

On the Origin of e-species

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Life



This topic is highly controversial

- An organismic state characterized by capacity for metabolism, growth, reaction to stimuli, and reproduction (*Merriam-Webster Definition*)

Life: What About?

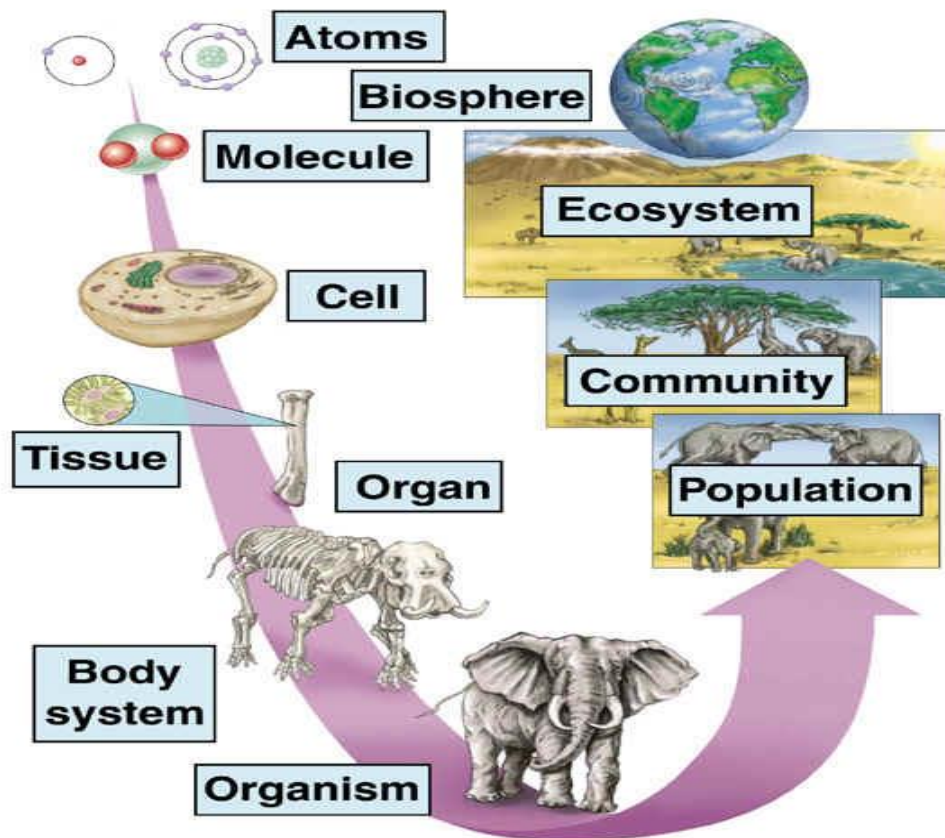


- Mule — cannot self-reproduce; cannot evolve
- Virus — cannot self-reproduce; does not have a metabolism
- Prion — like a virus; no self-representation but itself

Life: Organization



Raven/Berg, Environment, 3/e
Figure 4.1



Life: Characterization



A pattern in space-time

Reproduction - Autopoeisis

Recombining instructions set

Metabolism

Interaction with the Environment

Life: Characterization



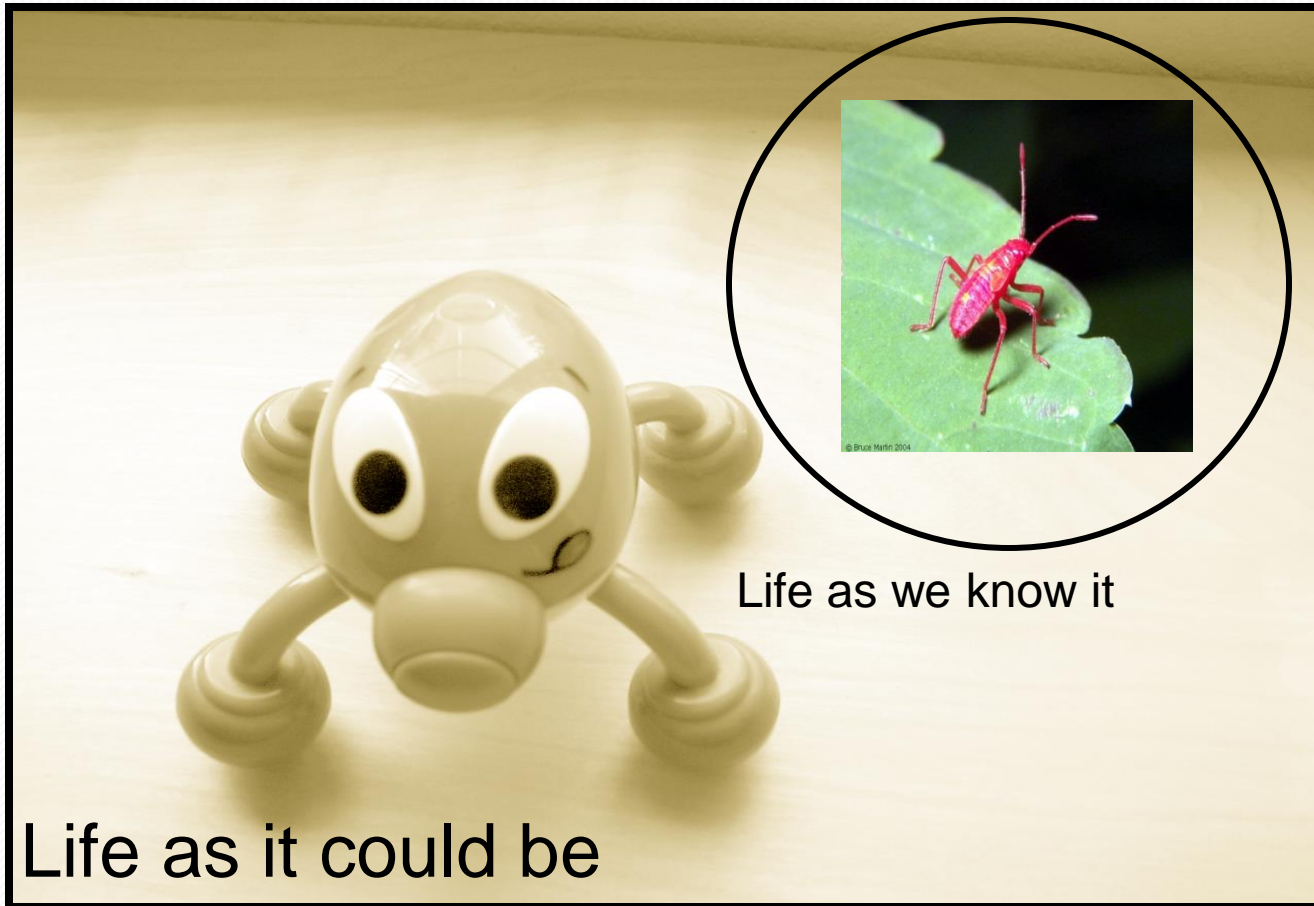
Interdependence of parts

Stability under perturbation

Ability to evolve

Homeostasis

Life: Space



Life as we know it

Life as it could be



Artificial Life

Relatively new research area in computer sciences that studies and recreates systems related to life by using computer simulations, robotics and bio chemistry

Chris Langton, 1987



Traditional Biology: Method

1. Analytic
2. Top-down

Starts from the top (e.g. organism level) and seeks for explanations in terms of lower level entities



Artificial Life: Method

1. Synthetic
2. Bottom up: starts at the bottom (e.g. molecular level)

It works by synthesizing complex systems from many simple local interacting entities.

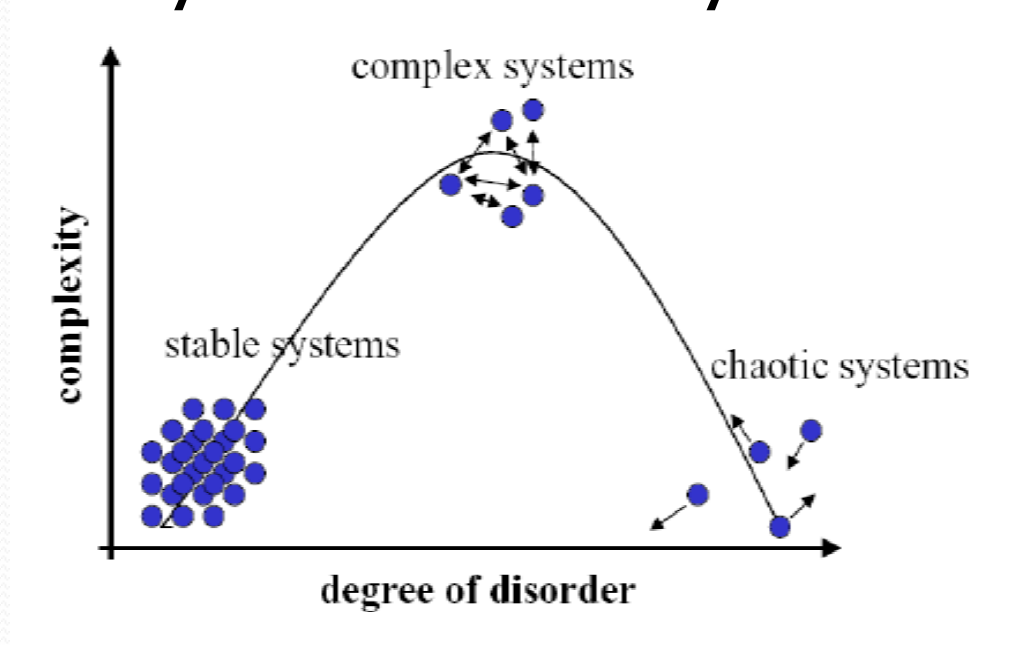


Artificial Life: Concepts

Complex Systems

Emergence and self-organization

Local rules usually defined as dynamic systems





Dynamic System

Evolves in time according to a set of rules

- What changes in time is a variable (e.g. Position, concentration, temperature, ...)
- Present conditions determine the future.
- Rules are usually nonlinear (e.g. set of diff. eq. Defining rates of change)
- There may be many interacting variables



