Aristo: Allen Al Challenge

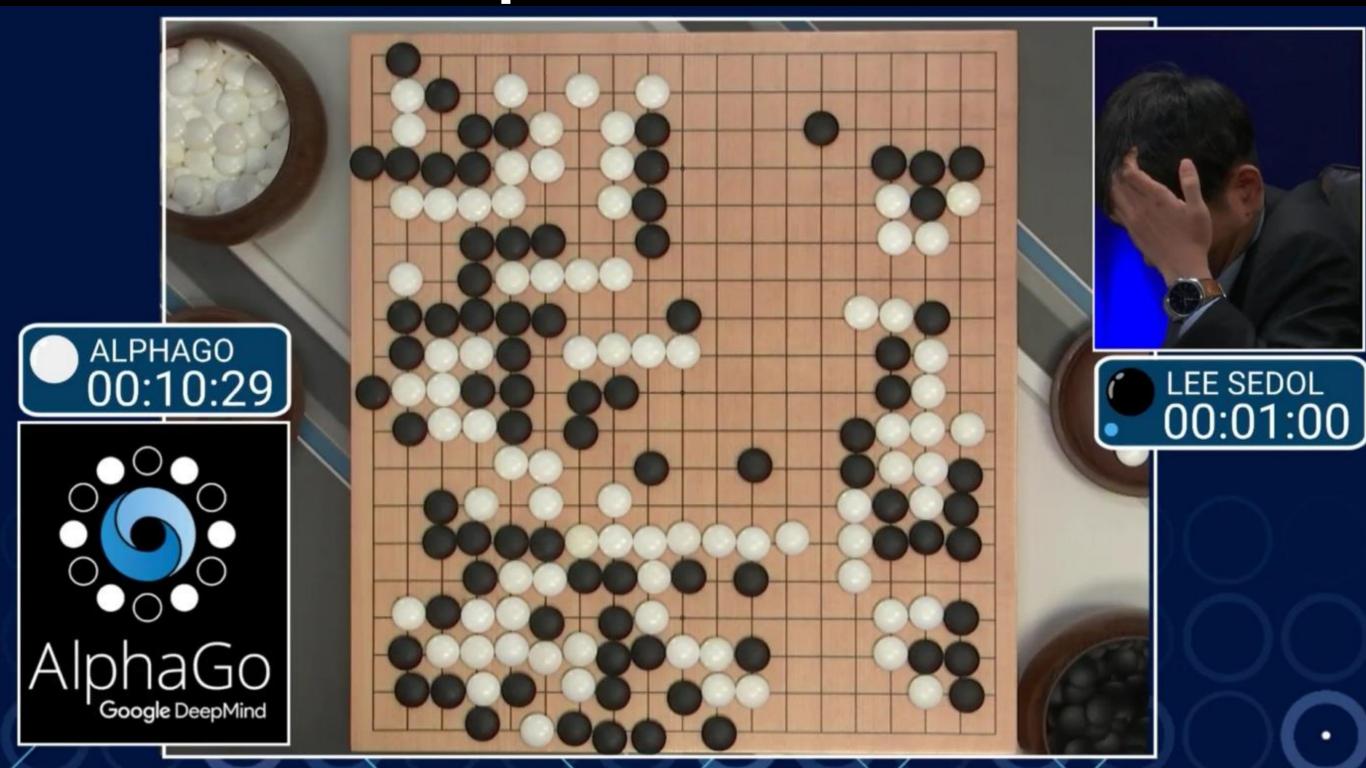
1996: Deep Blue



VS



2016: AlphaGo



Are these computers smarter than humans?

Are these computers INTELLIGENT?

