

EtherCAT Slave Editor

An editor for creating SOES slaves

rt-labs AB



Background

- When developing an EtherCAT slave it is often tiresome and error prone to update the object dictionary, ESI file and EEPROM and keep them aligned
- ► The EtherCAT Slave Editor is a tool for helping out with this process
- ► The EtherCAT Slave Editor generates ESI files, EEPROM files, object dictionaries and data structures for slaves using the SOES stack by providing a easy to use interface



Preparation

- Download the EtherCAT Slave Editor from http://download.rt-labs.com/ethercat/slaveeditor
- ► Unzip and run
- ► The Slave Editor needs the Java Runtime Environment (JRE): http://www.oracle.com/technetwork/java/javase/ downloads/jre8-downloads-2133155.html



Create a project

- ► First we need to create a project
- Right click in the Project Explorer
- ► Choose New / Project

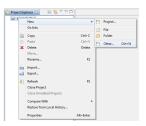






Use the EtherCAT Slave Editor

► To work with the EtherCAT Slave Editor we need to add a slave description file







Use the EtherCAT Slave Editor

- ► Choose a file destination and fill in some basic administrative data
- Parts of the data will be remembered when creating other slaves

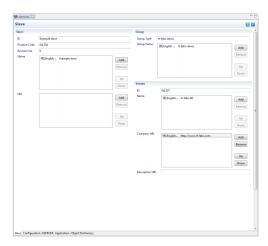


New File Wizard				- C - X-
EtherCAT Slave Editor				
Enter slave parameters				
Product ID	Example slave			
Product Code				
Product Name	Example slave			
Group Type	rt-labs slaves			
Group Name	rt-labs slaves			
Vendor ID	0:1337			
Vendor Name	rt-labs AB			
(P)	< Back	Next >	Finish	Cancel



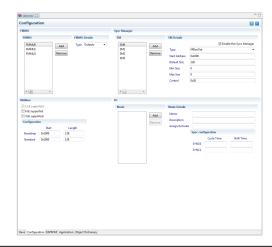
Administrative data

► This tab contains information previously provided in the wizard





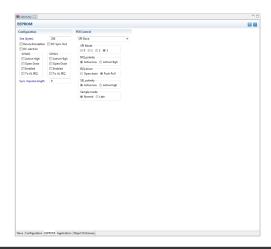
► Parameters for an advance slave with CoE and inputs and outputs are filled in by default





EEPROM/ESC connection

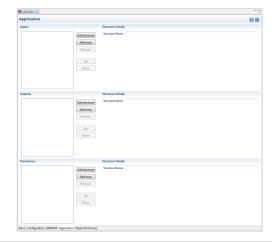
► This tab contains settings for the EEPROM such as the connection method of the ESC





Process and service data

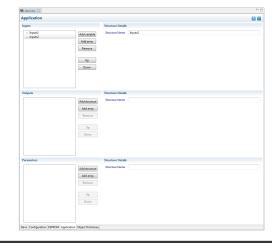
- ► In the Application tab we design the interface between the slave and the system
- ► In this tab we specify our PDOs and SDOs





Process and service data

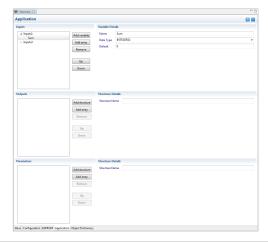
- We have the possibility to add multiple structures
- ► In this case we have created two structures which will later appear at different indexes in the object dictionary
- ► Inputs are the data that is sent from the slave





Process and service data

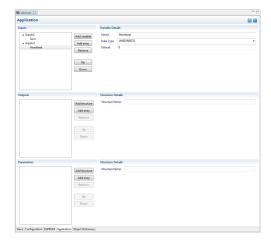
► Add a variable named **Sum** to the **Inputs1** structure





Process and service data

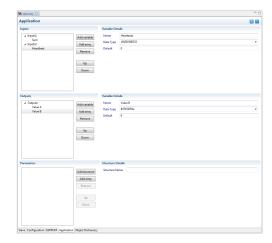
► Add a variable named Heartbeat to the Inputs2 structure





Process and service data

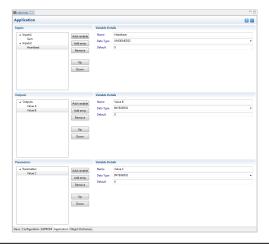
- ► Add an Output structure
- Add two PDOs to the Output structure





Process and service data

► And add an SDO as well





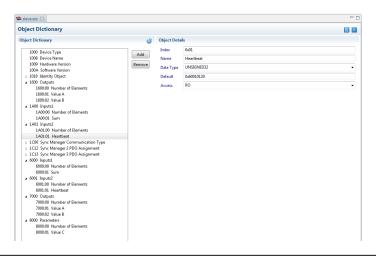
Object dictionary

- ► The Object dictionary tab provides a visualisation of the object dictionary
- ► To populate the object dictionary with the data supplied on the other tabs we need to synchronize it





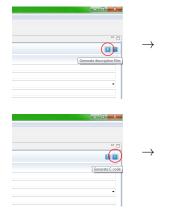
Populated object dictionary

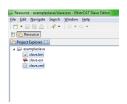


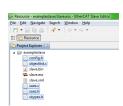


Generate files

EEPROM, ESI, code









Download SOES

- ► The generated files could be used with **SOES**
- ► **SOES** is available for download from Open EtherCAT Society's GitHub page
- ▶ https://github.com/OpenEtherCATsociety/SOES



Implement callback functions

- All function interfaces are specified in soes.h
- We need to implement the callback functions to handle the PDO and SDO exchanges

```
* This function reads physical input values and assigns the
corresponding members of Rb.Inputs1
*/
void cb_get_Inputs1();

/**

* This function reads physical input values and assigns the
corresponding members of Rb.Inputs2
*/
void cb_get_Inputs2();

/**

* This function writes physical output values from the
corresponding members of Wb.Outputs
*/
void cb_set_Outputs();

/**

* This function is called after a SDO write of the object
cb.Parameters.
*/
void cb_post_write_Parameters(int subindex);
```

Example implementation of the callback functions

```
void cb_get_Inputs1()
{
    Rb.Inputs1.Sum = Wb.Outputs.Value_A + Wb.Outputs.Value_B + Cb.Parameters.Value_C;
}

void cb_get_Inputs2()
{
    static int32_t tick = 0;
    Rb.Inputs2.Heartbeat = tick++;
}

void cb_set_Outputs()
{
}

void cb_post_write_Parameters(int subindex)
{
    if (subindex == 1)
        printf ("Value_C_written_->_UXd\n", Cb.Parameters.Value_C);
}
```