Sierpinski Triangle

Algorithm

Draw a random point

Throw a dice

Draw the middle point
between the current point
and the associated vertex

Go line 2

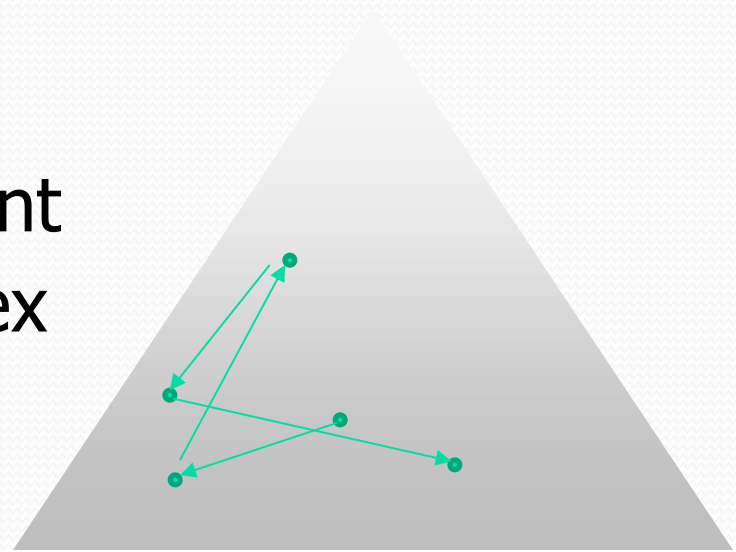


...

1, 2

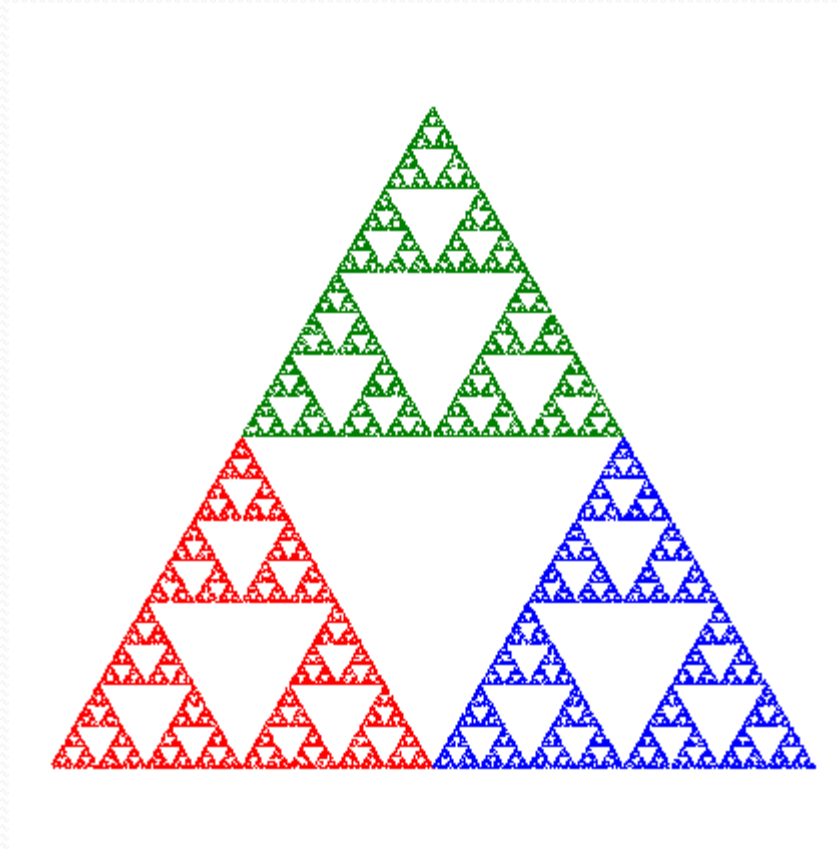
5, 6

3, 4





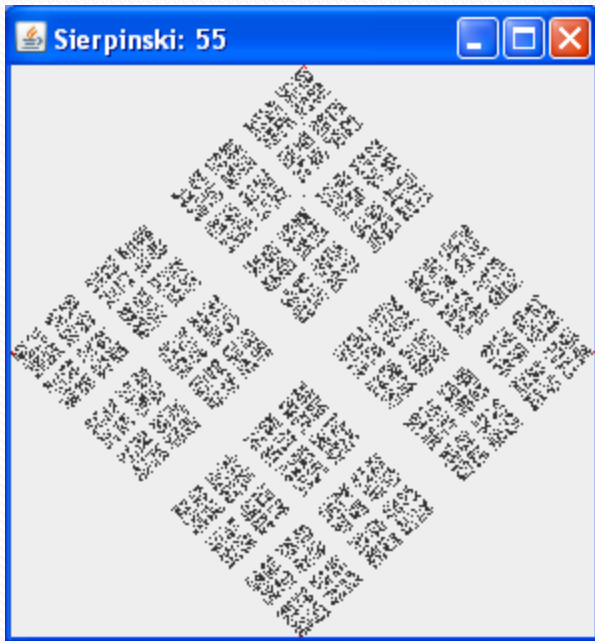
Sierpinski Triangle



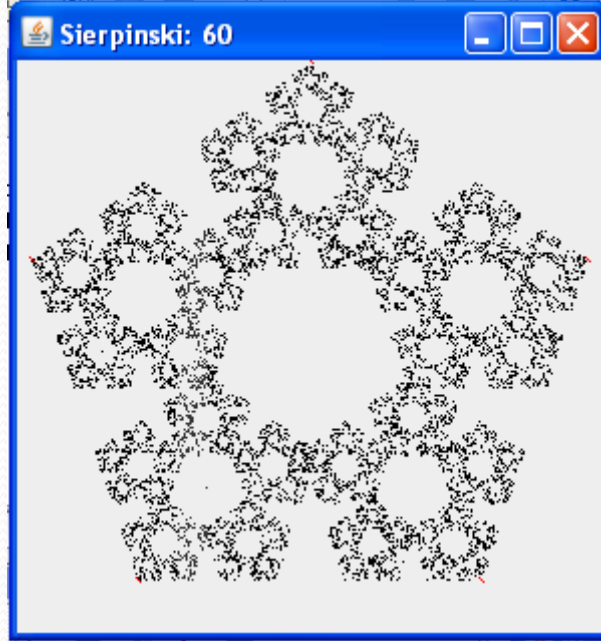
Demo



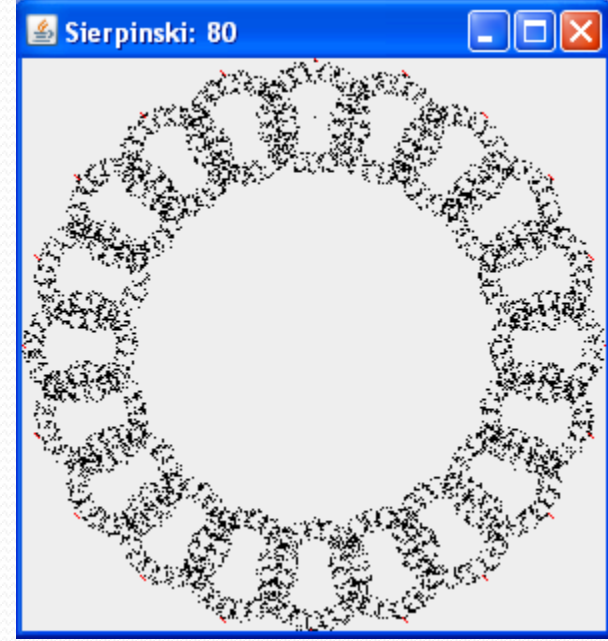
Beyond Sierpinski



Square



Pentagon



20-sides



Rand Gravitational Clustering

Data Clustering is viewed as a dynamic system

Points change in time and group themselves according to some dynamic rules

Clusters emerge from the dynamic behavior of the data points

No optimization approach



Rand Gravitational Clustering

Non hierarchical approach, Robust and Unsupervised Clustering approach

Each point is moved using the gravitational force exerted by another single object over it and Newton's second motion law

$$F(t) = \frac{Gm_xm_y}{d(x(t), y(t))^2}$$

$$x(t+1) = x(t) + \vec{d} \frac{G}{\|\vec{d}\|^3}$$

[Video](#)



Rand Gravitational Clustering

Algorithm 13 Randomized Gravitational Clustering

RGC(x , G , $\Delta(G)$, M , ϵ)

```
1  for  $i=1$  to  $n$  do // each data point is a candidate cluster
2    MAKE( $i$ )
3  for  $i=1$  to  $M$  do // iterations performed by the algorithm
4    for  $j=1$  to  $n$  do // moving each data point
5       $k$  = random point index such that  $k \neq j$  // selecting another data point
6      MOVE(  $x_j$ ,  $x_k$  ) (see Eq (6.22)) //Move both points
7      if  $\text{dist}(x_j, x_k) \leq \epsilon$  then UNION(  $j$ ,  $k$  ) // merging cluster if possible
8       $G = (1 - \Delta(G)) * G$  // Cooling the system
9  for  $i=1$  to  $n$  do // organizing the final clusters
10   FIND( $i$ )
11  return disjoint-sets
```

Algorithm 14 Cluster Extraction.

