

A Common Package Specification:

Getting Build Tools to Talk to Each Other:
Lessons Learned From Making Thousands of
Binaries Consumable by Any Build System

DIEGO RODRIGUEZ-LOSADA GONZALEZ



CONAN 2.0
C/C++ Package Manager

Outline

- **Definition and scope**
- Implementation experience
- CPS basics
 - Directories and libraries: ZLib
 - Components and requirements: Openssl
 - Full CPS
- Advanced use cases
 - Full library definition
 - Runtime
 - Conditionals
 - Editable packages
 - Protobuf modules and cross-building
 - CPS files location
- Speeding adoption hints
- Conclusions and next steps

Problem definition and scope

```
#include <zlib.h>

int main(void){
    ...
    deflateInit(&defstream,
                Z_BEST_COMPRESSION);
}
```

Build system scripts

1. Define the version to use
2. Define the configuration: Windows, x86_64, VS-2022, Release, static library
3. Install (system package manager or language package manager), build from source by the user, with that configuration
4. **Pass information to the build system so it can locate and use it successfully**

What is a package

```
#include <zlib.h>

int main(void){
    ...
    deflateInit(&defstream,
                Z_BEST_COMPRESSION);
}
```

Build system scripts

ZLib

```
include
    zconf.h
    zlib.h

lib
    zlib.lib
```

- Independent unit of build and release (versionable)
- Ready to use (binary)

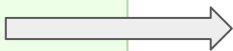
Consuming a package

```
#include <zlib.h>
```

```
int main(void){
```

```
...
```

```
    deflateInit(&defstream,  
                Z_BEST_COMPRESSION);
```

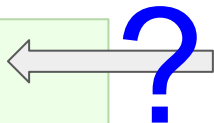


ZLib

```
include  
    zconf.h  
    zlib.h
```

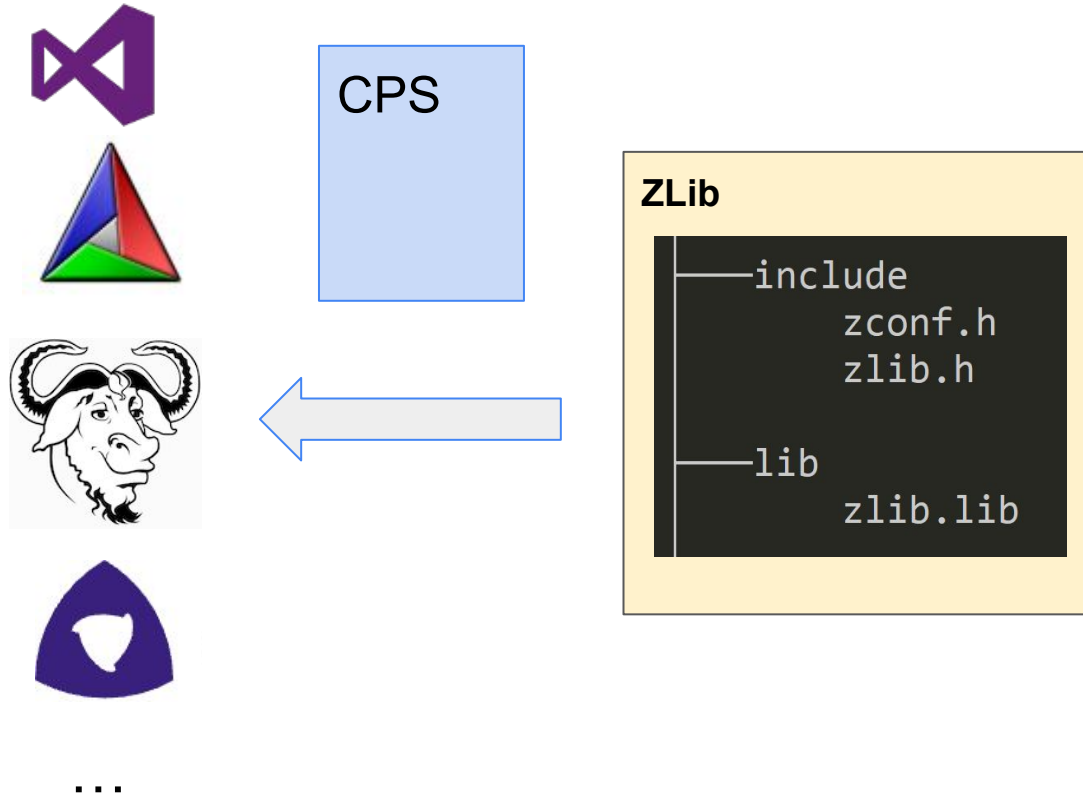
```
lib  
    zlib.lib
```

```
Build system scripts
```



```
-I<path>/include  
-L<path>/lib  
-lzlib
```

Common Package Specification (CPS): Scope



Related work

- CPS: <https://cps-org.github.io/cps> by Matthew Woehlke et al
 - <https://www.open-std.org/jtc1/sc22/wg21/docs/papers/2018/p1313r0.html>
- ISO C++: <https://github.com/isocpp/pkg-fmt>
- Libman
<https://api.csswg.org/bikeshed/?force=1&url=https://raw.githubusercontent.com/vector-of-bool/libman/develop/data/spec.bs> by Colby Pike (@vectorofbool)



Existing solutions

```
prefix=@CMAKE_INSTALL_PREFIX@
exec_prefix=@CMAKE_INSTALL_PREFIX@
libdir=@INSTALL_LIB_DIR@
sharedlibdir=@INSTALL_LIB_DIR@
includedir=@INSTALL_INC_DIR@

Name: zlib
Description: zlib compression library
Version: @VERSION@

Requires:
Libs: -L${libdir} -L${sharedlibdir} -lz
Cflags: -I${includedir}
```

```
set(_ZLIB_x86 "(x86)")
set(_ZLIB_SEARCH_NORMAL PATHS
"[HKEY_LOCAL_MACHINE\\SOFTWARE\\GnuWin32\\Zlib;InstallPath]"
list(APPEND _ZLIB_SEARCHES _ZLIB_SEARCH_NORMAL)

if(ZLIB_USE_STATIC_LIBS)
    set(ZLIB_NAMES zlibstatic zlibstat zlib z)
    set(ZLIB_NAMES_DEBUG zlibstaticd zlibstatd zlibd zd)
else()
    set(ZLIB_NAMES z zlib zdll zlib1 zlibstatic zlibwapi ..)
    set(ZLIB_NAMES_DEBUG zd zlibd zdlld zlibd1 zlib1d ..)
endif()

if(ZLIB_FOUND)
    set(ZLIB_INCLUDE_DIRS ${ZLIB_INCLUDE_DIR})

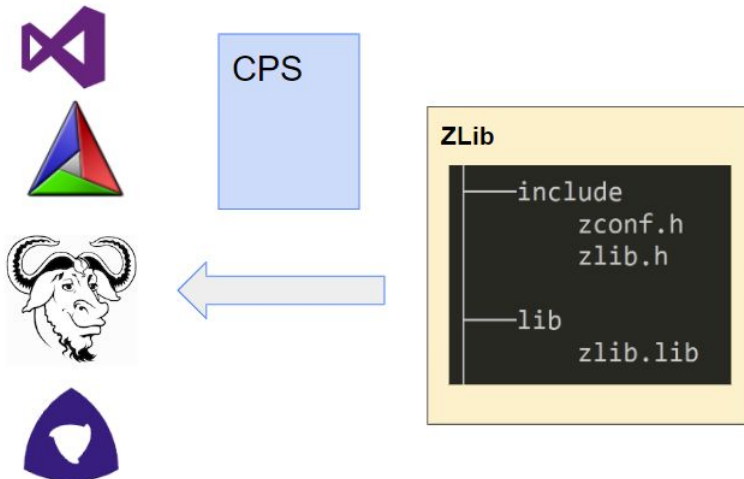
    if(NOT TARGET ZLIB::ZLIB)
        add_library(ZLIB::ZLIB UNKNOWN IMPORTED)
        set_target_properties(ZLIB::ZLIB PROPERTIES
            INTERFACE_INCLUDE_DIRECTORIES
            "${ZLIB_INCLUDE_DIRS}")
```

[Searching for Convergence in C++ Package Management](#) - Bret Brown & Daniel Ruoso - CppNow 2022

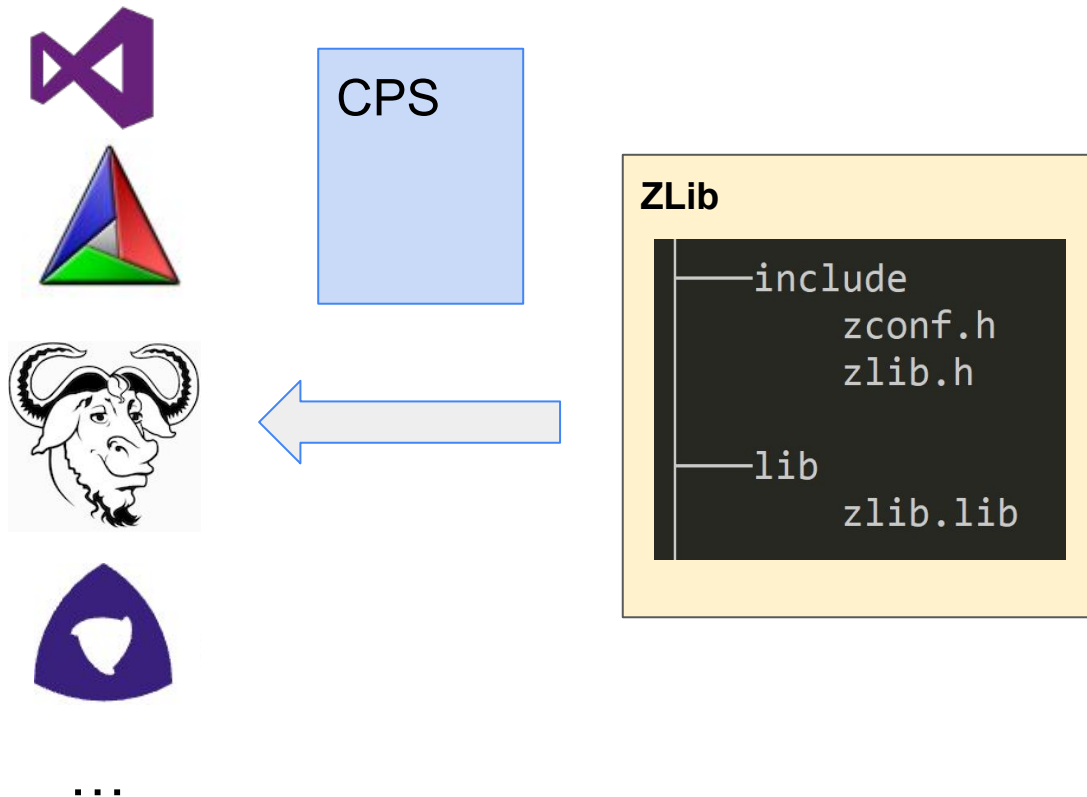
[Case For a Standardized Package Description Format for External C++ Libraries](#) by Luis Caro Campos - CppCon22

Why this scope?

