

# Design and Analysis of a Low Loss, Wideband Digital Step Attenuator With Minimized Amplitude and Phase Variations

Ickhyun Song<sup>ID</sup>, *Member, IEEE*, Moon-Kyu Cho<sup>ID</sup>, *Member, IEEE*, and John D. Cressler, *Fellow, IEEE*

**Abstract**—A compact, low loss, wideband digital step attenuator (DSA) is presented. The proposed DSA utilizes amplitude/phase-compensated T-type attenuator cells, in which the locations of poles and zeros are manipulated for minimizing variations in attenuation and phase. In addition, the reduced T-type attenuator cells that eliminate series switch transistors are used to achieve low insertion loss (IL). These techniques provide wideband (dc–20 GHz) operation for the DSA, with significantly decreased attenuation/phase errors and reduced IL. The DSA was implemented in a 130-nm silicon-germanium (SiGe) BiCMOS platform. The full attenuator circuit has binary-coded 6-bit digital control inputs with a least significant bit of 0.5-dB attenuation. It has a root-mean-square (rms) attenuation error of 0.37 dB and an rms phase error of 4°, both at 20 GHz. The IL and the input 1-dB compression point at 10 GHz are 4 dB and 10 dBm, respectively. The active core layout area is 0.14 mm<sup>2</sup> (1.0 mm × 0.14 mm).

**Index Terms**—Attenuation/phase error compensation, attenuator, digital step attenuator (DSA), insertion loss (IL), modified switched T-type, passive, reduced switched T-type, silicon-germanium (SiGe) BiCMOS, wideband.

## I. INTRODUCTION

ATTENUATORS are one of the key building blocks in many RF communications, radar, and measurement systems. The primary function of attenuators is to provide amplitude control for various purposes such as linearity adjustment and damage protection [1], [2]. With regard to phased array applications, attenuators should provide an accurate control for sidelobes in antenna radiation patterns [3]. While as a gain control element variable-gain amplifiers (VGAs) perform a similar function, they typically exhibit one or more limitations, consisting of: large amplitude/phase variation, narrow bandwidth, limited linearity, unidirectional operation, and large power consumption, complex system configuration (due to RF chokes or biasing) [4]–[9] compared to passive-type attenuators, all of which can be detrimental to the realization of wideband large-scale phased array systems. From this perspective, passive digital step attenuators (DSAs) are more attractive, since they can provide most of the following

advantages, including wide bandwidth, fine amplitude control, high linearity, bidirectional operation, reduced amplitude and phase variations, and simple system configurations [10]–[13].

In passive DSAs, three topologies have been investigated in the literature: distributed, switched-path, and switched  $\pi$ -T-type attenuators [11], [13]–[18]. First, distributed step attenuators provide wide bandwidth and low insertion loss (IL) among passive DSAs. However, they exhibit low values of maximum attenuation (e.g., <10–15 dB), large chip size due to the use of transmission lines, and performance degradation in a low gigahertz region [13], [14]. Second, switched-path step attenuators have advantages of low amplitude and phase variations (e.g., <0.5 dB, 5°, respectively), but they often suffer from high IL and large chip size due to the use of many series switches and lumped inductors, respectively [15], [16]. Finally, switched  $\pi$ -T-type step attenuators show low IL, high maximum attenuation (e.g., >30 dB), and compact size, which are attractive features in large phased array systems. However, they still have the drawbacks of relatively high attenuation variation (2–3 dB) that potentially limit a fine amplitude control (e.g., attenuation variations <1 dB) in wideband applications [11], [17], [18].

Recently, several techniques for compensating amplitude and phase variations of switched  $\pi$ -T-type step attenuators have been proposed [3], [19]–[21]. Either the inductive or the capacitive amplitude/phase compensation techniques is able to reduce such variations, but capacitive compensation is better suited for large-scale wideband phased array systems [3], [20], [21] than the inductive compensation due to the size increase associated with the inductors [19]. While the compensation solution proposed in [3] is very simple and effective in the minimization of amplitude/phase variations, only a qualitative, first-order description of the approach has been addressed in the literature [3], [22], which over simplified the detailed physics and behavior associated within such structures.

In this paper, we present an in-depth, thorough investigation of the amplitude/phase compensation technique, based on pole-zero analysis. By developing the analytic equations for the conventional and the modified T-type attenuator cells, the locations of poles and zeros can be found, and then the mechanisms of the reduction in amplitude/phase variations can be explained. As an example of the application of this analysis, the design and the characterization of a 6-bit DSA in a silicon-germanium (SiGe) BiCMOS platform is demonstrated. The

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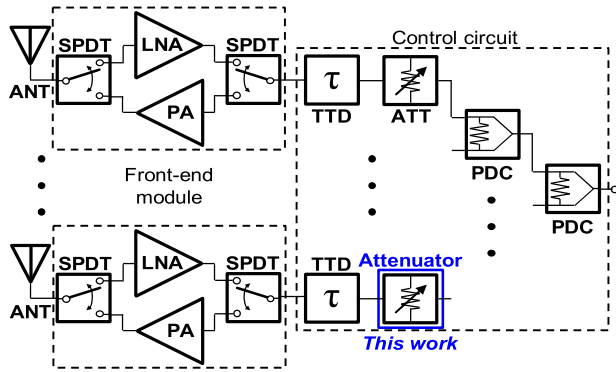


Fig. 1. Configuration of a wideband phased array transceiver chipset. It includes switchable front-end modules and bi-directional control circuit block. ANT: antenna. SPDT: single-pole double-throw. LNA: low-noise amplifier. PA: power amplifier. TTD: true-time delay. ATT: attenuator. PDC: power divider/combiner.

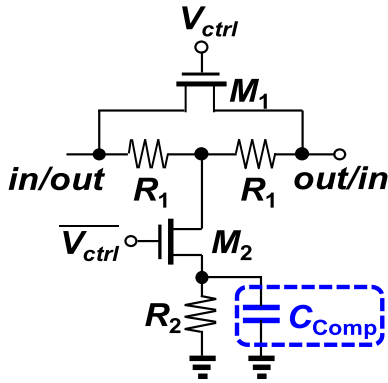


Fig. 2. Schematic of a switched T-type attenuator cell. The conventional attenuator topology includes all components except  $C_{Comp}$ , while the modified schematic utilizes  $C_{Comp}$  for compensating attenuation and phase errors. Large bias resistors at the transistor gate terminals are not shown.

DSA is intended for a multi-channel wideband phased array transceiver (T/R) system, which consists of antennas, front-end modules, and bidirectional control circuits, as shown in Fig. 1. The designed DSA employs not only the capacitive compensation technique but also the loss minimization scheme [23]–[25] for maximized performance over the entire bandwidth (from dc to 20 GHz). For comparison purposes, the performance of the conventional T-type DSA without the amplitude/phase compensation is also presented. Section II describes the detailed analysis of the amplitude/phase compensation technique compared with a conventional T-type attenuator cell. In addition, the effects of the loss minimization technique will be investigated. In Section III, the measured results will be shown, followed by discussion, and Section IV will summarize this paper.