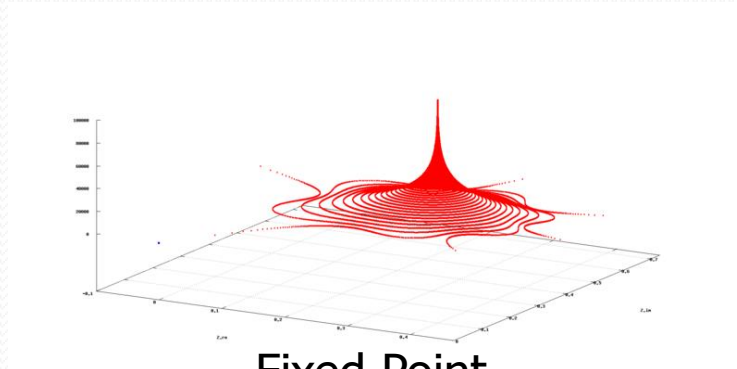
GETCLUSTERS(clusters, α , n)

```
1  newClusters =  $\emptyset$ 
2   $\text{MIN\_POINTS} = \alpha n$ 
3  for  $i=0$  to number of clusters do
4    if  $\text{size}(\text{cluster}_i) \geq \text{MIN\_POINTS}$  then
5      newClusters = newClusters  $\cup$  {  $\text{cluster}_i$  }
6  return newClusters
```

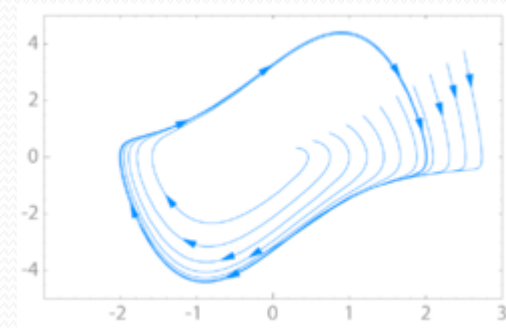


Dynamic System: Attractors

Atracctor



Fixed Point



Limit Cycle

Strange



[Video](#)



Fractals

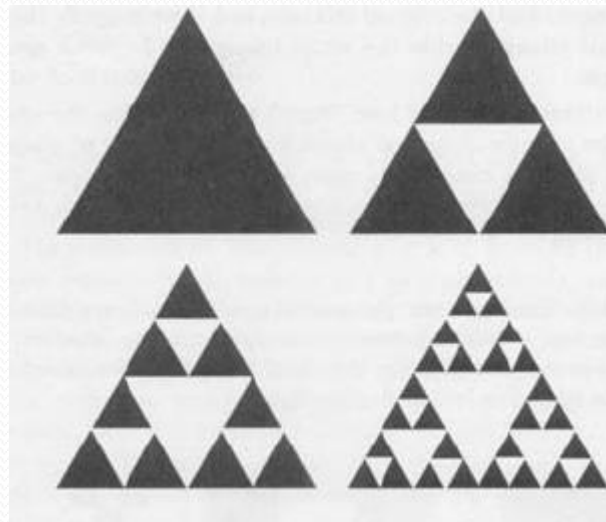




Lindenmayer Systems

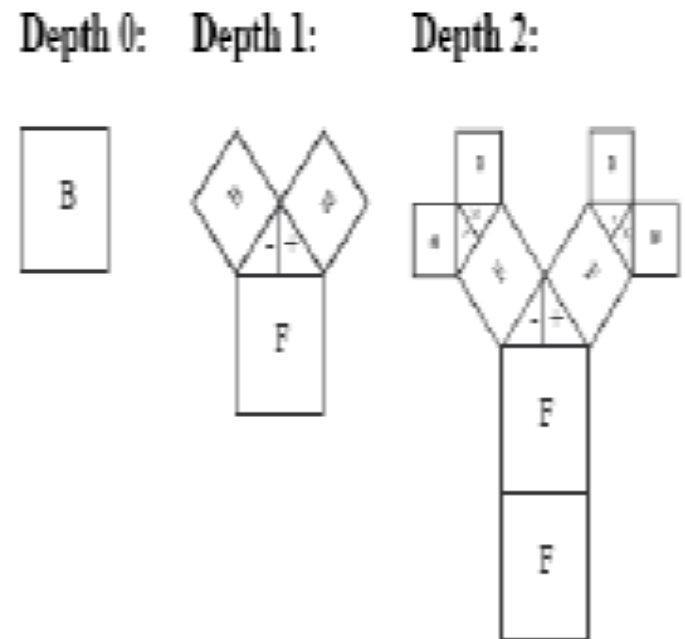
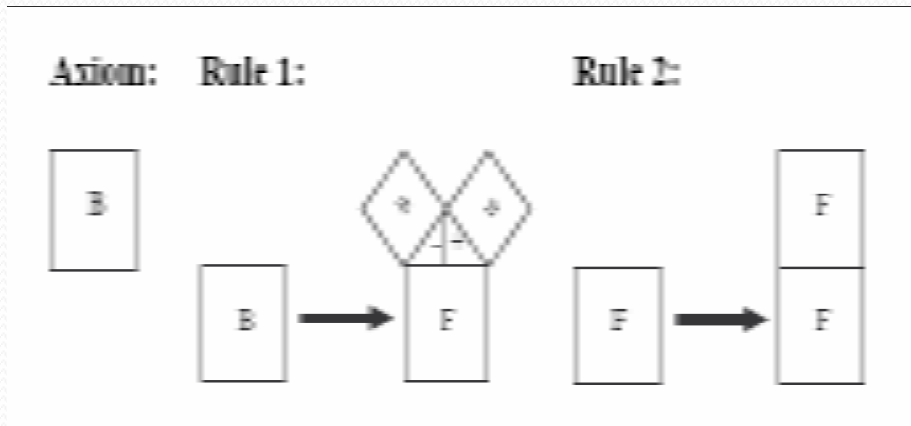
Production Systems (Grammar)

Example: Replace any filled triangle (left) with the three smaller filled triangles leaving empty the center (right)



