





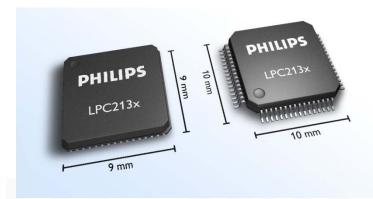
Microcontroller Overview



LPC213x Series Overview

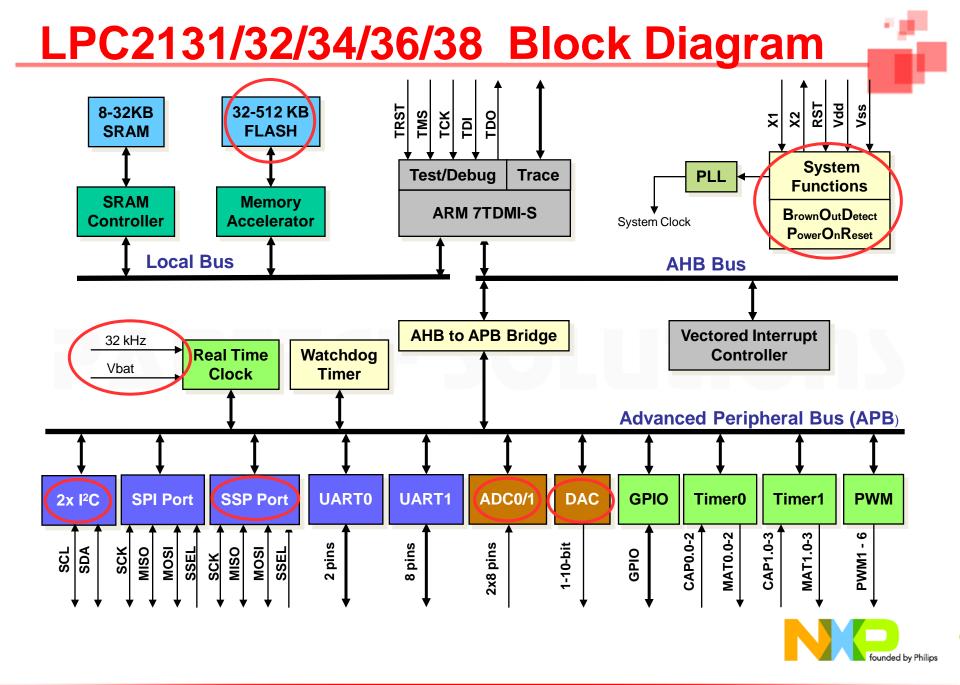
- **ARM**
- 1

- 60 MHz Operation (54MIPS)
 from both on-chip Flash and SRAM
- 2 I2C, 2 UARTs, 1 SPI, 1 SPI/ SSP
- Two 8-ch 10-bit ADCs
- One 10-bit DAC
- 4 Timers (Capture/Match/PWM/WDT)
- 47 I/O pins (5V tolerant)
- 3.3V Single-Voltage Supply
- ▶ 32KHz RTC, BOD, POR
- User-code security
- Real-time Debugging & Trace
- ▶ ISP, IAP, Parallel Programmer Support
- Tiny Packages: QFP64 (10 x 10 x 1.4 mm), HVQFN64 (9 x 9 x 0.85 mm)



	Flash	SRAM	ADC	DAC	Pkg
LPC2131	32KB	8KB	1		QFP64
LPC2132	64KB	16KB	1	1	QFP64 QFN64
LPC2134	128KB	16KB	2	1	QFP64
LPC2136	256KB	32KB	2	1	QFP64
LPC2138	512KB	32KB	2	1	QFP64 QFN64





