

Compressed Sensing

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Advanced Seminar

02/06/2017

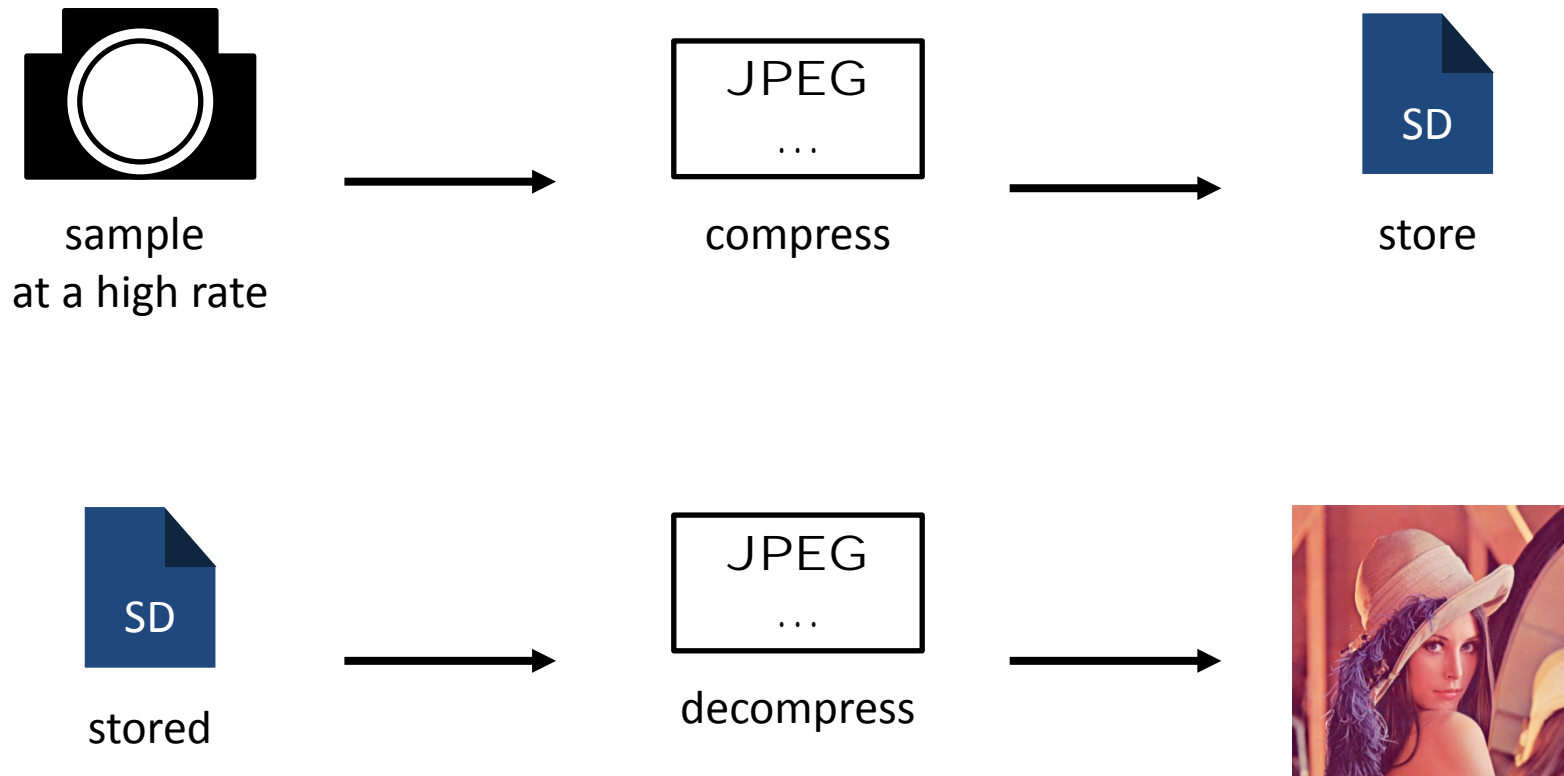
ziti, Heidelberg University

Supervisor: Prof. Dr. Peter Fischer

Outline

1. Compression after sensing
2. Why we can compress
3. Theory on Compressed Sensing
4. Example applications

Compression after sensing



Problems of „Compression after Sensing“

We likely gather too much data

Sampling with Shannon rate

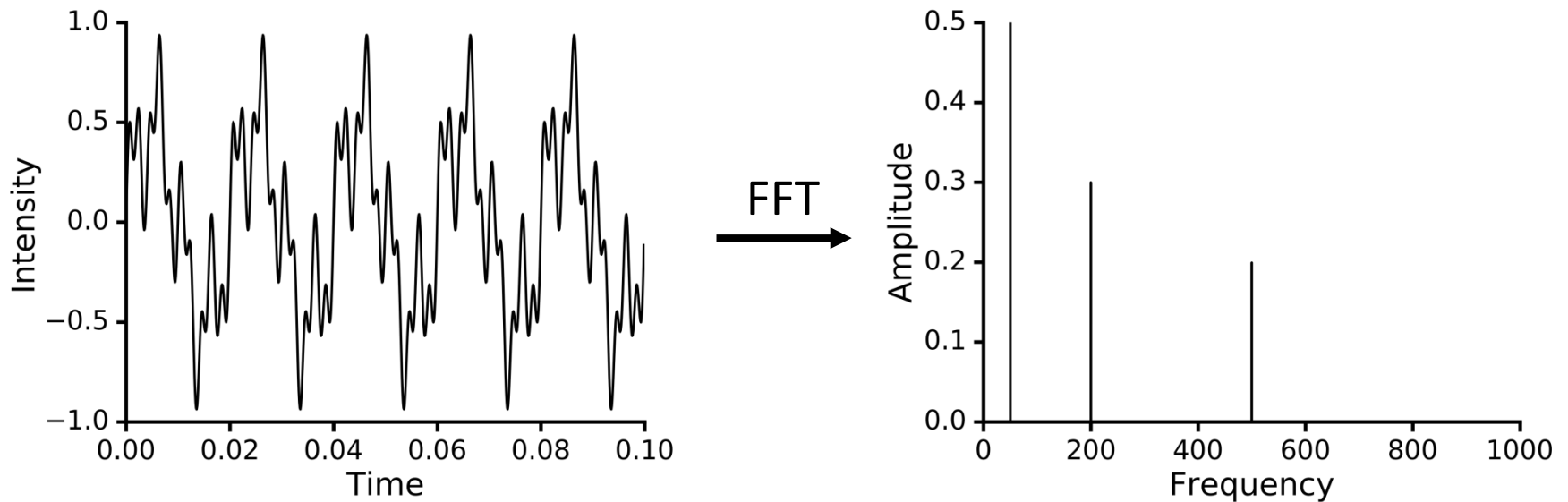
- slow
- expensive
- problematic (eg. medical applications)

Compression on recorder side

- expensive (satellites)

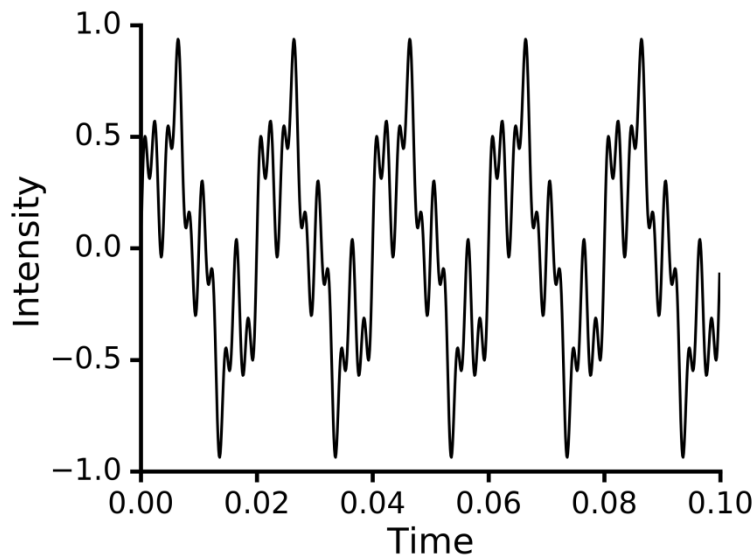
Sparsity – why we can compress

Superposition of 3 sinus waves:

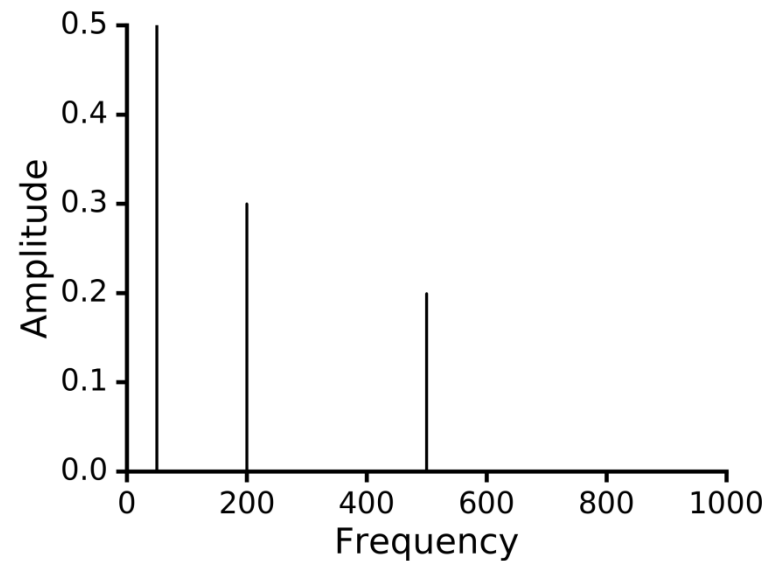


Sparsity – why we can compress

Superposition of 3 sinus waves:



FFT
→

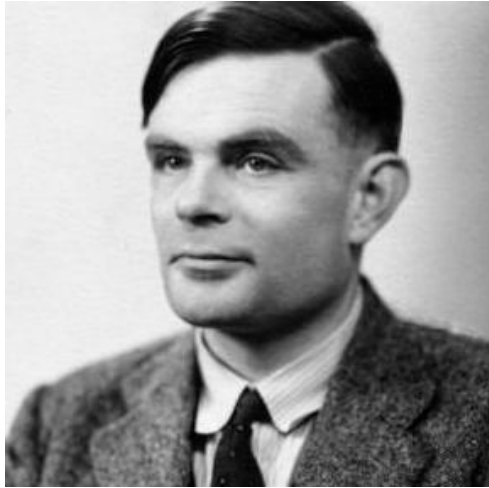


→ sampling at at least 1000Hz
twice the highest frequency
according to Shannon

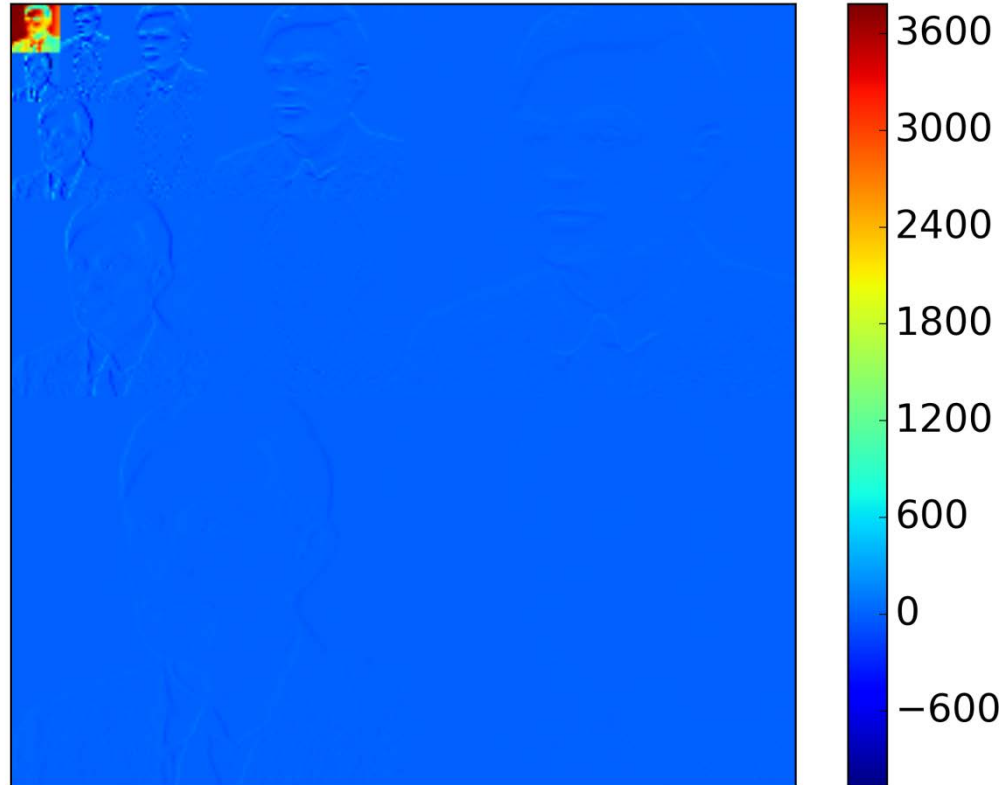
→ 6 parameters:
3 frequencies
3 amplitudes

Sparsity – why we can compress

8bit 288x288 image:

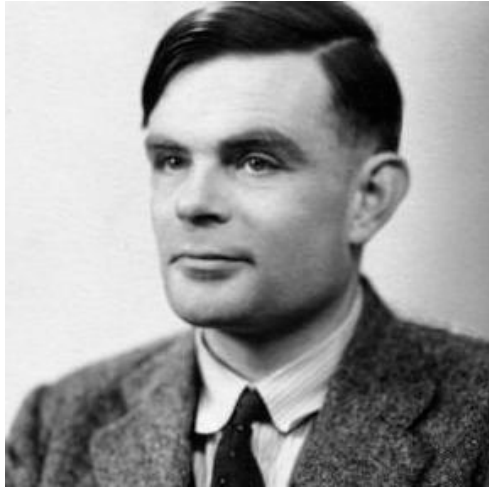


Wavelet
Trafo

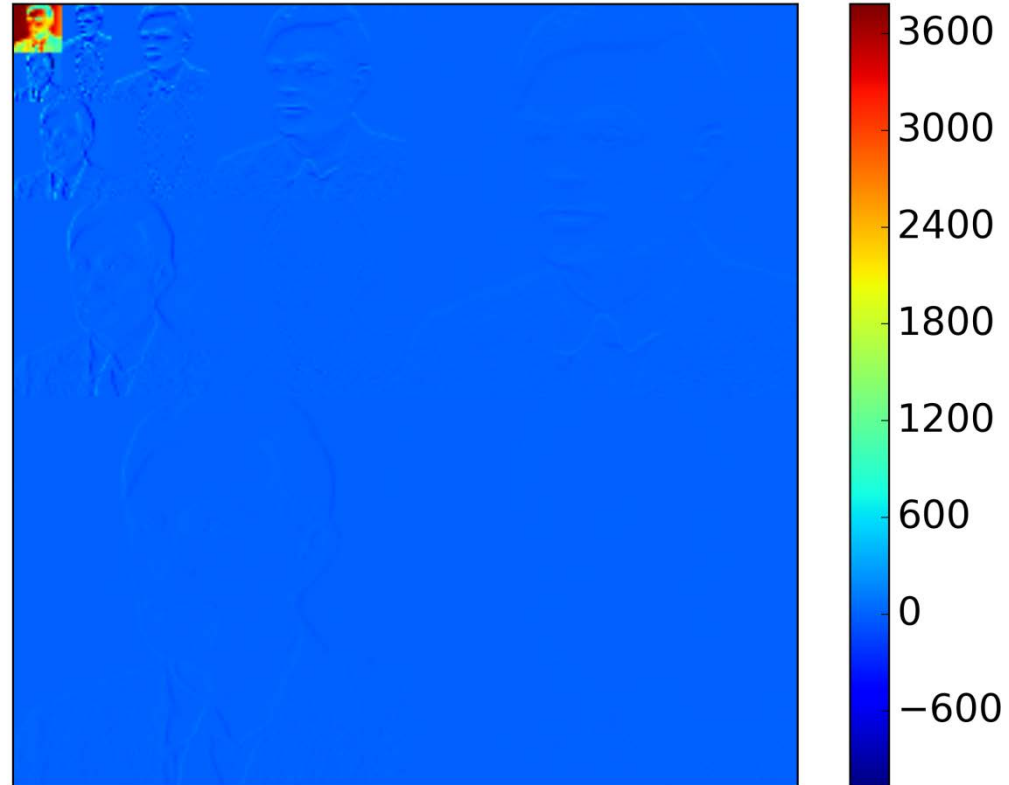


Sparsity – why we can compress

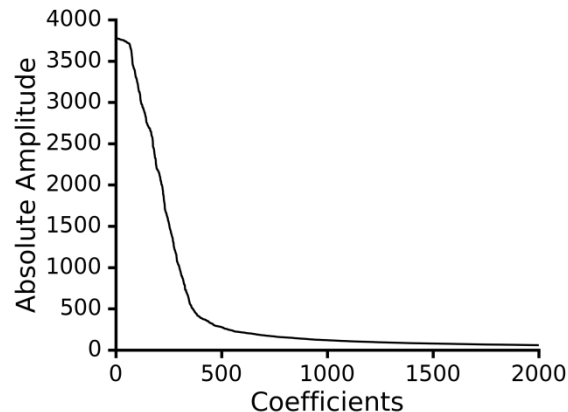
8bit 288x288 image:



Wavelet
Trafo



First 2000 of ~83k coefficients:



→ Most coefficients close to 0

Sparsity – why we can compress

Omitting the 90% smallest coefficients
and transforming back:

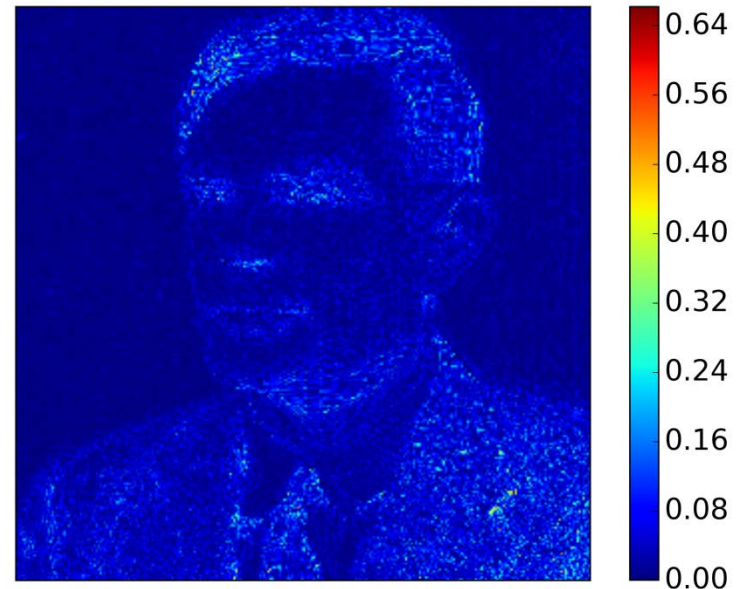


Sparsity – why we can compress

Omitting the 90% smallest coefficients
and transforming back:



Relative difference to original image:



Sparsity – why we can compress

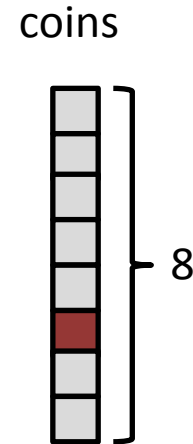
most signals are sparse in some basis
(e.g. Fourier, Wavelet)

Counterfeit example

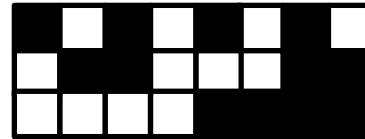
How many weightings do we need to always find the counterfeit?

Hint 1: it is not 8

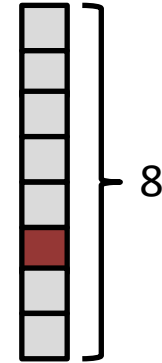
Hint 2: you may want to weigh multiple coins at once