## II. DSA WITH MODIFIED T-TYPE ATTENUATION CELLS

### A. Limitations of Conventional T-Type Switched Attenuators

The schematic of a switched T-type attenuator cell is shown in Fig. 2. The conventional design includes T-type resistors ( $R_1$  and  $R_2$ ) for attenuation, and series/shunt transistors ( $M_1$  and  $M_2$ ) for mode switching [19], whereas the modified attenuator cell utilizes an additional capacitor  $C_{Comp}$

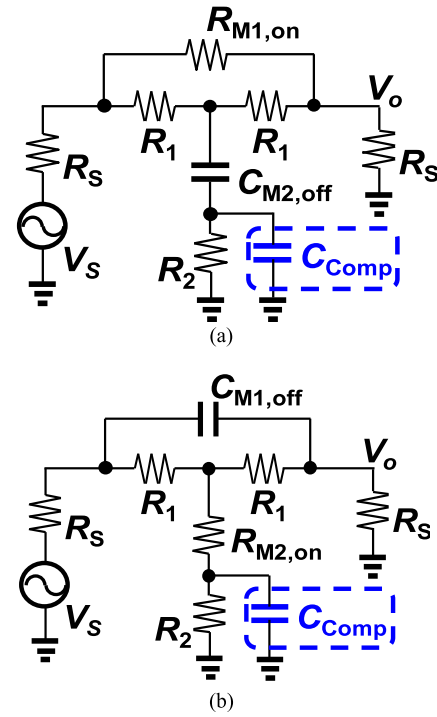


Fig. 3. Simplified small-signal equivalent circuits for (a) reference state and (b) attenuation state.

(the dashed box in Fig. 2). Under a reference (no attenuation) state, the large series transistor ( $M_1$ ) provides a low-loss path from the input to the output. Under an attenuation state,  $M_1$  is OFF and the two resistors,  $R_1$  and  $R_2$ , and together with the fully turned-ON shunt transistor  $M_2$  form a T-type network. Given the required attenuation  $A$  (in decibel) and the characteristic impedance  $Z_0$ , ideal values of  $R_1$  and  $R_2$  can be calculated using the following equations [26]:

$$R_1 = Z_0 \cdot \left( \frac{10^{A/20} - 1}{10^{A/20} + 1} \right) \quad (1)$$

$$R_2 = 2 \cdot Z_0 \cdot \left( \frac{10^{A/20}}{10^{A/10} - 1} \right) - R_{M2,ON}. \quad (2)$$

In (2),  $R_{M2,ON}$  is the ON-state resistance of the shunt transistor  $M_2$ . While the conventional T-type cells offer a simple structure and accurate attenuation, they often suffer from two limitations: 1) large amplitude/phase variations and 2) high IL in a high-frequency region, which prohibits wideband operation. The former is mainly attributed to the change in parasitic capacitance when the transistors are either turned ON or OFF, while the latter is mainly associated with the ON-state resistance of the series transistor.

First, the amplitude and the phase variations associated with attenuator cells can be analyzed from their small-signal equivalent circuits. In Fig. 3, the equivalent circuits are shown, depending on the operational states. For simplicity, a switch transistor ( $M_1$ ,  $M_2$ ) is modeled as either a resistor for an ON-state ( $R_{M1,ON}$  and  $R_{M2,ON}$ ) or a capacitor ( $C_{M1,OFF}$  and  $C_{M2,OFF}$ ) for an OFF-state. The resistor and the capacitor represent the channel resistance and the combined capacitance

TABLE I  
PARAMETER VALUES FOR AN 8-DB ATTENUATOR CELL

$R_1$	22.5 $\Omega$	$R_2$	37.6 $\Omega$
$R_{M1,on}$	4.3 $\Omega$	$C_{M1,off}$	74.5 fF
$R_{M2,on}$	10.3 $\Omega$	$C_{M2,off}$	33.7 fF

in the oxide, junction, and substrate regions of the transistor, respectively. While this first-order approximation does not reflect the complex response of the attenuator cells at high frequencies, due to the omission of many parasitic components, we can more easily understand their frequency behavior from a dominant pole-zero analysis for the band of interest, thus providing useful insight. In order to find the locations of poles and zeros, the transfer functions of the conventional attenuator cells under a reference state and an attenuation state are derived, as shown in equations (3) and (4), at the bottom of this page.

As an example, we present the frequency response of an 8-dB attenuation cell, since three identical 8-dB cells will be used in the final DSA schematic. Inspecting (3) and (4), we expect the attenuator cell has one pole and one zero in both states, and their corresponding poles and zeros are obtained from the following equations:

$$f_{Conv,Ref,z} = \frac{2R_1 + R_{M1,ON}}{2\pi C_{M2,OFF}(R_1^2 + 2R_1R_2 + R_2R_{M1,ON}t)} \quad (5)$$

$$f_{Conv,Ref,p} = \frac{1}{\pi C_{M2,OFF}(R_1 + 2R_2 + R_S)} \quad (6)$$

$$f_{Conv,Att,z} = \frac{R_2 + R_{M2,ON}}{2\pi C_{M1,OFF}(R_1^2 + 2R_1R_2 + 2R_1R_{M2,ON})} \quad (7)$$

$$f_{Conv,Att,p} = \frac{R_1 + R_S}{4\pi C_{M1,OFF}R_1R_S} \quad (8)$$

Using the values from Table I, which summarizes reasonably optimized values for the 8-dB attenuation, we see that the pole ( $\omega_{Ref,c,p}$ ) first appears at 60 GHz, and a zero ( $\omega_{Ref,c,z}$ ) is at 100 GHz in the reference state, as shown in Fig. 4(a). On the other hand, in the attenuation state, a zero ( $\omega_{Att,c,z}$ ) is located at 40 GHz and a pole ( $\omega_{Att,c,p}$ ) comes next at 70 GHz. Since the changes in  $S_{21}$  slope and phase for a pole and a zero are opposite from each other, the resulting amplitude variations become worse as frequency increases, thereby limiting the operational bandwidth of the attenuator cell. In Fig. 4(b), the phase response of both the ON- and OFF-states is shown. As expected from the amplitude response in Fig. 4(a), the phase variation monotonically increases until 60 GHz. It should be noted that the simulation results were made using a process design kit (PDK), and show a different frequency behavior at high frequencies. This is expected, since

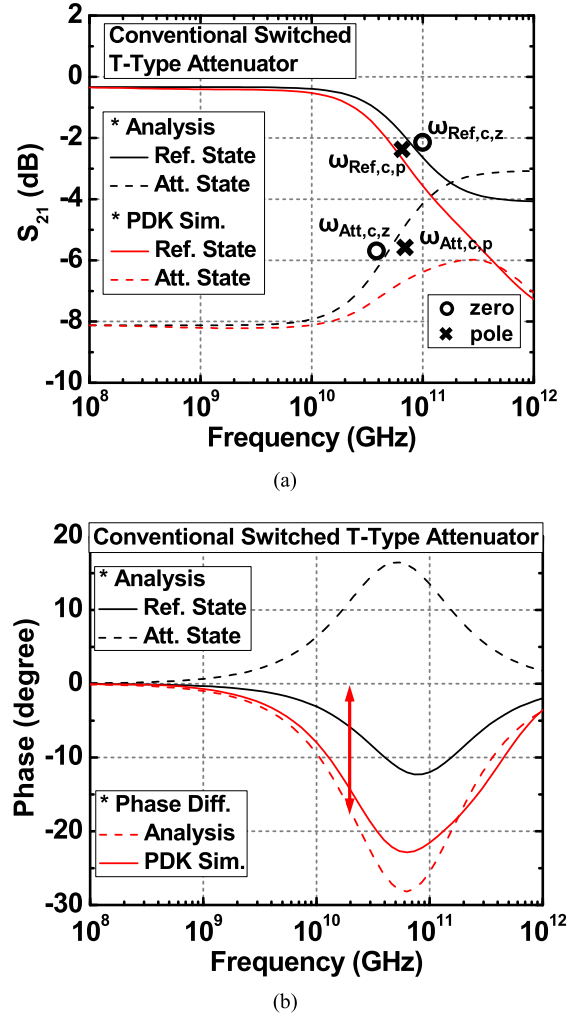


Fig. 4. (a) Frequency response of a conventional T-type 8-dB attenuator cell. The parameters in Table I are used for the pole-zero calculation in (5)–(8). For simulation results, a PDK was used. (b) Phase response of the same 8-dB attenuator cell.

the accurate PDK model includes numerous poles and zeros which are not revealed at low frequencies.