Extending the success to LPC214x

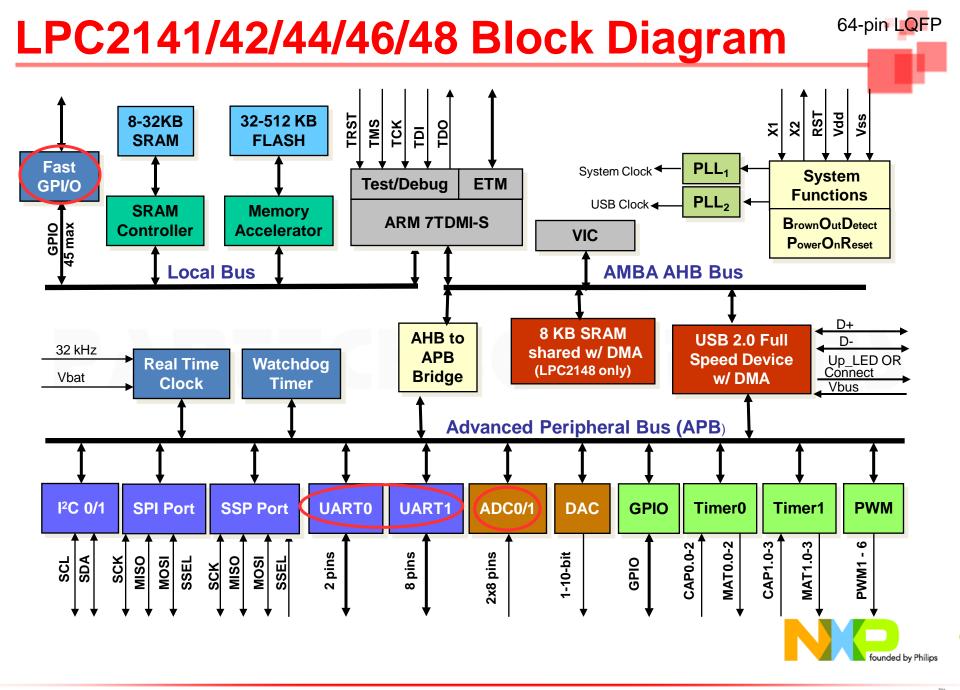




- ▶ Same device features as LPC213x
- ▶ USB 2.0 device
- ▶ Fast GPIO's
- ADC improvements
- ▶ Enhanced UART







NXP Implementation



Memory Addressing

- 2. System Control Block
- 3. General Purpose I/O / Pin Connect Block
- 4. Vectored Interrupt Controller
- 5. Integrated Peripherals

Timer 0 / Timer 1, UART 0 / UART 1, I²C, SPI, PWM, RTC, Watchdog, ADC, USB, CAN, Ethernet, SD, IIS, GPDMA



LPC2000 Memory Map



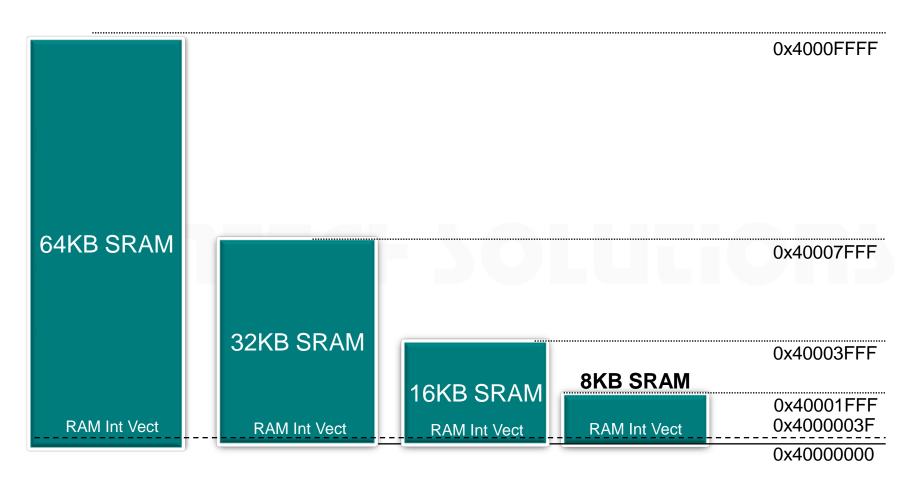
4.0 GB			_
3.75 GB	AHB Peripherals	0xFFFF FFFF 0xF000 0000	
3.5 GB	VPB Peripherals	0xEFFF FFFF 0xE000 0000	
3.5 GB	Reserved for External Memory	<u> </u>	Memory blocks not drawn to scale!
3.0 GB		0x8000 0000	
2.0 GB	Boot Block (re-mapped from On-Chip Flash)	0x7FFF E000	
	16 KB On-Chip Static RAM, USB	0x7FE0 0000	RAM on AHB
	16 KB On-Chip Static RAM, ETHERNET	0x7FD0 0000	
	Reserved for On-Chip Memory		
	16 / 32 / 64 KB On-Chip Static RAM	0x4000 nnnn* 0x4000 0000	RAM on local bus -> fast access!
1.0 GB		0x3FFF FFFF	(
	Reserved for On-Chip Memory		
0.0 GB	8KB 1MB On-Chip Non-Volatile Memory	0x000m FFFF 0x0000 0000	

Not valid for LPC2888/0



SRAM: 8, 16, 32 or 64 KB



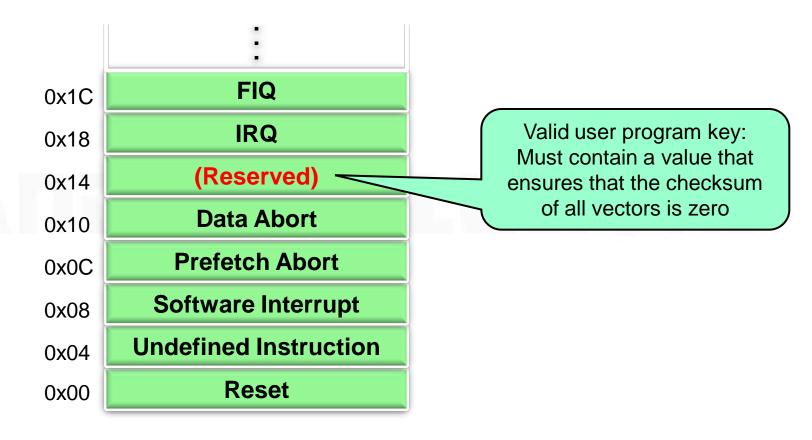




Exception Vectors



Vector Table







- Memory Addressing
- 2. System Control Block
- 3. General Purpose I/O / Pin Connect Block
- 4. Vectored Interrupt Controller
- 5. Integrated Peripherals