- Easiest **consensus**
- It will deliver the **most value**, the sooner, for users and the community
- Largest contributor to **interoperability**
- **Wide** scope: system packages, closed-source pre-compiled binaries from vendors, to open source built with any build system

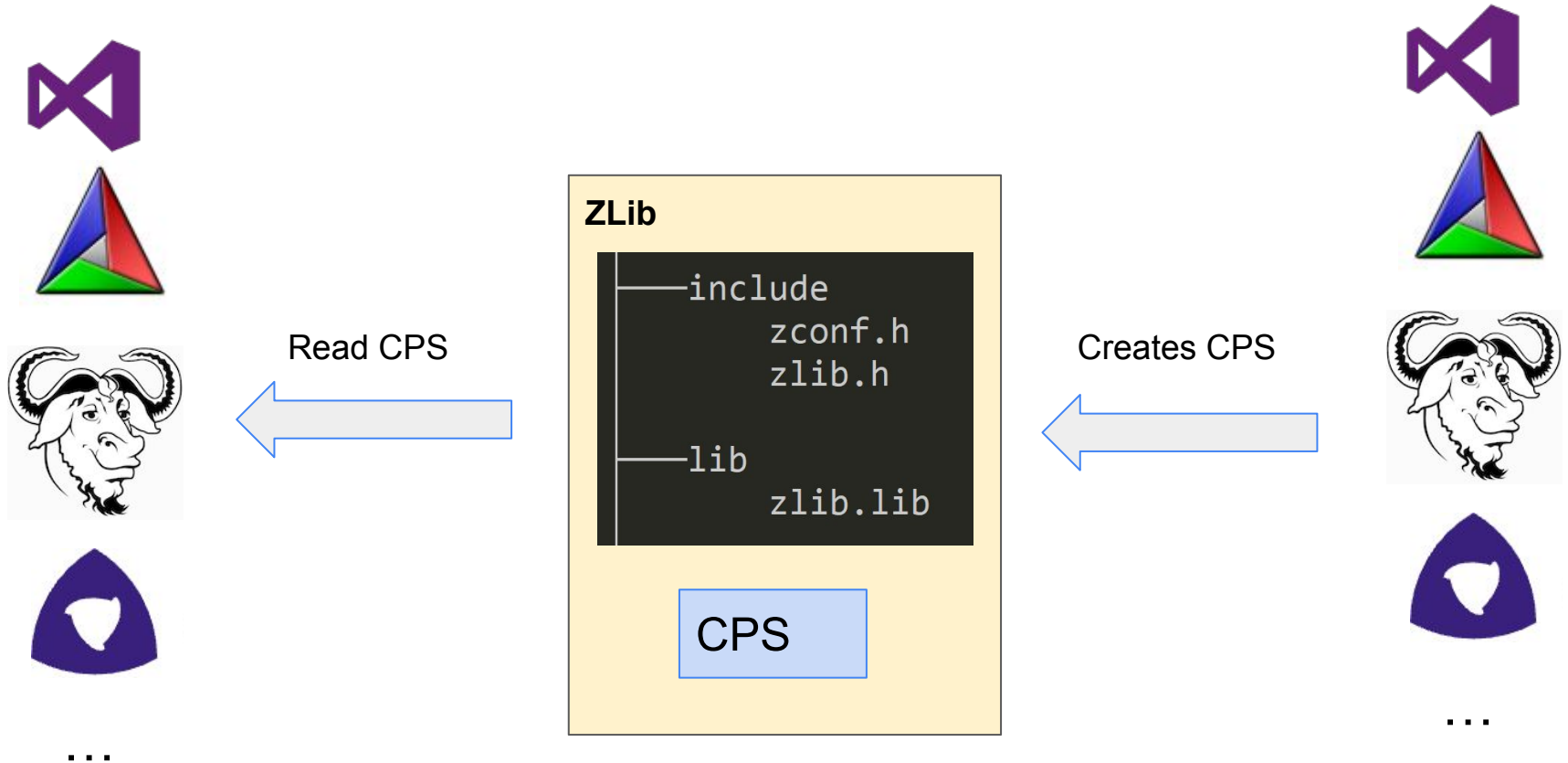


Assumptions



- Compiled **binary**
 - Any build system
 - Closed source
- **Single**-configuration
 - Valid for the current build
- **No version** information
- **No ABI** information

Interoperability



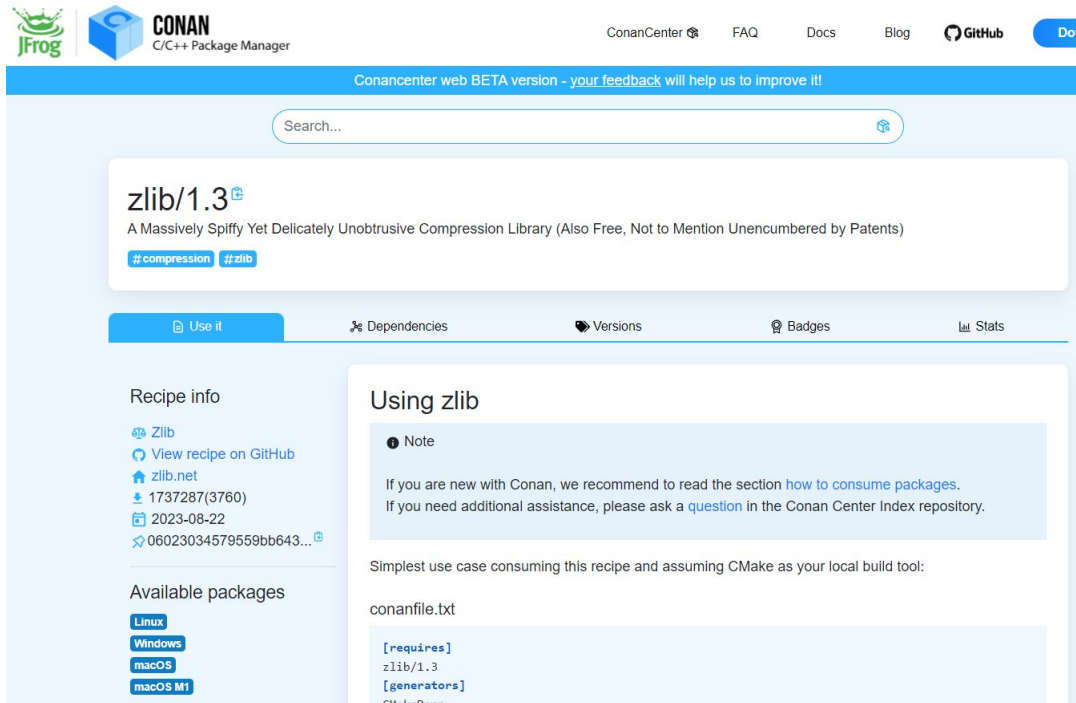
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Implementation experience



- ConanCenter:
 - 1500 recipes x 3 versions x 100 binaries = **500K packages**
 - **3,1 million** packages download/month = **16Tb/month**

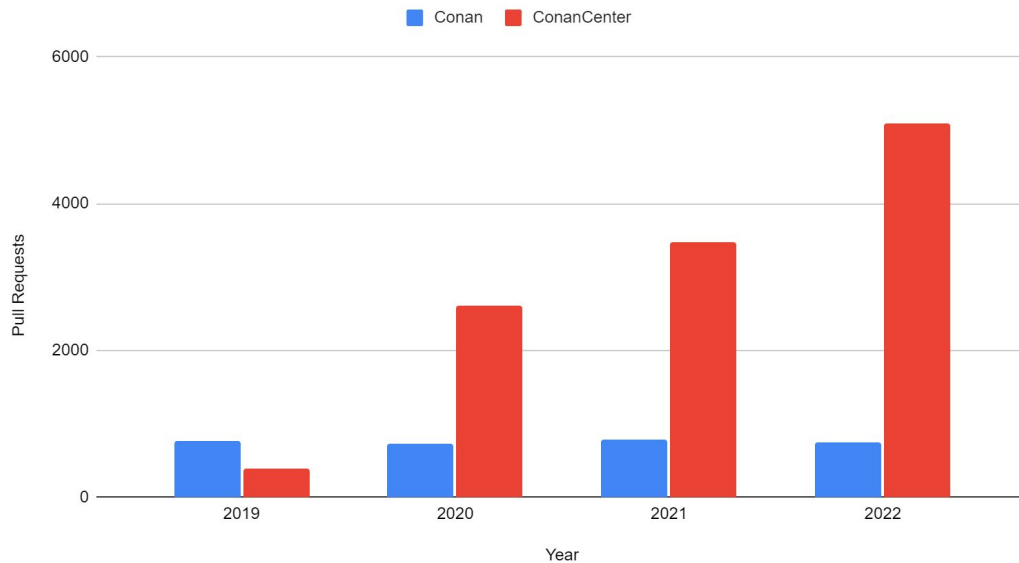


Implementation experience



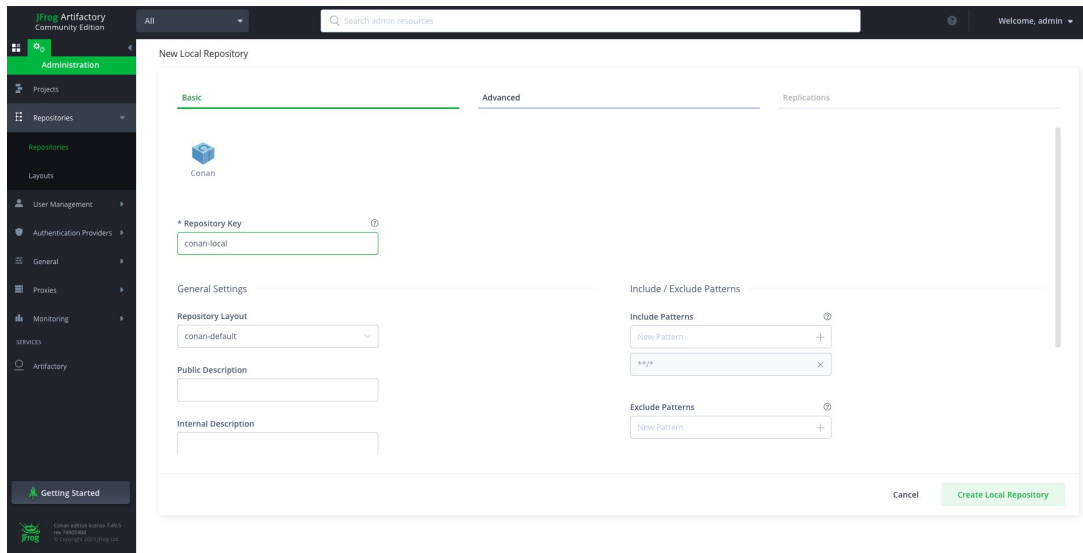
- + 5000 PRs / year

Conan and ConanCenter Pull Requests



Implementation experience

- Private packages
 - **75%** of users don't use ConanCenter
 - Client **750K downloads/month** (PyPI 1% critical project)
- Many thousands of organizations using Artifactory-Conan in production



What brings this implementation experience?