Second, the conventional switched T-type attenuator inevitably exhibits finite IL since the ON-state resistance of a series transistor cannot be zero. While a large-sized series transistor can reduce the ON resistance, an excessive increase in parasitic capacitance moves a pole and a zero to lower frequencies, as implied from (3) and (4). In Fig. 5, the simulated IL and bandwidth of the conventional switched T-type 8-dB attenuator cell are presented. In this simulation, the bandwidth is defined as the frequency at which the amplitude variation equals to 0.5 dB. It is shown that lower IL can be achieved at the cost of the substantial reduction in the operational

$$T(s)_{Conv,Ref} = \frac{R_S[2R_1 + R_{M1,ON} + C_{M2,OFF}(R_1^2 + 2R_1R_2 + R_2R_{M1,ON})s]}{(R_1R_{M1,ON} + 2R_1R_S + R_{M1,ON}R_S)[2 + C_{M2,OFF}(R_1 + 2R_2 + R_S)s]} \quad (3)$$

$$T(s)_{Conv,Att} = \frac{R_S[R_2 + R_{M2,ON} + C_{M1,OFF}(R_1^2 + 2R_1R_2 + 2R_1R_{M2,ON})s]}{(R_1 + 2R_2 + 2R_{M2,ON} + R_S)(R_1 + R_S + 2C_{M1,OFF}R_1R_S \cdot s)} \quad (4)$$

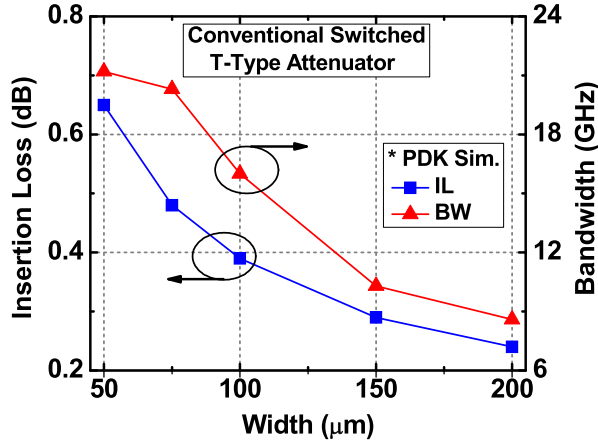


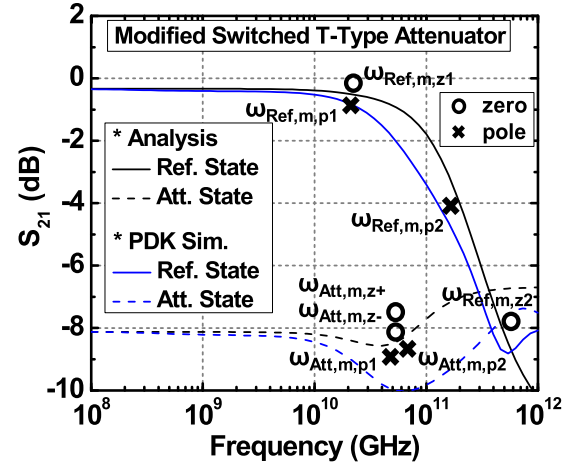
Fig. 5. Simulated IL and bandwidth of the conventional T-type 8-dB attenuator cell versus the width of the series transistor.

bandwidth of the attenuator cell. Therefore, it is important to eliminate series transistors as much as possible in order to avoid the tradeoff relationship.

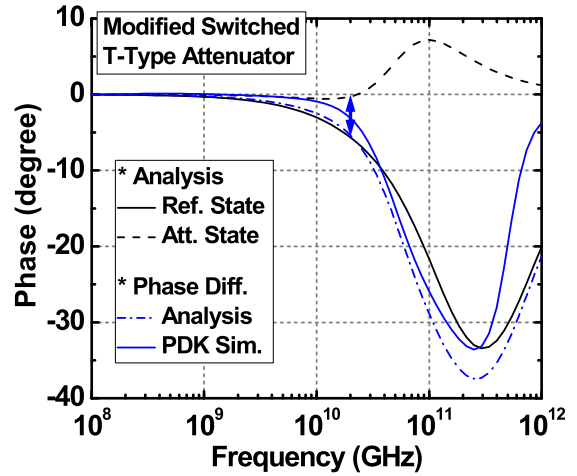
### B. Amplitude/Phase-Compensated T-Type Attenuator Cell

The modified attenuator cell schematic, which includes an amplitude- and phase-compensation capacitor  $C_{\text{Comp}}$  [3], is shown in Fig. 2. The addition of  $C_{\text{Comp}}$  changes the attenuator cell (in Fig. 3) to become a two-pole, two-zero system (the denominators and the numerators are now in quadratic forms), as analytically derived in the following equations. The explanation in [3] and [22] briefly states that the inclusion of  $C_{\text{Comp}}$  extends the operational bandwidth due to the phase lagging associated with an additional pole or the introduction of a low-pass filter network under an attenuation state. However, closely located poles and zeros may affect the frequency behavior of an attenuator cell. In addition, under a reference state, the hidden pole-zero cancellation plays an important role in bandwidth extension.

With a careful selection of the  $C_{\text{Comp}}$  capacitance, the resulting frequency response an 8-dB attenuator cell is presented in Fig. 6(a). For the reference state, since both the first pole ( $\omega_{\text{Ref},m,p1}$ ) and the first zero ( $\omega_{\text{Ref},m,z1}$ ) appear at about 20 GHz, they effectively cancel each other, while the second pole ( $\omega_{\text{Ref},m,p2}$ ) at 160 GHz becomes dominant. Hence, the flat-response bandwidth is extended compared with a conventional attenuator cell [Fig. 4(a)]. On the other hand, in the attenuation state, now a pole ( $\omega_{\text{Att},m,p1}$ ) first appears at 47 GHz, shaping the  $S_{21}$  response similar to the reference state beyond 10 GHz. Two co-located zeros ( $\omega_{\text{Att},m,z+}$  and  $\omega_{\text{Att},m,z-}$ ) at 53 GHz raise the  $S_{21}$  slope to be positive, which is eventually compensated by the second pole ( $\omega_{\text{Att},m,p2}$ ) at 70 GHz. This implies that the  $C_{\text{Comp}}$  capacitance can favorably modify the frequency response by adjusting the pole and zero locations so that the maximized operational bandwidth and the minimized attenuation and phase variations are achieved. The phase response of the modified attenuation cell is presented in Fig. 6(b). Compared with Fig. 4(b), the phase difference at



(a)



(b)

Fig. 6. (a) Frequency response of the modified T-type 8-dB attenuator cell. The parameters in Table I are used for the pole-zero calculation in (9) and (10). For simulation results, a PDK was used. (b) Phase response of the same 8-dB attenuator cell.