Timer 0 / Timer 1, UART 0 / UART 1, I²C, SPI, PWM, RTC, Watchdog, Ethernet, SD, IIS, GPDMA



System Control



- Includes a number of important system features
 - Power Control
 - Memory mapping configuration
 - Oscillator
 - PLL
 - VPB (VLSI Peripheral Bus) divider
 - Reset (active low)
 - Wakeup Timer
 - External Interrupts

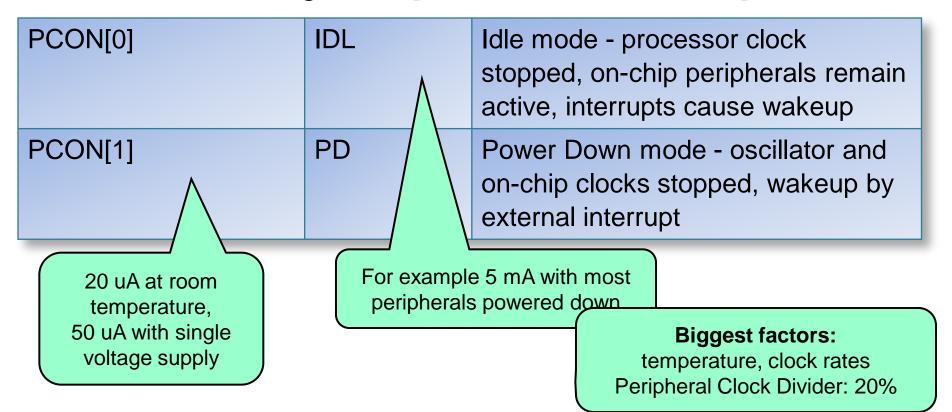


Power Control (1)



• Power Control Register [PCON – 0xE01FC0C0]

R/W







Power Control (2)



- When disabled, peripherals are switched off to conserve power
- Power Control for Peripherals Register

[PCONP - 0xE01FC0C4]

R/W

PCONP 1	PCTIM0	Enable Timer0	
PCONP 2	PCTIM1	Enable Timer1	
PCONP 3	PCURT0	Enable UART0	
PCONP 4	PCURT1	Enable UART1	Each peripheral
PCONP 5	PCPWM0	Enable PWM0	typically below 1mA
PCONP 7	PCI2C	Enable I2C	
PCONP 8	PCSPI	Enable SPI	
PCONP 9	PCRTC	Enable RTC	





Power Control (3)



Power Control for Peripherals Register cont'd

PCONP 8	PCSP0	Enable SPI0		
PCONP 9	PCRTC	Enable RTC		
PCONP 10	PCSPI1	Enable SPI1		
PCONP 11	PCEMC	Enable External Memory Controller		
PCONP 12	PCAD	Enable A/D-Converter		
PCONP 13	PCCAN1	Enable CAN Controller 1	Acceptance Filter — enabled with any CAN Controller	
PCONP 14	PCCAN2	Enable CAN Controller 2		
PCONP 15	PCCAN3	Enable CAN Controller 3		
PCONP 16	PCCAN4	Enable CAN Controller 4 CAN periphera		
			typically below 2mA	



Memory Mapping Control 1



- ▶ Re-mapping of Exception Vectors
 - always appear to begin at 0x0000 0000
 - but can be mapped from different sources:
 - User Flash
 - Exception Vectors are not re-mapped and reside in Flash

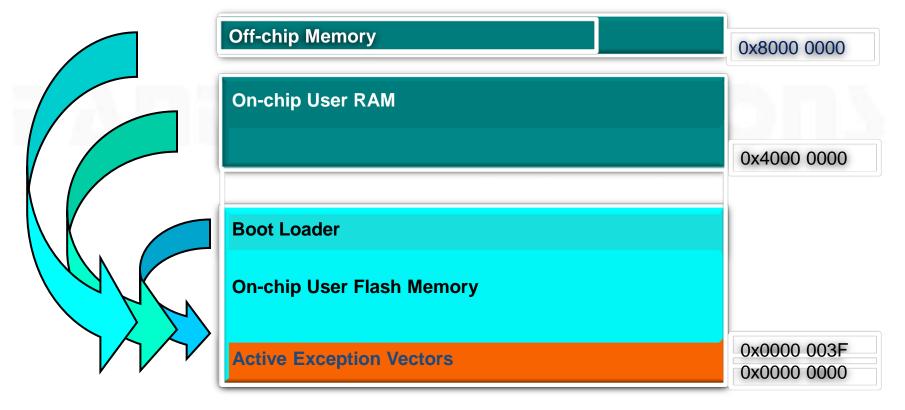




Memory Mapping Control (2)



- Boot Loader
 - Always executed after reset. Exception Vectors re-mapped from Boot Block
- User RAM
 - Exception Vectors are re-mapped from RAM

