

APD - QuickSort

QuickSort - Sequential Solution

1. Statement

In the quicksort algorithm, a special element called “pivot” is first selected and the array or list in question is partitioned into two subsets. The partitioned subsets may or may not be equal in size. The partitions are such that all the elements less than the pivot element are towards the left of the pivot and the elements greater than the pivot is at the right of the pivot. The Quicksort routine recursively sorts the two sub-lists. Quicksort works efficiently and also faster even for larger arrays or lists.

2. Classes

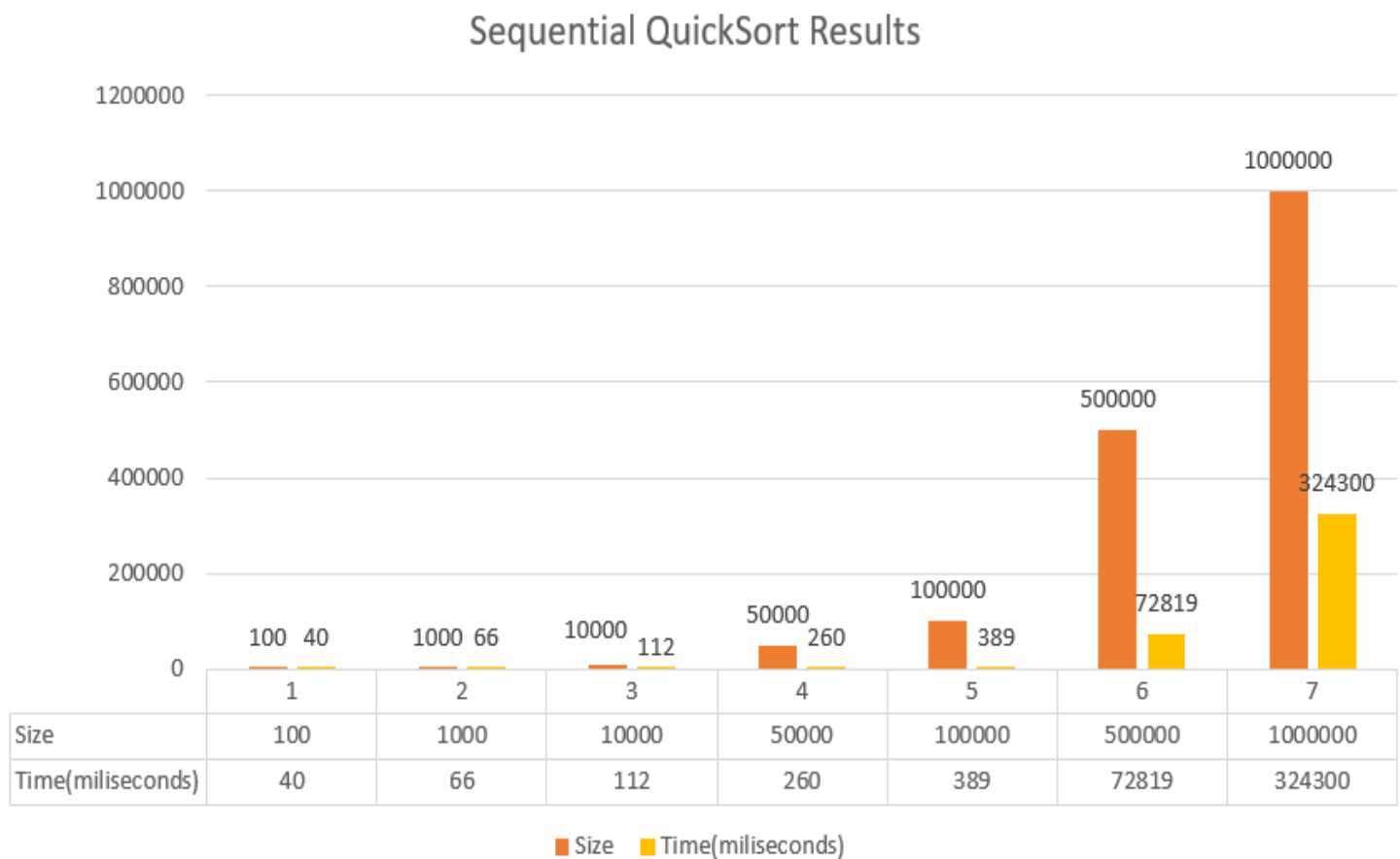
A total of three classes were used for the sequential solution of QuickSort:

- QuickSort - takes the array to be sorted as a parameter. This class has two methods:
 - **partition** - This function takes last element as pivot, places the pivot element at its correct position in sorted array, and places all smaller (smaller than pivot) to left of pivot and all greater elements to right of pivot;
 - **quicksort** - This is the main function that implements the quicksort algorithm. It finds the partition index and recursively calls quicksort for the two subparts created.
- FileManager - takes the size of the file as parameter (how many values are in that file):
 - **ReadFromFile** - returns an array containing the values read from the file that has the name “input(size).txt”;
 - **WriteToFile** - writes the values from the array given as parameter into the file with the name “output(size).txt”;
- Main - in the main program:
 - **FileManager** object is created in order to get a array with (size) elements;
 - **QuickSort** object is created in order to sort the array;
 - The FileManager object is used to put the values from the sorted array into a file;
 - The time is calculated from the start of the program to the end using **Instant** and **Duration** classes.

3. Platform Information

- Operation System: **Windows 10 Home**
- CPU: **i5-10210U**
 - Cores: **4**
 - Threads: **8**
 - Cache: **6 MB**
 - Base Frequency: **1.60 GHz**
 - Max Turbo Frequency: **4.20 GHz**
- GPU: **Intel(R) UHD Graphics**
- RAM: **8.0 GB at 2133 MHz running in dual channel mode**

4. Table and Chart



As it can be seen QuickSort is a very fast algorithm for inputs smaller than 100000 elements. The running time increases with increasing input size.

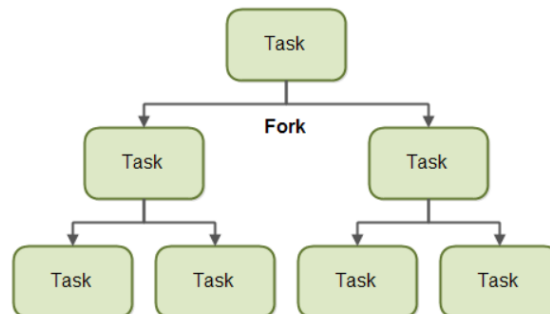
5. Work Plan for Parallel Solutions

- **Java Threads - ForkJoinPool**

Explanation: The fork and join principle consists of two steps which are performed recursively. These two steps are the fork step and the join step.

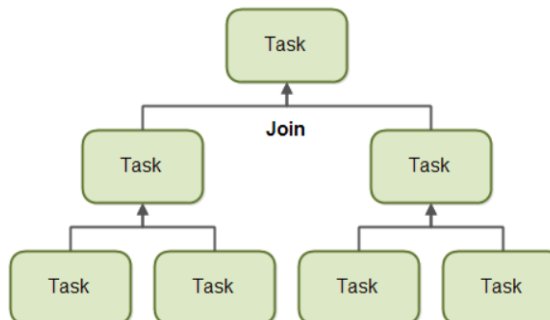
Fork

A task that uses the fork and join principle can *fork* (split) itself into smaller subtasks which can be executed concurrently. By splitting itself up into subtasks, each subtask can be executed in parallel by different CPUs, or different threads on the same CPU.



Join

When a task has split itself up into subtasks, the task waits until the subtasks have finished executing. Once the subtasks have finished executing, the task may join (merge) all the results into one result.



ForkJoinPool

The ForkJoinPool is a special thread pool which is designed to work well with fork-and-join task splitting.

Links:

- ❖ [Fork/Join Framework in Java](#)
- ❖ [Java Fork and Join using ForkJoinPool](#)
- ❖ [QuickSort using Multithreading](#)

6. [Github Repository](#)