20 GHz is reduced from  $18^\circ$  to  $6^\circ$

$$\omega_{\text{Att},m,p} = \frac{R_1 + 2R_2 + 2R_{M2,\text{ON}} + R_S}{C_{\text{Comp},\text{init}}(R_1 R_2 + 2R_2 R_{M2,\text{ON}} + R_2 R_S)} \quad (11)$$

$$\omega_{\text{Att},m,z} = \left( \frac{R_2 + R_{M2,\text{ON}}}{C_{\text{Comp},\text{init}} [C_{M1,\text{OFF}} (R_1^2 R_2 + 2R_1 R_2 R_{M2,\text{ON}})]} \right)^{1/2} \quad (12)$$

$$C_{\text{Comp},\text{init}} = \frac{C_{M1,\text{OFF}} R_1 (R_1 + 2R_{M2,\text{ON}})}{R_2 (R_2 + R_{M2,\text{ON}})} \times \left( \frac{R_1 + 2R_2 + 2R_{M2,\text{ON}} + R_S}{R_1 + 2R_{M2,\text{ON}} + R_S} \right)^2. \quad (13)$$

The calculation of the full analytical optimal capacitance of  $C_{\text{Comp}}$  for obtaining maximum bandwidth is cumbersome. However, finding a reasonable  $C_{\text{Comp}}$  capacitance is relatively simple, and this can be used for an initial value as a starting point. Since in the proposed circuit an additional dominant



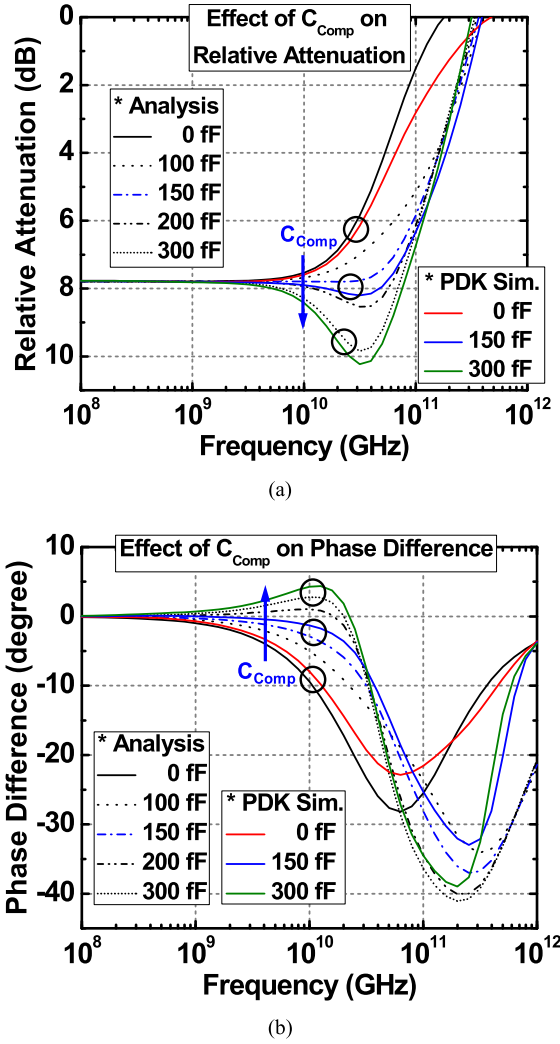


Fig. 7. Effect of the compensation capacitor  $C_{Comp}$  on the frequency response of (a) relative attenuation and (b) phase difference. The direction of the arrows indicates the increasing capacitance. For comparison, a few PDK simulation results are added.

pole needs to appear earlier than the zeros in an attenuation state, we can find  $C_{Comp,init}$  when the lowest pole and the lowest zero locations are at the same frequency. Therefore, by equating (11) and (12),  $C_{Comp,init}$  can be calculated as (13). Using the parameter values in Table I, it shows a  $C_{Comp,init}$  of about 130 fF. For the maximized bandwidth, the optimal  $C_{Comp}$  should be slightly larger than  $C_{Comp,init}$  due to the

TABLE II  
THEORETICAL RESISTANCE FOR T-TYPE ATTENUATION

Attenuation (dB)	4	2	1	0.5
$R_1$ ( $\Omega$ )	11.3	5.7	2.9	1.4
$R_2$ ( $\Omega$ )	104.8	215.2	433.3	868.1

co-located zeroes, so that the falling slope of  $S_{21}$  increases similar to the reference state response, as shown in Fig. 6(a).

The optimal value of  $C_{Comp}$  is determined by graphically analyzing the relative attenuation and phase difference from (9) and (10), as shown at the bottom of this page. In Fig. 7(a), the relative attenuation with varying  $C_{Comp}$  is shown. When there is no compensation capacitance ( $C_{Comp} = 0$  fF), the relative attenuation decreases as the frequency increases at values higher than about 9 GHz, as expected from Fig. 4(a). The optimum  $C_{Comp}$  lies at around 150 fF, with which the maximum flat amplitude response is obtained. The similar result is observed in the phase difference plot, as shown in Fig. 7(b). In this case,  $C_{Comp}$  of 200 fF is optimal for the maximally flat phase difference between a reference state and an attenuation state. Therefore, a compensation capacitance between 150 and 200 fF should be chosen for the final design depending on the DSA specifications. In the present design, PDK-based simulations predict the optimal capacitance of about 155 fF, which minimized the phase variations under other design constraints such as impedance matching and attenuation errors.

### C. Reduced T-Type Attenuator Cell

The dominant IL of the conventional attenuator cell is associated with the ON-state resistance of a series transistor. While this finite series resistance is inevitable in the switched T-type attenuator topology, however, there are certain cases in which the series transistor can be removed without loss of functionality. When the required attenuation for a given cell is as low as 0.5 or 1.0 dB, the theoretical resistances of  $R_1$  and  $R_2$  become smaller and larger, respectively. Table II summarizes the ideal values of  $R_1$  and  $R_2$  for different attenuations. For low attenuation cells, the role of the series resistance is much less significant than the shunt resistance in the overall response. This implies that the series resistance  $R_1$  can be eliminated in the T-type network and the remaining series transistor is now redundant. The resulting reduced attenuator

$$T(s)_{Mod,Ref} = \frac{R_S [2R_1 + R_{M1,ON} + C_{M2,OFF}(R_1^2 + 2R_1R_2 + R_2R_{M1,ON})s + C_{Comp}(2R_1R_2 + R_2R_{M1,ON})s + C_{M2,OFF}C_{Comp}R_1R_2 \cdot s^2]}{(R_1R_{M1,ON} + 2R_1R_S + R_{M1,ON}R_S)[2 + C_{M2,OFF}(R_1 + 2R_2 + R_S) \cdot s + 2C_{Comp}R_2s + C_{M2,OFF}C_{Comp}(R_1R_2 + R_2R_S)s^2]} \quad (9)$$

$$T(s)_{Mod,Att} = \frac{R_S [R_2 + R_{M2,ON} + C_{M1,OFF}(R_1^2 + 2R_1R_2 + 2R_1R_{M2,ON})s + C_{Comp}R_2R_{M2,ON} \cdot s + C_{M1,OFF}C_{Comp}(R_1^2R_2 + 2R_1R_2R_{M2,ON})s^2]}{[R_1 + 2R_2 + 2R_{M2,ON} + R_S + C_{Comp}(R_1R_2 + 2R_2R_{M2,ON} + R_2R_S)s](R_1 + R_S + 2C_{M1,OFF}R_1R_S \cdot s)} \quad (10)$$

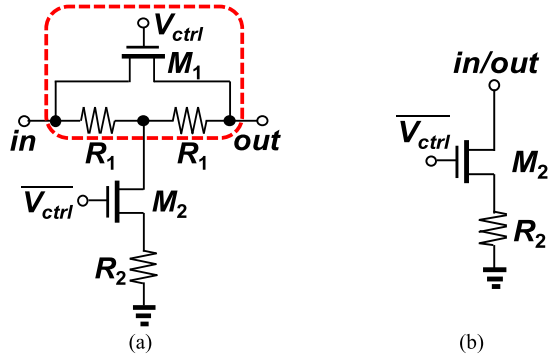


Fig. 8. (a) Schematic of the conventional T-type attenuator cell. (b) Schematic of the reduced T-type attenuator cell.

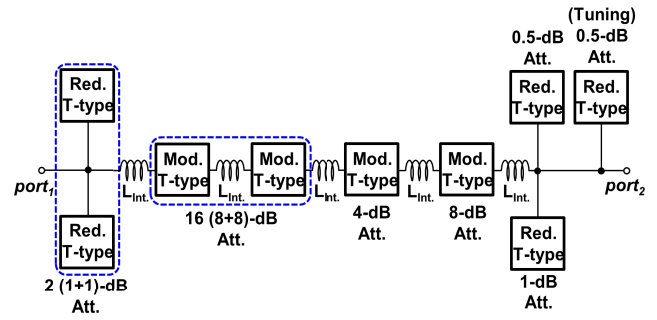


Fig. 10. Full schematic of the 6-bit digital-step attenuator. It consists of the modified and the reduced T-type attenuator cells. For 2-dB attenuation, two 1-dB cells are parallel-combined, while for 16-dB attenuation, two 8-dB cells are series connected.