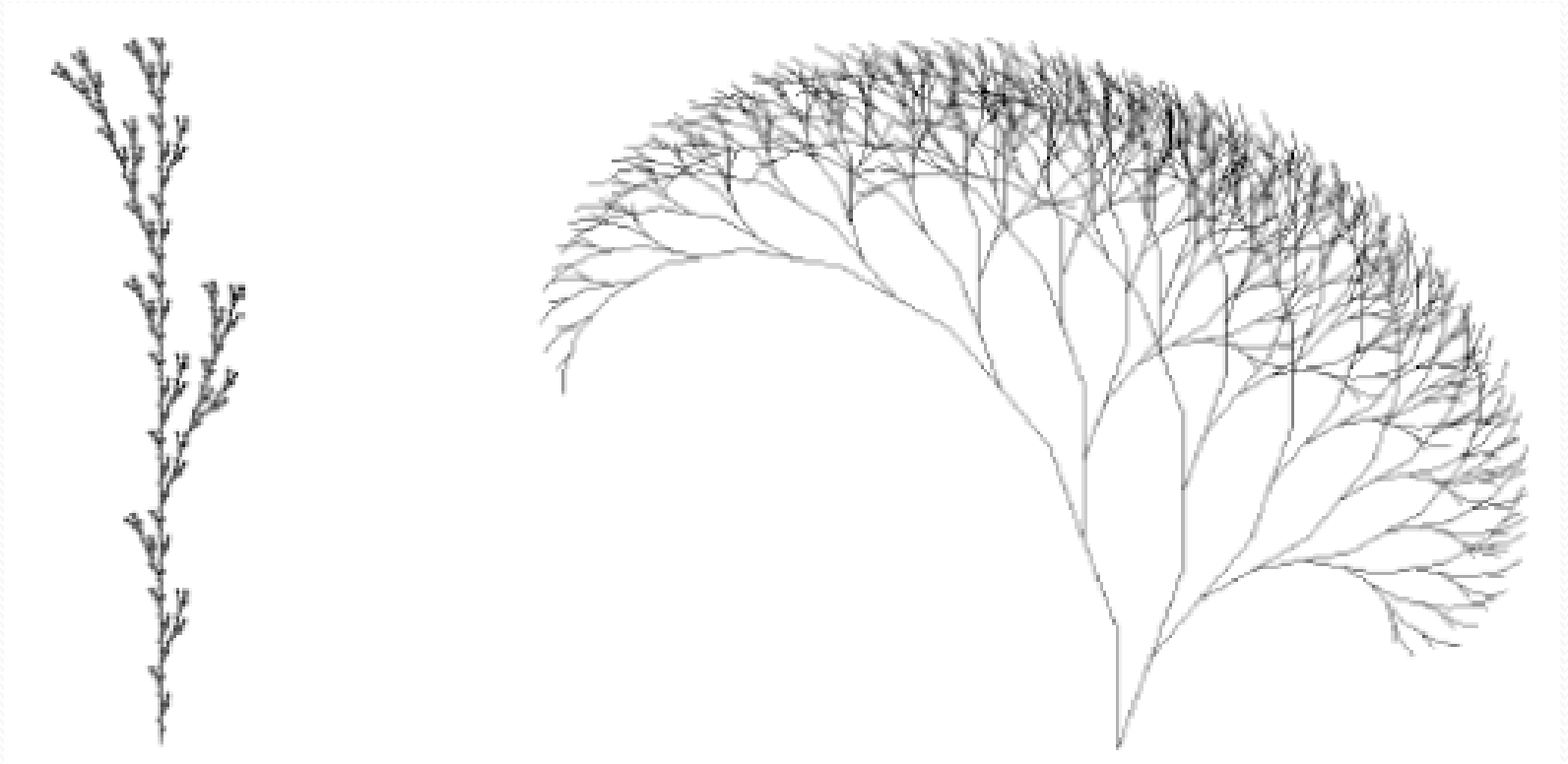


Lindenmayer Systems



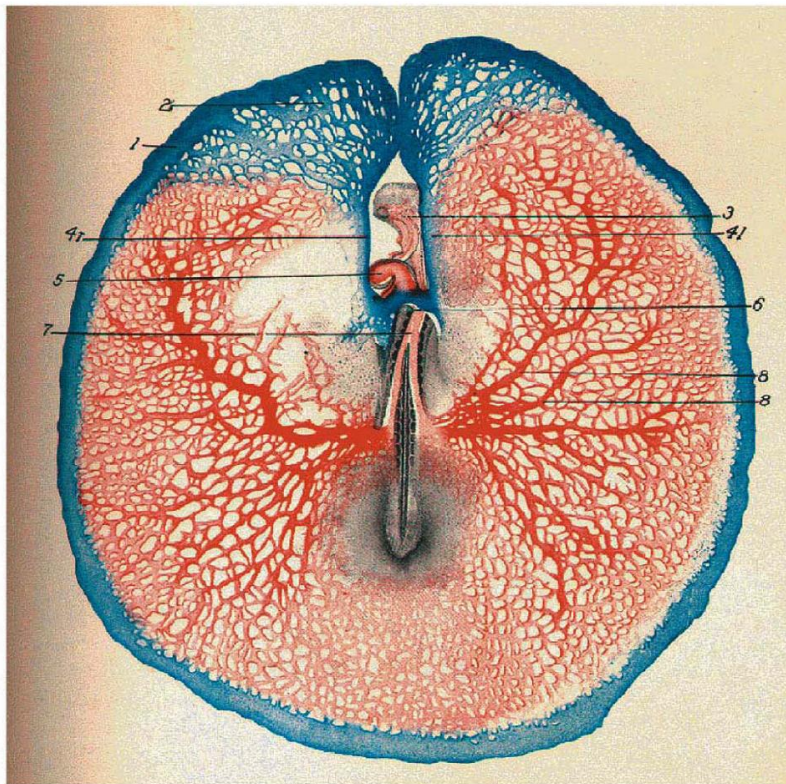
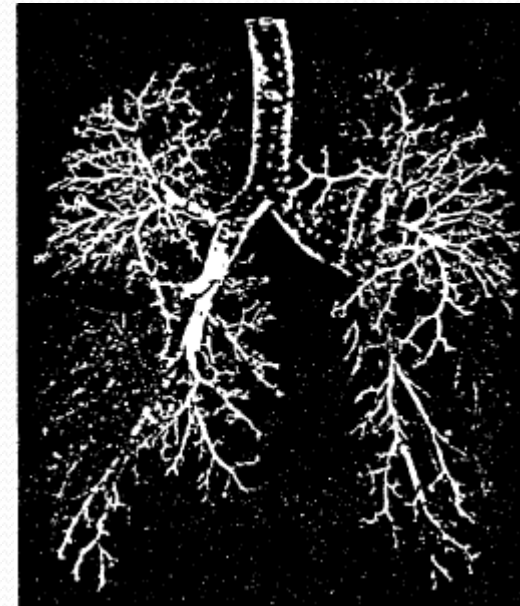


Lindenmayer Systems

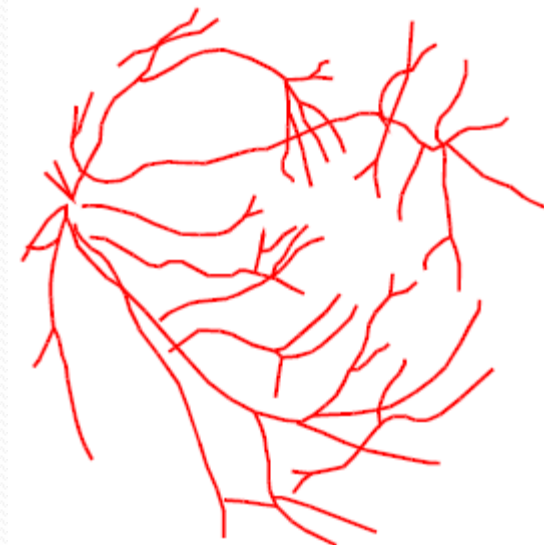


Video

Looks like



DEVELOPMENTAL BIOLOGY, Eighth Edition, Part 1, C



Video



Reaction/Diffusion Systems

$a(x, t)$, $b(x, t)$: activator, inhibitor concentrations

s : Auto-catalysis capability of cell

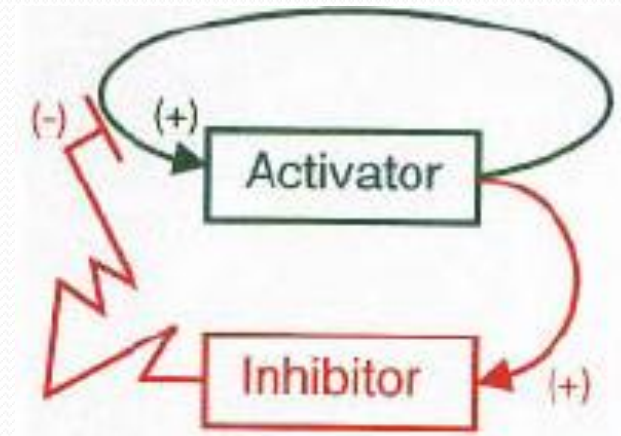
D_a , D_b : diffusion constants

r_a , r_b : decay rates

b_a , b_b : Basic production activator/inhibitor

$s a^2/b$: no lineal auto-catalytic influence

r_{aa} : removing rate (proportional to concentration)



$$\frac{\partial a}{\partial t} = s \left(\frac{a^2}{b} + b_a \right) - r_a a + D_a \frac{\partial^2 a}{\partial x^2}$$

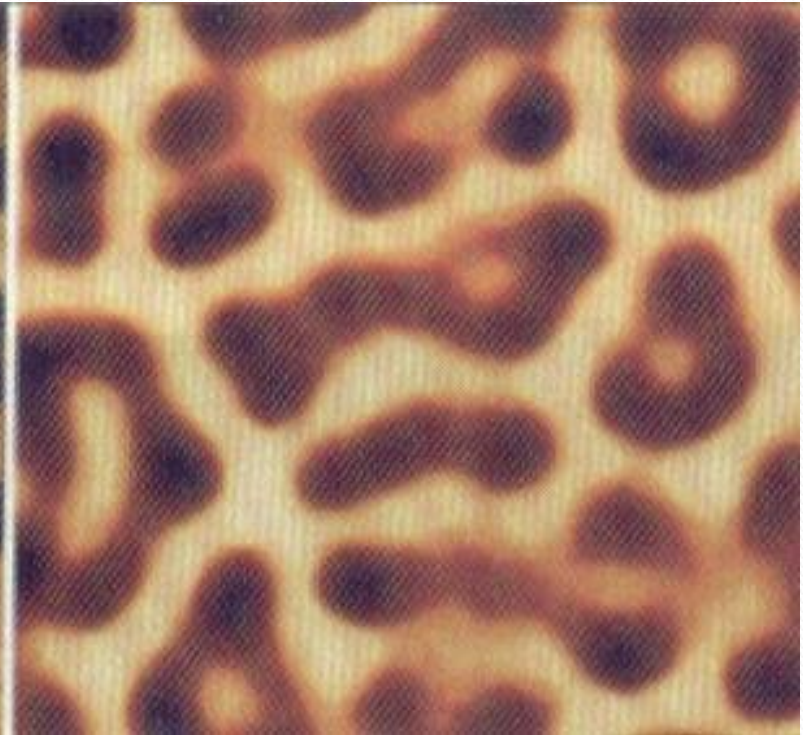
$$\frac{\partial b}{\partial t} = s a^2 - r_a b + b_b + D_b \frac{\partial^2 b}{\partial x^2}$$



Reaction/Diffusion Systems



Cheetah motif

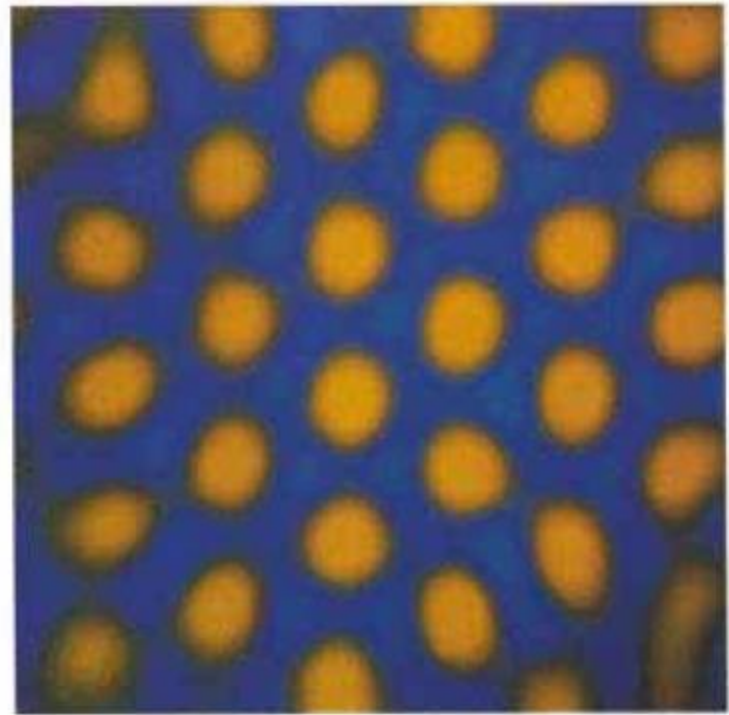
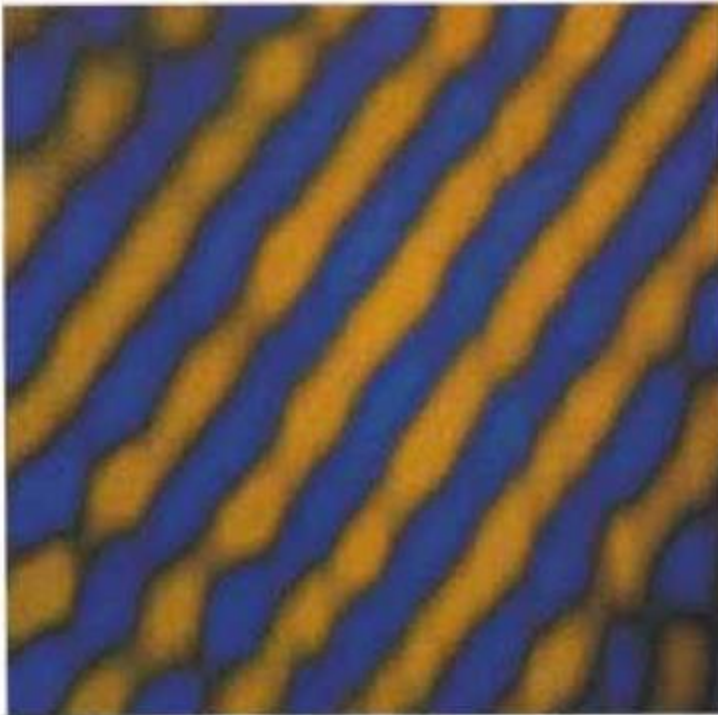


