Gradient descent

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Application cases

Minimize a differentiable function f

$$\min_{x \in \mathbb{R}^n} f(x)$$

A very simple algorithm, and the basis for more evolved ones

Problems that fit in this framework

- ► Least squares $f(x) = \frac{1}{2} ||Zx y||^2$
- ▶ logistic regression $f(x) = \log(1 + \exp(-y_i z_i^\top x)) + \lambda ||x||^2$
- ► Collaborative filtering $f(P,Q) = \sum_{(i,j) \in C} (R_{i,j} \sum_{k=1}^K P_{i,k} Q_{k,j})^2$
- **.**..

The algorithm

► Goal: Minimize a differentiable function f

$$\min_{x \in \mathbb{R}^n} f(x)$$

Algorithm: Let $(\gamma_k)_k$ with $\gamma_k > 0$ be a step size sequence. Fix $x_0 \in \mathbb{R}^n$ and for all $k \in \mathbb{N}$, do

$$x_{k+1} = x_k - y_k \nabla f(x_k)$$

- ► Requirements:
 - + Be able to compute of
 - · Set (YK) so that f(UK) → min f(X)



Analysis without convexity

$$x_{k+1} = x_k - \gamma_k \nabla f(x_k)$$

Assumptions:

 ∇f is L-Lipschitz continuous: $\|\nabla f(x) - \nabla f(y)\| \le \|x - y\|$ $\inf_{x} f(x) > -\infty$

Theorem:

- i) $(f(x_k))$ is decreasing and converges
- ii) $\lim_{k\to+\infty} \|\nabla f(x_k)\| = 0$

Proof:

By Taylor-Lagrange inequality

$$f(x_{kn}) \leq f(x_k) + \langle \nabla f(x_k), x_{kn} - x_k \rangle + \frac{1}{2} \|x_{kn} - x_k\|^2 \leq f(x_k) - (y_k - \frac{1}{2} y_k^2) \|\nabla f(x_k)\|^2$$

We choose
$$\gamma_k = \gamma < \frac{2}{L}$$
 then $\|\nabla f(\mathbf{x}_k)\| \leq \frac{1}{\gamma - \frac{L}{\Sigma} \gamma^2} \left(f(\mathbf{x}_k) - f(\mathbf{x}_{kn})\right)$

Suppose f is convex and ∇f is L-Lipschitz: $x_0 \in \mathbb{R}^n$ and $x_{k+1} = x_k - \frac{1}{L} \nabla f(x_k)$

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|^2$$

$$\leq f(x_k) + \langle \nabla f(x_k), x_* - x_k \rangle + \frac{L}{2} \|x_* - x_k\|^2 - \frac{L}{2} \|x_* - x_{k+1}\|^2$$

$$\leq f(x_*) + \frac{L}{2} \|x_* - x_k\|^2 - \frac{L}{2} \|x_* - x_{k+1}\|^2$$

$$\frac{K}{L}\big(f(x_K) - f(x_*)\big) \leq \frac{1}{L}\Big(\sum_{k=0}^{K-1} f(x_{k+1}) - f(x_*)\Big) \leq \frac{1}{2}\|x_* - x_0\|^2 - \frac{1}{2}\|x_* - x_K\|^2$$

$$f(x_K) - f(x_*) \le \frac{L\|x_* - x_0\|^2}{2K}$$

Suppose f is convex and ∇f is L-Lipschitz: $x_0 \in \mathbb{R}^n$ and $x_{k+1} = x_k - \frac{1}{L} \nabla f(x_k)$

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} ||x_{k+1} - x_k||^2$$

$$\leq f(x_k) + \langle \nabla f(x_k), x_* - x_k \rangle + \frac{L}{2} ||x_* - x_k||^2 - \frac{L}{2} ||x_* - x_{k+1}||^2$$

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Suppose f is convex and ∇f is L-Lipschitz: $x_0 \in \mathbb{R}^n$ and $x_{k+1} = x_k - \frac{1}{L} \nabla f(x_k)$

RHS independent of x_*

$$\overbrace{f(x_{k+1})} \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|^2
\leq f(x_k) + \langle \nabla f(x_k), x_* - x_k \rangle + \frac{L}{2} \|x_* - x_k\|^2 - \frac{L}{2} \|x_* - x_{k+1}\|^2
\leq f(x_*) + \frac{L}{2} \|x_* - x_k\|^2 - \frac{L}{2} \|x_* - x_{k+1}\|^2$$

$$\frac{K}{L}(f(x_K) - f(x_*)) \le \frac{1}{L}\left(\sum_{k=0}^{K-1} f(x_{k+1}) - f(x_*)\right) \le \frac{1}{2}\|x_* - x_0\|^2 - \frac{1}{2}\|x_* - x_K\|^2$$

$$f(x_K) - f(x_*) \le \frac{L\|x_* - x_0\|^2}{2K}$$

Suppose f is convex and ∇f is L-Lipschitz: $x_0 \in \mathbb{R}^n$ and $x_{k+1} = x_k - \frac{1}{L} \nabla f(x_k)$

$$\begin{array}{l}
f \text{ is convex} \\
f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} ||x_{k+1} - x_k||^2 \\
\leq f(x_k) + \langle \nabla f(x_k), x_* - x_k \rangle + \frac{L}{2} ||x_* - x_k||^2 - \frac{L}{2} ||x_* - x_{k+1}||^2 \\
\leq f(x_*) + \frac{L}{2} ||x_* - x_k||^2 - \frac{L}{2} ||x_* - x_{k+1}||^2
\end{array}$$

$$\frac{K}{L}(f(x_K) - f(x_*)) \le \frac{1}{L}\left(\sum_{k=0}^{K-1} f(x_{k+1}) - f(x_*)\right) \le \frac{1}{2}\|x_* - x_0\|^2 - \frac{1}{2}\|x_* - x_K\|^2$$

$$f(x_K) - f(x_*) \le \frac{L\|x_* - x_0\|^2}{2K}$$

Summary of convergence results for gradient descent

No convexity

f is convex

f is $\mu\text{-strongly convex}$

Subgradient method

What if f is not differentiable?