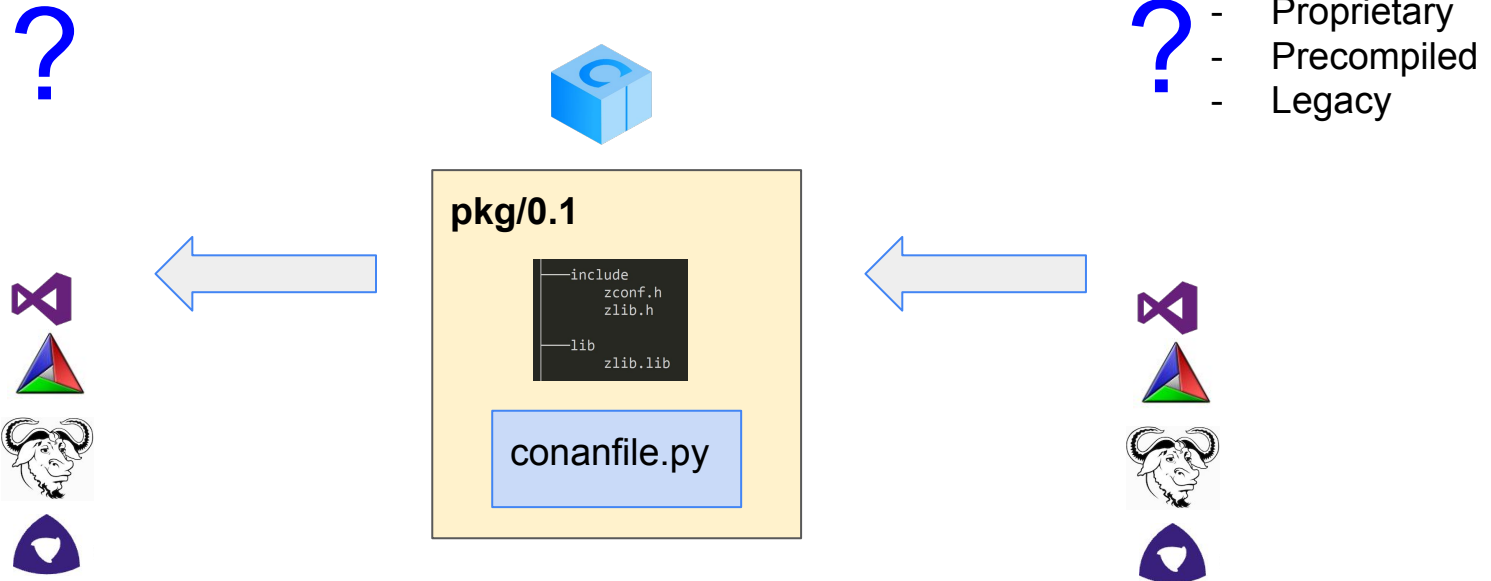
- What is important and what not. Dos and donts.
- Edge and corner cases to cover
- Both open-source and closed-source experience
- Both lessons learned and open questions

Bring me
solutions, not problems

Bring me
problems, not solutions



Every package is consumable by any build system




How Conan models the CPS

```
def package_info(self):
    self.cpp_info.set_property("cmake_find_mode", "both")
    self.cpp_info.set_property("cmake_file_name", "ZLIB")
    self.cpp_info.set_property("cmake_target_name", "ZLIB::ZLIB")
    if self.settings.os == "Windows" and not self._is_mingw:
        libname = "zdll" if self.options.shared else "zlib"
    else:
        libname = "z"
    self.cpp_info.libs = [libname]
```

How Conan models the CPS

```
def package_info(self):
    self.cpp_info.set_property("cmake_find_mode", "both")
    self.cpp_info.set_property("cmake_file_name", "ZLIB")
    self.cpp_info.set_property("cmake_target_name", "ZLIB::ZLIB")
    if self.settings.os == "Windows" and not self._is_mingw:
        libname = "zdll" if self.options.shared else "zlib"
    else:
        libname = "z"
    self.cpp_info.libs = [libname]
    import json
    print(json.dumps(self.cpp_info.serialize(), indent=2))
```



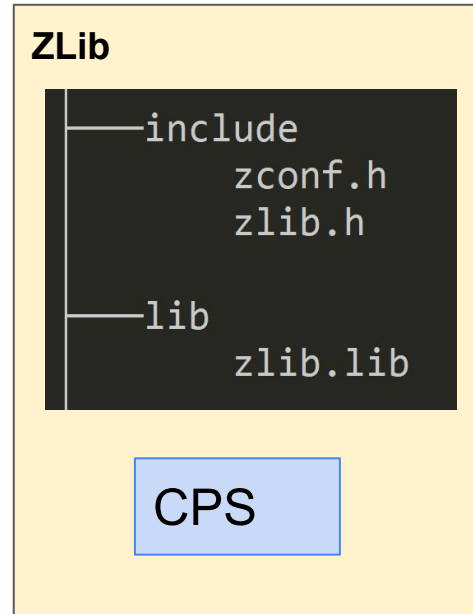
```
{
  ...
  "libs": ["zlib"],
}
```

Can we do better?

```
def package_info(self):
    self.cpp_info.set_property("cmake_find_mode", "both")
    self.cpp_info.set_property("cmake_file_name", "ZLIB")
    self.cpp_info.set_property("cmake_target_name", "ZLIB::ZLIB")
    if self.settings.os == "Windows" and not self._is_mingw:
        libname = "zdll" if self.options.shared else "zlib"
    else:
        libname = "z"
    self.cpp_info.libs = [libname]
```

- Repetition
- For large packages like boost, tedious
- Python

Can we do better



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ZLib

zlib.cps

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|  
| --licenses  
|     LICENSE
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "properties": {  
    "cmake_find_mode": "both",  
    "cmake_file_name": "ZLIB",  
    "cmake_target_name": "ZLIB::ZLIB",  
  }  
}
```

* Just an instance, for Windows MSVC, static library

Why json?

I don't care, let's just use any



ZLib

zlib.cps

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|  
| --licenses  
|     LICENSE
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "properties": {  
    "cmake_find_mode": "both",  
    "cmake_file_name": "ZLIB",  
    "cmake_target_name": "ZLIB::ZLIB",  
  }  
}
```

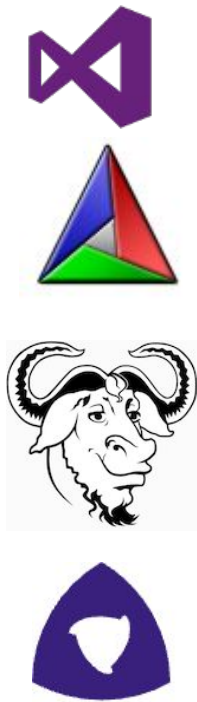
Include Directories

- Maps to `-I<folder>` or to `-Isystem<folder>?`
- Why it is a list of folders?
- Conventions?

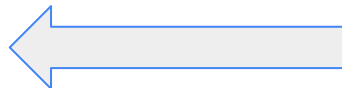
zlib.cps

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "properties": {  
    "cmake_find_mode": "both",  
    "cmake_file_name": "ZLIB",  
    "cmake_target_name": "ZLIB::ZLIB",  
  }  
}
```

Relative paths by default: package “relocatability”



```
zlib_win
|--include
|       zconf.h
|       zlib.h
|
|--lib
|       zlib.lib
|--zlib.cps
```



\$ mv zlib zlib_win

```
zlib
|--include
|       zconf.h
|       zlib.h
|
|--lib
|       zlib.lib
|--zlib.cps
```

Relative paths? “System” packages

- In non-standard (absolute) locations

mypkg.cps

```
{  
  "includedirs": ["/usr/nonstandardpath/headers/mylib/include"],  
  "libdirs": ["/usr/othernonstandardpath/libs/mylib/lib"]  
  "libs": ["mylib2", "mylib1"]  
}
```

Litmus test:

- Can it be the output of a “build/install” process?
- Can it be consumed by build systems?

Libraries directories and libraries

zlib.cps

Maps to -L<librarydir1>

-L<librarydir2>...

Maps to -l<libname1>

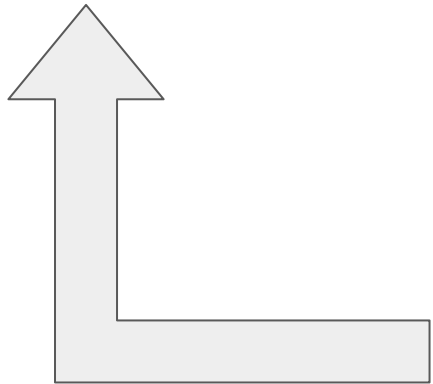
-l<libname2>..

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "properties": {  
    "cmake_find_mode": "both",  
    "cmake_file_name": "ZLIB",  
    "cmake_target_name": "ZLIB::ZLIB",  
  }  
}
```

Properties: playing nice with ecosystem

```
find_package(ZLIB REQUIRED)
# find_package(ZLIB MODULE)
target_link_libraries(... ZLIB::ZLIB)
```

zlib.cps



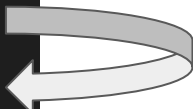
```
{
  "includedirs": ["include"],
  "libdirs": ["lib"],
  "libs": ["zlib"],
  "properties": {
    "cmake_find_mode": "both",
    "cmake_file_name": "ZLIB",
    "cmake_target_name": "ZLIB::ZLIB",
  }
}
```

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OpenSSL

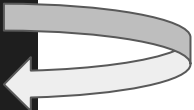
```
| --include/openssl  
|     ssl.h  
|     crypto.h  
|     ...  
|  
| --lib  
|     libssl.lib  
|     libcrypto.lib
```



What “linking openssl” means?