Counterfeit example



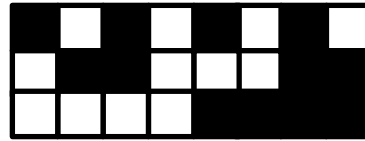
coins



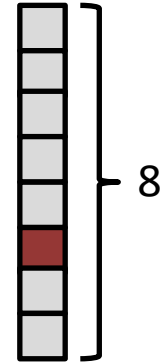
Counterfeit example



=



coins



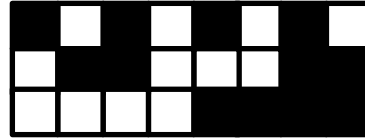
Counterfeit example

measurement

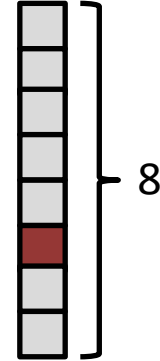


=

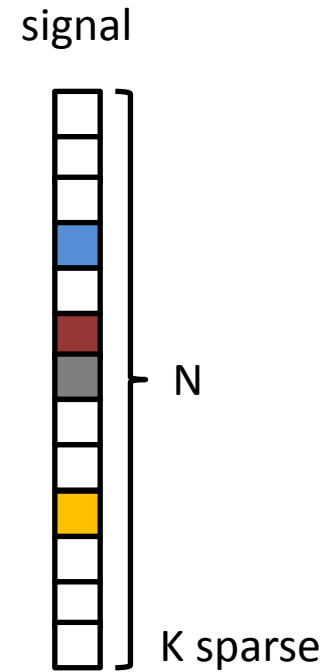
sensing matrix



signal



Sensing a sparse vector



Standard approach

measurement

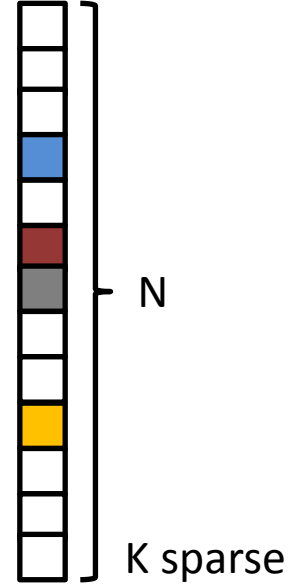


sensing matrix



=

signal

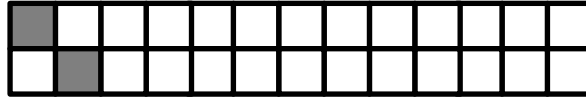


Standard approach

measurement

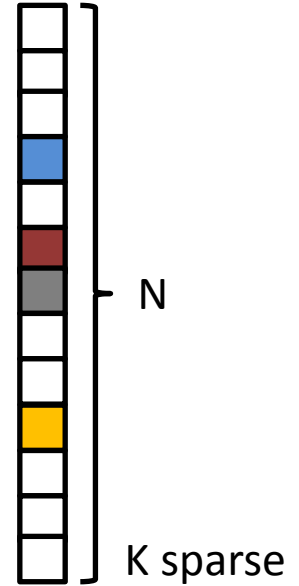


sensing matrix



=

signal

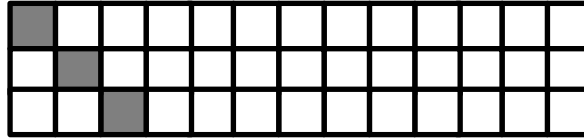


Standard approach

measurement

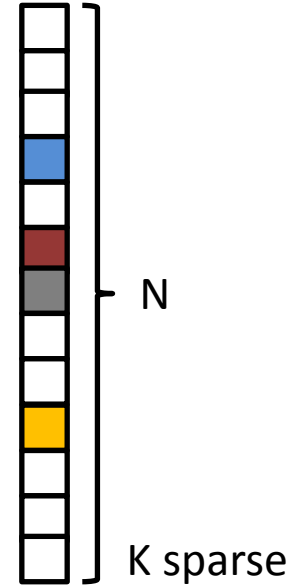


sensing matrix



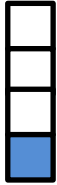
=

signal

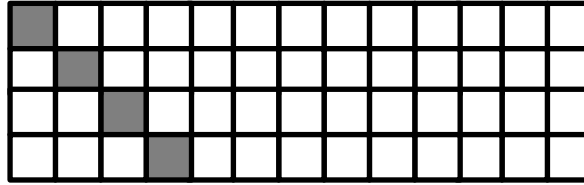


Standard approach

measurement

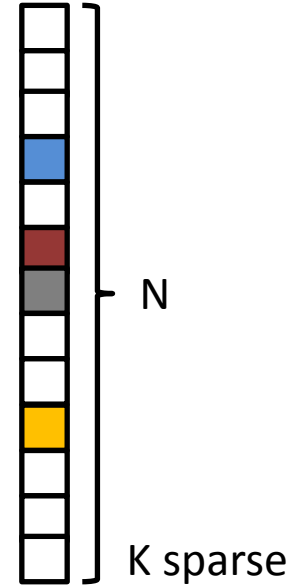


sensing matrix



=

signal

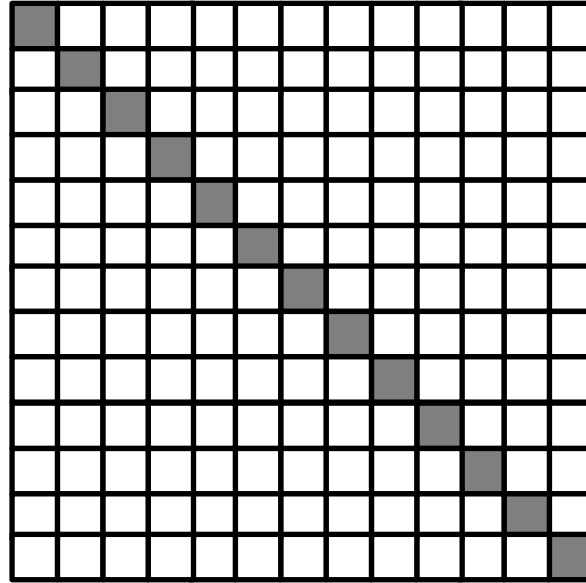


Standard approach

measurement

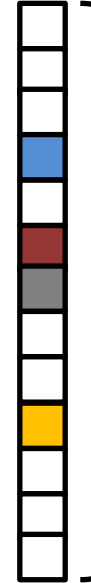


sensing matrix



=

signal



x

N

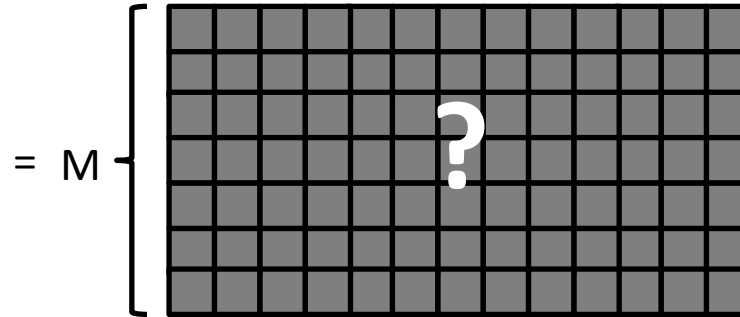
K sparse

Compressed Sensing

measurement



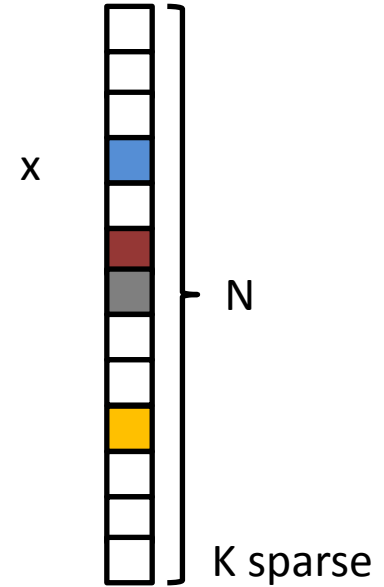
sensing matrix



$M \times N$

$K < M \ll N$

signal

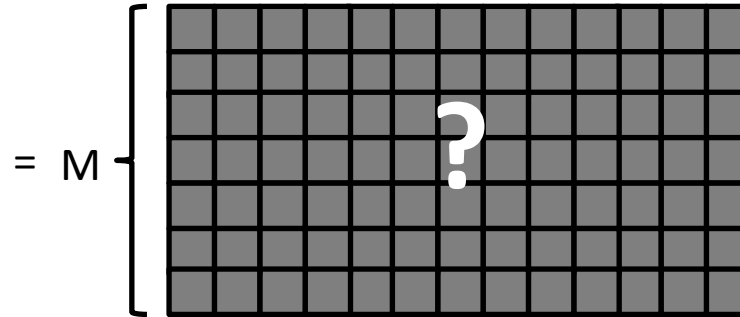


Compressed Sensing

measurement



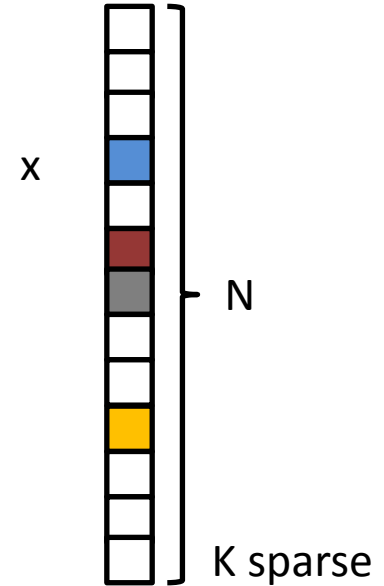
sensing matrix



$M \times N$

$K < M \ll N$

signal



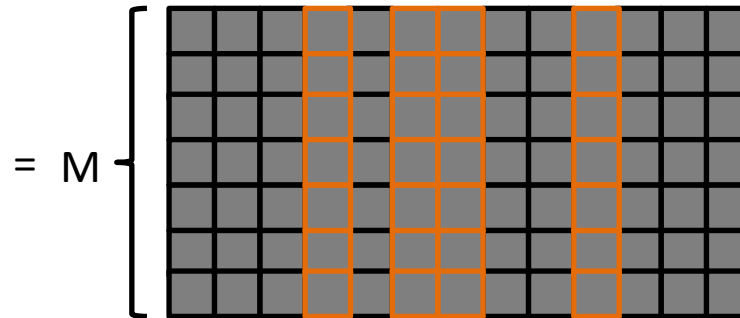
→ $M < N$: information loss (not full rank)

Compressed Sensing

measurement



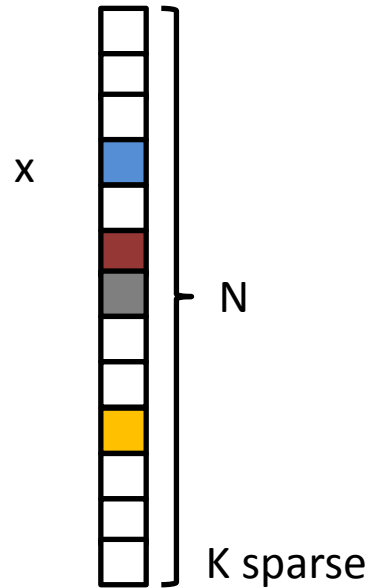
sensing matrix



$M \times N$

$K < M \ll N$

signal



→ $M < N$: information loss (not full rank)

