =$	1	3	2	9	6	4
	1	1	1	1	1	1
	\vdots					\vdots

$\mathbf{y} =$	7
	3
	\vdots

$$\mathbf{z} = (1, x_1, x_2, x_1^2, x_1x_2, x_2^2)$$

$$\beta = (\mathbf{Z}^T \mathbf{Z})^{-1} (\mathbf{Z}^T \mathbf{y})$$

$$y_{\text{est}} = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1^2 + \beta_4 x_1 x_2 + \beta_5 x_2^2$$

Quadratic Regression

It's trivial

Each component of a \mathbf{z} vector is called a term.

Each column of the \mathbf{Z} matrix is called a term column

How many terms in a quadratic regression with m inputs?

- 1 constant term

- m linear terms

- $(m+1)\text{-choose-}2 = m(m+1)/2$ quadratic terms

$(m+2)\text{-choose-}2$ terms in total = $O(m^2)$

Note that solving $\beta = (\mathbf{Z}^T \mathbf{Z})^{-1} (\mathbf{Z}^T \mathbf{y})$ is thus $O(m^6)$

X_1	X_2
3	2
1	1
\vdots	\vdots

$\mathbf{Z} =$

1
1
\vdots

$\mathbf{z} = (1$

Qth-degree polynomial Regression

X_1	X_2	Y
3	2	7
1	1	3
\vdots	\vdots	\vdots

$$\mathbf{X} = \begin{bmatrix} 3 & 2 \\ 1 & 1 \\ \vdots & \vdots \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 7 \\ 3 \\ \vdots \end{bmatrix}$$

$$\mathbf{Z} = \begin{bmatrix} 1 & 3 & 2 & 9 & 6 & \dots \\ 1 & 1 & 1 & 1 & 1 & \dots \\ \vdots & & & & & \dots \end{bmatrix} \quad \mathbf{y} = \begin{bmatrix} 7 \\ 3 \\ \vdots \end{bmatrix}$$

\mathbf{z} =(all products of powers of inputs in which sum of powers is q or less,)

$$\beta = (\mathbf{Z}^T \mathbf{Z})^{-1} (\mathbf{Z}^T \mathbf{y})$$

$$y^{\text{est}} = \beta_0 + \beta_1 x_1 + \dots$$

m inputs, degree Q: how many terms?

= the number of unique terms of the form

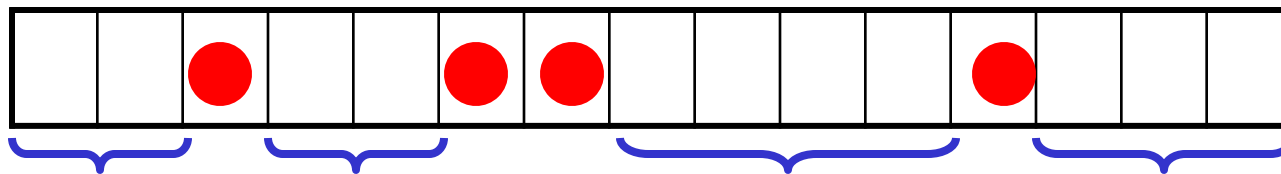
$$x_1^{q_1} x_2^{q_2} \dots x_m^{q_m} \text{ where } \sum_{i=1}^m q_i \leq Q$$

= the number of unique terms of the form

$$1^{q_0} x_1^{q_1} x_2^{q_2} \dots x_m^{q_m} \text{ where } \sum_{i=0}^m q_i = Q$$

= the number of lists of non-negative integers $[q_0, q_1, q_2, \dots, q_m]$ in which $\sum q_i = Q$

= the number of ways of placing Q red disks on a row of squares of length Q+m = (Q+m)-choose-Q



Q=11, m=4

$$q_0=2$$

$$q_1=2$$

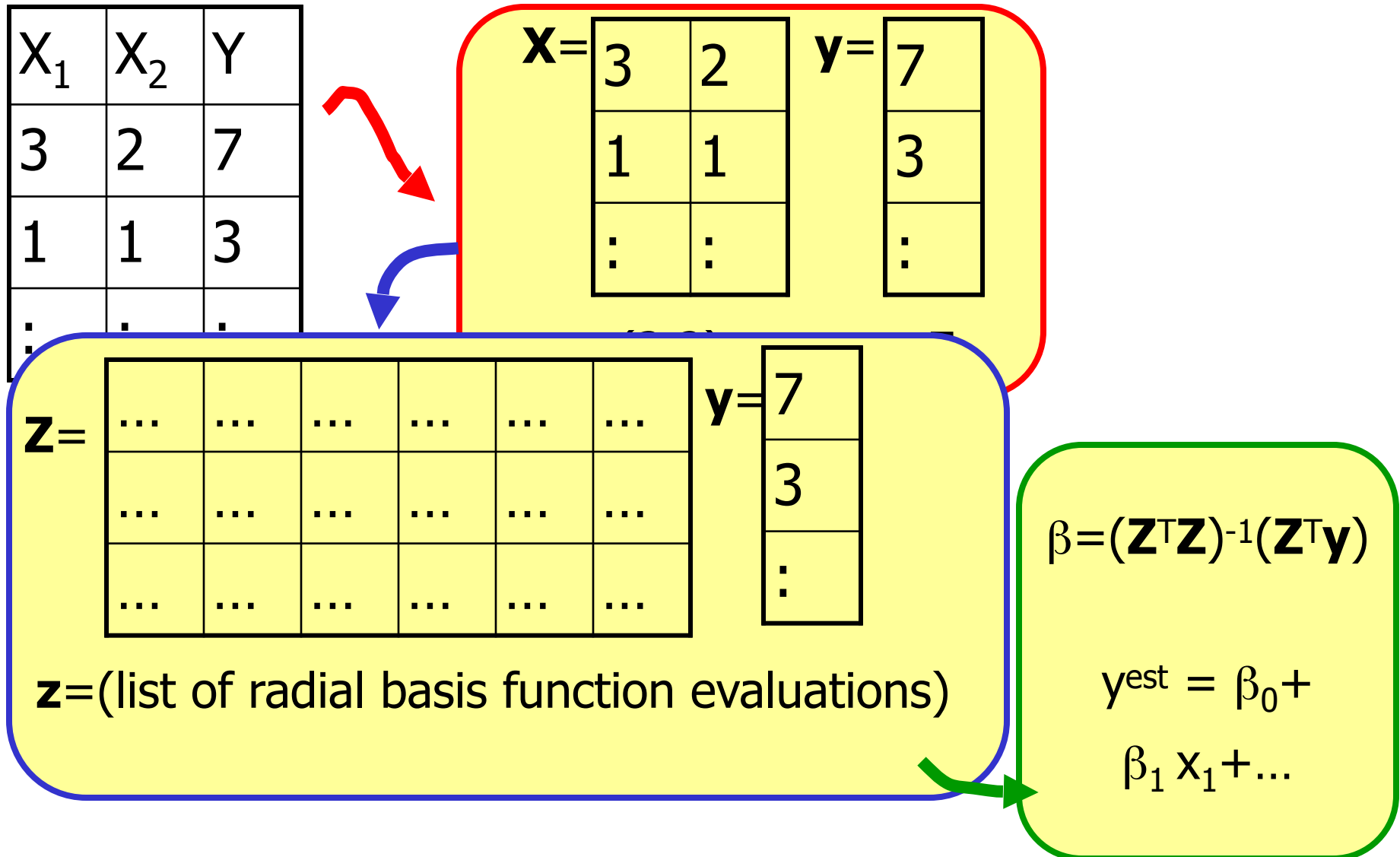
$$q_2=0$$

$$q_3=4$$

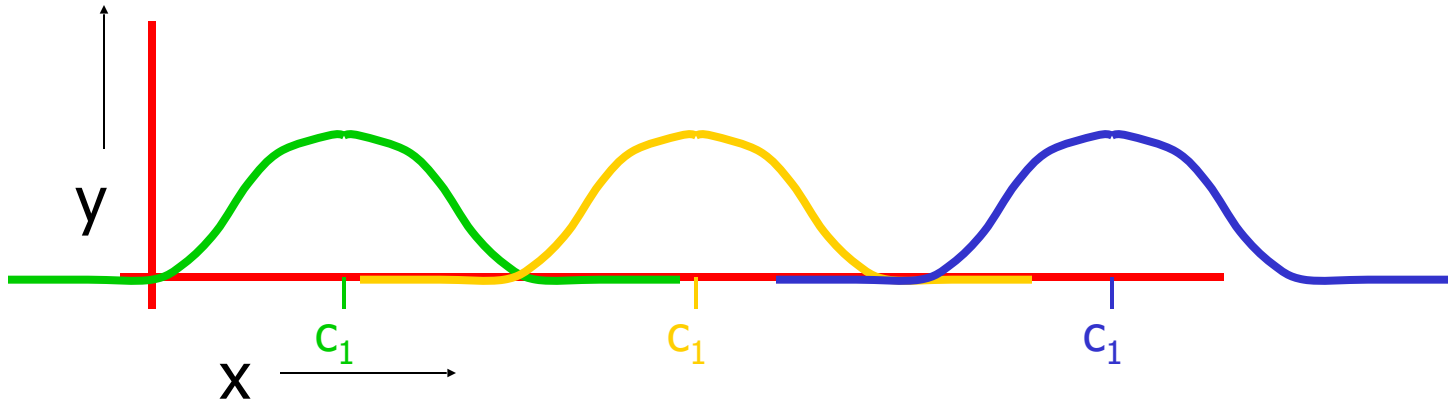
$$q_4=3$$

Radial Basis Functions

Radial Basis Functions (RBFs)



1-d RBFs

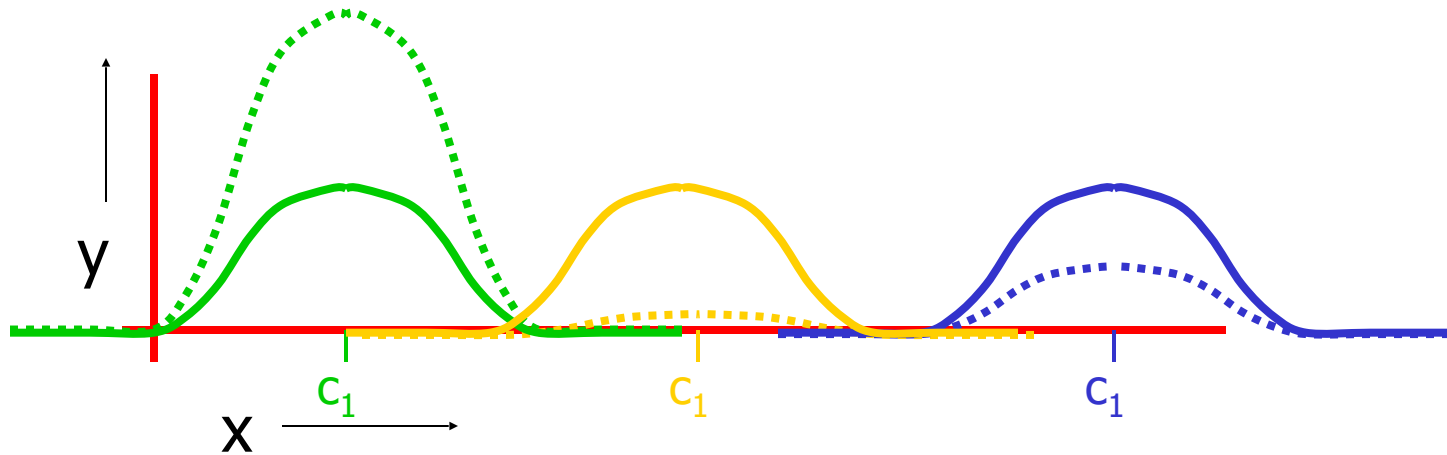


$$y^{\text{est}} = \beta_1 \phi_1(x) + \beta_2 \phi_2(x) + \beta_3 \phi_3(x)$$

where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / KW)$$

Example

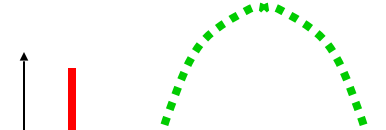


$$y^{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 0.5\phi_3(x)$$

where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / KW)$$

RBFs with Linear Regression



All c_i 's are held constant
(initialized randomly or
on a grid in m-
dimensional input space)

KW also held constant
(initialized to be large
enough that there's decent
overlap between basis
functions*)

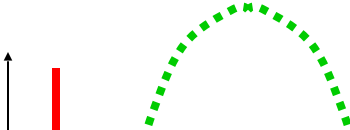
*Usually much better than the crappy
overlap on my diagram

$$y^{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 0.5\phi_3(x)$$

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*Usually much better than the crappy
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$$y^{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 5\phi_3(x)$$

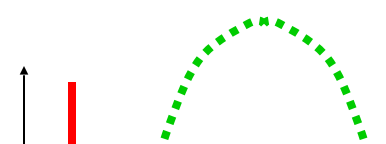
where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / \text{KW})$$

then given Q basis functions, define the matrix Z such that $Z_{kj} = \text{KernelFunction}(|x_k - c_j| / \text{KW})$ where x_k is the k th vector of inputs

And as before, $\beta = (\mathbf{Z}^T \mathbf{Z})^{-1} (\mathbf{Z}^T \mathbf{y})$

RBFs with NonLinear Regression



Allow the c_i 's to adapt to the data (initialized randomly or on a grid in m-dimensional input space)

KW allowed to adapt to the data. (Some folks even let each basis function have its own KW_j , permitting fine detail in dense regions of input space)

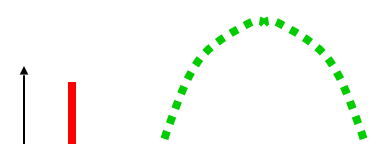
$$y^{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 5\phi_3(x)$$

where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / KW)$$

But how do we now find all the β_j 's, c_i 's and KW ?

RBFs with NonLinear Regression



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$$y_{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 5\phi_3(x)$$

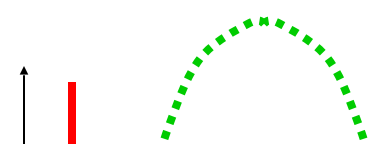
where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / KW)$$

But how do we now find all the β_j 's, c_i 's and KW ?

Answer: Gradient Descent

RBFs with NonLinear Regression



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KW allowed to adapt to the data. (Some folks even let each basis function have its own KW_j , permitting fine detail in dense regions of input space)

$$y_{\text{est}} = 2\phi_1(x) + 0.05\phi_2(x) + 5\phi_3(x)$$

where

$$\phi_i(x) = \text{KernelFunction}(|x - c_i| / KW)$$

But how do we now find all the β_j 's, c_i 's and KW ?

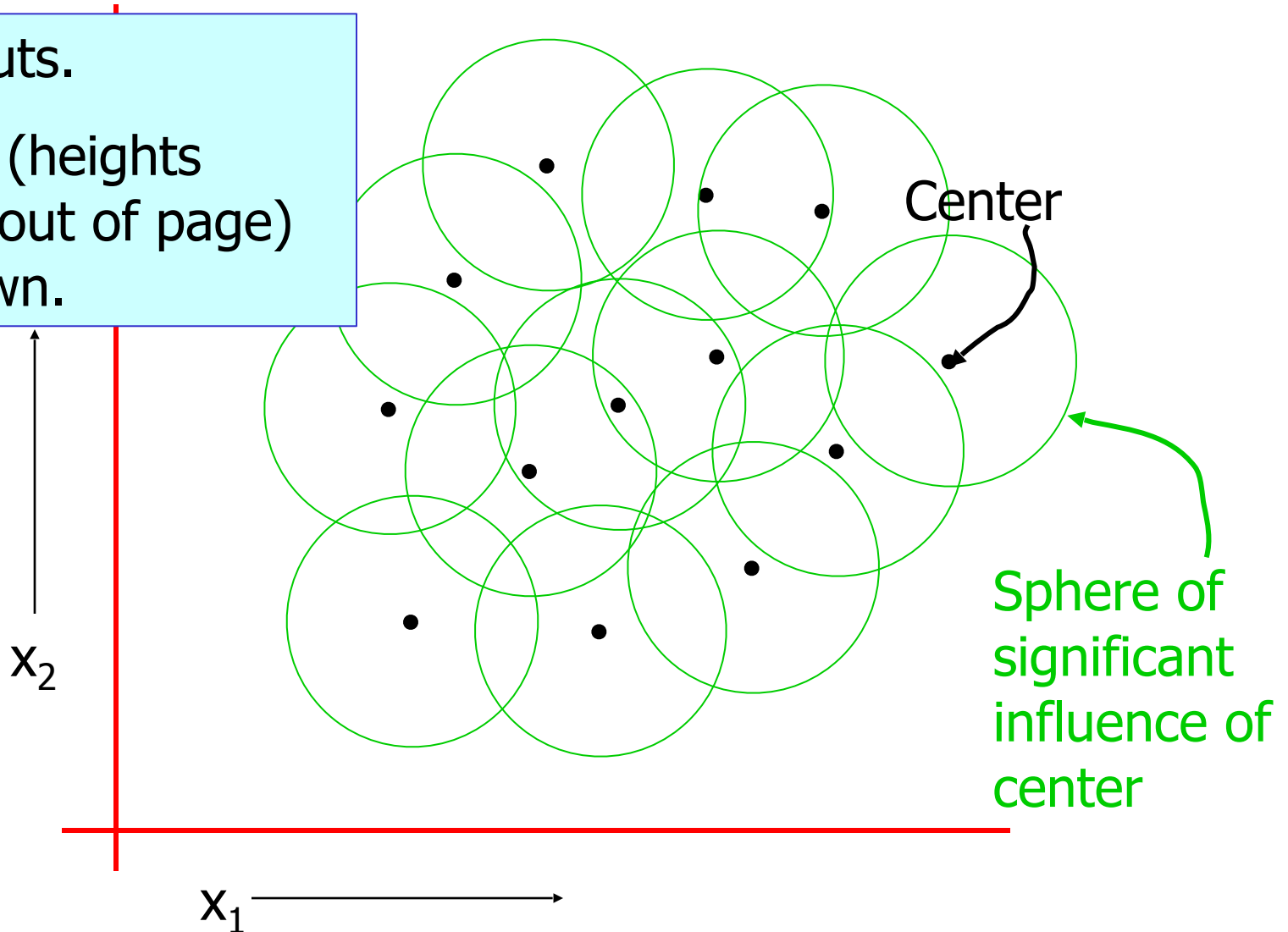
(But I'd like to see, or hope someone's already done, a hybrid, where the c_i 's and KW are updated with gradient descent while the β_j 's use matrix inversion)

Answer: Gradient Descent

Radial Basis Functions in 2-d

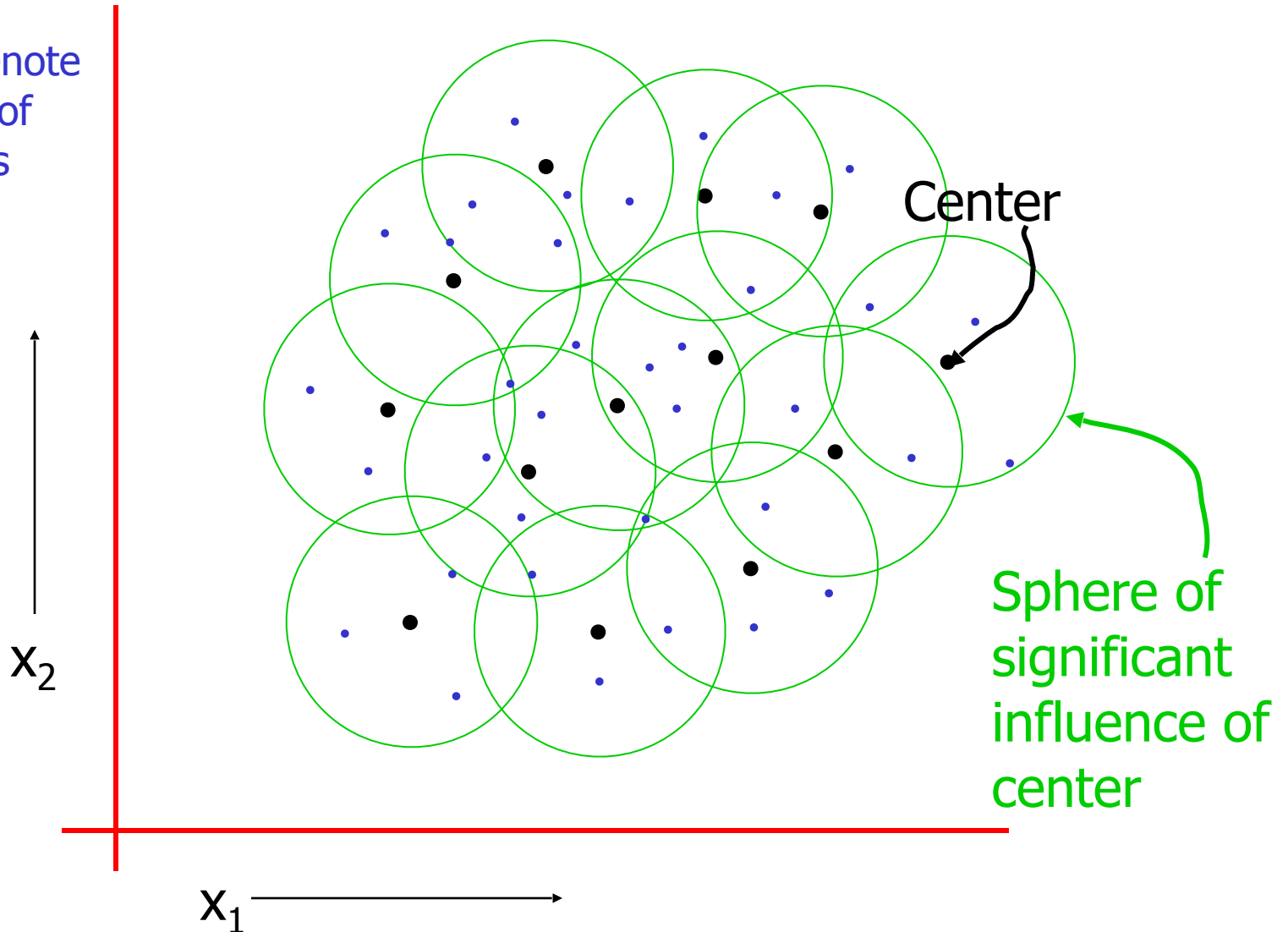
Two inputs.