- By default, most users want to use and link with “ssl” library
 - Link “crypto” transitively
- But, some users will want to use only “crypto”
 - What if we pass “-lssl -lcrypto”?
 - Some linkers can be smart and optimize away
 - Some linkers (embedded cross-toolchains) will not
 - Larger than necessary binaries

```
| --include/openssl  
|     ssl.h  
|     crypto.h  
|     ...  
  
| --lib  
|     libssl.lib  
|     libcrypto.lib
```



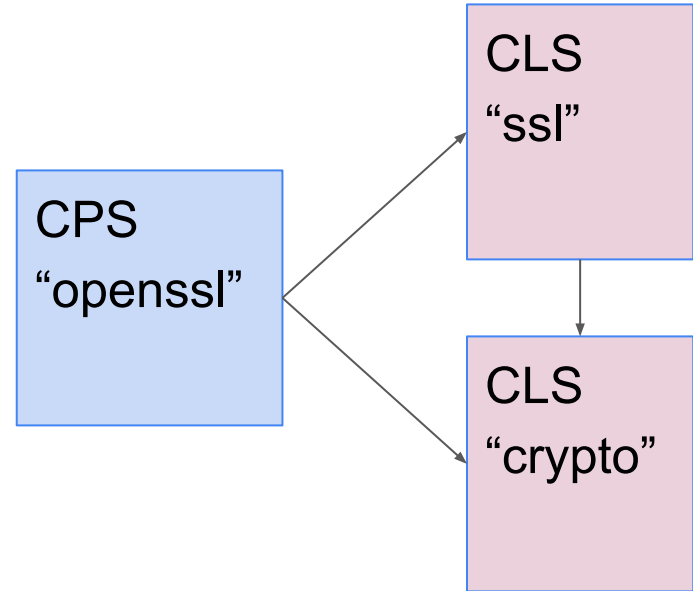
OpenSSL: Components

openssl.cps

```
"root": {  
  "properties": {"cmake_file_name": "OpenSSL"}  
},  
"ssl": {  
  "includedirs": ["include"],  
  "libs": ["libssl"],  
  "requires": ["crypto"],  
},  
"crypto": {  
  "includedirs": ["include"],  
  "system_libs": ["crypt32", "ws2_32", "advapi32",...],  
  "libs": ["libcrypto"],  
  "requires": ["zlib::zlib"],  
}
```

Why not 2 separate CPS files, one for each?

- OpenSSL maintainers will not split the project in 2
 - Can we build once, create 2 independent packages?
- Different packages could evolve differently, versioned differently
 - Openssl maintainers don't want that
- It is a “package” specification, not a “library” specification
- But we can certainly separate,
Common Library Specification (Libman)



OpenSSL: System libraries

openssl.cps

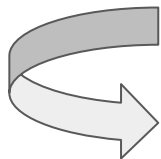
```
"root": {  
  "properties": {"cmake_file_name": "OpenSSL"}  
},  
"ssl": {  
  ...  
  "libs": ["libssl"],  
  "requires": ["crypto"],  
},  
"crypto": {  
  ...  
  "system_libs": ["crypt32", "ws2_32", "advapi32", ...],  
  "libs": ["libcrypto"],  
  "requires": ["zlib::zlib"],  
}
```

OpenSSL: Requirements

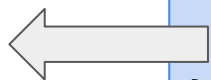
openssl.cps

```
"root": {  
  "properties": {"cmake_file_name": "OpenSSL"}  
},  
"ssl": {  
  ...  
  "libs": ["libssl"],  
  "requires": ["crypto"],  
},  
"crypto": {  
  ...  
  "system_libs": ["crypt32", "ws2_32", "advapi32",...],  
  "libs": ["libcrypto"],  
  "requires": ["zlib::zlib"],  
}
```

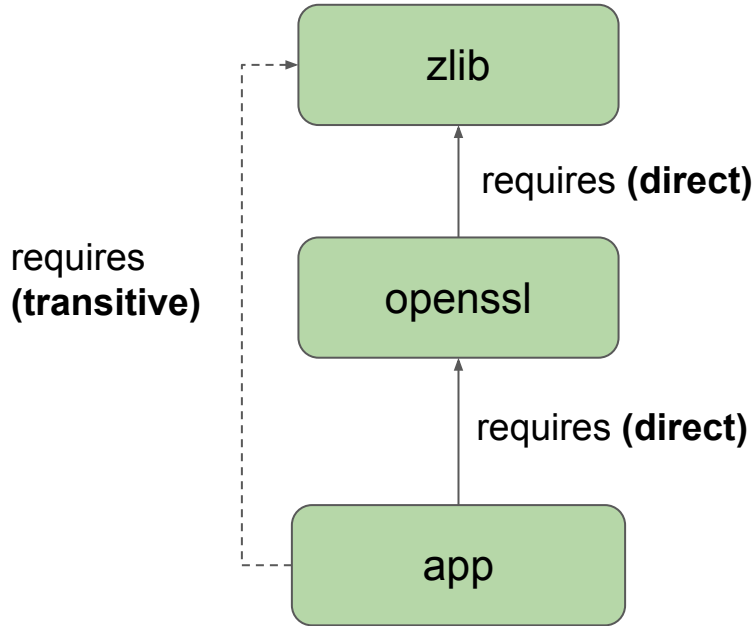
internal



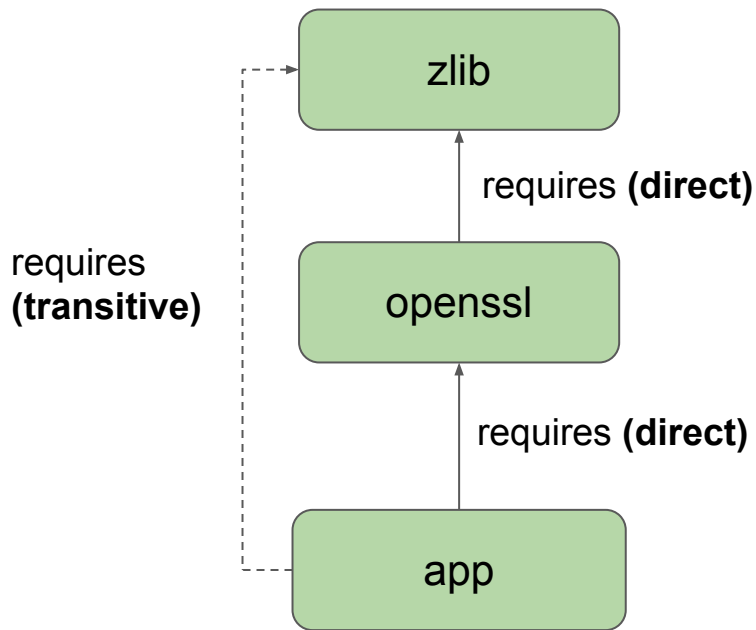
external



Requirements transitivity



Requirements transitivity



app.cpp flags	ssl.h includes zlib.h	ssl.h not includes zlib.h
app links zlib	-I.../zlib/include -L.../zlib/lib -lzlib	-I.../zlib/include -L.../zlib/lib -lzlib
app not links zlib	-I.../zlib/include (-L.../zlib/lib) -lzlib	-I.../zlib/include -L.../zlib/lib -lzlib

