

Systemtheorie der Sinnesorgane

3 Übung

3.1

First, the reaction of an inner hair cell (IHC) to an external actuation of the stereocilia was measured for two frequencies: 100 Hz (Fig. 1) and 10 kHz (Fig. 2) with 100 nm peak displacement. We observe a saturation at the higher frequency, where the IHC cannot follow the actuation because of capacitive effects. Regarding the envelope, this cell fires one single continuous signal.

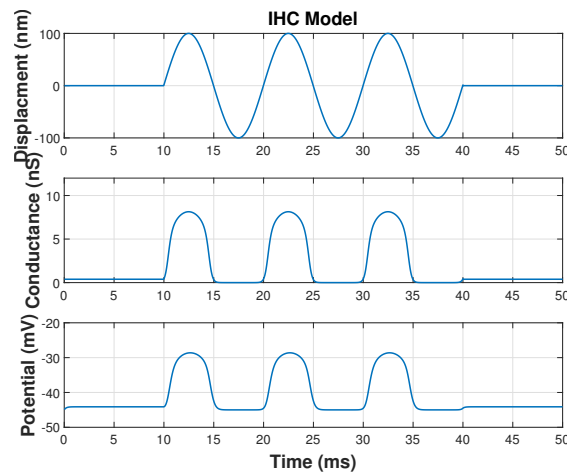


FIGURE 1 – Reaction of an Inner Hair Cell to an external stimulus with 100 nm peak displacement at 100 Hz

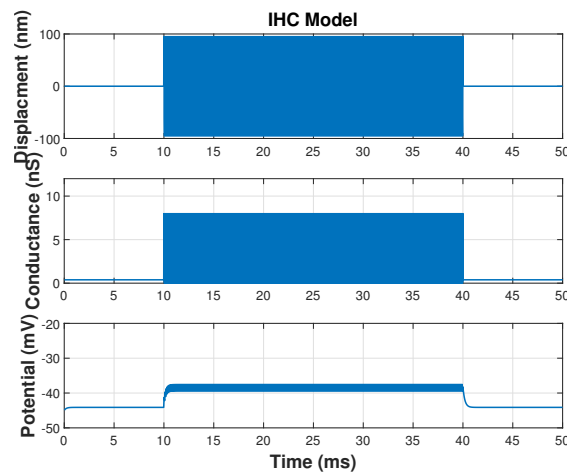


FIGURE 2 – Reaction of an Inner Hair Cell to an external stimulus with 100 nm peak displacement at 10 kHz

3.2

Second, we evaluated the non-linearity of the system by looking at the amplitude spectra of input (Fig. 3) and output (Fig. 4) as well as at the actuation conductivity (Fig. 5). At a frequency-confined displacement at the input, we got several harmonics in the output frequency at the same frequency. Hereby, the red dash indicates the 200 Hz of our initial actuation. In contrast to a LTI-system, the fluid interacts nonlinearly after the Navier-Stokes-Equation with the stereocilia.

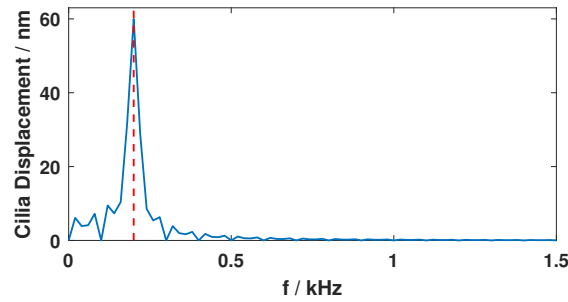


FIGURE 3 – Spectrum of the input wave. A sinusoidal wave, which displaces the stereocilia of the IHC and triggers its activation.

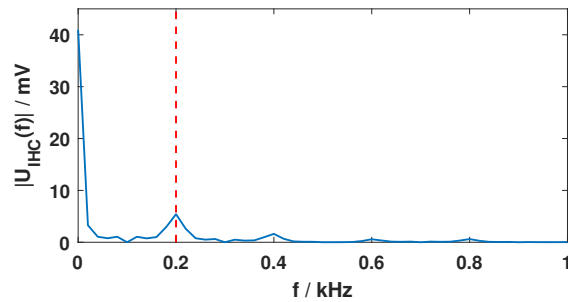


FIGURE 4 – Output voltage of the in Fig. 3 excited inner hair cell.

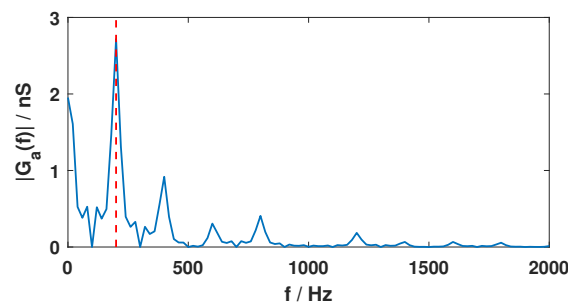


FIGURE 5 – Receptor conductance for a displacement of 100 nm in its peak at 200 Hz

3.3

As developed in the equations below, we can show, that the system is divergent at a displacement of 100 nm with 200 Hz below a sampling rate of 2789 Hz. The divergence is shown in figure 7, where figure 6 acts as the convergent reference.

