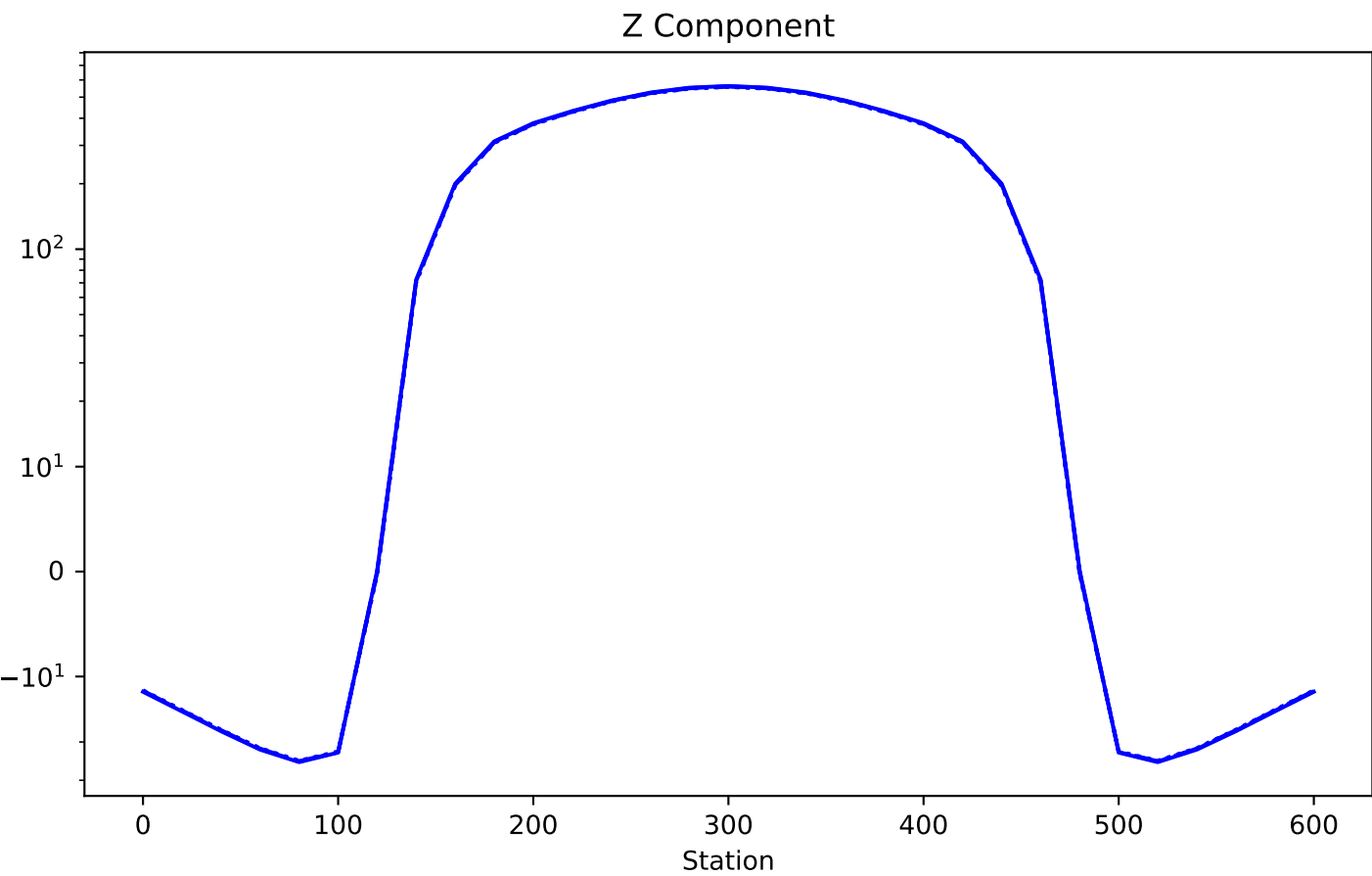
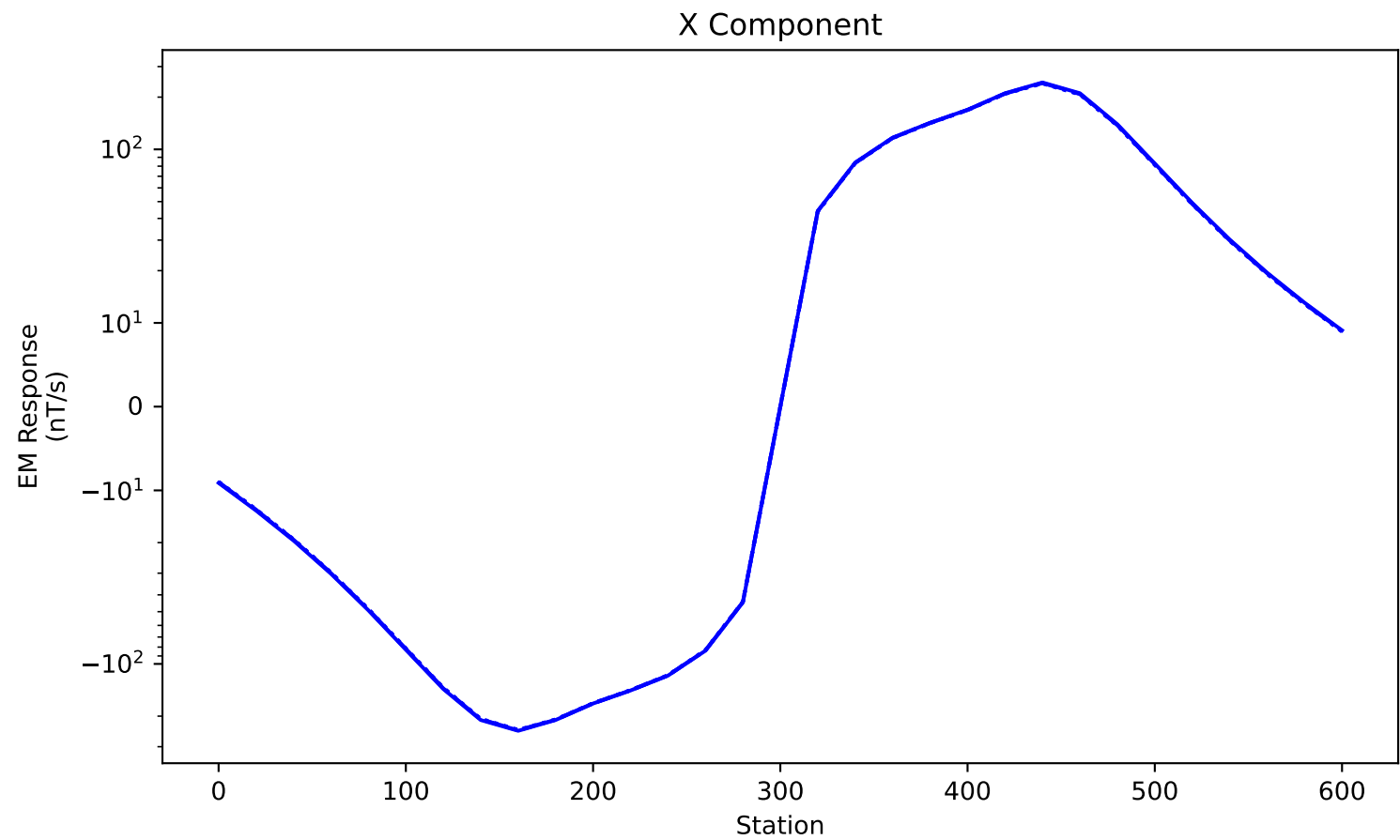
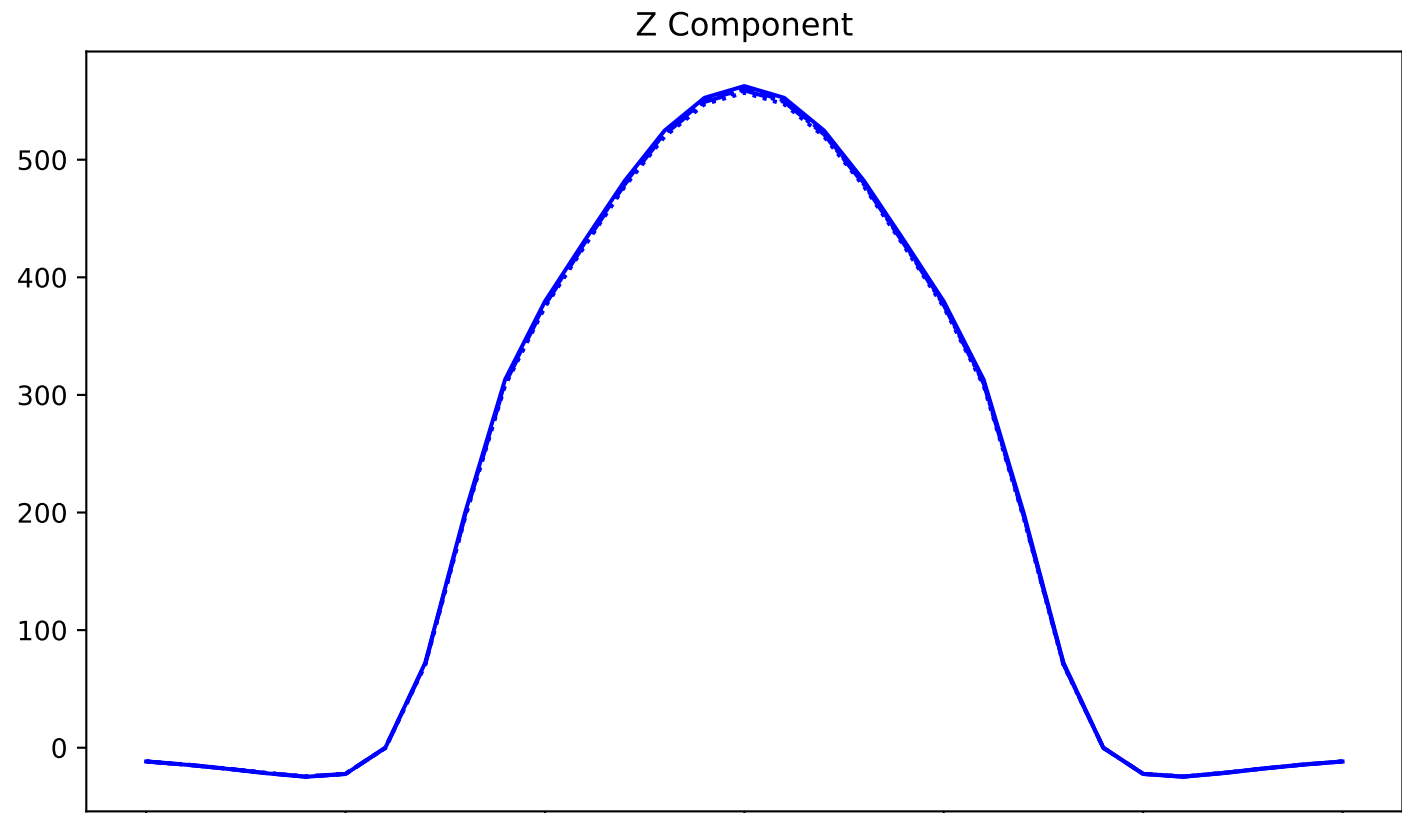
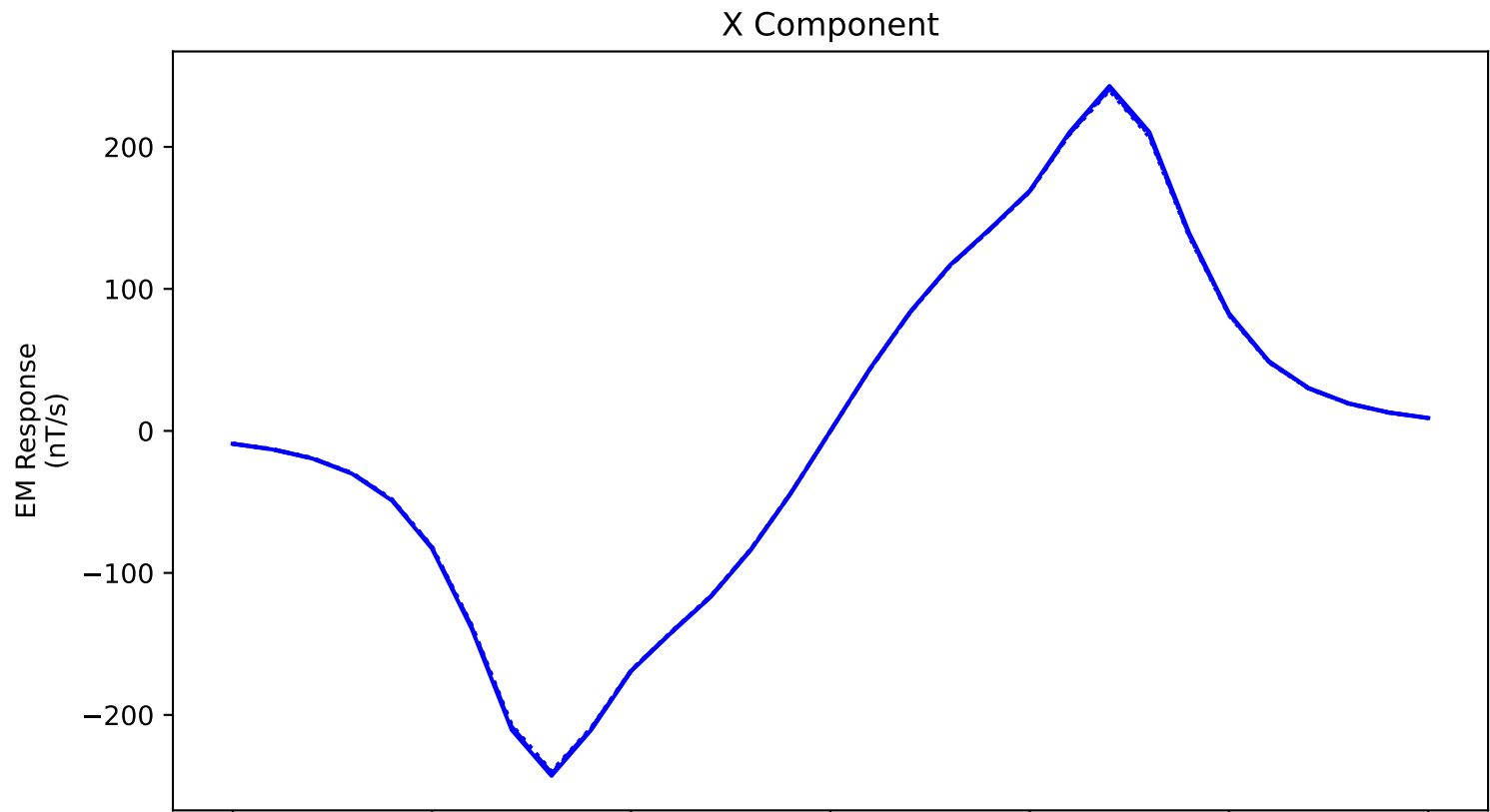
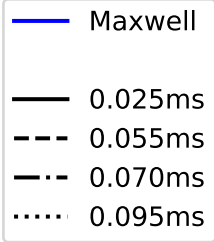
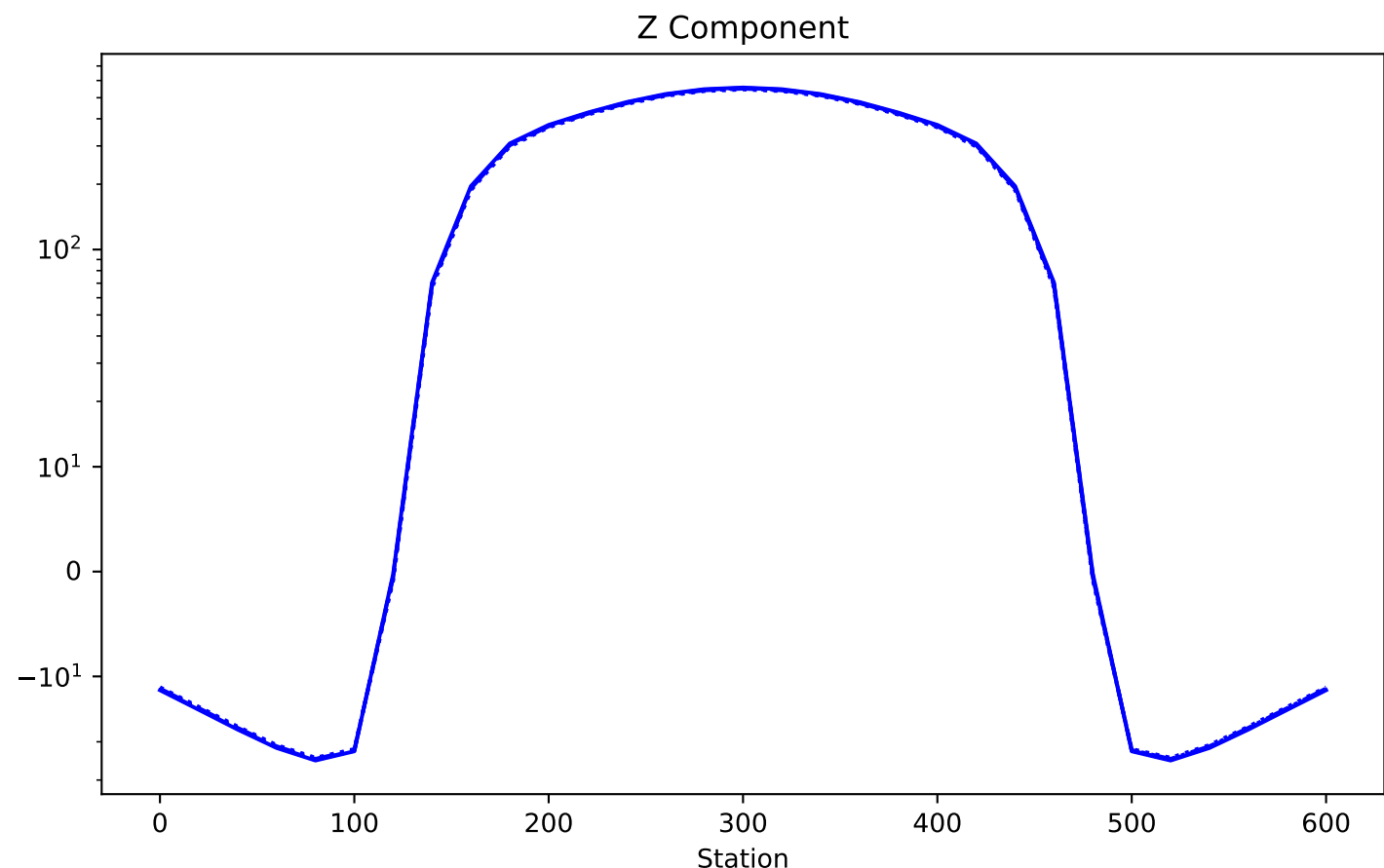
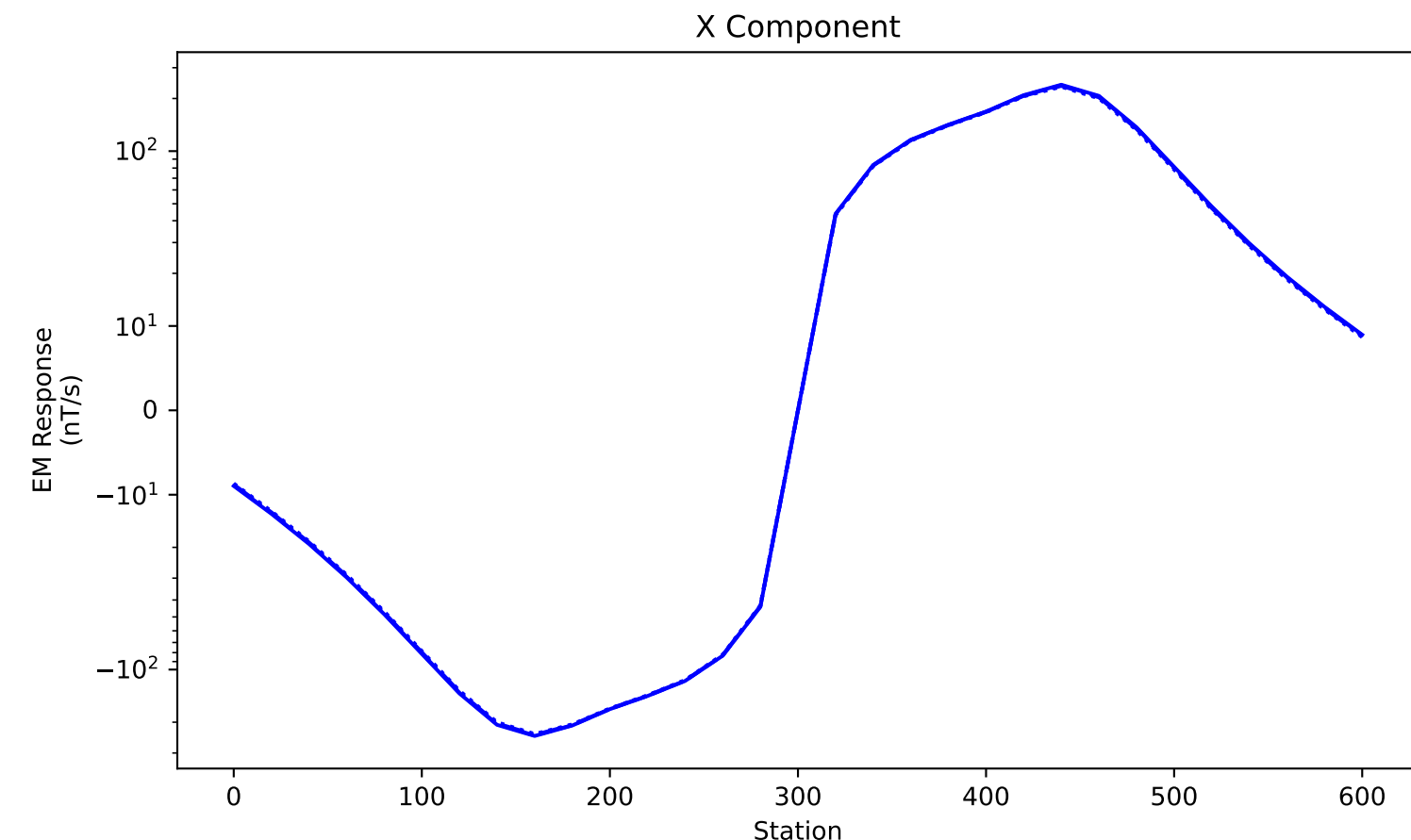
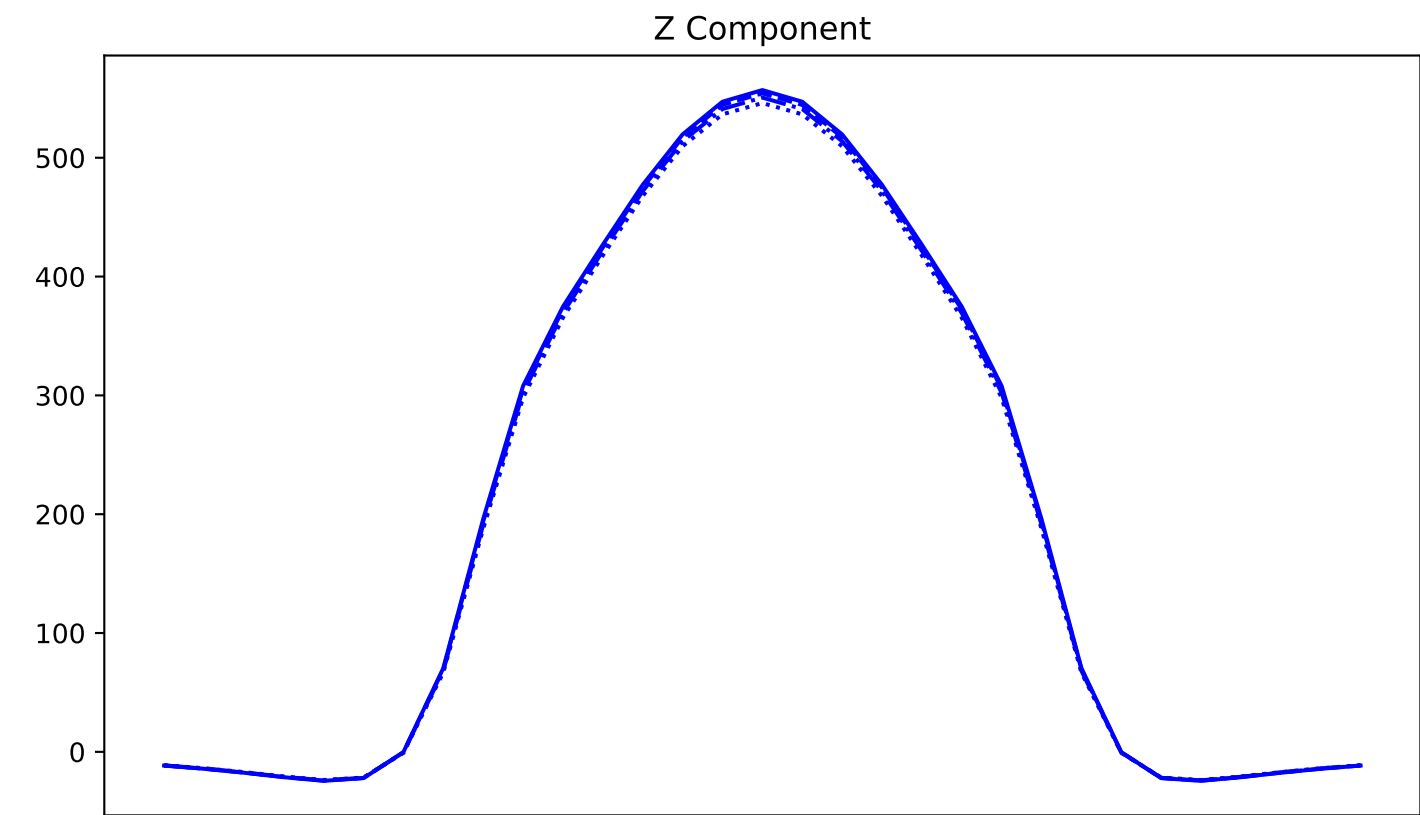
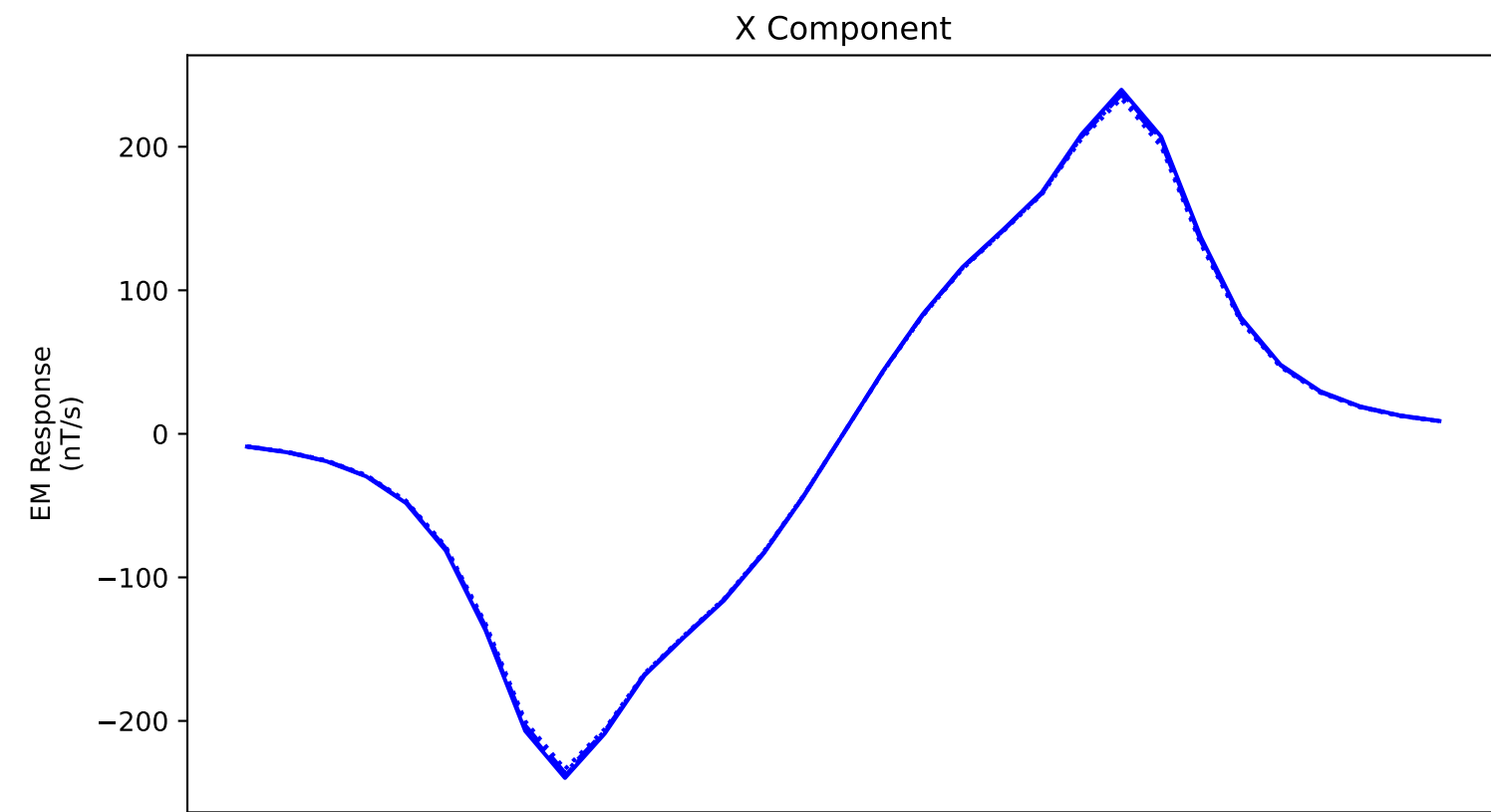
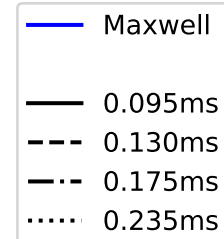