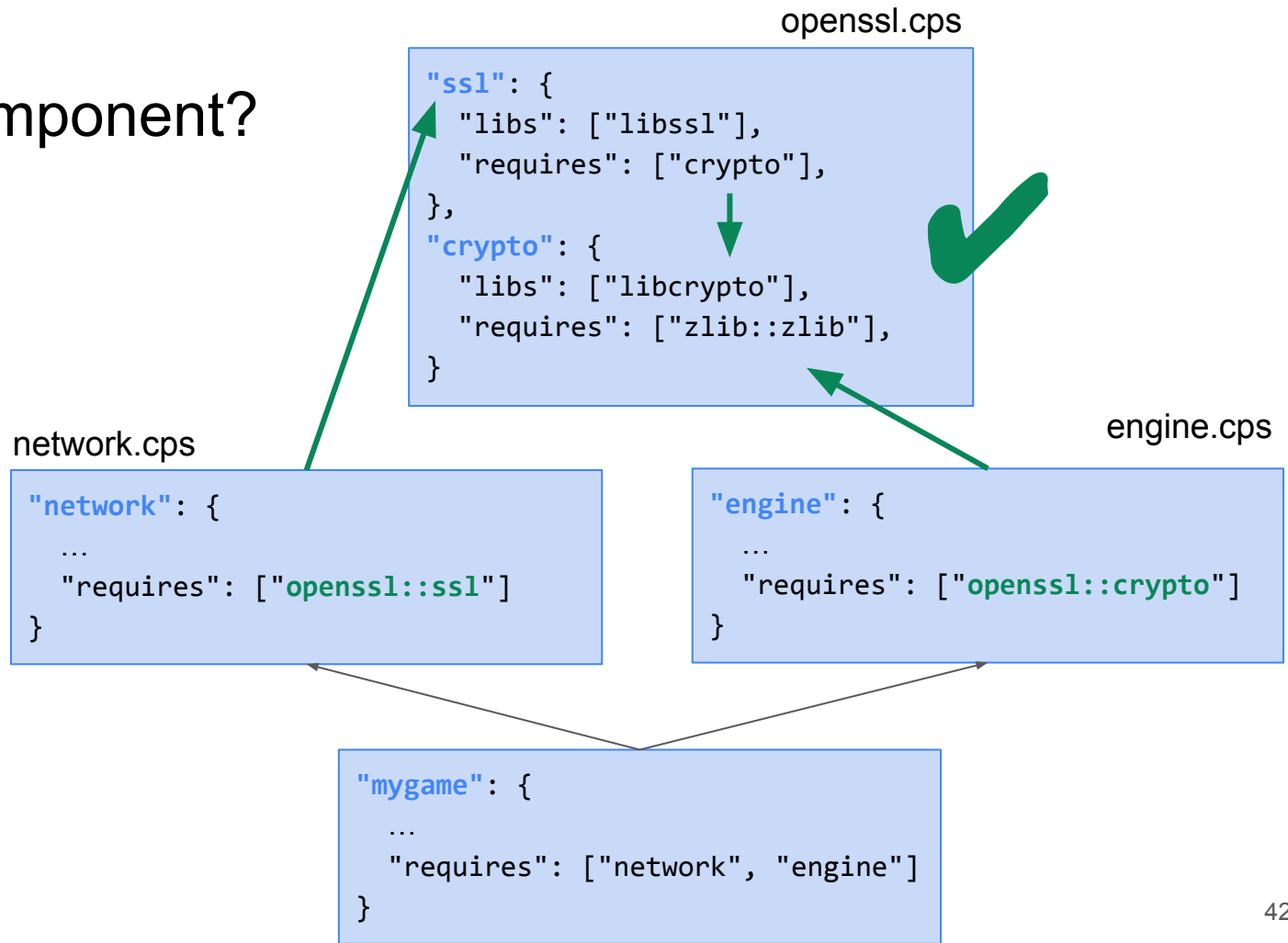
* Not real, just possibilities

OpenSSL: Requirements

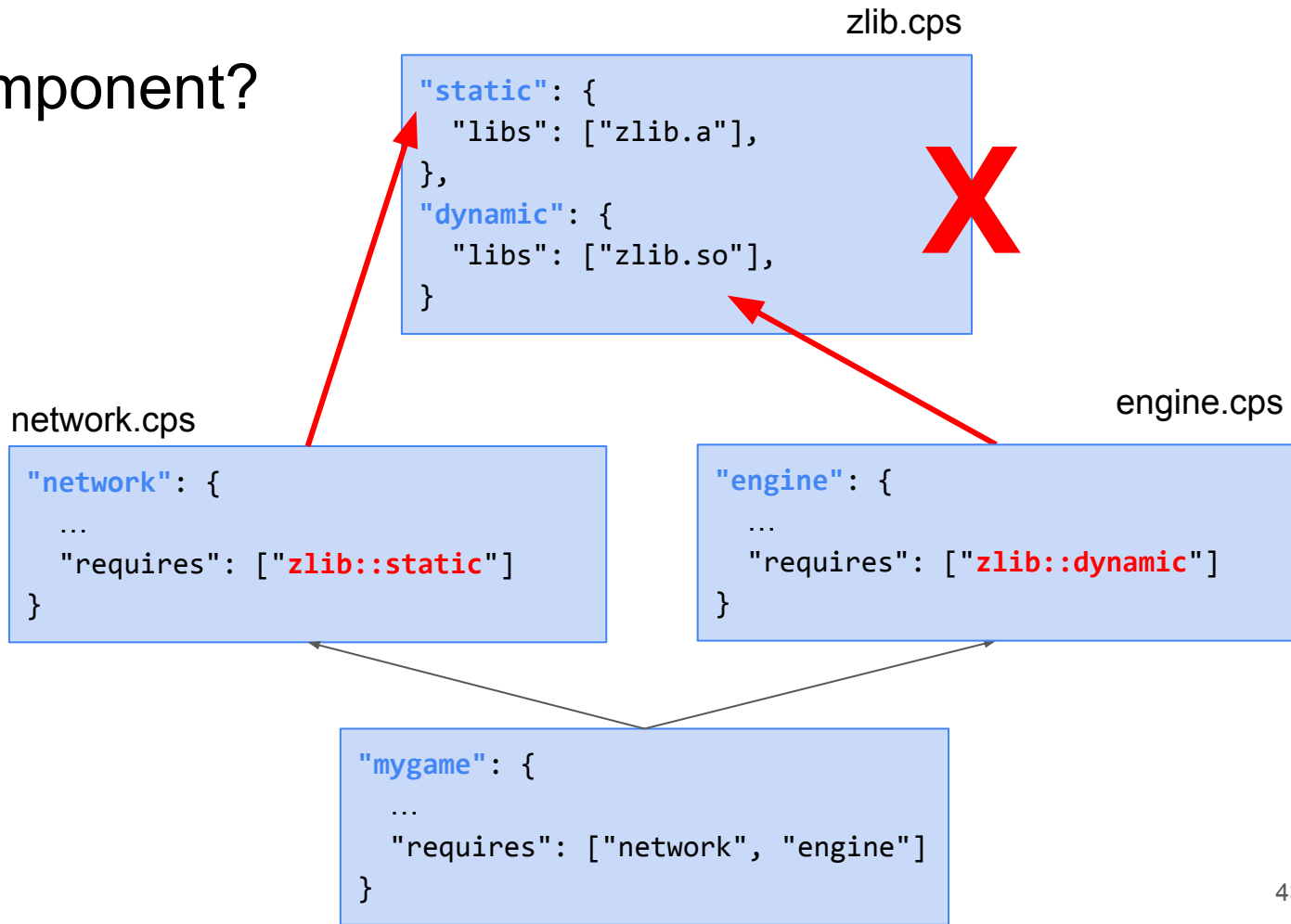
openssl.cps

```
"ssl": {  
  "libs": ["libssl"],  
  "requires": ["crypto"],  
},  
"crypto": {  
  "libs": ["libcrypto"],  
  "requires": {  
    "zlib::zlib": {  
      "headers": True,  
      "libs": False  
    }  
  },  
}
```

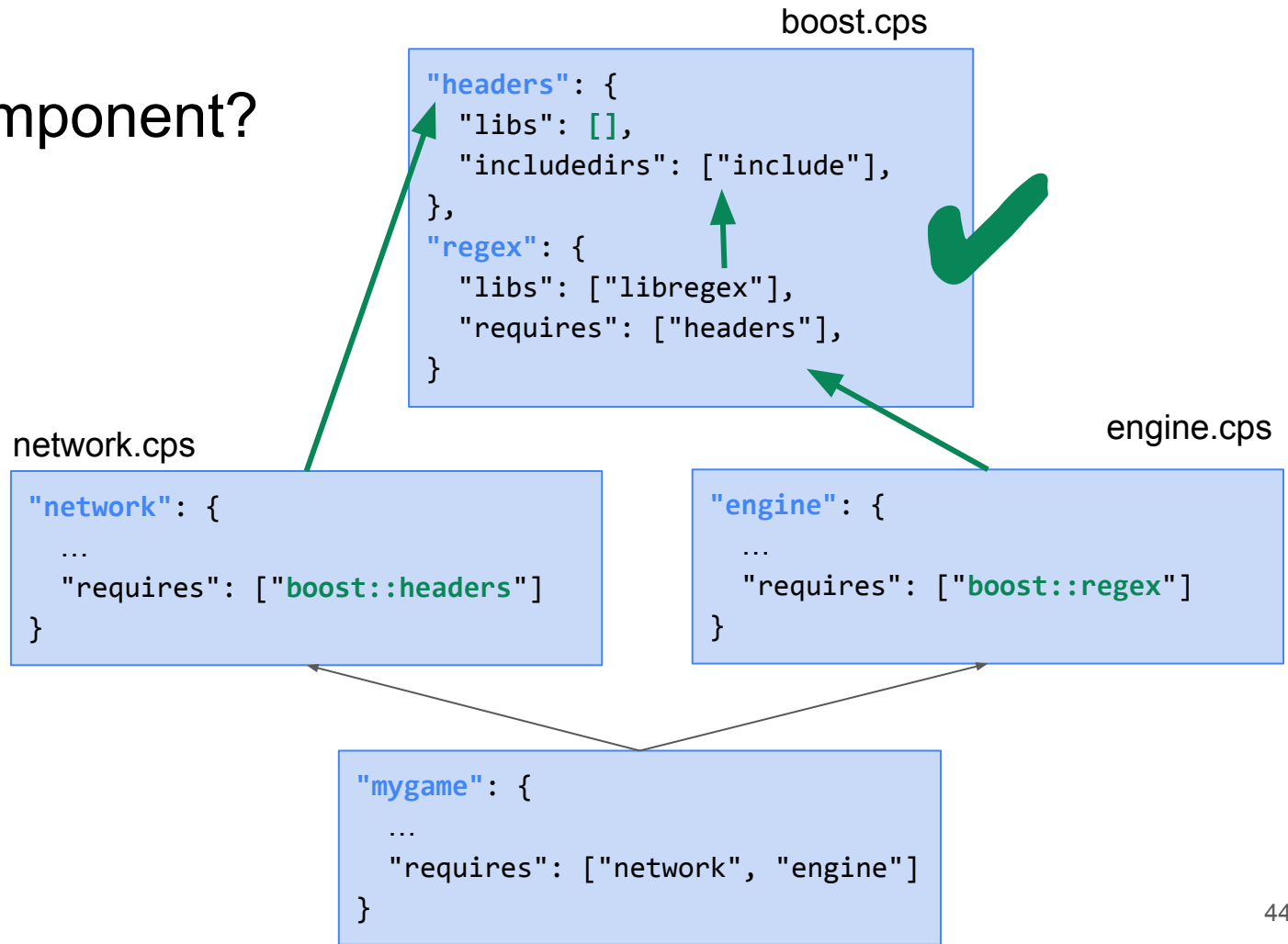
What is a component?



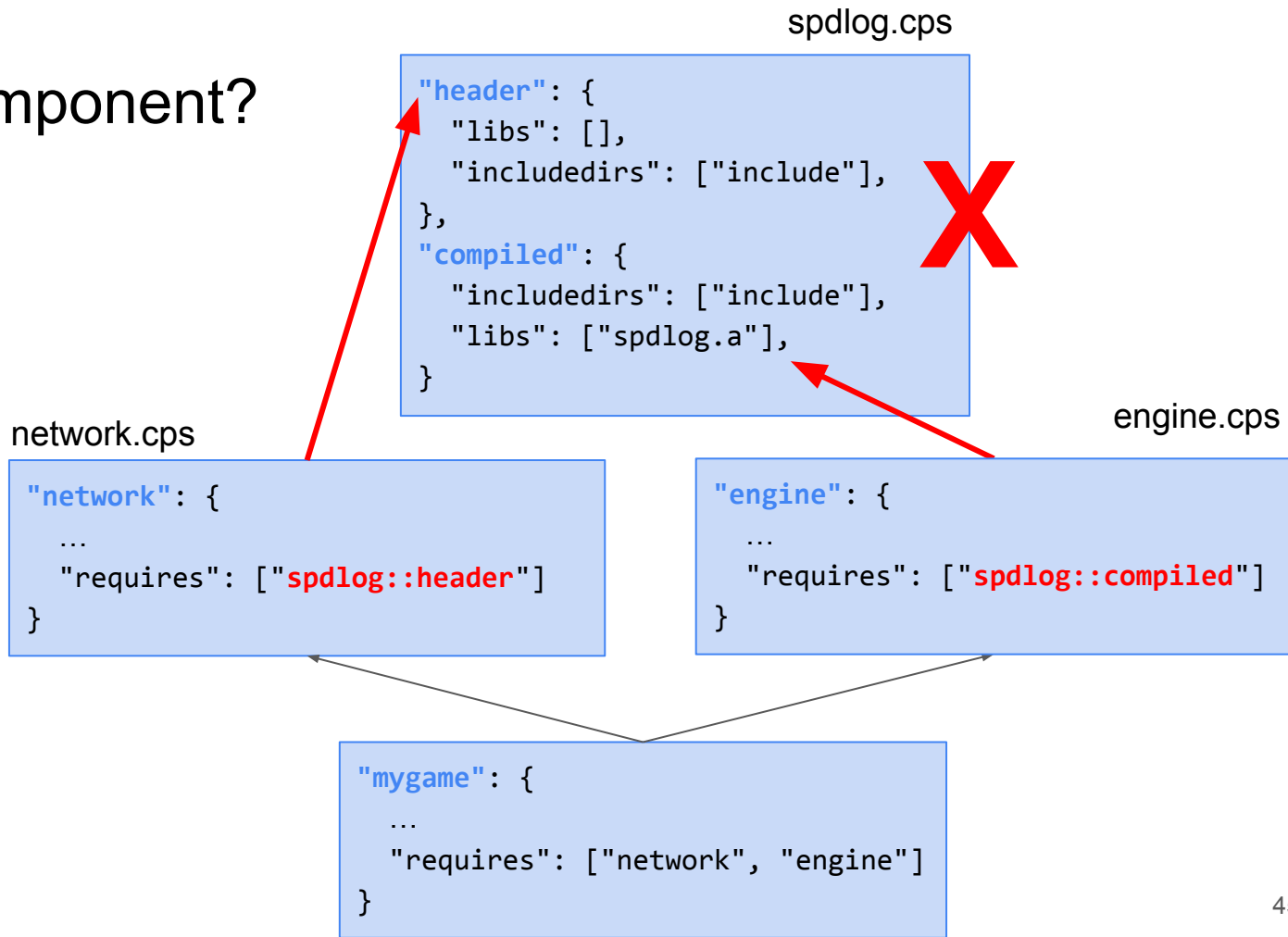
What is a component?