Outputs (heights
sticking out of page)
not shown.



Happy RBFs in 2-d

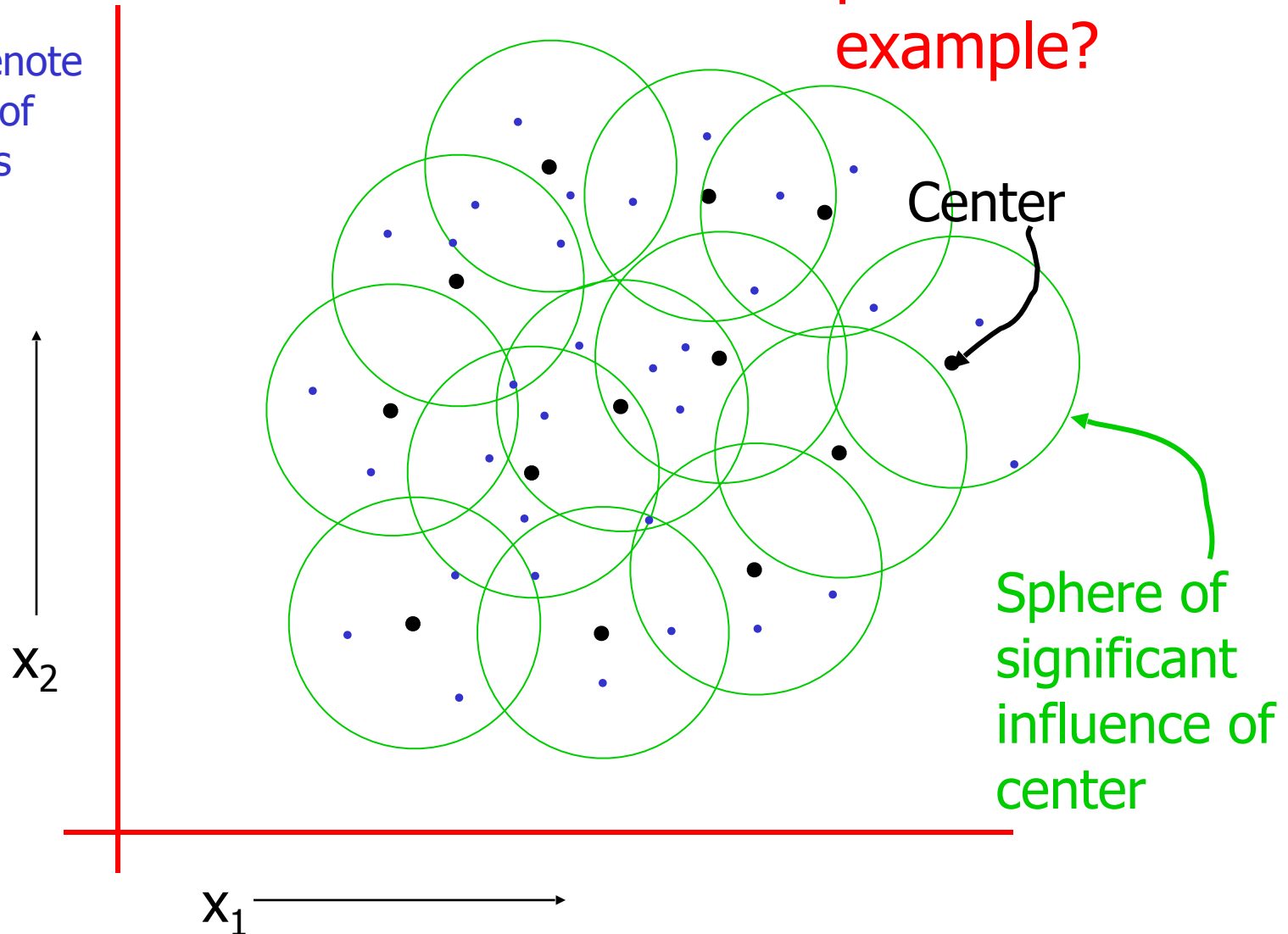
Blue dots denote
coordinates of
input vectors



Crabby RBFs in 2-d

What's the problem in this example?

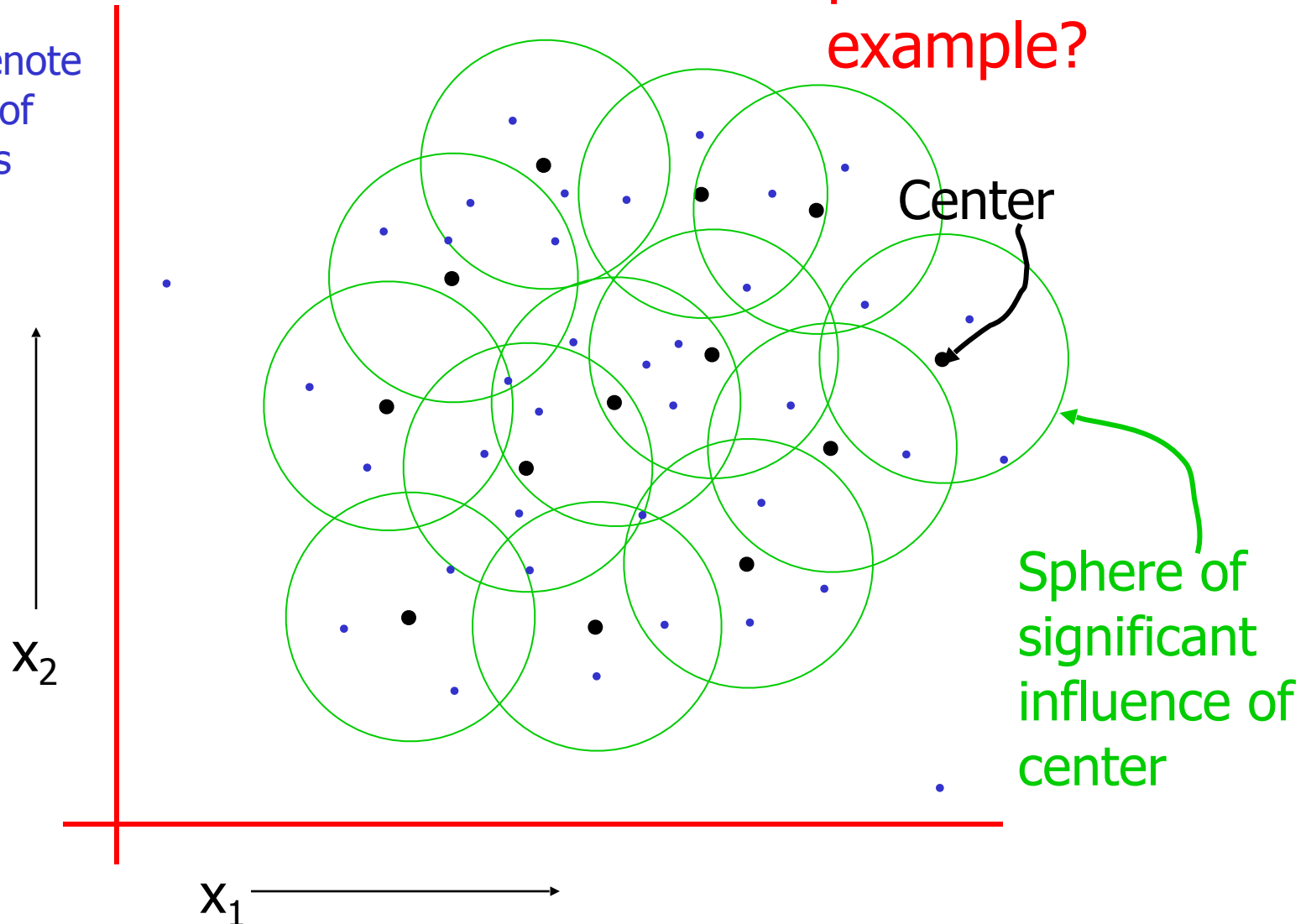
Blue dots denote coordinates of input vectors



More crabby RBFs

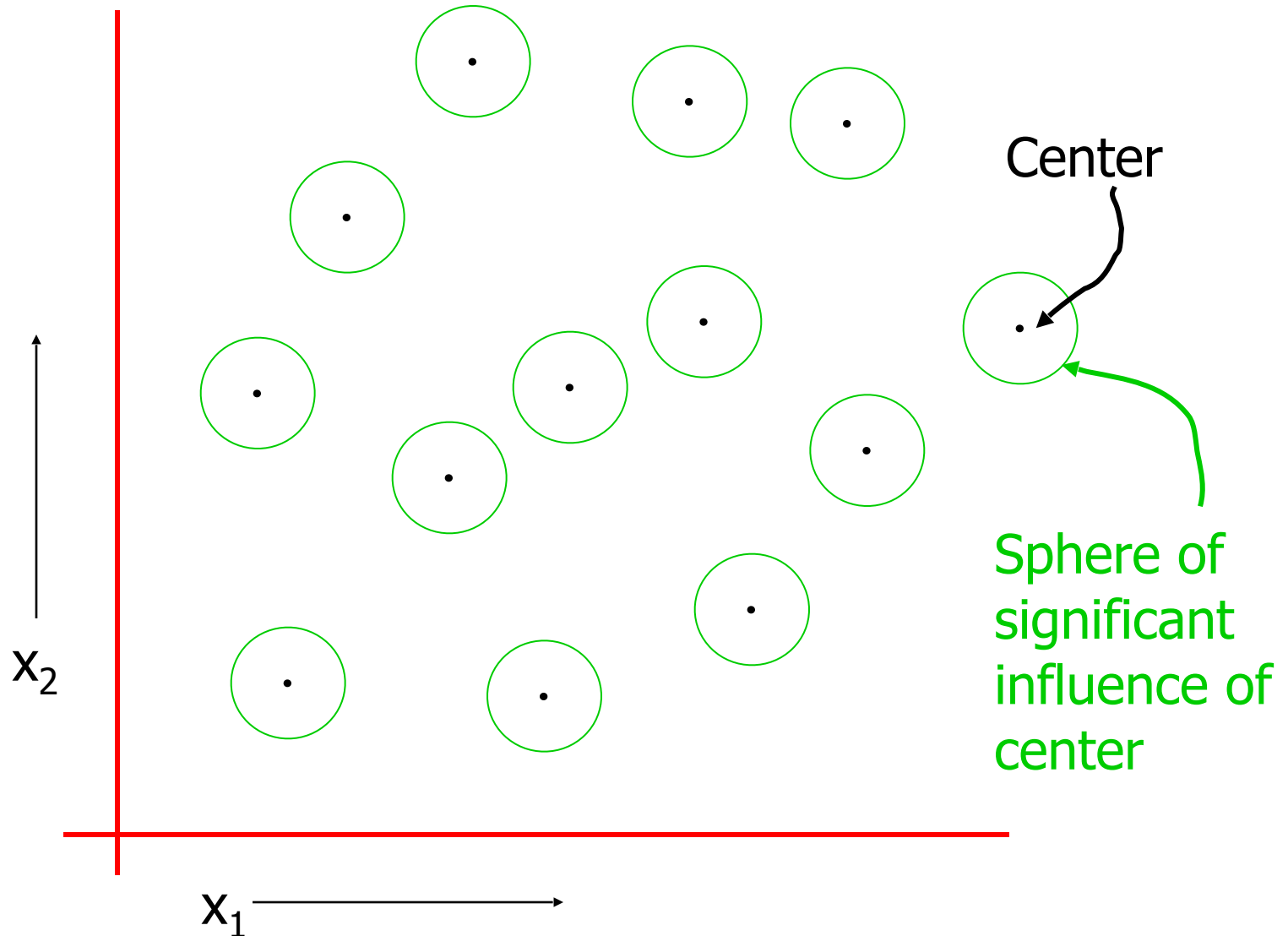
And what's the problem in this example?

Blue dots denote coordinates of input vectors



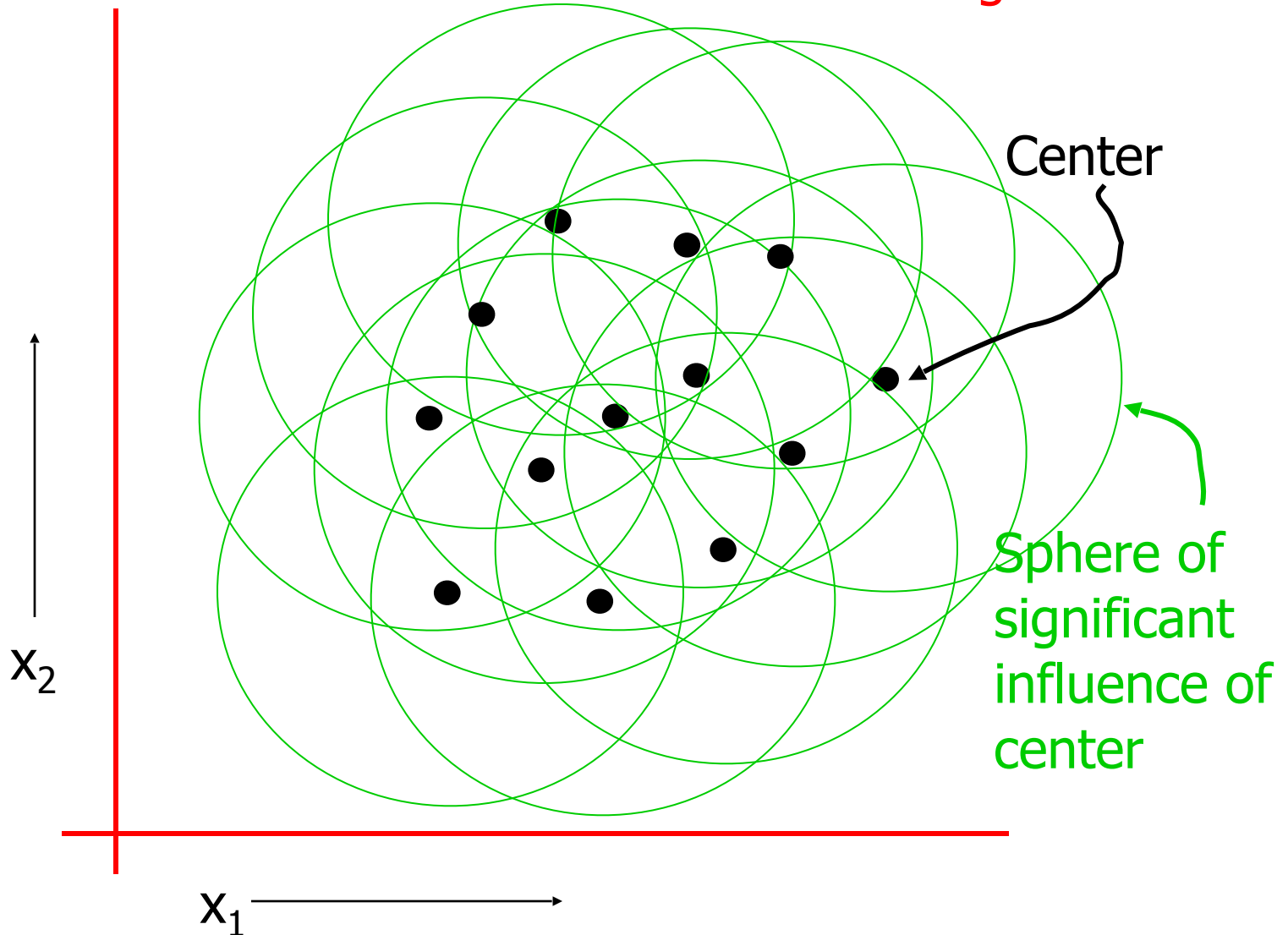
Hopeless!

Even before seeing the data, you should understand that this is a disaster!