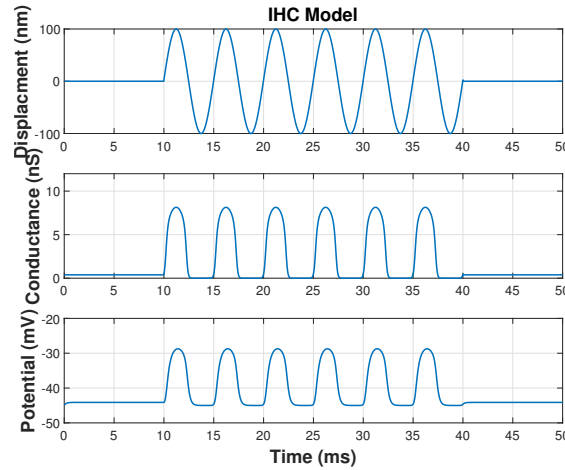


FIGURE 6 – Reaction of an Inner Hair Cell to an external stimulus with 100 nm peak displacement at 200 Hz

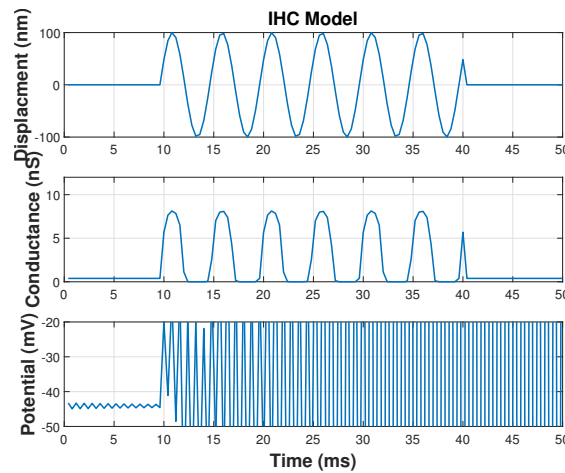


FIGURE 7 – Divergent model driven with the same parameters of 6, but at a sample rate of = 2500.

The limit was computed by concatenating the three given equations (1), (2) and (3) into the differential equation (Eq. (4)). We substituted for simplification purposes (5) and discretized the continuous differential equation by Euler's Explicit Method (Eqs. 6-8). From there, we conducted a limit of the sequence where the discretized steps tended to infinity. We argument with the geometric series (10), that the term with the highest order had to be smaller than one to let the system converge (Eqs. 9:12). Resolving the inequality concludes to the solution in equation 15.

An evaluation of the dependent parameters led to the insight that the maximum of the stereocilia displacement x_{st} provides the upper boundary for the step size and therefore the lower boundary for the sampling rate. With the given parameters from above, we can calculate a minimal sampling frequency of 2789 Hz.

$$g_a(t) = \frac{G_{max}}{\left[1 + \exp\left(\frac{x_0 - x_{st}(t)}{S_{x0}}\right)\right] \cdot \left[1 + \exp\left(\frac{x_0 - x_{st}(t)}{S_{x0}}\right)\right]} \quad (1)$$

$$i_{rez}(t) = (EP - u_{IHC}(t)) \cdot g_a(t) \quad (2)$$

$$i_b(t) = (V_0 - u_{IHC}(t)) \cdot G_b \quad (3)$$

$$\frac{d}{dt}u_{IHC}(t) = \frac{i_{rez}(t) + i_b(t)}{C_m} \quad (4)$$

$$\frac{d}{dt}u_{IHC}(t) = \underbrace{\left(\frac{-g_a - G_b}{C_m}\right)}_A \cdot u_t + \underbrace{\frac{EP \cdot g_a + V_0 \cdot G_b}{C_m}}_B \quad (5)$$

$$\frac{d}{dt}u_{IHC}(t) \approx \frac{\Delta u}{\Delta t} = \frac{u_{t+1} - u_t}{\Delta t} \quad (6)$$

$$u_{t+1} = (1 + A\Delta t) \cdot u_t + B\Delta t \quad (7)$$

$$u_n = (1 + A\Delta t)^n \cdot u_0 + B\Delta t \cdot \sum_{i=0}^{n-1} (1 + A\Delta t)^i \quad (8)$$

$$\lim_{n \rightarrow \infty} \underbrace{(1 + A\Delta t)^n}_{\stackrel{!}{\rightarrow} |1 + A\Delta t| < 1} \cdot u_0 + B\Delta t \cdot \underbrace{\sum_{i=0}^{n-1} (1 + A\Delta t)^i}_{\stackrel{n \rightarrow \infty}{\rightarrow} \text{geom. Series}} \quad (9)$$

$$\sum_{k=0}^{\infty} a_0 \cdot q^k = \frac{a_0}{1 - q}, \quad |q| < 1 \quad (10)$$

$$|1 + A\Delta t| < 1 \Rightarrow A \stackrel{!}{\leq} 0 \quad (11)$$

$$|A| = -\frac{-g_a - G_b}{C_m} \geq 0 \quad (12)$$

$$1 - \frac{g_a + G_b}{C_m} \cdot \Delta t > -1 \quad (13)$$

$$\frac{g_a + G_b}{C_m} \cdot \Delta t < 2 \quad (14)$$

$$\Delta t < \frac{2C_m}{g_a + G_b} \quad (15)$$

$$\min(g_a(t)) \Rightarrow \max(x_{st}) = 100 \text{ nm} \Rightarrow \min(g_a(t)) = 8.14 \text{ nS} \quad (16)$$

$$\Delta t < \frac{2 \cdot 12 \text{ pF}}{8.14 \text{ nS} \cdot 58.8 \text{ nS}} = 359 \text{ } \mu\text{s} \quad (17)$$

$$\Rightarrow \text{Minimum Sampling Rate} = 2789 \text{ Hz} \quad (18)$$