



Software Safety Requirements and Architecture

Lane Assistance

Document Version: [Version]

Template Version 1.0, Released on 2017-06-21



Document history

[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real world project.

For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]

Date	Version	Editor	Description
7/20/2018	1.0	Yafei Qin	First submission

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Purpose

[Instructions: Answer what is the purpose of this document?]

This document identifies the new requirements for the software components at a component level to identify potential problems on software design and architecture that could lead to a violation of safety goals. These requirements are more detail oriented than the technical safety concept requirements.

Inputs to the Software Requirements and Architecture Document

[Instructions:

REQUIRED:

You are only required to develop this document for the LDW (lane departure warning) amplitude malfunction. So here, provide the technical safety requirements for the LDW amplitude malfunction as well as the refined system architecture diagram from the technical safety concept.

OPTIONAL:

Expand this document to include software safety requirements for the LDW frequency malfunction as well. Go even further and document software safety requirements for the Lane Keeping Assistance (LKA) function as well.

Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

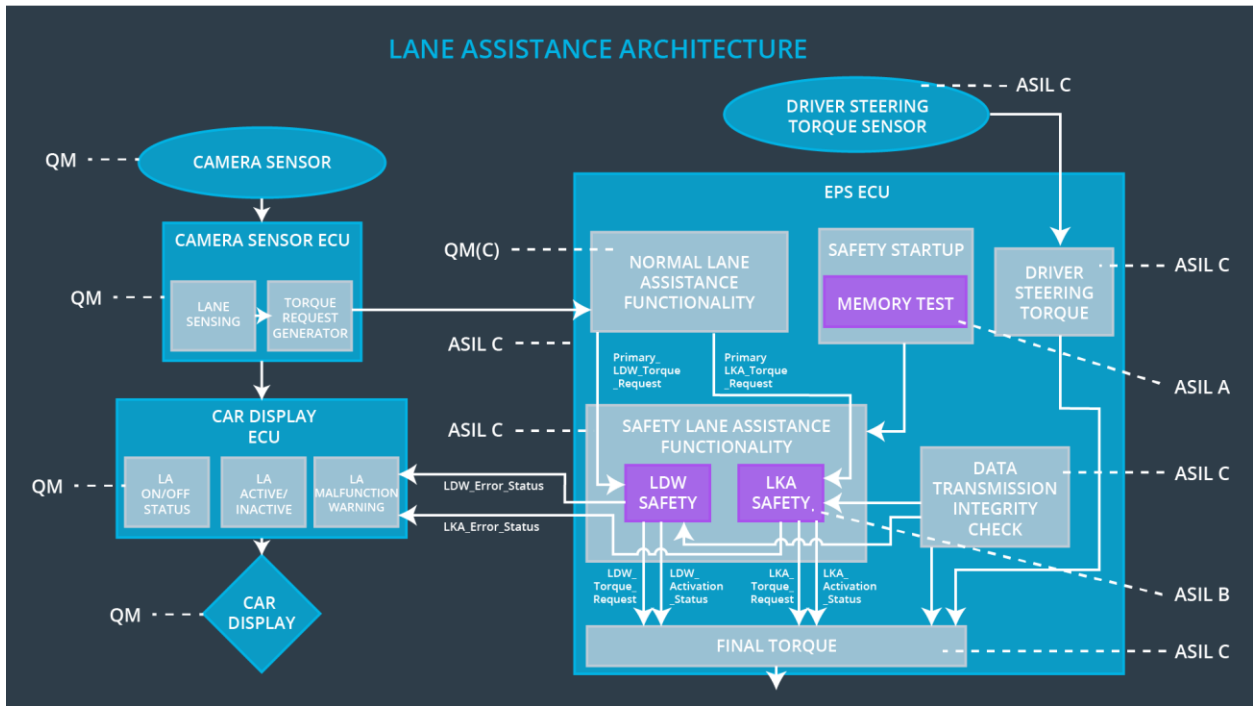
ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The Lane Departure Warning safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude'	C	50 ms	LDW Safety	Lane Departure
Technical Safety Requirement 02	When the Lane Departure Warning is deactivated, the 'LDW Safety' software module shall send a signal to the Car Display ECU to turn on a warning signal.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 03	When a failure is detected by the Lane Departure Warning functionality, it shall deactivate the Lane Departure Warning feature and set 'LDW_Torque_Request' to zero.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement 04	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.
Technical Safety Requirement	Memory test shall be conducted at start up of the	A	Ignition cycle	Data Transmission Integrity	Lane Departure Warning

05	EPS ECU to check for any memory problems			Check	torque to zero.
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Refined Architecture Diagram from the Technical Safety Concept

[Instructions:

REQUIRED: Provide the refined system architecture diagram from the technical safety concept
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Software Requirements

Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

[Instructions: Fill in the software safety requirements for the LDW amplitude malfunction technical safety requirements. We have provided the associated technical safety requirements. Hint: The software safety requirements were discussed in the text from the software and hardware lesson.