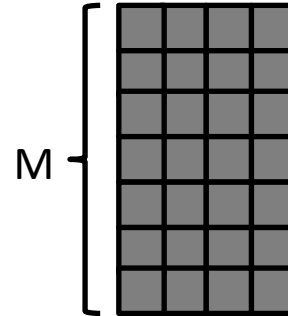
Compressed Sensing

measurement



=

sensing matrix



$M \times K$

$K < M \ll N$

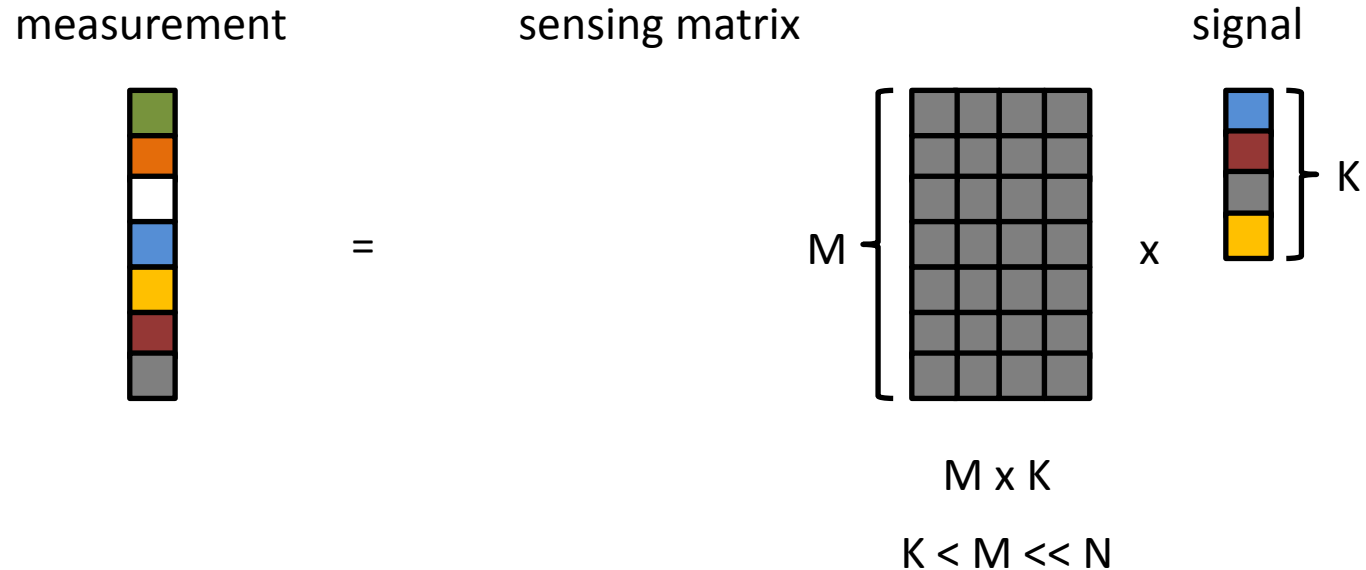
x

signal



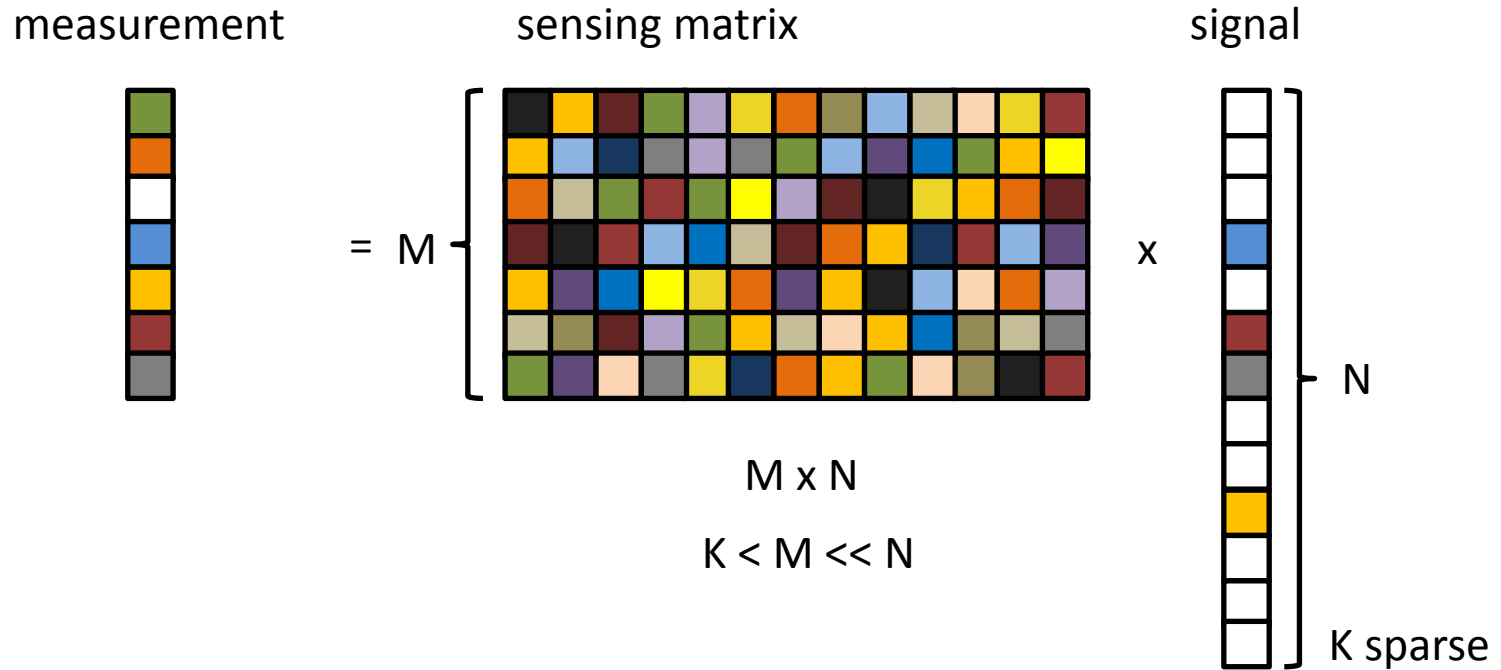
→ $M > K$: we preserve all information if $M \times K$ has full rank

Compressed Sensing



- $M > K$: we preserve all information if $M \times K$ has full rank
- **Design problem:** Find a $M \times N$ matrix such that all $M \times K$ submatrices have full rank and are almost orthogonal to each other
Restricted Isometry Problem (RIP)

Using a random sampling matrix



→ a randomized (iid gaussian) matrix has this property to a very high likelihood if:

$$M = O(K \log(N/K))$$

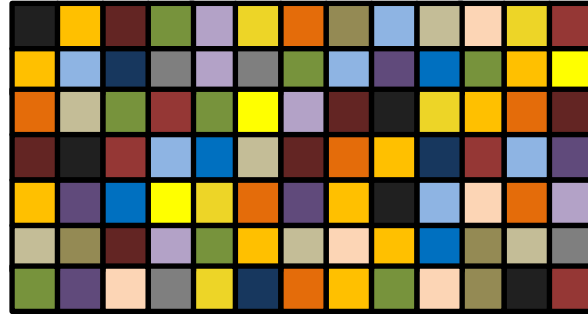
Recovering the input signal

measurement



=

sensing matrix



$M \times N$

signal

\times ?

y

=

Φ

\times

x

Recovery with regression

Find \hat{x} that solves $y = \Phi x$

Least squares: $\min\{\|\Phi\hat{x} - y\|_2\}$

Recovery with regression

Find \hat{x} that solves $y = \Phi x$

Least squares: $\min\{\|\Phi\hat{x} - y\|_2\}$
finds perfect \hat{x} , but not a sparse one

Ridge regression: $\min\{\|\Phi\hat{x} - y\|_2 + \lambda\|\hat{x}\|_2\}$

Recovery with regression

Find \hat{x} that solves $y = \Phi x$

Least squares: $\min\{\|\Phi\hat{x} - y\|_2\}$
finds perfect \hat{x} , but not a sparse one

Ridge regression: $\min\{\|\Phi\hat{x} - y\|_2 + \lambda\|\hat{x}\|_2\}$
finds small \hat{x} , but not a sparse one

Lasso regression: $\min\{\|\Phi\hat{x} - y\|_2 + \lambda\|\hat{x}\|_1\}$

Recovery with regression

Example:

$$\Phi \hat{x} = y$$

$$\Phi = \text{random}(200, 1000)$$

$$y = \text{random}(200)$$

Recovery with regression

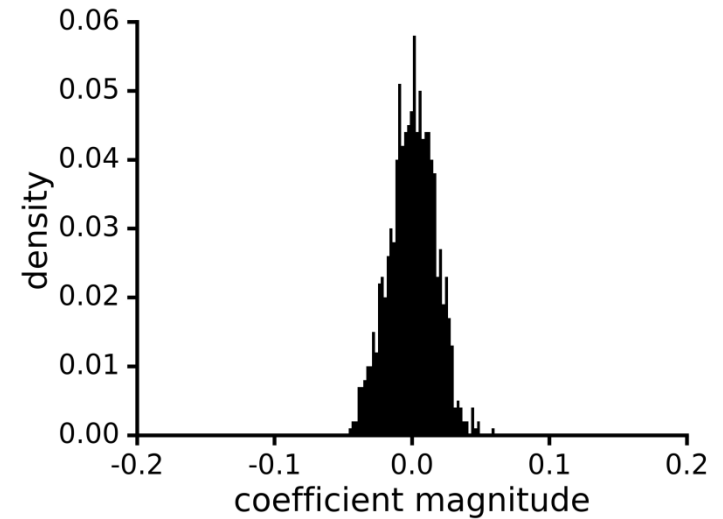
Example:

$$\Phi \hat{x} = y$$

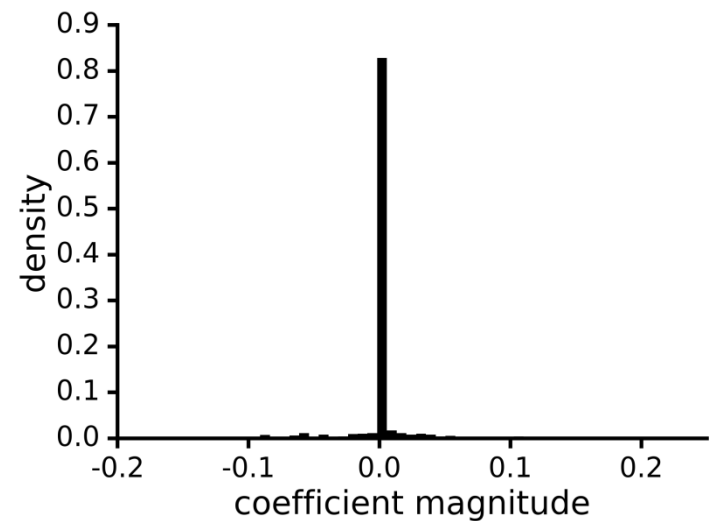
$\Phi = \text{random}(200, 1000)$

$y = \text{random}(200)$

Ridge



Lasso



Dealing with non-sparse signals

measurement



=

sensing matrix



x

signal



Dealing with non-sparse signals

Let x' be the representation of x in a sparse basis Ψ

$$\Psi x' = x$$

Same sampling process

$$y = \Phi \Psi x'$$

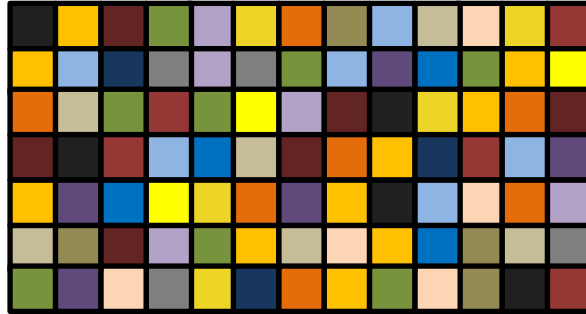
Dealing with non-sparse signals

measurement



=

sensing matrix



x

signal



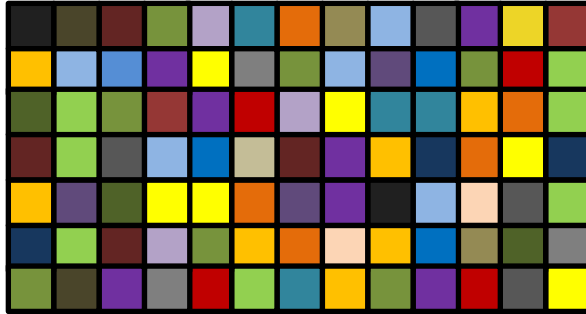
Dealing with non-sparse signals

measurement

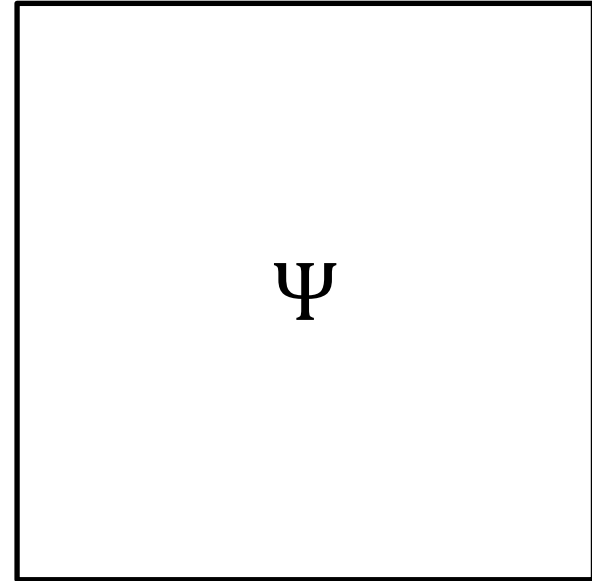


=

measurement matrix



transformation



signal



Dealing with non-sparse signals

Let x' be the representation of x in a sparse basis Ψ

$$\Psi x' = x$$

Same sampling process

$$y = \Phi \Psi x'$$

Update measurement matrix when recovering

$$\min\{\|\Phi \Psi \hat{x}' - y\|_2 + \lambda \|\hat{x}'\|_1\}$$

Dealing with non-sparse signals

Let x' be the representation of x in a sparse basis Ψ

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Transform back after recovering: $\hat{x} = \Psi \hat{x}'$

Dealing with non-sparse signals

Let x' be the representation of x in a sparse basis Ψ

$$\Psi x' = x$$

Same sampling process

$$y = \Phi \Psi x'$$

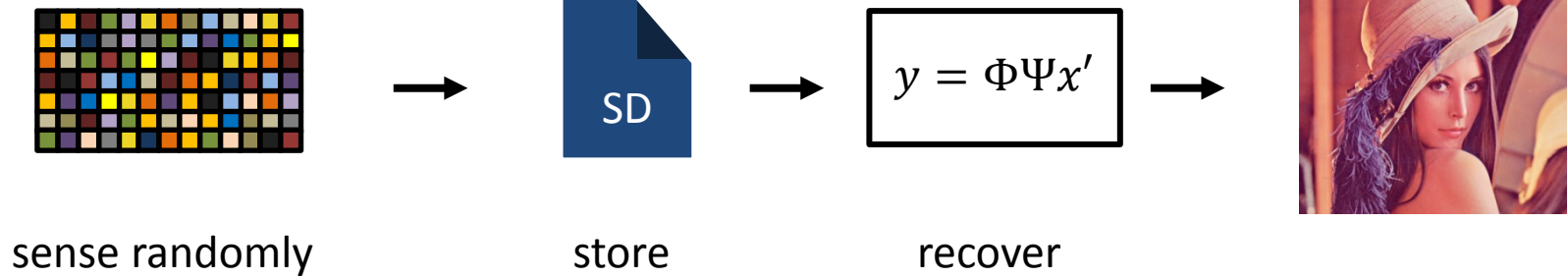
Update measurement matrix when recovering

$$\min\{\|\Phi \Psi \hat{x}' - y\|_2 + \lambda \|\hat{x}'\|_1\}$$

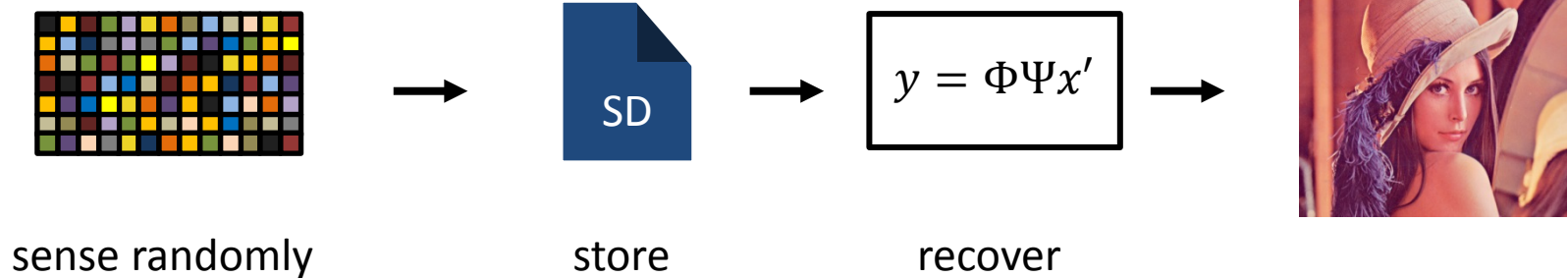
Transform back after recovering: $\hat{x} = \Psi \hat{x}'$

→ Ψ does not have to be known when sensing!

Wrap Up



Wrap Up



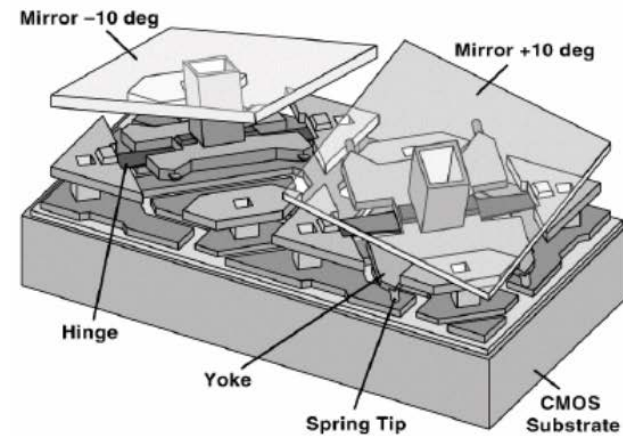
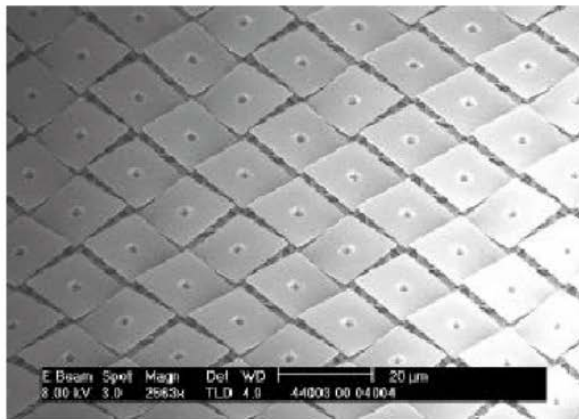
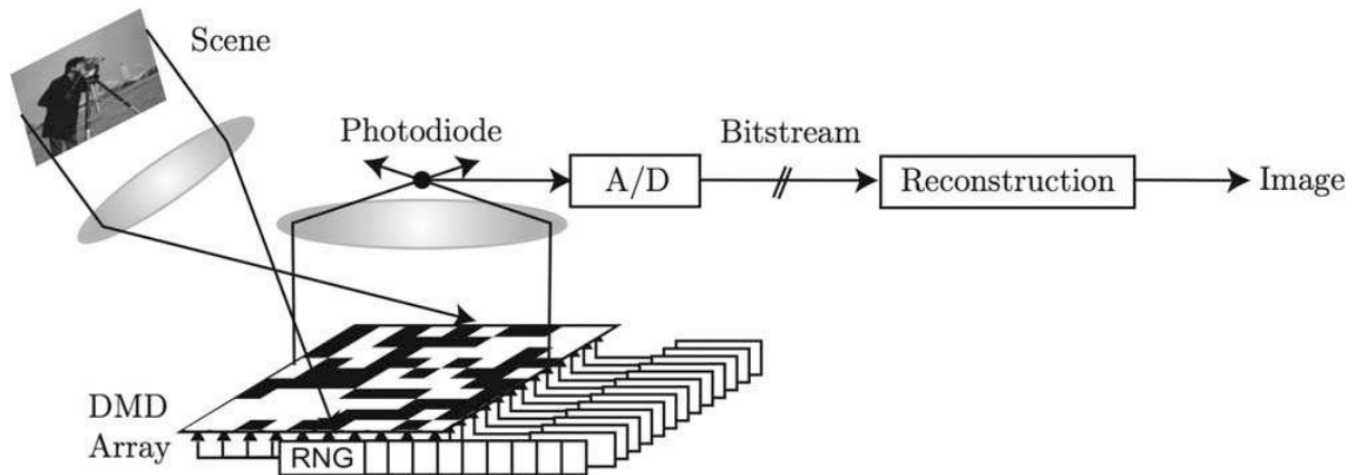
Sampling below Shannon frequency