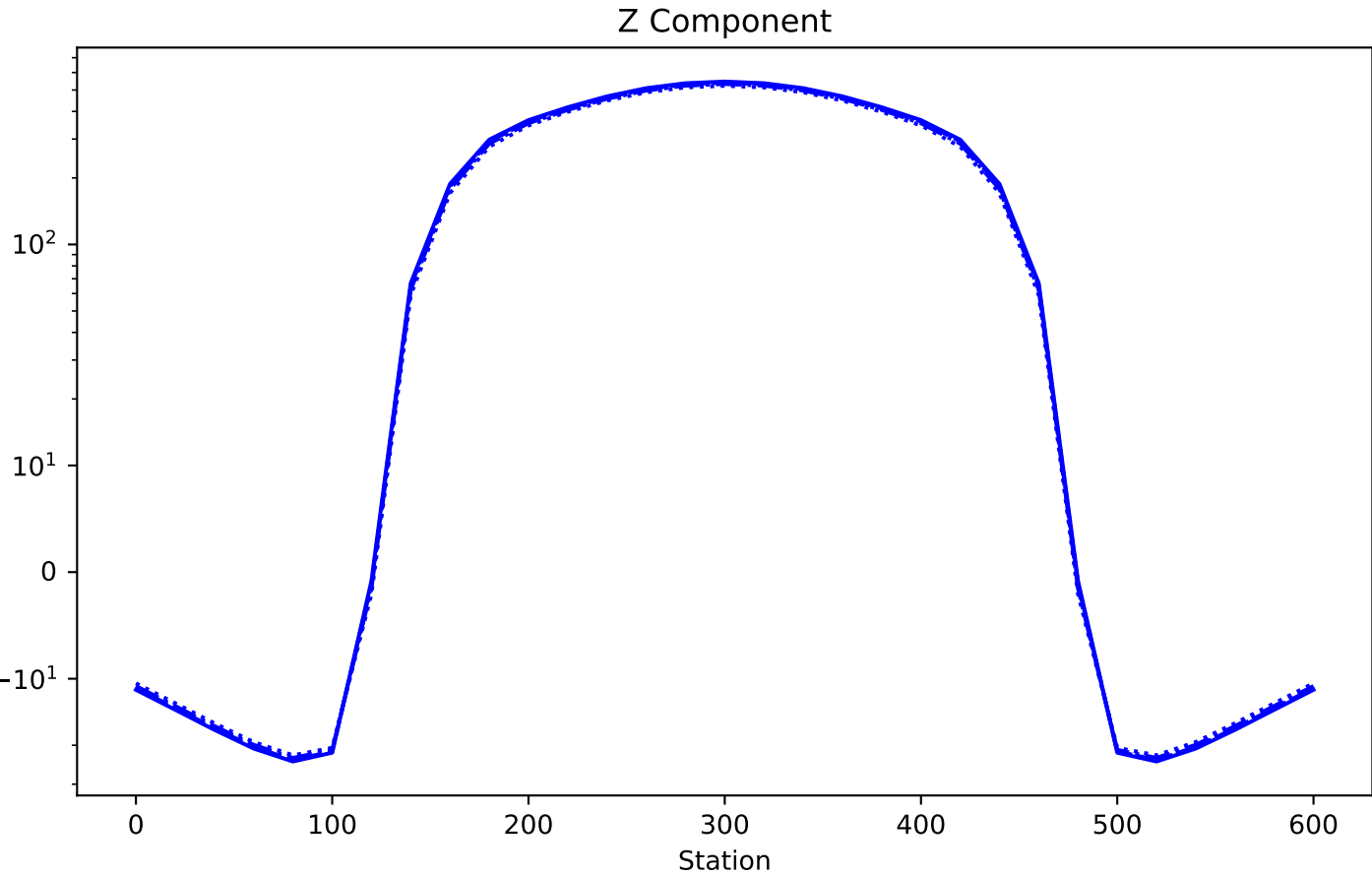
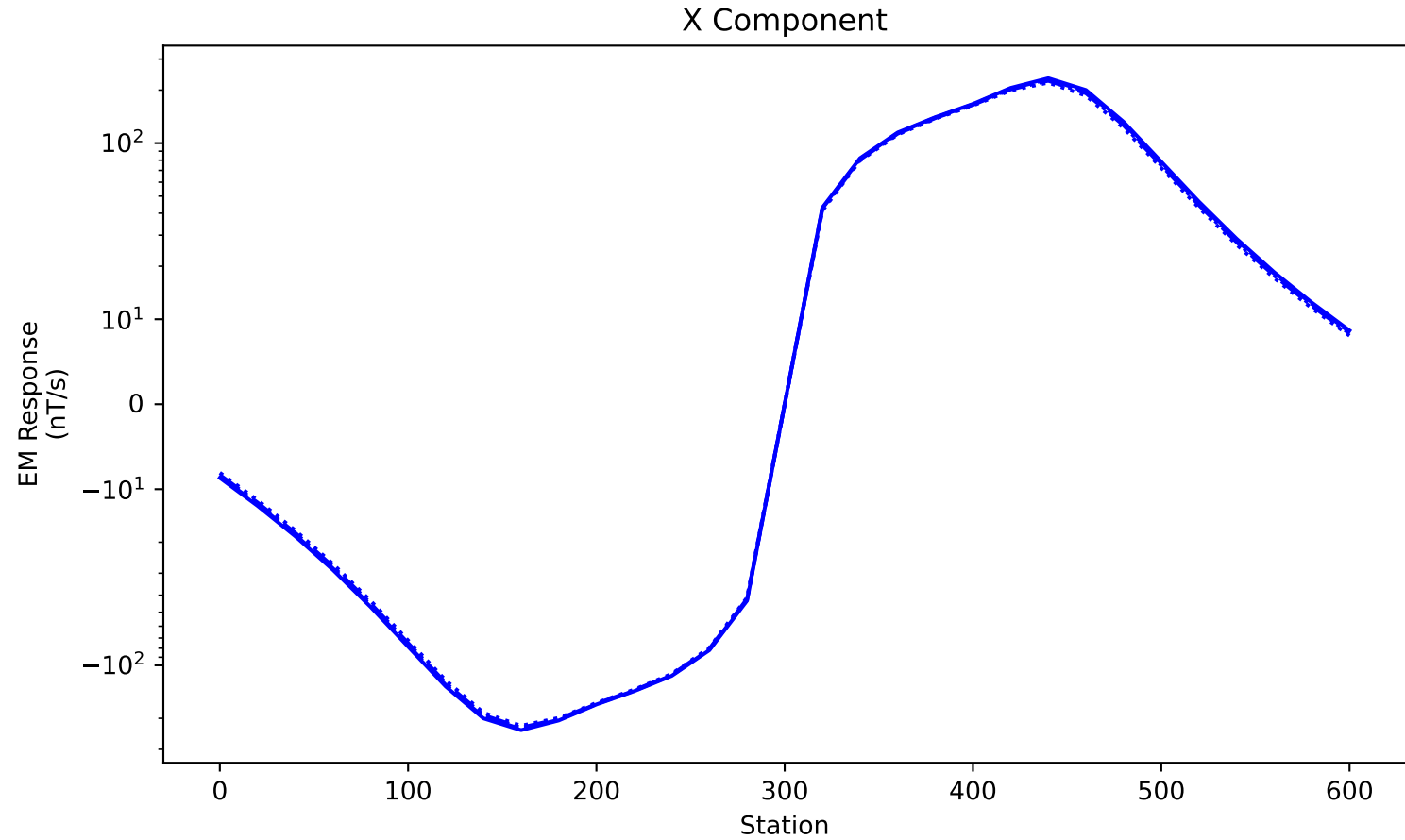
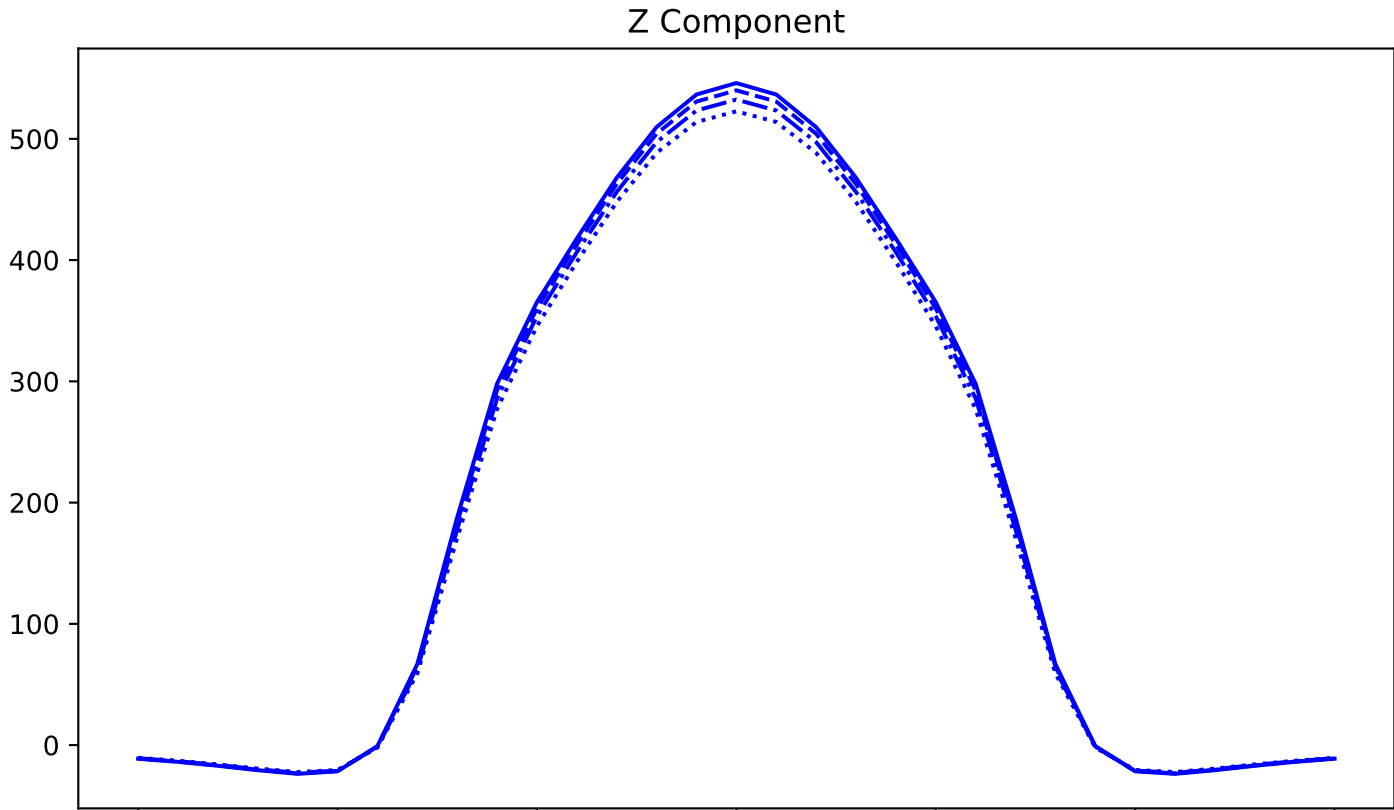
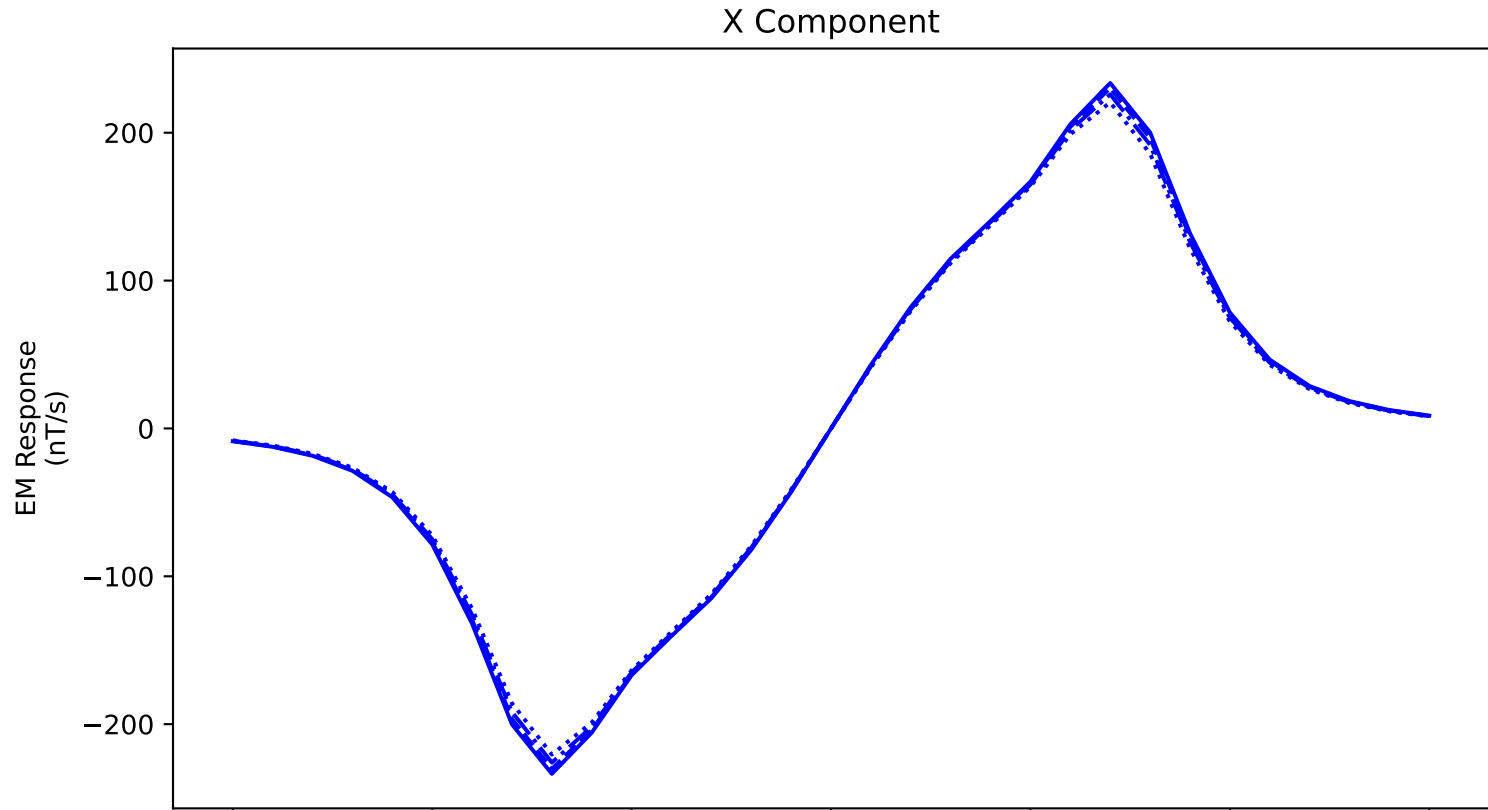
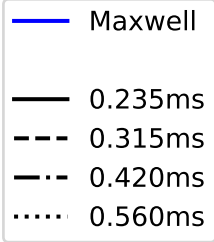
Two-Way Induction
300x100m, 1000S
LOOP=0
0.0255ms to 0.095ms



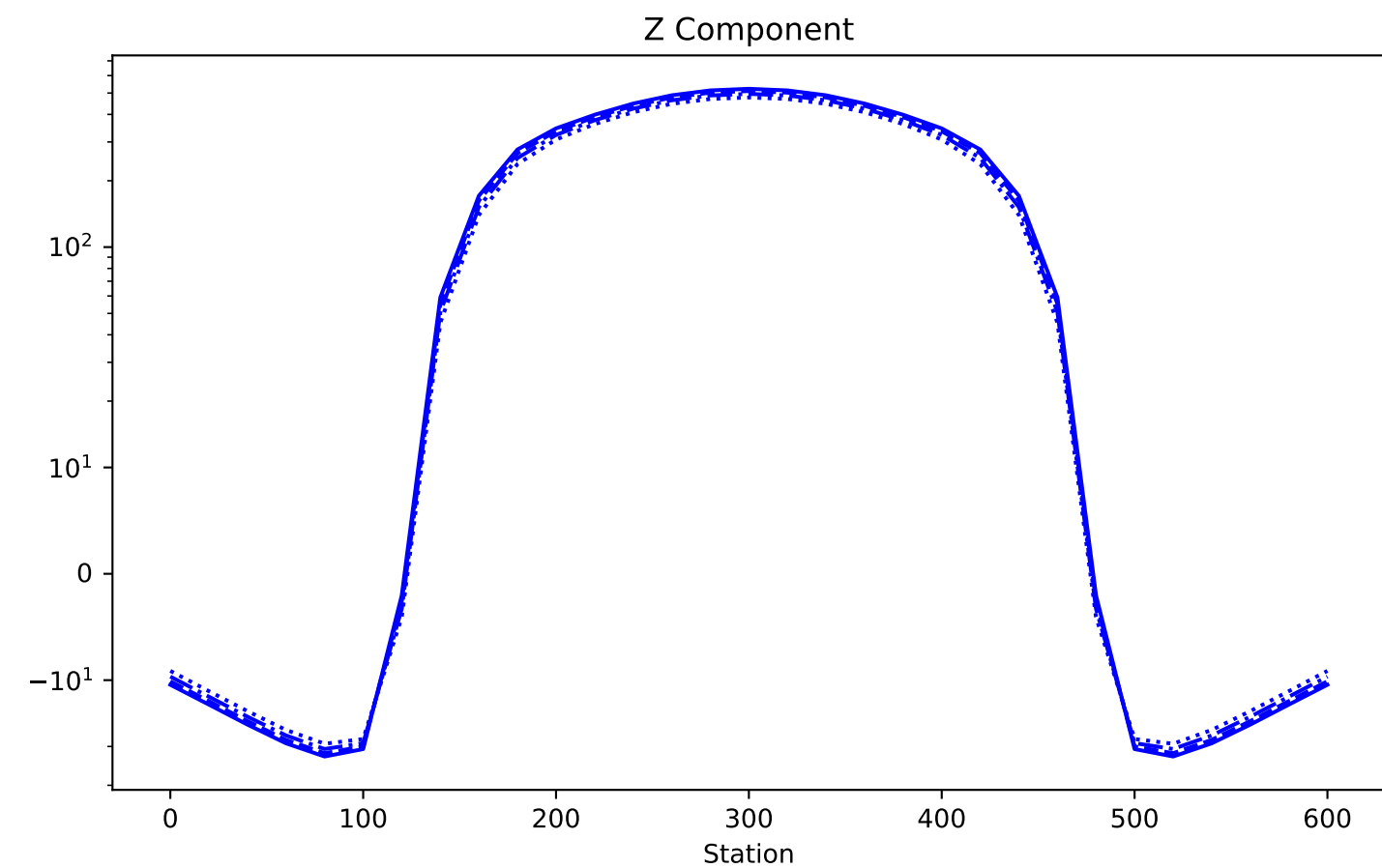
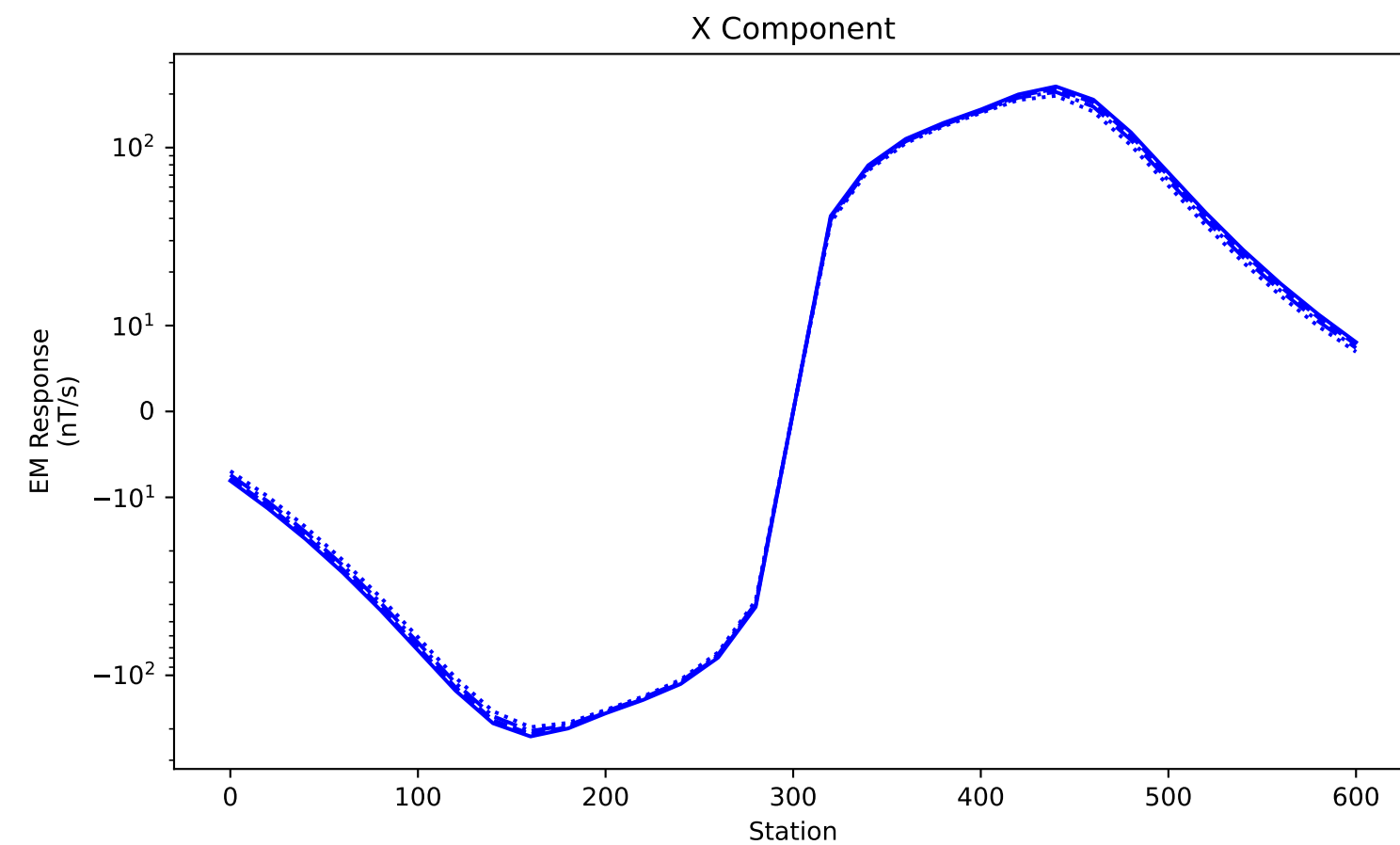
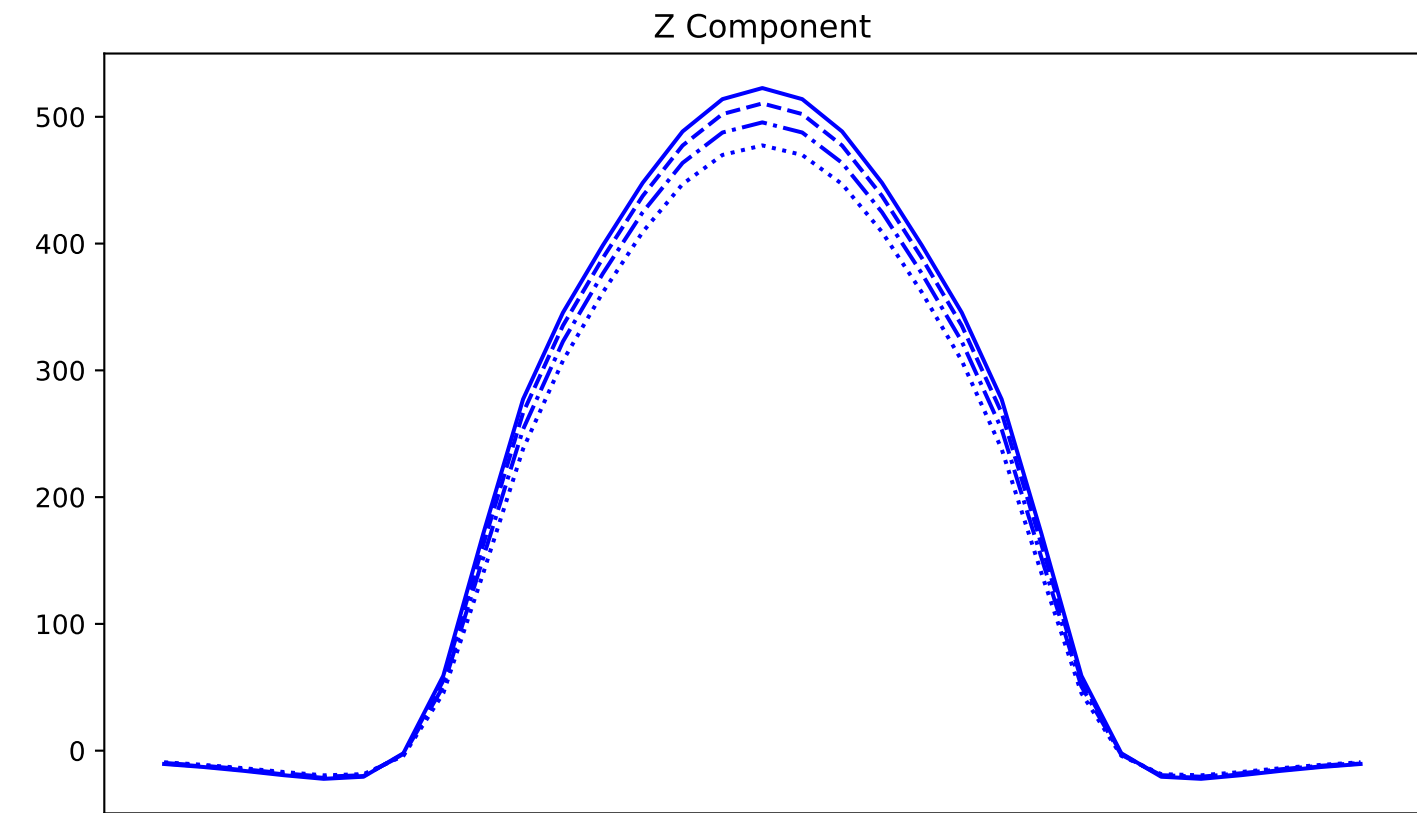