OPTIONAL:

CHALLENGE ONE

Develop software safety requirements for the Lane Departure Warning (LDW) frequency function and modify the system architecture as needed.

CHALLENGE TWO

Develop software safety requirements for the Lane Keeping Assistance (LKA) function and modify the system architecture as needed.

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ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 01-01	The input signal 'Primary_LDW_Torq_Req' shall be read and pre-processed to determine the torque request	C	LDW_SAGETY_INPUT_P ROCESSING	N/A

	coming from the 'Basic/Main LAFunctionality' SW Component. Signal 'processed_LDW_Torq_Req' shall be generated at the end of the processing.			
Software Safety Requirement 01-02	In case the 'processed_LDW_Torq_Req' signal has a value greater than 'Max_Torque_Amplitude_LDW' (maximum allowed safe torque), the torque signal 'limited_LDW_Torq_Req' shall be set to zero, else 'limited_LDW_Torq_Req' shall take the value of 'processed_LDW_Torq_Req'	C	TORQUE_LIMITER	'limited_LDW_Torq_Req' = 0 (Nm=Newton-meter)
Software Safety Requirement 01-03	The 'limited_LDW_Torq_Req' shall be transformed into a signal 'LDW_Torq_Req' which is suitable to be transmitted outside the LDW Safety component ('LDW Safety') to the 'Final EPS Torque' component.	C	LDW_SAFETY_OUTPUT_GENERATOR	LDW_Torq_Req = 0 (Nm)

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 02-01	When the Lane Departure Warning function is deactivated ('activation_status' set to zero), the activation_status shall be sent to the Car Display ECU.	C	LDW_SAFETY_ACTIVATION, Car Display ECU	N/A
Software Safety Requirement 02-02				

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 03-01	Each Software element shall output a a signal to indicate any error which is detected by the element. Error signal = error_status_input (LDW_SAFETY_INPUT_PROCESSING), error_status_torque_limiter(TORQUE_LIMITER), error_status_output_gen(LDW_SAFETY_OUTPUT_GENERATOR)	C	All	N/A
Software Safety Requirement 03-02	A software element shall evaluate the error status of all other software elements and in case any one of them indicates an error, it shall deactivate the Lane Departure Warning feature ('activation_status'=0)	C	LDW_SAFETY_ACTIVATION	Lane Departure Warning function deactivated ('activation_status' =0).
Software Safety Requirement 03-03	In case of a no error from the software elements, the status of the Lane Departure Warning feature shall be set to activated ('activation_status'=1).	C	LDW_SAFETY_ACTIVATION	N/A
Software Safety Requirement	In case an error is detected by any of the software elements, it shall set the value to its corresponding	C	All	LDW_Torq_Req = 0

03-04	torque to zero so that 'LDW_Torq_Req' is set to zero			
Software Safety Requirement 03-05	Once the Lane Departure Warning functionality has been deactivated, it shall stay deactivating until the time the ignition is switched from off to on again.	C	LDW_SAFETY_A CTIVATION	Lane Departure Warning function deactivated (‘activation_status’ =0).

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	C	50 ms	LDW Safety	Lane Departure Warning torque to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 04-01	When the Lane Departure Warning function is deactivated ('activation_status' set to zero), the activation_status shall be sent to the Car Display ECU.	C	LDW_SAFETY_ACTIVATION, Car Display ECU	N/A

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	A	Ignition cycle	Data Transmission Integrity Check	Lane Departure Warning torque to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any content corruption.	A	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-02	Standard RAM test to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on (e. G. walking 1s test, RAM pattern test, Refer to RAM and processor vendor recommendations)	A	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the 'test_status' signal.	A	MEMORYTES T	Activation_status = 0
Software Safety Requirement 05-04	In case any fault is indicated via the 'test_status' signal the INPUT_LDW_PROCESSING shall set an error on the error_status_input(=1) so that the Lane Departure Warning functionality is deactivated and the LDW_Torque_Req is set to zero.	A	LDW_SFETY_ INPUT_PRO CESSING	Activation_status = 0

Refined Architecture Diagram

[Instructions: Include the refined system architecture. Hint: The refined system architecture should include the system architecture from the end of the software and hardware lesson, including all of the ASIL labels.]