Chemical motif

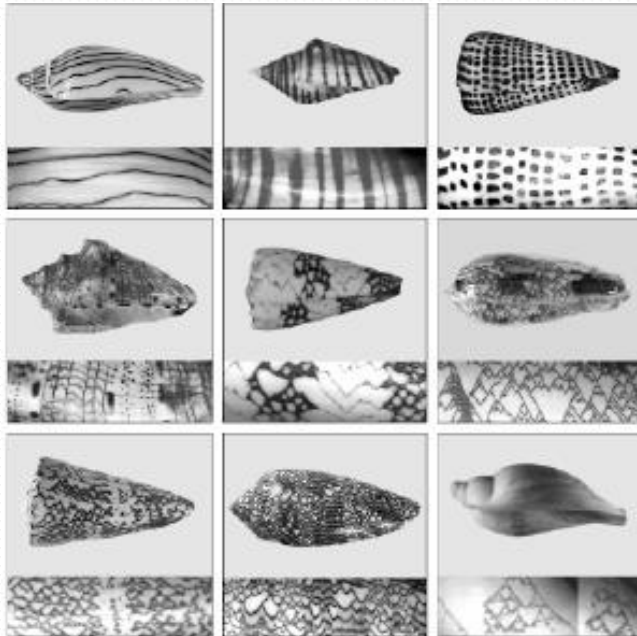


Reaction/Diffusion Systems

Motifs



[Demo](#)





Reaction/Diffusion Systems

We are developing a virtual central nervous system growing mechanism based on reaction/diffusion systems.

Each neuron locates other neurons, sensors and actuators by expanding nerve cells according to the activator/inhibitor concentrations induced by such elements.



Cellular Automata

Lattice, each cell taking a finite possible set of values

Value of each cell changes in the same discrete synchronous way

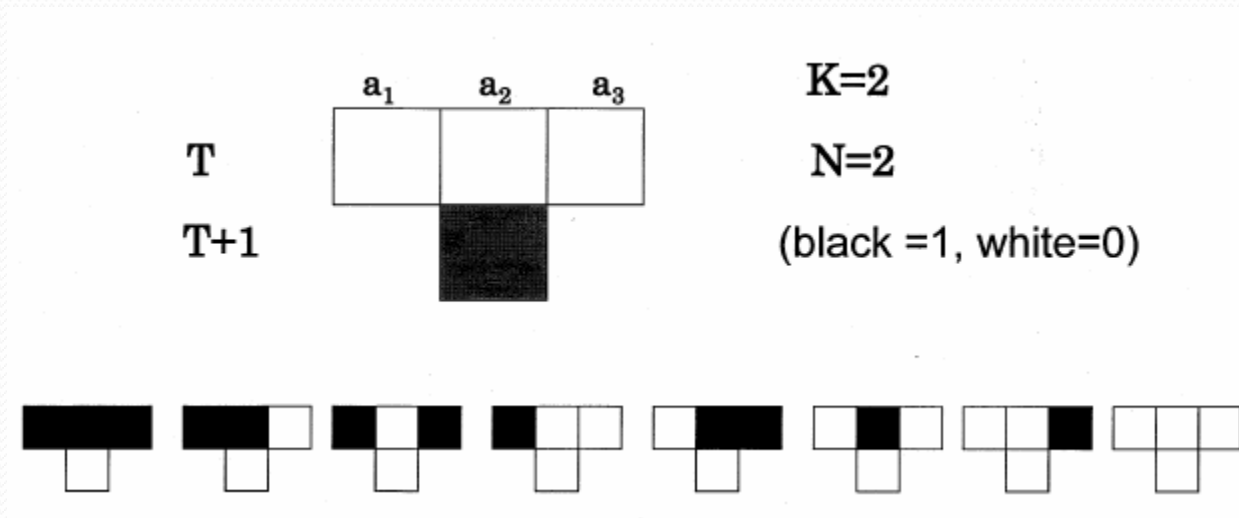
Change depends only on the neighbor cells (possibly including itself)





Cellular Automata

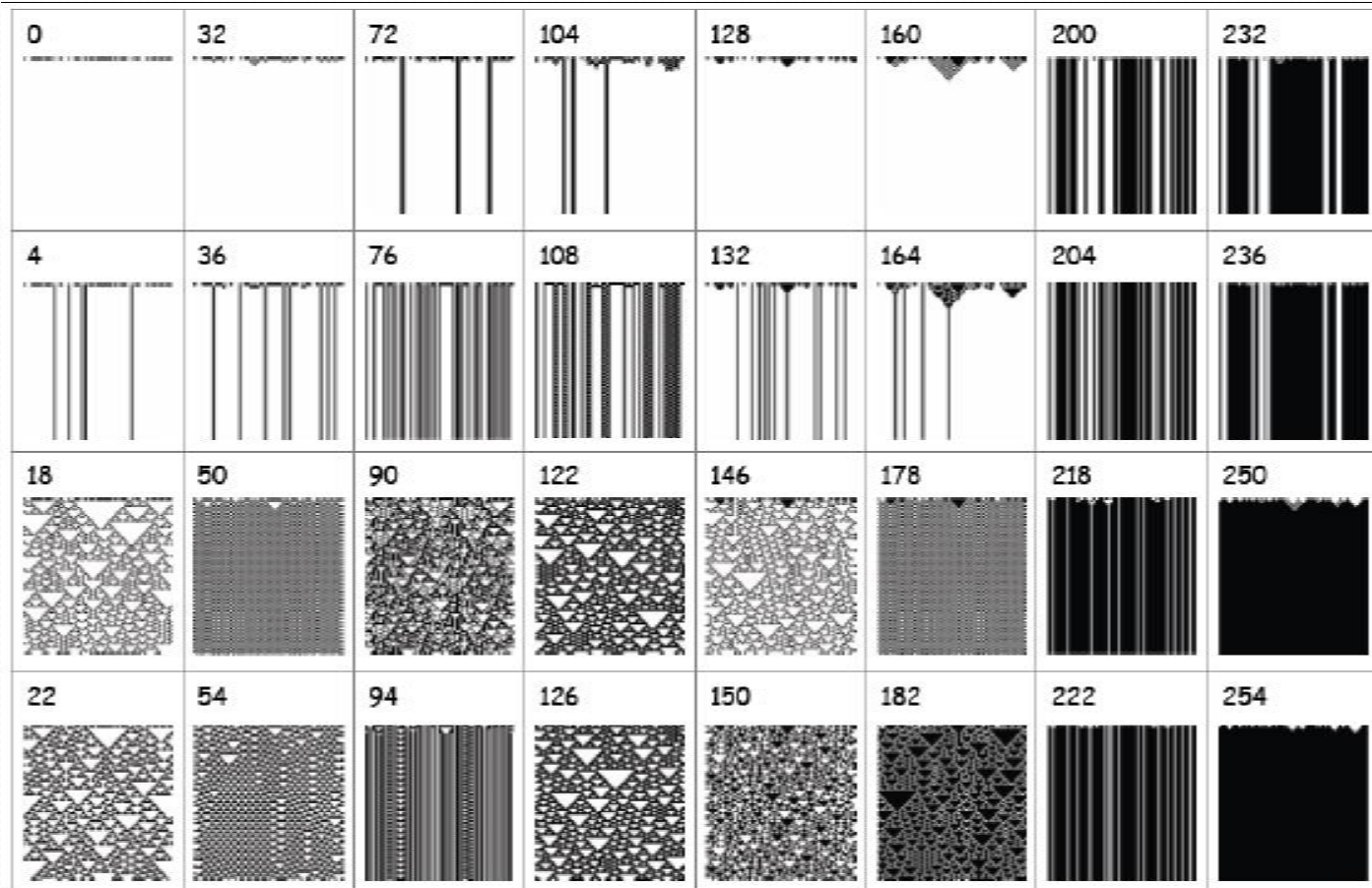
1 Dimensional





Cellular Automata

Space-time Diagram



[Video](#)



Game of Life

2 dimensional

1. Any live cell with fewer than two live neighbours dies, as if caused by underpopulation.
2. Any live cell with two or three live neighbours lives on to the next generation.
3. Any live cell with more than three live neighbours dies, as if by overpopulation.
4. Any dead cell with exactly three live neighbours becomes a live cell, as if by reproduction.



Cellular Automata

We develop a Wireless Sensor Network coordination mechanism based on a non regular cellular automaton that is able to improve the performance of the WSN

We combine CA with evolutionary algorithms for inducing diversity in the EA population. We are able to simulate sort of Cambrian Explosion and Massive extinction mechanisms.



Cellular Automata

We define a Cellular automaton and agent concepts for simulating the life cycle of the PapillomaVirus Variant 16 and its interaction with the immune system for inducing cervical cancer.

We use an hexagonal cellular automaton for simulating the life cycle of a cell.



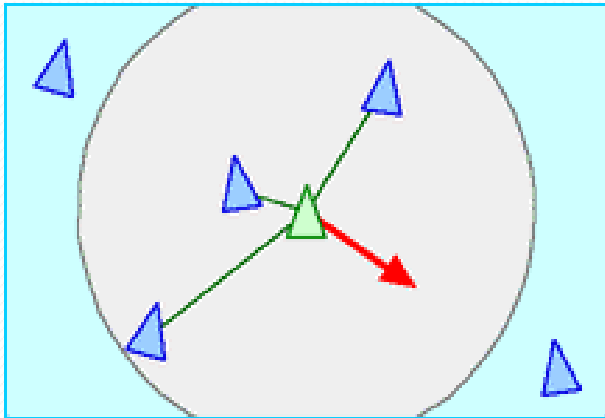
Cellular Automata

We use an hexagonal cellular automaton for simulating the horizontal transcription process (plasmid transference) in bacteria and study antibiotic resistance.