Turing test

Inventor: Alan Turing

Year: 1950

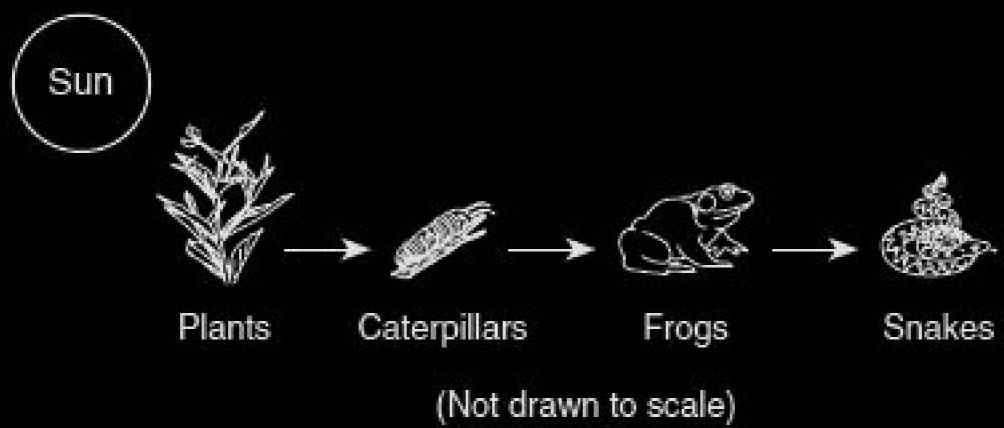
Test: Convince a human that it is chatting with another human instead of a computer

TURING TEST EXTRA CREDIT: CONVINCE THE EXAMINER THAT HE'S A COMPUTER. YOU KNOW, YOU MAKE SOME REALLY GOOD POINTS. I'M ... NOT EVEN SURE WHO I AM ANYMORE.

If a computer can solve the Turing test, is it truly intelligent? If a computer can solve the Turing test, is it truly intelligent?

No.

An example



If the population of snakes increases, the population of frogs will most likely

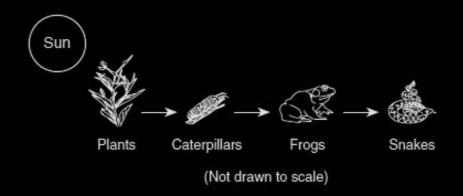
- (A) decrease
- (B) increase
- remain the same

An example

Target: 4th grader

Goal: Interpreting a figure and world modelling

Problem: Not factoid questions and requires language understanding



If the population of snakes increases, the population of frogs will most likely

- (A) decrease
- (B) increase
- (C) remain the same

Expectations

Wide variety of questions

Complex questions

Commonsense and world knowledge

Acquire knowledge scalably

Why 4th grade tests?

Measurable /

Graduated /

Not game-able ✓

Ambitious but realistic <

Motivating

Tackling the problem

Artificial Intelligence



IMAGE RETRIEVAL

TEXT-BASED KNOWLEDGE EXTRACTION

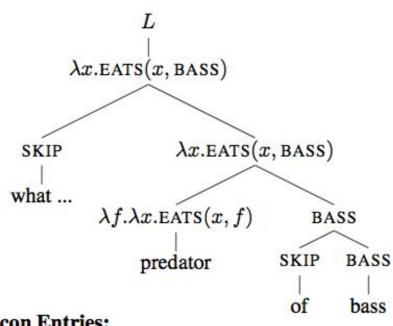
Input: Scientific papers

Step 1: Find the caption (keywords)

Removing false positives (filters)

Removing false positives (filters)

- 1. All caps
- 2. Abbreviated
- 3. Occupy a single line
- 4. Uncommon font
- 5. Left aligned to the text beneath them



Lexicon Entries:

predator := $N/NP : \lambda f. \lambda x. EATS(x, f)$

bass := NP : BASS

Figure 1: Parse tree of a training example and the lexicon entries derived from it.

the parser and thereby determines the set of meaning representations that can be produced for any given sentence. Therefore, a good lexicon is necessary to achieve both high accuracy and parsing speed. However, the lexicon is unobserved in real semantic parsing applications, leading us to ask: how do we learn a lexicon for a semantic parser?

Input: Scientific papers

Step 1: Find the caption (keywords)

Step 2: Classify regions

Text on position (filters)

lmages on tags in metadata

Classify figure text:

- 1. Graphic Overlap
- 2. Vertical Text
- 3. Wide-Spaced Text (Tables)
- 4. Line Width
- 5. Small Font
- 6. Margin Alignment