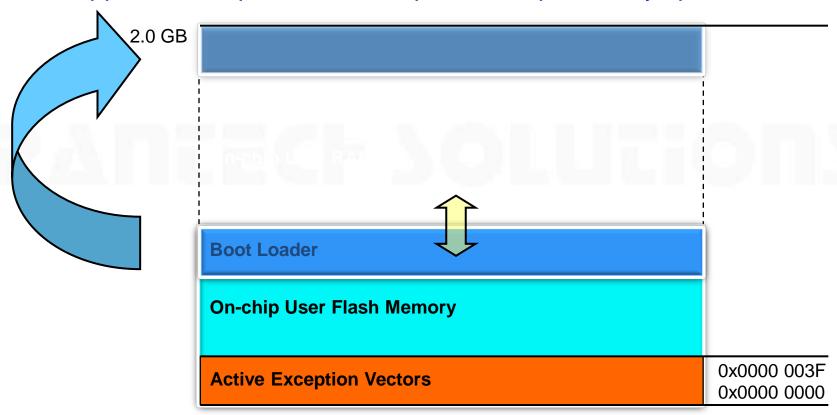




Memory Mapping Control (3)



- ▶ Re-mapping of Boot Block
 - mapped from top of Flash to top of on-chip memory space





Memory Mapping Control Register





Memory Mapping Control [MEMMAP – 0xE01FC040]
 R/W

MEMMAP 1:0	MAP 1:0	00: Boot Loader Mode	
		01: User Flash Mode (no re-mapping)	
3 A D =		10: User RAM Mode	
		11: External Memory	

Selects the memory being mapped to address zero





Phase Locked Loop (1)

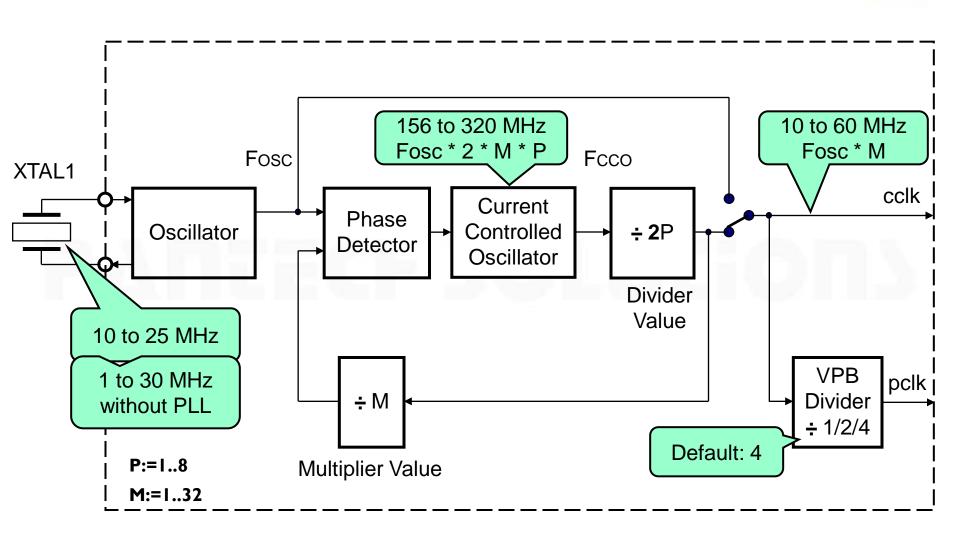


- ▶ 10 to 25 MHz input clock frequency
- Output frequency from 10 MHz up to the max.
- PLL bypassed on reset
- PLL lock indicator can be used as an interrupt to connect the PLL once it is locked
- PLL programming requires a special feed sequence (like the watchdog) for safety



PLL(for old families LPC21xx and LPC22xx)







General Purpose I/O (1)



▶ Pins available for GPIO:

▶ LPC21xx/22xx

48-pin devices: 32

64-pin devices: 46

– 144 pin devices:76 (max.) (with external memory)

112 (w/o external memory)

- ▶ LPC23xx/24xx
 - Up to 160 GPIO pins, all implemented as fast GPIOs, with 64 GPIO interrupts (plus 4 other external interrupts).
- Shared with
 - Alternate functions of all peripherals
 - Data/address bus and strobe signals for external memories







- Memory Addressing
- 2. System Control Block
- **3.** General Purpose I/O / Pin Connect Block
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Timer 0 / Timer 1, UART 0 / UART 1, I²C, SPI, PWM, RTC, Watchdog, Ethernet, SD, IIS, GPDMA



General Purpose I/O (2)



- Direction control of individual bits
- Separate set and clear registers
- ▶ Pin value and output register can be read separately
- Slew rate controlled outputs (10 ns)
- ▶ 5 registers used to control I/Os



General Purpose I/O (3)



Register

IODIR

IOPIN The current state of the port pins is read from this register

IOSET Writing "1" sets pins **high**, writing "0" has no effect

IOCLR Writing "1" sets pins low and clears corresponding bits in IOSET

Port pin direction: 0 = INPUT 1 = OUTPUT

Selects function of pins (Pin Connect Block)

