

Problem [1]

(a)

$$\textcircled{1} \quad \gamma > 0, -2\gamma < 0$$

$\because \cos(t)$ has max/min at $t = 0/\pi$

$$\therefore \varepsilon(\vec{k}) = (-2\gamma)[\cos(k_x a) + \cos(k_y a)]$$

has min/max at $(k_x, k_y) = (0, 0)/(\pm\frac{\pi}{a}, \pm\frac{\pi}{a})$

\Rightarrow Bottom: P-point $(0, 0)$

Top : Four corners of 1st BZ
 $(\pm\frac{\pi}{a}, \pm\frac{\pi}{a})$

$$\textcircled{2} \quad \gamma < 0, -2\gamma > 0$$

The opposite of $\textcircled{1}$

\Rightarrow Bottom: Four corners $(\pm\frac{\pi}{a}, \pm\frac{\pi}{a})$

Top : P-point $(0, 0)$

$$(b) (M^{-1})_{ij} = \frac{1}{\hbar^2} \frac{2^2 \varepsilon(\vec{k})}{2k_i 2k_j} \quad (\text{A&M } 12.29)$$

$$= \frac{-2\gamma}{\hbar^2} \begin{bmatrix} -a^2 \cos(k_x a) & 0 \\ 0 & -a^2 \cos(k_y a) \end{bmatrix}$$

$$= \frac{2\gamma a^2}{\hbar^2} \begin{bmatrix} \cos(k_x a) & 0 \\ 0 & \cos(k_y a) \end{bmatrix} \quad (1=x, 2=y)$$

$$\Rightarrow (M(\vec{k}))_{ij} = \frac{\hbar^2}{2\gamma a^2} \begin{bmatrix} \sec(k_x a) & 0 \\ 0 & \sec(k_y a) \end{bmatrix}$$

For $\gamma > 0$, Bottom is at $(0, 0)$

① Top is at $(\frac{\pi}{a}, \frac{\pi}{a})$

At Bottom $(0, 0)$

$$(M(k=(0,0)))_{ij} = \frac{h^2}{2\gamma a^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

And all elements are positive

② At Top $(\frac{\pi}{a}, \frac{\pi}{a})$

$$\Sigma (M(k=(\frac{\pi}{a}, \frac{\pi}{a})))_{ij} = \frac{h^2}{2\gamma a^2} \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

all elements are negative.

=) The same conclusion can also be found
for $\gamma < 0$ case that

$M > 0$ for bottom

& $(= (\frac{\pi}{a}, \frac{\pi}{a}) \text{ for } \gamma < 0)$

$M < 0$ for top ($= (0, 0)$ for $\gamma < 0$)

Problem [2] (A) (5)

$$\epsilon(\vec{k}) = -2\gamma \left[c_{01}(k_x a) + c_{02}(k_y a) + c_{03}(k_z a) \right]$$

$$(\bar{M}(\vec{k}))_{ij} = \frac{1}{\hbar^2} \frac{\partial \epsilon(\vec{k})}{\partial k_i \partial k_j} \quad (i=x, j=y, z=2)$$

$$= \frac{-2\gamma}{\hbar^2} \begin{bmatrix} -a^2 c_{01}(k_x a) & 0 & 0 \\ 0 & -a^2 c_{02}(k_y a) & 0 \\ 0 & 0 & -a^2 c_{03}(k_z a) \end{bmatrix}$$

$$= \frac{2\gamma a^2}{\hbar^2} \begin{bmatrix} c_{01}(k_x a) & 0 & 0 \\ 0 & c_{02}(k_y a) & 0 \\ 0 & 0 & c_{03}(k_z a) \end{bmatrix}$$

$$\Rightarrow (\bar{M}(\vec{k}))_{ij} = \frac{\hbar^2}{2\gamma a^2} \begin{bmatrix} \sec(k_x a) & 0 & 0 \\ 0 & \sec(k_y a) & 0 \\ 0 & 0 & \sec(k_z a) \end{bmatrix}$$

For $\vec{k} = (0, 0, 0)$,

$$(\bar{M}(\vec{k}))_{ij} = \frac{\hbar^2}{2\gamma a^2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

②

And for $\vec{k} = \left(\frac{\pi}{a}, \frac{\pi}{a}, \frac{\pi}{a}\right)$

$$(M(\vec{k}))_{ij} = \frac{t^2}{2\pi a^2} \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$