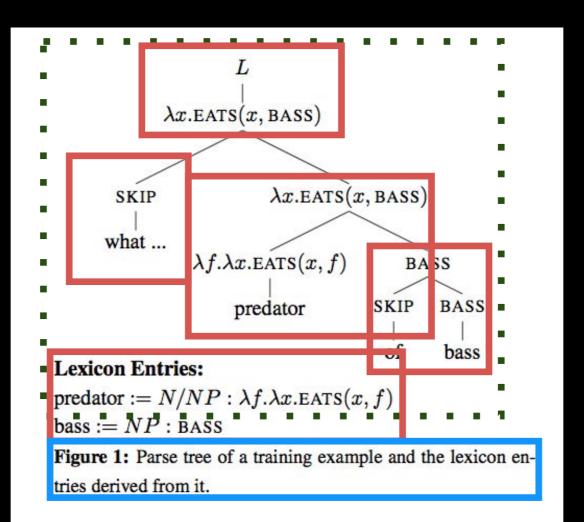
Input: Scientific papers

Step 1: Find the caption (keywords)

Step 2: Classify regions

Text on position (filters)

lmages on tags in metadata



the parser and thereby determines the set of meaning representations that can be produced for any given sentence. Therefore, a good lexicon is necessary to achieve both high accuracy and parsing speed. However, the lexicon is unobserved in real semantic parsing applications, leading us to ask: how do we learn a lexicon for a semantic parser?

Input: Scientific papers

Step 1: Find the caption (keywords)

Step 2: Classify regions and text

Step 3: Assign captions with titles through clustering to images

PDFFigures2.0 (Result)

k λ n_s n_{cys} ε_c pcior MCMC Shopping Cart 1000 1.5 4 10 20 continuous 2e4,1e3,10,30 Apartment 1000 1.5 4 10 20 categorical 5e3,1e3,10,1

Table 2. Table of the relevant algorithm parameters for each experiment. k: number of nearest neighbors (LWR,OO-LWR), \(\lambda\): bandwidth (LWR,OO-LWR), \(\tau_a\): number of section (OO-LWR), \(\tau_{aa}\): number of rayeast collision tests per sector (OO-LWR), \(\tau_a\): collision radius (OO-LWR), prior: type of prior (PBRL), MCMC: sampler parameters (iterations, burn-in, thin, number of chains) (PBRL).

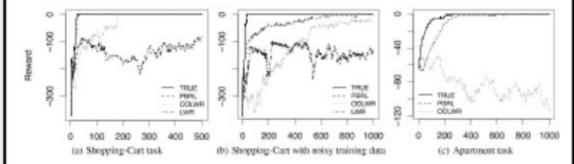


Figure 4. Online performance of various agents under different domain sizes and training conditions.

PBRL is complementary to the existing controls literature.

7. Discussion and Conclusions

In this paper we presented two physics-inspired approaches to modeling object dynamics for physical domains. The first, OO-LWR, leveraged only the geometric properties of physical dynamics, and the second extended this by exploiting modern physical simulation methods. Our results suggest that PBRL has a learning bias which is well matched to RL tasks in physical domains.

An example of a reasoning pattern enabled by a PBRL representation is illustrated in Fig. 5, which depicts a Navigation Among Movable Obstacles (NAMO) problem (LaValle, 1998). In NAMO the task is to find a minimum-cost path to a goal position which may be obstracted by movable obstacles. If the robot begins with no knowledge of the dynamics of these obstacles, it can benefit from the learning efficiency of the PBRL approach. We demonstrated this in (Levihn et al., 2012; 2013) in which a pre-liminary version of PBRL enabled a robot to quickly infer that a round table is indeed static, without having to try every action at its disposal.

Extending this work will require broadening the set of physical models supported by a single PBRL prior. However, this greater expressiveness comes at the cost of a larger parameter space. In order to be feasible for online applications, our goal is to find the right balance between over-precise physical models which are brittle and hard to fit, and coarse models that lack expressive power. We feel that the wheel model presented here provides such an ex-

