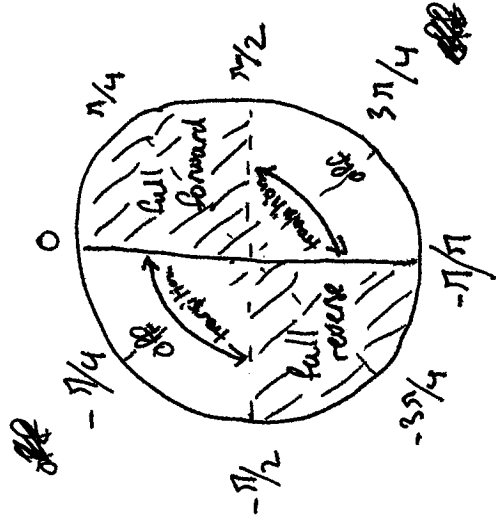


Movement heading to motor power calculation

Left motor



Right motor