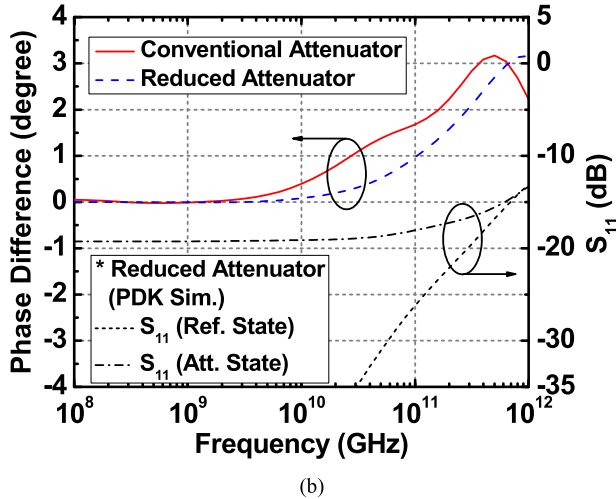
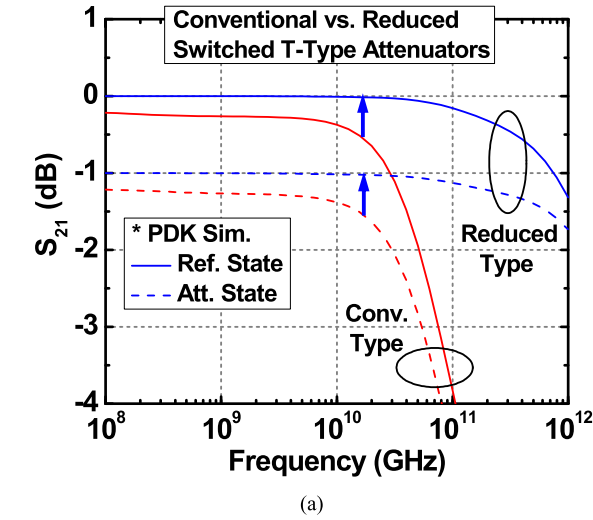


Fig. 9. (a) Simulated  $S_{21}$  under attenuation and reference states for both the conventional and the reduced cells. (b) Comparison of phase difference between attenuation and reference states for both attenuators. Matching results of the reduced attenuator is presented as well.

cell schematic is shown in Fig. 8. From the conventional schematic in Fig. 8(a),  $R_1$  and  $M_1$  are removed and the required attenuation is achieved by adjusting  $R_2$  and  $M_2$  only [Fig. 8(b)] [23], [25].

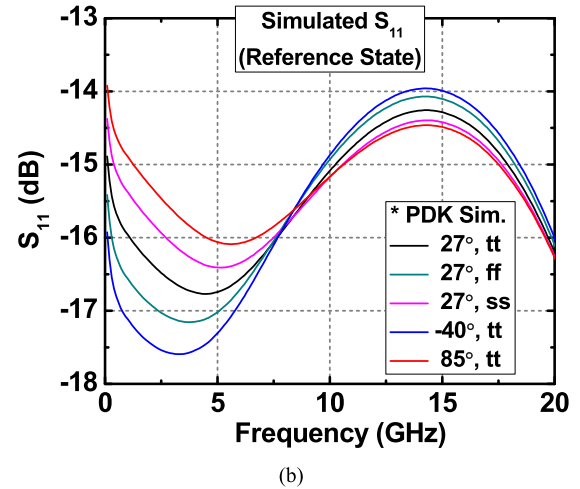
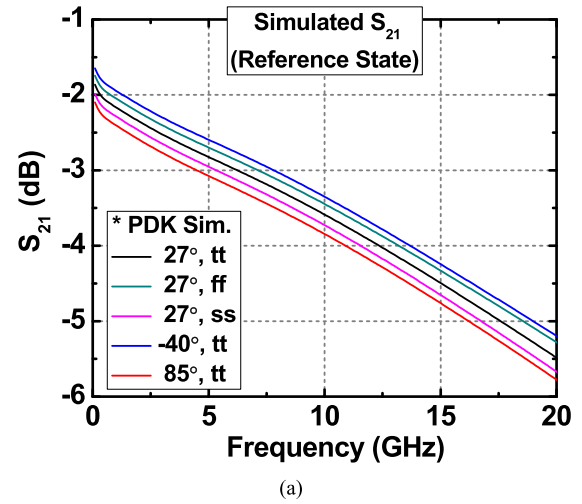


Fig. 11. Simulated performance variations of (a)  $S_{21}$  and (b)  $S_{11}$  under different process and temperature corners for the reference state.

In Fig. 9, the S-parameter response of the reduced T-type attenuator cell is presented. As an example, a 1-dB attenuator cell is selected for the comparison with the conventional design. The simulated  $S_{21}$  results of both the conventional and the reduced attenuator cells are shown in Fig. 9(a). While in both case, the required 1-dB attenuation is achieved,

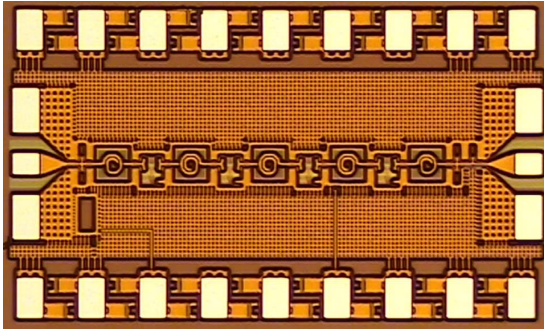


Fig. 12. Chip micrograph of the proposed 6-bit DSA. The total chip size is  $0.98 \text{ mm}^2$  ( $1.3 \text{ mm} \times 0.75 \text{ mm}$ ).

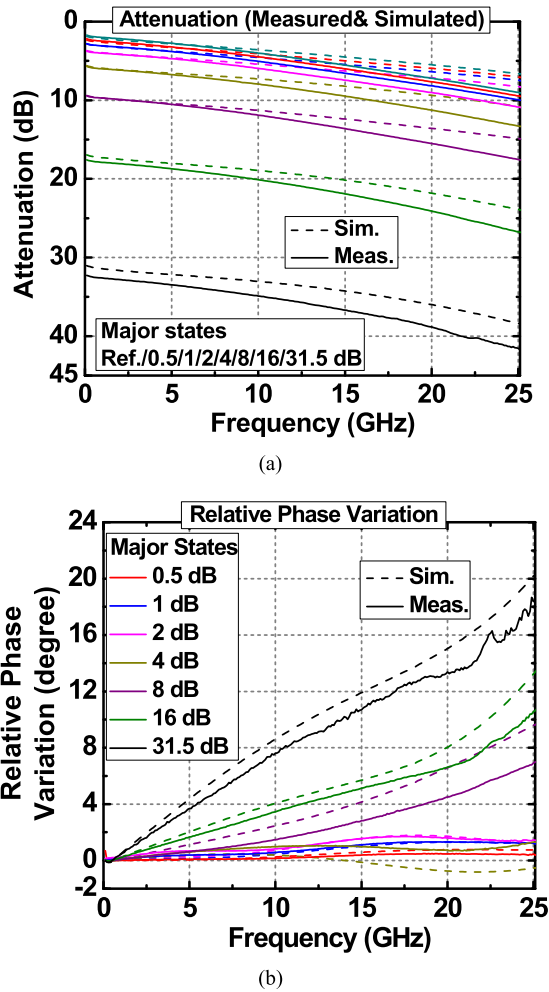


Fig. 13. Measured and simulated (a) attenuation response and (b) relative phase variations for major states.

the reduced cell provides almost negligible IL ( $<0.1 \text{ dB}$ ) below  $30 \text{ GHz}$ . In addition, since the dominant pole appears at much higher frequency ( $60 \text{ GHz}$ ) than the operational bandwidth (due to their smaller parasitic capacitance), it does not impose any bandwidth limitations when combined with the other modified T-type attenuator cells discussed in Section II-A.