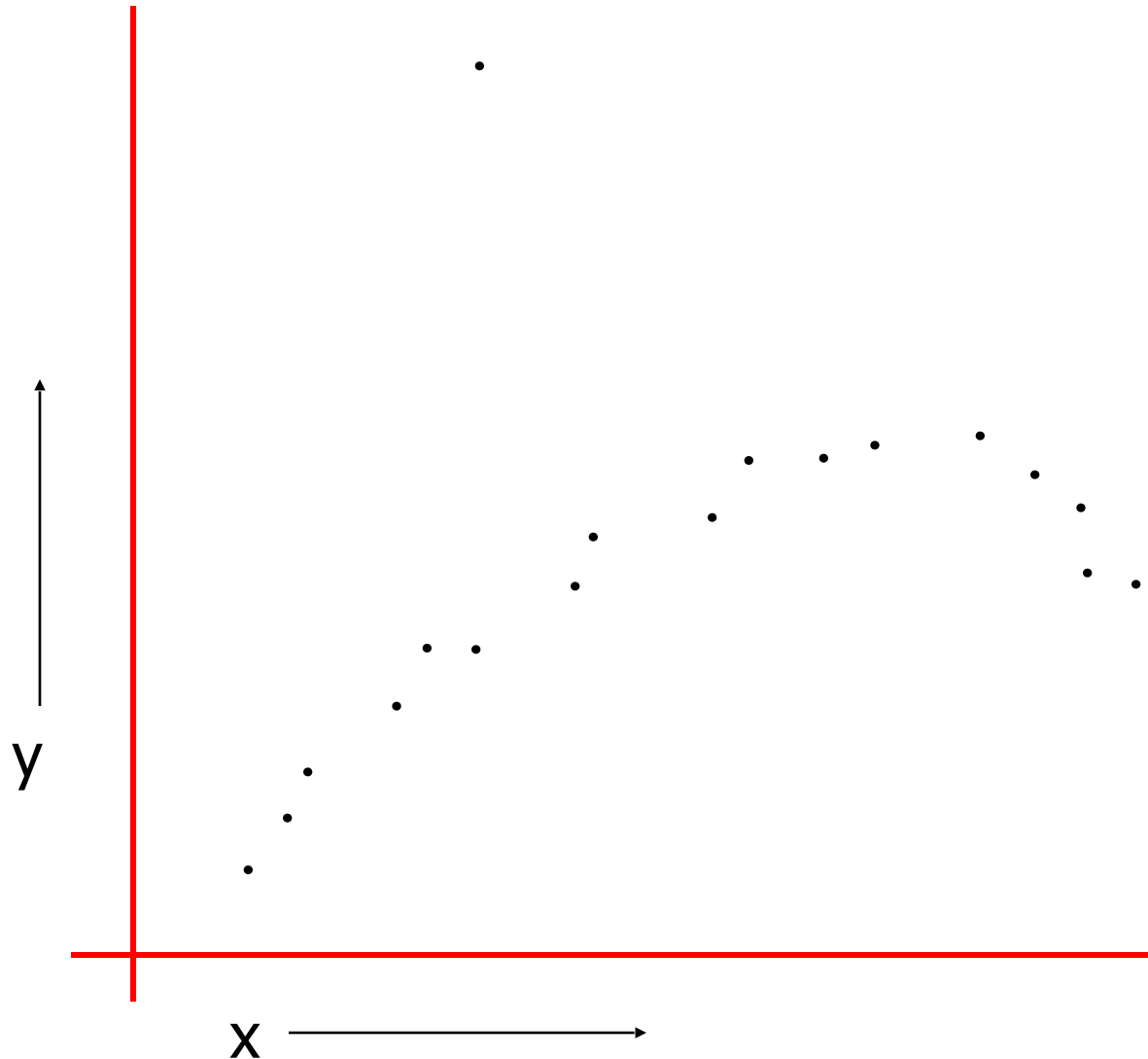
Unhappy

Even before seeing the data, you should understand that this isn't good either..

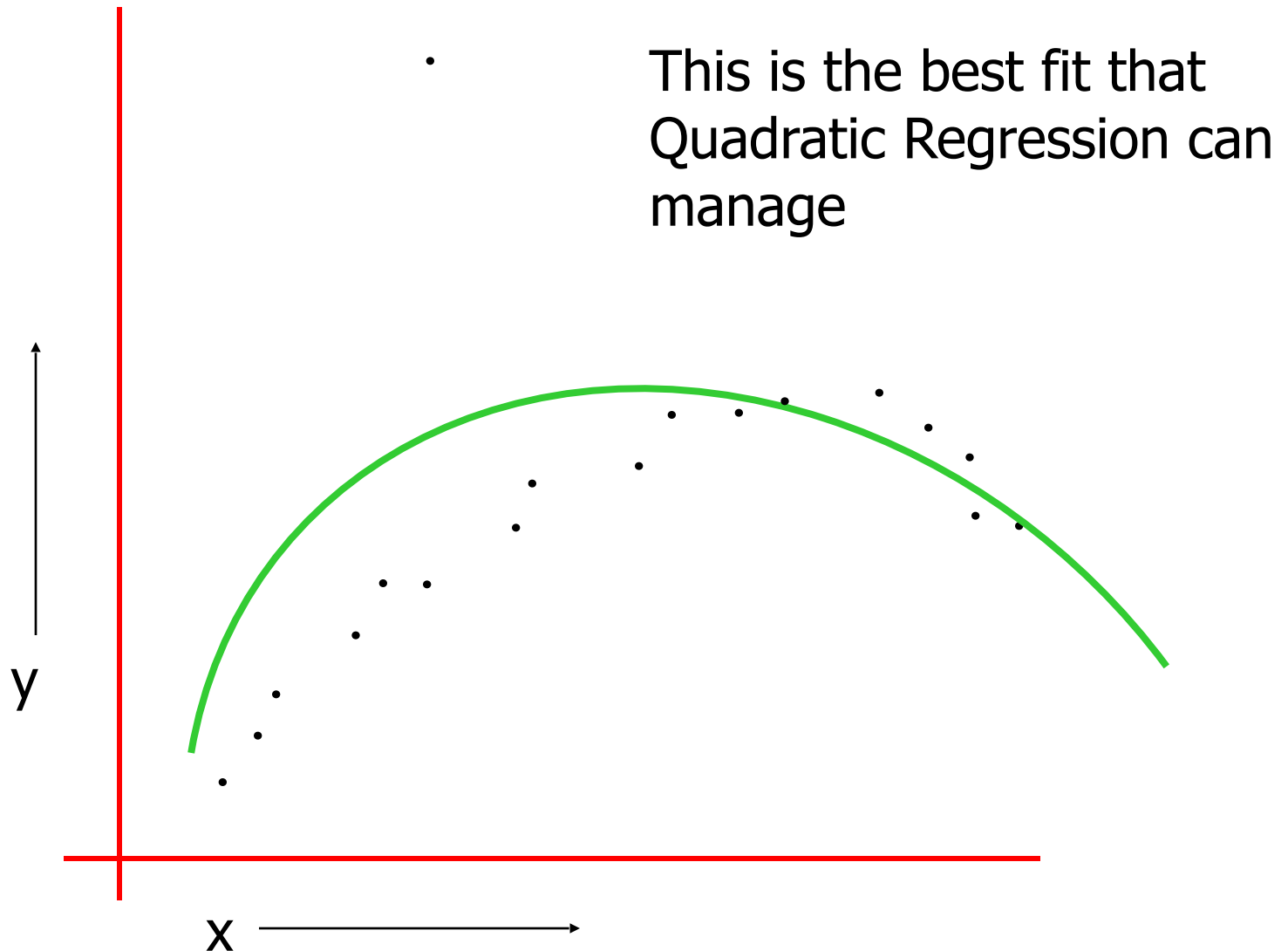


Robust Regression

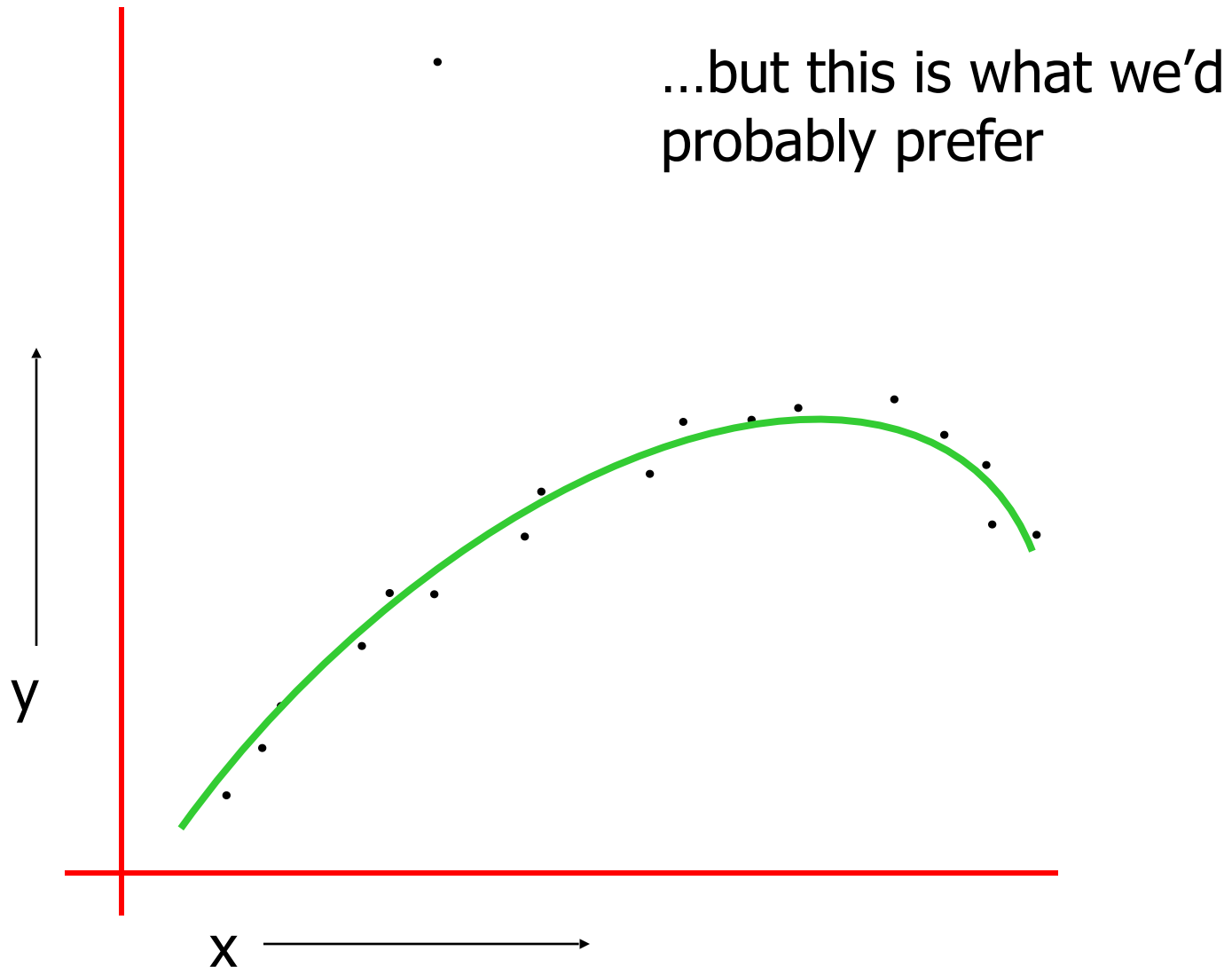
Robust Regression



Robust Regression

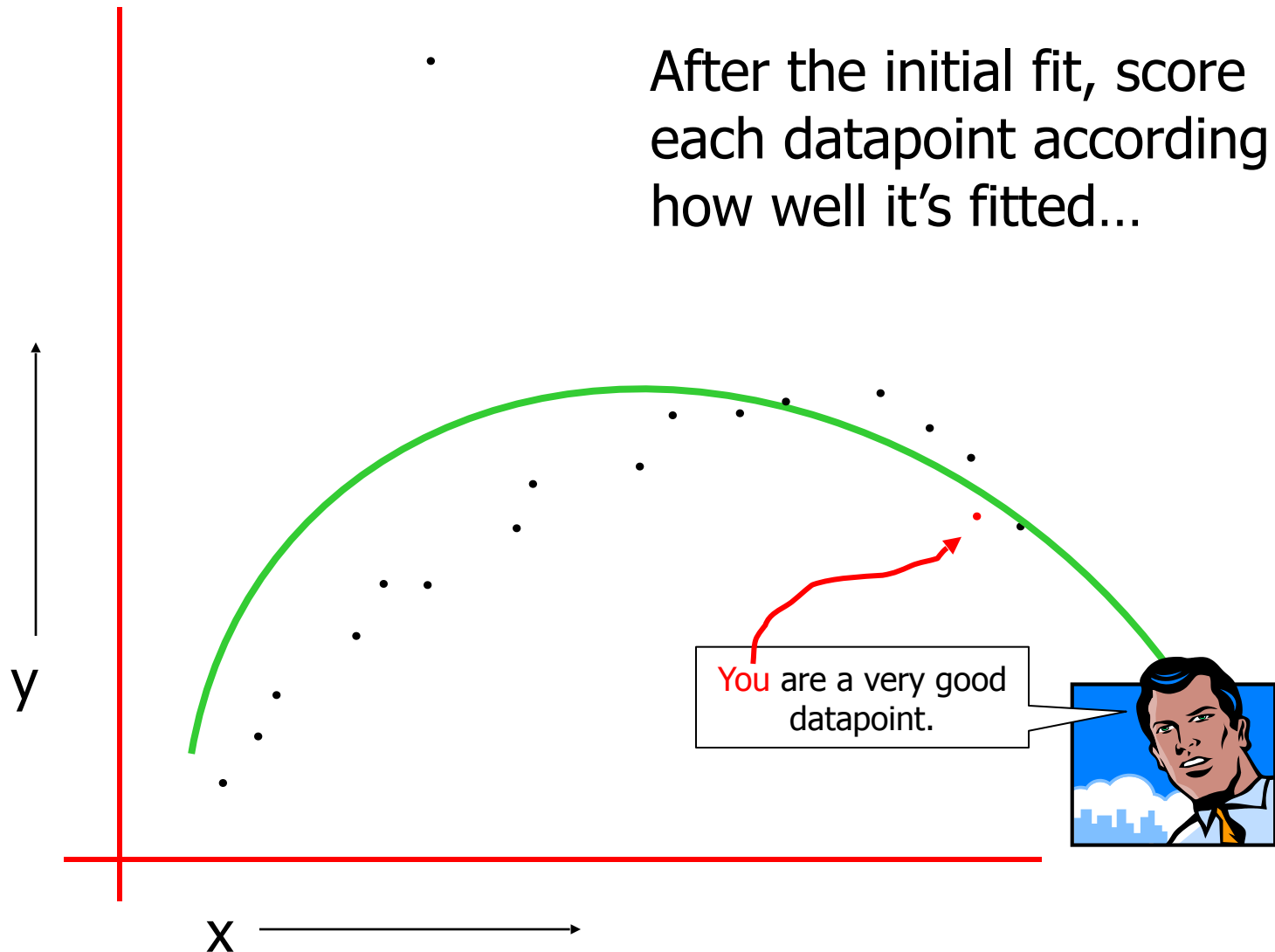


Robust Regression



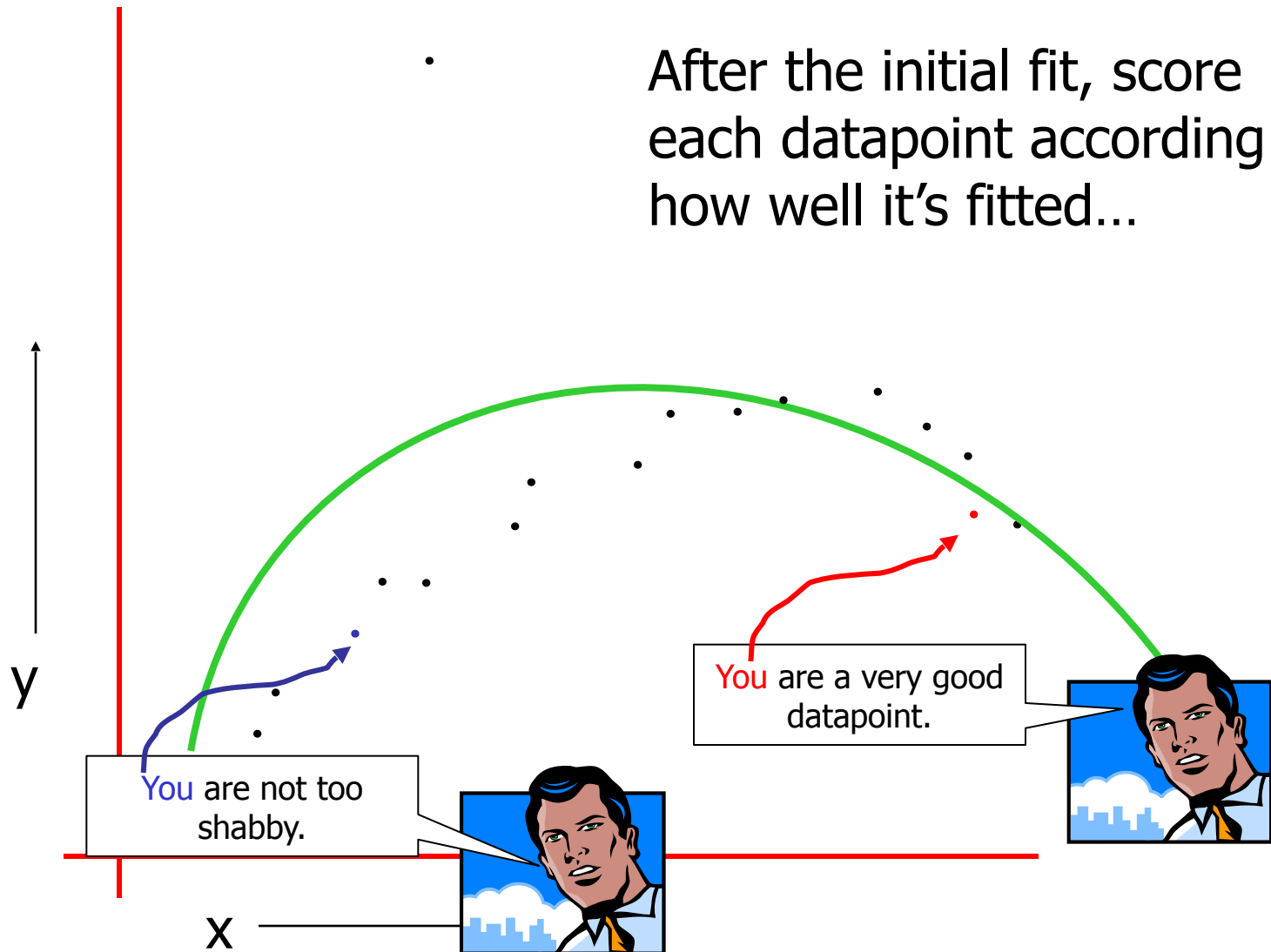
LOESS-based Robust Regression

After the initial fit, score each datapoint according to how well it's fitted...