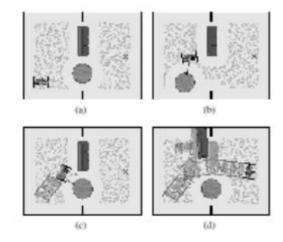
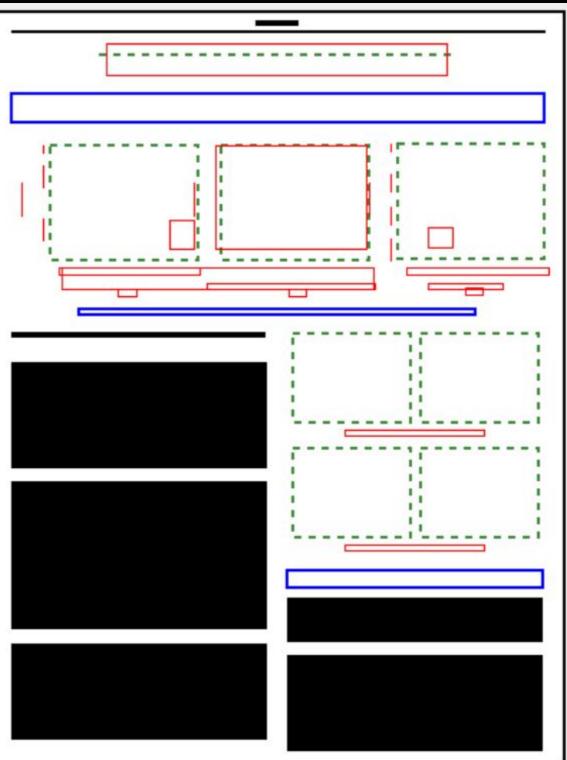


Figure 5. (a) Initial state (b) expected outcome (c) actual outcome; model updated (d) final solution

ample for furniture-like applications. However, in realworld scenarios, it may be useful to incorporate the flexibility of non-parametric methods into a PBRL approach, in order to guard against model mis-specification.

More generally, PBRL can be viewed as an ontological constraint on the world model: it is governed by the laws of physics. We hope that this approach helps to close the representational gap between the sorts of models used in Reinforcement Learning and the models that robotics engineers use in practice. If successful, this approach may yield opportunities for learning representations that are currently engineered by hand in robotics.



Possible approach:

Input: 4th grade textbooks

Step 1: Match patterns with text to find relations between concepts

Step 2: Translate matched patterns (+ variants) to formal logic language

Step 3: Store knowledge as logical statements in knowledge base

Input: 4th grade textbooks

Step 1: Match patterns with text to find relations between concepts

"Mechanical energy is produced when two objects move together."



Step 2: Translate matched patterns (+ variants) to formal logic language



forall m, t, o

isa(m, "move"), isa(t, "together"), isa(o, "two objects"), agent(m,o), arg(m,t) -> exists p, e

isa(p, "produce"), isa(e, "Mechanical energy"), agent(p,o), object(p,e), condition(p,m).

Step 2: Translate matched patterns (+ variants) to formal logic language

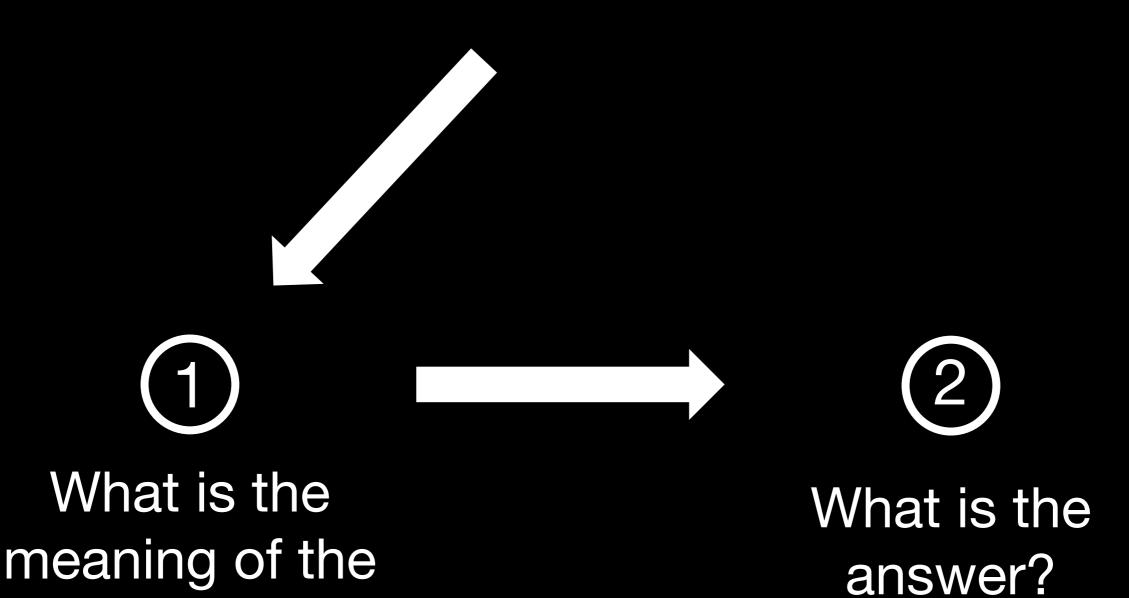
forall m, t, o
isa(m,"move"), isa(t,"together"), isa(o,"two objects"), agent(m,o), arg(m,t)
-> exists p, e
isa(p,"produce"),isa(e,"Mechanical energy"), agent(p,o), object(p,e),