What is a component?





What is a component?



What is a component?

openssl.cps

```
"ssl": {  
  "libs": ["libssl"],  
  "requires": ["crypto"],  
},  
"crypto": {  
  "libs": ["libcrypto"],  
  "requires": ["zlib::zlib"],  
}
```




Components:

- Should be different “parts” of a package, that can be optionally consumed
- Shouldn't be mutually exclusive
- Will typically have inter-dependencies

spdlog.cps

```
"header": {  
  "libs": [],  
  "includedirs": ["include"],  
},  
"compiled": {  
  "includedirs": ["include"],  
  "libs": ["spdlog.a"],  
}
```



Components:

- Shouldn't be different binary “variants” of the same code/functionality
- Aren't an optimization over building or distribution

What is not a component?

spdlog.cps

```
"header": {  
  "libs": [],  
  "includedirs": ["include"],  
},  
"compiled": {  
  "includedirs": ["include"],  
  "libs": ["spdlog.a"],  
}
```



spdlog.cps

```
"spdlog": {  
  "libs": [],  
  "includedirs": ["include"],  
},
```

```
|--include  
|   spdlog.h  
|   spdlog_impl.h  
|--lib (empty)  
|--spdlog.cps
```

spdlog.cps

```
"spdlog": {  
  "includedirs": ["include"],  
  "libs": ["spdlog.a"],  
}
```



```
|--include  
|   spdlog.h  
|--lib  
|   spdlog.a  
|--spdlog.cps
```

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Full CPS

```
"includedirs": ["include"],
"srcdirs": null,
"libdirs": ["lib"],
"resdirs": null,
"bindirs": [ "bin"],
"builddirs": null,
"frameworkdirs": null,
"system_libs": null,
"frameworks": null,
"libs": ["zlib"],
"defines": null,
"cflags": null,
"cxxflags": null,
"sharedlinkflags": null,
"exelinkflags": null,
"objects": null,
"sysroot": null,
"requires": null,
"properties": {
  "cmake_find_mode": "both",
  "cmake_file_name": "ZLIB",
  "cmake_target_name": "ZLIB::ZLIB",
  "pkg_config_name": "zlib"
}
```

Defines

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|  
| --licenses  
|     LICENSE
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "defines": ["ZLIB_STATIC"]  
}
```

zlib.h

```
#ifdef ZLIB_STATIC  
void deflateInit(...  
#else  
__declspec(dllexport) void deflateInit(...  
#endif
```

Source packages

- No build system! (aka submodules)
- Build system agnostic
- Usage up to the consumer
- Abuse as source management to be avoided
- ODRs violations not checkeable by tooling

```
"srcdirs": ["mysrc"], # or  
"sources": ["file.h", "file.cpp", ...],
```

Objects

- No build system! (aka submodules)
- Build system agnostic
- Usage up to the consumer
- ODRs violations not checkeable by tooling

```
"objdirs": ["mysrc"], # or  
"objects": ["file.obj", ...],
```

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 - Directories and libraries: ZLib
 - Components and requirements: Openssl
 - Full CPS
- **Advanced use cases**
 - **Full library definition**
 - **Runtime**
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 - Editable packages
 - Protobuf modules and cross-building
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- Speeding adoption hints
- Conclusions and next steps

Library definitions

- Paths and extensions?
- Types:
 - Header
 - Static
 - Shared
 - Dynamic

zlib.cps

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "bindirs": ["bin"],  
  "libs": {  
    "zlib": {  
      "type": "shared",  
      "importlib": "zlib.lib",  
      "sharedlib": "zlib.dll",  
    },  
  },  
}
```

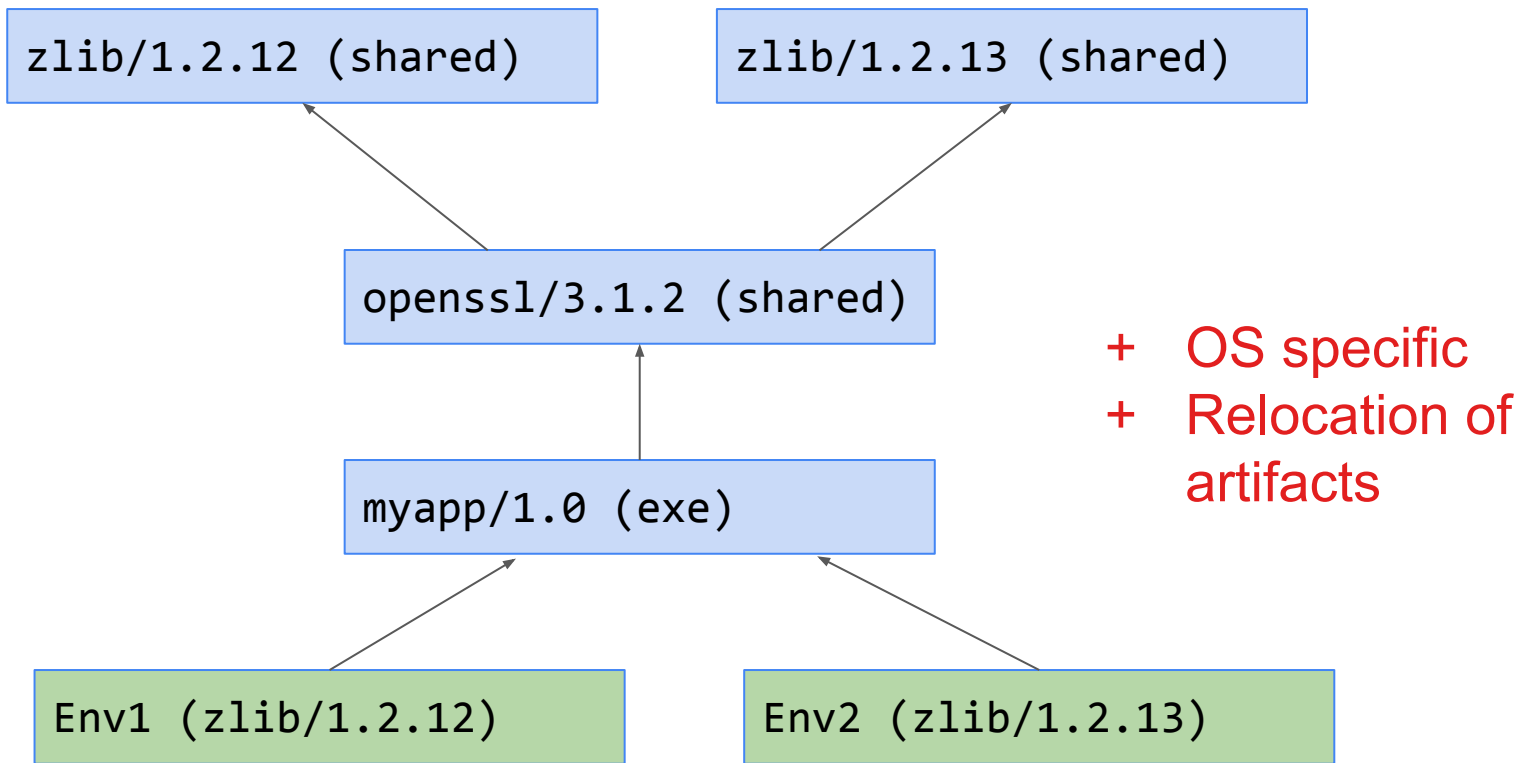
Runtime

3 mechanisms:

- RPaths
- Copy .dll to exe location
- Env-vars (PATH, LD_LIBRARY_PATH, ...)

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "bindirs": ["bin"],  
  "libs": {  
    "myplugin": {  
      "type": "plugin",  
      "sharedlib": "plugin.dll",  
    },  
  },  
}
```

Runtime: why RPATHs are not great for dev-dependencies



Runtime: Information is necessary

3 mechanisms:

- RPaths
- Copy .dll to exe location
- Env-vars (PATH, LD_LIBRARY_PATH, ...)

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "bindirs": ["bin"],  
  "libs": {  
    "myplugin": {  
      "type": "plugin",  
      "sharedlib": "plugin.dll",  
    },  
  },  
}
```

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Conditional CPS?

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|     zlib_d.lib
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": {  
    "Release": ["zlib"],  
    "Debug": ["zlib_d"]  
  }  
}
```

Conditional CPS? Better avoid it

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|     zlib_d.lib
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"]  
}
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib_d"]  
}
```

Conditional CPS: Better avoid it, also binary

```
| --include  
|     zlib.h  
| --lib  
|     zlib.lib
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"]  
}
```

```
| --include  
|     zlib.h  
| --lib  
|     zlib_d.lib
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib_d"]  
}
```

Conditional CPS?

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.lib  
|     zlib_safe.lib  
|  
| --licenses  
|     LICENSE
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": {  
    "fast_unsafe": ["zlib"],  
    "slow_safe": ["zlib_safe"]  
  }  
}
```

Conditional CPS?

```
| --include  
|     zconf.h  
|     zlib.h  
|  
| --lib  
|     zlib.a(OSX fat)  
|  
| --licenses  
|     LICENSE
```

```
{  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"],  
  "defines": {  
    "x86_64": ["-DMY_Z_ARCH_X86"],  
    "armv8": ["-DMY_Z_ARCH_ARM"]  
  }  
}
```

Conditional CPS for a header-only?