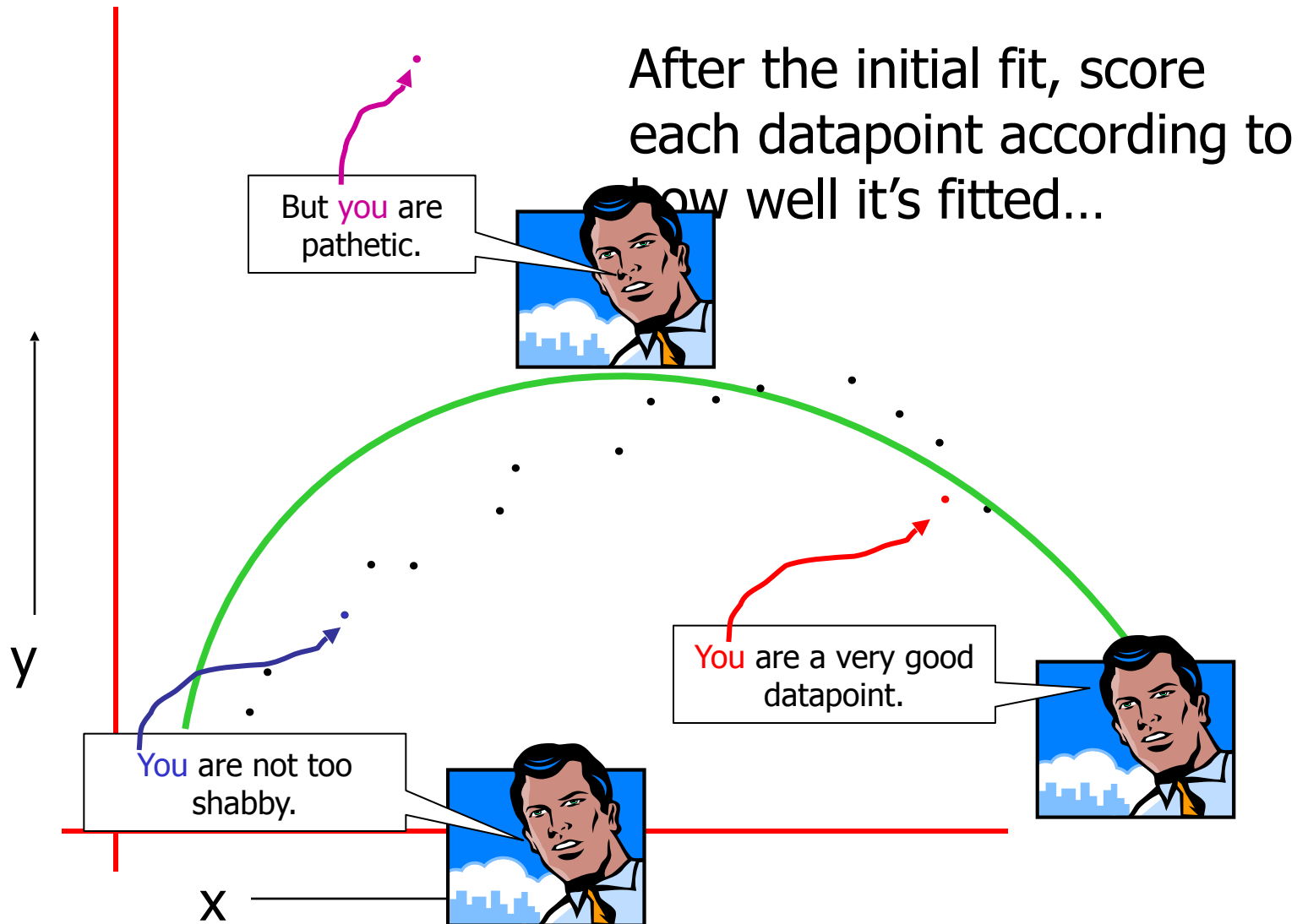


LOESS-based Robust Regression

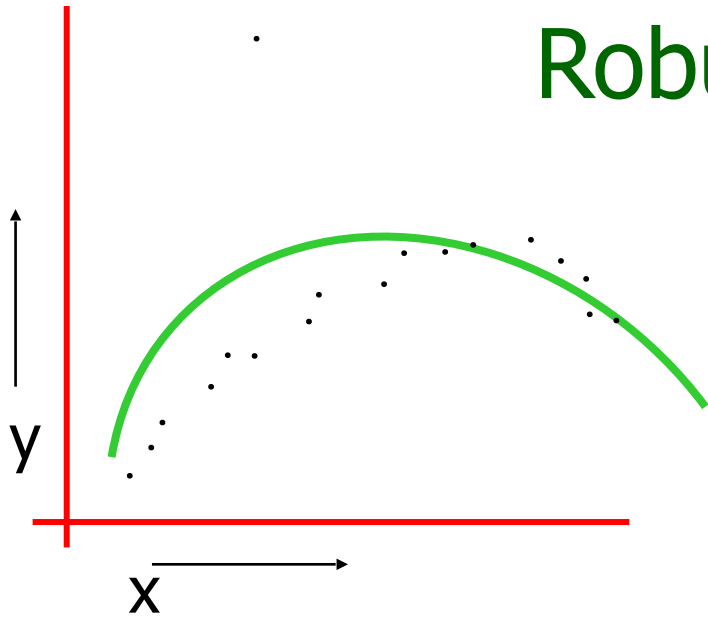
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LOESS-based Robust Regression



Robust Regression

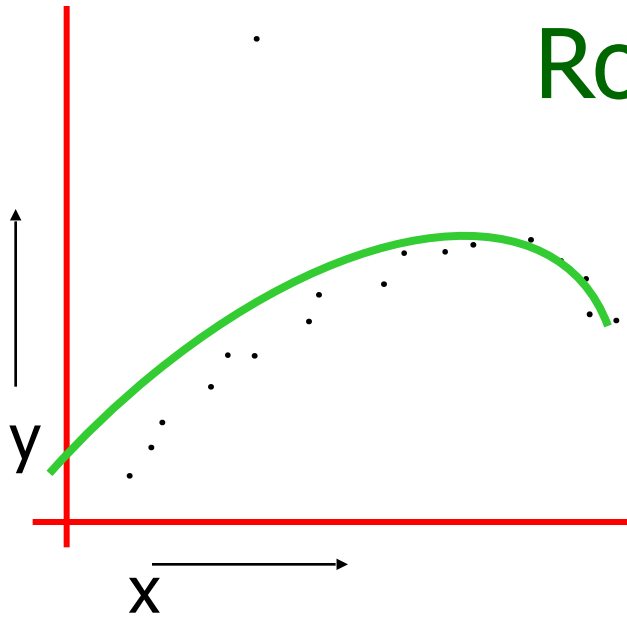


For $k = 1$ to $R...$

- Let (x_k, y_k) be the k th datapoint
- Let y_k^{est} be predicted value of y_k
- Let w_k be a weight for datapoint k that is large if the datapoint fits well and small if it fits badly:

$$w_k = \text{KernelFn}([y_k - y_k^{\text{est}}]^2)$$

Robust Regression



Then redo the regression using weighted datapoints.

Weighted regression was described earlier in the “vary noise” section, and is also discussed in the “Memory-based Learning” Lecture.

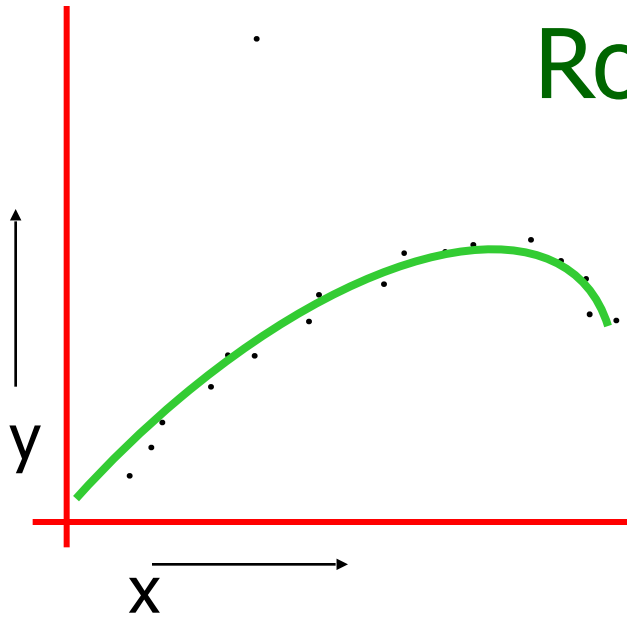
Guess what happens next?

For $k = 1$ to $R...$

- Let (x_k, y_k) be the k th datapoint
- Let y_k^{est} be predicted value of y_k
- Let w_k be a weight for datapoint k that is large if the datapoint fits well and small if it fits badly:

$$w_k = \text{KernelFn}([y_k - y_k^{\text{est}}]^2)$$

Robust Regression



Then redo the regression
using weighted datapoints.

I taught you how to do this in the "Instance-based" lecture (only then the weights depended on distance in input-space)

Repeat whole thing until
converged!

For $k = 1$ to $R...$

- Let (x_k, y_k) be the k th datapoint
- Let y_k^{est} be predicted value of y_k
- Let w_k be a weight for datapoint k that is large if the datapoint fits well and small if it fits badly:

$$w_k = \text{KernelFn}([y_k - y_k^{\text{est}}]^2)$$

Robust Regression---what we're doing

What regular regression does:

Assume y_k was originally generated using the following recipe:

$$y_k = \beta_0 + \beta_1 x_k + \beta_2 x_k^2 + N(0, \sigma^2)$$

Computational task is to find the Maximum Likelihood β_0 , β_1 and β_2

Robust Regression---what we're doing

What LOESS robust regression does:

Assume y_k was originally generated using the following recipe:

With probability p :

$$y_k = \beta_0 + \beta_1 x_k + \beta_2 x_k^2 + N(0, \sigma^2)$$

But otherwise

$$y_k \sim N(\mu, \sigma_{\text{huge}}^2)$$

Computational task is to find the Maximum Likelihood β_0 , β_1 , β_2 , p , μ and σ_{huge}

Robust Regression---what we're doing

What LOESS robust regression does:

Assume y_k was originally generated using the following recipe:

With probability p :

$$y_k = \beta_0 + \beta_1 x_k + \beta_2 x_k^2 + N(0, \sigma^2)$$

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Computational task is to find the Maximum Likelihood β_0 , β_1 , β_2 , p , μ and σ_{huge}

Mysteriously, the reweighting procedure does this computation for us.

Your first glimpse of two spectacular letters:

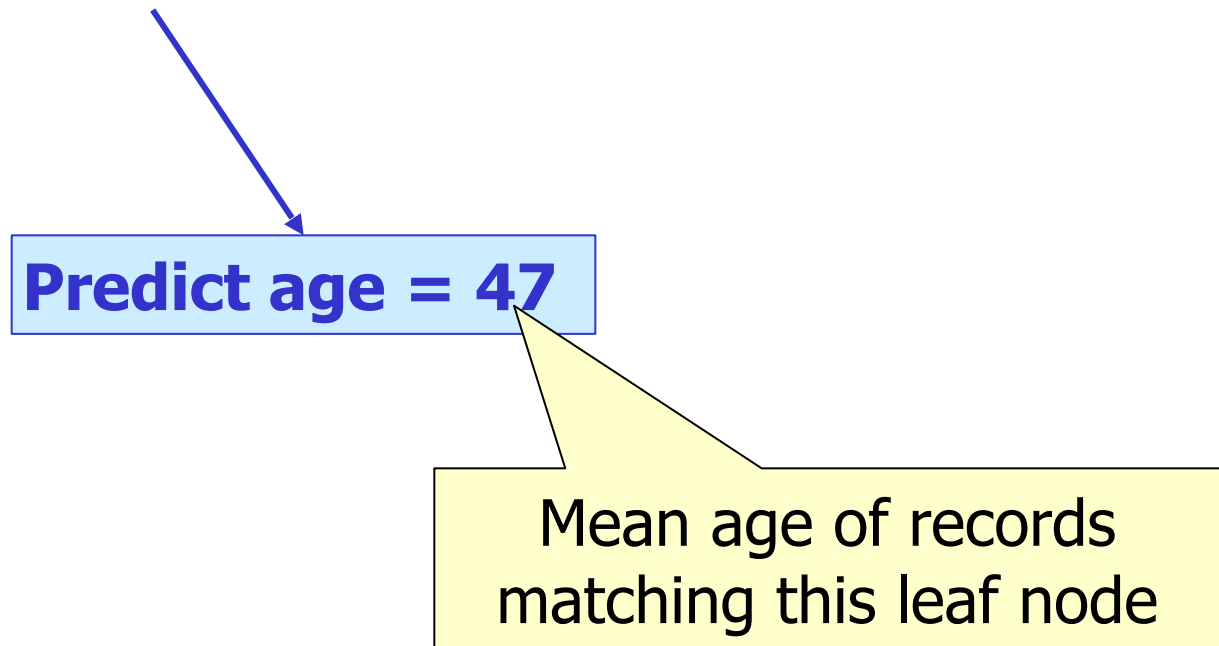
E.M.

Regression Trees

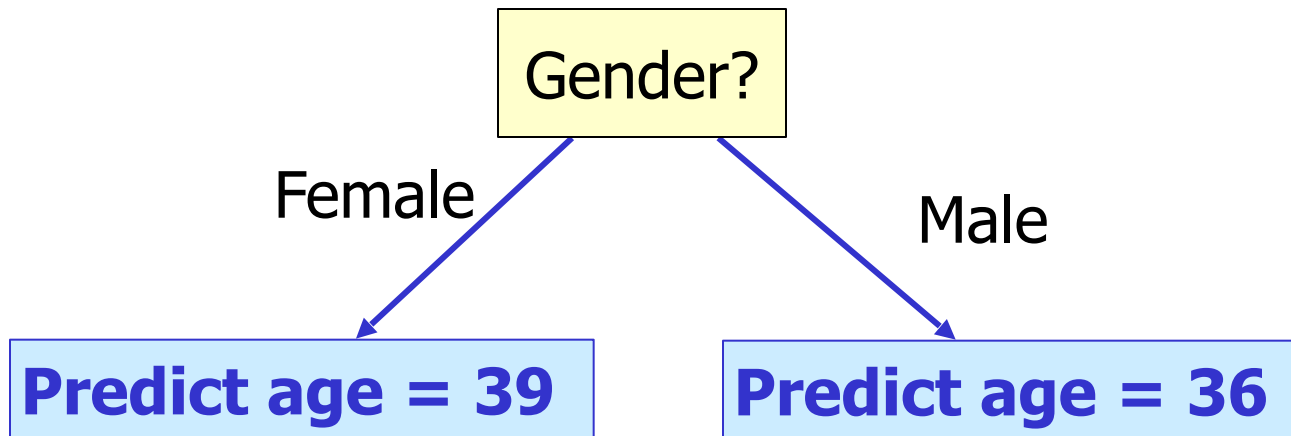
Regression Trees

- “Decision trees for regression”

A regression tree leaf



A one-split regression tree



Choosing the attribute to split on

Gender	Rich?	Num. Children	Num. Beany Babies	Age
Female	No	2	1	38
Male	No	0	0	24
Male	Yes	0	5+	72
:	:	:	:	:

- We can't use information gain.
- What should we use?

Choosing the attribute to split on

Gender	Rich?	Num. Children	Num. Beany Babies	Age
Female	No	2	1	38
Male	No	0	0	24
Male	Yes	0	5+	72
:	:	:	:	:

$MSE(Y|X)$ = The expected squared error if we must predict a record's Y value given only knowledge of the record's X value

If we're told $x=j$, the smallest expected error comes from predicting the mean of the Y-values among those records in which $x=j$. Call this mean quantity $\mu_y^{x=j}$

Then...

$$MSE(Y | X) = \frac{1}{R} \sum_{j=1}^{N_X} \sum_{(k \text{ such that } x_k = j)} (y_k - \mu_y^{x=j})^2$$

Choosing the attribute to split on

Gender	Rich?	Num. Children	Num. Beany Babies	Age
Female	No			
Male	No			
Male	Yes			
:	:			

Regression tree attribute selection: greedily choose the attribute that minimizes $MSE(Y|X)$

Guess what we do about real-valued inputs?

Guess how we prevent overfitting

$MSE(Y|X)$ = The expected squared error if we must predict a record's Y value given only knowledge of the record's X value

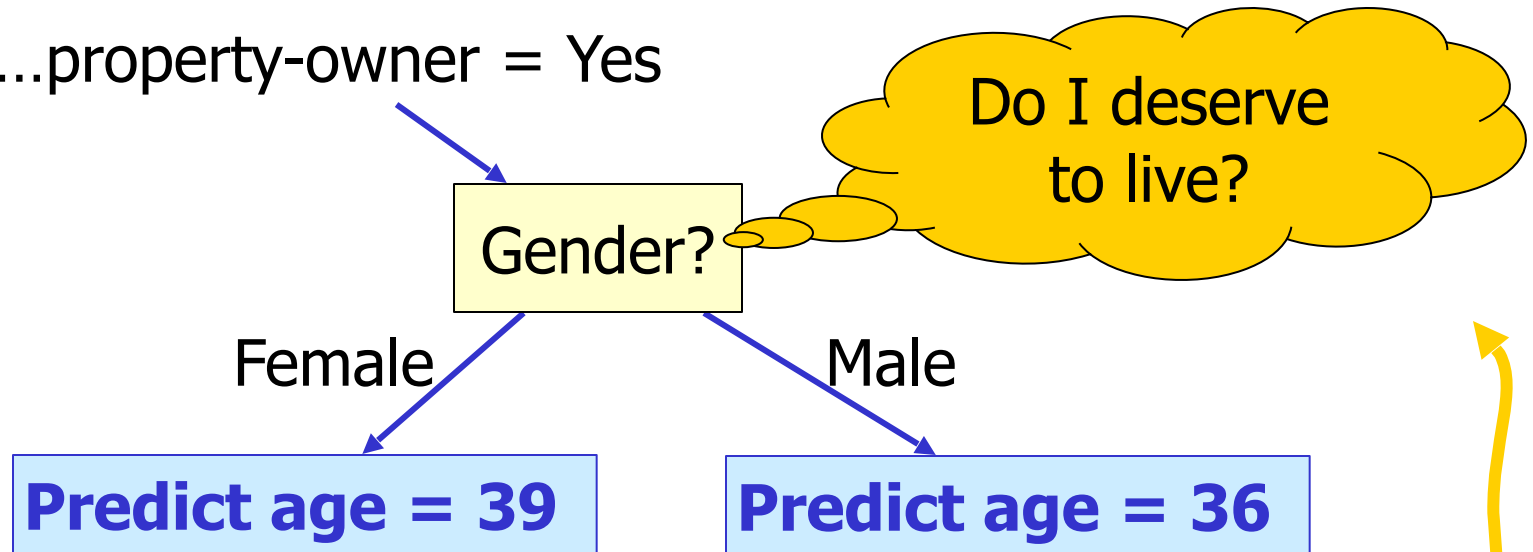
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Then...

$$MSE(Y | X) = \frac{1}{R} \sum_{j=1}^{N_X} \sum_{(k \text{ such that } x_k = j)} (y_k - \mu_y^{x=j})^2$$

Pruning Decision

...property-owner = Yes



property-owning females = 56712

Mean age among POFs = 39

Age std dev among POFs = 12

property-owning males = 55800

Mean age among POMs = 36

Age std dev among POMs = 11.5

Use a standard Chi-squared test of the null-hypothesis "these two populations have the same mean" and Bob's your uncle.

Linear Regression Trees

...property-owner = Yes

Also known as
"Model Trees"

Gender?

Female

Male

Predict age =

$$26 + 6 * \text{NumChildren} - 2 * \text{YearsEducation}$$

Predict age =

$$24 + 7 * \text{NumChildren} - 2.5 * \text{YearsEducation}$$

Leaves contain linear functions (trained using linear regression on all records matching that leaf)

Split attribute chosen to minimize MSE of regressed children.

Pruning with a different Chi-squared

Linear Regression Trees

...property-owner = Yes

Gender?