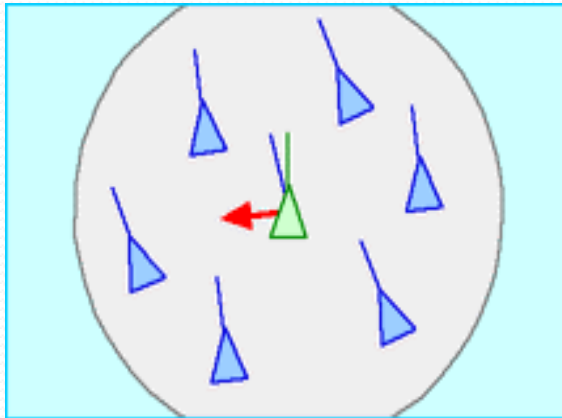


Collective Behaviour - Boids

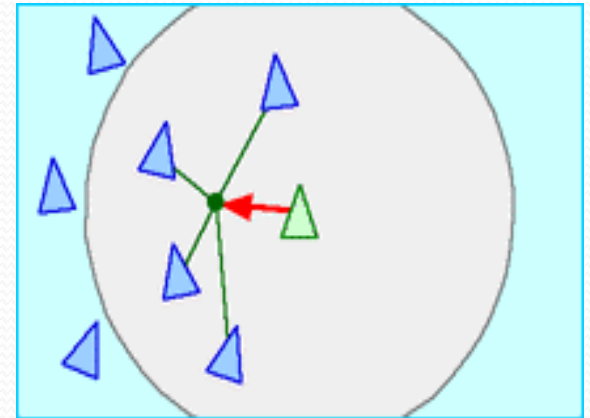
Separation



Alignment



Cohesion



[Video](#)



Collective Behaviour - Termites

Simple Units able to solve (optimization) problems

Stigma based communication (pheromone)

[Video](#)



Collective Behaviour - Termites

We combine ants (termites) ideas with Q-learning and Language Game theory for designing a Self failure detection and repairing mechanism (Autonomic computing)

[Video](#)



Collective Behaviour - Robots

We develop a simulation framework for studying collective robotics and applied it to robot-soccer.

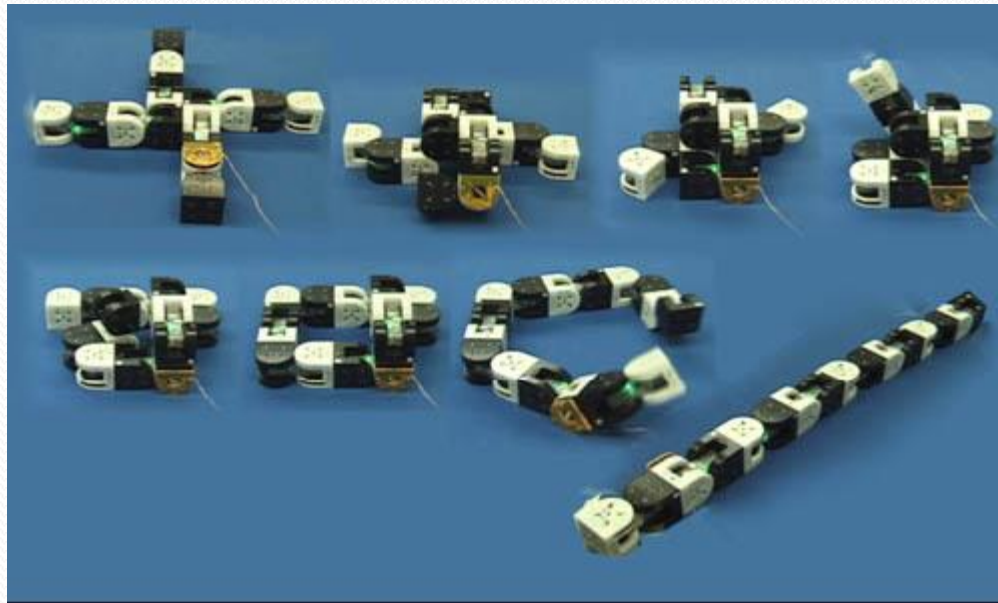
We develop a previous version of the robot-soccers and we are developing an improved version of such robot-soccers

[Video](#)



Modular Robots

Simple Cooperative Robots



[Video](#)



Modular Robots

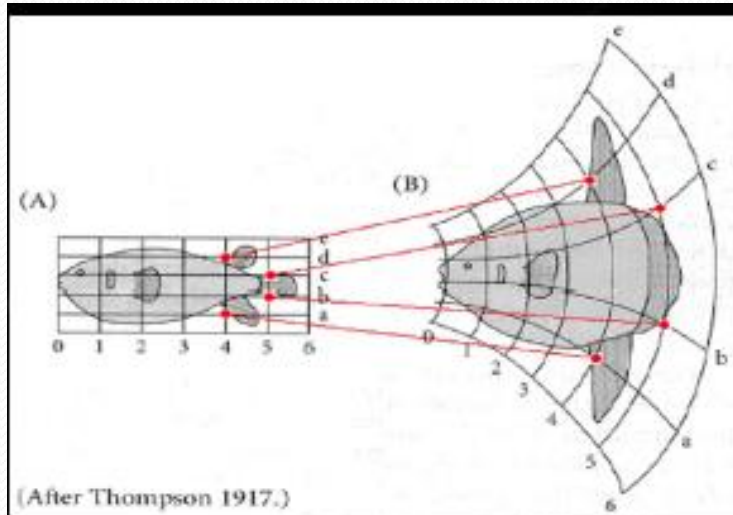
We develop a Modular Robot that combines Central Pattern Generator (sinusoidal waves) with Hormone inspired communication for moving the robot in odd terrains and avoid obstacles.

[Video](#)

[Video 2](#)

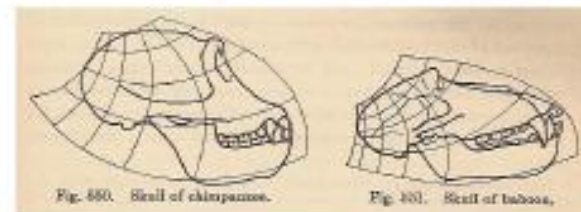
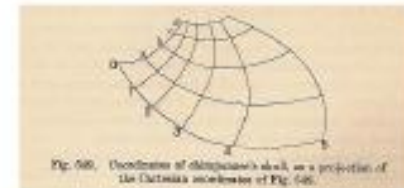
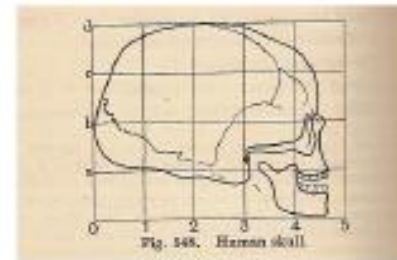


Transformation



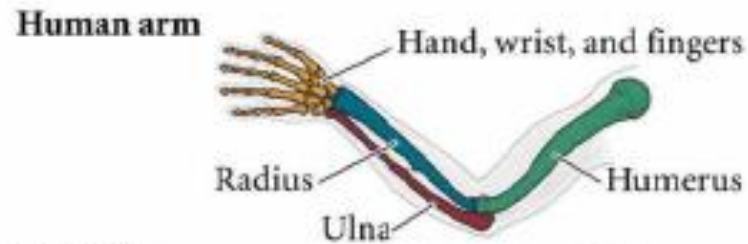
(After Thompson 1917.)

Theory of transformation:
Comparison of related
morphological forms (Thompson,
1917)





Transformation





Bio-inspired Robots

We design a robot that uses organic waste and a colony of bacteria as source of energy

We are developing a mini-robot that uses vibration for moving and such organic waste and colony of bacteria as source of energy

[Video](#)



Evolution: Darwin Pond

Designed by Jeffrey Ventrella (1996)

Simulation of “swimmers”

