EECS 16B Fall 2020 10B: SVD

## Geometric interpretation of the SVD

In this exercise, we explore the geometric interpretation of symmetric matrices and how this connects to the SVD. We consider how a real  $2 \times 2$  matrix acts on the unit circle, transforming it into an ellipse. It turns out that the principal semiaxes of the resulting ellipse are related to the singular values of the matrix, as well as the vectors in the SVD.

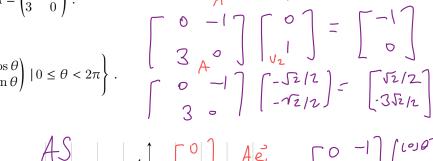
a) Consider the real  $2 \times 2$  matrix

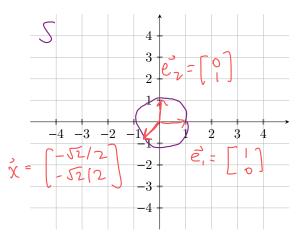
$$A = \begin{pmatrix} 0 & -1 \\ 3 & 0 \end{pmatrix}.$$

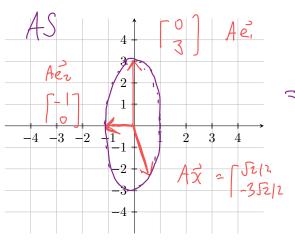
Now consider the unit circle in  $\mathbb{R}^2$ 

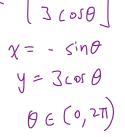
$$S = \left\{ \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \mid 0 \le \theta < 2\pi \right\}.$$

Plot AS on the  $\mathbb{R}^2$  plane.









b) Calculate the SVD of A. Write this as a matrix factorization, i.e.  $A = U\Sigma V^{\top}$ .

$$A = \begin{bmatrix} 0 & -1 \\ 3 & 0 \end{bmatrix}$$

(ompute 
$$A^TA$$

$$\begin{bmatrix} 0 & 3 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 9 & 0 \\ 0 & 1 \end{bmatrix}$$

Compute eig of ATA

$$V_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$A^{T}A - 91 = \begin{bmatrix} 0 & 0 \\ 0 & 8 \end{bmatrix} \quad A^{T}A - 1 = \begin{bmatrix} 8 & 0 \\ 0 & 0 \end{bmatrix}$$

$$V_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$U_{1} = \frac{AU_{1}}{V_{1}}$$

$$U_{1} = \frac{1}{3} \begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

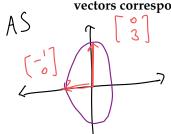
$$U_{2} = \frac{1}{3} \begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

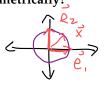
Z. Compute o: = Uzi

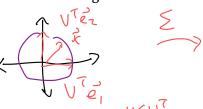
$$A = 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}^{T} + 1 \begin{bmatrix} -1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}^{T} = \begin{bmatrix} 0 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$$

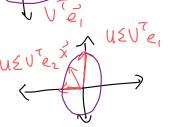
c) Consider the columns of the matrices *U*, *V* obtained in the previous part, and treat them as vectors in  $\mathbb{R}^2$ . Let  $U = (\vec{u_1} \vec{u_2})$ ,  $V = (\vec{v_1} \vec{v_2})$ . Let  $\sigma_1$ ,  $\sigma_2$  be the singular values of A, where

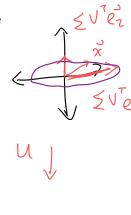
Draw in your plot of AS the vectors  $\sigma_1 \vec{u_1}$  and  $\sigma_2 \vec{u_2}$ , drawn from the origin. What do these vectors correspond to geometrically?











$$3 = 0, U_1 = []$$

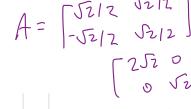
$$3 = 0, U_2 = []$$

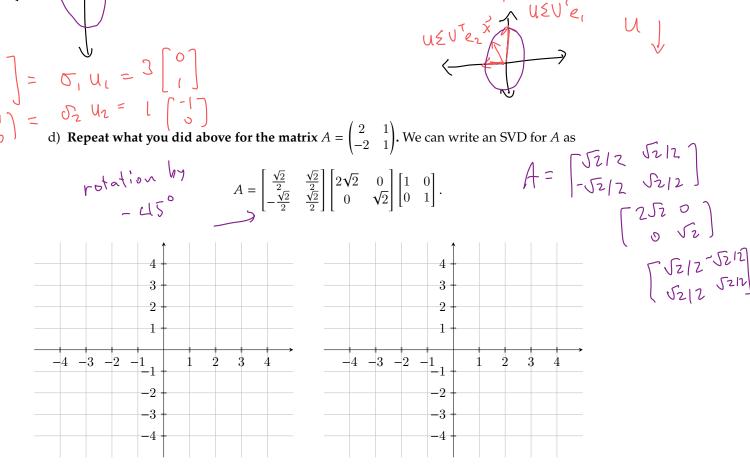
$$3 = 0, U_2 = []$$

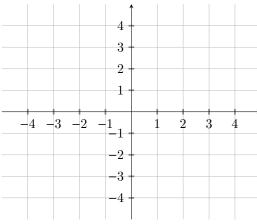
$$3 = 0, U_2 = []$$

$$4) \text{ Repeat what you did about the points of the poin$$

$$A = \begin{bmatrix} \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} \end{bmatrix} \begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & \sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$







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## 2 SVD and Induced 2-Norm

a) Show that if U is a unitary matrix then for any  $\vec{x}$ 

$$\|u\|^{2} = \langle w, w7$$

$$\|w\| = \sqrt{\langle w, w7\rangle}$$

$$\|u\vec{x}\| = \|\vec{x}\|.$$

$$\|u\vec{x}\| = \sqrt{\langle u\vec{x}, u\vec{x}\rangle}$$

$$= \sqrt{(u\vec{x})^{T}(u\vec{x})} \quad u \text{ is unitary so } u^{T}u = I$$

$$= \sqrt{\vec{x}^{T}u^{T}u\vec{x}}$$

$$= \sqrt{\vec{x}^{T}\vec{x}}$$

$$= \|\vec{x}\|$$

b) Find the maximum

$$\max_{\{\vec{x}: ||\vec{x}||=1\}} ||A\vec{x}||$$

in terms of the singular values of *A*.

b) Find the maximum

$$\max_{\{\vec{x}: ||\vec{x}||=1\}} ||A\vec{x}|| \qquad \text{if } y = Ax$$
in terms of the singular values of  $A$ .

$$Consider \quad ||A\vec{x}|| \quad A = U \leq V^T \qquad \text{what is } \max \text{ llyll}$$

$$||A\vec{x}|| = ||U \leq V^T \vec{x}|| \qquad V^T \vec{x} \text{ is a rotation of } \vec{x}$$

$$= || \leq \vec{z}|| \qquad \vec{z} = V^T \vec{x} = V^T \vec{x}$$

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c) Find the  $\vec{x}$  that maximizes the expression above.

$$\frac{1}{2} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$V \vec{z} = V \vec{x}$$

$$\vec{x} = V \vec{z}$$

$$\vec{x} = V \vec{z}$$

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10B: SVD