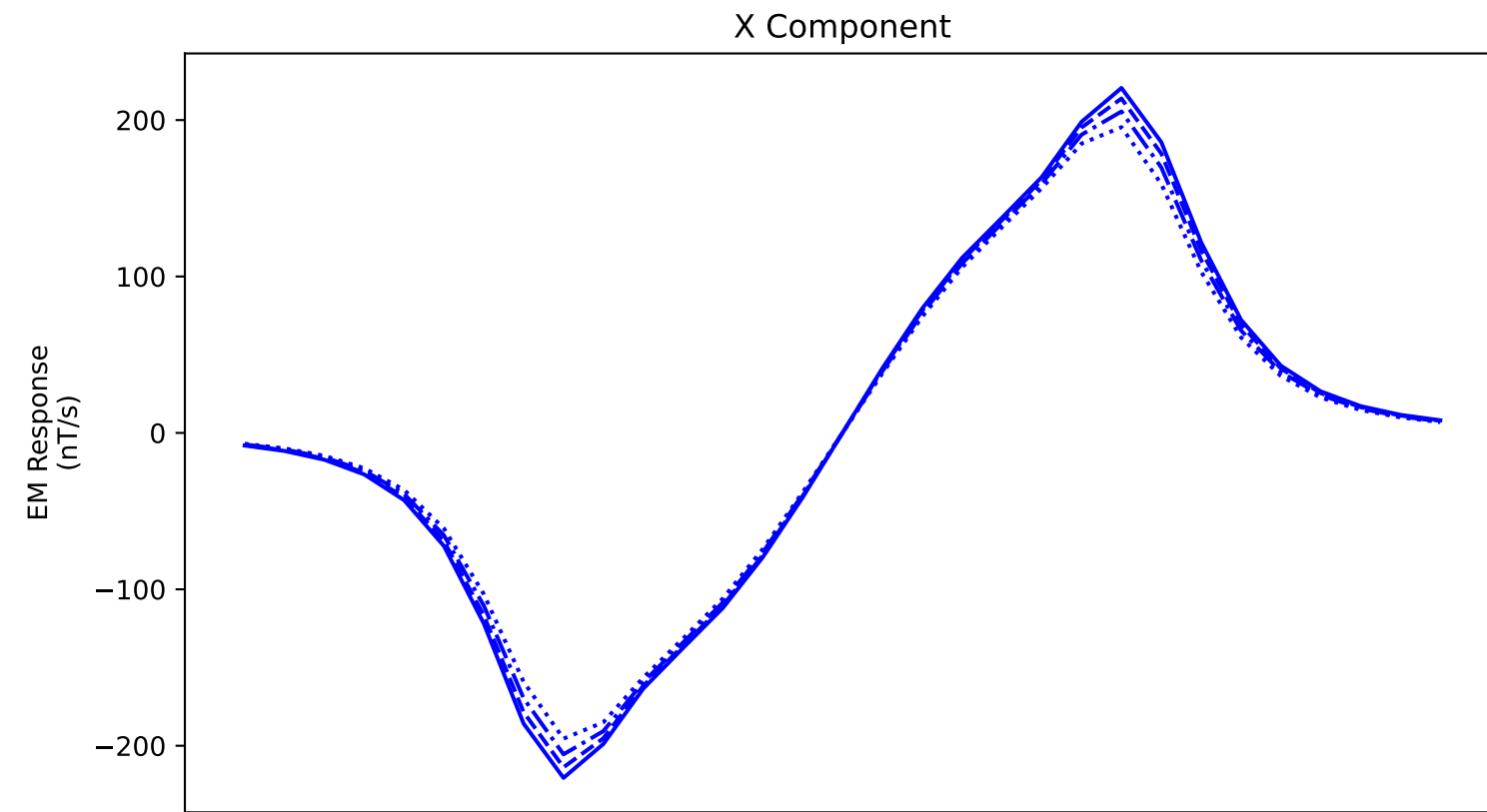
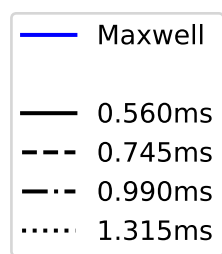
Two-Way Induction
300x100m, 1000S
LOOP=0
0.095ms to 0.235ms



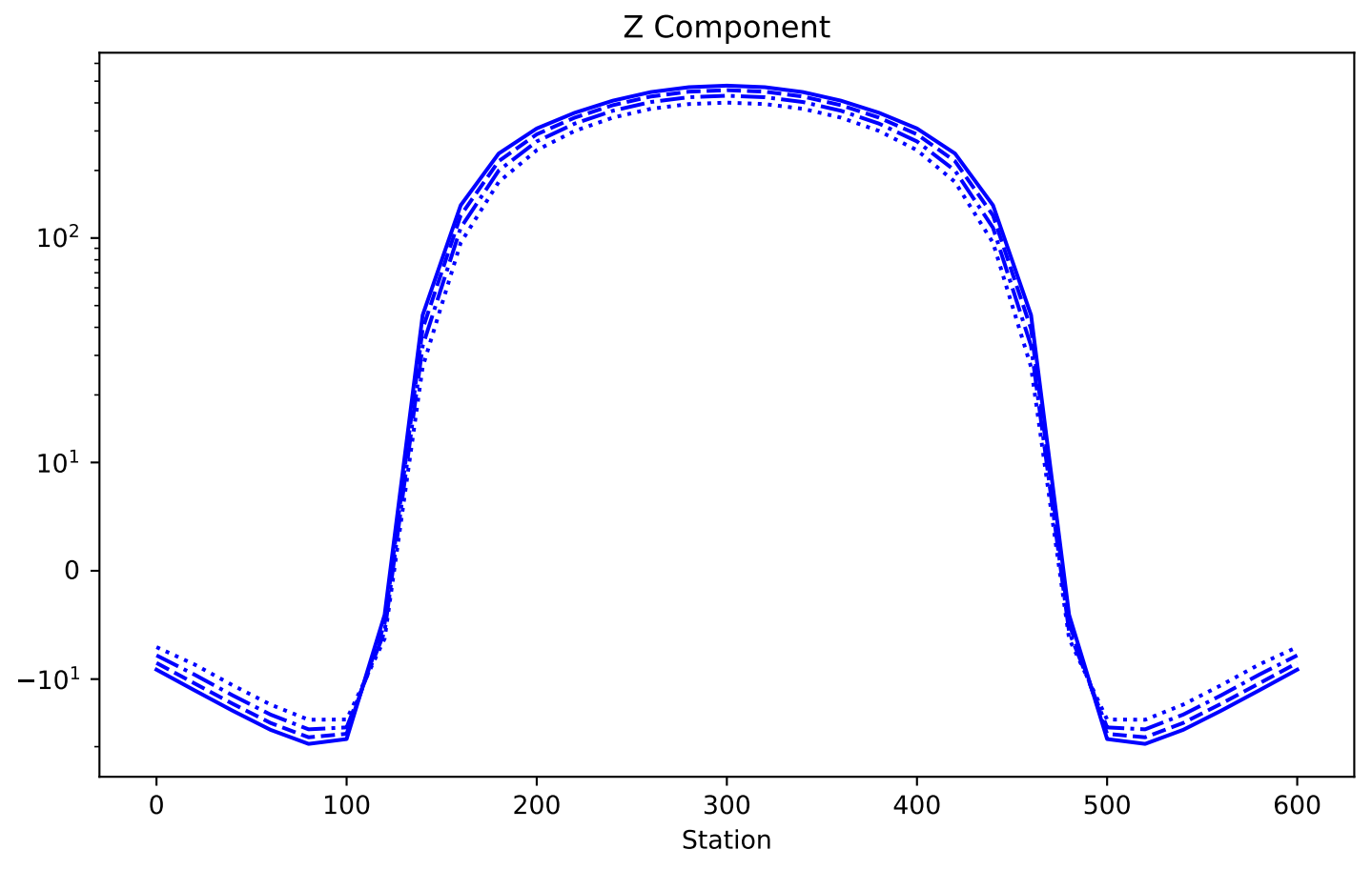
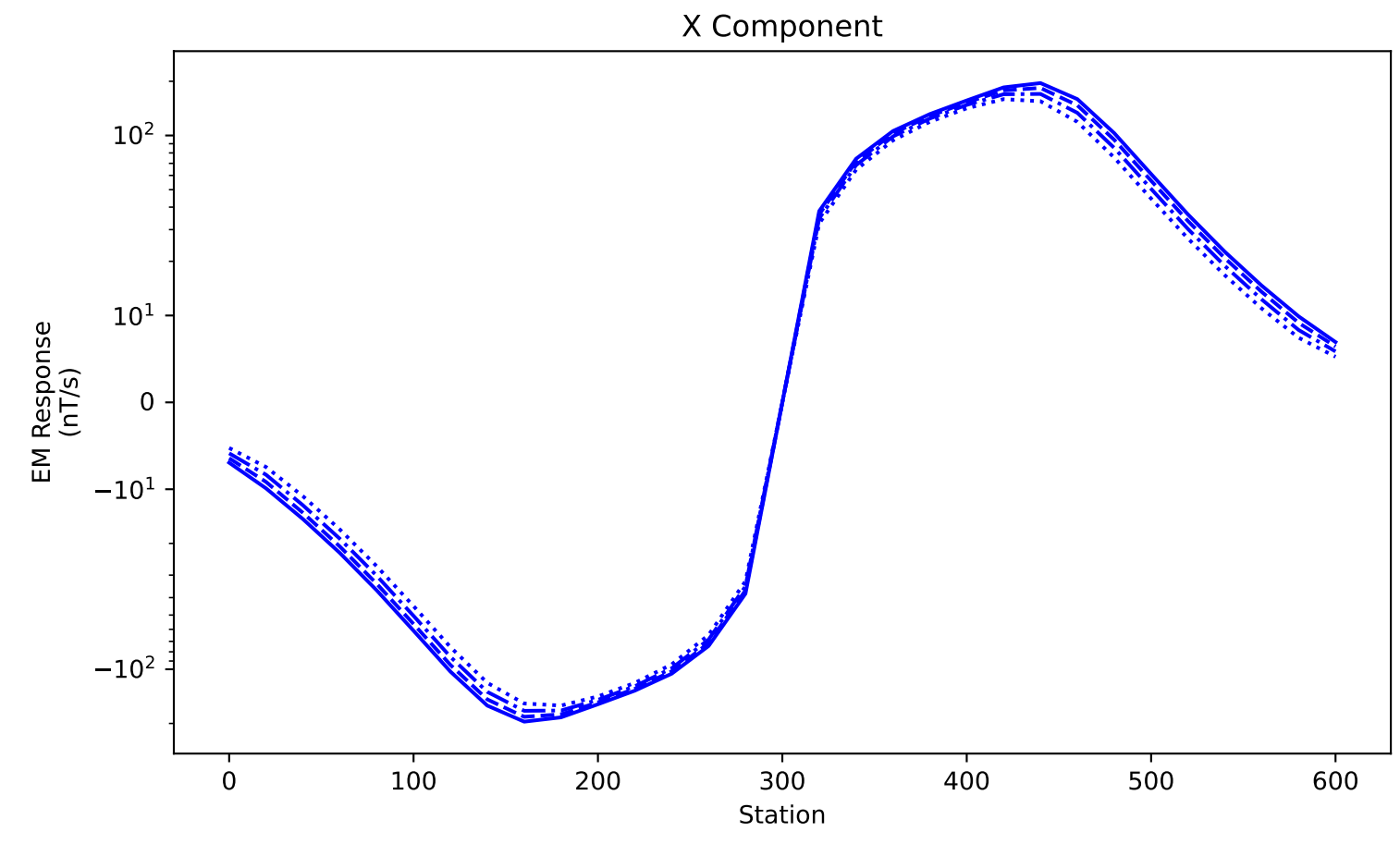
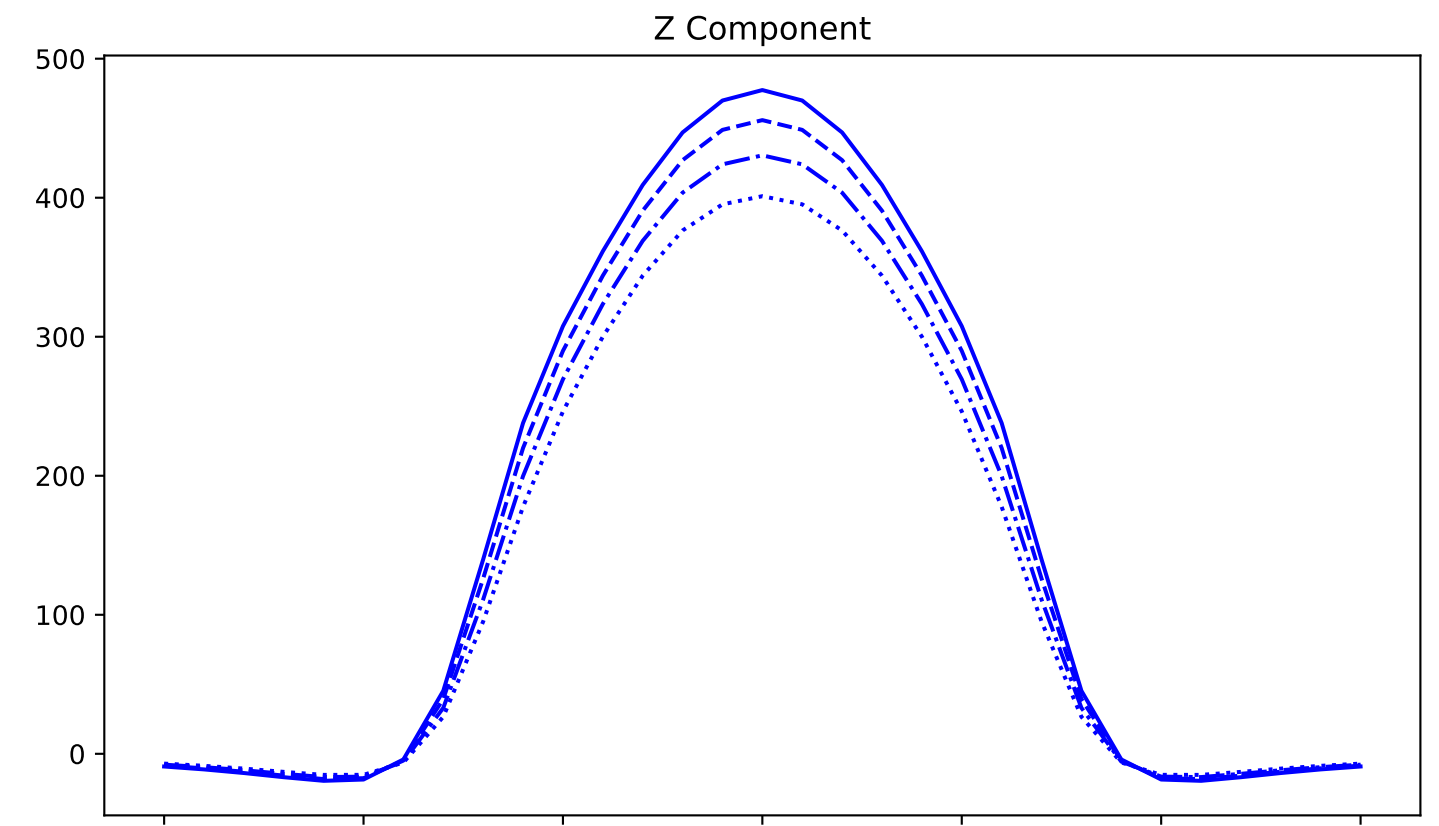
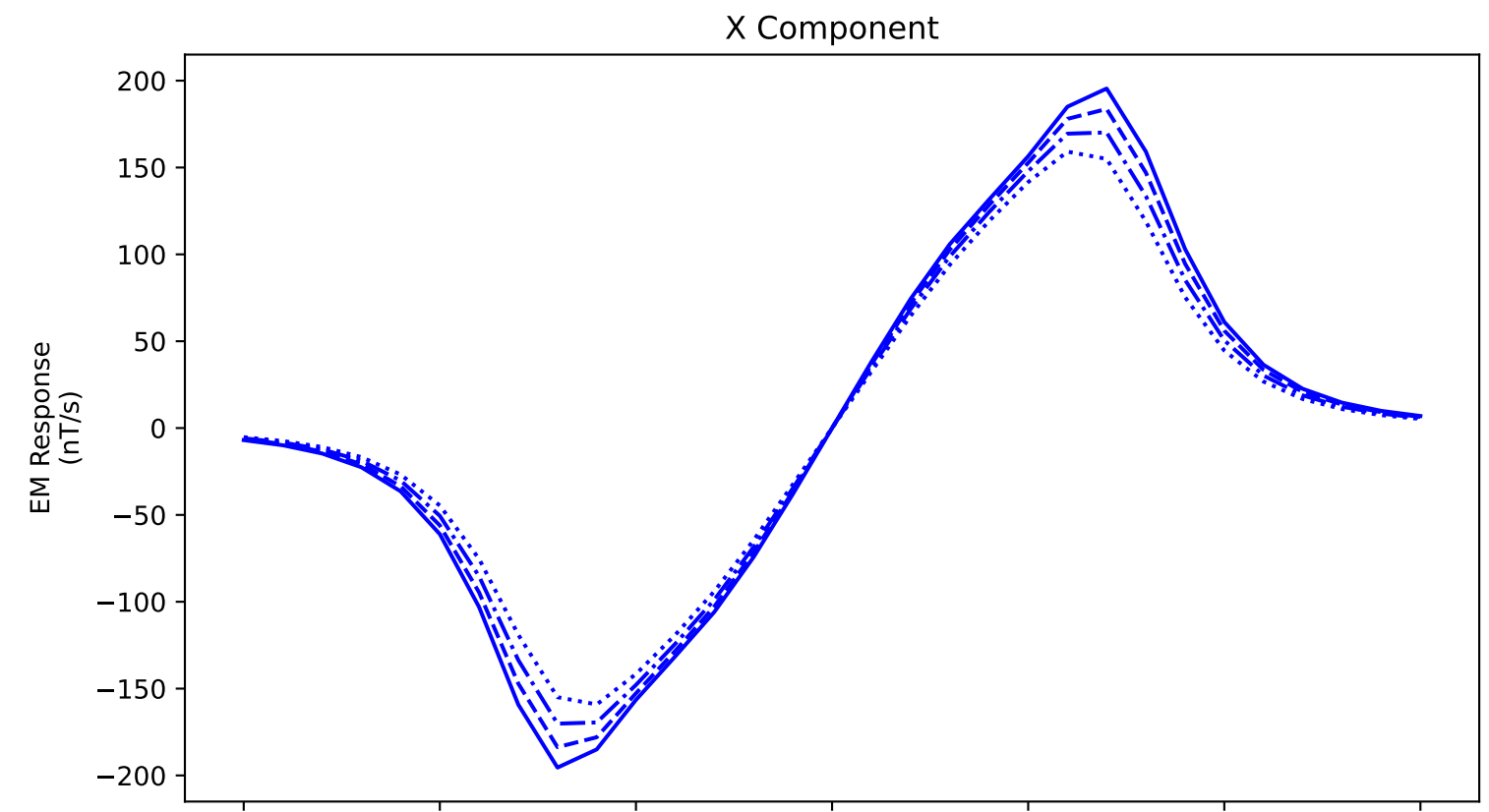
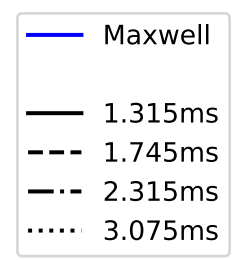
Two-Way Induction
300x100m, 1000S
LOOP=0