- faster

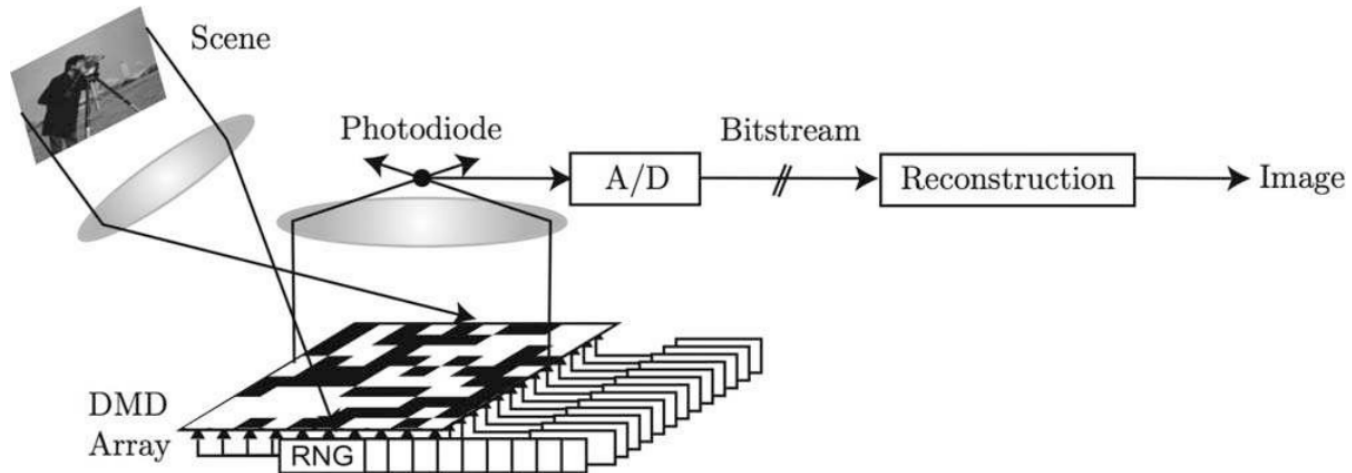
Asymmetric

- the decoder has to do most of the work

One pixel camera



One pixel camera



target
65536 pixels



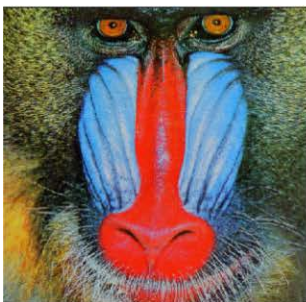
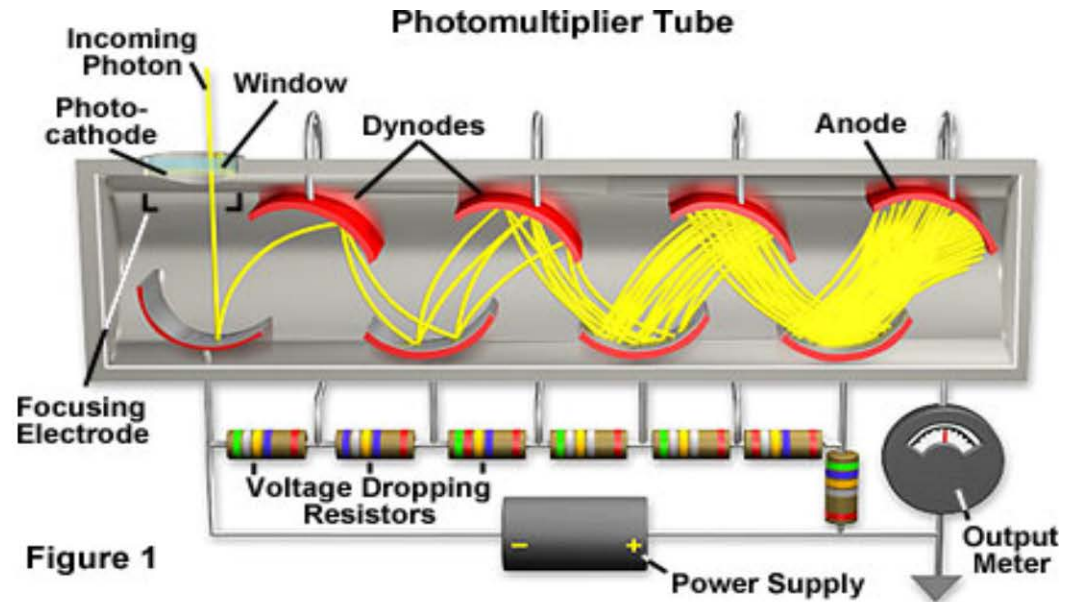
11000 measurements
(16%)



1300 measurements
(2%)



Low light one pixel camera



true color low-light imaging
256 x 256 image with 10:1
compression

Little experiment

10% highest wavelets coefficients



RMSE: 0.010

RMSE of random image: 0.423

Little experiment

10% highest wavelets coefficients



RMSE: 0.010

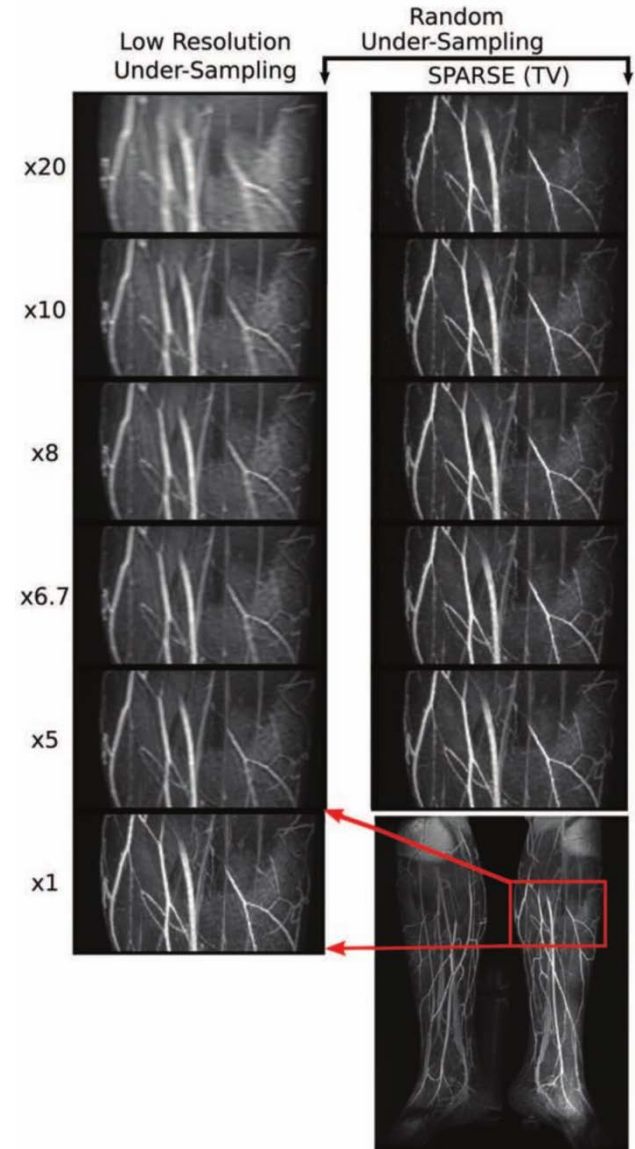
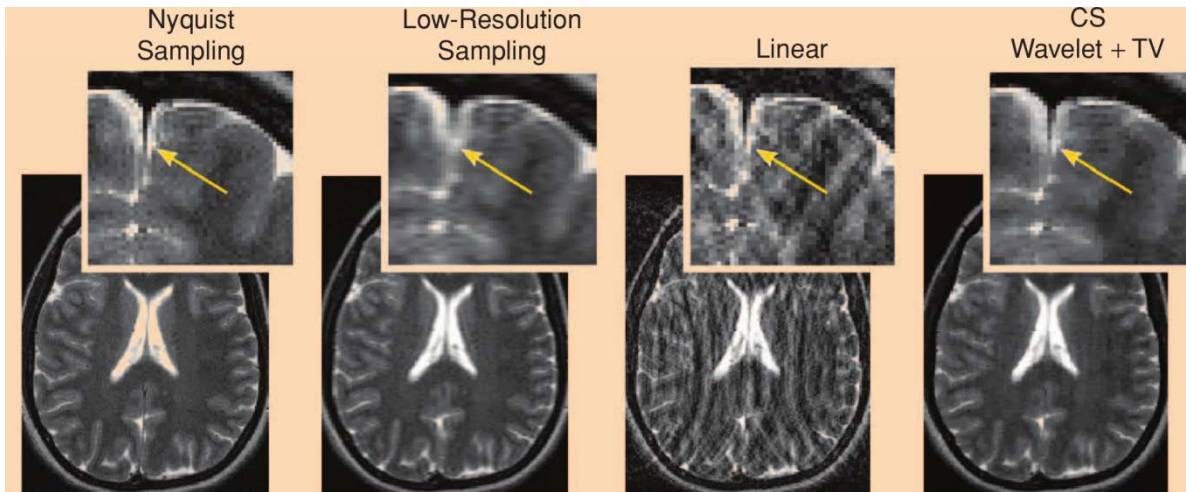
30% as many measurements