$$g \in \partial f(x) \Leftrightarrow f(y) > f(x) + (9, 9-x) \forall y.$$

Algorithm

$$g_k \in \partial f(x_k)$$

$$x_{k+1} = x_k - \gamma_k g_k$$

$$\bar{x}_k^{\gamma} = \frac{1}{\sum_{l=0}^k \gamma_l} \sum_{j=0}^k \gamma_j x_j$$

Theorem

If f is convex and Lipschitz continuous and $\gamma_k=\frac{\gamma_0}{\sqrt{k+1}}$ $f(\bar{x}_k^\gamma)-f(x^*)\in O(\frac{\ln(k)}{\sqrt{k}})$

Example on Lasso problem

$$\min_{x} \frac{1}{2} \|Ax - b\|_{2}^{2} + \lambda \|x\|_{1} = \min_{x} f(x)$$

$$x_{k+1} = x_{k} - \frac{\gamma_{0}}{\sqrt{k}} g_{k}, \qquad g_{k} \in \partial f(x_{k})$$

$$\lim_{x \to \infty} \frac{1}{2} \|Ax - b\|_{2}^{2} + \lambda \|x\|_{1} = \min_{x} f(x)$$

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iteration number

Example on Lasso problem

$$\min_{x} \frac{1}{2} ||Ax - b||_{2}^{2} + \lambda ||x||_{1} = \min_{x} f(x)$$

$$x_{k+1} = x_{k} - \frac{\gamma_{0}}{\sqrt{k}} g_{k}, \quad g_{k} \in \partial f(x_{k})$$

$$x_{k+1} = \operatorname{prox}_{\frac{1}{L}g} (x_{k} - \frac{1}{L} \nabla f(x_{k}))$$

$$10^{-1}$$

$$10^{-2}$$

$$\frac{1}{2} \int_{0}^{1} \int_{0}^{1} dx \, dx \, dx = 1$$

$$10^{-4}$$

$$10^{-5}$$

$$0 \quad 5 \quad 10 \quad 15 \quad 20 \quad 25 \quad 30 \quad 35 \quad 40$$

iteration number

Proximal gradient descent

- ▶ The subgradient method is a general but slow algorithm
- ▶ Idea: use structure of the problem to design a faster algorithm
- Composite objective: $\min_x f(x) + g(x)$ f differentiable and ∇f is L-Lipschitz g not differentiable but $\operatorname{prox}_g(x) = \arg\min_y g(y) + \frac{1}{2} \|x - y\|^2$ easy to compute

Algorithm

$$x_{k+1} = \operatorname{prox}_{\frac{1}{L}g}\left(x_k - \frac{1}{L}\nabla f(x_k)\right)$$

Theorem

If f is convex, ∇f is L-Lipschitz and g is convex, then

$$f(x_k) + g(x_k) - f(x^*) - g(x^*) \le \frac{L}{2k} ||x_0 - x^*||^2$$

Moreover, if f + g is strongly convex, we have linear convergence



Why does it work?

Set
$$T(x) = \operatorname{prox}_{\frac{1}{l}g}\left(x - \frac{1}{l}\nabla f(x)\right) = T_2 \circ T_1(x)$$

Proposition

$$\|\operatorname{prox}_{\gamma_{\mathcal{B}}}(x) - \operatorname{prox}_{\gamma_{\mathcal{B}}}(y)\| \le \|x - y\|$$

Show that T is a contraction as soon as T_1 is a contraction.

Examples of proximal operators

- Let C be a convex set and $g(x) = \iota_C(x) = \begin{cases} 0 & \text{if } x \in C \\ +\infty & \text{if } x \notin C \end{cases}$ $\operatorname{prox}_{\gamma\iota_C}(x) = \arg\min_y \gamma\iota_C(y) + \frac{1}{2}\|x y\|^2 = \arg\min_{y \in C} \frac{1}{2}\|x y\|^2 = \operatorname{Proj}_C(x)$ $\operatorname{Proximal gradient descent generalizes projected gradient descent}$
- $prox_{\gamma|\cdot|}(x) = \begin{cases} x + \gamma & \text{if } x < -\gamma \\ 0 & \text{if } -\gamma \le x \le \gamma \\ x \gamma & \text{if } x > \gamma \end{cases}$
- ▶ $g: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ such that $g(x) = \sum_{i=1}^n g_i(x_i)$ (g is thus a separable function)

For all i, the ith coordinate of $prox_{\gamma g}(x)$ is $(prox_{\gamma g}(x))_i = prox_{\gamma g_i}(x_i)$

