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# Adversarial Search

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# Objectives

- ▶ To know the basics of adversarial search.
- ▶ To apply the *minimax* algorithm and *alpha-beta* pruning.

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# 1 Adversarial search

Adversarial search consists in finding the best move in games being:

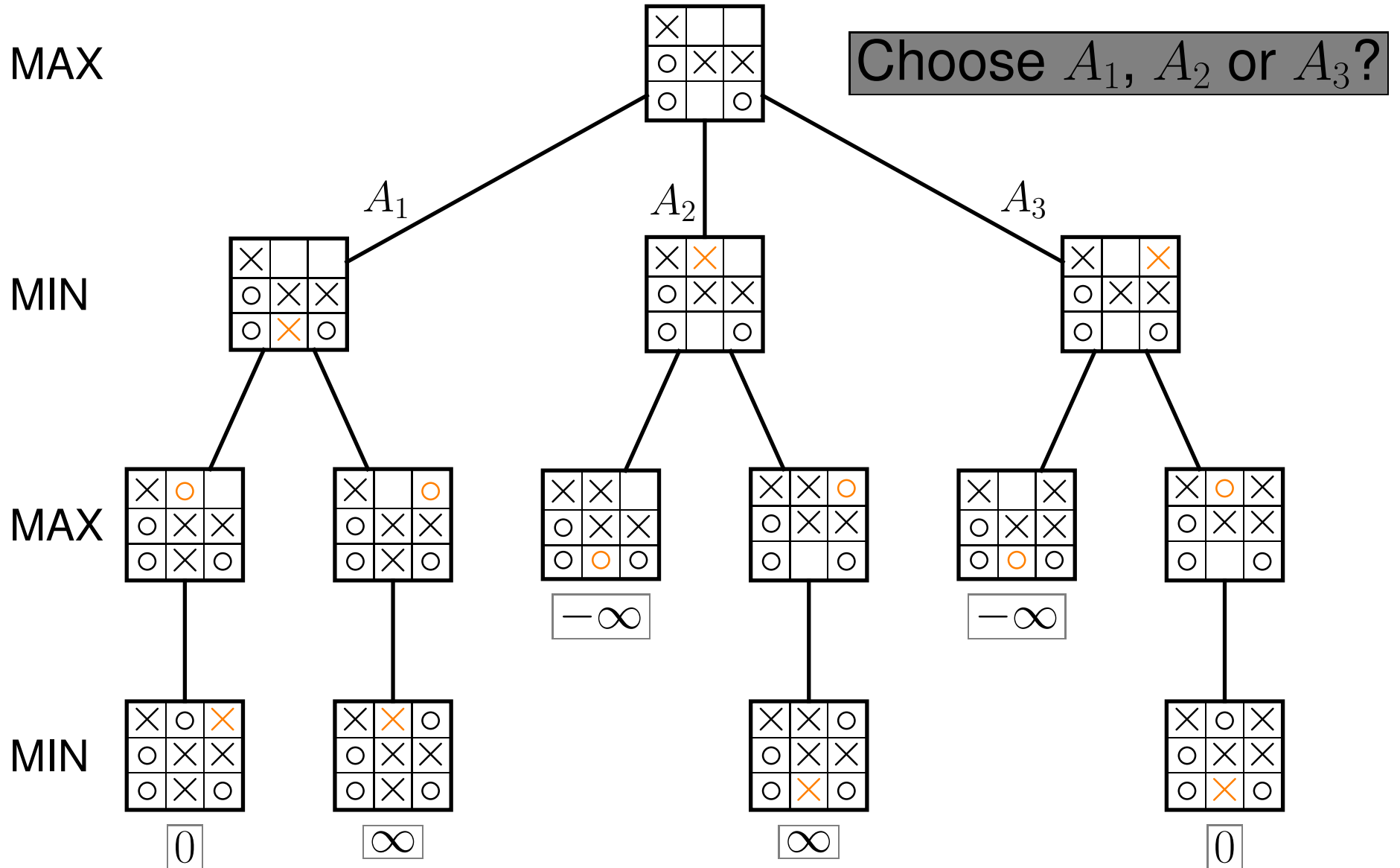
- ▶ **Deterministic** i.e. luck does not play a role
- ▶ **Two-player** MAX (the system) and MIN (the opponent)
- ▶ **Turn-taking** MAX starts and decides its move
- ▶ **Perfect info** states and rules are known (i.e. chess)
- ▶ **Zero-sum** MAX/MIN utilities balanced at the end of the game

Basic elements:

- ▶ **Initial state**  $s_0$ : from which MAX chooses the best move.
- ▶ **Actions( $s$ ):** set of legal moves from state  $s$ .
- ▶ **Terminal( $s$ ):** true if the game in  $s$  is over and false otherwise.
- ▶ **Utility( $s$ ):** utility for MAX of the terminal state  $s$ .

**Goal: choose a move leading to a state of maximum utility**

# Example: Choose a move in tic-tac-toe



## 2 Minimax algorithm and alpha-beta pruning

Minimax value, decision and algorithm:

- ▶ **Minimax value** of a state/node: utility (for MAX) of the terminal state that we reach if both players play optimally.
- ▶ **Minimax decision**: Choose the move with highest minimax value
- ▶ **Minimax algorithm**: Computation of minimax decision based on (bounded) depth-first adversarial search.