0.235ms to 0.56ms



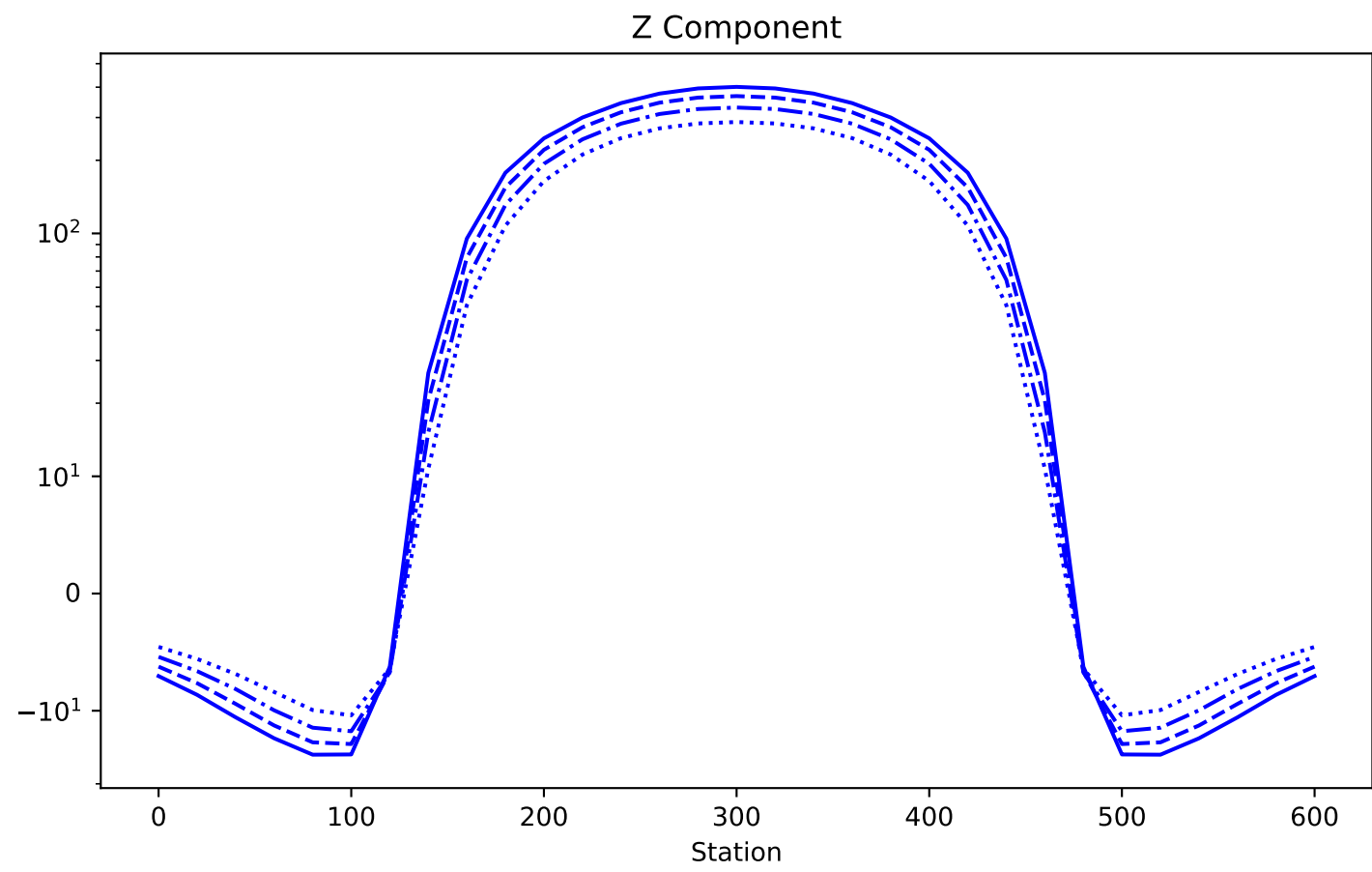
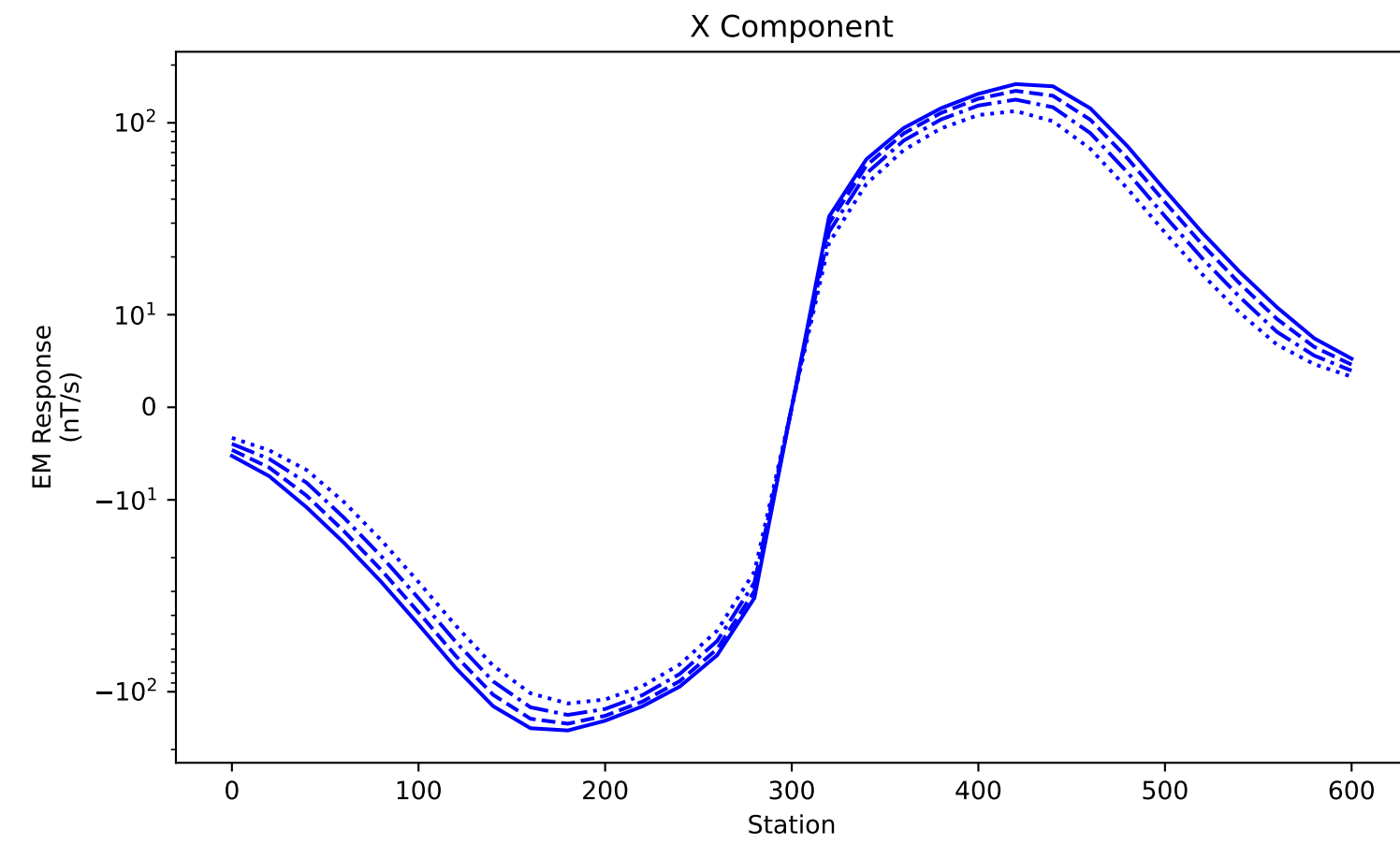
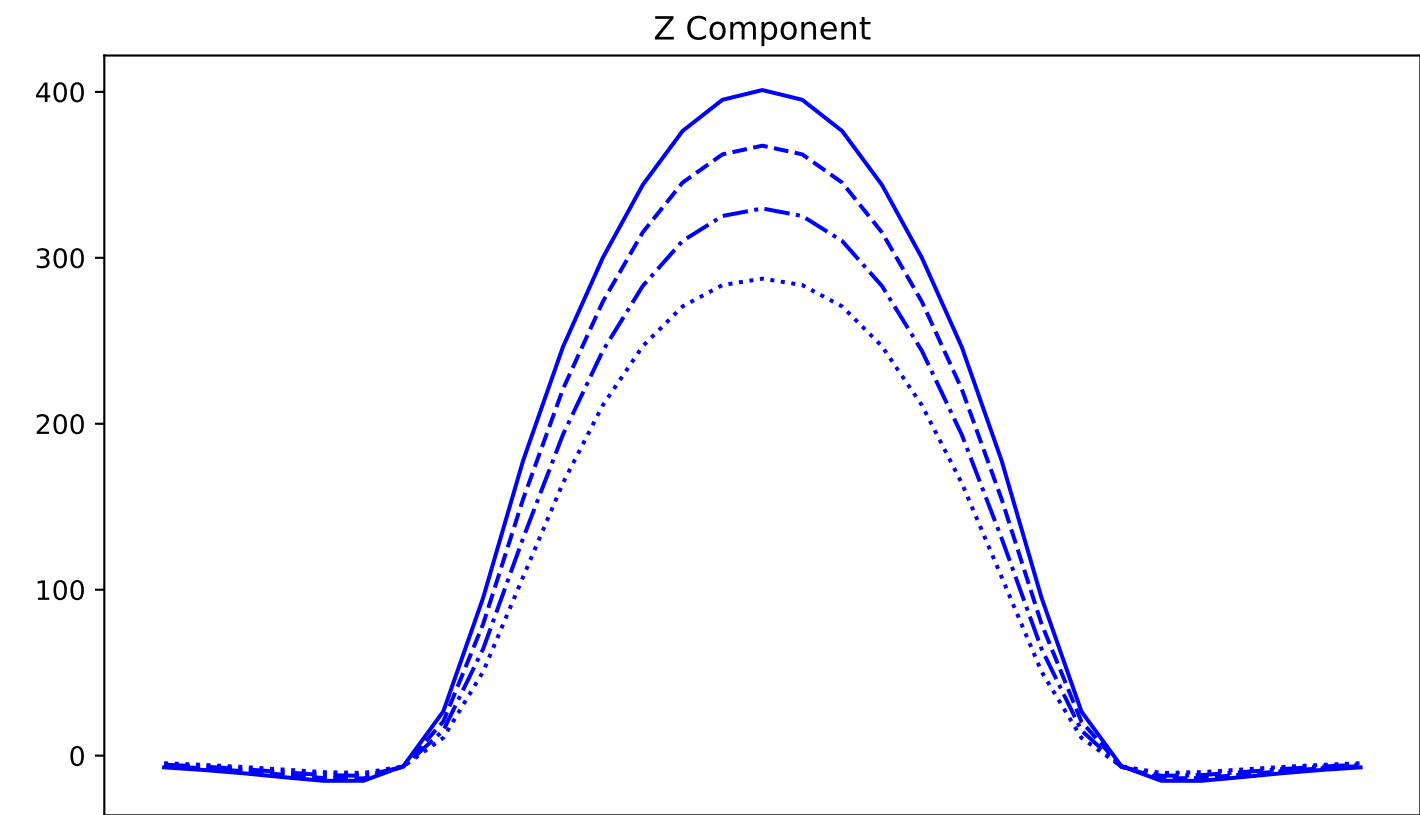
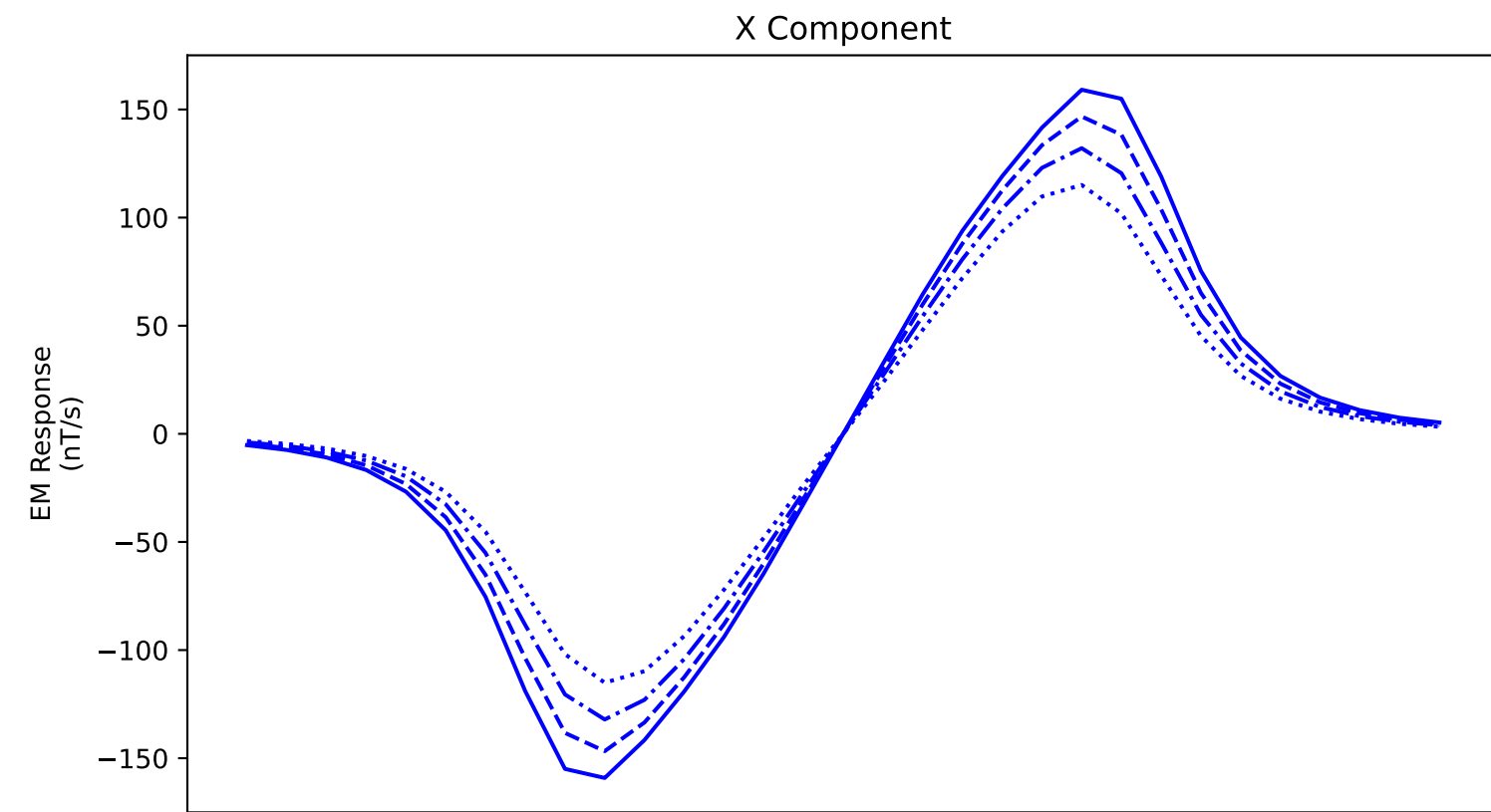
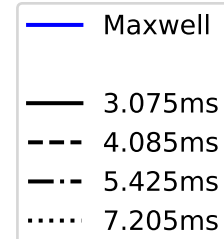
Two-Way Induction
300x100m, 1000S
LOOP=0
0.56ms to 1.315ms



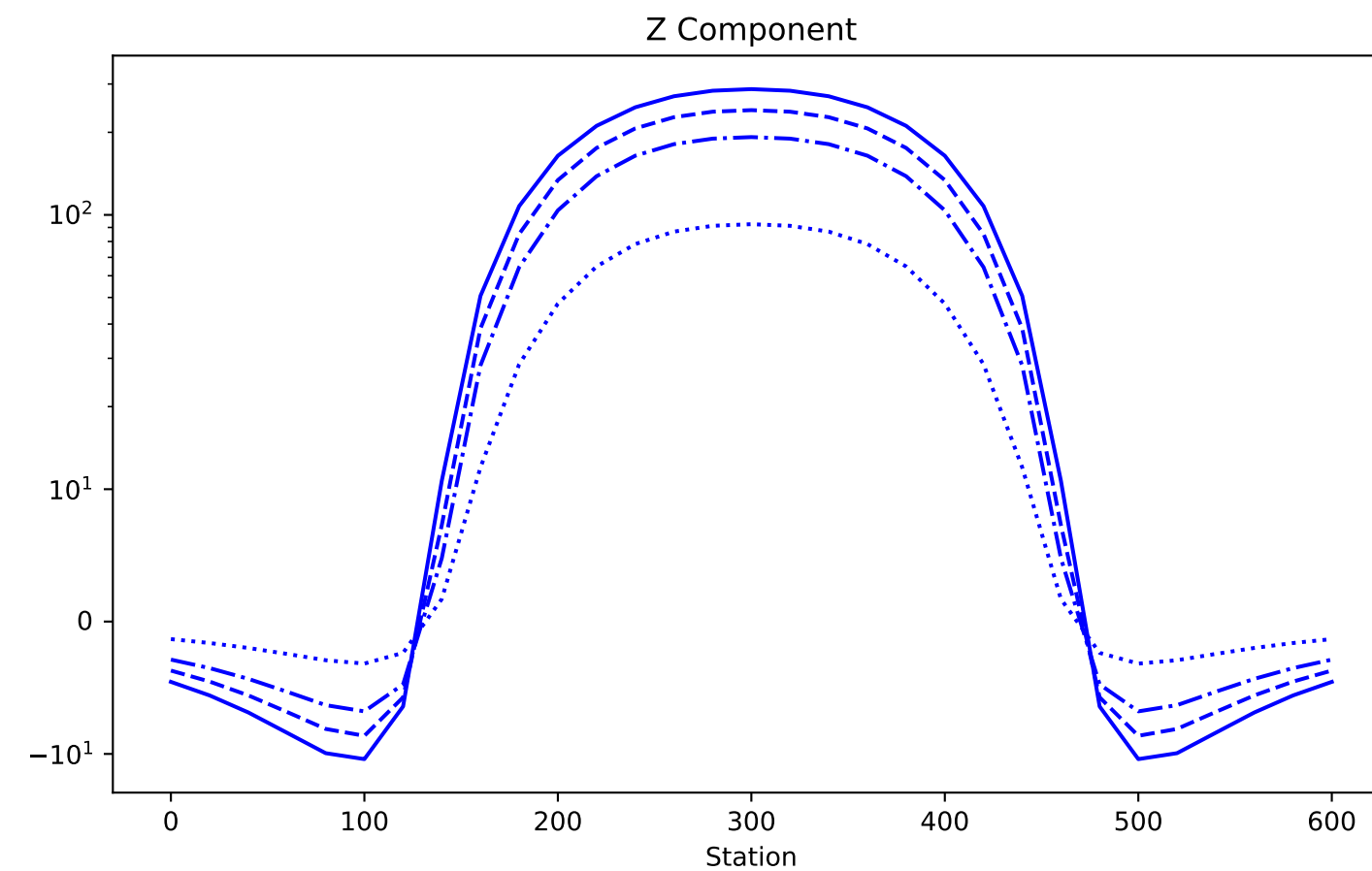
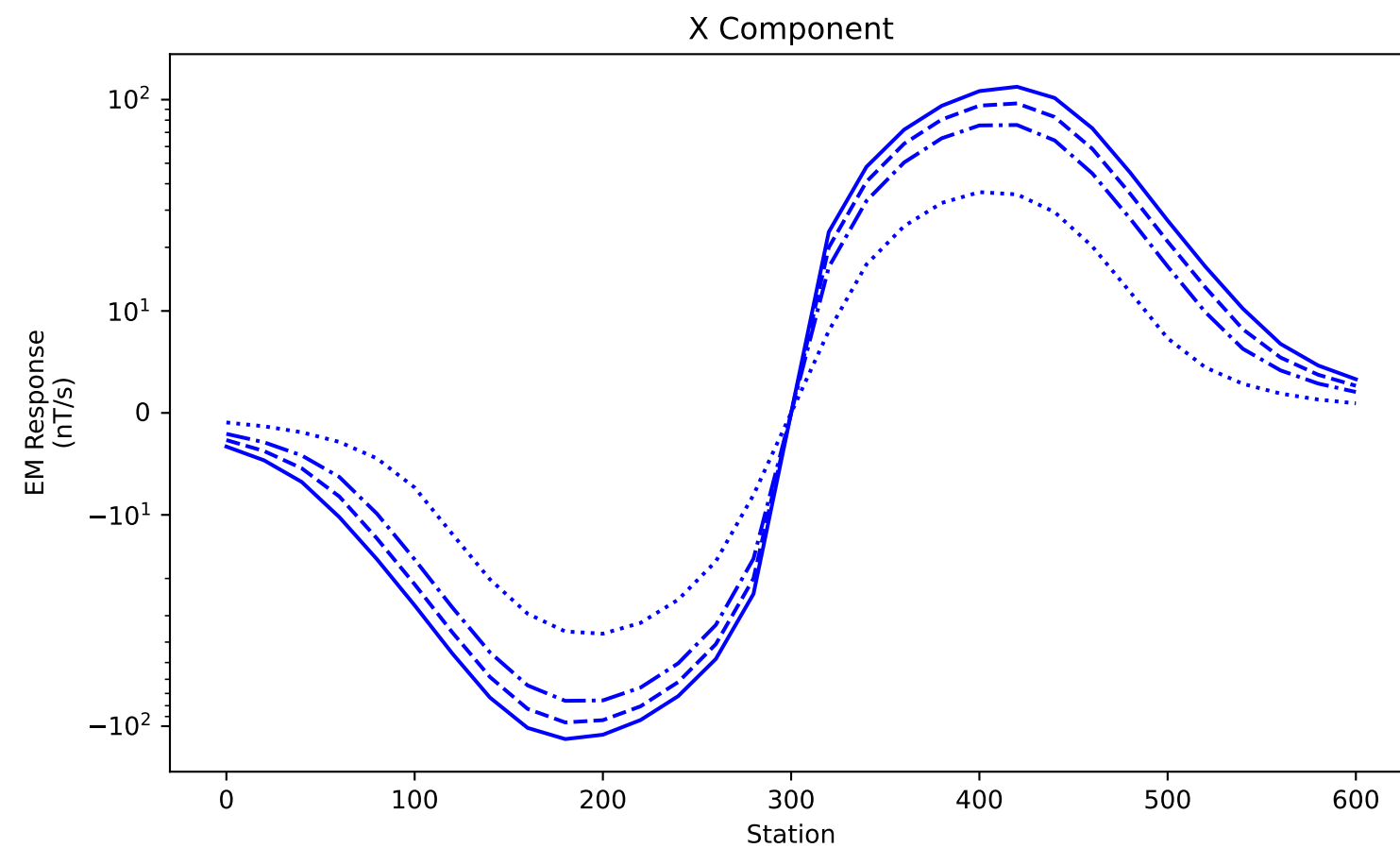
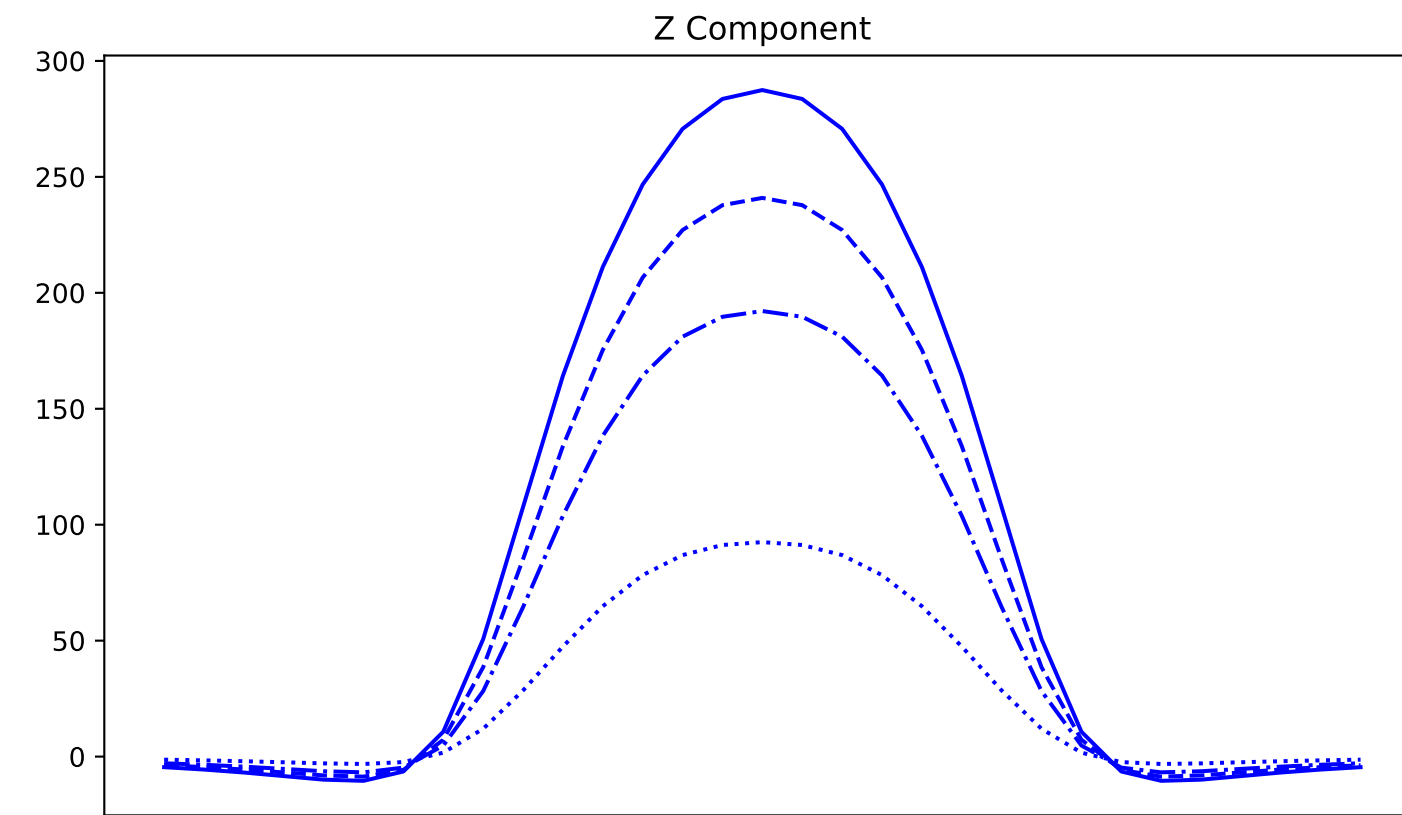
