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Application of C++ in Computational Cancer Modeling

RUIBO ZHANG



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24



Application of C++ in Cancer Modeling

- The speaker (Ruibo)
- University of Washington, department of applied mathematics
- Cancer Modeling Group: Evolution of cancer initiation
- Group leader: Personal programming advisor:



Ivana Bozic
Associate Professor
UW AMATH

Fred Hutchinson Cancer Research center



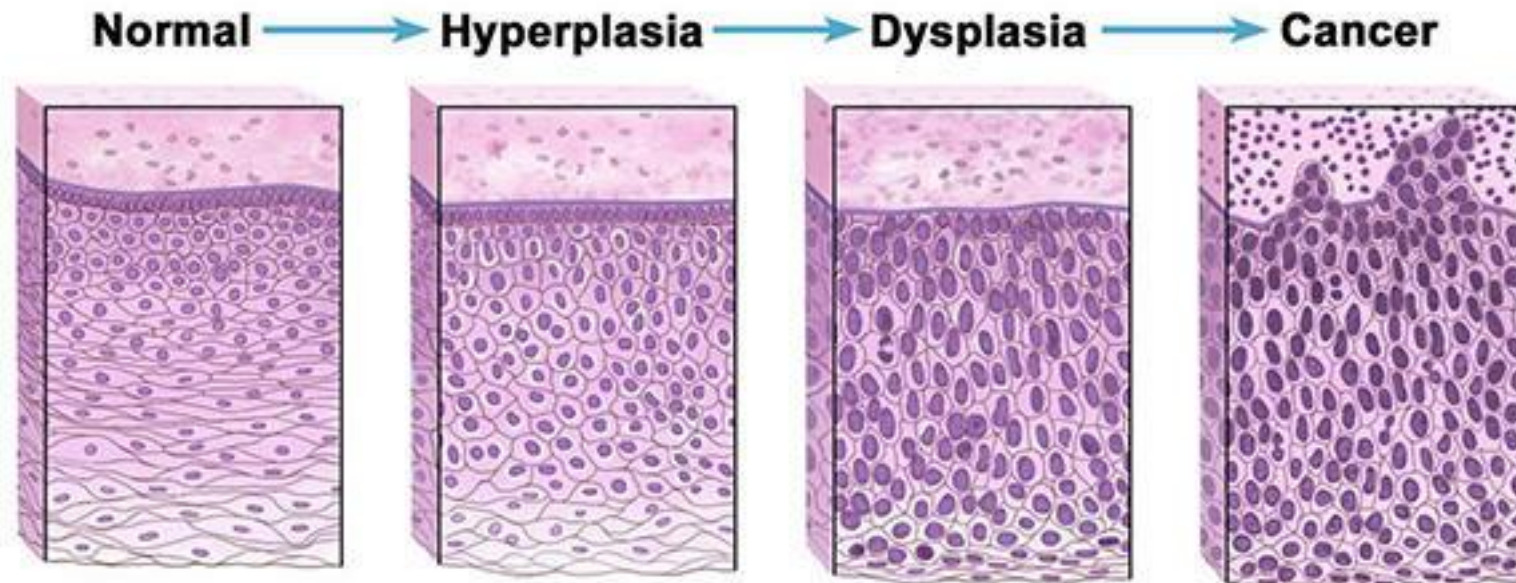
Daniel Hanson
CppCon, Student Program Chair
SG20

Outline

- Main Topic: use C++ to simulate the process of cancer initiation
- The mathematical model and simulation study
 - Generate a single tumor (A single step of evolution)
 - Generate multiple tumors (Tasked Based Concurrency)
 - Obtain statistical properties of the tumors (Parallel STL algorithms)
- Eigen (Array Class)
 - Eigen is a C++ template library for linear algebra: matrices, vectors, numerical solvers, and related algorithms.
- Modern C++:
 - <random>: Pseudo-random number generation
 - <future>: Task-Based Concurrency
 - <numeric>: Parallel versions of certain STL algorithms

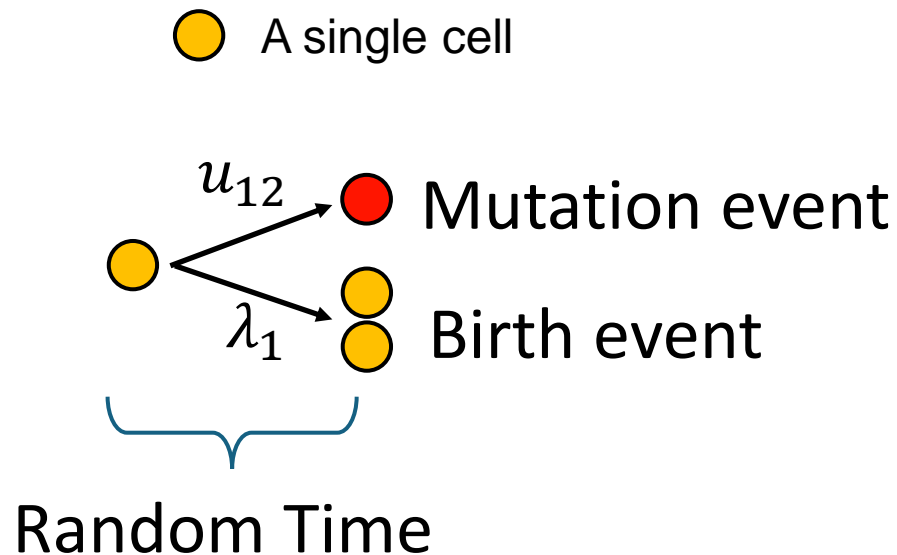
Cancer and early detection

- Cancer is a disease characterized by the uncontrolled division of abnormal cells caused by changes in genes (DNA).
- When cancer is found early, it may be easier to treat or cure
- Mathematical models help understand the evolution quantitatively. (e.g. predict the window of opportunity for screening)



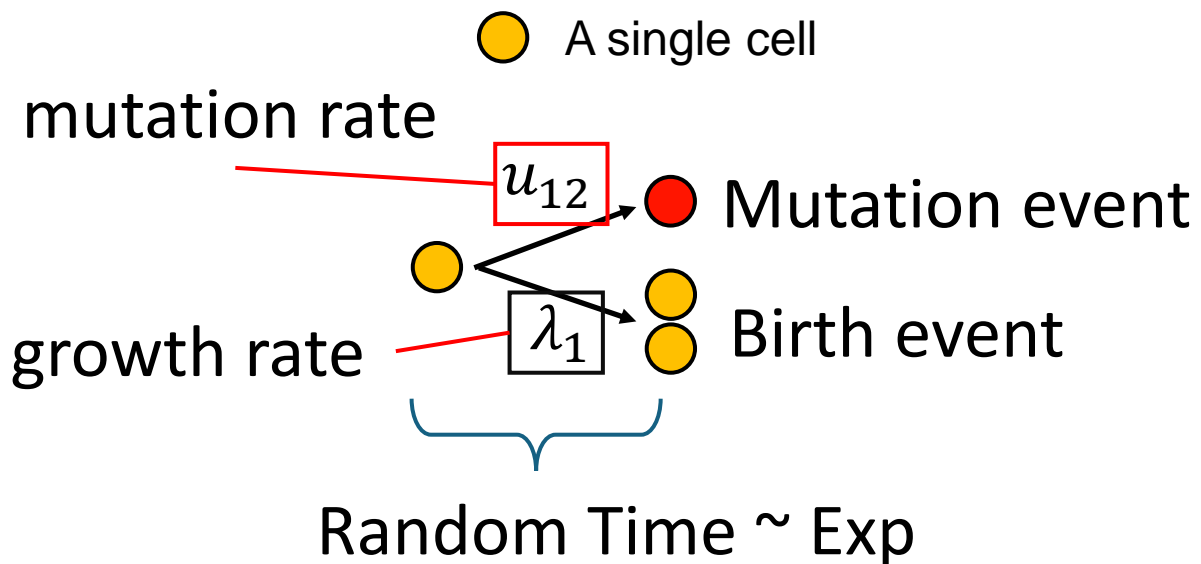
A computational model for cancer initiation

- Consider a bunch of 'pseudo' cells.
- Cells have different types that determines their behavior.
- Each cell can do two things: alter its type or divide into two cells of the same type.
- Formally, this model is a stochastic process (Markov process).