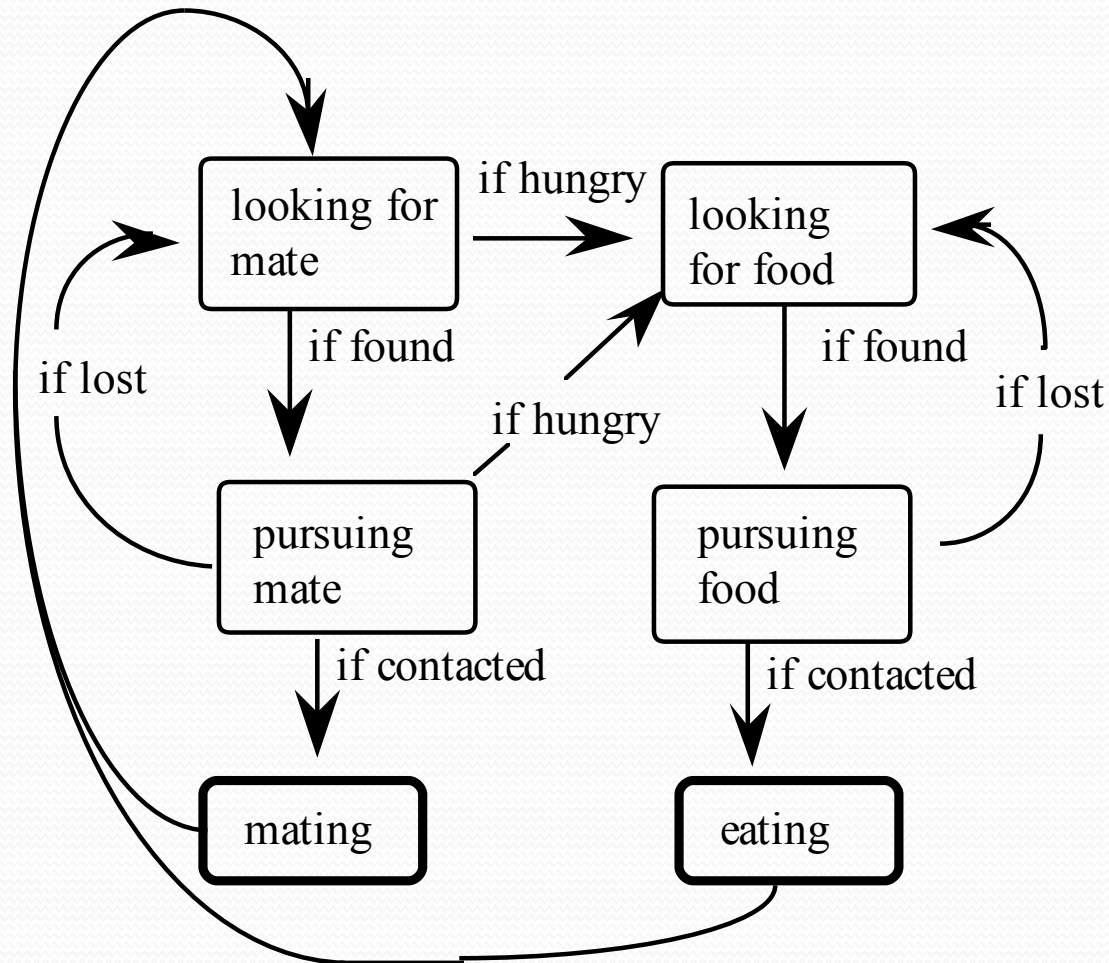
Evolving behaviors and form

Phenotype is defined by color, age, legs

Purpose of swimmers: Eat and Sex

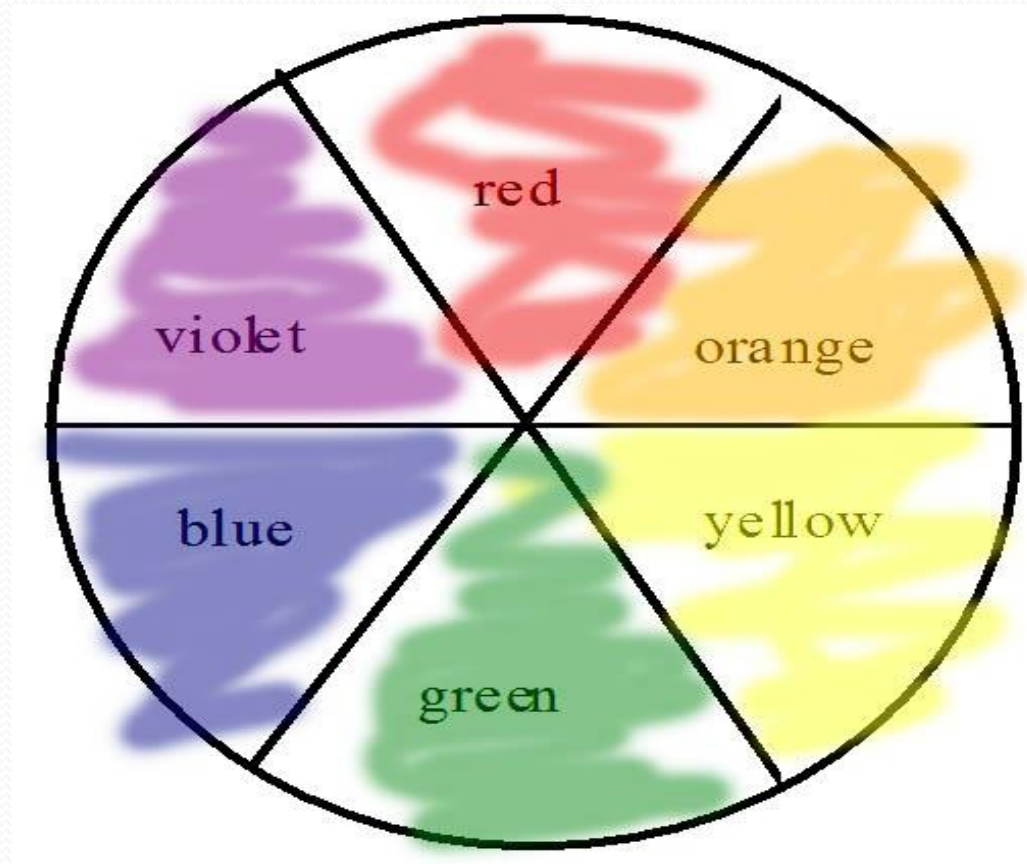


Evolution: Darwin Pond





Evolution: Darwin Pond





Evolution: Darwin Pond



[Video](#)