In Fig. 9(b), the phase difference between a reference state and an attenuation state is shown for both the conventional and

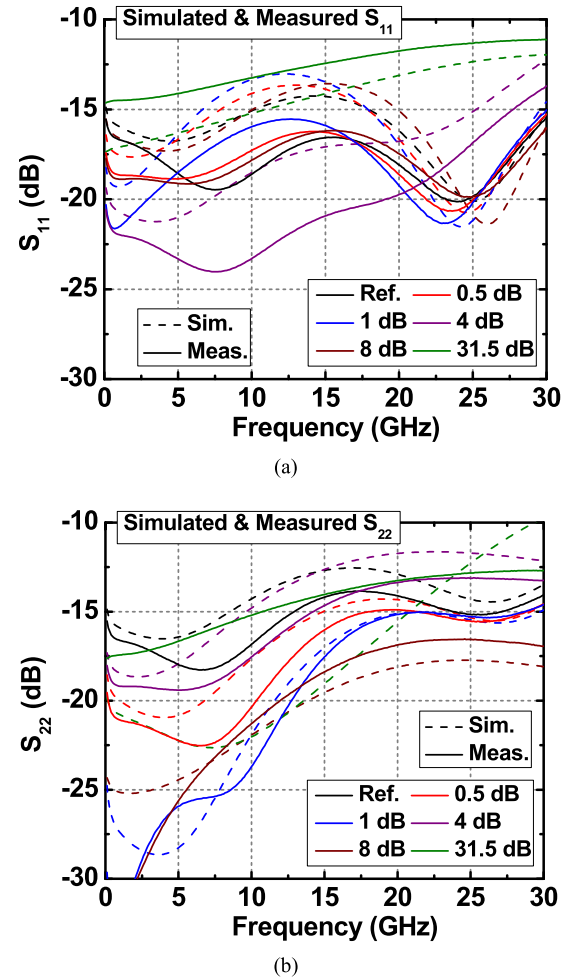


Fig. 14. Simulated and measured (a)  $S_{11}$  and (b)  $S_{22}$  for major states.

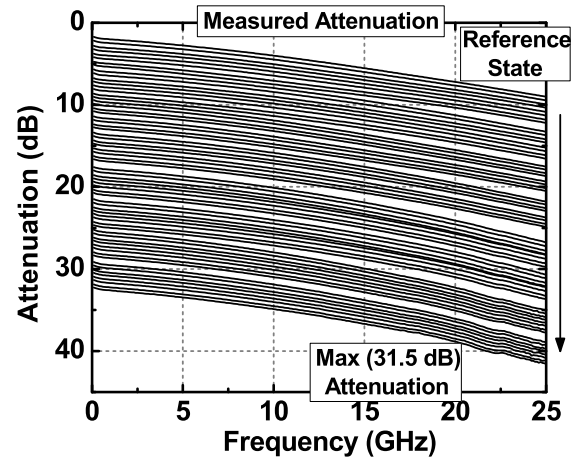


Fig. 15. Measured attenuation over frequency for all states.

the reduced T-type attenuator cells. The reduced attenuation cell presents a low phase variation of  $0.2^\circ$  at  $20 \text{ GHz}$ , which is more than 60% reduction from the conventional design. On the other hand, when it comes to the matching response, the reduced cell cannot present an ideal  $50\text{-}\Omega$ -matched condition due to the omission of the series resistors  $R_1$  from

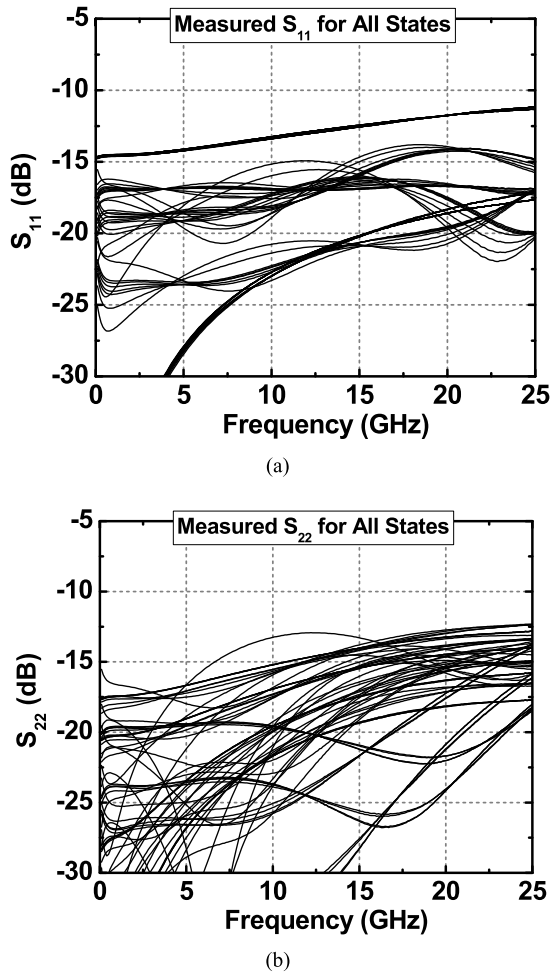


Fig. 16. Measured (a)  $S_{11}$  and (b)  $S_{22}$  versus frequency for all attenuation states.

the original T-type network. The simulated matching ( $S_{11}$  or  $S_{22}$ ) results are shown in Fig. 9(b) for the reduced T-type 1-dB attenuator cell. The worst case is the attenuation state, but  $S_{11}$  remains lower than  $-18$  dB below 100 GHz. From a practical point of view, since the reduced attenuator cells present reasonable matching response, they can replace the conventional designs in the case of low attenuation such as 0.5, 1.0, or 2.0 dB, effectively minimizing the loss associated with the series transistors.

#### D. Full DSA Design

The full schematic of the proposed wideband low-loss DSA is shown in Fig. 10. It has six digital bit inputs, which provide an independent control of binary-coded attenuation levels (0.5, 1, 2, 4, 8, and 16 dB). The high-attenuation cells, including 4, 8, and 16 dB, use the modified switched T-type cells, while the low-attenuation cells (0.5, 1, and 2 dB) use the reduced T-type cells. The 16-dB cell consists of two identical 8-dB cells to minimize amplitude errors and phase variations. Similarly, the 2-dB cell is composed of two 1-dB cells for better impedance matching response. For system optimization, an additional 0.5-dB attenuator cell is included for performance tuning. Since the parasitic capacitance associated with the transistors and the interconnection structures presents a