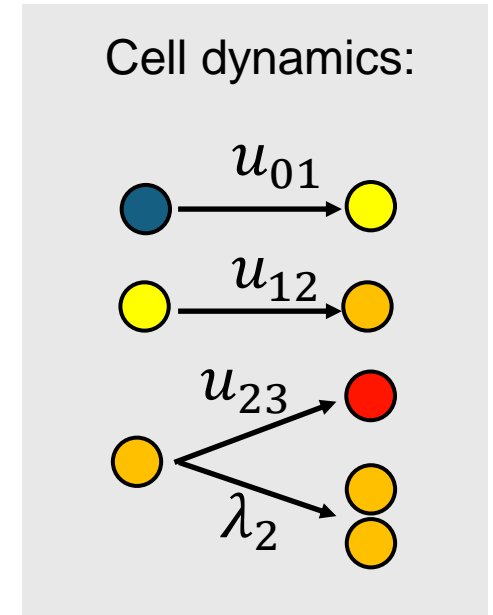
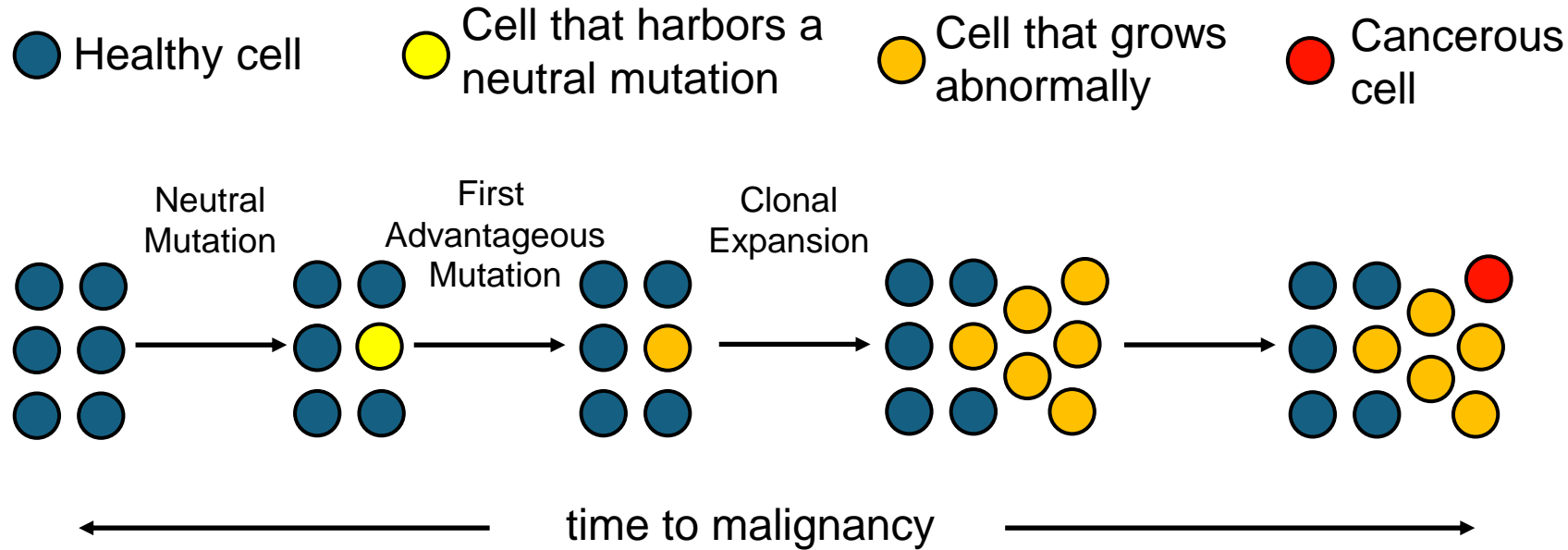
A computational model for cancer initiation

- Consider a bunch of 'pseudo' cells.
- Cells have different types that determines their behavior.
- Each cell can do two things: alter its type or divide into two cells of the same type.
- Formally, this model is a stochastic process (Markov process).



```
#include <random>
std::mt19937_64 rnd_generator;
std::exponential_distribution<> exp{rate};
double time = exp(rnd_generator);
```

A computational model for cancer initiation

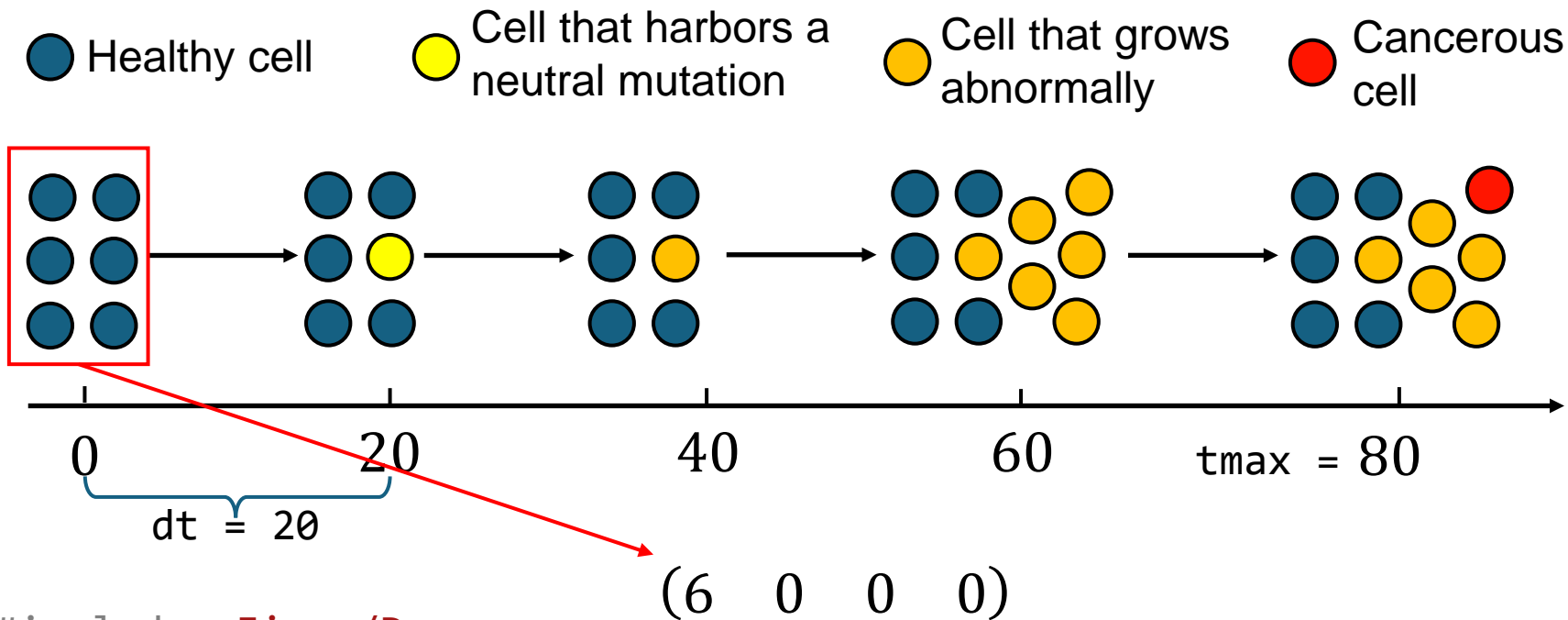


Input: Parameters.

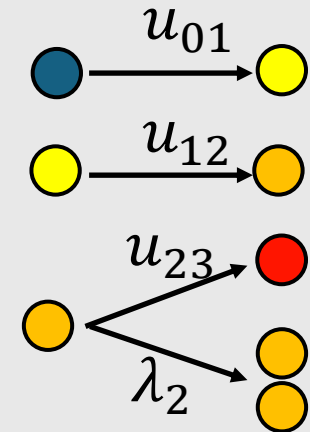
Output: Population at desired times: $N_i(t_1), N_i(t_2), \dots$

- Need many simulated tumors for understanding their statistical properties.
 - The waiting time to each type: τ_i = the first time such that $N_i(t) > 0$
 - The distribution of population size for cell of each type.

Parameters for simulating a single tumor



Cell dynamics:

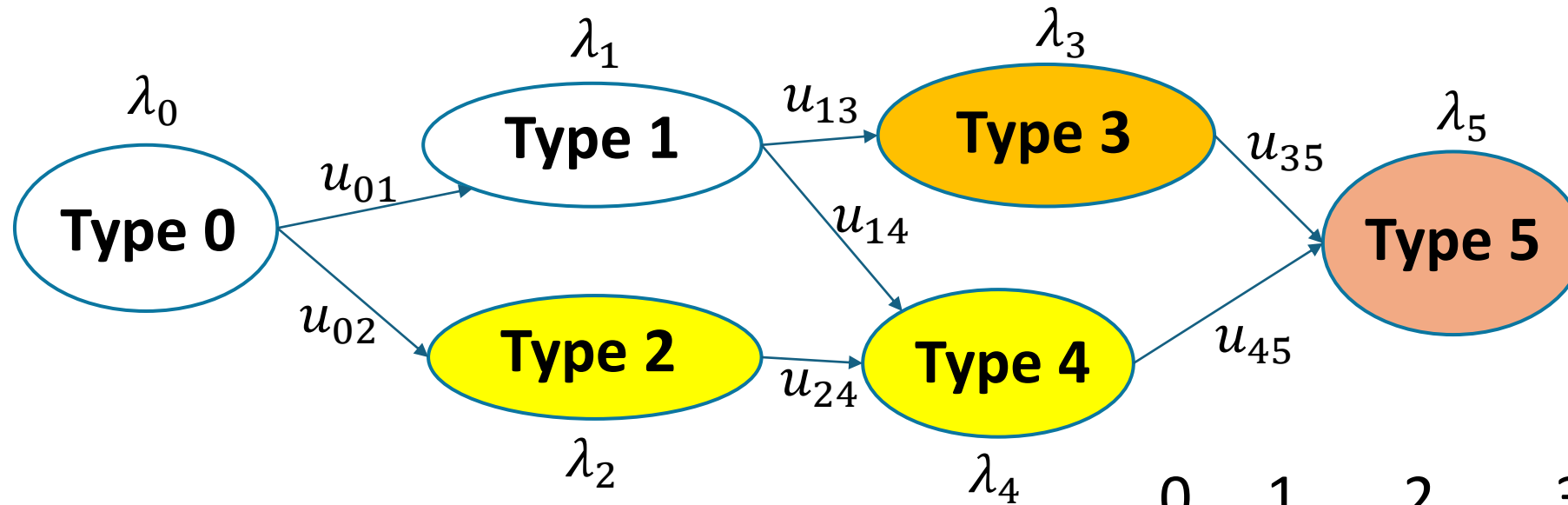


```

#include <Eigen/Dense>
class TumorGenerator {
Eigen::ArrayXd initial_population;
double tmax;
double dt; //...
    
```