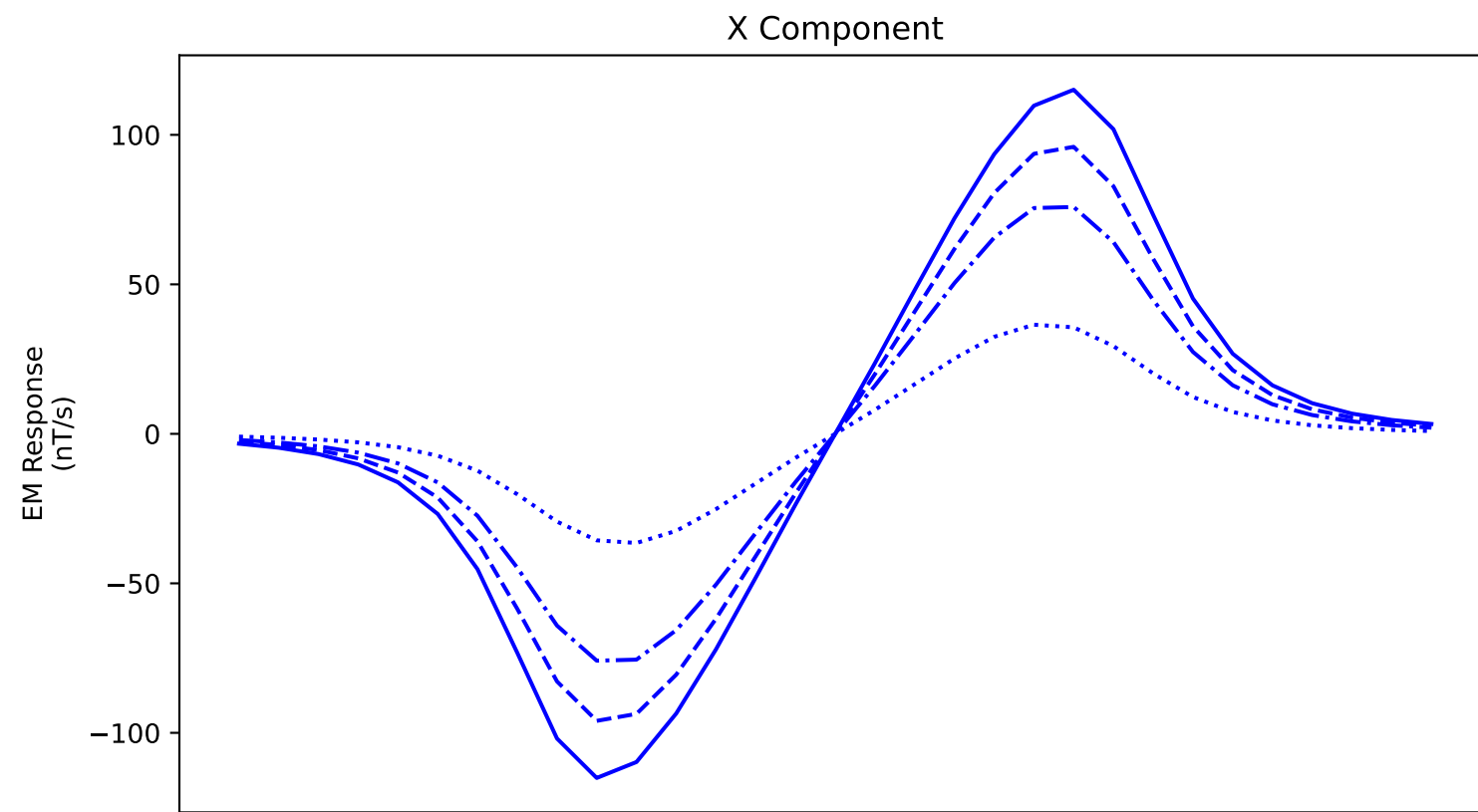
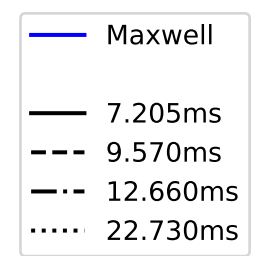
Two-Way Induction
300x100m, 1000S
LOOP=0
1.315ms to 3.075ms



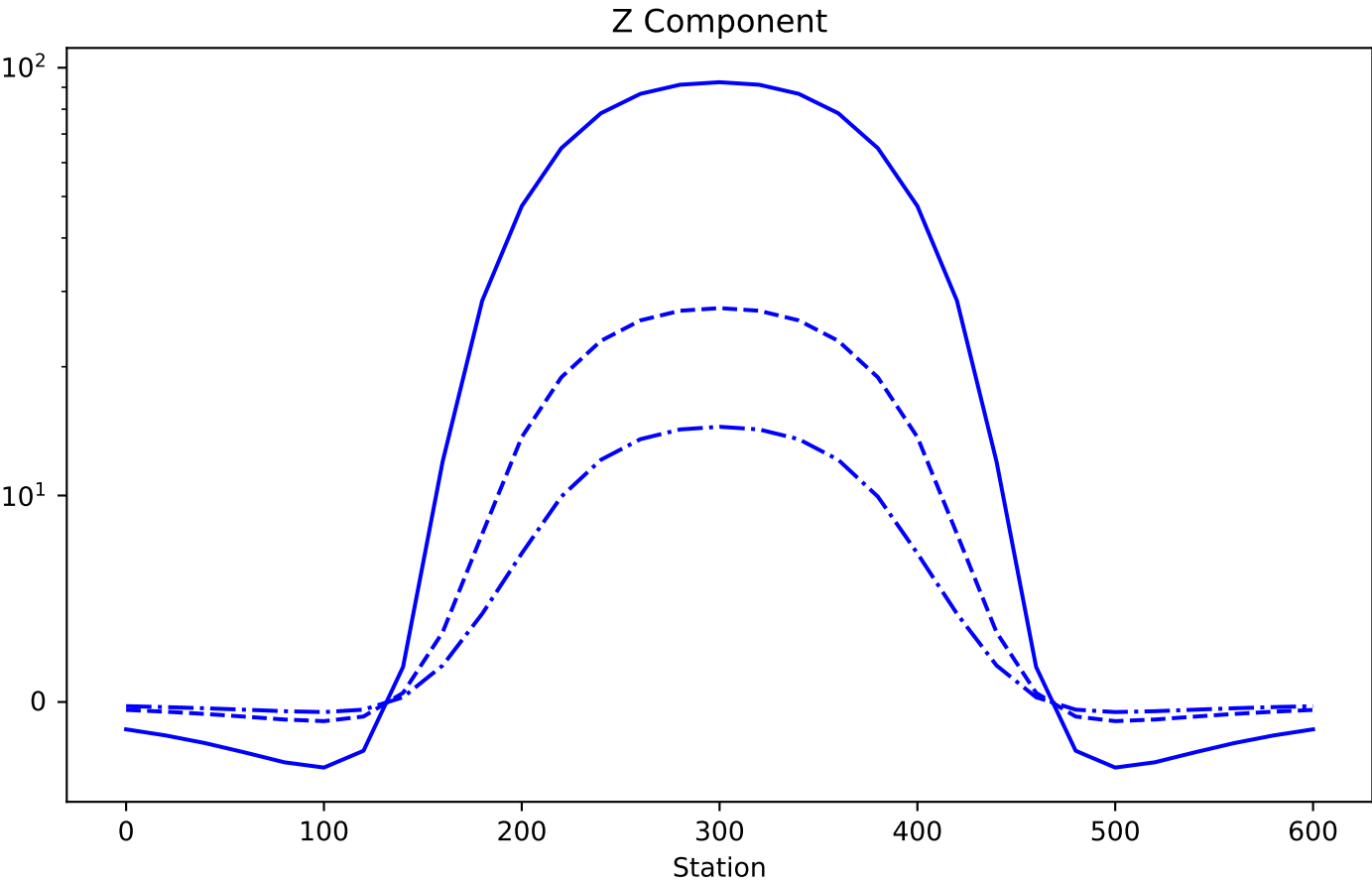
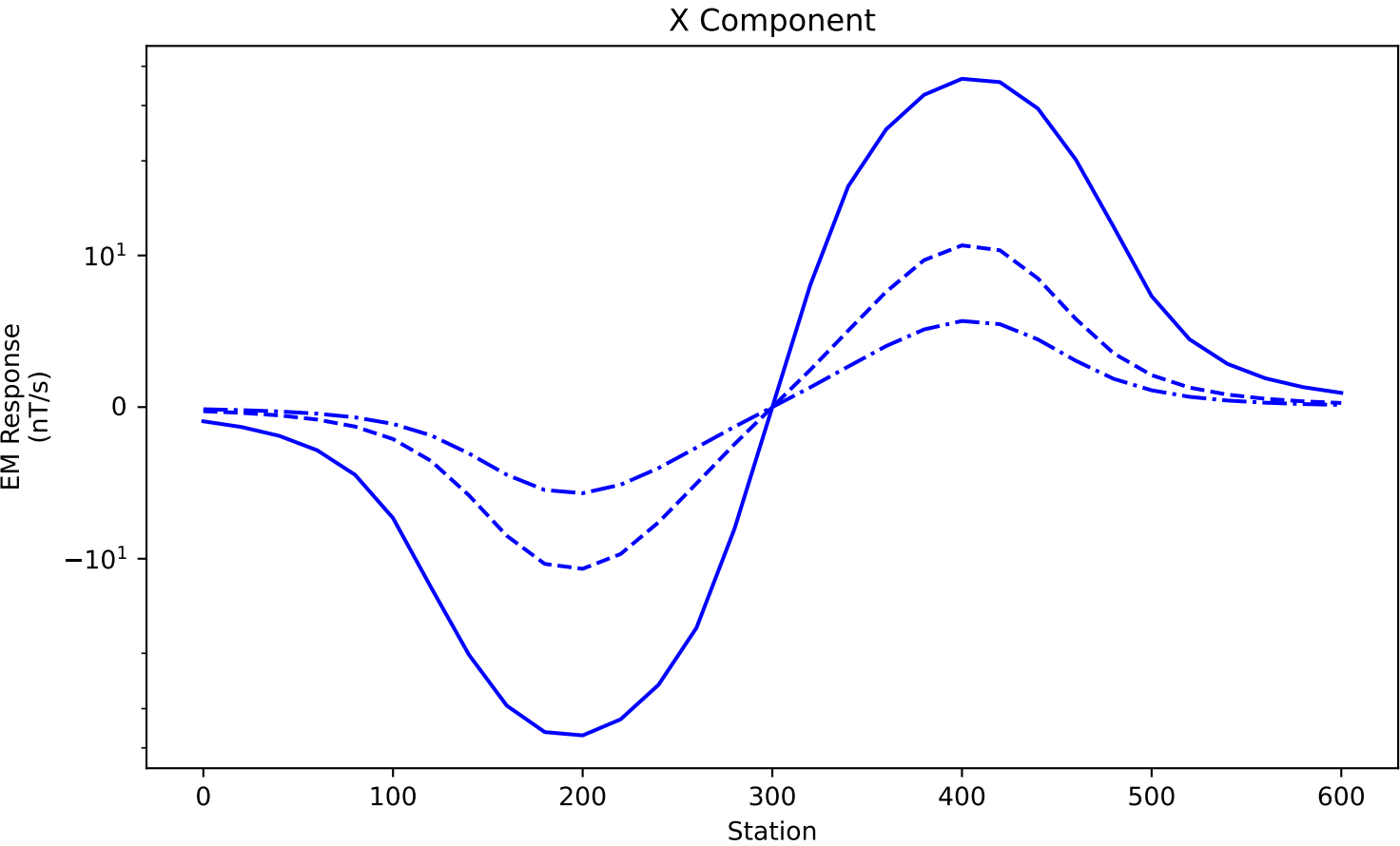
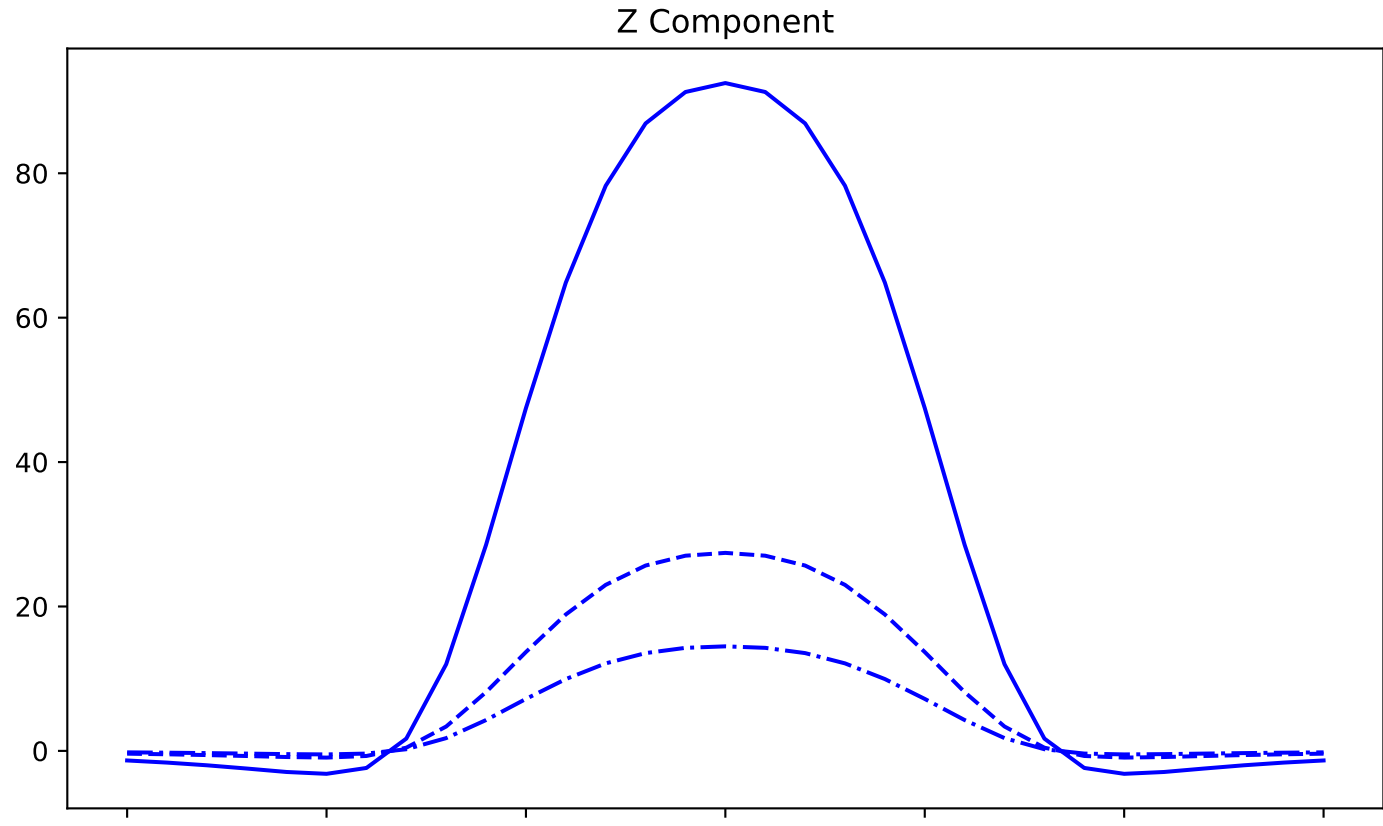
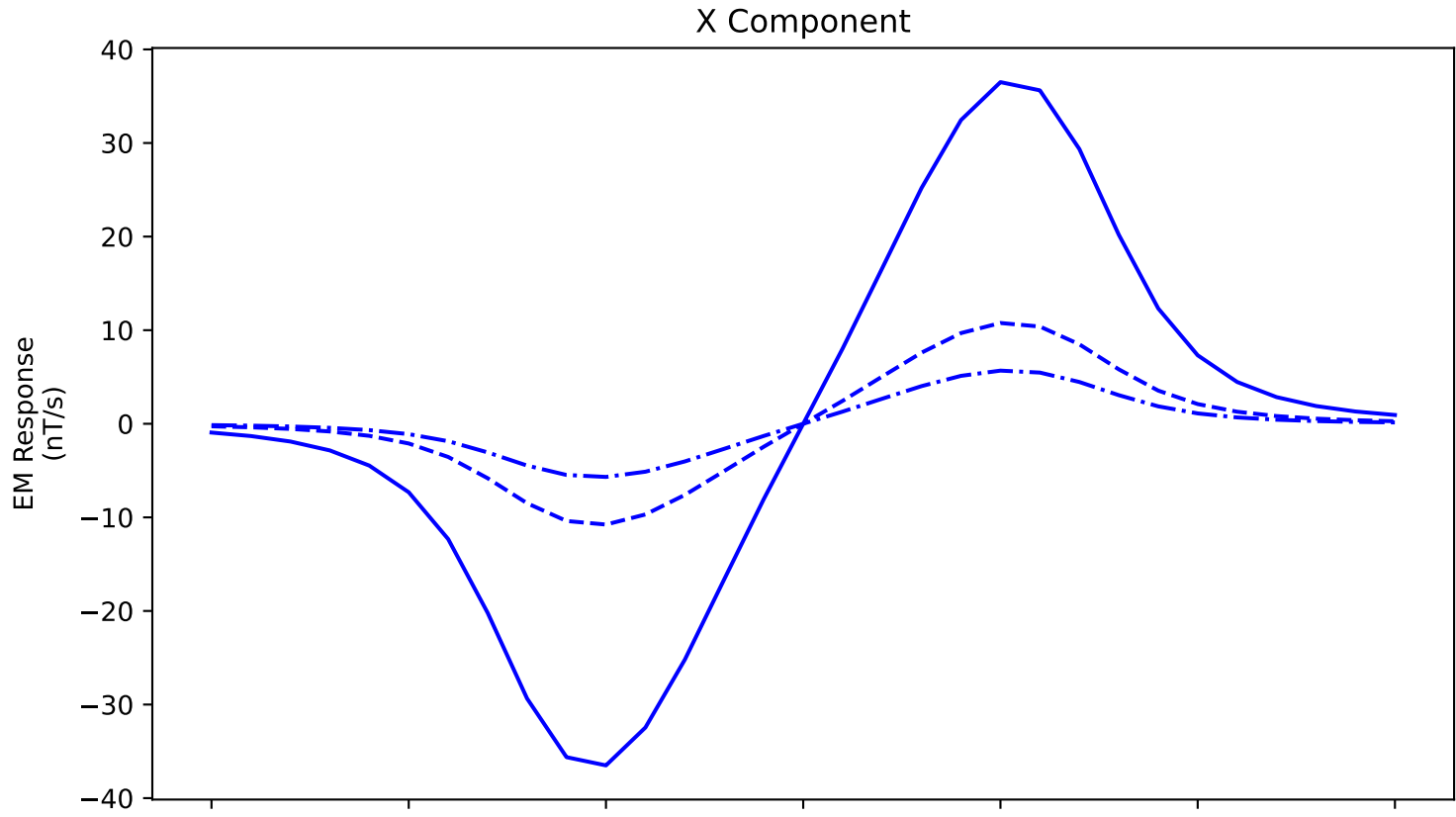
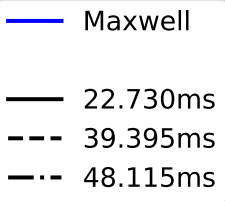
Two-Way Induction
300x100m, 1000S