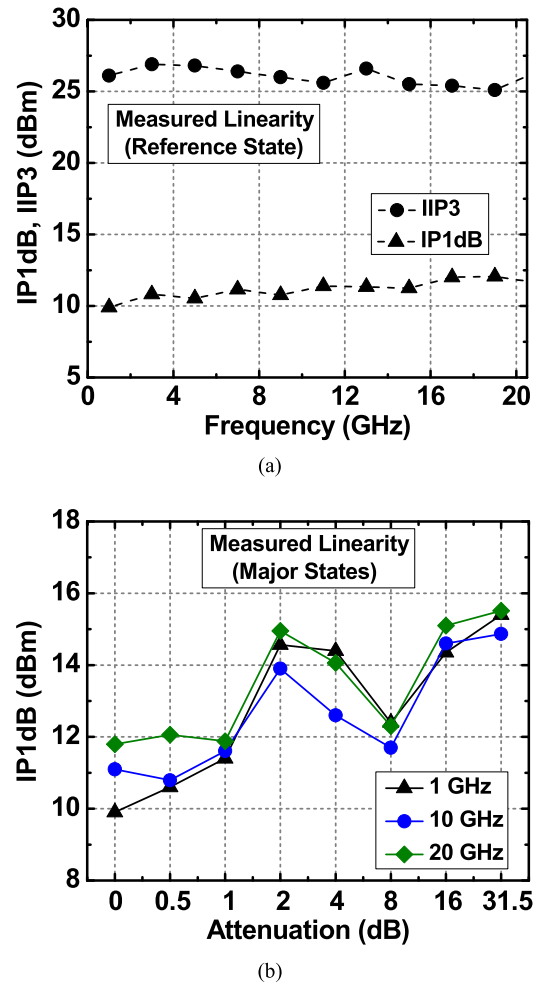


Fig. 17. (a) Measured IP1dB compression point and IIP3 under the reference state. (b) Measured IP1dB for the major states.

negative imaginary impedance, this shifts  $S_{11}$  and  $S_{22}$  down along the 50- $\Omega$  circle on the Smith chart. Inserting series inductors between stages improves the matching characteristics, thereby maximizing operational bandwidth.

The series and the shunt transistors in the modified T-type attenuator cells have dimensions of 19 fingers of  $5 \mu\text{m} \times 120 \text{ nm}$  and 8 fingers of  $5 \mu\text{m} \times 120 \text{ nm}$ , respectively, whereas the shunt transistors in the reduced cells have a dimension of 1 finger of  $4 \mu\text{m} \times 120 \text{ nm}$ . In addition, each series and shunt switch transistor employed a body/N-well-floating technique for minimizing signal leakage through substrate junctions [27]. Parasitic components such as interconnections, pads, and signal line structures were modeled with an electromagnetic (EM) simulation tool (SONNET) [28]. The proposed attenuator used coplanar waveguide (CPWG) lines with ground plane for interconnect signal lines. The series inductors have an inductance of about 300 pH, and the IL of an inductor is 0.5–0.7 dB at 20 GHz. Overall, the simulated IL of the DSA is about 5.5 dB at 20 GHz, considering five series inductors and four series attenuation cells.

#### E. Process and Temperature Effects

Process and temperature variations affect the performance of attenuators, as they change both the active and the passive



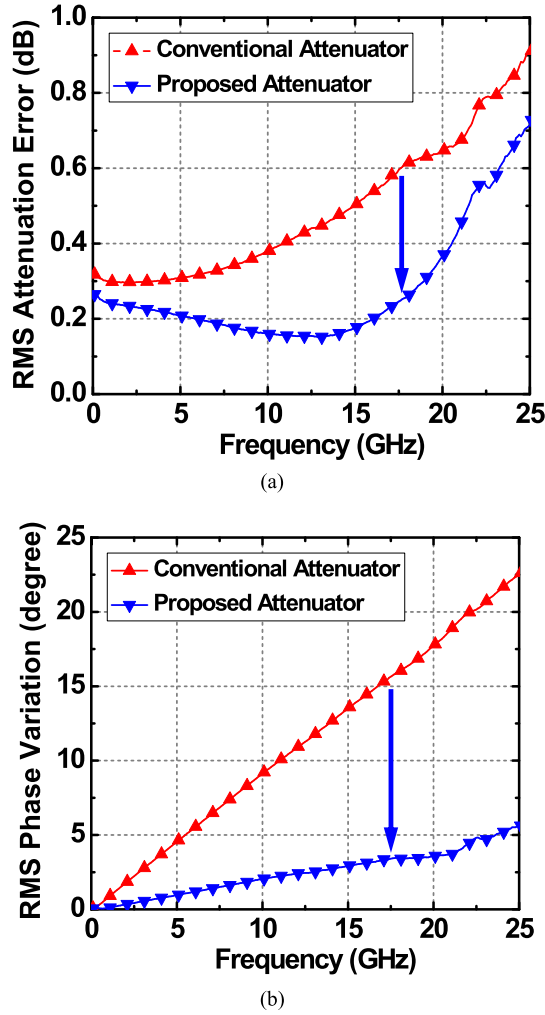


Fig. 18. (a) Measured rms attenuation error.(b) Measured rms phase variation for both the conventional and the proposed attenuators.

device parameters. In addition, since passive DSAs have no signal gain, they are likely to be more sensitive to parameter variations. The simulated  $S_{21}$  and  $S_{11}$  under different corners for the reference state are shown in Fig. 11(a) and (b), respectively. For low temperature and fast process corners, IL decreases due to reduced resistances, whereas IL increases for high temperatures and slow process corners. Capacitance also changes according to process and temperature corners, modifying the matching characteristics [Fig. 11(b)]. If the system requires constant performance (e.g., IL) across different corners, adaptive bias circuitry may be necessary to adjust gate control voltages, using internal or external process and temperature sensors.

### III. MEASURED RESULTS AND DISCUSSION

The proposed wideband DSA was fabricated in GlobalFoundries 130-nm 8HP SiGe BiCMOS technology platform, which provided triple-well RF nFETs with a unity-gain frequency ( $f_T$ ) of about 90 GHz [29]. Since advanced SiGe BiCMOS platforms provide high-performance SiGe heterojunction bipolar transistors (HBTs), they are suitable for the realization of full wideband T/R chipsets as shown in Fig. 1. Power supplies of 2.5 and 1.2 V were used for N-well biasing

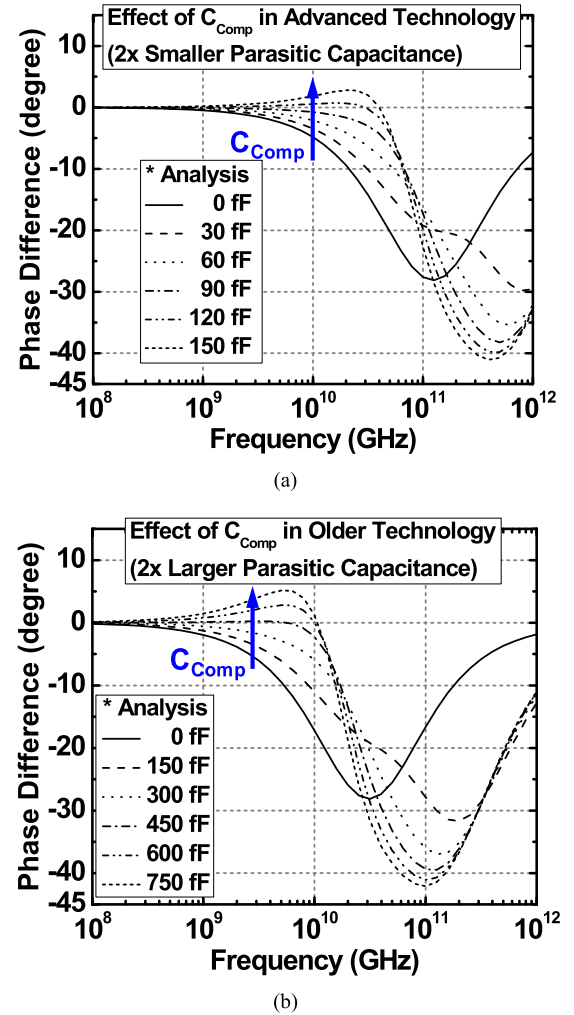


Fig. 19. Phase difference between a reference state and an attenuation state for (a) advanced technology platform which has  $2\times$  smaller parasitic capacitance and (b) older platform which has  $2\times$  larger parasitic capacitance. The values in Table I is used as a reference.

and digital control blocks, respectively. A chip micrograph is shown in Fig. 12. The core layout area without measurement pads and non-active space was  $0.14 \text{ mm}^2$  ( $1.00 \text{ mm} \times 0.14 \text{ mm}$ ), while the total chip size was  $0.98 \text{ mm}^2$  ( $1.30 \text{ mm} \times 0.75 \text{ mm}$ ). For the S-parameter characterization, a network analyzer (Agilent PNA E8364B) was used, whereas analog signal generators (Agilent PSG E8257D) and a signal analyzer (Agilent PXA N9030A) were used for linearity measurements.