The **Array** class template: `Array<typename Scalar, int RowsAtCompileTime, int ColsAtCompileTime>`
`typedef Eigen::Array<double, Eigen::Dynamic, 1> Eigen::ArrayXd;`

Transition of types forms a network



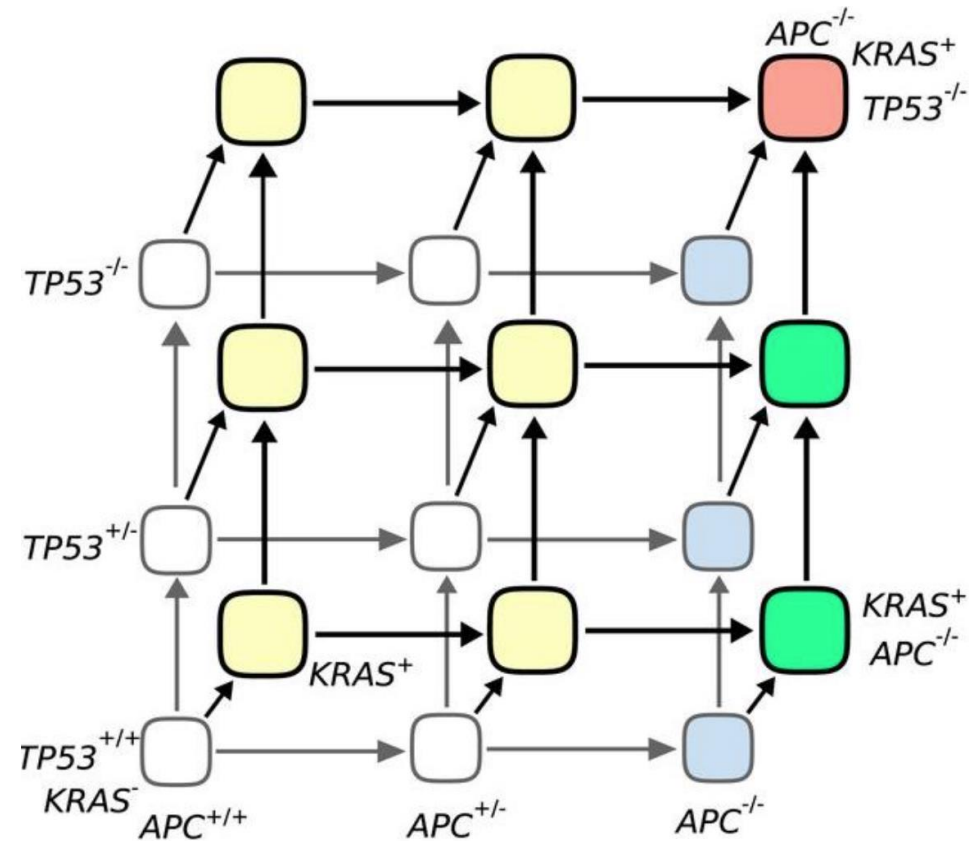
- A weighted graph for the transition of types
- Parameters form a weighted adjacent matrix.

```
int ntype;
```

```
Eigen::ArrayXXd transition_rates;
```

$$\begin{pmatrix}
 \lambda_0 & u_{01} & u_{02} & & & \\
 & \lambda_1 & & u_{13} & u_{14} & \\
 & & \lambda_2 & & u_{24} & \\
 & & & \lambda_3 & & u_{35} \\
 & & & & \lambda_4 & u_{45} \\
 & & & & & \lambda_5
 \end{pmatrix}
 \begin{matrix}
 0 \\ 1 \\ 2 \\ 3 \\ 4 \\ 5
 \end{matrix}$$

Example: Colorectal Cancer with 5 mutations

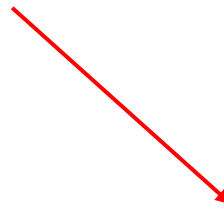


5 mutations can occur in any order.

Track a single tumor by a 2d array

```
ArrayXXd TumorGenerator::single_tumor(unsigned seed)
{
    rnd_generator.seed(seed); // set the seed of the random number generator
    const int datalen = (int)(tmax / dt) + 1;
    Eigen::ArrayXXd time_population(datalen, ntype + 1);

    //...
```



time population

...				

Track a single tumor by a 2d array

```
ArrayXXd TumorGenerator::single_tumor(unsigned seed)
{
    rnd_generator.seed(seed); // set the seed of the random number generator
    const int datalen = (int)(tmax / dt) + 1;
    Eigen::ArrayXXd time_population(datalen, ntype + 1);

    const Eigen::VectorXd record_time = Eigen::VectorXd::LinSpaced(datalen, 0, tmax);
    time_population.block(0, 0, datalen, 1) = record_time;
    //...
```

Block operation

Block of size (p,q), starting at (i,j) `matrix.block(i,j,p,q);`

Version constructing a
dynamic-size block expression

time	population			
0				
1				
2				
3				
...				

Track a single tumor by a 2d array

```
ArrayXXd TumorGenerator::single_tumor(unsigned seed)
```

```
{
```

```
    //...
```

```
    int data_index = 0;
```

```
    while(data_index < datalen){
```

```
        //...
```

```
        time_population.block(data_index, 1, 1, ntype) = population_old.transpose();
```

```
        //...
```

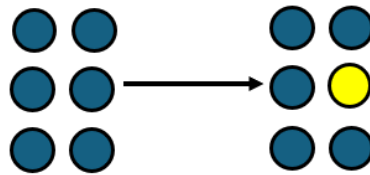
```
        evolve_step();
```

```
    }
```

```
    return time_population;
```

```
}
```

A single step of evolution



Version constructing a
dynamic-size block expression

Block operation

Block of size (p,q), starting at (i,j) `matrix.block(i,j,p,q);`

time population

0	6	0	0	0
1	5	1	0	0
2				
3				
...				

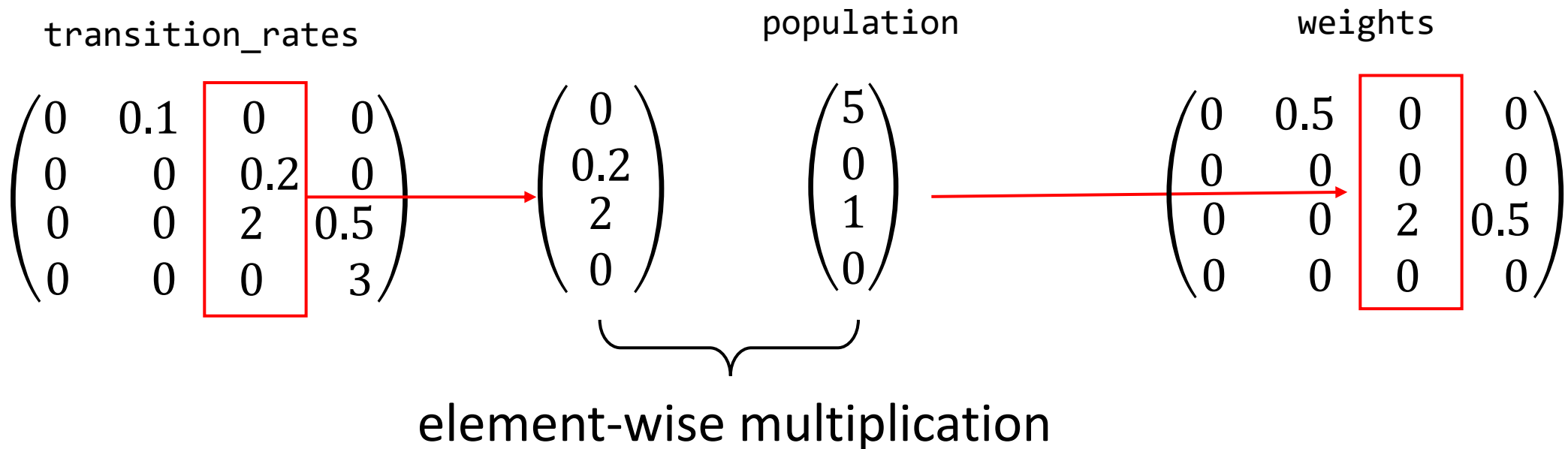
A single step of evolution

```
double TumorGenerator::lifespan(const Eigen::ArrayXXd& weights);  
std::pair<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd& weights);  
  
void TumorGenerator::evolve_step()  
{  
    Eigen::ArrayXXd weights = transition_rates.colwise() * population; // 1  
    time += lifespan(weights); // 2  
  
    auto [decre_type, incre_type] = increment_type(weights); // 3  
    population(incre_type)++;  
    if (decre_type != -1) population(decre_type)--;  
}
```

1. Compute the weights matrix.
2. Determine the arrival time by sampling an exponential distribution.
3. Normalize the weights to get the probabilities for possible events. Sample a random variable to decide which event happens.