Female

Predict age =

$26 + 6 * \text{Number of children}$

$* \text{Years Education}$

Also known as
"Model Trees"

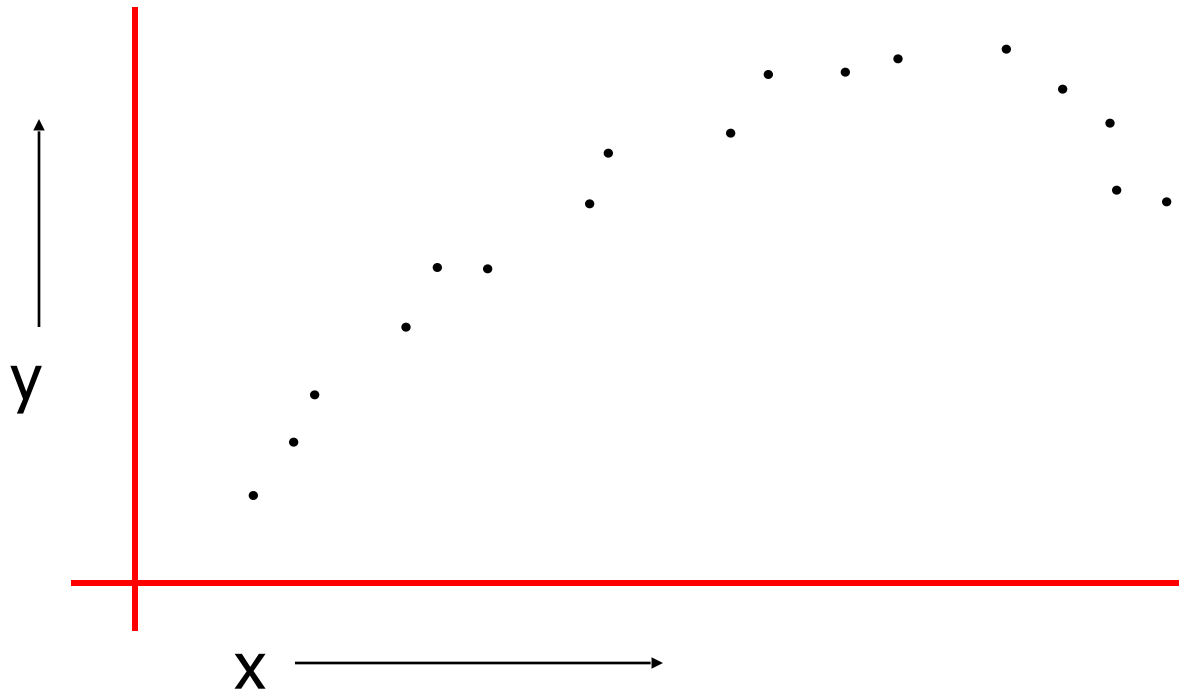
Detail: You typically ignore any categorical attribute that has been tested on higher up in the tree during the regression. But use all untested attributes, and use real-valued attributes even if they've been tested above

Leaves contain linear regression coefficients (trained on records matching that leaf)

Attribute chosen to minimize MSE of regressed children.
Pruning with a different Chi-squared

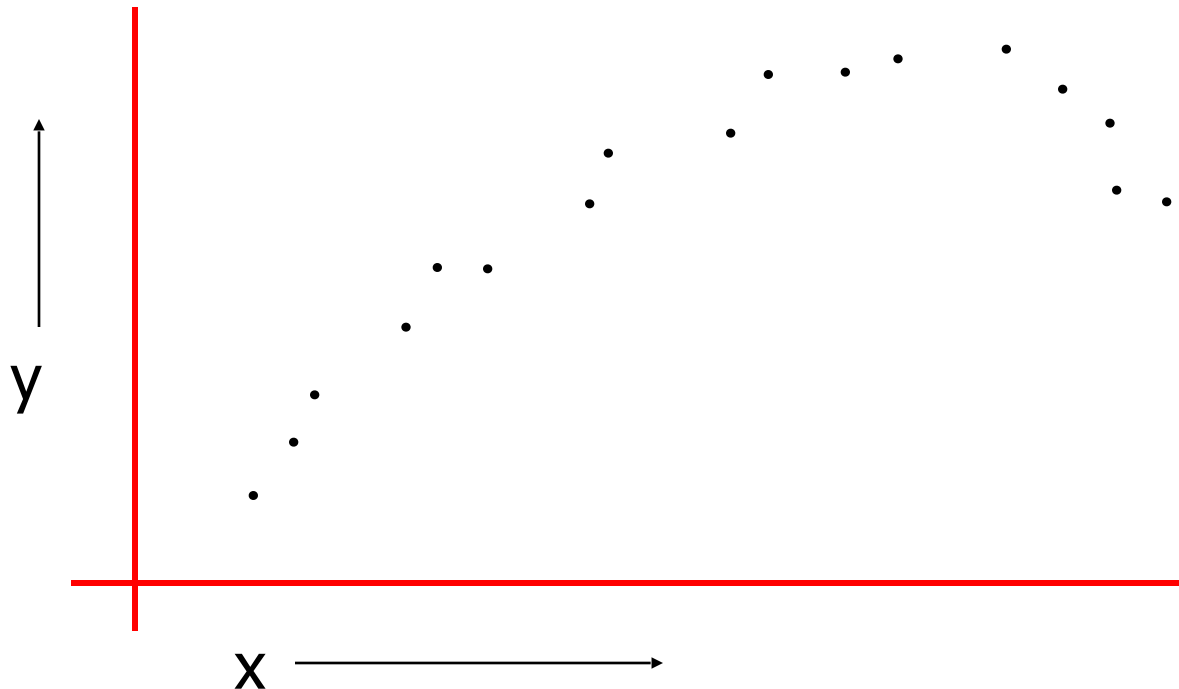
Test your understanding

Assuming **regular** regression trees, can you sketch a graph of the fitted function $y^{\text{est}}(x)$ over this diagram?



Test your understanding

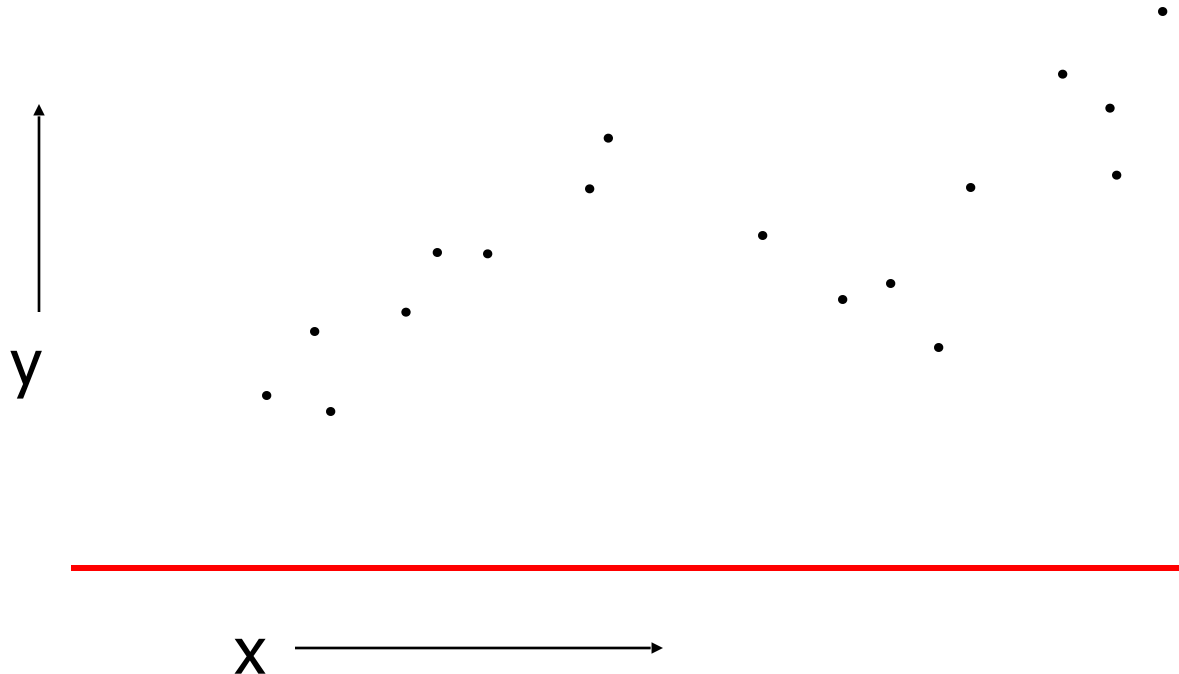
Assuming **linear** regression trees, can you sketch a graph of the fitted function $y^{\text{est}}(x)$ over this diagram?



Multilinear Interpolation

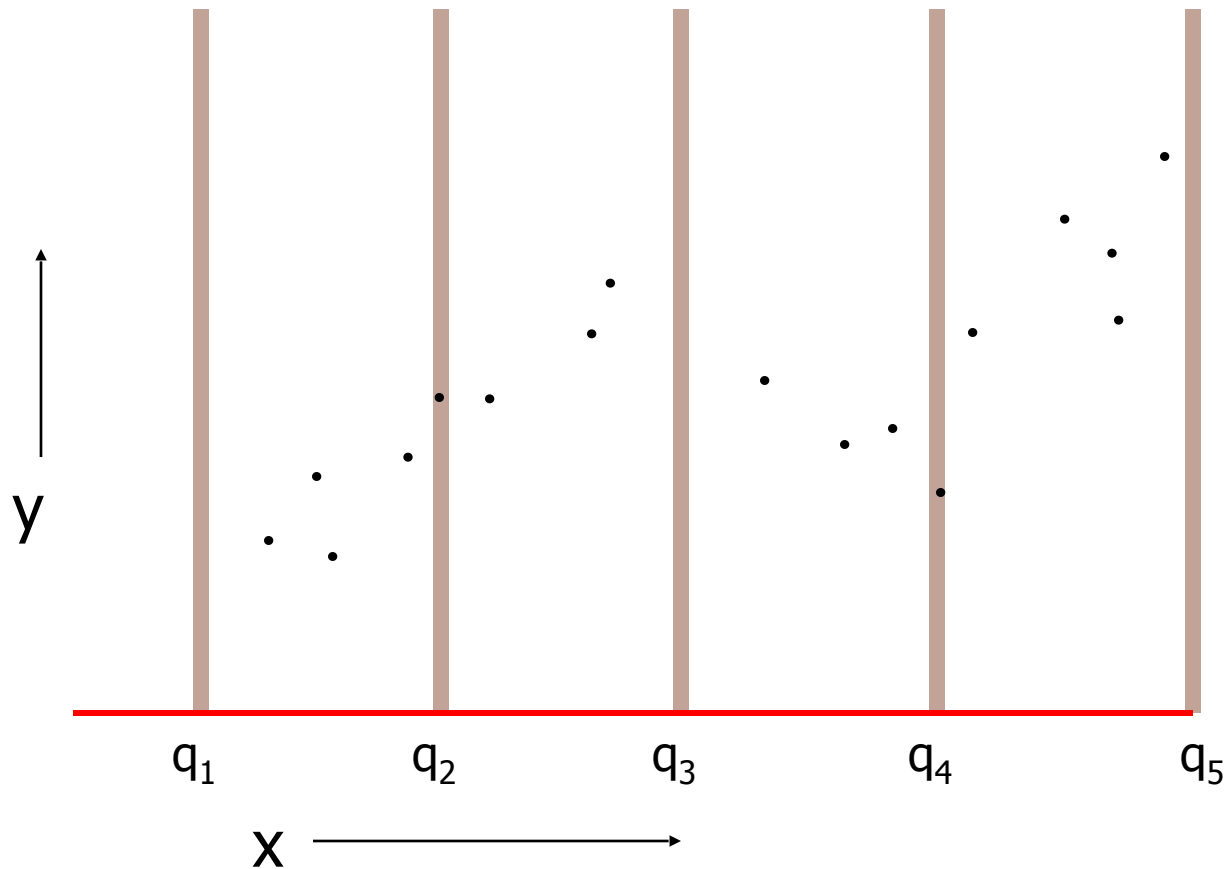
Multilinear Interpolation

Consider this dataset. Suppose we wanted to create a continuous and piecewise linear fit to the data



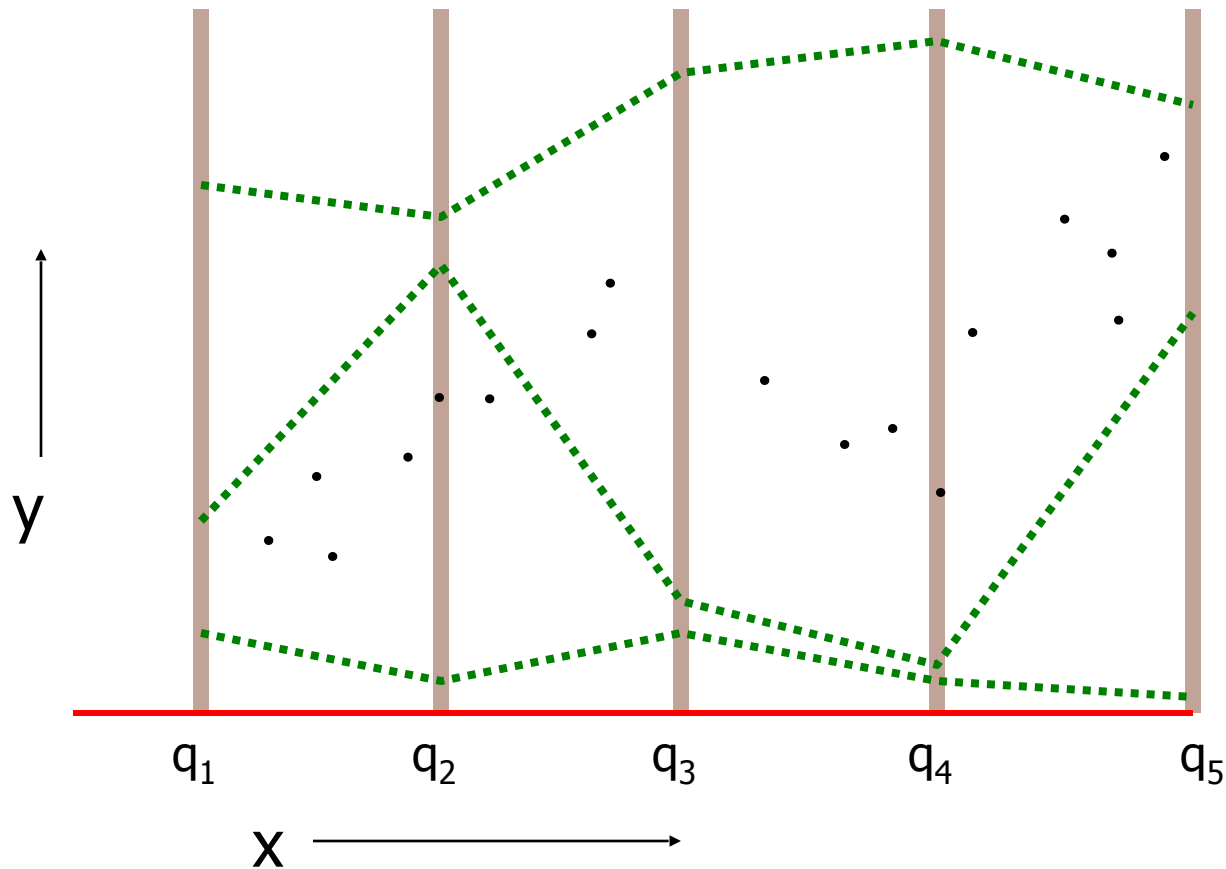
Multilinear Interpolation

Create a set of knot points: selected X-coordinates (usually equally spaced) that cover the data



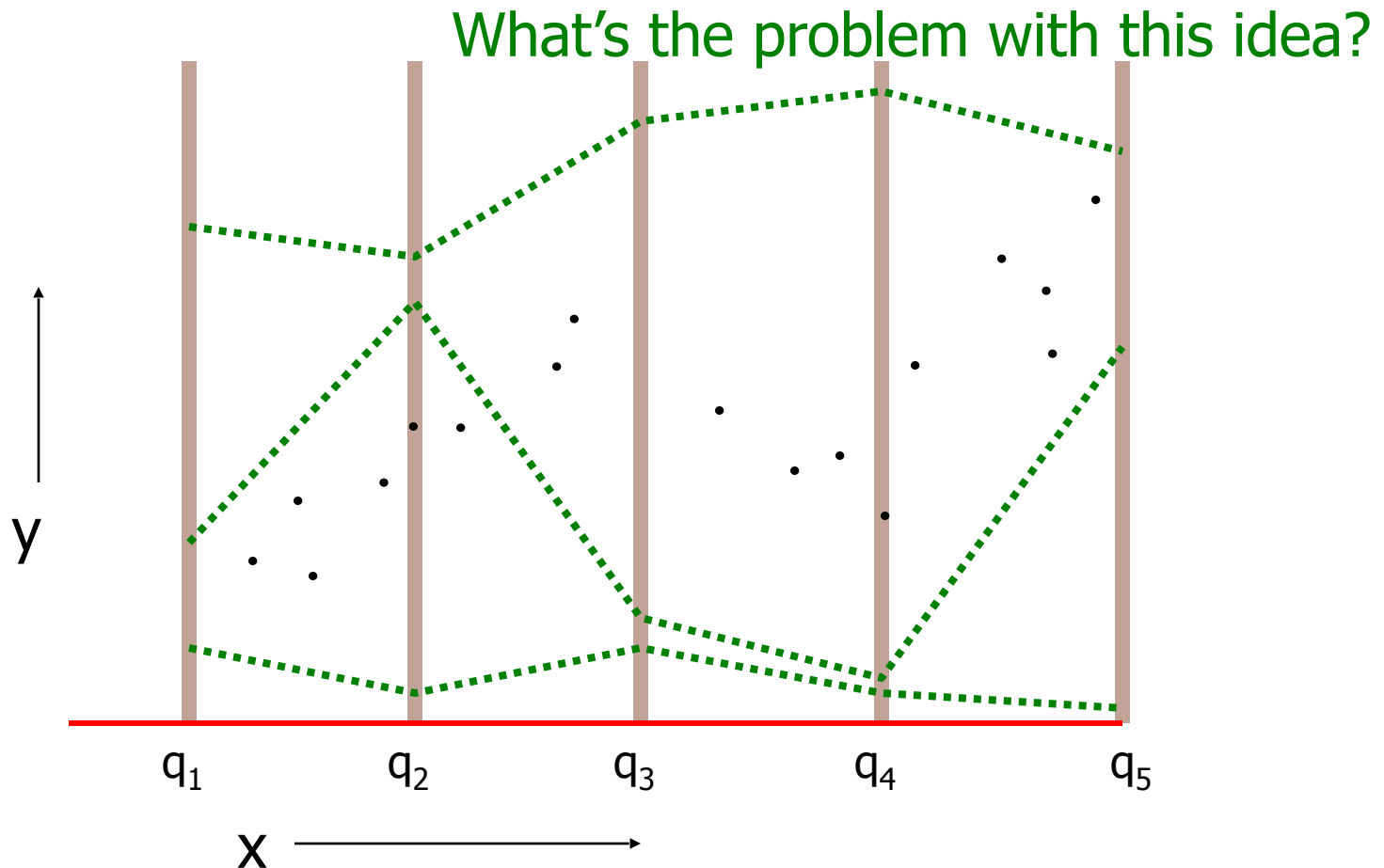
Multilinear Interpolation

We are going to assume the data was generated by a noisy version of a function that can only bend at the knots. Here are 3 examples (none fits the data well)



How to find the best fit?

