

# Boost.Graph tutorial

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## 1 Introduction

### 1.1 Coding style used

I prefer not to use the keyword `auto`, but to explicitly mention the type instead. I think this is beneficial to beginners. When using `Boost.Graph` in production code, I do prefer to use `auto`.

## 2 Creating graphs

`Boost.Graph` is about creating graphs. In this chapter we create graphs, starting from simple to more complex.

### 2.1 Creating an empty graph

Let's create a trivial empty graph:

---

**Algorithm 1** Creating an empty graph

---

```
#include "create_empty_graph.h"

boost::adjacency_list<
create_empty_graph() noexcept
{
    return boost::adjacency_list<>();
}
```

---

Congratulations, you've just created a `boost::adjacency_list` in which:

- The out edges are stored in a `std::vector`
- The vertices are stored in a `std::vector`
- The graph is directed

- Vertices, edges and graph have no properties
- Edges are stored in a `std::list`

The `boost::adjacency_list` is the most commonly used graph type, the other is the `boost::adjacency_matrix`.

## 2.2 Creating $K_2$ , a fully connected graph with two vertices

To create a fully connected graph with two vertices (also called  $K_2$ ), one needs two vertices and one (undirected) edge, as depicted in figure 1.

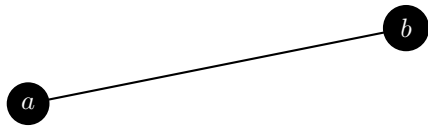


Figure 1:  $K_2$ : a fully connected graph with two vertices named  $a$  and  $b$

To create  $K_2$ , the following code can be used:

---

```
#include "create_k2_graph.h"

boost::adjacency_list<
    boost::vecS,
    boost::vecS,
    boost::undirectedS
>
create_k2_graph() noexcept
{
    using graph = boost::adjacency_list<
        boost::vecS,
        boost::vecS,
        boost::undirectedS
    >;
    using vertex_descriptor
        = typename boost::graph_traits<graph>::
            vertex_descriptor;
    using edge_descriptor
        = typename boost::graph_traits<graph>::
            edge_descriptor;
    using edge_insertion_result
        = std::pair<edge_descriptor, bool>;

    graph g;
    const vertex_descriptor va = boost::add_vertex(g);
    const vertex_descriptor vb = boost::add_vertex(g);
```

```
const edge_insertion_result ea = boost::add_edge(va, vb
    , g);
assert(ea.second);
return g;
}
```

---

Note that this code has more lines of using statements than actual code! In this code, the third template argument of `boost::adjacency_list` is `boost::undirectedS`, to select (that is what the S means) for an undirected graph. Adding a vertex with `boost::add_vertex` results in a vertex descriptor, which is a handle to the vertex added to the graph. Two vertex descriptors are then used to add an edge to the graph. Adding an edge using `boost::add_edge` returns two things: an edge descriptor and a boolean indicating success. In the code example, we assume insertion is successful.

Note that the graph lacks all properties: nodes do not have names, nor do edges.