```
| --include  
|   my_algos.h  
|
```

```
{  
  "includedirs": ["include"],  
  "defines": {  
    "fast": ["-DMY_FAST_VERSION"],  
    "slow": ["-DMY_SLOW_VERSION"]  
  }  
}
```


Conditional CPS

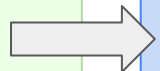
- The amount of conditionals in Conan `package_info()` is very large:
 - Toolchains, NDKs
 - The space is very continuous and large (Android NDK api level)
 - Not easy to generate a ton of **android_ndk_apiXX_archYY.cps**
- Avoid as much as possible
 - Regular libraries

Focus on 1 package = 1 binary configuration = 1 cps

“System” packages

```
def system_requirements(self):  
    yum = package_manager.Yum(self)  
    yum.install(["mesa-libGL-devel"])  
    apt = package_manager.Apt(self)  
    apt.install_substitutes(["libgl-dev",  
                             "libgl1-mesa-dev"])  
    ...
```

```
def package_info(self):  
    if self.settings.os == "Macos":  
        self.cpp_info.frameworks.append("OpenGL")  
    elif self.settings.os == "Windows":  
        self.cpp_info.system_libs = ["opengl32"]  
    ...
```



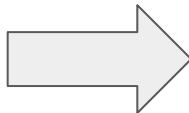
```
{  
  "system_libs": ["opengl32"],  
}
```

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“Editable” packages

```
| --src/  
|     zconf.h  
|     zlib.h  
  
| --Release/x64  
|     zlib.lib  
|     zlib.obj  
|     ... (build)
```



packaging

```
| --include  
|     zconf.h  
|     zlib.h  
  
| --lib  
|     zlib.lib
```

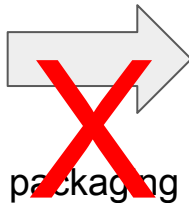
zlib.cps

```
| -- openssl
```

```
"includedirs": ["include"],  
"libdirs": ["lib"],  
"libs": ["zlib"]
```

“Editable” packages

```
| --src/  
|     zconf.h  
|     zlib.h  
  
| --Release/x64  
|     zlib.lib  
|     zlib.obj  
|     ... (build)
```



```
| --include  
|     zconf.h  
|     zlib.h  
  
| --lib  
|     zlib.lib
```

```
| -- openssl
```

zlib.cps

```
"includedirs": ["src", "include"],  
"libdirs": ["Release/x64"],  
"libs": ["zlib"]
```

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About CMake modules: Protobuf

CMakeLists.txt

```
find_package(protobuf CONFIG REQUIRED)

add_executable(${PROJECT_NAME} test_package.cpp
               addressbook.proto)

target_link_libraries(${PROJECT_NAME} PRIVATE
                     protobuf::libprotobuf)

protobuf_generate_cpp(PROTO_SRCS PROTO_HDRS TARGET
                     ${PROJECT_NAME})

protobuf_generate(LANGUAGE cpp TARGET ${PROJECT_NAME}
                 PROTOS addressbook.proto)
```

About CMake modules: Protobuf

CMakeLists.txt

```
find_package(protobuf CONFIG REQUIRED)

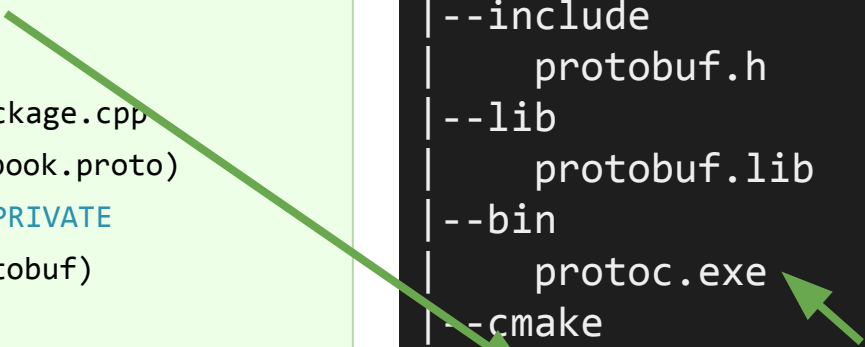
add_executable(${PROJECT_NAME} test_package.cpp
               addressbook.proto)

target_link_libraries(${PROJECT_NAME} PRIVATE
                     protobuf::libprotobuf)

protobuf_generate_cpp(PROTO_SRCS PROTO_HDRS TARGET
                     ${PROJECT_NAME})

protobuf_generate(LANGUAGE cpp TARGET ${PROJECT_NAME}
                 PROTOS addressbook.proto)
```

```
| --include
|     protobuf.h
| --lib
|     protobuf.lib
| --bin
|     protoc.exe
| --cmake
|     protobuf-config.cmake
```



```
function(protobuf_generate_cpp)
    find_program(protoc ...)
    execute_process(protoc ...)
function(protobuf_generate)
    ...
```


About CMake modules: Protobuf

```
"includedirs": ["include"],  
"libdirs": ["lib"],  
"libs": ["protobuf"],  
"properties": {  
    "cmake_modules":  
        ["cmake/protoutils.cmake"],  
}
```

```
| --include  
|     protobuf.h  
| --lib  
|     protobuf.lib  
| --bin  
|     protoc.exe  
| --cmake  
|     protoutils.cmake
```

Cross-building with build & host contexts

Build context (Windows PC)

protobuf

```
--include  
|   protobuf.h  
--lib  
|   protobuf.lib  
--bin  
|   protoc.exe  
--cmake  
|   protobuf-config.cmake
```

Windows, x86_64
msvc 16

Host context (embedded Linux)

protobuf

```
--include  
|   protobuf.h  
--lib  
|   protobuf.lib  
--bin  
|   protoc.exe  
--cmake  
|   protobuf-config.cmake
```

Linux, armv8
gcc 5

myapp



Cross-building with build & host contexts

Build context (Windows PC)

protobuf

```
--include  
|   protobuf.h  
--lib  
|   protobuf.lib  
--bin  
|   protoc.exe  
--cmake  
|   protobuf-config.cmake  
--protobuf.cps
```

Windows, x86_64
msvc 16

Host context (embedded Linux)

protobuf

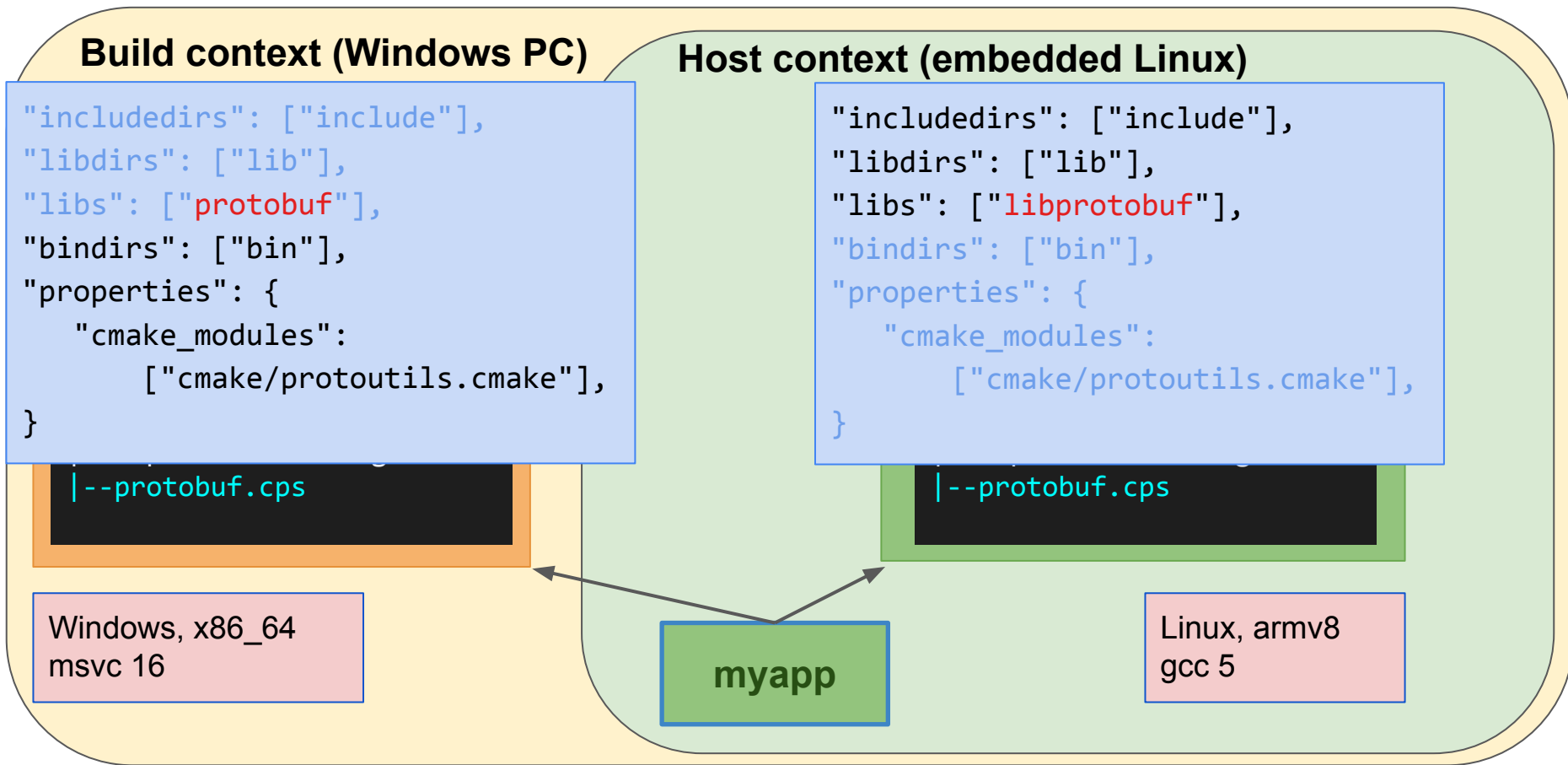
```
--include  
|   protobuf.h  
--lib  
|   protobuf.lib  
--bin  
|   protoc.exe  
--cmake  
|   protobuf-config.cmake  
--protobuf.cps
```

Linux, armv8
gcc 5

myapp



Cross-building with build & host contexts



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CPS files mapping

<https://cps-org.github.io/cps/searching.html>

Tools shall locate a package by searching for a file `<name>.cps` in the following paths:

- `<prefix>/cps/` (Windows)
- `<prefix>/cps/ <name-like> /` (Windows)
- `<prefix>/ <name>.framework/Versions/ * /Resources/CPS/` (macOS)
- `<prefix>/ <name>.framework/Resources/CPS/` (macOS)
- `<prefix>/ <name>.app/Contents/Resources/CPS/` (macOS)
- `<prefix>/ <libdir>/cps/ <name-like> /`
- `<prefix>/ <libdir>/cps/`
- `<prefix>/share/cps/ <name-like> /`
- `<prefix>/share/cps/`

CPS file location mapping

Consumer project

CMakeLists.txt

```
find_package(OpenSSL CONFIG REQUIRED)
find_package(ZLIB CONFIG REQUIRED)
```

Built packages

```
| --zlib
|   include
|     zlib.h
|   ...
|   zlib.cps
| --openssl
|   include
|     ssl.h
|   ...
|   openssl.cps
```

zlib.cps

```
"includedirs": ["include"],
"libdirs": ["lib"],
"libs": ["zlib"]
```

openssl.cps

```
"crypto": {
  "libs": ["libcrypto"],
  "requires": [zlib::zlib],
}
```

CPS file location mapping

Consumer project

CMakeLists.txt

mapping.cpsm