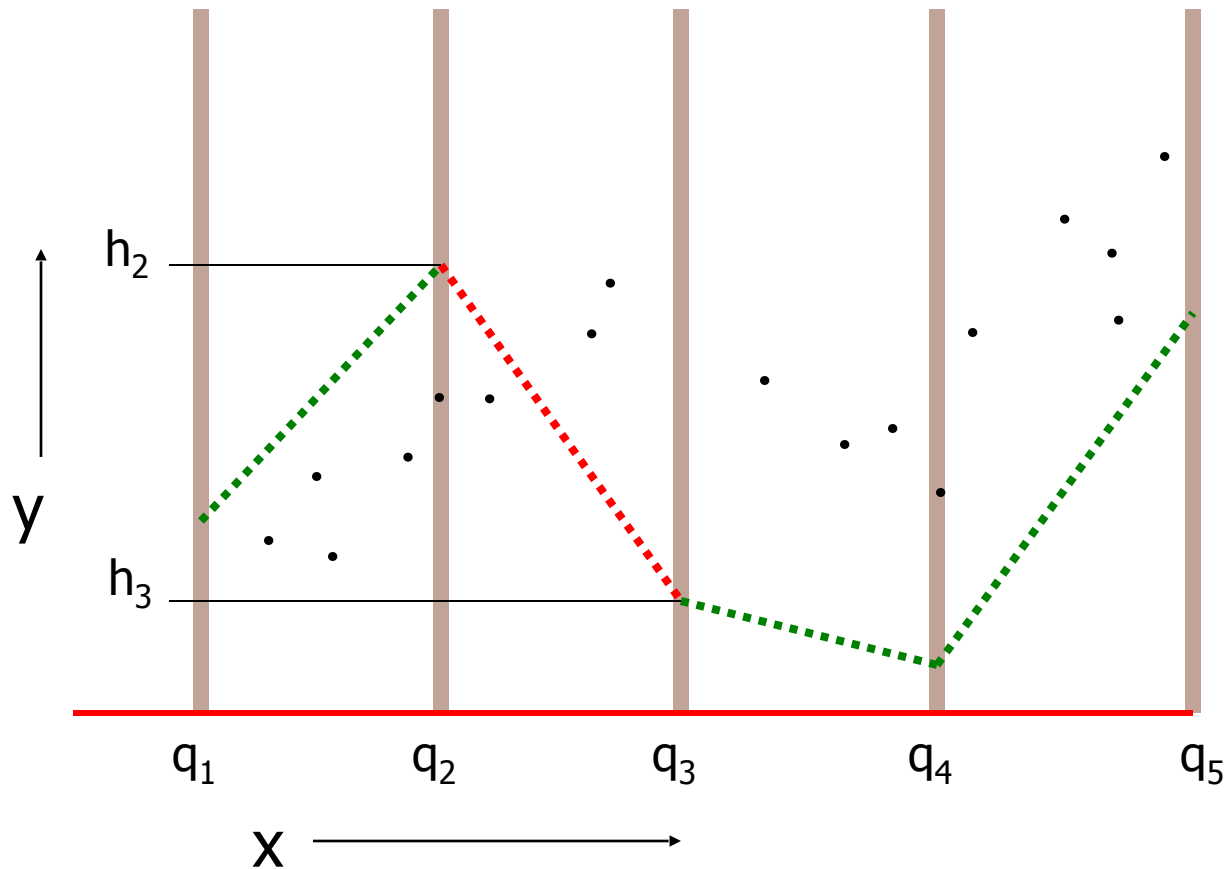
Idea 1: Simply perform a separate regression in each segment for each part of the curve



How to find the best fit?

Let's look at what goes on in the red segment

$$y^{est}(x) = \frac{(q_3 - x)}{w} h_2 + \frac{(x - q_2)}{w} h_3 \text{ where } w = q_3 - q_2$$

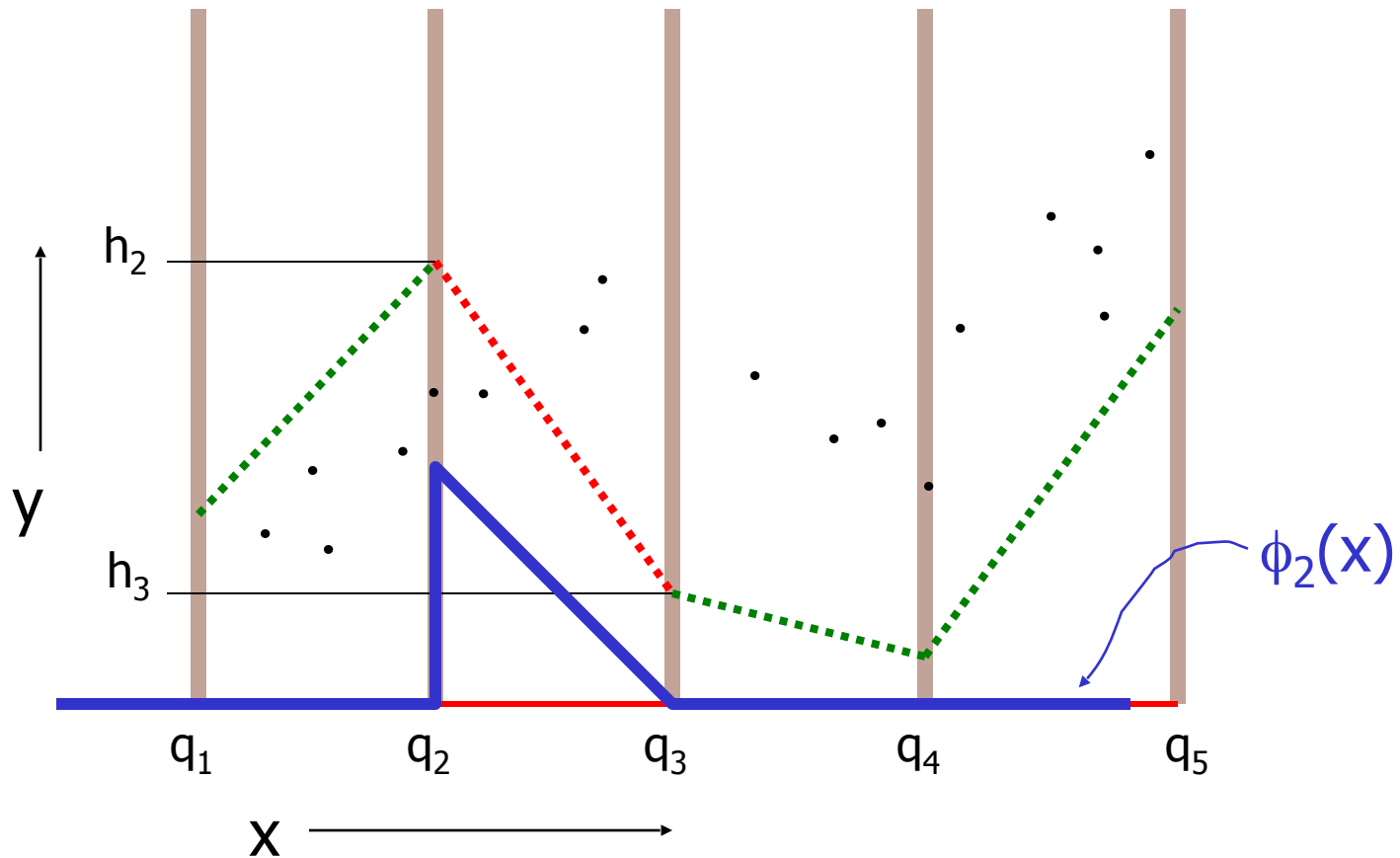


How to find the best fit?

In the red segment...

$$y^{est}(x) = h_2\varphi_2(x) + h_3\varphi_3(x)$$

$$\text{where } \varphi_2(x) = 1 - \frac{x - q_2}{w}, \varphi_3(x) = 1 - \frac{q_3 - x}{w}$$

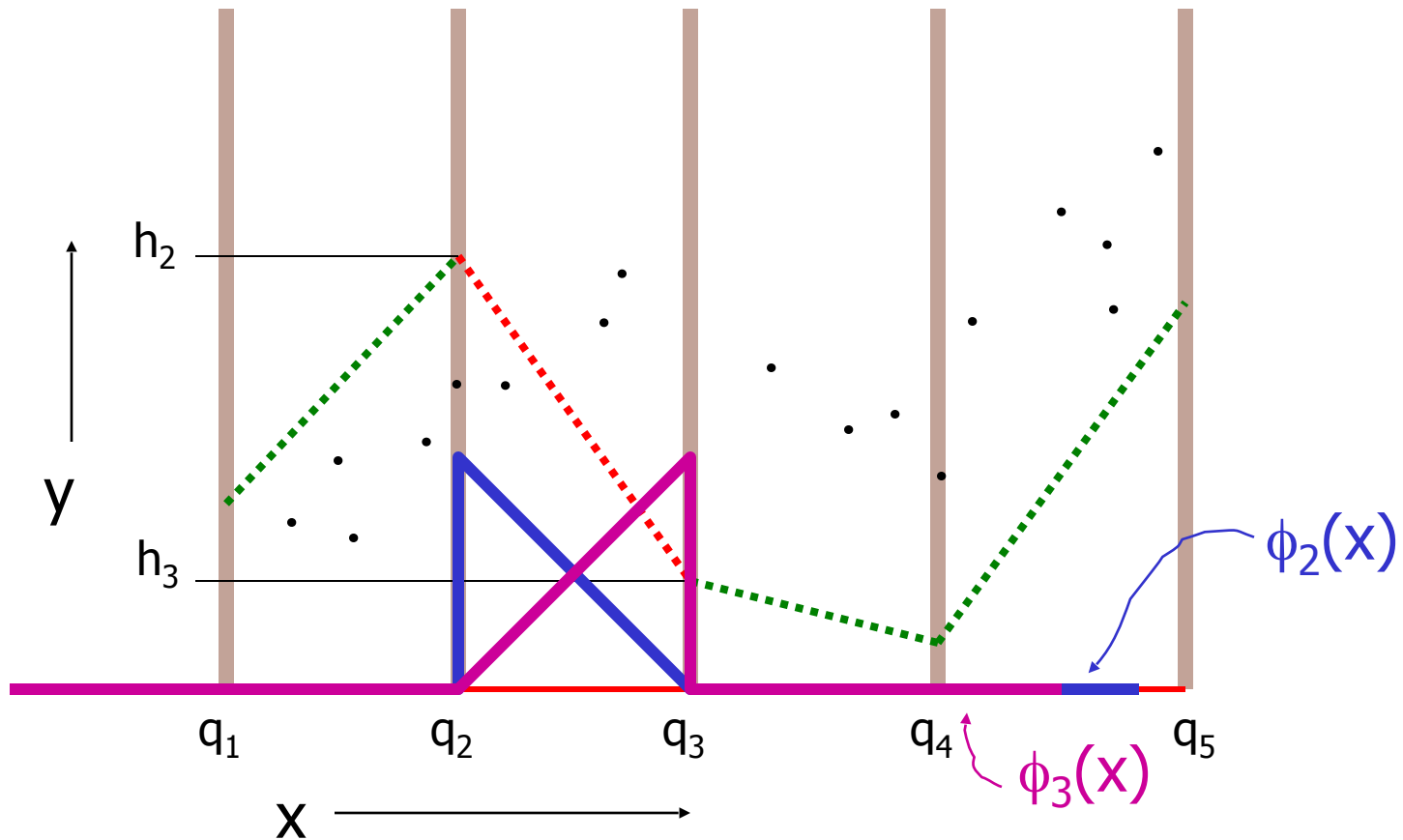


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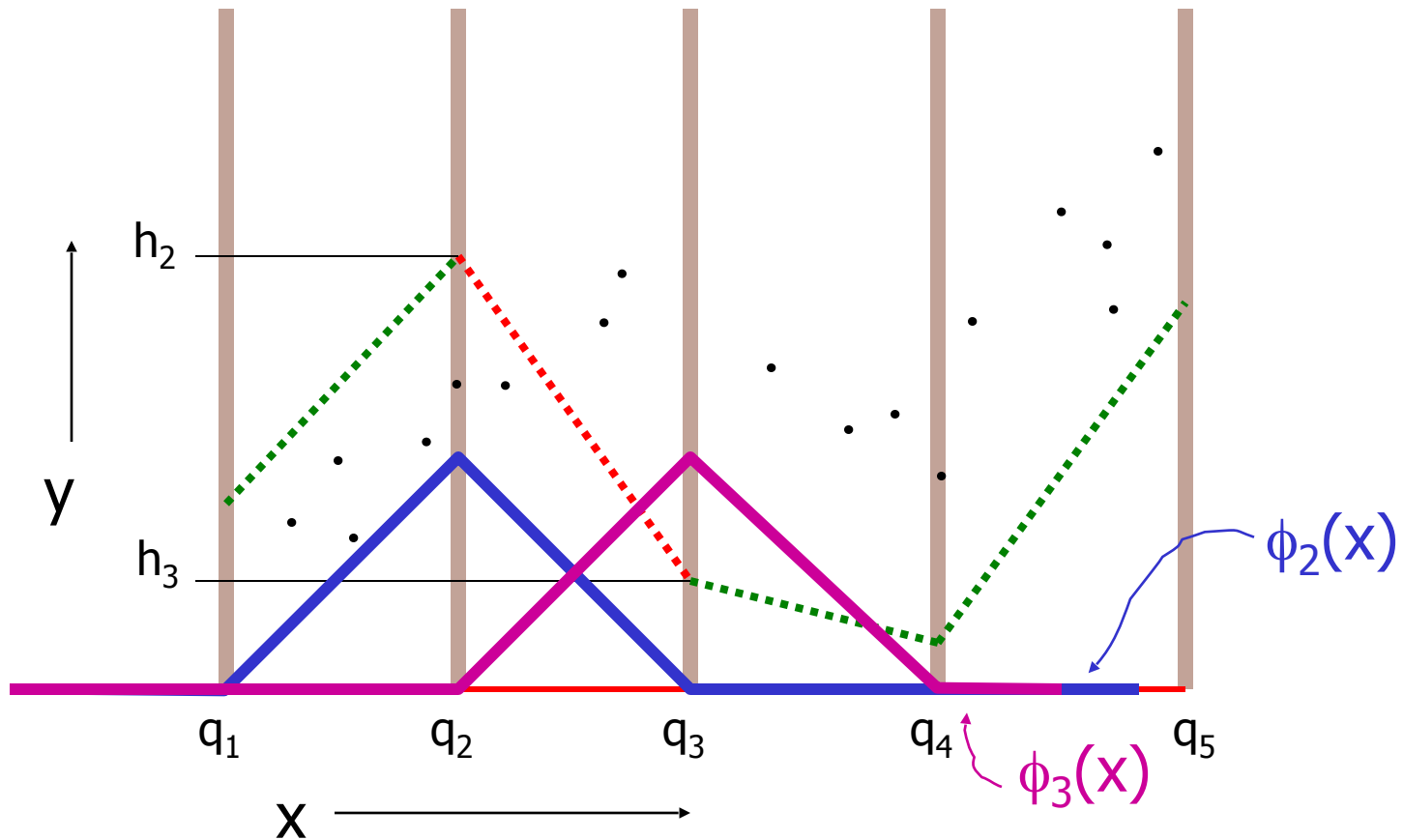


How to find the best fit?

In the red segment...

$$y^{est}(x) = h_2\varphi_2(x) + h_3\varphi_3(x)$$

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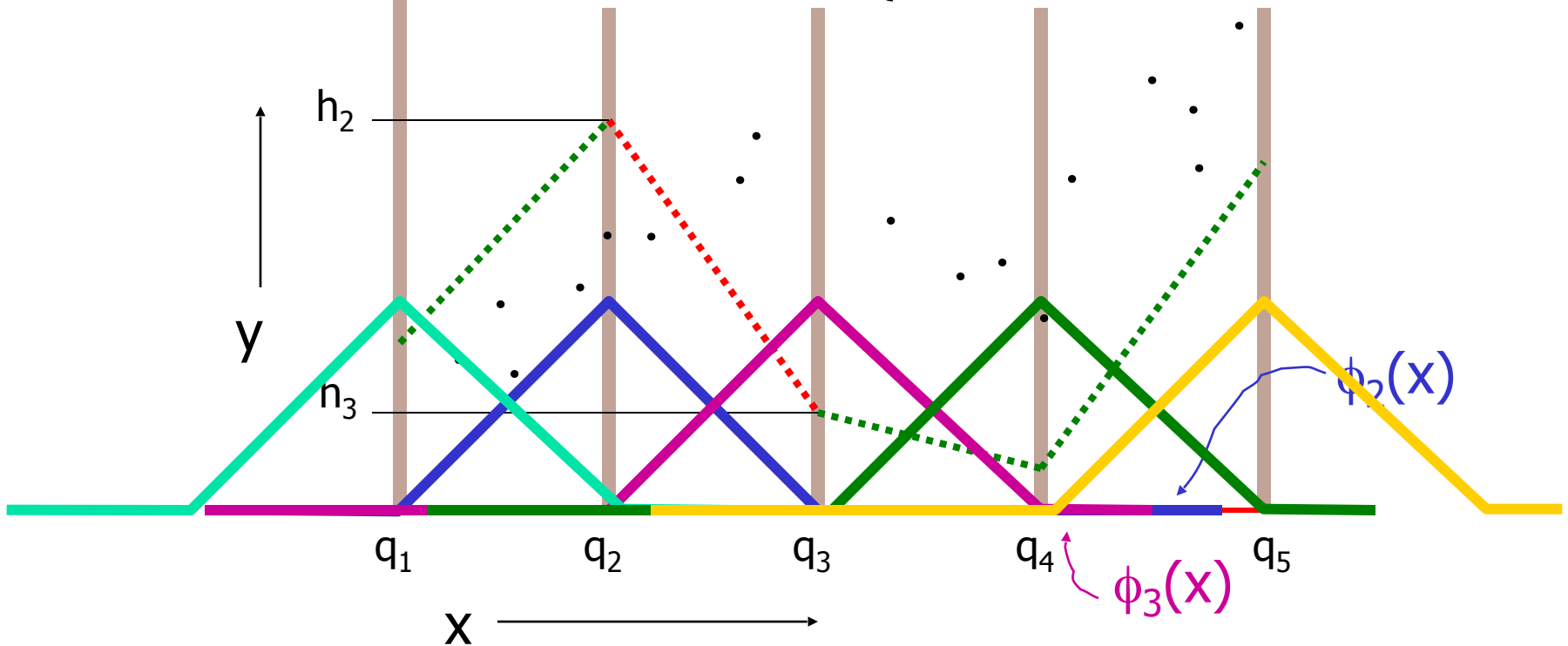


How to find the best fit?

In **general**

$$y^{est}(x) = \sum_{i=1}^{N_K} h_i \varphi_i(x)$$

$$\text{where } \varphi_i(x) = \begin{cases} 1 - \frac{|x - q_i|}{w} & \text{if } |x - q_i| < w \\ 0 & \text{otherwise} \end{cases}$$

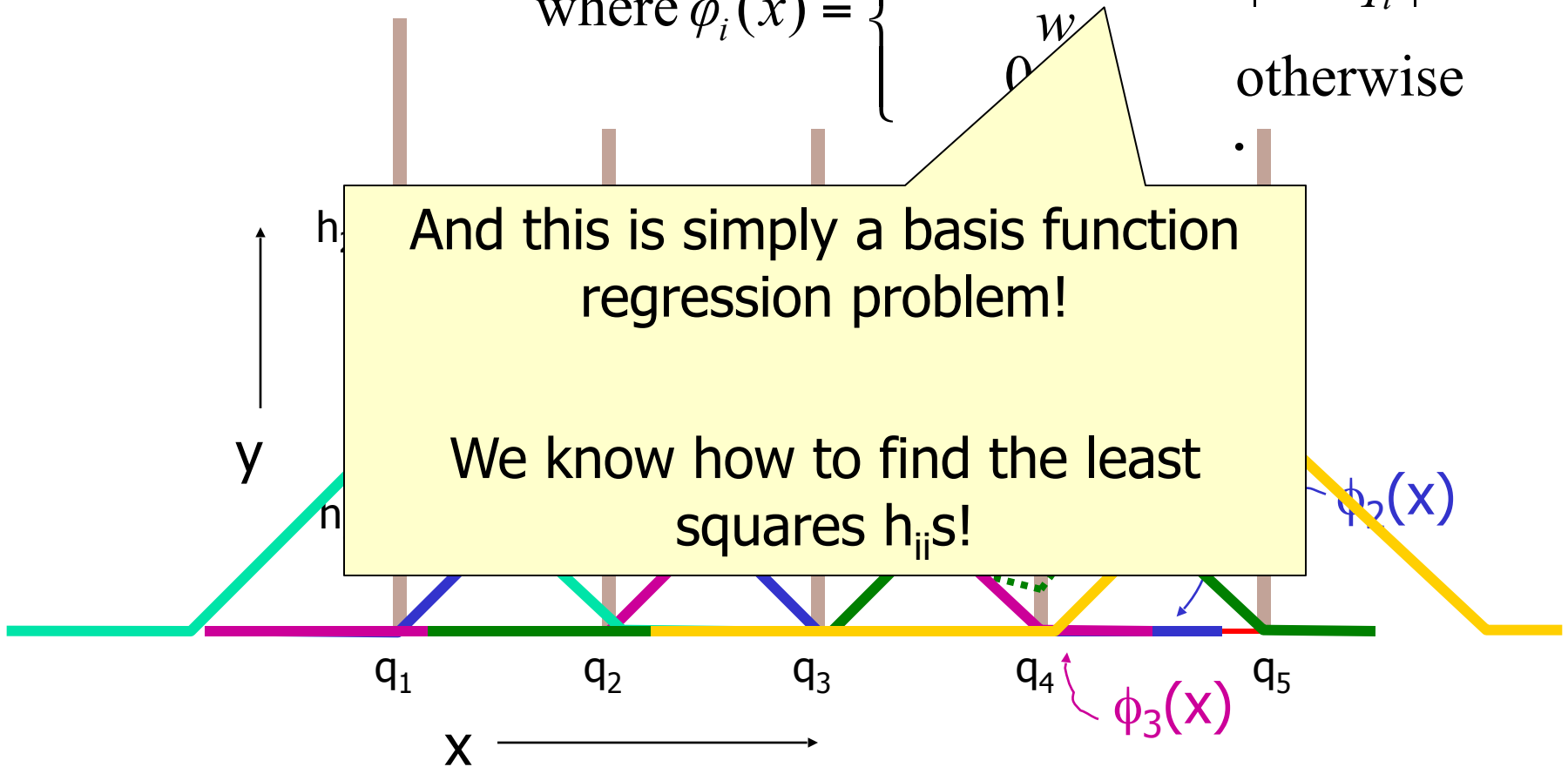


How to find the best fit?