condition(p,m).

Knowledge Base

Answering questions



question?

1. What is the meaning?

- A question == A query for some piece of data
- Goal: Construct a logical query that matches the question
- One approach: Use a probabilistic context-free grammar

Refresher: CFG

Production rules:

- (1) [S] -> [Subject] [Verb] [Object]
- (2) [Subject] -> My dog
- (3) [Subject] -> Arnold Schwarzenegger
- (4) [Verb] -> likes
- (5) [Verb] -> hates
- (6) [Object] -> treats
- (7) [Object] -> Sarah Connor

Constructing a sentence:

```
[S]
↓ (1)
[Subject] [Verb] [Object]
↓ (2)
My dog [Verb] [Object]
↓ (4)
My dog likes [Object]
↓ (7)
My dog likes Sarah Connor
```

Training Example:

1. Model weak supervision. Add L to the grammar as a nonterminal and add a unary rule $L \to \ell$ for all $\ell \in L$.

Generated Grammar:

```
Unary rules:

L \to \lambda x. \text{EATS}(x, \text{BASS})

L \to \lambda x. \text{CAUSE}(\text{INCREASE}(\text{BASS}), \text{INCREASE}(x))
```

Training Example:

```
w = What is the predator of bass ?

L = \{\lambda x. \text{EATS}(x, \text{BASS}), \\ \lambda x. \text{CAUSE}(\text{INCREASE}(\text{BASS}), \text{INCREASE}(x)), \\ \dots\}
```

2. Enumerate logical form splits. For all $\ell \in L$, perform a depth-first search over logical forms starting at ℓ . To explore a logical form f during the search, use SPLIT(f) to produce a collection of g, h pairs. For each g, h pair, add the binary rules $f \to g h$ and $f \to h g$ to the grammar, then add g and h to the search queue for later exploration.

Training Example:

```
\mathbf{w} = \text{What is the predator of bass?}
L = \{\lambda x. \text{EATS}(x, \text{BASS}), \\ \lambda x. \text{CAUSE}(\text{INCREASE}(\text{BASS}), \text{INCREASE}(x)), \\ \dots\}
```

Generated Grammar:

Nonterminal rules:

```
\lambda x. \text{EATS}(x, \text{BASS}) \to \text{BASS} \ \lambda f. \lambda x. \text{EATS}(x, f)
\lambda x. \text{EATS}(x, \text{BASS}) \to \lambda f. \lambda x. \text{EATS}(x, f) \ \text{BASS}
```

Training Example:

3. Create lexicon entries. Add a terminal rule $f \to w$ to G for every word in the question, $w \in \mathbf{w}$, and logical form f encountered during the search above.

Generated Grammar:

Terminal rules:

$$\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{what}$$

 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{is}$

Training Example:

4. Allow word skipping. Add a special SKIP non-terminal, along with the rules $|f \rightarrow f|$ SKIP, $f \rightarrow SKIP$ f and SKIP $\rightarrow w$ for all logical forms f and words $w \in \mathbf{w}$.

Generated Grammar:

Unary rules:

 $L \to \lambda x.\text{EATS}(x, \text{BASS})$

 $L \to \lambda x$.CAUSE(INCREASE(BASS), INCREASE(x))

Nonterminal rules:

 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{BASS} \ \lambda f. \lambda x. \text{EATS}(x, f)$

 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \lambda f. \lambda x. \text{EATS}(x, f)$ BASS

BASS → SKIP BASS

...