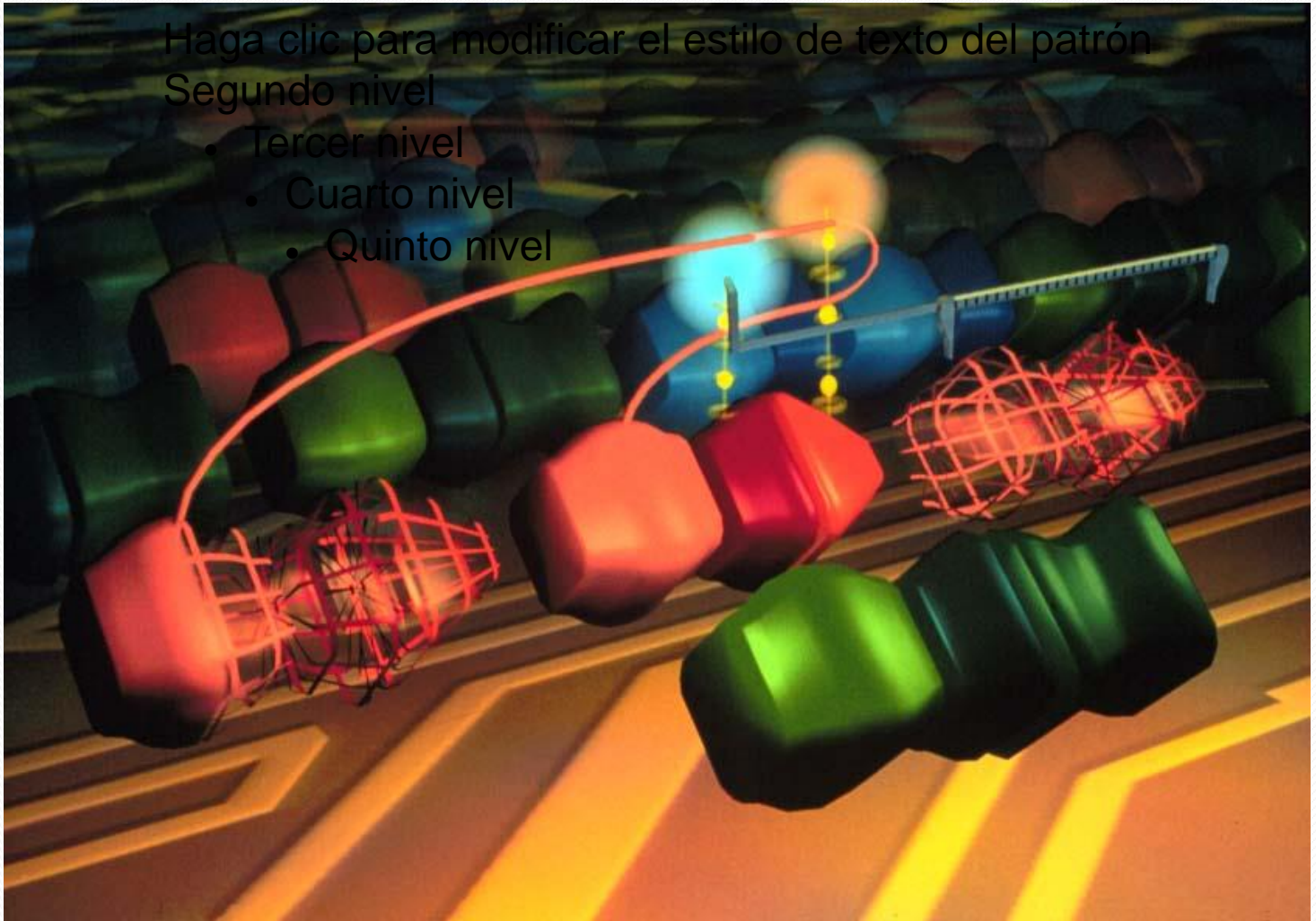


Tierra

Haga clic para modificar el estilo de texto del patrón

Segundo nivel

- Tercer nivel
- Cuarto nivel
- Quinto nivel



Tierra: Life

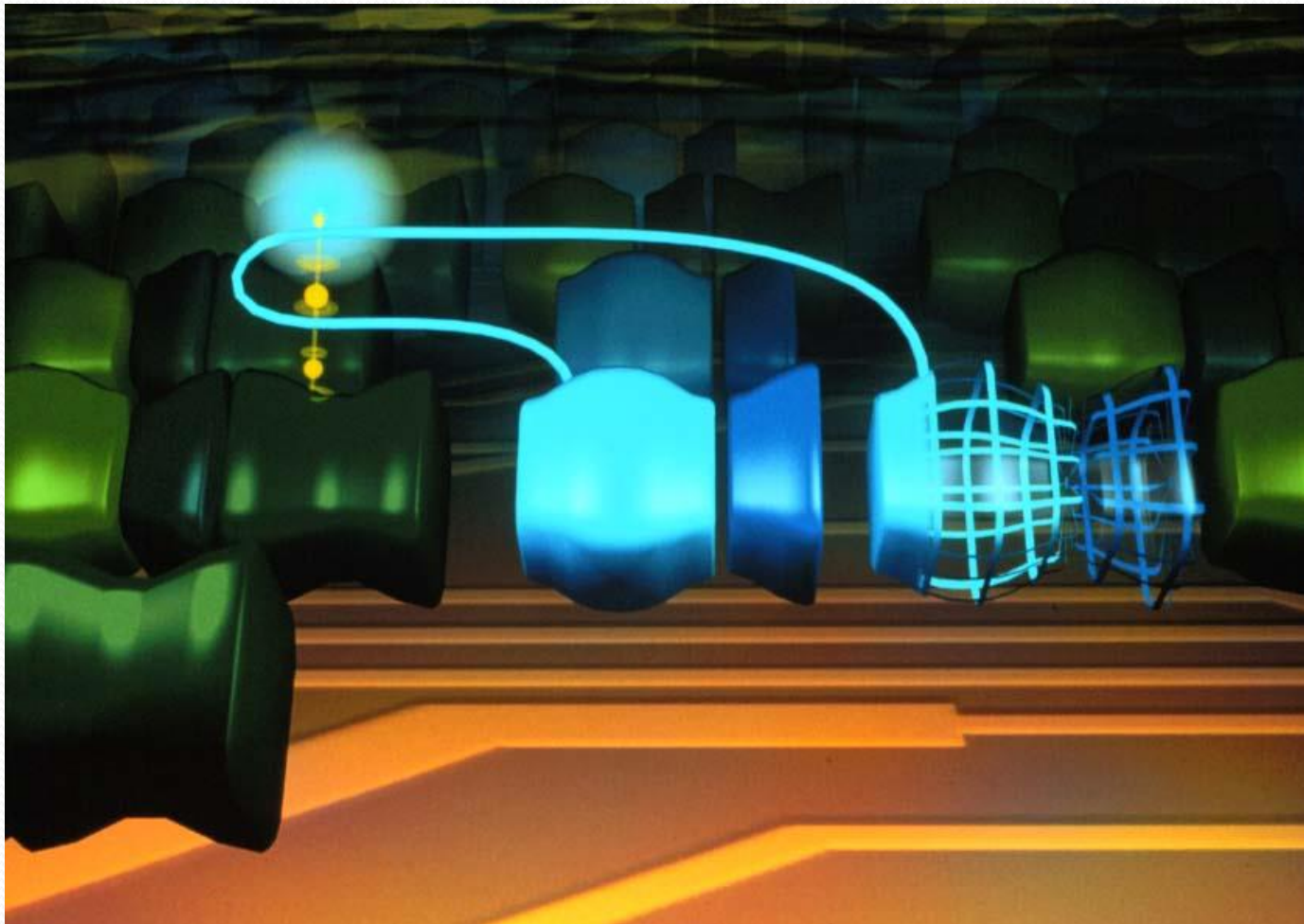


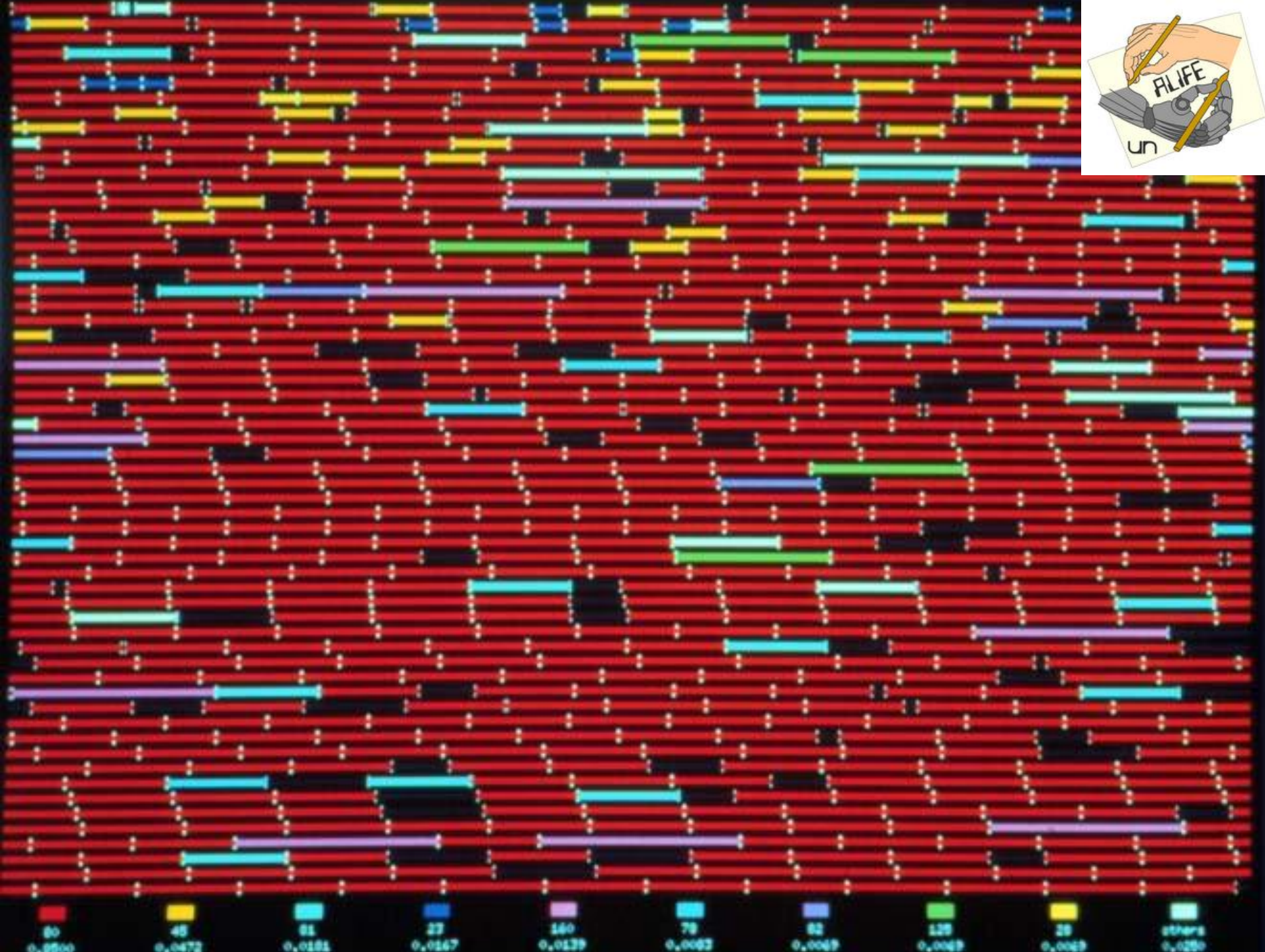


Tierra: Mutation and Death

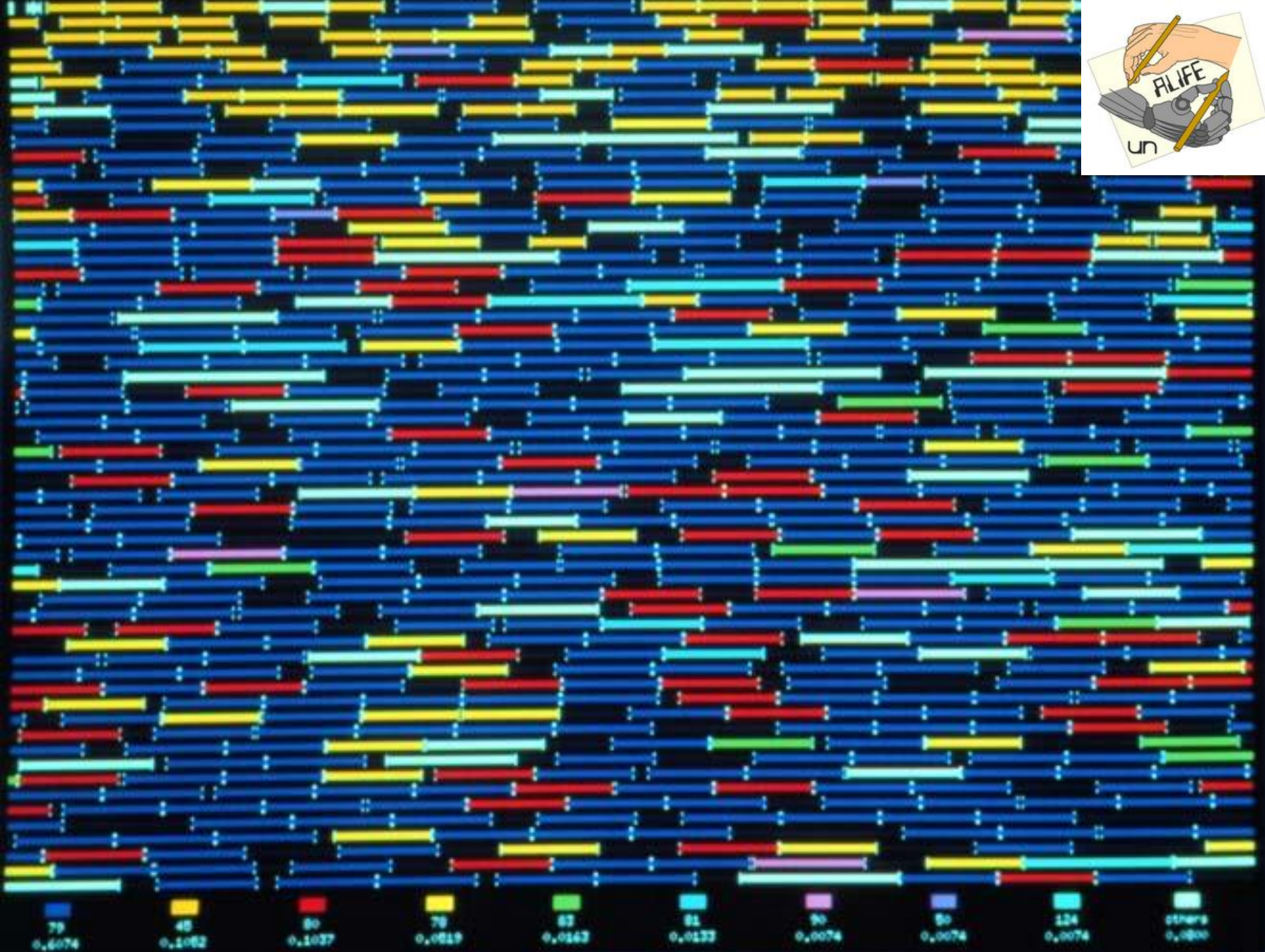


Tierra: Parasite











Evolution

We design a new evolutionary algorithm that uses chaotic behaviour for adapting the probability of applying the genetic operators

We develop a system that uses such EA and functional rewriting concepts for inducing functional programs



Evolution

We are using such EA for obtaining near optimal solutions to optimization problems like Two Steps Distribution Chain Problem, The Quadratic Assignment Problem

We use it for studying the prisoner dilemma and some other related theory of games problems.



Evolution

We are extending such EA not for just adjusting the probabilities but for evolving the genetic operators (Meta-evolution)

We are combining EA with neural networks for solving general artificial intelligence problems

God and Alife



[Video](#)