

**Our approach:** Whenever you approach a significant problem, rather than trying to implement the entire solution right away, it is often a good idea to break it down into a series of sub-systems. Sub-systems are designed to solve a portion of the overall problem. This means that we can start implementing and testing at an earlier stage, and it is easier to identify and fix any issues that occur along the way. We can then combine each of these smaller sub-systems at the end to solve our complete problem.

We can break our overall solution down into a series of sub-systems, like as follows:

1. We need to program our robot to move.
2. We need to program our robot to detect small curves in the line and adjust its movement accordingly.
3. We need to program our robot to detect significant turns in the line and adjust its movement accordingly.
4. We need to program our robot to detect the presence of a fire and automatically put it out.
5. We will then combine each of these smaller programs to solve the complete problem.

To get started with building your solution, proceed to the first iteration below. In each iteration, we will research, plan and then code one of our sub-systems. At the end of an iteration, proceed horizontally into the next iteration until you have completed them all and solved the problem!