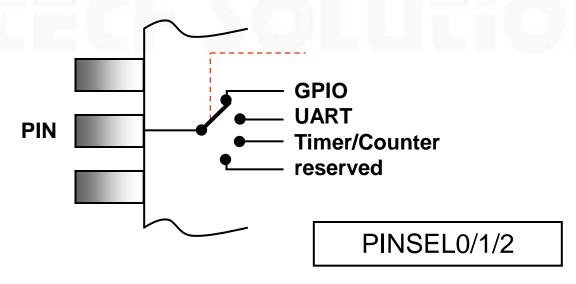
PINSELO/1 Selects function of pins (Pin Connect Block



Pin Connect Block (1)



- Many on-chip functions can use I/O pins
- Number of I/O-pins is limited
 - ⇒ I/Os can be configured to adapt various functions
- Configuration done by Pin Connect Block





Pin Connect Block (2)



▶ Pin Function Select Registers

- PINSEL0 and PINSEL1
 - Configuration of P0
 - Assign P0.0 ... P0.31 to GPIO or an alternate function (1 of max. 3)

- PINSEL2

(**not** available in 48-pin devices)

- Configuration of P1 (64/144-pin devices) and P2, P3 (144-pin devices)
- Select availability of debug and trace ports on Port1 pins
- Controls use of address/data bus and strobe pins (144-pin devices)
- Selection of additional ADC-inputs (144-pin devices)



Pin Connect Block (3)



Example:

Pin Function Select Register 0 [PINSEL0 - 0xE002C000)] R/W

PINSEL0 21:20	P0.10	00: GPIO Port 0.10
		01: RTS (UART1)
		10: Capture 1.0 (Timer 1)
		11: reserved





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Vectored Interrupt Controller

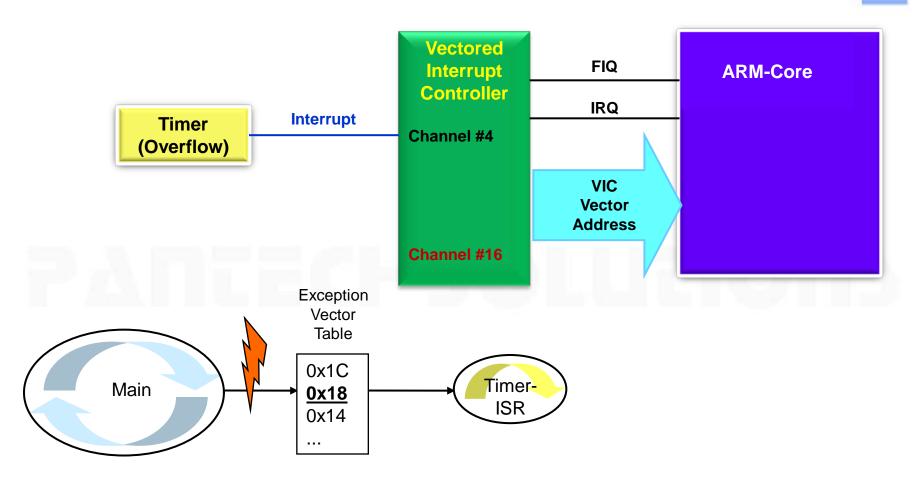


- ▶ ARM PrimeCell™
- 32 interrupt request inputs
- 16 IRQ interrupts can be auto-vectored
 - single instruction vectoring to ISR
 - dynamic software priority assignment
- ▶ 16 FIQ non-vectored interrupts
- Software interrupts



IRQ Interrupts





CONST = 0x0FF for LPC21xx, and LPC22xx 0x120 for LPC23xx, and LPC24xx



VIC - FIQ Interrupt



- FIQs have higher priority than IRQs
 - Serviced first
 - FIQs disable IRQs

- FIQ Vector is last in vector table (allows handler to be run sequentially from that address)
- ▶ FIQ mode has 5 extra banked registers, r8-12 (interrupt handlers must always preserve non-banked registers)







- Memory Addressing
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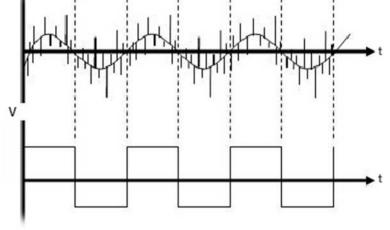
ADC

A/D Converter



Features

- 10 bit successive approximation analog to digital converter
- Multiplexed inputs
 - 4 pins (64-pin devices)
 - 8 pins (144-pin devices)
- Power down mode
- Measurement range 0V ... 3V
- Minimum 10 bit conversion time: 2.44 μs
- Burst conversion mode for single or multiple inputs
- Optional conversion on transition on input pin or Timer Match signal
- Programmable divider to generate required 4.5MHz from VPB clock





A/D Converter – Burst mode



- ▶ CLKS: bit 17, 18, 19 of ADCR select the number of clocks used per conversion and the accuracy
 - 000b: 11 clocks, 10 bits
 - 001b: 10 clocks, 9 bits
 - 010b: 9 clocks, 8 bits
 - 011b: 8 clocks, 7 bits
 - **—** ...
 - 111b: 4 clocks, 3 bits