Compute the weights matrix

```
void TumorGenerator::evolve_step()
{
    Eigen::ArrayXXd weights = transition_rates.colwise() * population; // 1
    //...
}
```



Sample a position in a matrix randomly

```
std::pair<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd &weights)
{
    int ntype = weights.rows();
    std::discrete_distribution<> d(weights.resaped().begin(),weights.resaped().end());
    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```

weights

	0	1	2	3	
	0	0.5	0	0	0
	0	0	0	0	1
	0	0	2	0.5	2
	0	0	0	0	3

```
template< class InputIt >
discrete_distribution( InputIt first, InputIt last );
```

Constructs the distribution on integers with weights in the range [first, last)

Sample a position in a matrix randomly

```
std::pair<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd &weights)
{
    int ntype = weights.rows();
    std::discrete_distribution<> d(weights.resshaped().begin(),weights.resshaped().end());
    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```

reshape() returns a **view** on the input expression.

0, 0, 0, 0, 0.5, 0, 0, 0, 0, 0, 2, 0, 0, ... 0

weights

	0	1	2	3	
	0	0.5	0	0	0
	0	0	0	0	1
	0	0	2	0.5	2
	0	0	0	0	3

```
template< class InputIt >
discrete_distribution( InputIt first, InputIt last );
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Constructs the distribution on integers with weights in the range [first, last)

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    int ntype = weights.rows();
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    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```

0, 0, 0, 0; 0.5, 0, 0, 0; 0, 0, 2, 0; 0, ... 0

Eigen: STL iterators are intrinsically designed to iterate over 1D structures. This is why begin()/end() methods are disabled for 2D expressions.

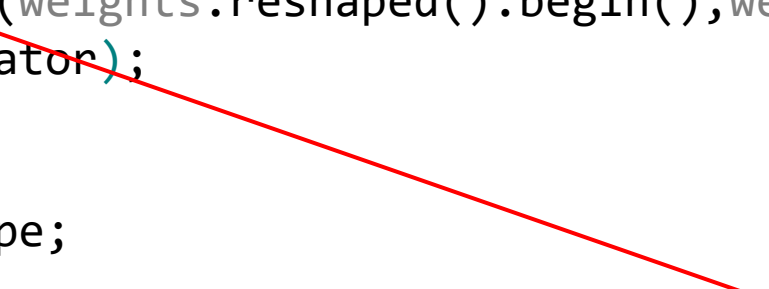
```
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discrete_distribution( InputIt first, InputIt last );
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Constructs the distribution on integers with weights in the range [first, last)

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    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```



					weights.resaped()										
					0, 0, 0, 0; 0.5, 0, 0, 0; 0, 0, 2, 0, ... 0										
					<hr/>										
					Integers: 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, ...,15										
					Probabilities: 0, 0, 0, 0, 1/6, 0, 0, 0, 0, 0, 2/3, 0, ...,0										

weights

$$\begin{pmatrix} 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \end{matrix}$$

Sample a position in a matrix randomly

```
std::pair<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd &weights)
{
    int ntype = weights.rows();
    std::discrete_distribution<> d(weights.resaped().begin(),weights.resaped().end());
    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```

Select an integer according to the probabilities

`weights.resaped()` 0, 0, 0, 0; 0.5, 0, 0, 0; 0, 0, 2, 0, ... 0

Integers: 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, **10**, 11, ..., 15

Probabilities: 0, 0, 0, 0, 1/6, 0, 0, 0, 0, 0, 2/3, 0, ..., 0

`weights` $\begin{pmatrix} 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \end{matrix}$

Sample a position in a matrix randomly

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std::pair<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd &weights)
{
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    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    //...
}
```

Select an integer according to the probabilities

`weights.resaped()` 0, 0, 0, 0; 0.5, 0, 0, 0; 0, 0, 2, 0, ... 0

Integers: 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, ..., 15

Probabilities: 0, 0, 0, 0, 1/6, 0, 0, 0, 0, 0, 2/3, 0, ..., 0

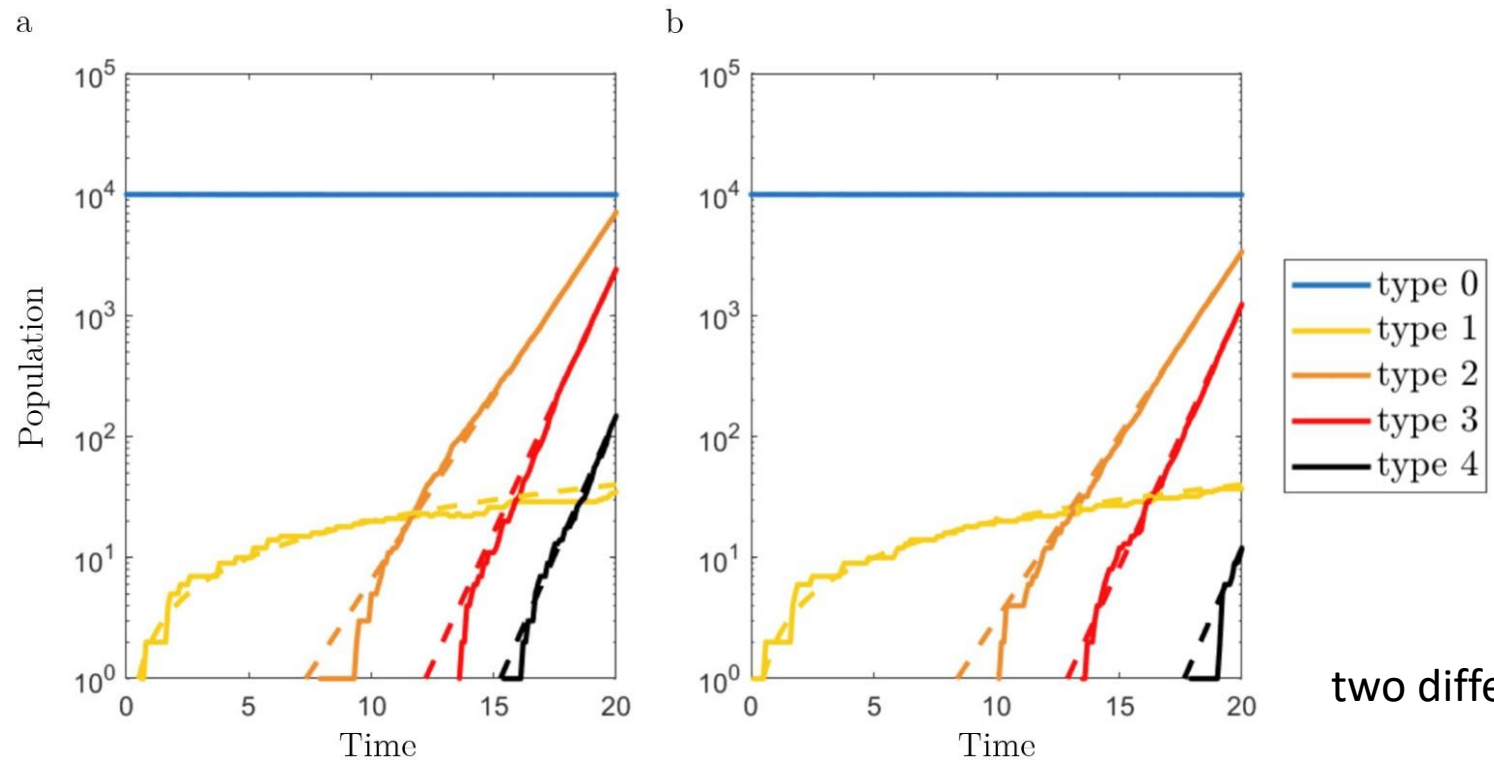
`weights`

0	1	2	3
0	0.5	0	0
0	0	0	0
0	0	2	0.5
0	0	0	0

10 = 2 x 4 + 2 → 10 == `weights(2,2)`

Task-based concurrency

- Each tumor is a parallel task:
`std::vector<std::future<Eigen::ArrayXXd>>`
- For each future object, call `get()` to obtain a 2d array.



two different tumors

Task-based concurrency

```
Eigen::ArrayXXd tumor_par(const unsigned& seed, const double& tmax, const double& dt,  
    const Eigen::ArrayXd& initial_population, const Eigen::ArrayXXd& transition_rates);  
  
int main(){  
    //...  
    std::vector<std::future<Eigen::ArrayXXd>> sample_tumor_par;  
    for (auto k : seeds)  
        sample_tumor_par.emplace_back(std::async(std::launch::async, tumor_par, k, tmax,  
            dt, initial_population, transition_rates));  
  
    // store results (a vector of future Eigen arrays)  
    std::vector<Eigen::ArrayXXd> population_result;  
    population_result.reserve(sample_tumor_par.size());  
  
    // get results (a vector of future Eigen arrays)  
    std::ranges::transform(sample_tumor_par, std::back_inserter(population_result),  
        [](std::future<Eigen::ArrayXXd> &fut){  
            return fut.get();  
        });  
};
```