### *Basic minimax algorithm*

```
mm( $s$ ,  $d$ ,  $max$ )           // state, depth,  $max$ ="Does MAX move?"  
if  $s$  is terminal: return utility for  $s$   
if  $d = 0$ :                return heuristic value for  $s$   
// if  $max$ , return maximum minimax value from children  
if  $max$ :  $v = -\infty$ ;  $\forall n \in \text{succ}(s)$ :  $v = \max(v, \text{mm}(n, d - 1, \text{FALSE}))$   
// if  $min$ , return minimum minimax value from children  
else:    $v = \infty$ ;    $\forall n \in \text{succ}(s)$ :  $v = \min(v, \text{mm}(n, d - 1, \text{TRUE}))$   
return  $v$ 
```

# Solution for minimax example

# Minimax algorithm and alpha-beta pruning

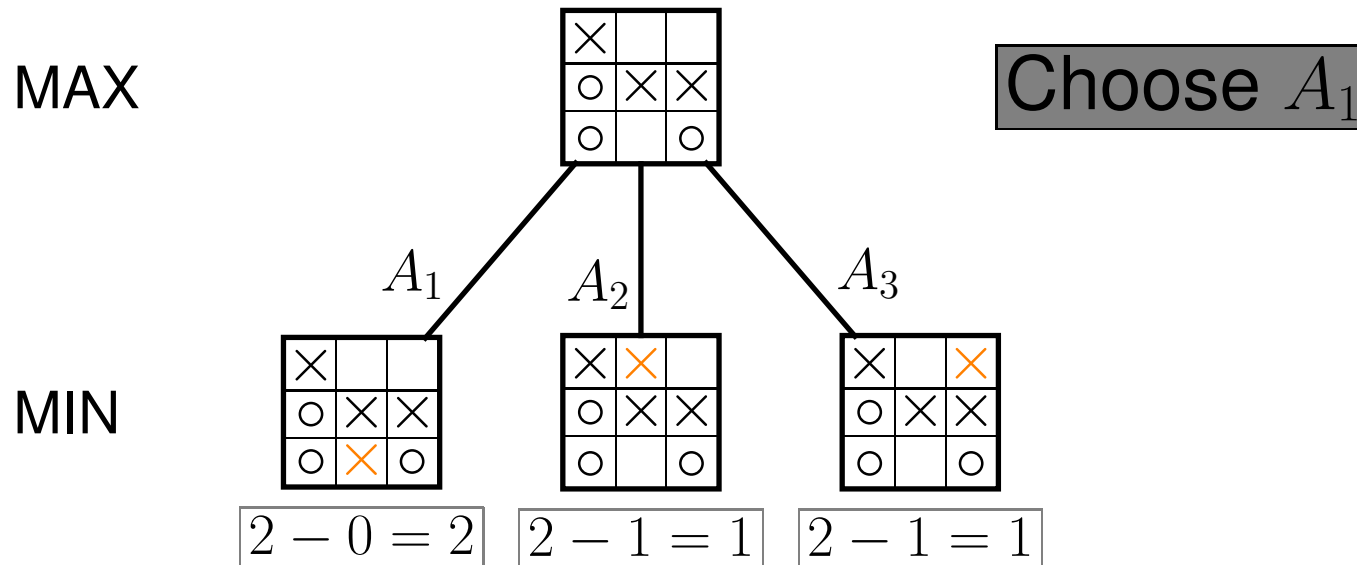
```
mm( $s, d, max$ )           // state, depth,  $max$ ="Does MAX move?"  
if  $s$  is terminal: return utility for  $s$   
if  $d = 0$ :           return heuristic value for  $s$   
if  $max$ :  $v = -\infty$ ;  $\forall n \in \text{succ}(s)$ :  $v = \max(v, \text{mm}(n, d - 1, \text{FALSE}))$   
else:    $v = \infty$ ;    $\forall n \in \text{succ}(s)$ :  $v = \min(v, \text{mm}(n, d - 1, \text{TRUE}))$   
return  $v$ 
```

```
 $\alpha$ - $\beta$ ( $s, d, \alpha, \beta, max$ )  
if  $s$  is terminal: return utility for  $s$   
if  $d = 0$ :           return heuristic value for  $s$   
if  $max$ :  $v = -\infty$   
         $\forall n \in \text{succ}(s)$   
             $v = \max(v, \alpha\text{-}\beta(n, d - 1, \alpha, \beta, \text{FALSE}))$   
             $\alpha = \max(\alpha, v)$ ;   if  $\beta \leq \alpha$ : break //  $\beta$  cut  
else:    $v = \infty$   
         $\forall n \in \text{succ}(s)$   
             $v = \min(v, \alpha\text{-}\beta(n, d - 1, \alpha, \beta, \text{TRUE}))$   
             $\beta = \min(\beta, v)$ ;   if  $\beta \leq \alpha$ : break //  $\alpha$  cut  
return  $v$ 
```



# Solution for example of alpha-beta pruning

# Solution for example max depth $d=1$ and heuristic



Heuristic function:

$$h(n, j) = \text{open}(n, \text{MAX}) - \text{open}(n, \text{MIN})$$

where

$\text{Open}(n, j)$  = "After placing player  $j$  their mark in all empty squares, number of their winning combinations"

# Conclusions

- ▶ We have studied the basics of adversarial search.
- ▶ We have applied the *minimax* algorithm and *alpha-beta* pruning.
- ▶ See [1, Chapter 5] for more details.

# References

- [1] S. Russell and P. Norvig. *Artificial Intelligence: A Modern Approach*. Pearson, third edition, 2010.