ADC LPC213x/01, LPC214x



- Separate result register for each channel
 - Reduces the interrupt overhead by a factor of 8
- Measurement range of 0 V to 3 V
 - Separate voltage pins for analogue 3V supply (V3A) and analogue ground (VSSA)

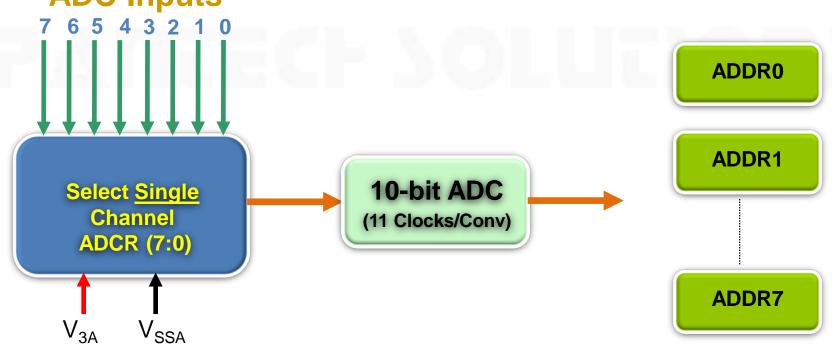




ADC – Software Controlled Mode



- All conversions are 10-bit and take 11 clocks
- ▶ 4.5MHz Maximum Clock
- Allows conversion to start on an external edge
 ADC Inputs



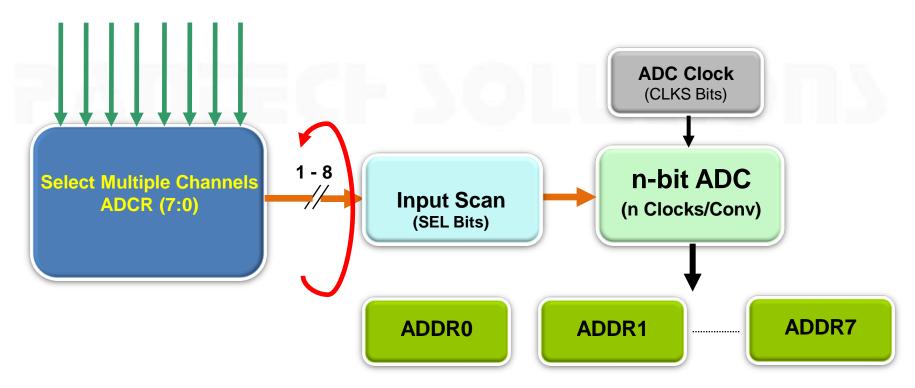


ADC – Burst Mode



- Result accuracy and speed are programmable
- Input selected by the SEL bits are scanned

ADC Inputs



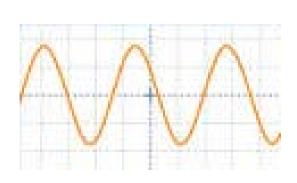


DAC

DAC (LPC213x, LPC214x, LPC23xx, LPC24xx)



- Enables the device to generate a variable analog output
- 10-bit resolution DAC with a buffered output
 - Last output value is held as long as DAC is on
- Register string architecture
- Output from Zero Volt to Reference Voltage in 1024 steps
- Selectable Conversion speed vs. power
 - Settling time 1us, up to 350uA
 - Settling time 2.5us, up to 700uA
- Selective power down





- •TIMERS
- •PWMs
- •RTC
- •WATCHDOG

Timers



Timer can be used to control the sequence of an event or process









Timer 0 and 1

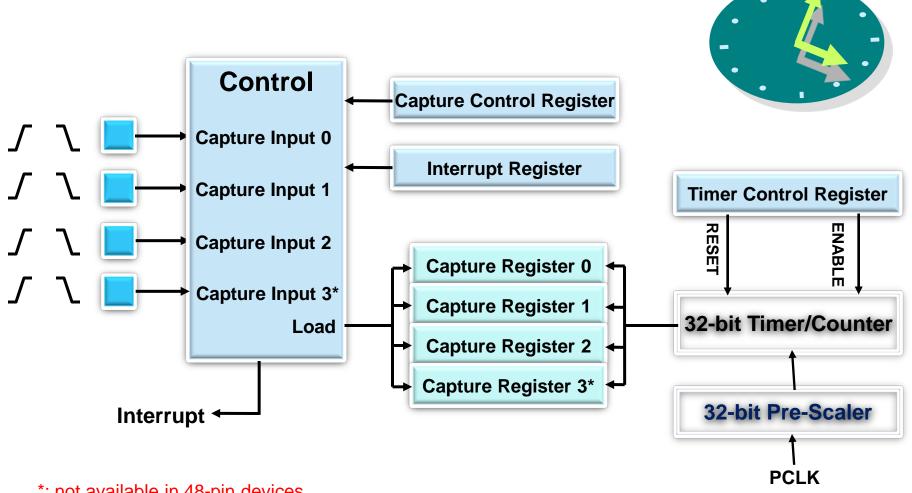
- ARM

- 32-bit Timer
- 32-bit Capture Registers and Capture Pins
 - Four on each timer (48-pin devices three on Timer 0 and four on Timer 1)
 - Capture event can optionally trigger an interrupt
- 32-bit Match Registers and Match Pins
 - Four on each timer (48-pin devices three on Timer 0 and four on Timer 1)
 - Interrupt, timer reset or timer halt on match
 - Match output can toggle, go high, go low or do nothing