Task-based concurrency

```
Eigen::ArrayXXd tumor_par(const unsigned& seed, const double& tmax, const double& dt,
    const Eigen::ArrayXd& initial_population, const Eigen::ArrayXXd& transition_rates);

int main(){
    //...
    std::vector<std::future<Eigen::ArrayXXd>> sample_tumor_par;
    for (auto k : seeds)
        sample_tumor_par.emplace_back(std::async(std::launch::async, tumor_par, k, tmax,
            dt, initial_population, transition_rates));

    // store results (a vector of future Eigen arrays)
    std::vector<Eigen::ArrayXXd> population_result;
    population_result.reserve(sample_tumor_par.size());

    // get results (a vector of future Eigen arrays)
    std::ranges::transform(sample_tumor_par, std::back_inserter(population_result),
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            return fut.get();
        });
}
```

Task-based concurrency

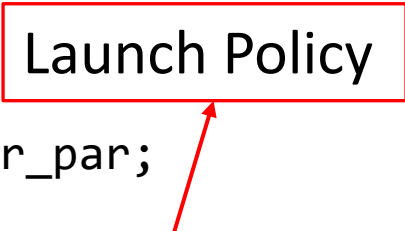
```
Eigen::ArrayXXd tumor_par(const unsigned& seed, const double& tmax, const double& dt,
    const Eigen::ArrayXd& initial_population, const Eigen::ArrayXXd& transition_rates);

int main(){
    //...
    std::vector<std::future<Eigen::ArrayXXd>> sample_tumor_par;
    for (auto k : seeds)
        sample_tumor_par.emplace_back(std::async(std::launch::async, tumor_par, k, tmax,
            dt, initial_population, transition_rates));

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    // get results (a vector of future Eigen arrays)
    std::ranges::transform(sample_tumor_par, std::back_inserter(population_result),
        [](std::future<Eigen::ArrayXXd> &fut){
            return fut.get();
        });
}
```

Launch Policy



Task-based concurrency

```
Eigen::ArrayXXd tumor_par(const unsigned& seed, const double& tmax, const double& dt,  
    const Eigen::ArrayXd& initial_population, const Eigen::ArrayXXd& transition_rates);
```

```
int main(){  
    //...  
    std::vector<std::future<Eigen::ArrayXXd>> sample_tumor_par;  
    for (auto k : seeds)  
        sample_tumor_par.emplace back(std::async(std::launch::async, tumor_par, k, tmax,  
            dt, initial_population, transition_rates));  
  
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        [](std::future<Eigen::ArrayXXd> &fut){  
            return fut.get();  
        });  
};
```

Launch Policy

Each tumor has a unique seed.

Parameters shared by all the tumors

Task-based concurrency

```
Eigen::ArrayXXd tumor_par(const unsigned& seed, const double& tmax, const double& dt,  
    const Eigen::ArrayXd& initial_population, const Eigen::ArrayXXd& transition_rates);
```

```
int main(){
```

```
    ...
```

```
    std::vector<std::future<Eigen::ArrayXXd>> sample_tumor_par;
```

```
    for (auto k : seeds)
```

```
        sample_tumor_par.emplace_back(std::async(std::launch::async, tumor_par, k, tmax,  
dt, initial_population, transition_rates));
```

```
    // store results (a vector of future Eigen arrays)
```

```
    std::vector<Eigen::ArrayXXd> population_result;
```

```
    population_result.reserve(sample_tumor_par.size());
```

```
    // get results (a vector of future Eigen arrays)
```

```
    std::ranges::transform(sample_tumor_par, std::back_inserter(population_result),
```

```
        [](std::future<Eigen::ArrayXXd> &fut){
```

```
            return fut.get();
```

```
        });
```

Launch Policy

Each tumor has a unique seed.

Parameters shared by all the tumors

call .get() to obtain population arrays.

Parallel STL algorithm (average population)

```
// compute average population
```

```
    Eigen::ArrayXXd initial_array = Eigen::ArrayXXd::Zero(population_result[0].rows(),  
population_result[0].cols());
```

```
    Eigen::ArrayXXd average_population = 1.0 / runs *  
std::reduce(std::execution::par, population_result.begin(), population_result.end(),  
initial_array);
```

The generalized sum of init and the elements of [first, last) over std::plus<>().

```
template< class ExecutionPolicy, class ForwardIt, class T >  
T reduce( ExecutionPolicy&& policy, ForwardIt first, ForwardIt last, T init );
```

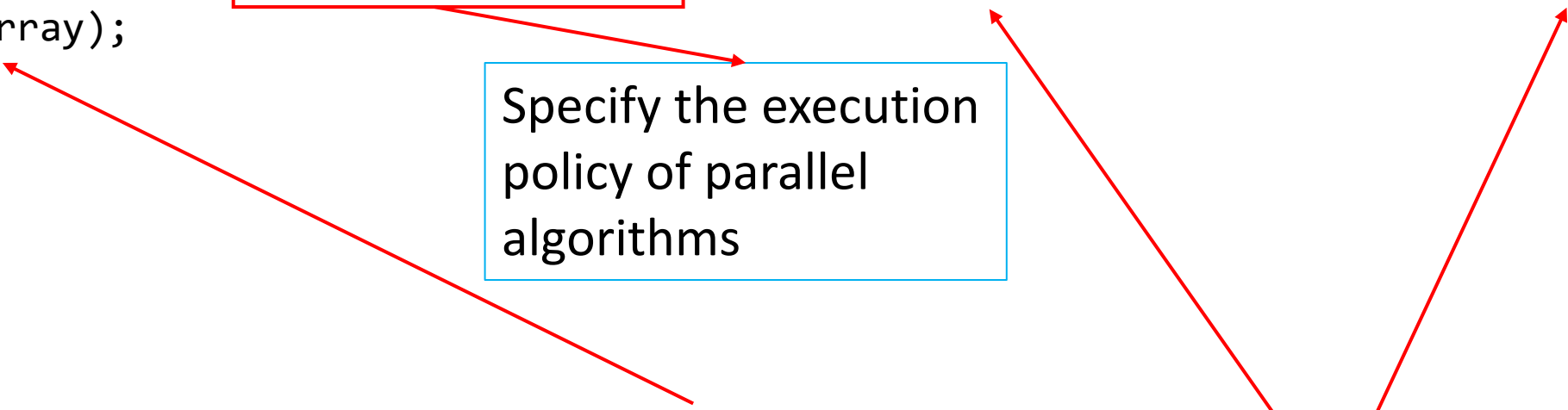
Parallel STL algorithm (average population)

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// compute average population
```

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    Eigen::ArrayXXd initial_array = Eigen::ArrayXXd::Zero(population_result[0].rows(),  
population_result[0].cols());
```

```
    Eigen::ArrayXXd average_population = 1.0 / runs *  
        std::reduce(std::execution::par, population_result.begin(), population_result.end(),  
initial_array);
```

Specify the execution
policy of parallel
algorithms



The generalized sum of init and the elements of [first, last) over std::plus<>().

```
template< class ExecutionPolicy, class ForwardIt, class T >  
T reduce( ExecutionPolicy&& policy, ForwardIt first, ForwardIt last, T init );
```


Parallel STL algorithm (waiting time)

```
// computing waiting time distribution
Eigen::ArrayXXd waitingtime_dist = 1.0 / runs *
std::transform_reduce(std::execution::par, population_result.begin(),
population_result.end(),
initial_array,
std::plus<Eigen::ArrayXXd>(), // binary operation
[](Eigen::ArrayXXd& array)->Eigen::ArrayXXd {return (array > 0).cast<double>();});
```

unary operation

Applies **transform** to each element in the range [first, last) and std::reduces the results along with the initial value init over reduce.

Performance

Generate a required number of tumors:

n _{type}	Initial cells	t _{max}	Number of tumors	Time-Serial (sec)	Time-Parallel (sec)
3	10 ⁵	85	10 ³	0.4914	0.0223
3	10 ⁵	85	10 ⁵	42.30	1.86
6	10 ⁸	70	1	68.24	69.29
6	10 ⁸	70	10	733.6	137.6

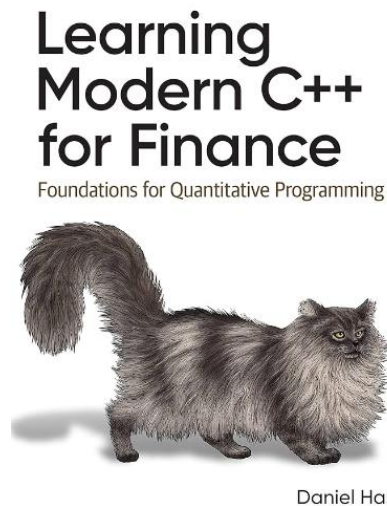
Use a STL algorithm to get waiting time distributions:

n _{type}	Initial cells	t _{max}	Number of tumors	Time-Serial (sec)	Time-Parallel (sec)
3	10 ⁵	85	10 ³	0.0175	0.0015
3	10 ⁵	85	10 ⁵	1.8663	0.0897

Concluding remarks

- Documentation of Eigen is pretty good.
- `std::future/std::async` are easy to pick up.
- Computational Biology is a rapidly growth field. (sequencing data)
- Major reference:

Daniel Hanson, Learning Modern C++ for Finance, O'Reilly

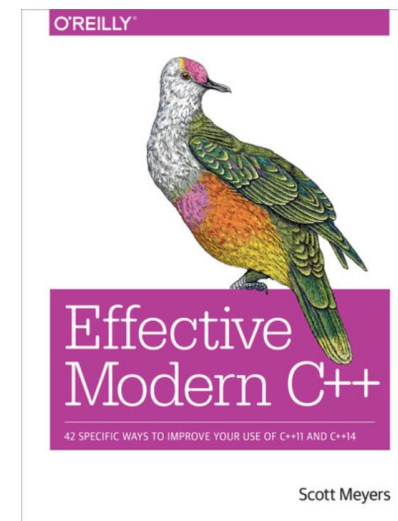
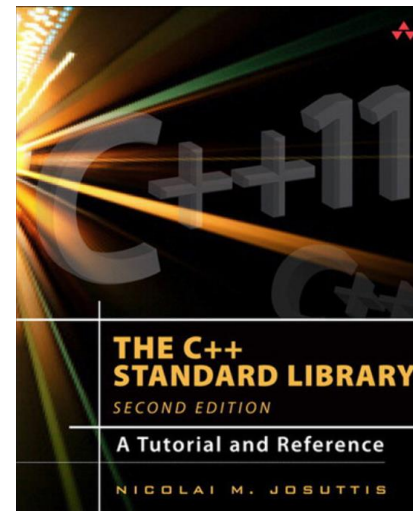


Thank you for attending!