In **general**

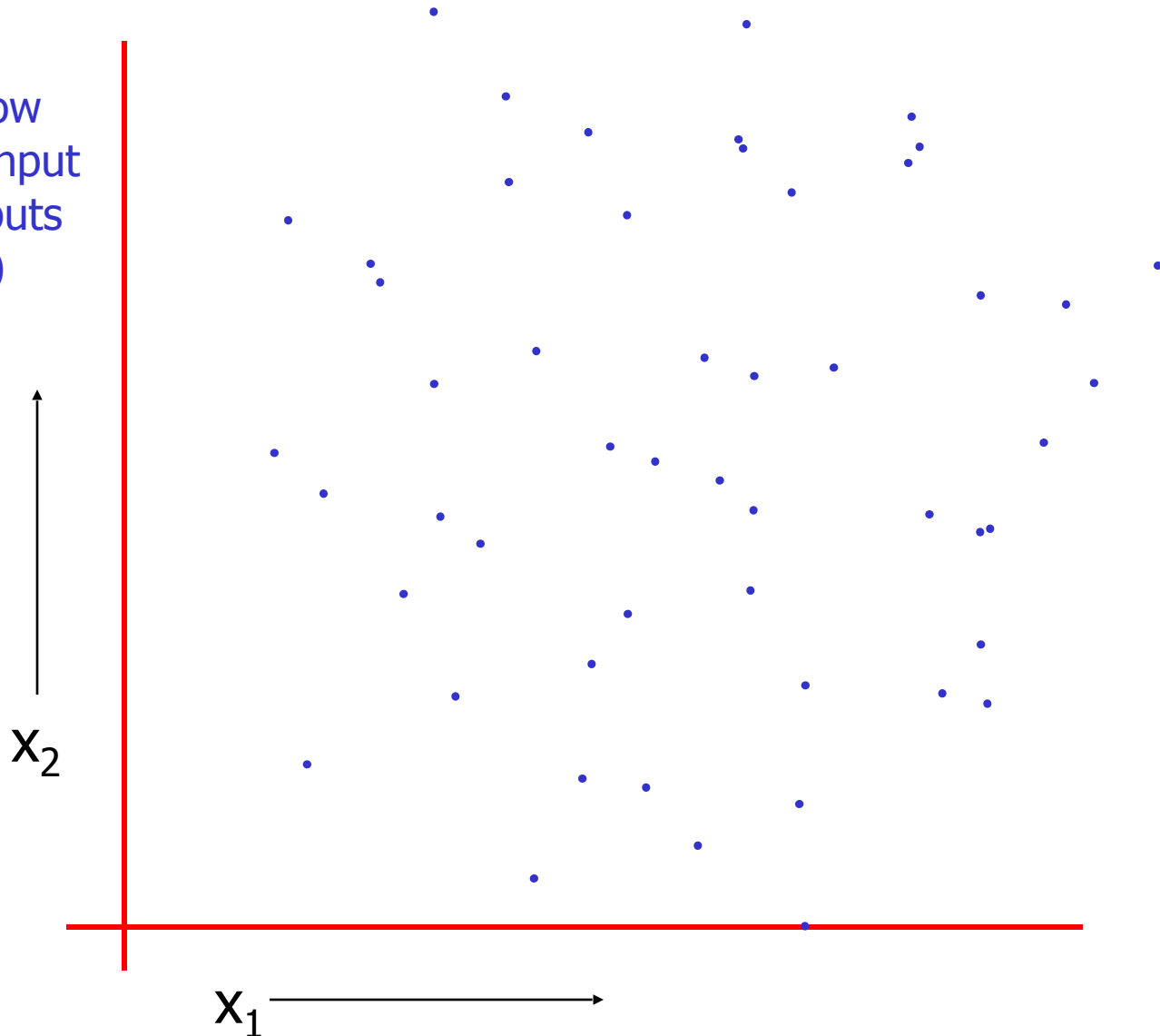
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In two dimensions...

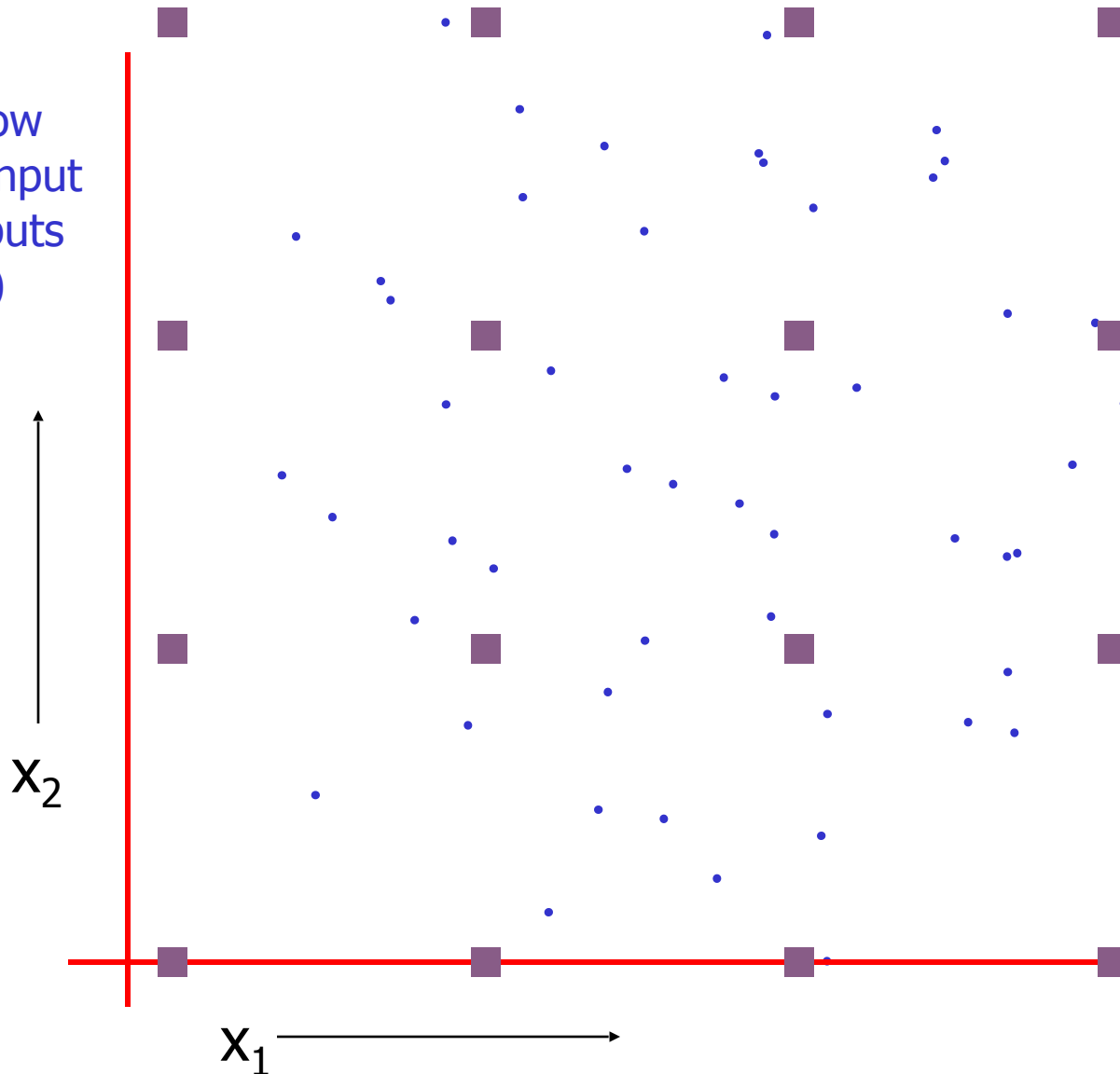
Blue dots show
locations of input
vectors (outputs
not depicted)



In two dimensions...

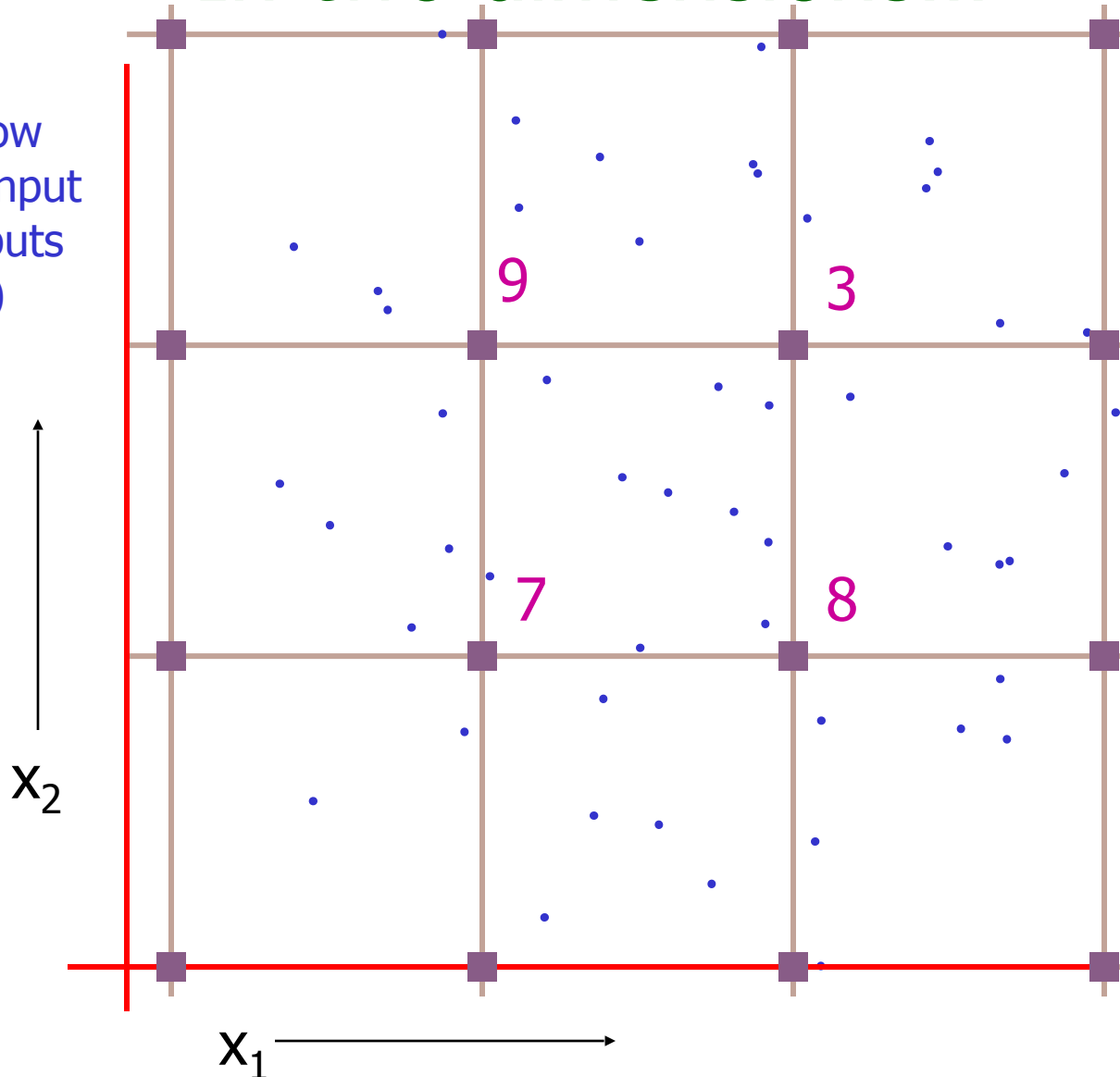
Blue dots show
locations of input
vectors (outputs
not depicted)

■ Each purple dot
is a knot point.
It will contain
the height of the
estimated
surface



In two dimensions...

Blue dots show
locations of input
vectors (outputs
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Each purple dot
is a knot point.
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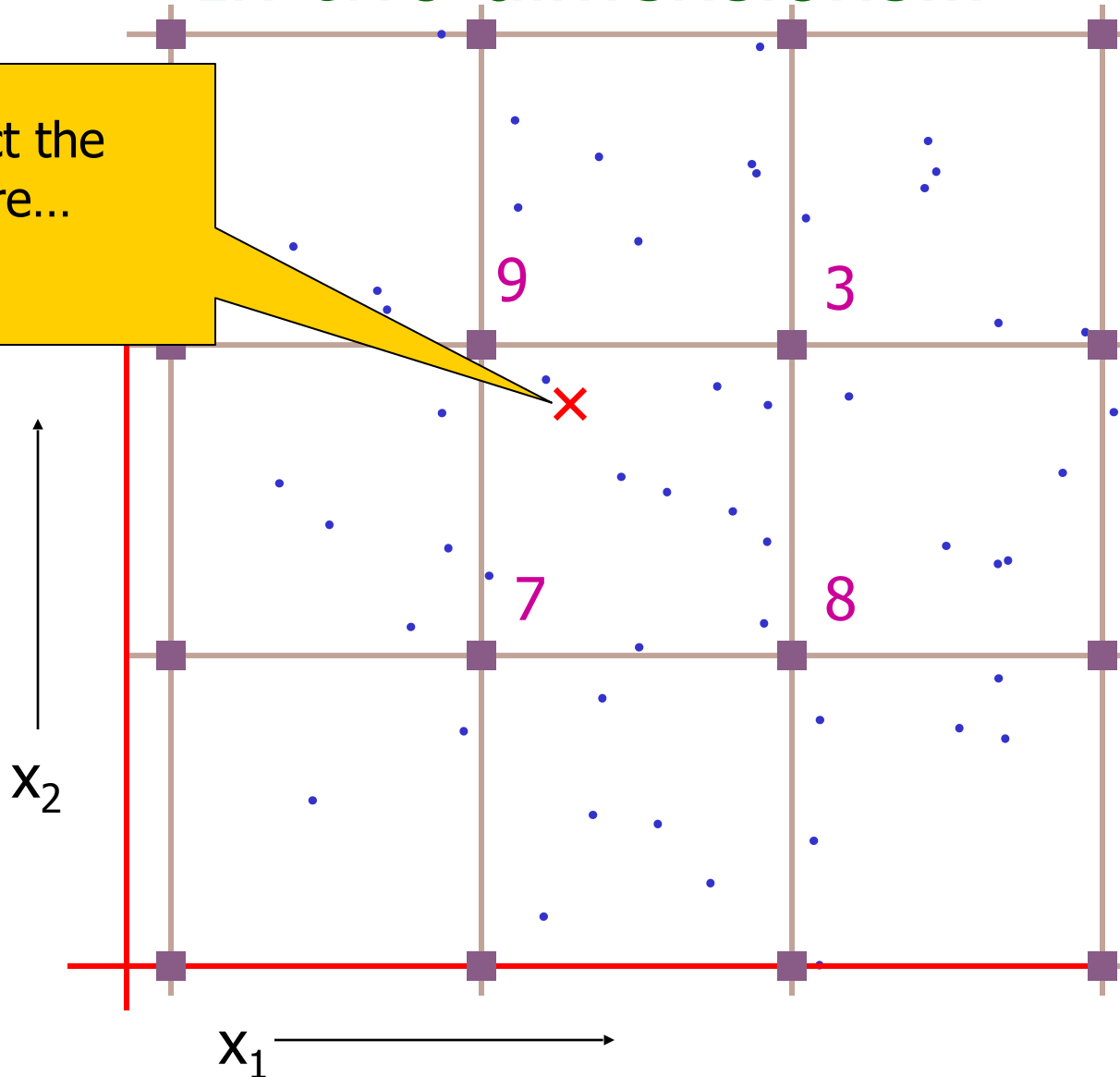
But how do we
do the
interpolation
to ensure that the
surface is
continuous?

In two dimensions...

To predict the value here...

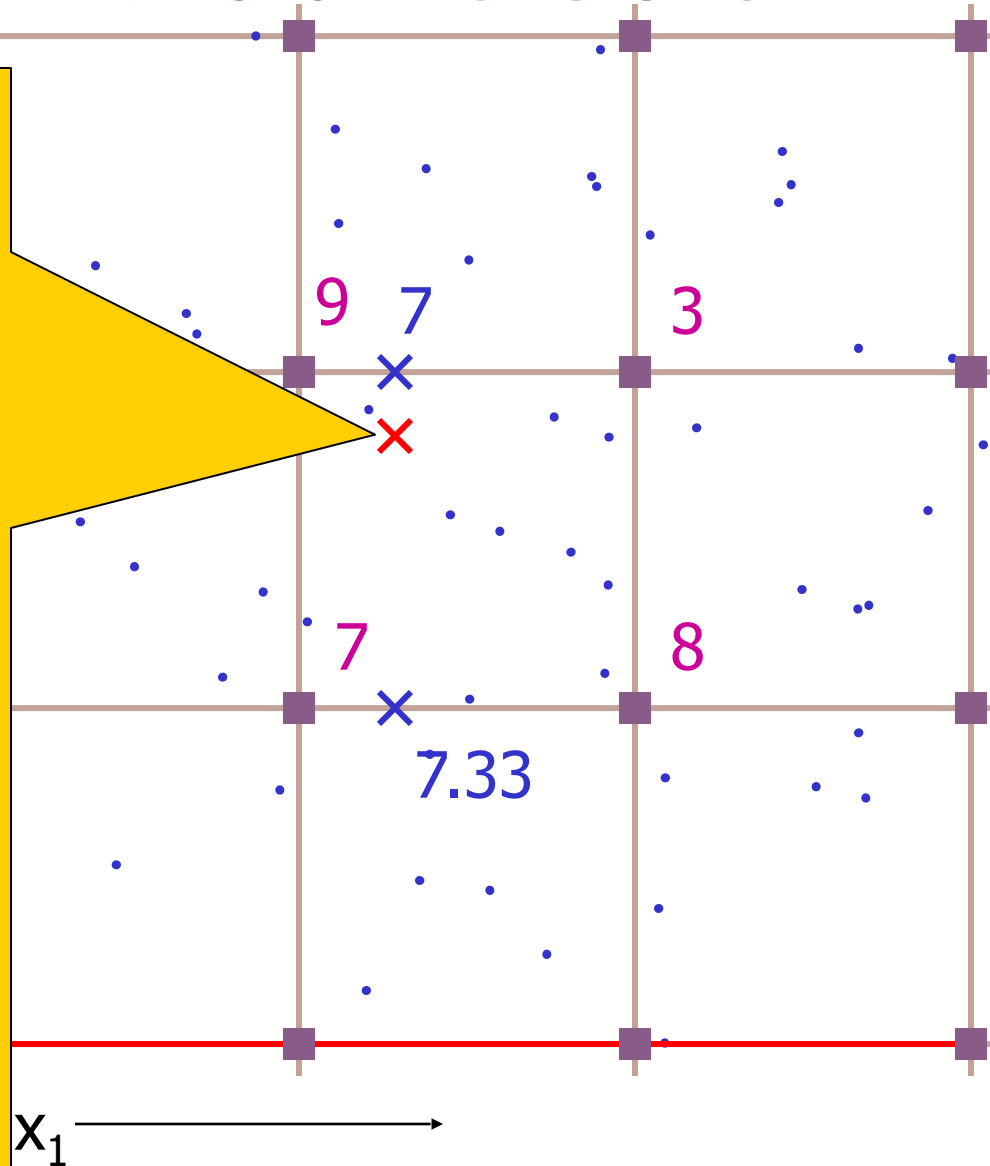
Each purple dot is a knot point. It will contain the height of the estimated surface

But how do we do the interpolation to ensure that the surface is continuous?