Terminal rules:

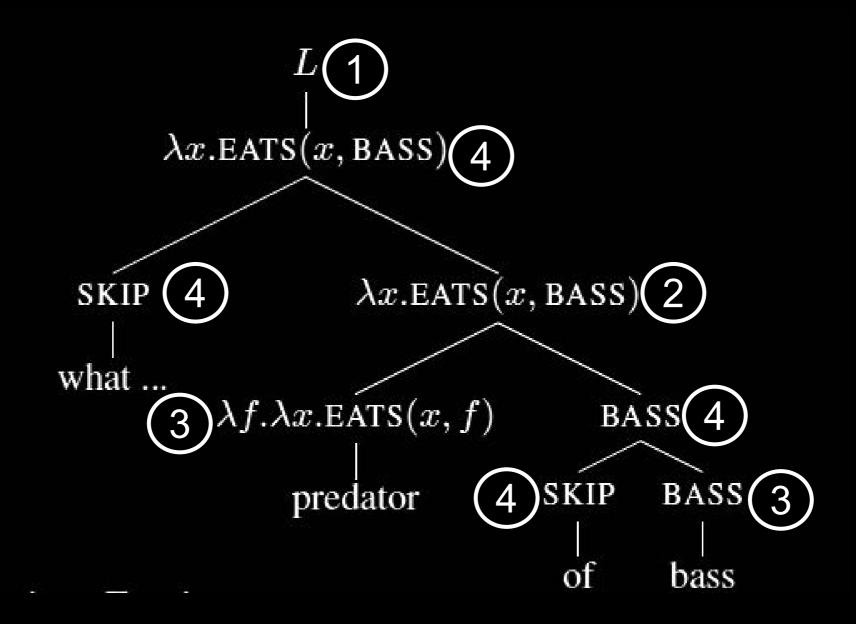
 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{what}$

 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{is}$

SKIP \rightarrow what

• • •

Training the model



Training the model

Nonterminal rules:

$$\lambda x. \text{EATS}(x, \text{BASS}) \to \text{BASS} \ \lambda f. \lambda x. \text{EATS}(x, f)$$

 $\lambda x. \text{EATS}(x, \text{BASS}) \to \lambda f. \lambda x. \text{EATS}(x, f) \text{ BASS}$
 $\text{BASS} \to \text{SKIP BASS}$



$$P(t|L;\theta) = \prod_{\substack{(f \to g \ h) \in t}} P(f \to g \ h;\theta) \times$$

$$\prod_{(f \to w) \in t} P(f \to w; \theta)$$



Terminal rules:

$$\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{what}$$

 $\lambda x. \text{EATS}(x, \text{BASS}) \rightarrow \text{is}$
 $\text{SKIP} \rightarrow \text{what}$

Jayant Krishnamurthy. Probabilistic models for learning a semantic parser lexicon. InProceedings of NAACL-HLT, pages 606–616,2016.

Training the model

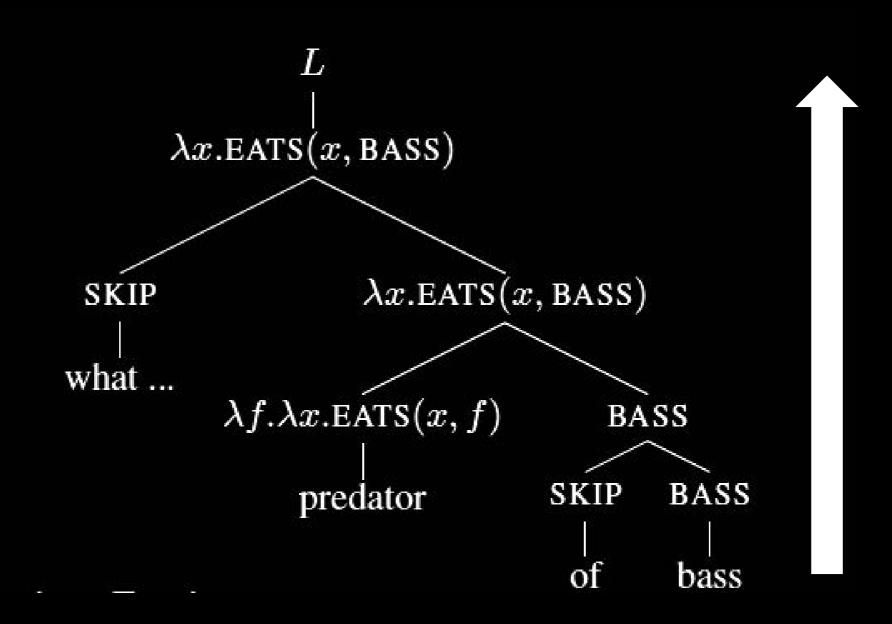
$$P(\mathbf{w}|L;\theta) = \sum_{t} P(\mathbf{w}, t|L;\theta)$$

