

# Java Threads →

## Basic LABS

Lab sources: <gitlab address>

# Exo1: Basic Multi-Threads

- Define a `Thread` subclass called `MyThread`
  - Each instance receives a `String name` upon creation
  - The `run()` method
    - Prints a message iteratively , for 100 times
    - Each message: <the thread's `name`> and <iteration index: 1..100>
    - Sleeps for 50ms between iterations
    - Prints an END message before exiting
- In a `main` method, create 2 instances of `MyThread` and start them
  - What is the order of the message printouts?
  - Execute several times: is the order the same each time?
  - Same questions when: adding more threads; changing the sleep delays.

# Exo2: Command Buffer

- Define a CommandsBuffer class as shown in the slides
  - Stores commands in an array: `String[ ] commands`
  - Provides `push` and `pop` methods to add and remove commands to/from the buffer, respectively
- Define two Thread types: PushThread and PullThread
  - Both take a CommandBuffer instance as input upon creation
  - Both act on the buffer for 100 iterations, with a sleep of 50ms in-between iterations
    - PushThread calls `push` on the buffer
    - PullThread calls `pull` on the buffer
- The main method creates an instance of each Thread type and starts them; use `join` at the end.
- Questions:
  - As the two threads push and pull 100 commands each, the buffer should be empty at the end – is this so?
  - Remove all synchronisation commands from the push and pull methods (`synchronize`, `wait` and `notifyall`) – is the outcome any different? why?
  - Leave synchronisation and remove the wait and notify commands from the push method – what happens?