Timer Capture







Pulse Width Modulator



- Dedicated 32-bit PWM timer
 - similar functionality to Timer0 / Timer1
- Three additional match registers for a total of 7
 - all PWM outputs have the same rate, which is programmable
 - allows up to 6 single edge controlled or 3 double edge controlled
 PWM outputs in any combination

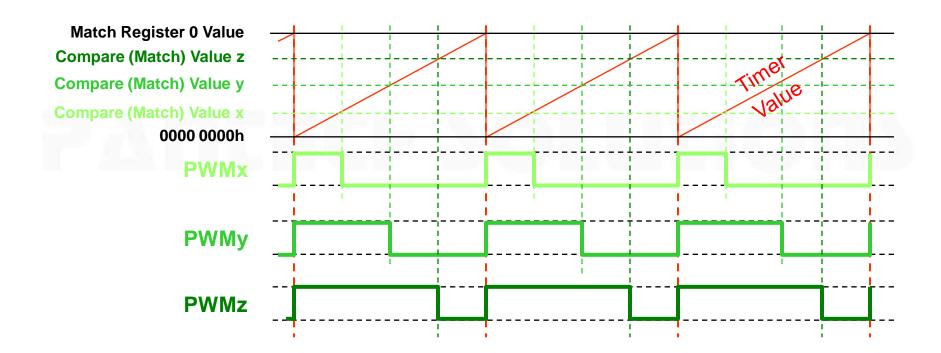




Single-Edge Controlled PWM



 PWM outputs all go high at the beginning of each cycle and go low on a Match



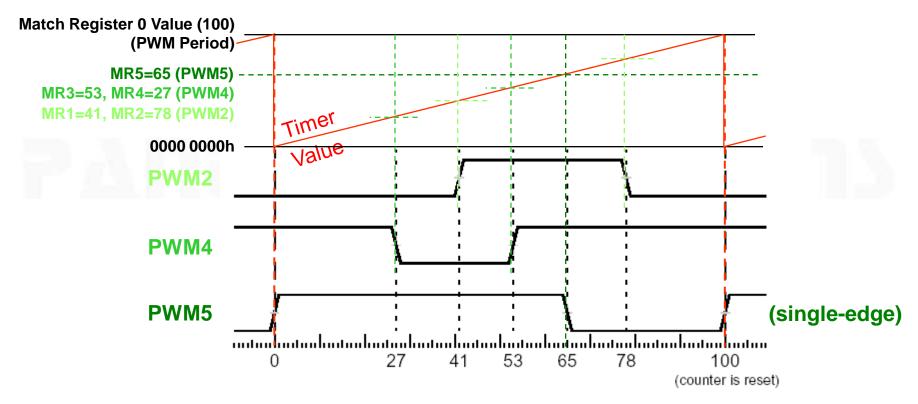




Double-Edge Controlled PWM



 Double edge controlled PWM outputs can have either edge occur at any position within a cycle





Real Time Clock (RTC)



- ▶ Full Clock/Calendar function with alarms
 - Dedicated 32-bit timer with 32-bit pre-scaler
 - Generates its own 32.768 kHz reference clock from any crystal frequency (Prescaler values need to be calculated)
 - Counts seconds, minutes, hours, day of month, month, year, day of week and day of year
 - Can generate an interrupt or set an alarm flag for any combination of the counters





Real Time Clock on newer devices



- Can be clocked by a separate 32.768KHz or by prescaler divider based on VPB clock
 - => RTC can run in Power Down mode

PANTECHSOLUTIONS

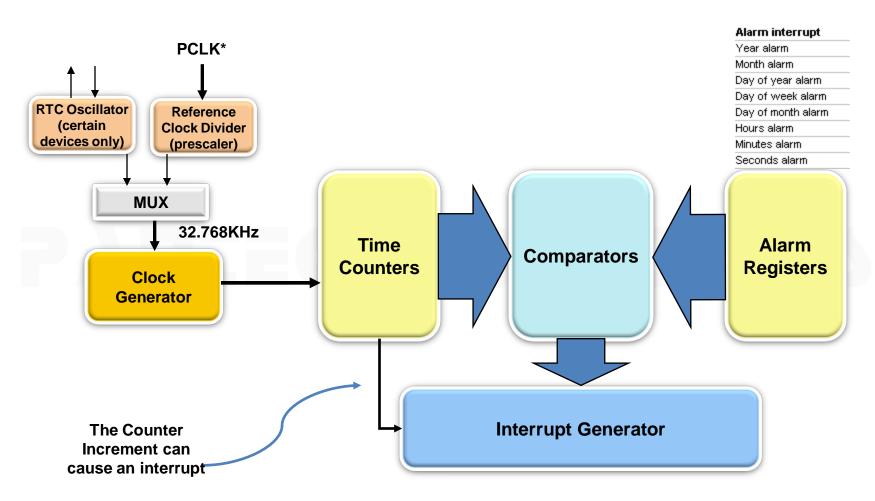
Separate supply pin Vbat which can be connected to battery or to the 3.3V supply