LOOP=0
3.075ms to 7.205ms



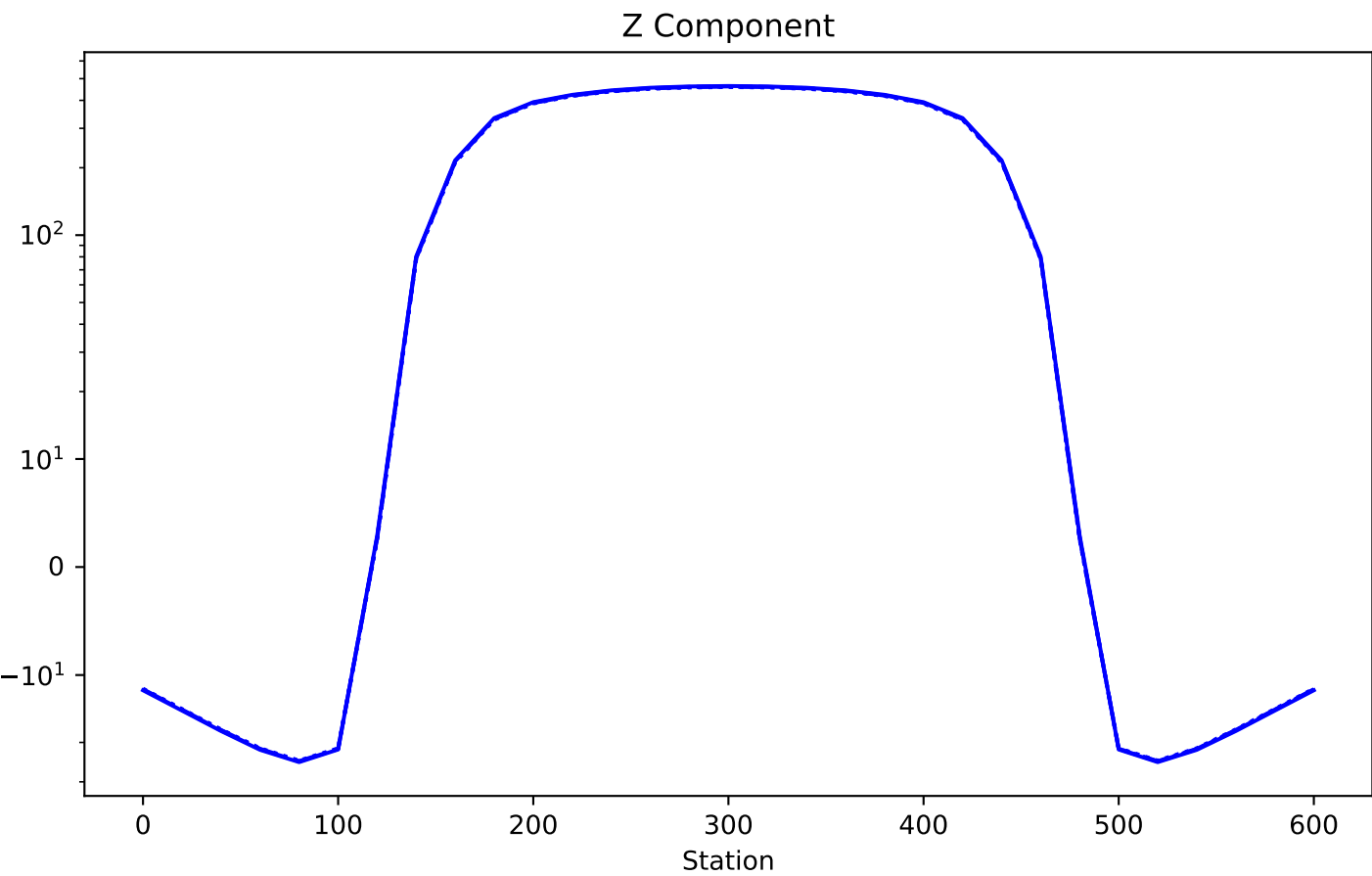
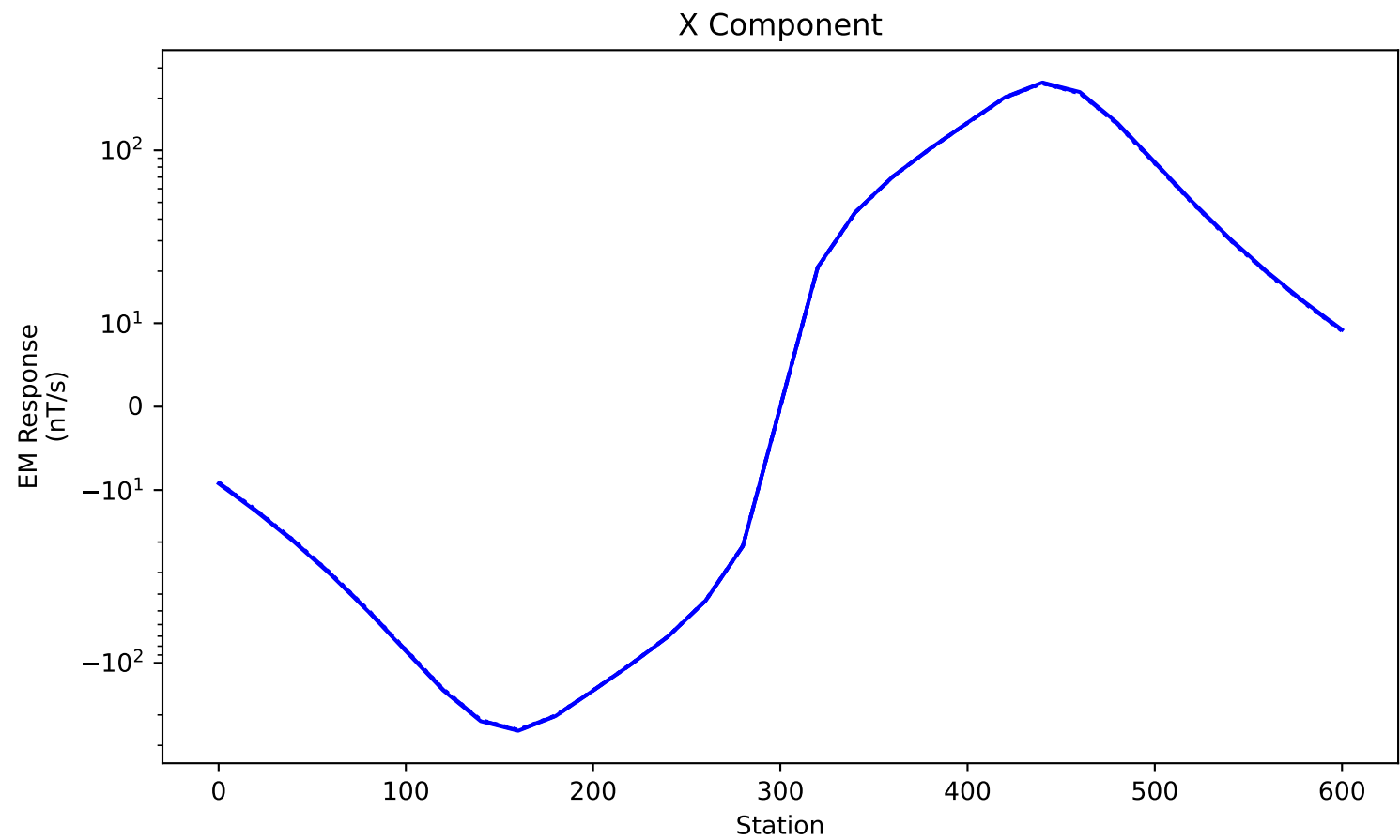
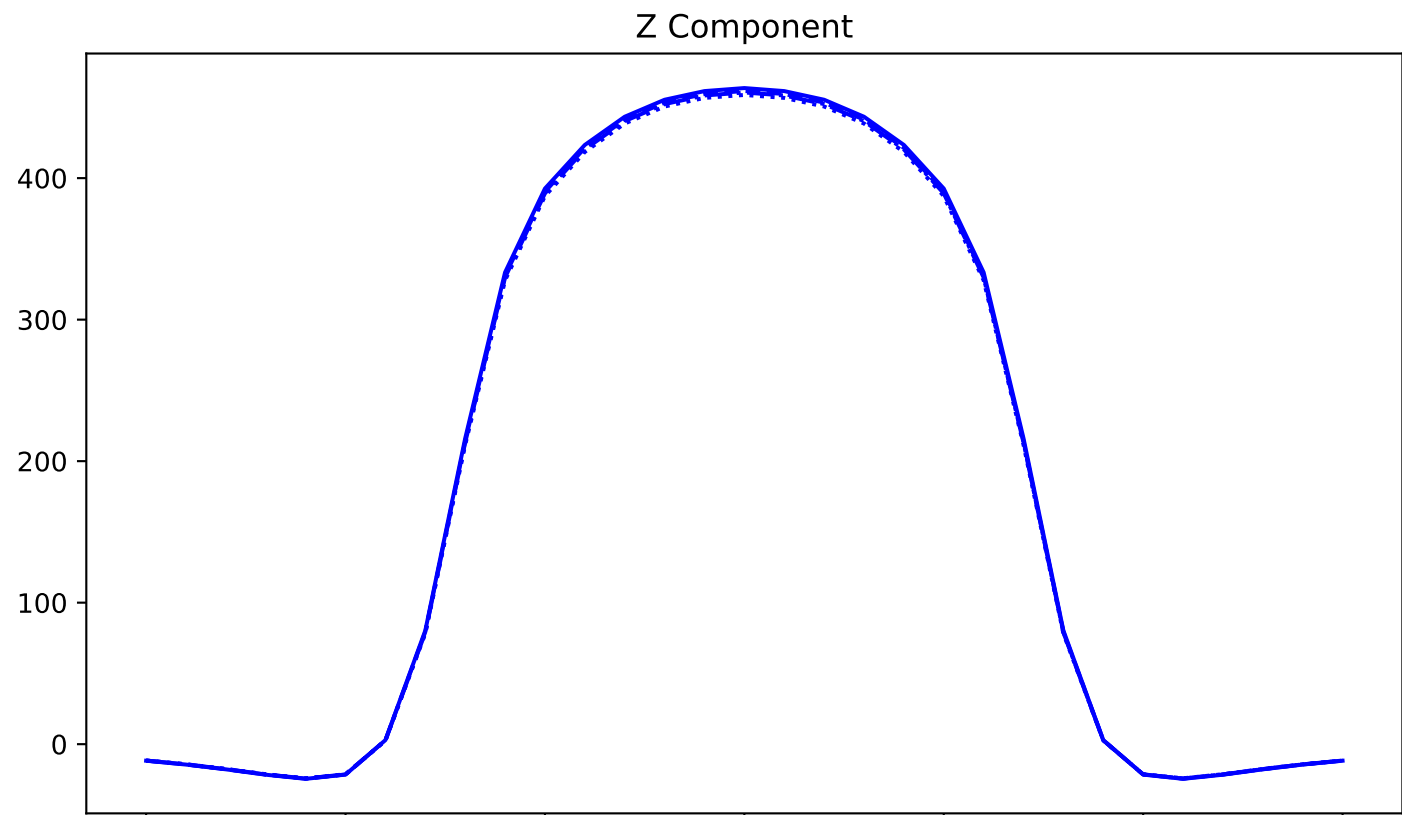
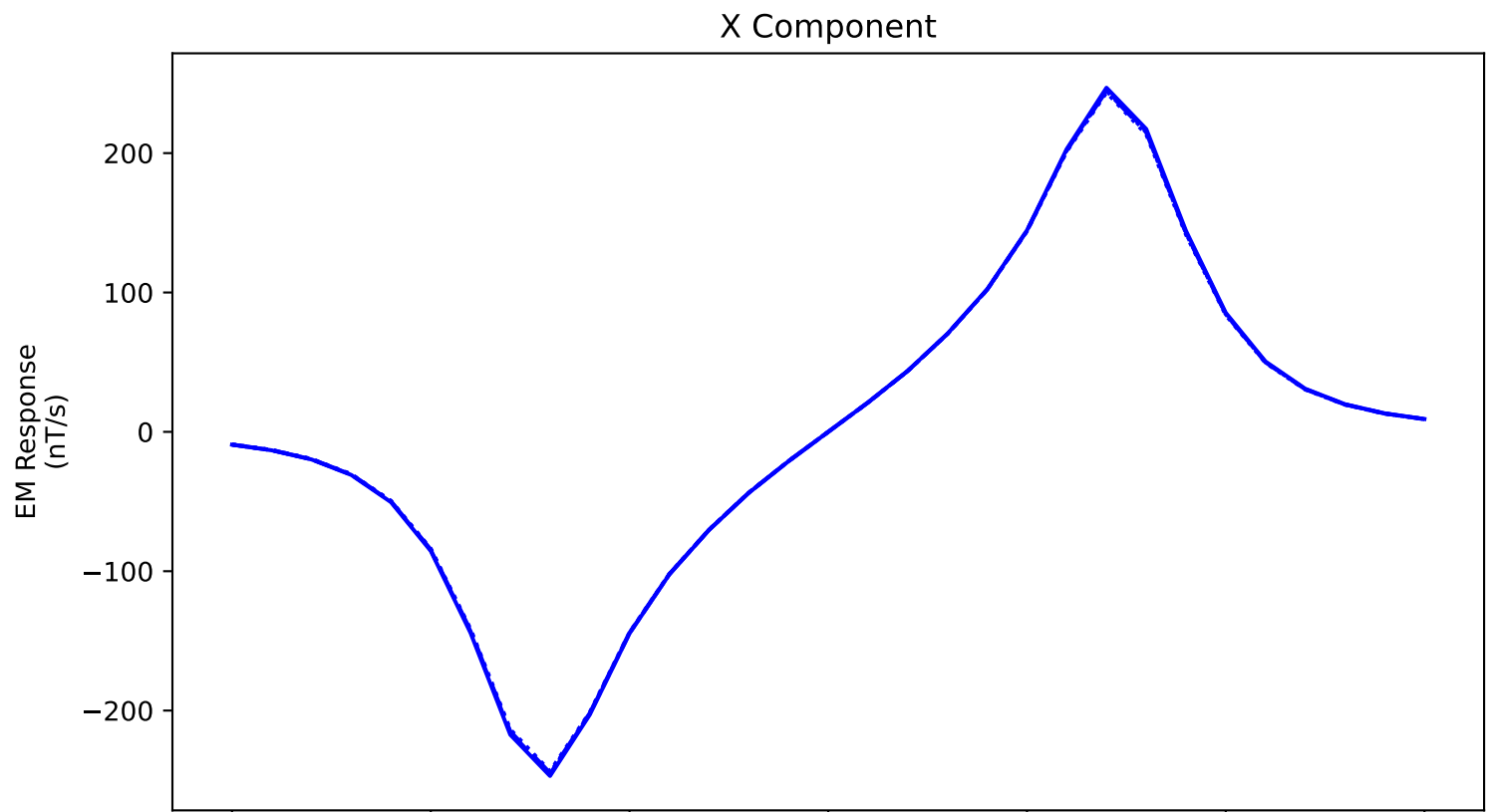
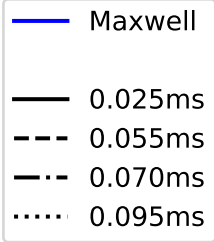
Two-Way Induction
300x100m, 1000S
LOOP=0
7.205ms to 22.73ms



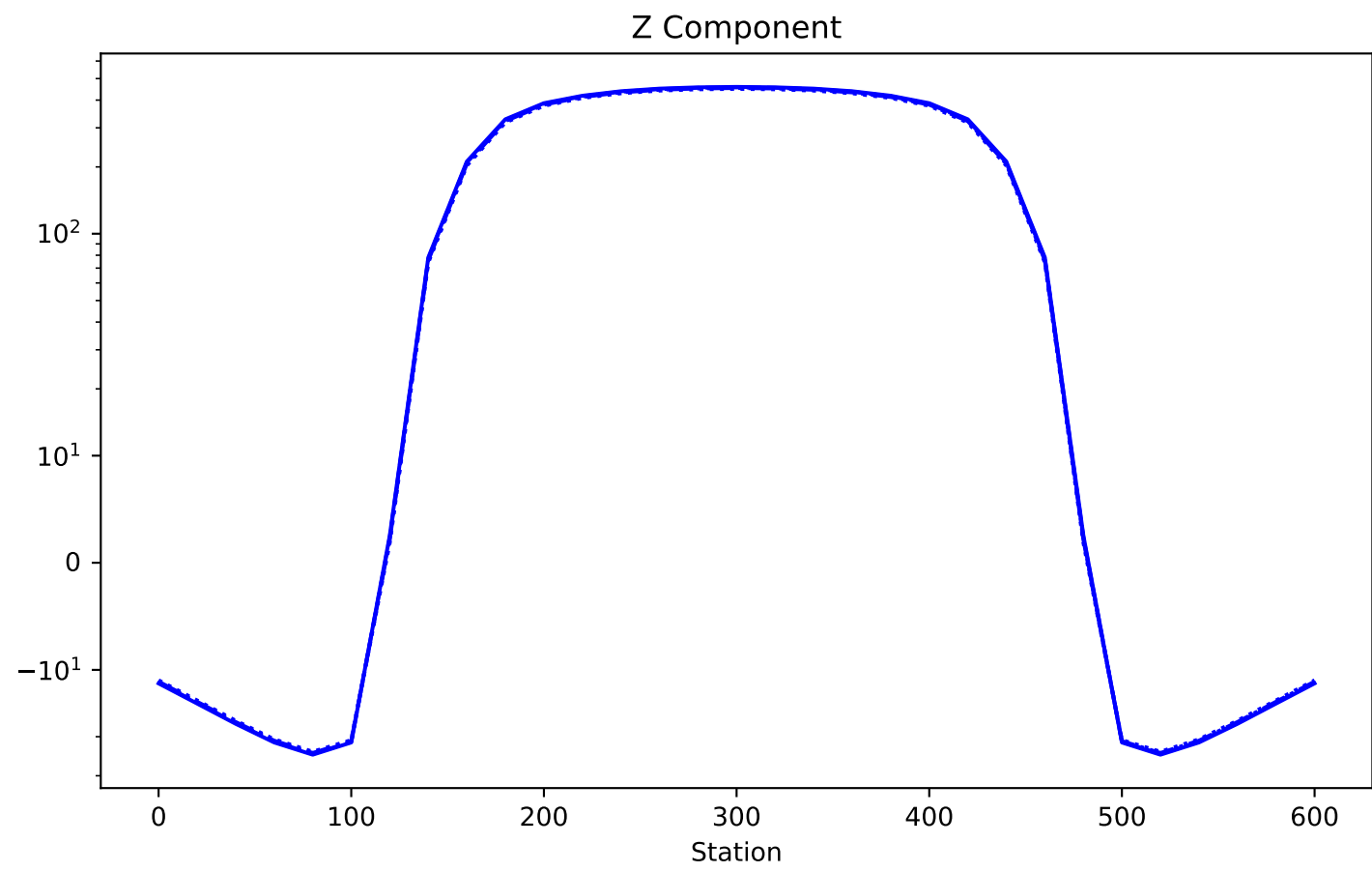
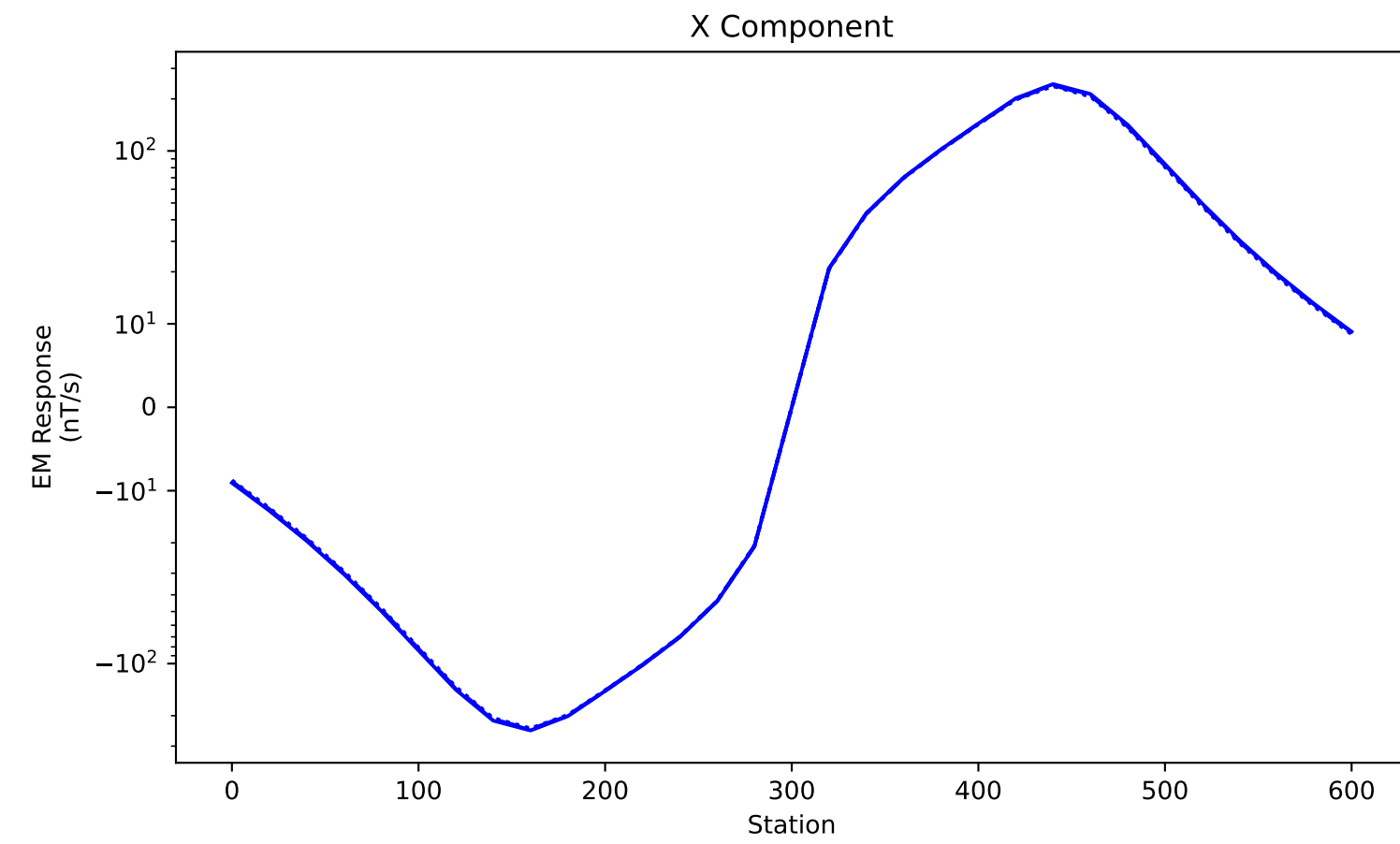