In two dimensions...

To predict the value here...
First interpolate its value on two opposite edges...



Each purple dot is a knot point. It will contain the height of the estimated surface

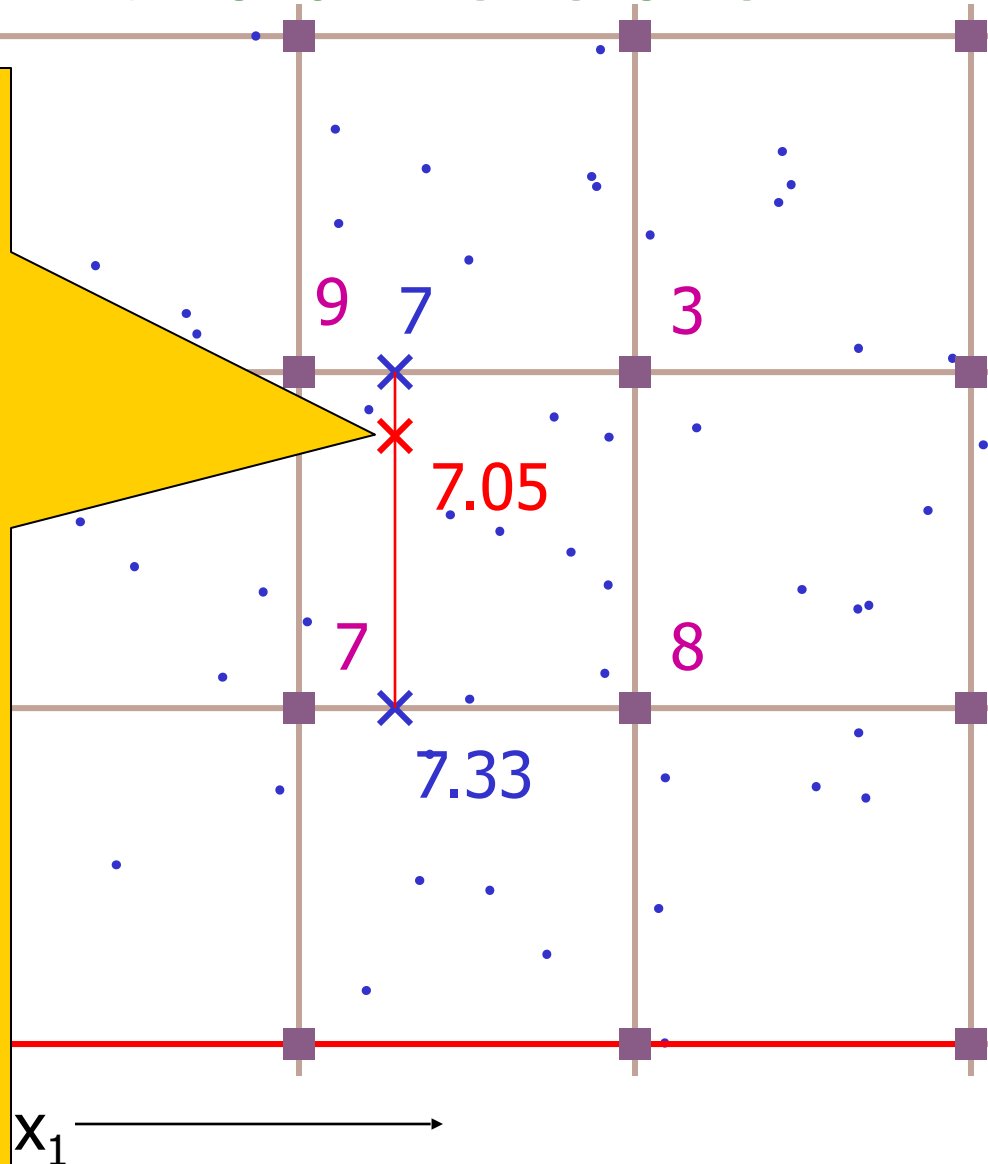
But how do we do the interpolation to ensure that the surface is continuous?

In two dimensions...

To predict the value here...

First interpolate its value on two opposite edges...

Then interpolate between those two values



Each purple dot is a knot point. It will contain the height of the estimated surface

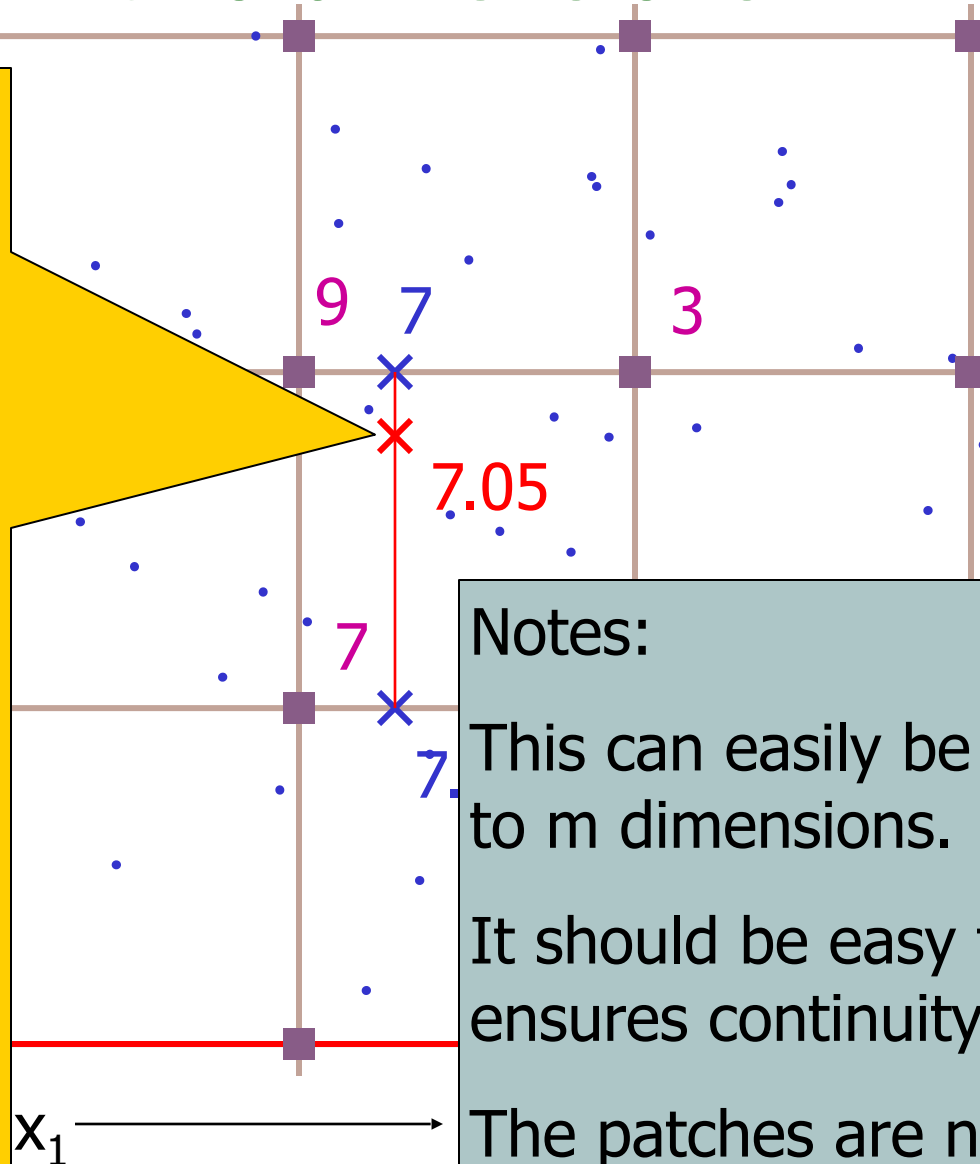
But how do we do the interpolation to ensure that the surface is continuous?

In two dimensions...

To predict the value here...

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Each purple dot is a knot point. It will contain the height of the estimated surface

But how do we do the interpolation to ensure that the

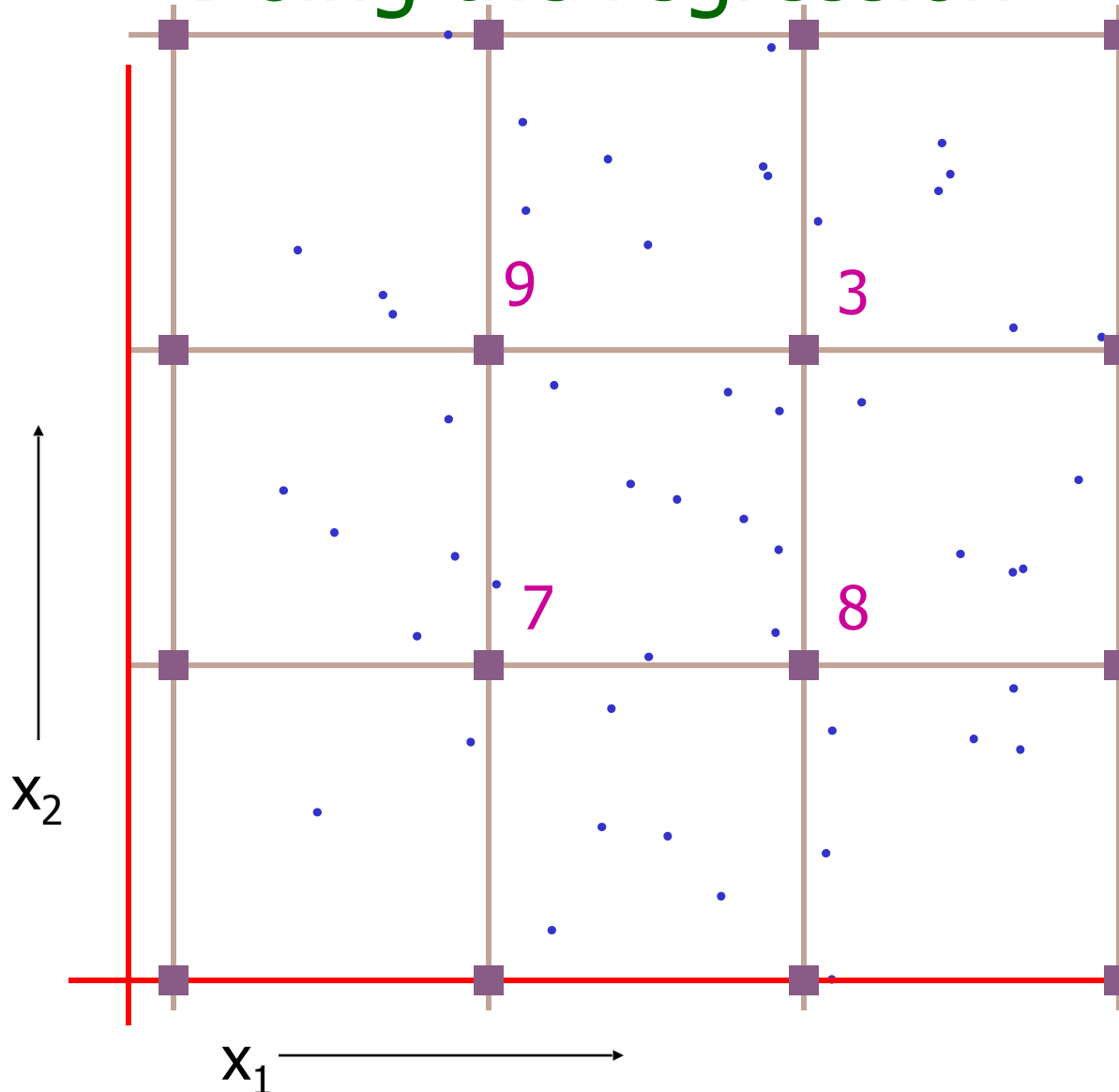
Notes:

This can easily be generalized to m dimensions.

It should be easy to see that it ensures continuity

The patches are not linear

Doing the regression



Given data, how do we find the optimal knot heights?

Happily, it's simply a two-dimensional basis function problem.

(Working out the basis functions is tedious, unilluminating, and easy)

What's the problem in higher dimensions?

MARS: Multivariate Adaptive Regression Splines

MARS

- Multivariate Adaptive Regression Splines
- Invented by Jerry Friedman (one of Andrew's heroes)
- Simplest version:

Let's assume the function we are learning is of the following form:

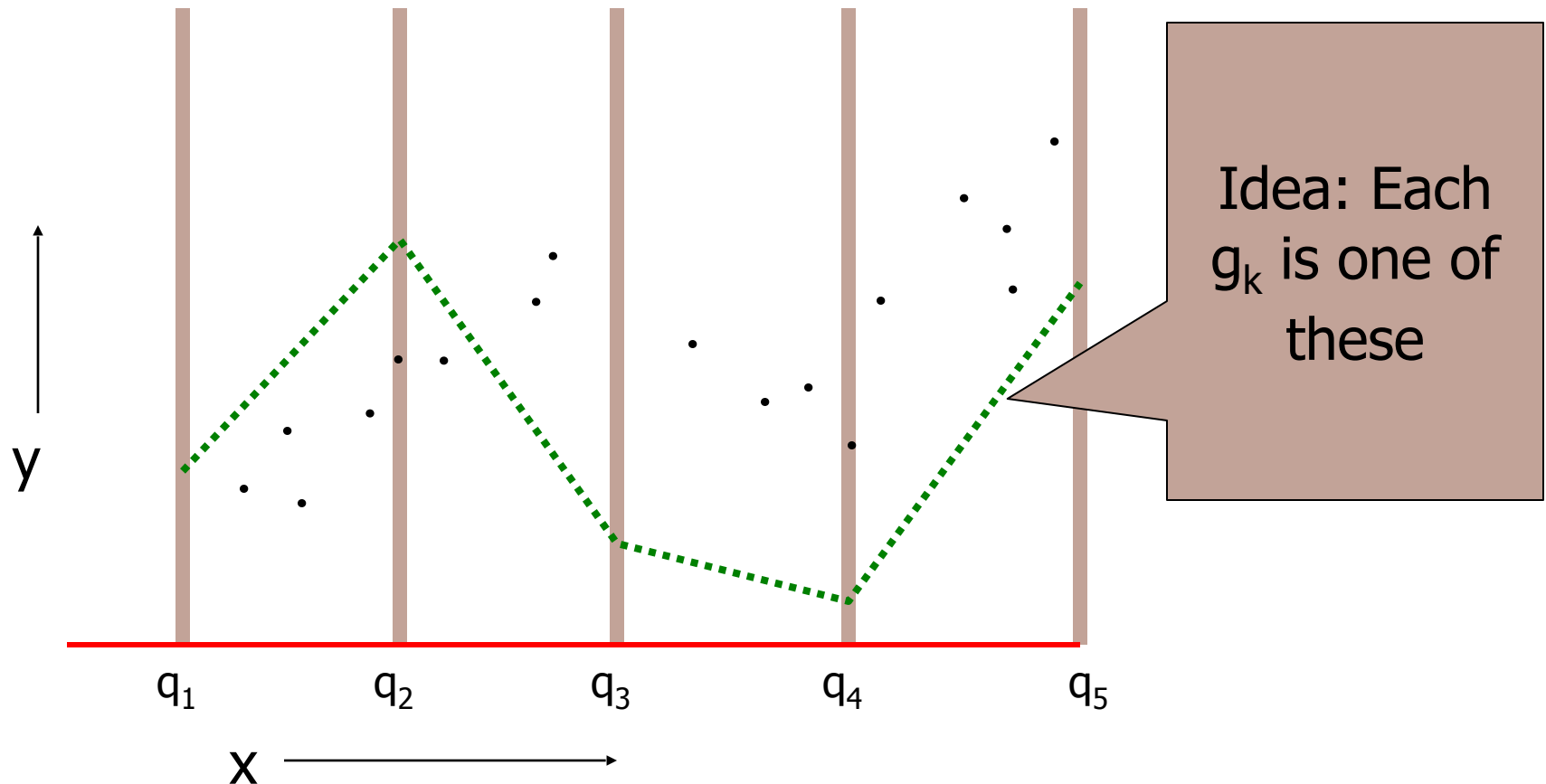
$$y^{est}(\mathbf{x}) = \sum_{k=1}^m g_k(x_k)$$

Instead of a linear combination of the inputs, it's a linear combination of non-linear functions of **individual** inputs

MARS

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Instead of a linear combination of the inputs, it's a linear combination of non-linear functions of **individual** inputs



MARS

$$y^{est}(\mathbf{x}) = \sum_{k=1}^m g_k(x_k)$$

Instead of a linear combination of the inputs, it's a linear combination of non-linear functions of **individual** inputs

$$y^{est}(\mathbf{x}) = \sum_{k=1}^m \sum_{j=1}^{N_K} h_j^k \varphi_j^k(x_k)$$

$$\text{where } \varphi_j^k(x) = \begin{cases} 1 - \frac{|x_k - q_j^k|}{w_k} & \text{if } |x_k - q_j^k| < w_k \\ 0 & \text{otherwise} \end{cases}$$

q_j^k : The location of the j 'th knot in the k 'th dimension

h_j^k : The regressed height of the j 'th knot in the k 'th dimension

w^k : The spacing between knots in the k th dimension

q_1

q_2

q_3

q_4

q_5

\mathbf{x}

That's not complicated enough!

- Okay, now let's get serious. We'll allow arbitrary "two-way interactions":

$$y^{est}(\mathbf{x}) = \sum_{k=1}^m g_k(x_k) + \sum_{k=1}^m \sum_{t=k+1}^m g_{kt}(x_k, x_t)$$

The function we're learning is allowed to be a sum of non-linear functions over all one-d and 2-d subsets of attributes

Can still be expressed as a linear combination of basis functions

Thus learnable by linear regression

Full MARS: Uses cross-validation to choose a subset of subspaces, knot resolution and other parameters.

If you like MARS...

...See also CMAC (Cerebellar Model Articulated Controller) by James Albus (another of Andrew's heroes)

- Many of the same gut-level intuitions
- But entirely in a neural-network, biologically plausible way
 - (All the low dimensional functions are by means of lookup tables, trained with a delta-rule and using a clever blurred update and hash-tables)

Where are we now?

Inputs	Inference Engine Learn	$p(E_1 E_2)$	Joint DE
Inputs	Classifier	Predict category	Dec Tree, Gauss/Joint BC, Gauss Naïve BC,
Inputs	Density Estimator	Probability	Joint DE, Naïve DE, Gauss/Joint DE, Gauss Naïve DE
Inputs	Regressor	Predict real no.	Linear Regression, Polynomial Regression, RBFs, Robust Regression Regression Trees, Multilinear Interp, MARS

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