

Math Midterm Cheat Sheet

1 Week 1

1.1 Second Order Differential Equations (DE)

Formula	Description
$ay'' + by' + cy = 0$	Second order linear homogeneous DE
$r = -\frac{b}{2a} \pm \frac{\sqrt{b^2 - 4ac}}{2a}$	Formula to determine 'r'
$y = C_1 e^{r_1 x} + C_2 e^{r_2 x}$	General solution if r_1 and r_2 two simple zeros of the characteristic eq
$y = (A + Bx)C e^{r_1 x}$	General solution if $r_1 = r_2 = r$ is a double zero of the characteristic eq (multiplicity 2)
$y = e^{rx}(A \cos(\omega x) + B \sin(\omega x))$	General solution If $r_1 = \alpha + i\omega$ and $r_2 = \alpha - i\omega$ (with $\alpha, \omega \in \mathbb{R}$) are the complex zeros of the characteristic equation

1.2 Guidelines for finding a particular solution

- If $f(t)$ is a polynomial in t , and $r = 0$ is not a solution of the characteristic polynomial, then try for $yp(t)$ a polynomial in t of the same degree as f . If $r = 0$ is a solution of the characteristic equation, then try for $yp(t)$ a polynomial of degree $\deg(f) + 1$, if $r = 0$ is a zero of multiplicity 1, and a polynomial of degree $\deg(f) + 2$ if $r = 0$ is a zero of multiplicity 2.
- If $f(t)$ is of the form $f(t) = \alpha \sin(\omega_0 t) + \beta \cos(\omega_0 t)$, and $\pm i\omega_0$ are not the zeros of the characteristic equation, then try $yp(t) = A \sin(\omega_0 t) + B \cos(\omega_0 t)$ as particular solution. If $\pm i\omega_0$ are the zeros of the characteristic equation, then try $yp(t) = At \sin(\omega_0 t) + Bt \cos(\omega_0 t)$ as particular solution
- If $f(t)$ is of the form $f(t) = p(t) * e^{\alpha t}$, with $p(t)$ a polynomial in t , and if α is not a zero of the characteristic equation, then try $yp(t) = q(t) * e^{\alpha t}$ as particular solution, with $q(t)$ a polynomial in t of the same degree as $p(t)$. If α is a zero of the characteristic polynomial of multiplicity k , then try $yp(t) = q(t) * t^k * e^{\alpha t}$ as particular solution, with $q(t)$ a polynomial in t , with $\deg(q) = \deg(p)$.

2 Week 2

2.1 Vectors in \mathbb{R}^2 and \mathbb{R}^3

Addition: $\vec{a} + \vec{b} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \end{bmatrix}$

Scaler/multiplication: $\alpha * \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} \alpha * a_1 \\ \alpha * a_2 \end{bmatrix}$

2.2 Parametric description

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} + \lambda \begin{bmatrix} d \\ e \\ f \end{bmatrix} + \mu \begin{bmatrix} g \\ h \\ i \end{bmatrix}$$

The vector containing a , b and c is the **supporting vector** and the vectors containing d , e , f and g , h , i are the **directional vectors**.

Example:

Let the following points P(2, 2, 0), Q(6, 0, 1) and R(3, 3, 1) be given. Find the parametric description of the plane containing P, Q and R.

Solution:

1. Determine supporting vector: $\vec{OP} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix}$

2. Determine directional vectors:

$$\vec{PQ} = \vec{OQ} - \vec{OP} = \begin{bmatrix} 6 - 2 \\ 0 - 2 \\ 1 - 0 \end{bmatrix} = \begin{bmatrix} 4 \\ -2 \\ 1 \end{bmatrix}$$

$$\vec{PR} = \vec{OR} - \vec{OP} = \begin{bmatrix} 3 - 2 \\ 3 - 2 \\ 1 - 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

3. Parametric description:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 4 \\ -2 \\ 1 \end{bmatrix} + \mu \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$