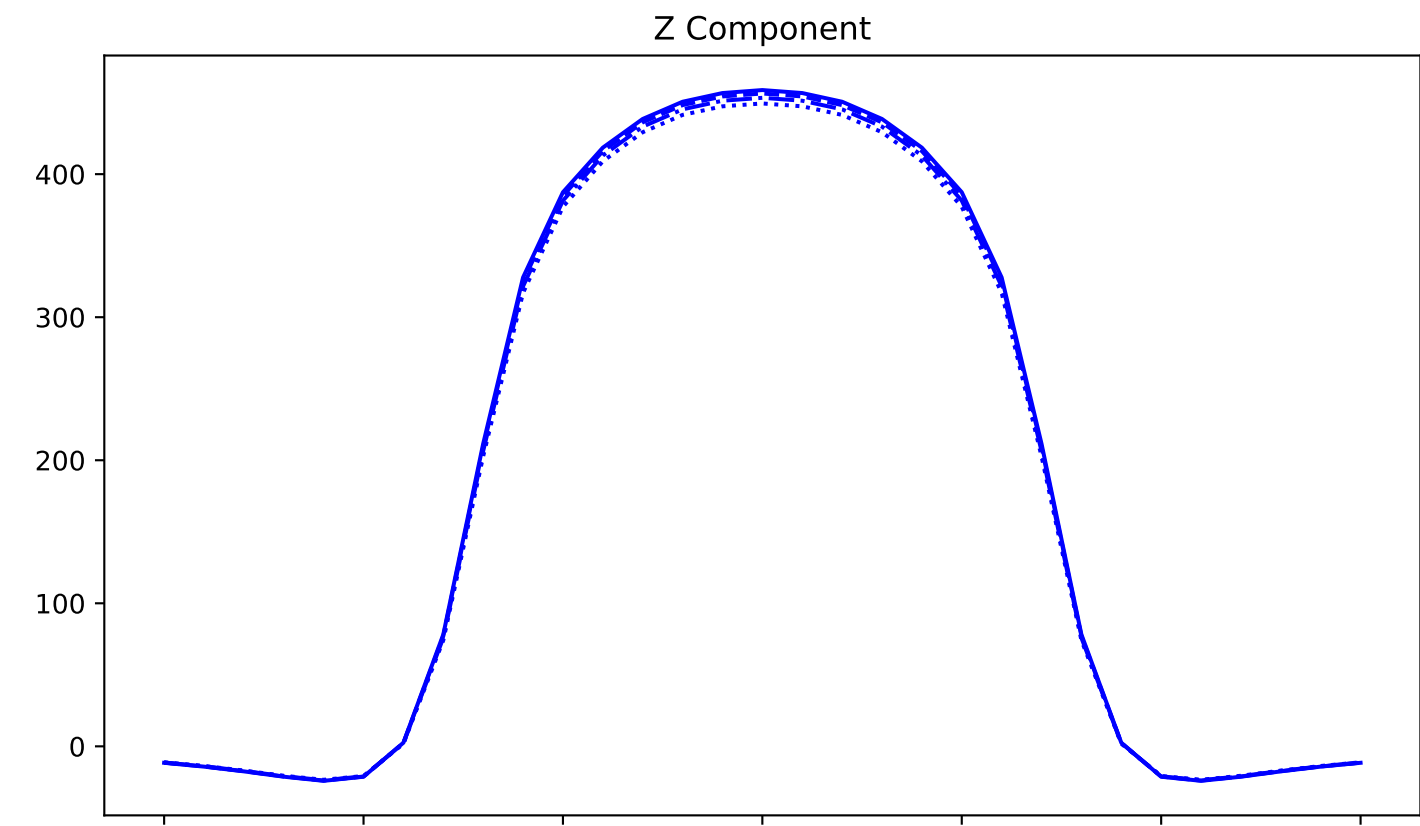
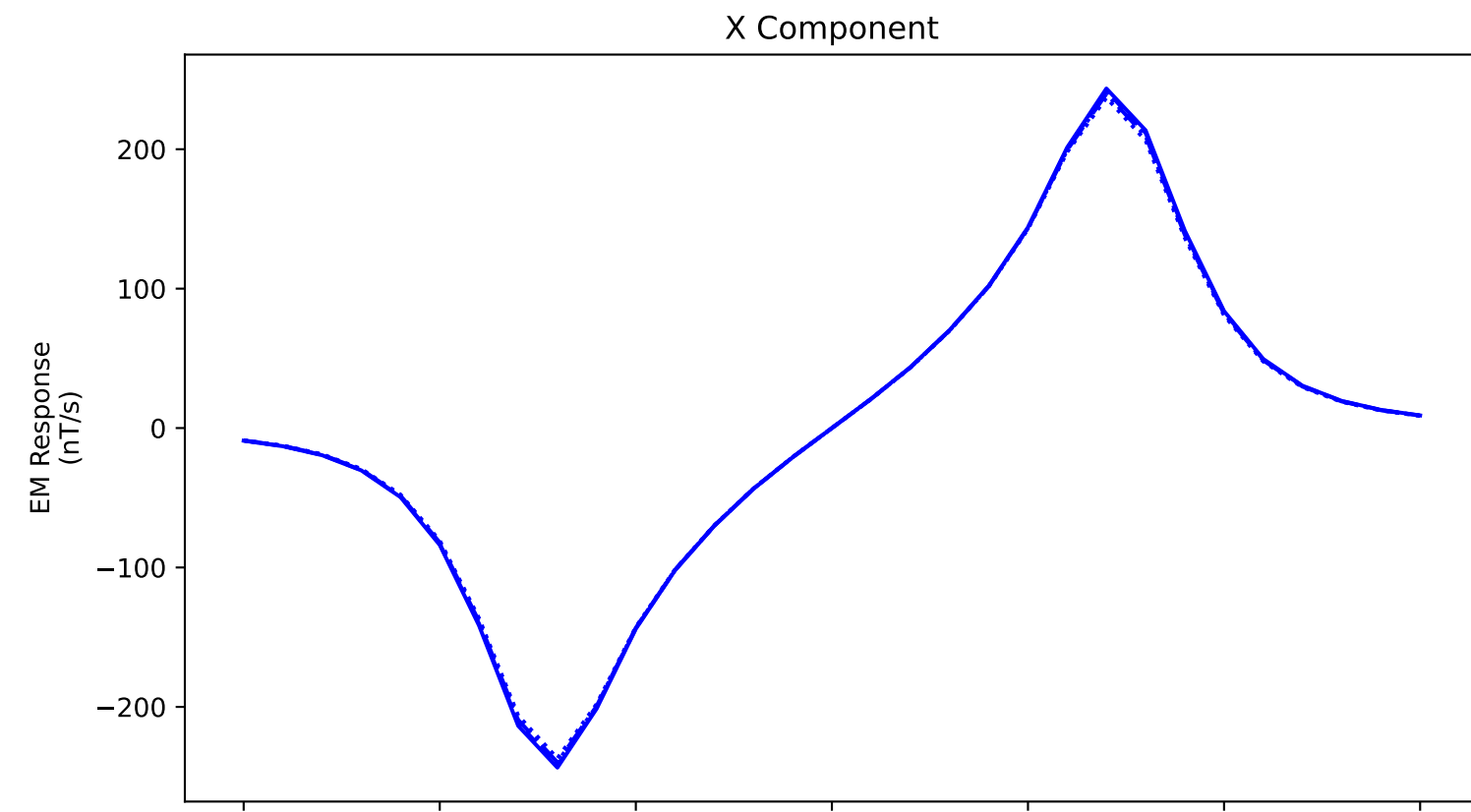
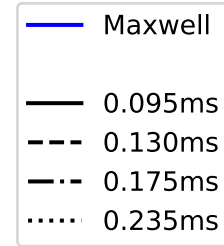
Two-Way Induction
300x100m, 1000S
LOOP=0
22.73ms to 48.115ms



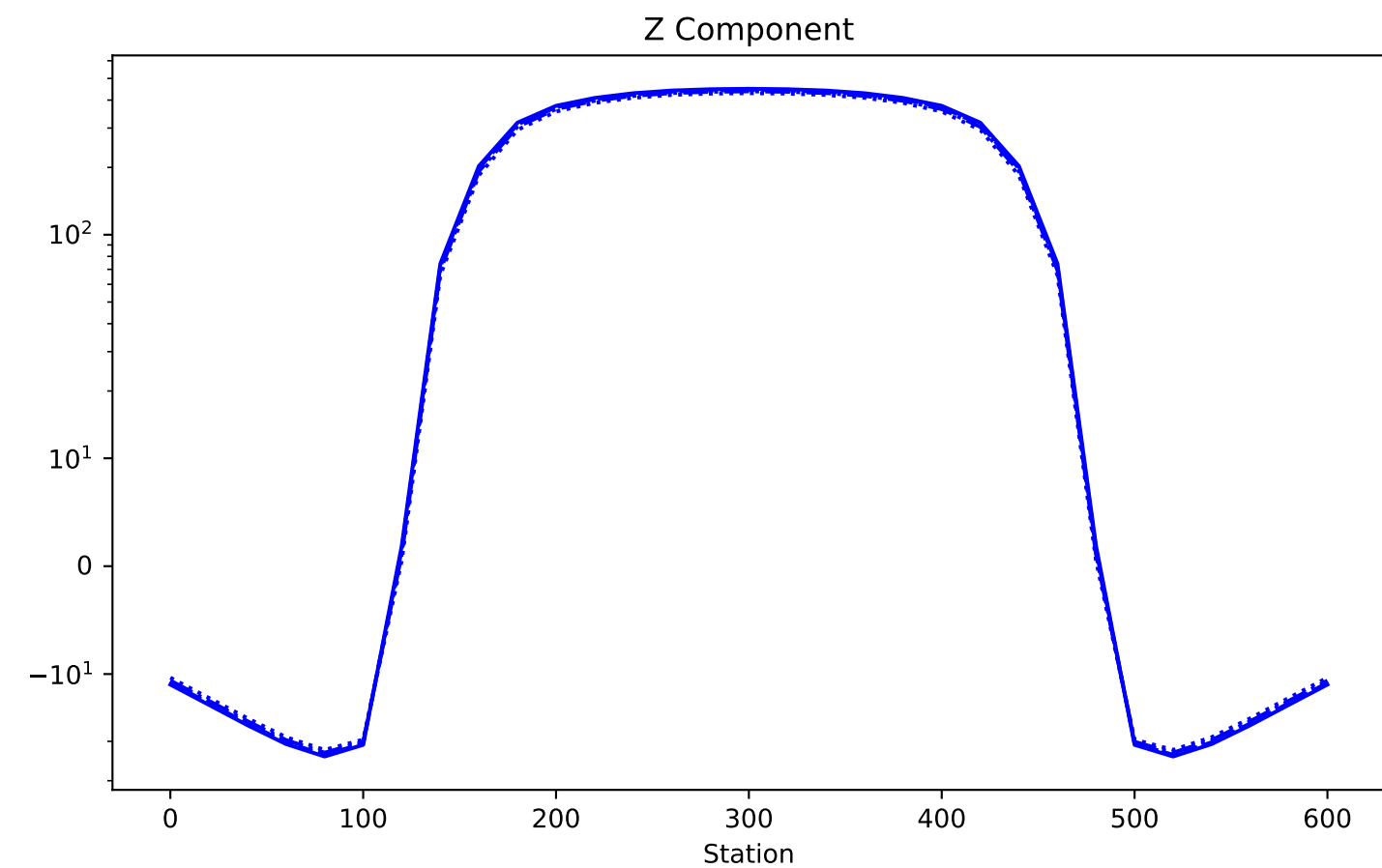
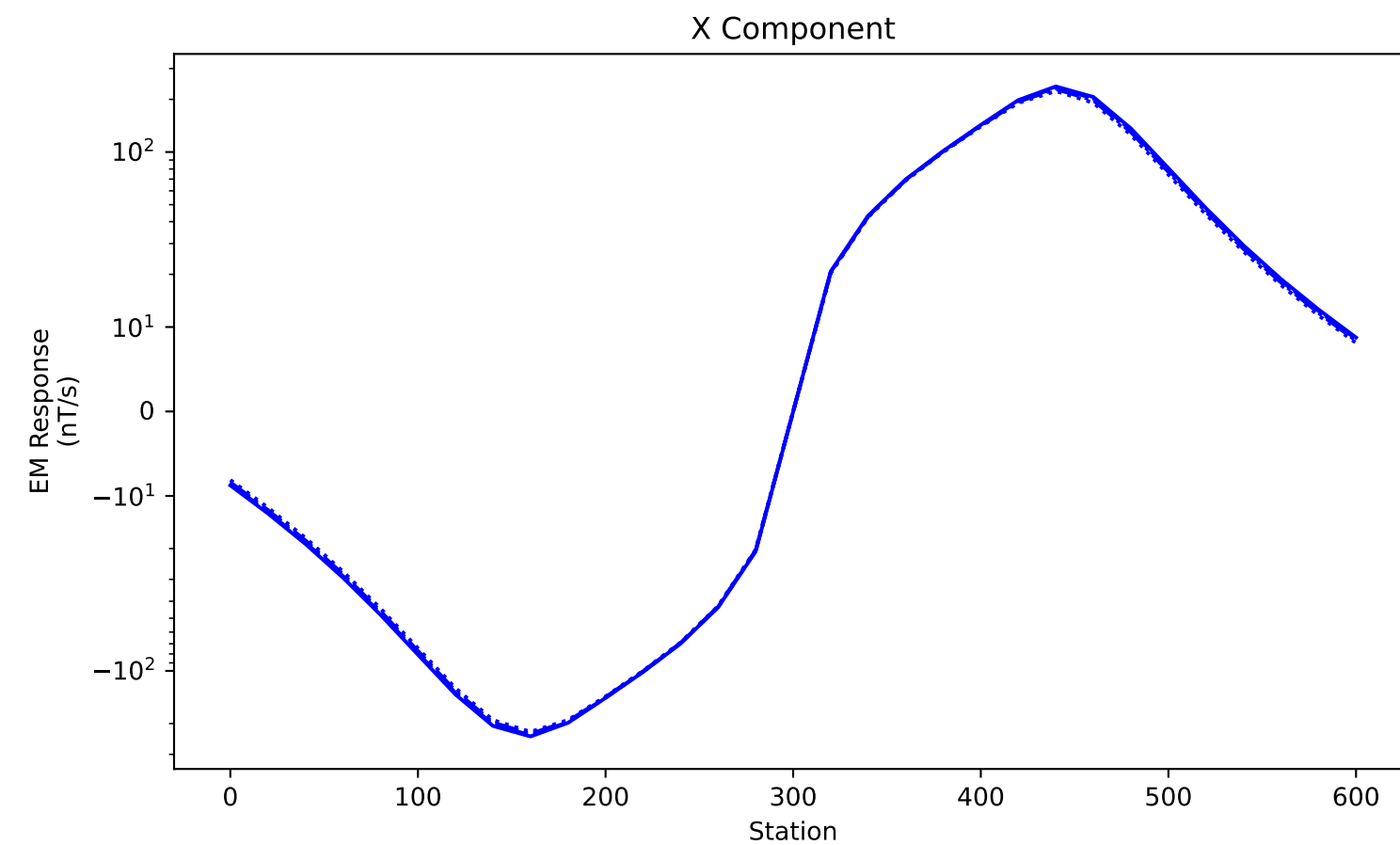
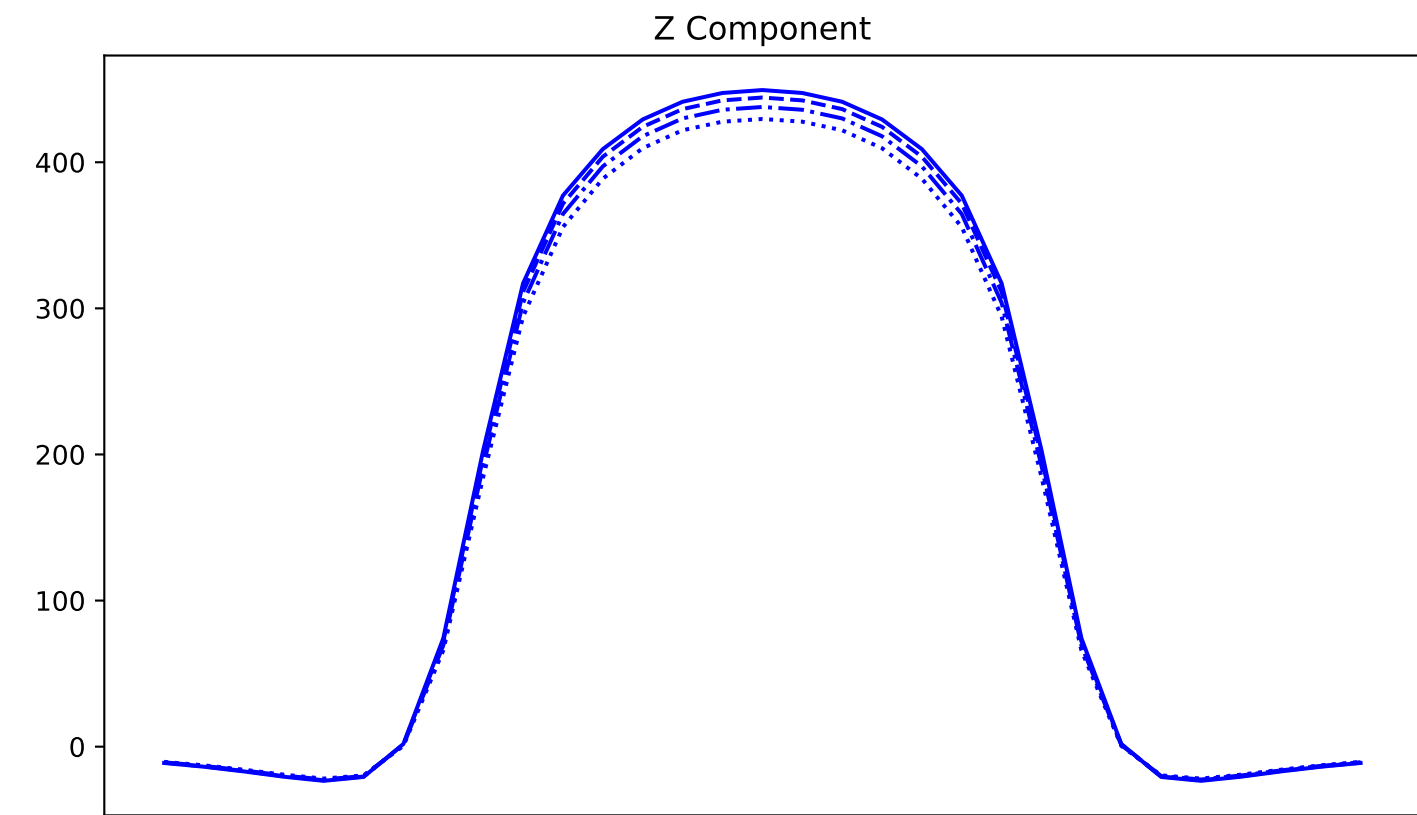
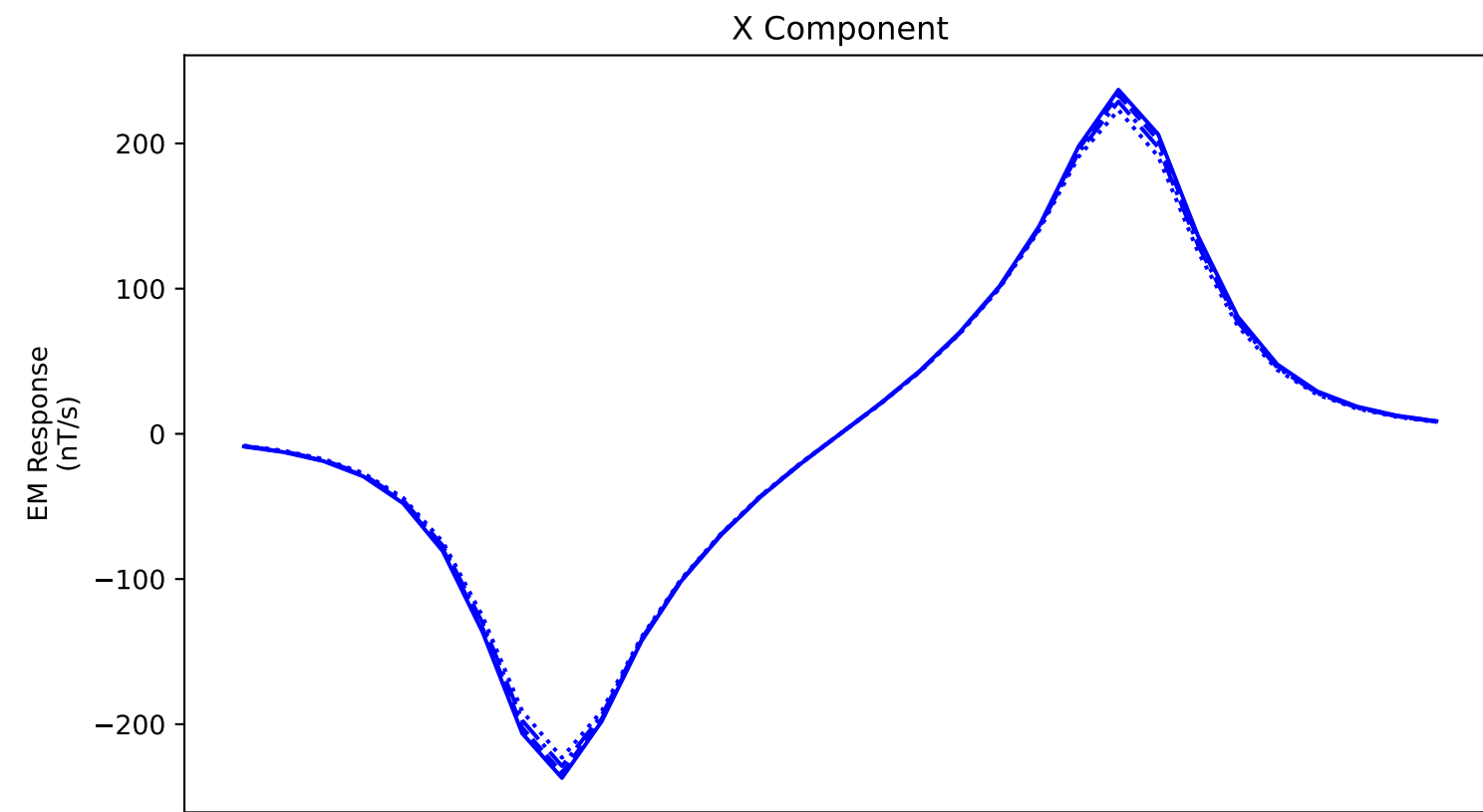
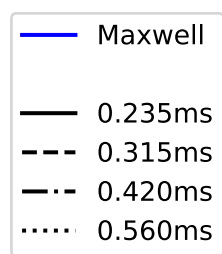
Two-Way Induction