RMSE: 0.039

RMSE of random image: 0.423

Speeding up MRI acquisition



Recovery of missing data

original image



Recovery of missing data

original image



corruption rate: 0.1



Recovery of missing data

recovered image



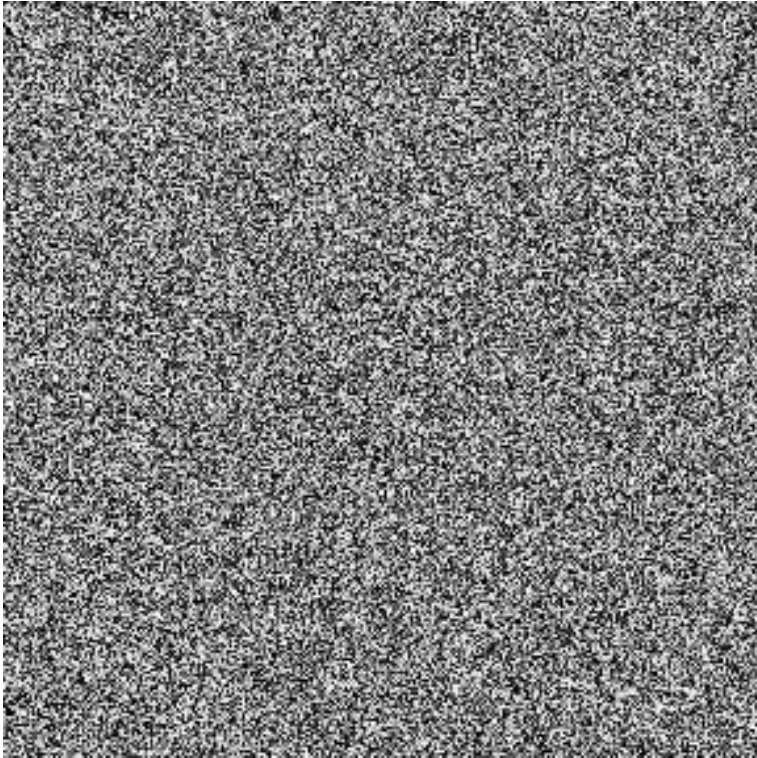
RMSE: 0.00611

corruption rate: 0.1



Recovery of missing data

random image



RMSE: 0.423

corruption rate: 0.1



Recovery of missing data

recovered image



RMSE: 0.00611

corruption rate: 0.1



Recovery of missing data

recovered image



RMSE: 0.00974

corruption rate: 0.2



Recovery of missing data

recovered image



RMSE: 0.0139

corruption rate: 0.3



Recovery of missing data

recovered image



RMSE: 0.0197

corruption rate: 0.4



Recovery of missing data

recovered image



RMSE: 0.0357

corruption rate: 0.5



Recovery of missing data

recovered image



RMSE: 0.0426

corruption rate: 0.6



Recovery of missing data

recovered image



RMSE: 0.063

corruption rate: 0.7



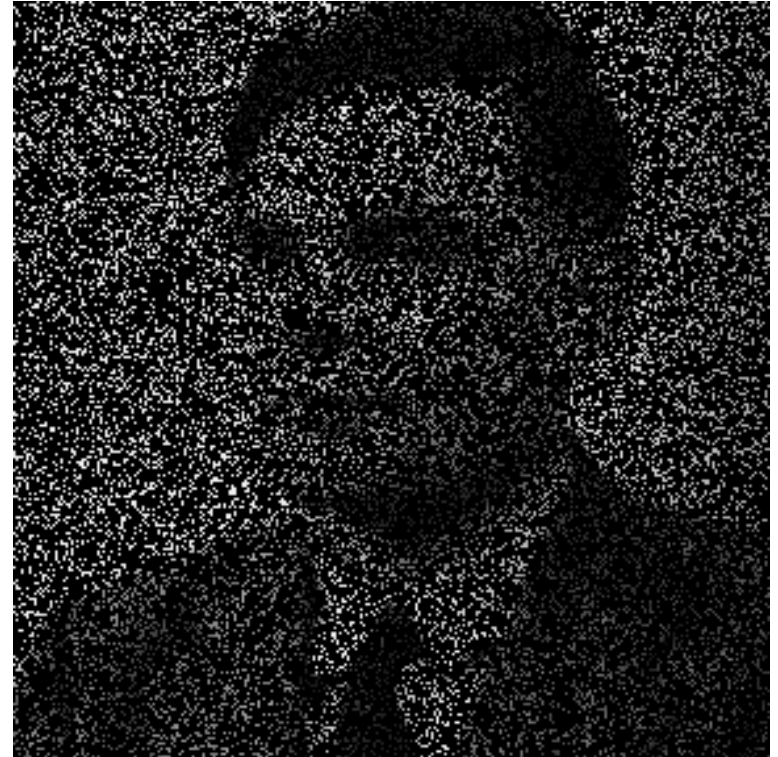
Recovery of missing data

recovered image



RMSE: 0.0773

corruption rate: 0.8



Recovery of missing data

recovered image

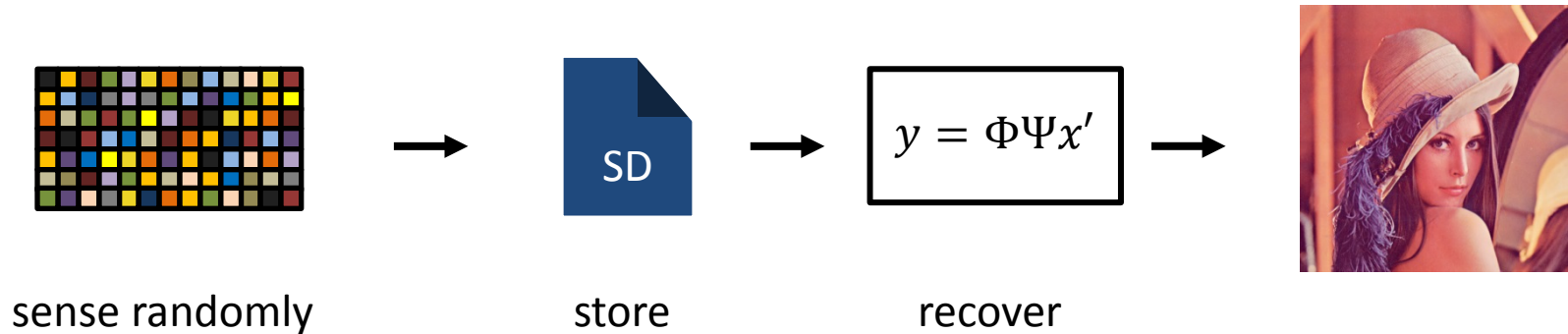


RMSE: 0.116

corruption rate: 0.9



Conclusion



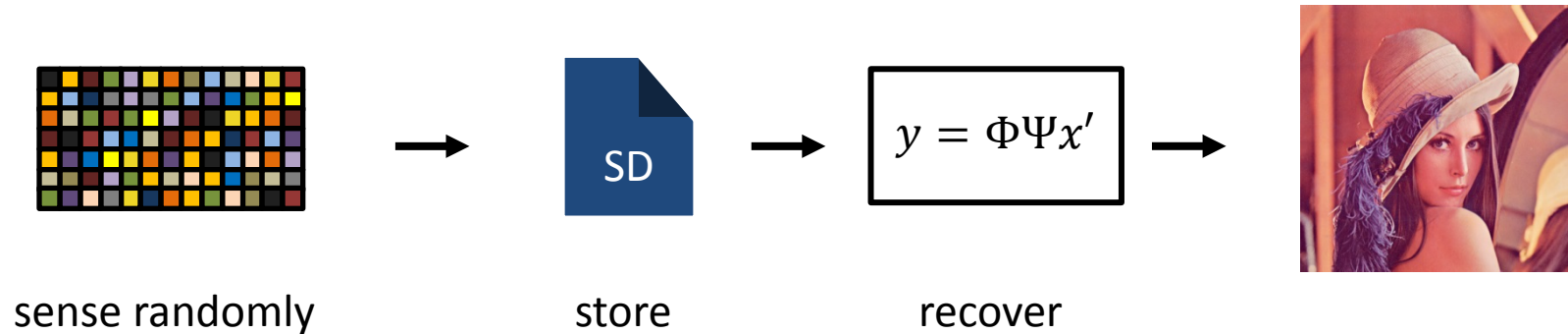
CS can beat the Nyquist Shannon limit

The computational burden is shifted to the decrypter

Adjustments to the sensor have to be made

Future: Combination with classification

Conclusion



Code and suggested talks and reading:

<https://github.com/sdorkenw/CompressedSensingSeminar>