In Fig. 13(a), the measured and simulated attenuation results for the major states (a reference state and 0.5/1/2/4/8/16/31.5-dB attenuation states) are shown. The measured attenuation exhibited higher loss due to an increase in parasitics associated with custom inductors and interconnect structures. Each inductor adds an additional 100–150 fF of shunt capacitance, and the interconnection presents about  $5\text{--}7 \Omega$  of series resistance from the circuit layout. The measured and the simulated relative phase variations are shown in Fig. 13(b). While the overall trend is similar, the measurement results have about  $1^\circ$  degradation for high attenuation states (8, 16, and 31.5 dB). The measured and simulated  $S_{11}$  and  $S_{22}$  are presented under major attenuation

TABLE III  
PERFORMANCE COMPARISON WITH STATE-OF-THE-ART DIGITAL-STEP ATTENUATORS

Reference	[24]	[30]	[31]	[19]	[16]	[20]	This work	
Process technology	GaAs FET	0.18 $\mu\text{m}$ GaAs PHEMT	InGaAs pin diode	0.18 $\mu\text{m}$ bulk CMOS	0.18 $\mu\text{m}$ SOI CMOS	0.25 $\mu\text{m}$ SiGe BiCMOS	0.13 $\mu\text{m}$ SiGe BiCMOS	
Topology	Distributed T-type	N/A	Switched $\pi$ -type w. pin diode	Switched T-/ $\pi$ -type w. inductive correction	Switched path w. DPDT	Switched T-/ $\pi$ -type w. iNMOS	Conventional Switched T-type	Switched T-type w. capacitive compensation
Bandwidth (GHz)	DC-20	1-15	7-40	DC-14	DC-20	6-12.5	DC-20	
Attenuation range (dB)	22.5 (4 bit) (LSB=1.5)	31.5 (6 bit) (LSB=0.5)	31 (5 bit) (LSB=1)	31.5 (6 bit) (LSB=0.5)	31 (5 bit) (LSB=1)	16.51 (7 bit) (LSB=0.26)	31.5 (6 bit) (LSB=0.5 dB)	
Insertion loss (dB)	3.1-4.8	3.0-6.2	7-11.5	3.7-10	3.1-7.6	12.7	1.7-7.4	1.7-7.2
Return loss (dB)	>13	>12	>8.0	>9	>12	13	>12	>12
RMS amplitude error (dB)	0.5	0.4	2.3	0.5	0.5	0.26	0.65	0.37
RMS phase variation ( $^\circ$ )	N/A	7.5	N/A	4.2	2.5	3.5	16	4.0
IP1dB (dBm)	24	20	N/A	15	10	12.5	10	10
OIP3 (dBm)	N/A	N/A	N/A	29	N/A	N/A	26	25
Chip area ( $\text{mm}^2$ )	4.2 (2.6 $\times$ 1.6)	3.1 (2.6 $\times$ 1.2)	1.3 (1.6 $\times$ 0.8)	0.5 (1.25 $\times$ 0.4)*	0.63 (0.93 $\times$ 0.68)	0.29	0.98 (1.30 $\times$ 0.75) 0.14 (1.00 $\times$ 0.14)*	

\* Core circuit area without pads and non-active space

states in Fig. 14(a) and (b), respectively. Since 2- and 16-dB attenuation states consist of two identical 1- and 8-dB cells, for simplicity, they are not included.

The measured attenuation results over frequency for all states from 0 to 31.5 dB are shown in Fig. 15. While the overall gaps between attenuation states are relatively constant, a few overlaps are still observed between some states from 10 to 20 GHz. The measured impedance matching results for all states are presented in Fig. 16. The input matching [ $S_{11}$  in Fig. 16(a)] and the output matching [ $S_{22}$  in Fig. 16(b)] were better than  $-12$  and  $-13$  dB for the entire bandwidth, respectively. The measured linearity of the proposed DSA is shown in Fig. 17(a). The input 1-dB-compression point (IP1dB) under a reference state is about 10–12 dBm across the operational bandwidth. The measured input third-order-intercept point (IIP3) under a reference state is about 25–27 dBm from 1 to 20 GHz. In Fig. 17(b), the measured IP1dB for the major states are presented. While IP1dB under the maximum attenuation (31.5 dB) state is about 15 dBm, the IP1dB response shows some fluctuations depending on the DSA state chosen.

The performance of the proposed wideband DSA is summarized in Table III and compared with the literature. The DSA exhibits the lowest IL among the state-of-the-art attenuators in silicon-based platforms, and the overall IL result is comparable to the best attenuators implemented in III–V technologies. In addition, the proposed DSA provides low root-mean-square (rms) amplitude/phase errors and good impedance matching for wideband operation. Regarding the attenuation roll-off in the proposed DSA, attenuators based on compound semiconductor technologies or silicon-on-insulator CMOS typically exhibit gradual roll-off due to their low parasitics. However, attenuators in bulk silicon technology suffer from steeper roll-off due to its inherently lossy substrate, which degrades the high-frequency performance of the active devices and the passive components. In order to minimize this roll-off, smaller devices can be used for obtaining smaller parasitics

at the cost of higher IL. At the system level, additional loss compensation amplifiers with an equalization function can be used for achieving flat in-band performance. Compared with other published designs, the proposed DSA also occupies the smallest core chip area, since it employs a small number of on-chip inductors and avoids the use of transmission lines as matching elements. While the linearity of the proposed DSA is somewhat limited, several high power-handling switch techniques, including stacked transistors, feed-forward capacitors, and negative bulk bias, can be applied for future design optimization, as required [32]. Table III also includes the performance of the uncompensated DSA as a reference circuit. It employs conventional switched T-type cells and the loss-minimized reduced T-type attenuator cells. While the matching and linearity results of both the reference and the proposed attenuators are similar, the amplitude and the phase variations are significantly improved in the proposed DSA. The measured rms amplitude errors and phase variations over frequency are shown in Fig. 18. The proposed attenuator exhibits a reduction of 45% and 75% in the amplitude and the phase variations at 20 GHz, respectively.

It should be noted that the amplitude/phase compensation technique is applicable to other technology platforms in general. As a conceptual verification, the phase difference of an 8-dB attenuator cell is simulated for increased and reduced capacitance with respect to Table I, in order to reflect the use of both more advanced and older technology platforms, respectively. When the capacitance of transistors is reduced by 50% [Fig. 19(a)],  $C_{\text{Comp}}$  of about 120 fF shows the flat response up to 30 GHz. On the other hand, when the capacitance is doubled [Fig. 19(b)],  $C_{\text{Comp}}$  of about 450 fF is the optimal for the maximum bandwidth of 6 GHz. In both extreme cases, the usable bandwidth is extended by more than a decade. Hence, the amplitude/phase-compensation technique investigated in this paper can be used in practical DSA designs as a simple, yet effective performance optimization method.

#### IV. CONCLUSION

In this paper, the design and the analysis of a wideband low-loss DSA with minimized amplitude/phase variations are presented. The DSA based on the combination of amplitude/phase-compensated switched T-type cells and loss-minimized T-type attenuator cells was implemented in a 130-nm SiGe BiCMOS technology platform. The fabricated DSA achieves low IL, minimized variations, matching characteristics, moderate linearity, and compact size.

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