- Sample Code available on Github:
<https://github.com/RuiboZhang98/CppGillespie>
- Contact information: rzhang98 (at) uw.edu

Additional References:

C++ Standard Library, The: A Tutorial and Reference, 2nd Edition, Addison Wesley
Effective Modern C++, Scott Meyers, O'Reilly
cppreference.com

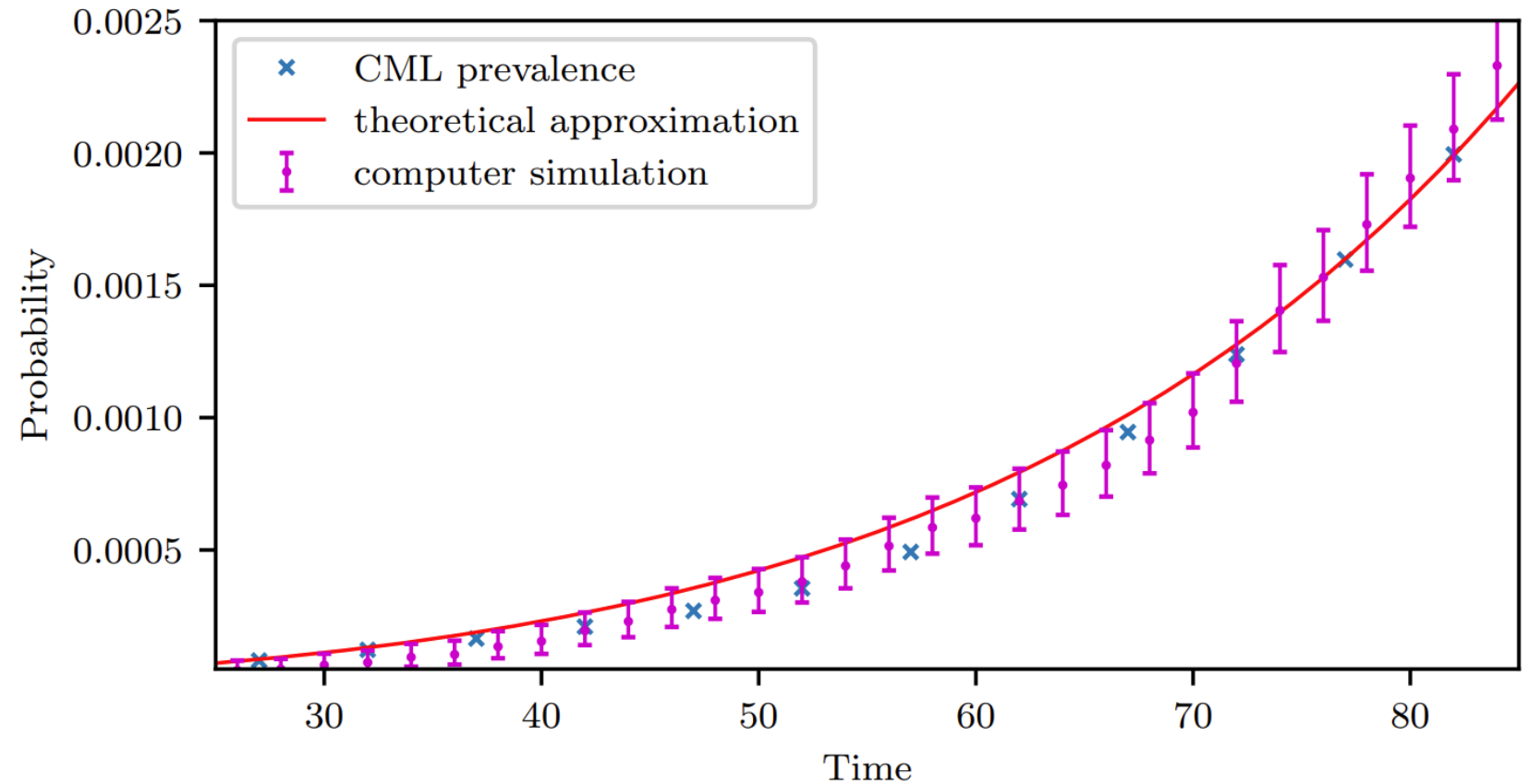


Appendices

Chronic Myeloid Leukemia

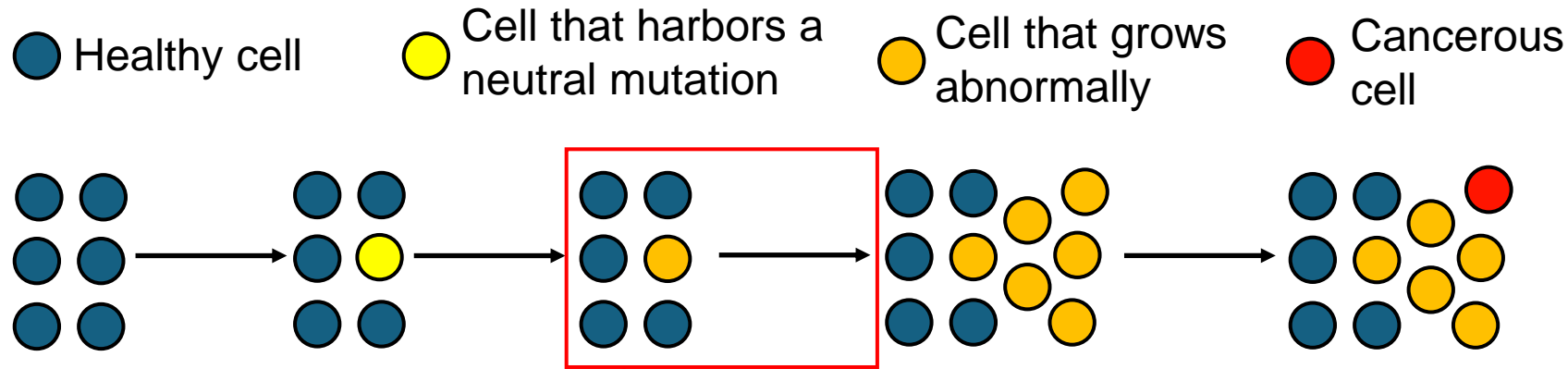
- One genetic alteration (BCR-ABL) can cause CML.
- A simple model with three types:

Healthy cells → cancerous cells → detectable cancer

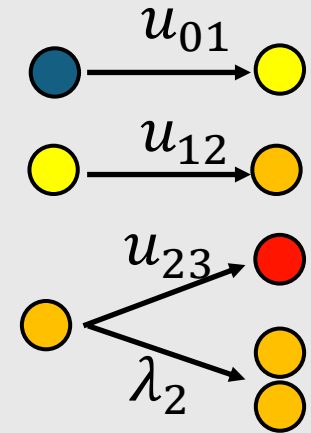


CML prevalence data points come from the SEER Incidence Data, National Cancer institute.
SEER (Surveillance, Epidemiology, and End Results Program)

A single step of evolution



Cell dynamics:



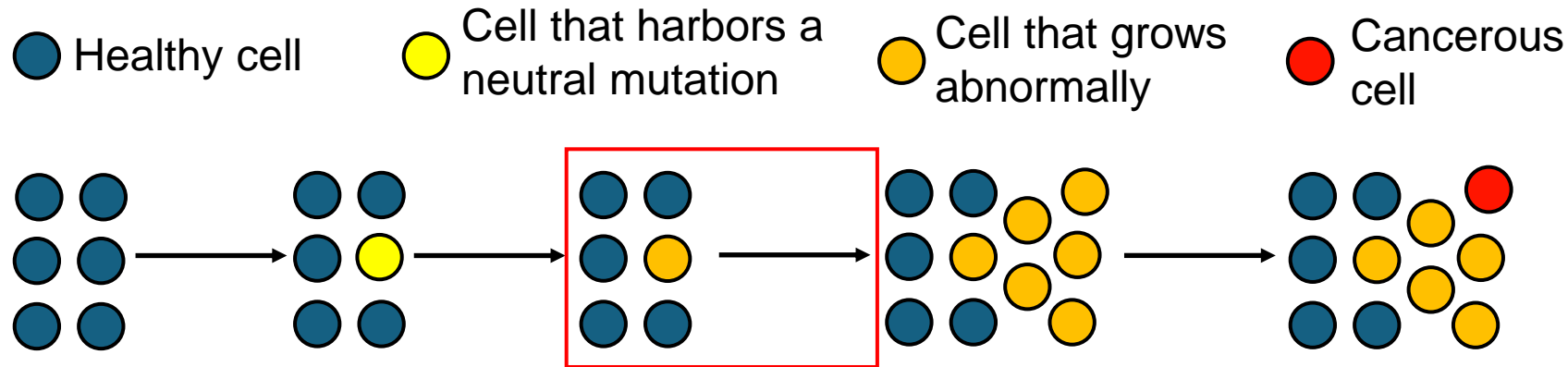
population (5 0 1 0)

transition_rates

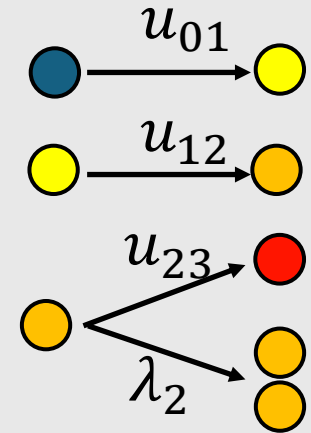
$$\begin{pmatrix} 0 & 0.1 & 0 & 0 \\ 0 & 0 & 0.2 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

```
// tumor population at a certain time
Eigen::ArrayXd population;
double time;
```


A single step of evolution



Cell dynamics:



population (5 0 1 0)

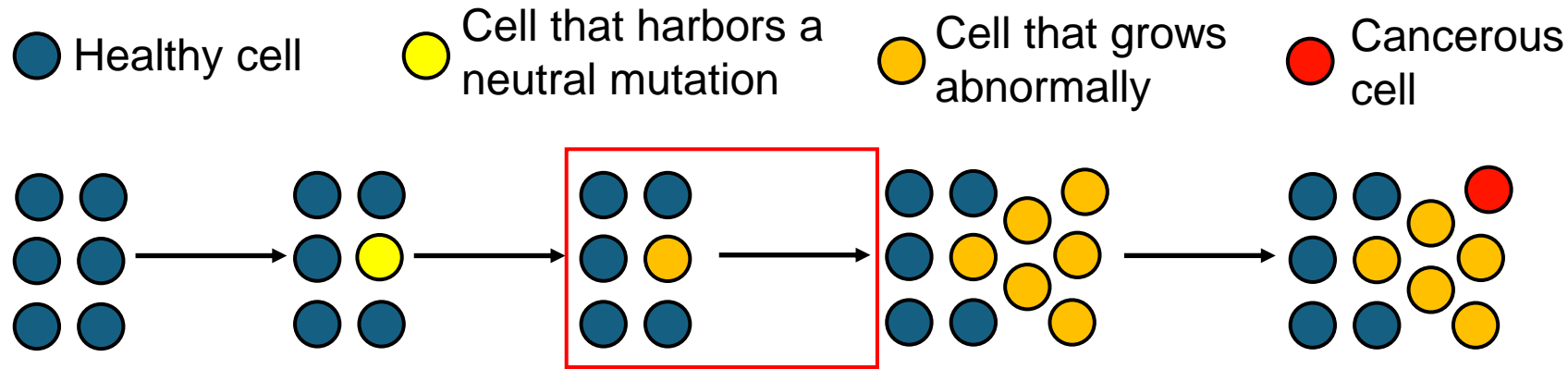
transition_rates

$$\begin{pmatrix} 0 & 0.1 & 0 & 0 \\ 0 & 0 & 0.2 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

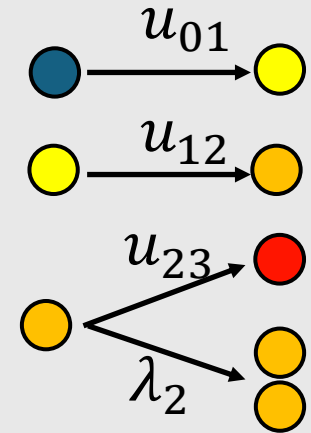
Weights for the next event:

$$\begin{aligned}
 &\text{Blue} \rightarrow \text{Yellow} \quad 5 \times 0.1 = 0.5 \\
 &\text{Orange} \rightarrow \text{Orange} \quad 1 \times 2 = 2 \\
 &\text{Orange} \rightarrow \text{Red} \quad 1 \times 0.3 = 0.5 \\
 &\text{Sum: } 0.5 + 2 + 0.5 = 3
 \end{aligned}$$

A single step of evolution



Cell dynamics:



population (5 0 1 0)

transition_rates

$$\begin{pmatrix}
 0 & 0.1 & 0 & 0 \\
 0 & 0 & 0.2 & 0 \\
 0 & 0 & \textcolor{red}{2} & \textcolor{red}{0.5} \\
 0 & 0 & 0 & 3
 \end{pmatrix}$$

Weights for the next event:

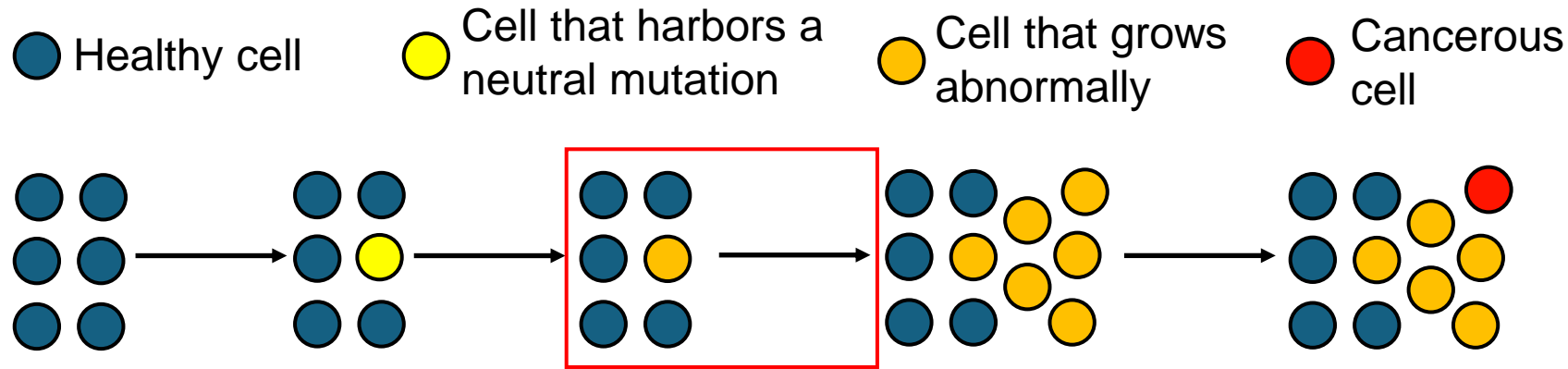
● \longrightarrow ● $5 \times 0.1 = 0.5$

● \longrightarrow ●● $1 \times 2 = 2$

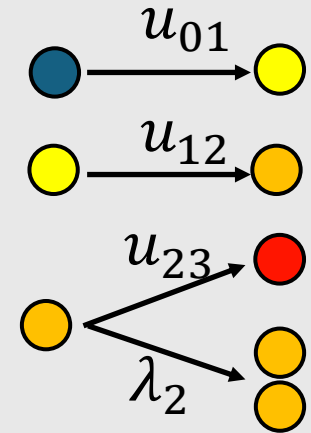
● \longrightarrow ● $1 \times 0.3 = 0.5$

Sum: $0.5 + 2 + 0.5 = 3$

A single step of evolution



Cell dynamics:



population (5 0 1 0)

transition_rates

$$\begin{pmatrix} 0 & 0.1 & 0 & 0 \\ 0 & 0 & 0.2 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

Weights for the next event:

● → ● $5 \times 0.1 = 0.5$

● → ●● $1 \times 2 = 2$

● → ● $1 \times 0.3 = 0.5$

Sum: $0.5 + 2 + 0.5 = 3$

Probabilities:

$0.5/3 = 1/6$

$2/3 = 2/3$

$0.5/3 = 1/6$

Time for the next event follows an exponential distribution $\sim \text{Exp}(3)$

Appendix A: Compute the weight matrix

```
void TumorGenerator::evolve_step()
```

```
{
```

```
1. Eigen::ArrayXXd weights = transition_rates.colwise() * population;
```

```
...
```

```
}
```

transition_rates

$$\begin{pmatrix} 0 & 0.1 & 0 & 0 \\ 0 & 0 & 0.2 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

population

$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \quad \begin{pmatrix} 5 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

weights

$$\begin{pmatrix} 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0.5 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

element-wise multiplication

Compute the weight matrix

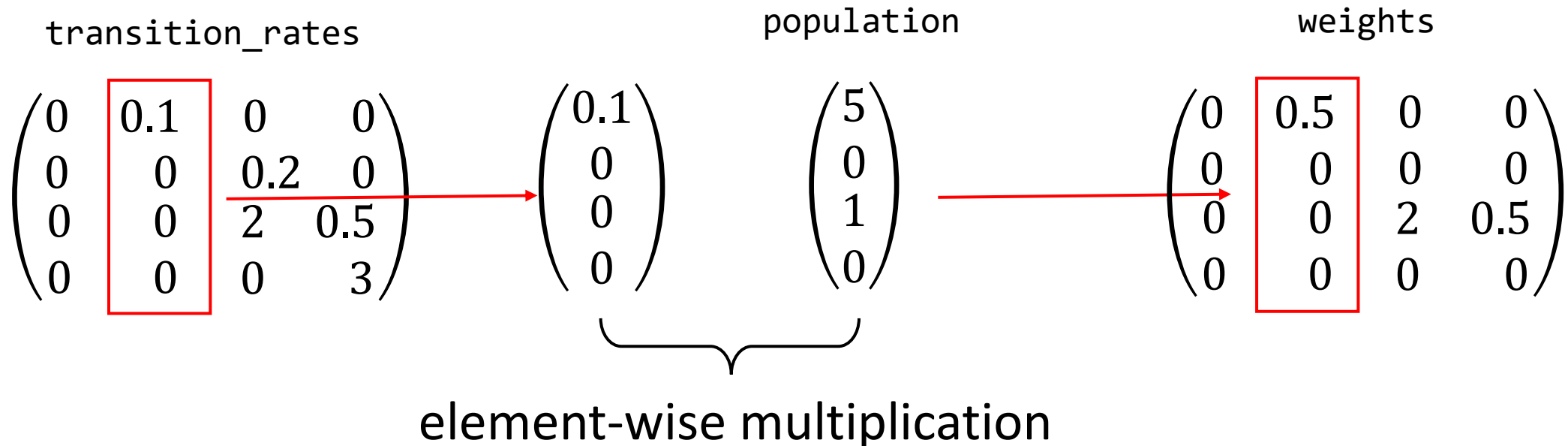
```
void TumorGenerator::evolve_step()
```

```
{
```

```
1. Eigen::ArrayXXd weights = transition_rates.colwise() * population;
```

```
...
```

```
}
```



Compute the weight matrix

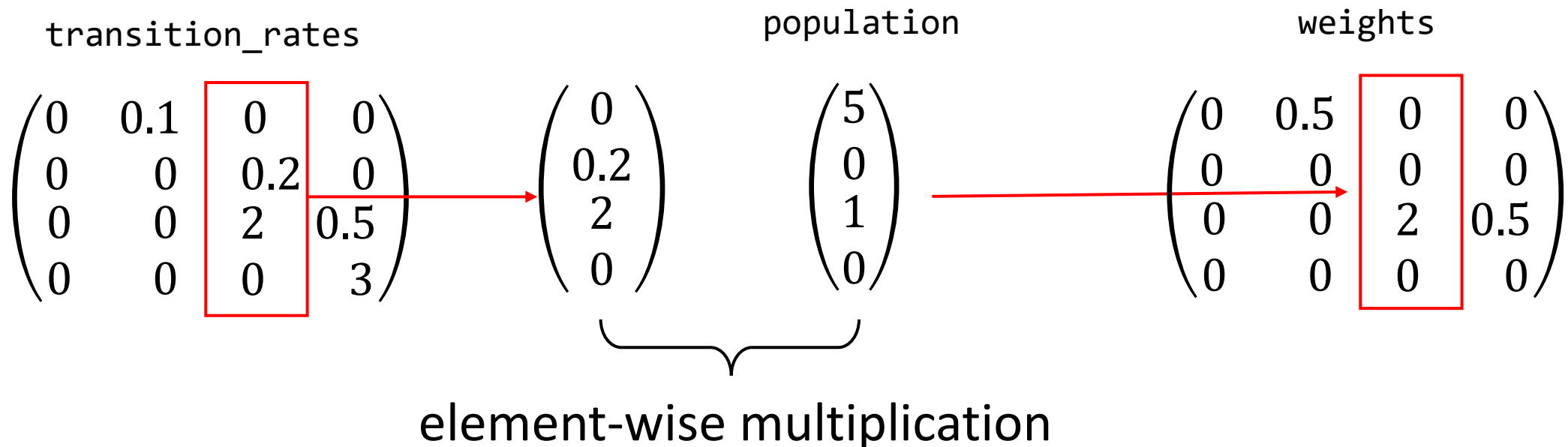
```
void TumorGenerator::evolve_step()
```

```
{
```

```
1. Eigen::ArrayXXd weights = transition_rates.colwise() * population;
```

```
...
```

```
}
```



Compute the weight matrix

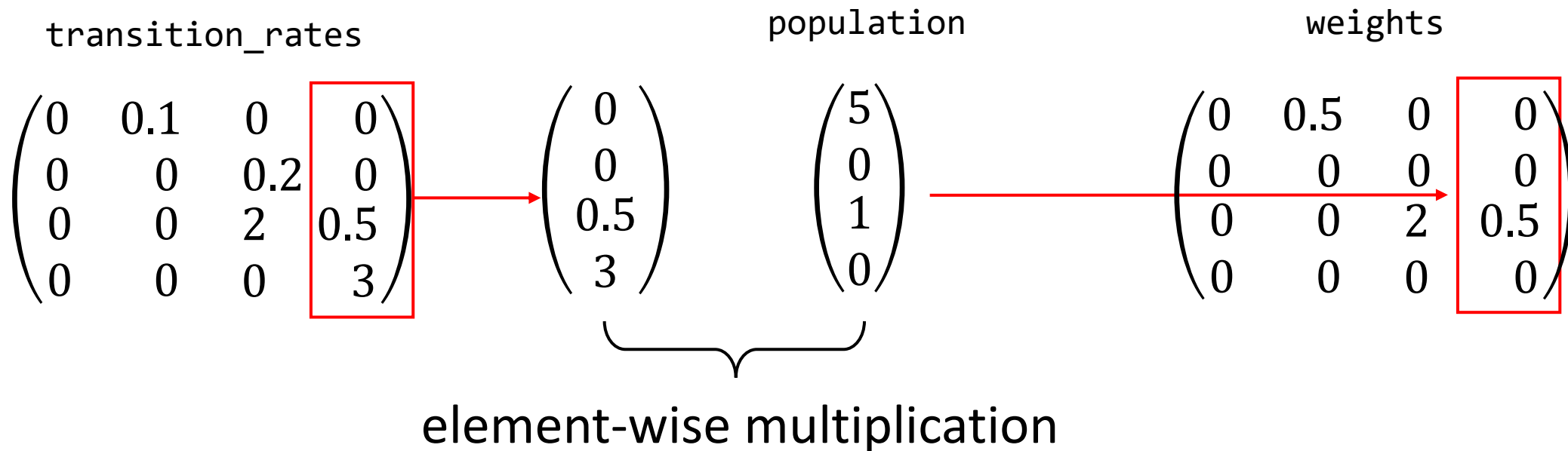
```
void TumorGenerator::evolve_step()
```

```
{
```

```
1. Eigen::ArrayXXd weights = transition_rates.colwise() * population;
```

```
...
```

```
}
```



Appendix B: Time evolution

```
void TumorGenerator::evolve_step()
{
    Eigen::ArrayXXd weights = transition_rates.colwise() * population;
    2. time += lifespan(weights);
    ...
}

double TumorGenerator::lifespan(const Eigen::ArrayXXd& weights){
    // The function computes the waiting time for next population change.
    double lambda = weights.sum();
    std::exponential_distribution<> exp{ lambda };
    return exp(rnd_generator);
}
```


Sample an entry in an array randomly

```
void TumorGenerator::evolve_step()
{
```

```
    ...
```

```
3.  auto [decre_type, incre_type] = increment_type(weights);
    population(incre_type)++;
    if (decre_type != -1) population(decre_type)--;
}
```

```
std::tuple<int,int> TumorGenerator::increment_type(const Eigen::ArrayXXd &weights)
{
    int ntype = weights.rows();
    std::discrete_distribution<> d(weights.resaped().begin(),weights.resaped().end());
    int random_entry = d(rnd_generator);

    int c = random_entry / ntype;
    int r = random_entry - c * ntype;
    int decrement = -1;
    if(r != c) decrement = r;

    return {decrement, c};
}
```

```

Eigen::ArrayXXd TumorGenerator::single_tumor(unsigned seed)
{
    rnd_generator.seed(seed); // set the seed of the random number generator
    const int datalen = (int)(tmax / dt) + 1; // length of recorded data
    const Eigen::VectorXd record_time = Eigen::VectorXd::LinSpaced(datalen, 0, tmax); //
record population at these populations
    Eigen::ArrayXXd time_population = Eigen::ArrayXXd::Constant(datalen, ntype + 1, -1.0); //
initiate the data table
    time_population.block(0, 0, datalen, 1) = record_time; // flush the first column with the
record times
    // initialize a tumor
    initiation();
    Eigen::ArrayXd population_old = population;
    // data_index indicates the current row of the result
    int data_index = 0;
    while(data_index < datalen){
        for ( ; (data_index < datalen) && (record_time(data_index) <= time) ; data_index++){
            time_population.block(data_index, 1, 1, ntype) = population_old.transpose();
        }
        population_old = population;
        evolve_step();
    }
    return time_population;
}

```

Initial value in reduce is necessary

```
reduce(first, last, typename std::iterator_traits<InputIt>::value_type{})
```

`value_type`: It is a nested type of `std::iterator_traits` that represents the type of the elements that the iterator points to.

`{}`: This is the syntax for value initialization, which will call the default constructor of the `value_type`.

`Eigen::ArrayXXd`: A default constructor is always available, never performs any dynamic memory allocation, and never initializes the matrix coefficients.