```
find_package(OpenSSL CONFIG REQUIRED)
find_package(ZLIB CONFIG REQUIRED)
```

```
"zlib": "/path/zlib/zlib.cps",
"openssl": "/path/openssl/openssl.cps"
```

Built packages

```
| --zlib
|   include
|     zlib.h
|   ...
|   zlib.cps
| --openssl
|   include
|     ssl.h
|   ...
|   openssl.cps
```

zlib.cps

```
"includedirs": ["include"],
"libdirs": ["lib"],
"libs": ["zlib"]
```

openssl.cps

```
"crypto": {
  "libs": ["libcrypto"],
  "requires": [zlib::zlib],
}
```


CPS file location mapping

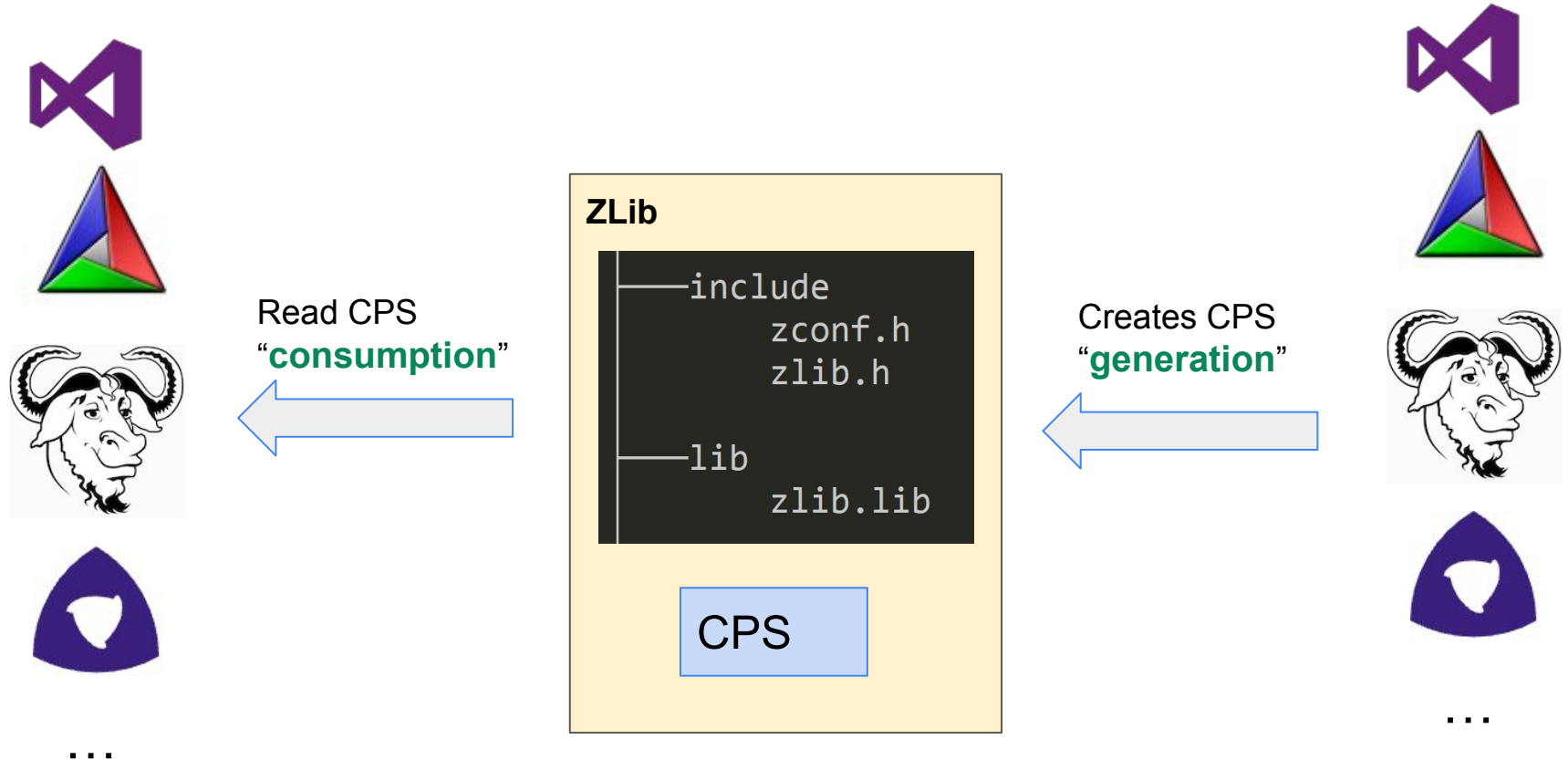
mapping.cpsm

```
"host": {
  "zlib": {
    "ReleaseDLL": "/path/zlib/linux/release/shared/zlib.cps",
    "DebugStatic": "/path/zlib/linux/debug/static/zlib.cps"
    ...
  },
  "openssl": {
    "*": "/system/openssl.cps",
  },
  "protobuf": { # for libprotobuf for linux
    "ReleaseDLL": "/path/protobuf/linux/release/shared/protobuf.cps",
  },
},
"build": {
  "protobuf": { # for protoc for windows
    "*": "/path/protobuf/windows/release/static/protobuf.cps",
  },
}
```

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Implementation tips: mapping from/to build systems



How to help (make, bazel, ...) projects to generate CPS?

```
def package_info(self):  
    if self.settings.os == "Windows"  
        and not self._is_mingw:  
        lib = "zdll" if self.options.shared else "zlib"  
    else:  
        lib = "z"  
    self.cpp_info.libs = [lib]
```

- Declarative
 - Batch/Shell scripts
 - Other scripts
- Introspection
 - Tool
- Custom solutions per-project
 - Templates

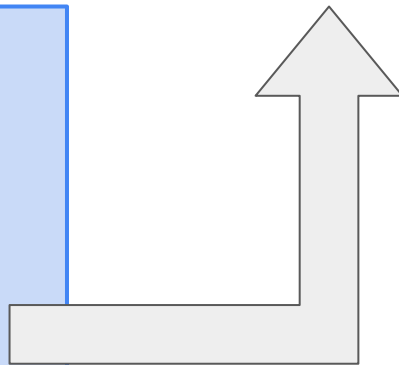
Consumption: Mapping to build systems

zlib.cps

```
"includedirs": ["include"],  
"libdirs": ["lib"],  
"libs": ["zlib"],  
"properties": {  
  "cmake_find_mode": "both",  
  "cmake_file_name": "ZLIB",  
  "cmake_target_name": "ZLIB::ZLIB",  
}
```

CMakeLists.txt (user)

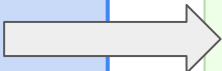
```
find_package(ZLIB REQUIRED)  
# find_package(ZLIB MODULE)  
target_link_libraries(... ZLIB::ZLIB)
```



Mapping to build systems

zlib.cps

```
"includedirs": ["include"],  
"libdirs": ["lib"],  
"libs": ["zlib"],  
"properties": {  
  "cmake_find_mode": "both",  
  "cmake_file_name": "ZLIB",  
  "cmake_target_name": "ZLIB::ZLIB",  
}
```



zlib-config.cmake

```
set(zlib_PKG_FOLDER "<full-path>")  
  
set(zlib_INCLUDE_DIRS  
    "${zlib_PKG_FOLDER}/include")  
set(zlib_LIB_DIRS "${zlib_PKG_FOLDER}/lib")  
set(zlib_LIBS zlib)  
  
set_property(TARGET ZLIB::ZLIB  
    PROPERTY  
    INTERFACE_LINK_LIBRARIES  
    ${zlib_LIBRARIES_TARGETS}>  
    APPEND)  
  
set_property(TARGET ZLIB::ZLIB  
    PROPERTY  
    INTERFACE_INCLUDE_DIRECTORIES  
    ${zlib_INCLUDE_DIRS}> APPEND)
```

Mapping to existing build systems

zlib.cps

```
"includedirs": ["include"],  
"libdirs": ["lib"],  
"libs": ["zlib"]
```

zlib-cmake-map.cps

```
"zlib": {  
  "cmake_find_mode": "both",  
  "cmake_file_name": "ZLIB",  
  "cmake_target_name": "ZLIB::ZLIB",  
}
```



zlib-config.cmake

```
set(zlib_PKG_FOLDER "<full-path>")  
  
set(zlib_INCLUDE_DIRS  
    "${zlib_PKG_FOLDER}/include")  
set(zlib_LIB_DIRS "${zlib_PKG_FOLDER}/lib")  
set(zlib_LIBS zlib)  
  
set_property(TARGET ZLIB::ZLIB  
    PROPERTY  
    INTERFACE_LINK_LIBRARIES  
    ${zlib_LIBRARIES_TARGETS}>  
    APPEND)  
set_property(TARGET ZLIB::ZLIB  
    PROPERTY  
    INTERFACE_INCLUDE_DIRECTORIES  
    ${zlib_INCLUDE_DIRS}> APPEND)
```

Mapping to build systems

zlibs.props

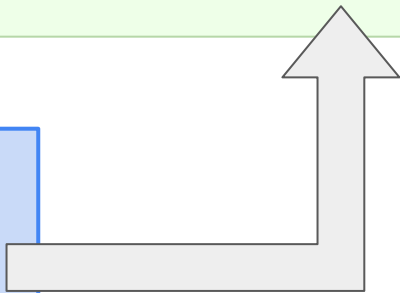


```
<ConanzlibRootFolder>path</ConanzlibRootFolder>

<ClCompile>
  <AdditionalIncludeDirectories>$(ConanzlibRootFolder)/include
</AdditionalIncludeDirectories>
</ClCompile>
<Link>
  <AdditionalLibraryDirectories>$(ConanzlibRootFolder)/lib
</AdditionalLibraryDirectories>
  <AdditionalDependencies>zlib.lib</AdditionalDependencies>
</Link>
```

zlib.cps

```
"includedirs": ["include"],
"libdirs": ["lib"],
"libs": ["zlib"]
```



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What about modules?

**C++20 Modules:
The Packaging and Binary
Redistribution Story**

Monday, Oct 2, 2023 | 16:45 - 17:45

 **CONAN**
C/C++ Package Manager

 **JFrog**





Luis Caro Campos
SW Tech Lead, JFrog

What about ABI, metadata information?



...

Read CPS



ZLib

```
build: {  
  "includedirs": ["include"],  
  "libdirs": ["lib"],  
  "libs": ["zlib"]  
},  
abi: {  
  dynamic_runtime: True,  
  kernel_version: 4.1,  
  glibc: 3.2  
},  
metadata: {  
  compiled: 2023-10-01  
  checksum: ...  
}
```

Creates CPS



...

Proposal: Lean MVP



Next steps

- Resume work on this
- Collaborate with CPS, Brett, Bill to mature proposal for ISO C++ (tooling)
- Continue evolving implementation in Conan 2.0
 - Move from Python `package_info()` => cps (poc)

Thank you! Questions?



CONAN 2.0
C/C++ Package Manager