The probability of generating a question from the given label

Goal: Optimise probabilities of applying each rule to maximise this for each training example

Method: Expectation Maximisation

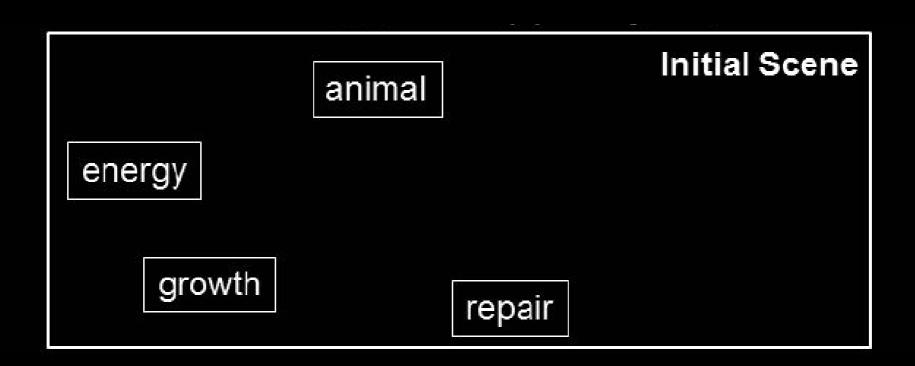
Applying the model



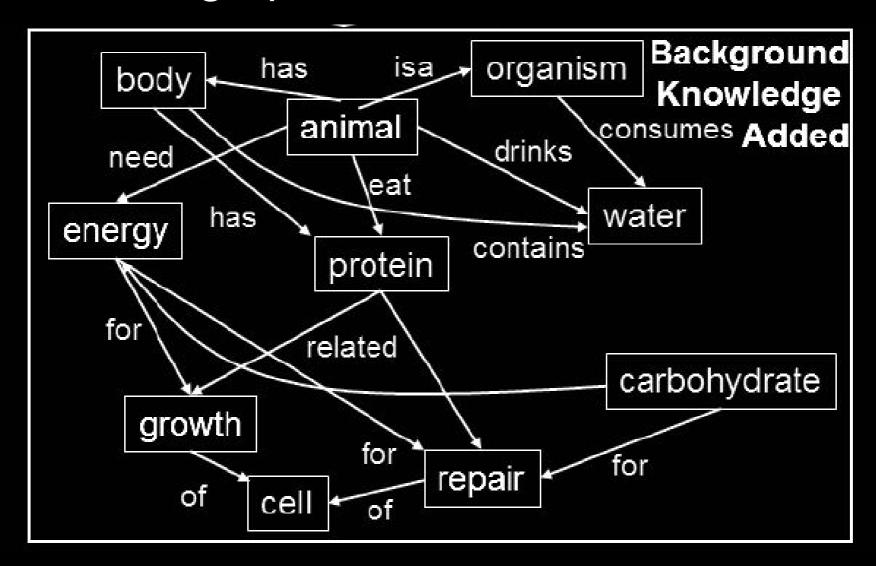
Input: A multiple-choice question

Example: "Animals get energy for growth and repair from (A) food, (B) water (C) ... "