RTC Block Diagram





* keep in mind what the settings are for PLL and the VPB Divider

founded by Philips

Watchdog Timer



- Once activated, the Watchdog will reset the entire chip if it is not fed regularly
- ▶ Feed is accomplished by a specific sequence of data writes
- Watchdog flag allows software to tell that a watchdog reset has occurred
- Selectable overflow time (μs ... minutes)
- Debug Mode generates an interrupt instead of a reset
- Secure: watchdog cannot be turned off once it is enabled
- Watchdog Timer value can be read in one cycle



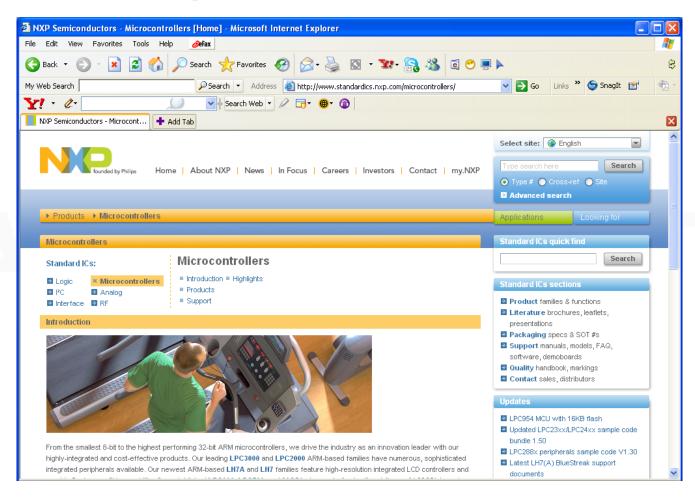


Helpful hints and links

Microcontroller Web Site



www.nxp.com/microcontrollers

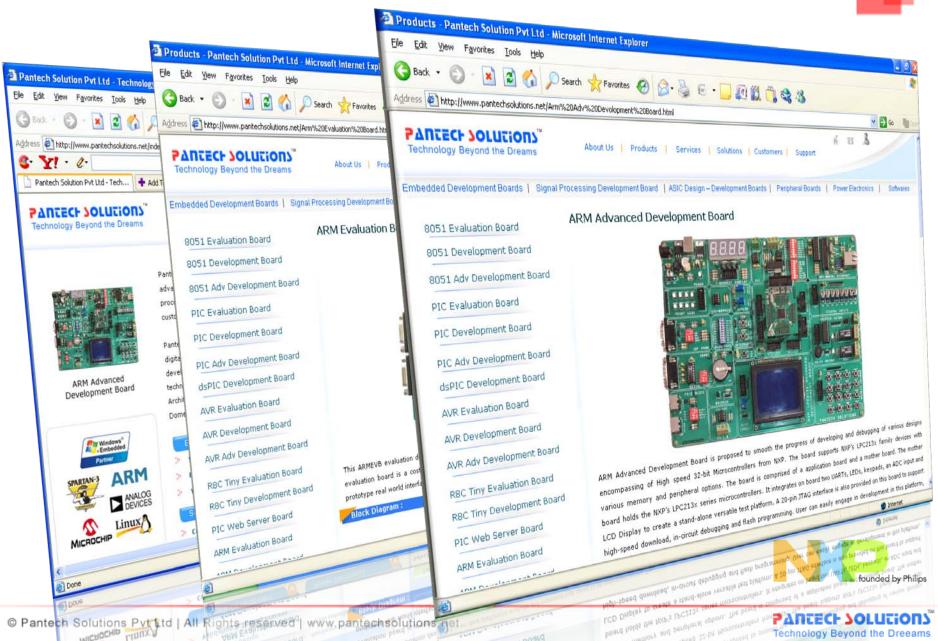






Product Link





LPC2000 User's Group – The #1 active microcontroller group on Yahoo YAHOO! Groups

Home

Activity within 7 days: 54 New Members - 309 New Messages

Description

The NXP (formerly Philips) LPC2000 family of ARM MCUs is sufficiently different from other ARM variants that I decided that a forum dedicated to it would be useful.



Message History

	Jan	Feb	Mar	Apr	May	Jun	Jul	Aug	Sep	Oct	Nov	Dec
2007	776	631	807	733	578	551	613	719	850	309		
2006	1039	930	1041	903	730	701	911	814	702	640	764	575
2005	592	577	551	550	385	436	418	377	471	754	1072	896
2004	328	545	344	286	364	335	322	178	299	427	393	571
2003											113	308

http://groups.yahoo.com/group/lpc2000/



Conclusion



- ▶ ARM7 is an open architecture
- ▶ On-Board Peripherals features, Advantages ARM7TDMI-S.
- Protocols Features.



Queries.....