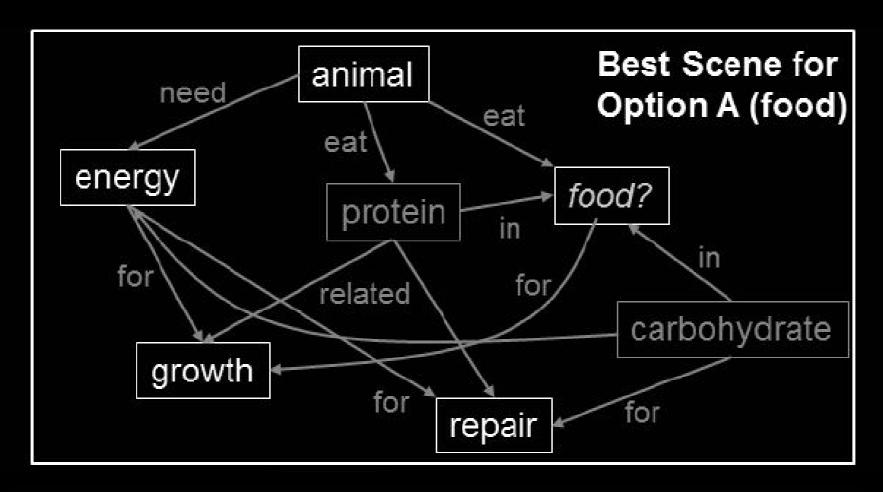
Step 1: Analyse the question and find important concepts (see previous algorithm)



Step 2: Add background knowledge from knowledge base to form a graph



Step 3: Add option and prune graph



$$score(w) = \sum_{kw \in K} IS(kw) * rel(kw, w)$$

Step 4: Score option based on coherence within knowledge graph

$$coherence(w) = \sum_{w' \in \{(w,r,w')\}} rel(w,w')$$

The chosen answer with the highest coherence value is chosen

DEMO

http://aristo-demo.allenai.org https://github.com/allenai/aristo-mini

Elasticsearch

What? Commercial search engine

Scalable, near real-time and multitenancy

How? JSON and Java API



Stemming

Domain: Natural Language Processing

What?

- 1. Removes stopwords
- 2. Removes Morphological affixes

Imports the remainder to Information Retrieval index

Stemming (Example)

Once a player commits five fouls, he is no longer allowed to play in the game, and a player on the bench must go in the game immediately.

Stemming (Example)

player commits five fouls, no longer allowed play game, player on bench must go game immediately.

Stemming (Example)

player commit five foul, no longer allow play game, player on bench must go game immedi.

Querying

"What color is the sky? red"

"What color is the sky? green"

"What color is the sky? blue"

Querying

"What color is the sky? red" Score: 0.3

"What color is the sky? green" Score: 0.1

"What color is the sky? blue" Score: 0.6

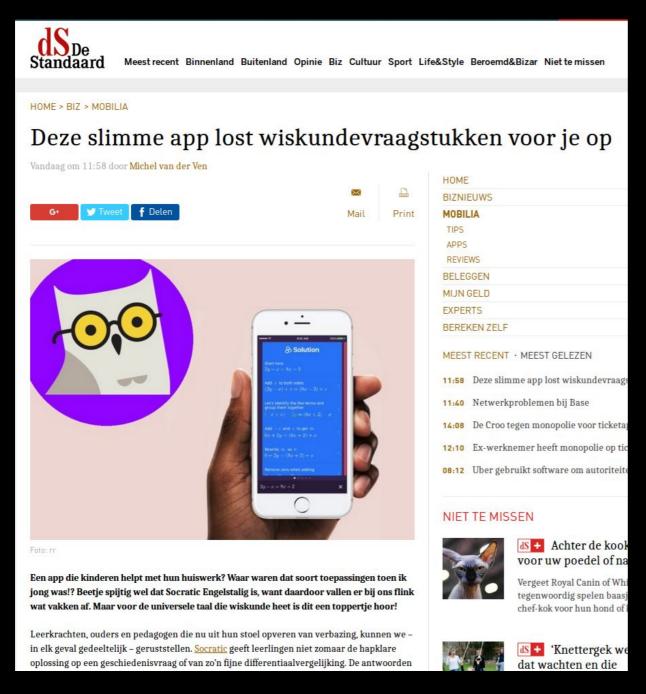
Score function

```
score(q,d)
             queryNorm(q)
           · coord(q,d)
           . 2 (
                  tf(t in d)
                                0
                · idf(t)<sup>2</sup>
                t.getBoost()
                                8
                norm(t,d)
             ) (t in q)
```

- -> Score =< 1
- -> Large overlap

- -> Frequency
- -> Inverse frequency
- -> Score =< 1

Recent developments



https://socratic.org/

http://www.standaard.be/cnt/dmf20170228_02755032