300x100m, 1000S
LOOP=-50
0.0255ms to 0.095ms



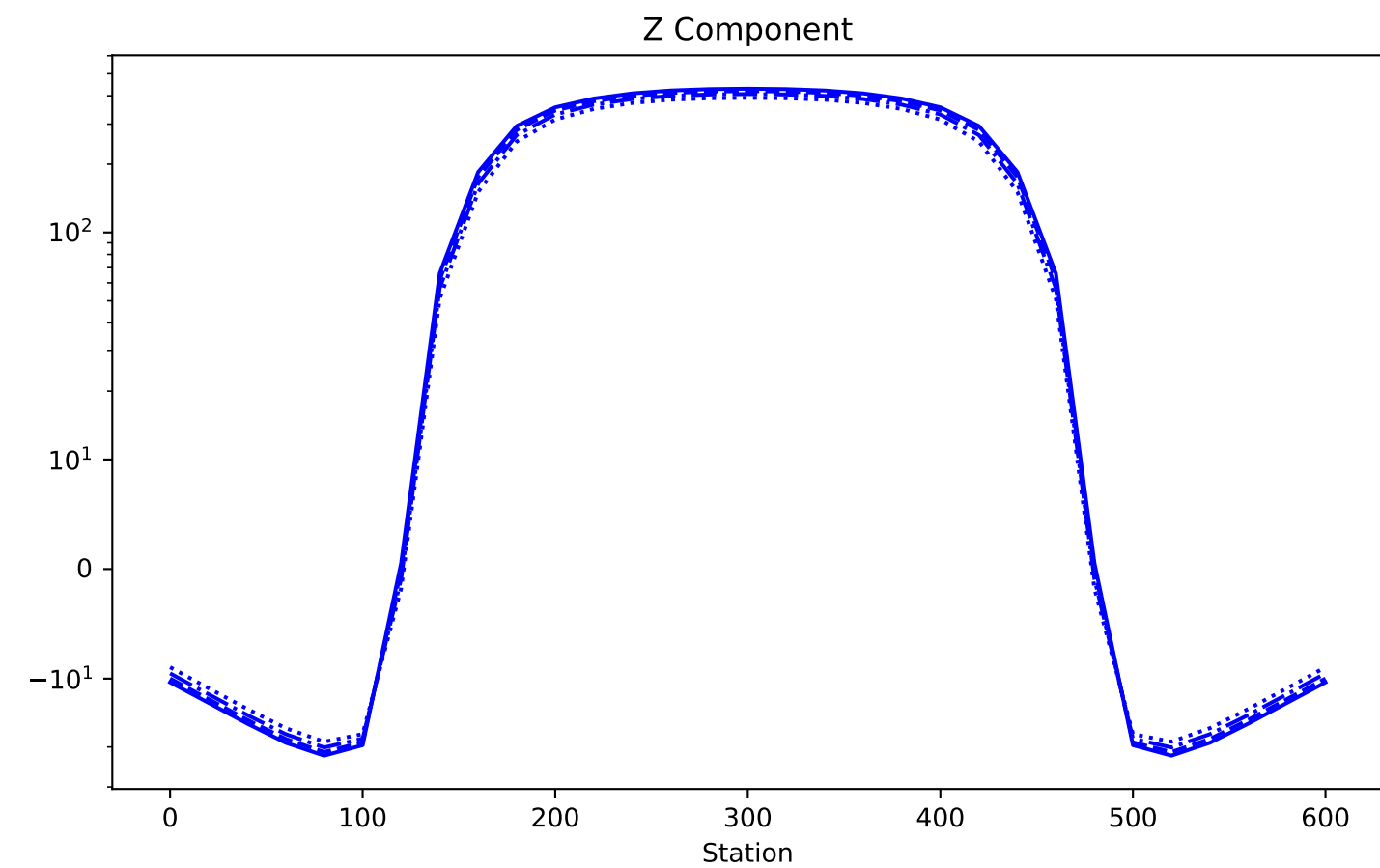
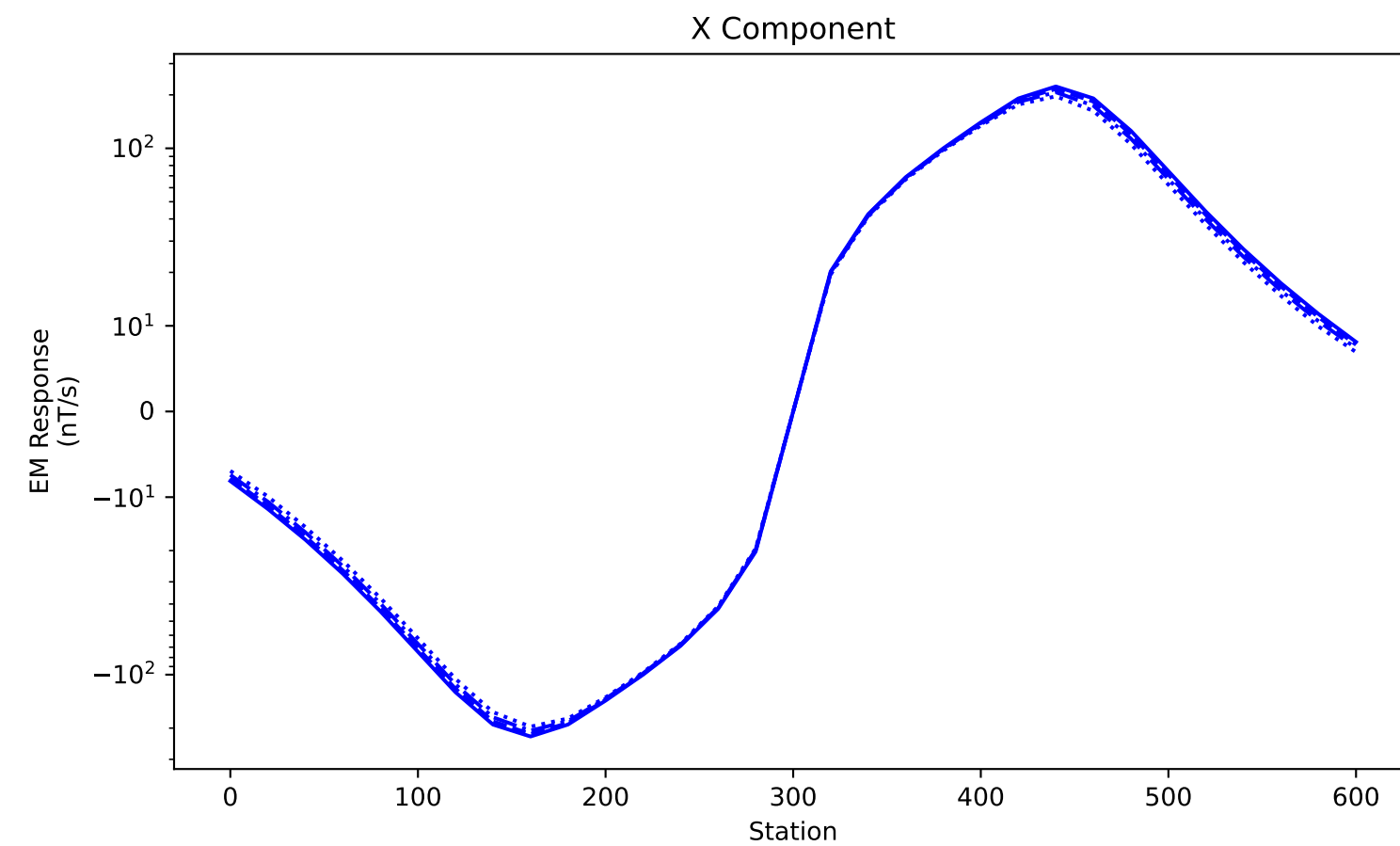
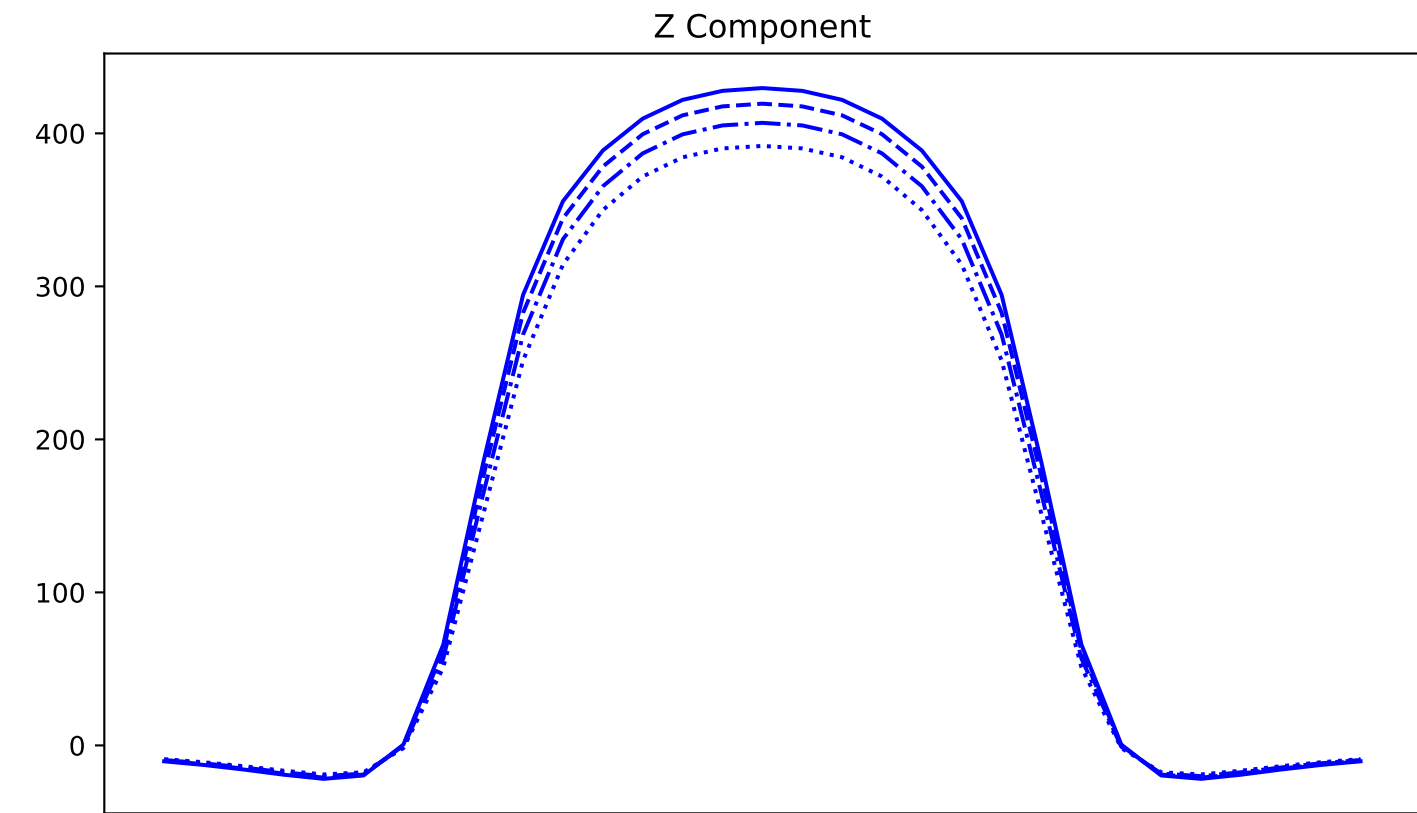
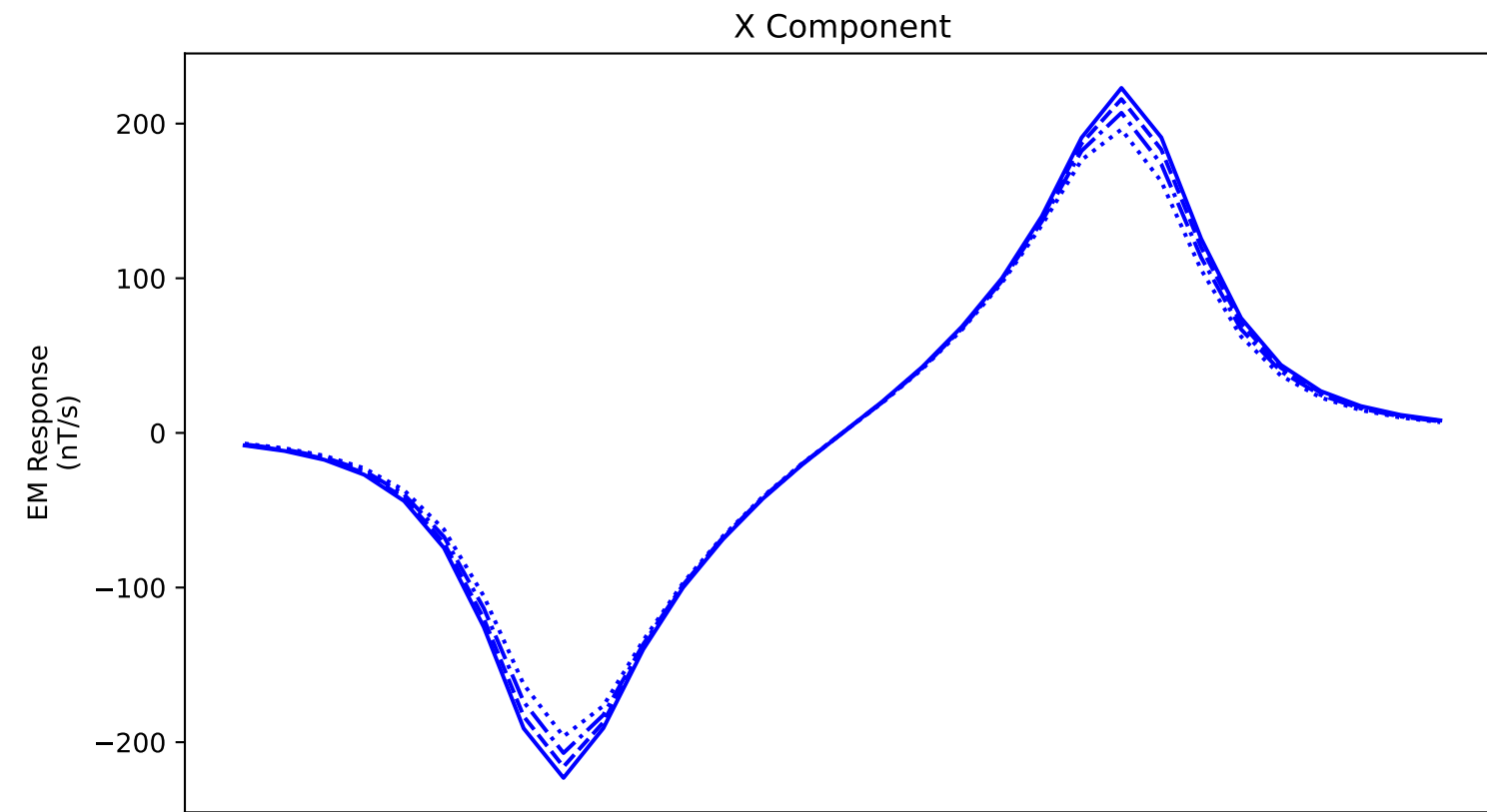
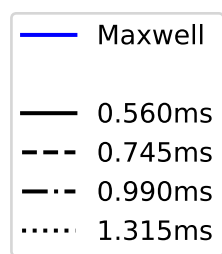
Two-Way Induction
300x100m, 1000S
LOOP=-50
0.095ms to 0.235ms



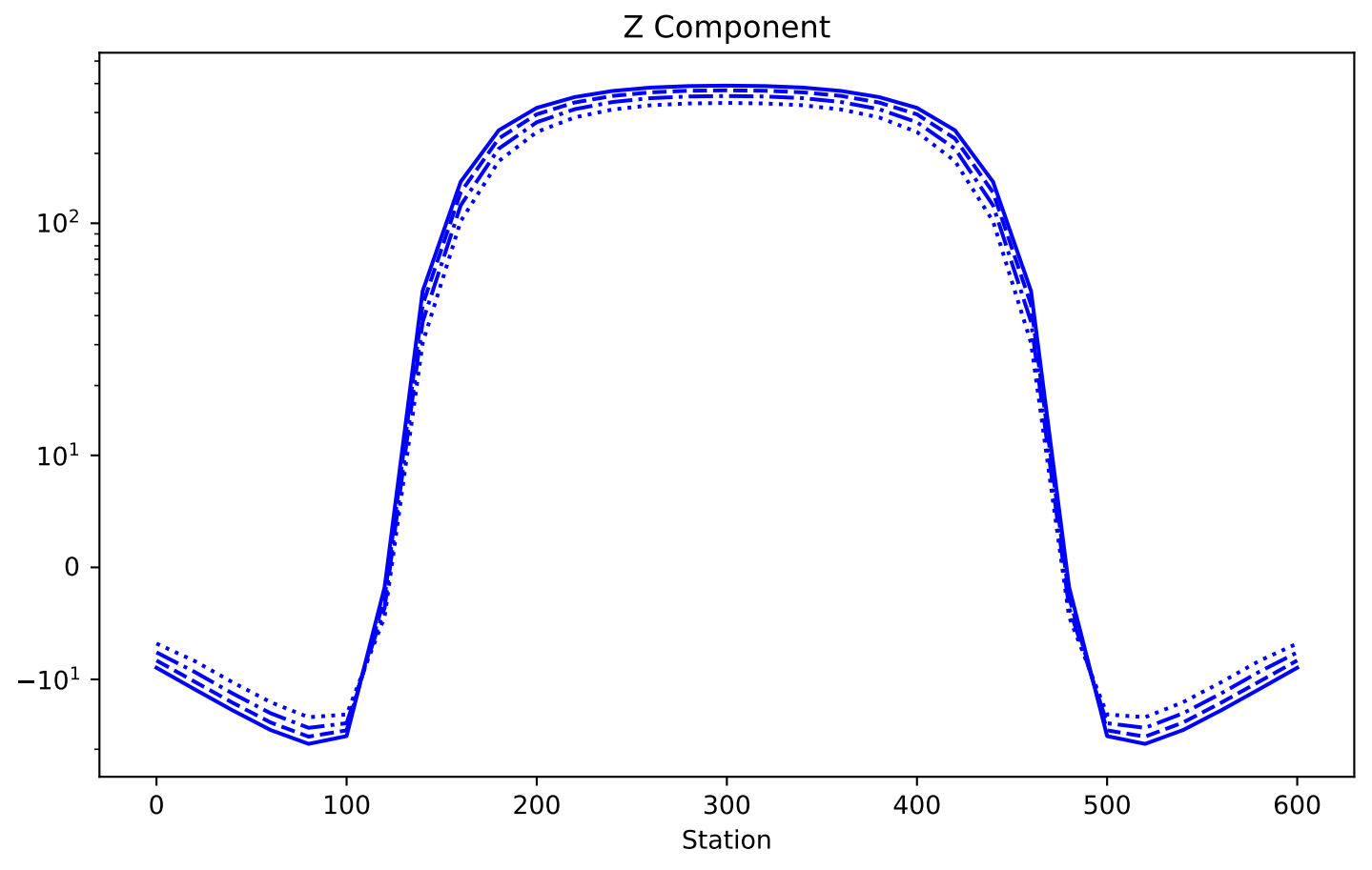
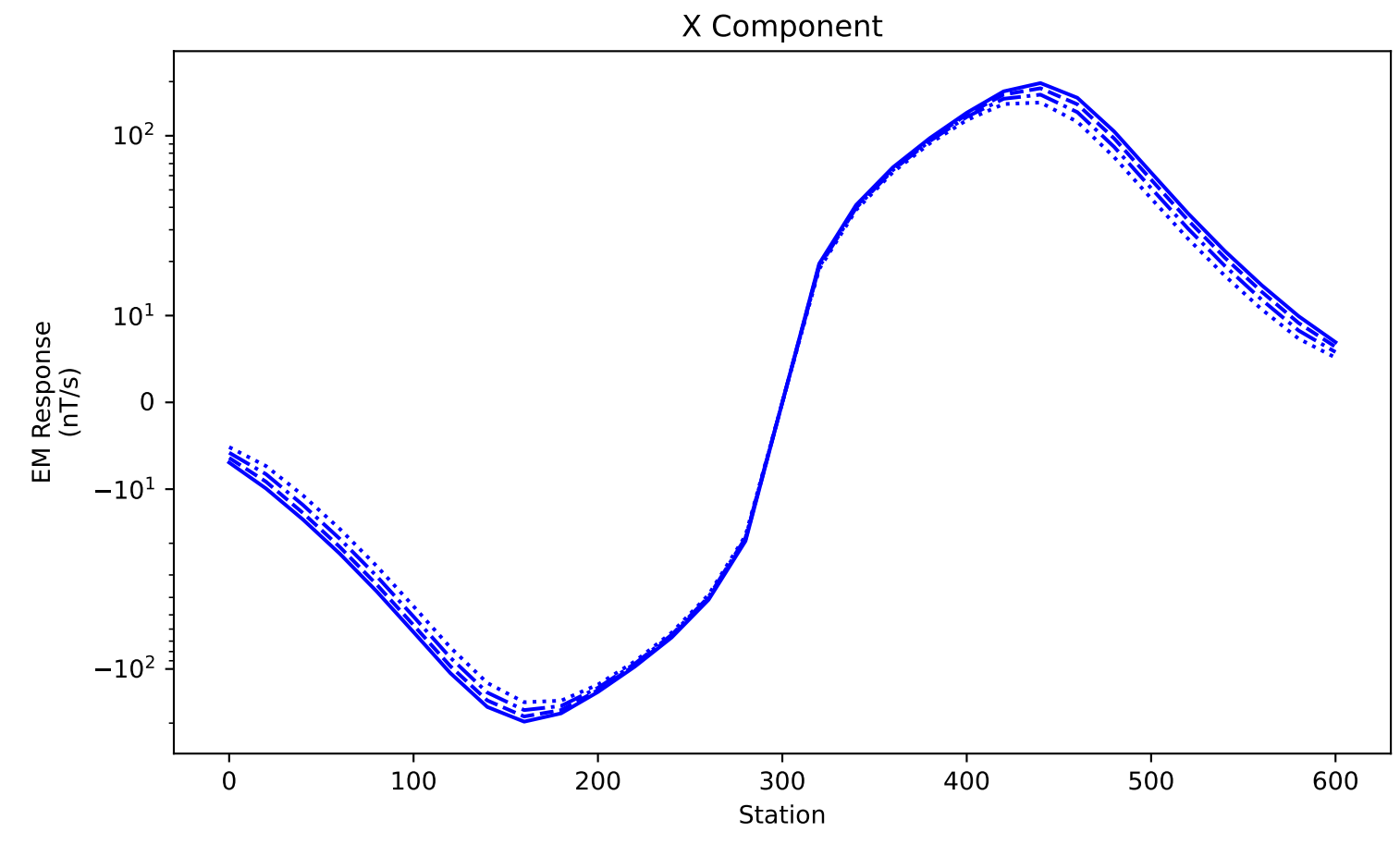
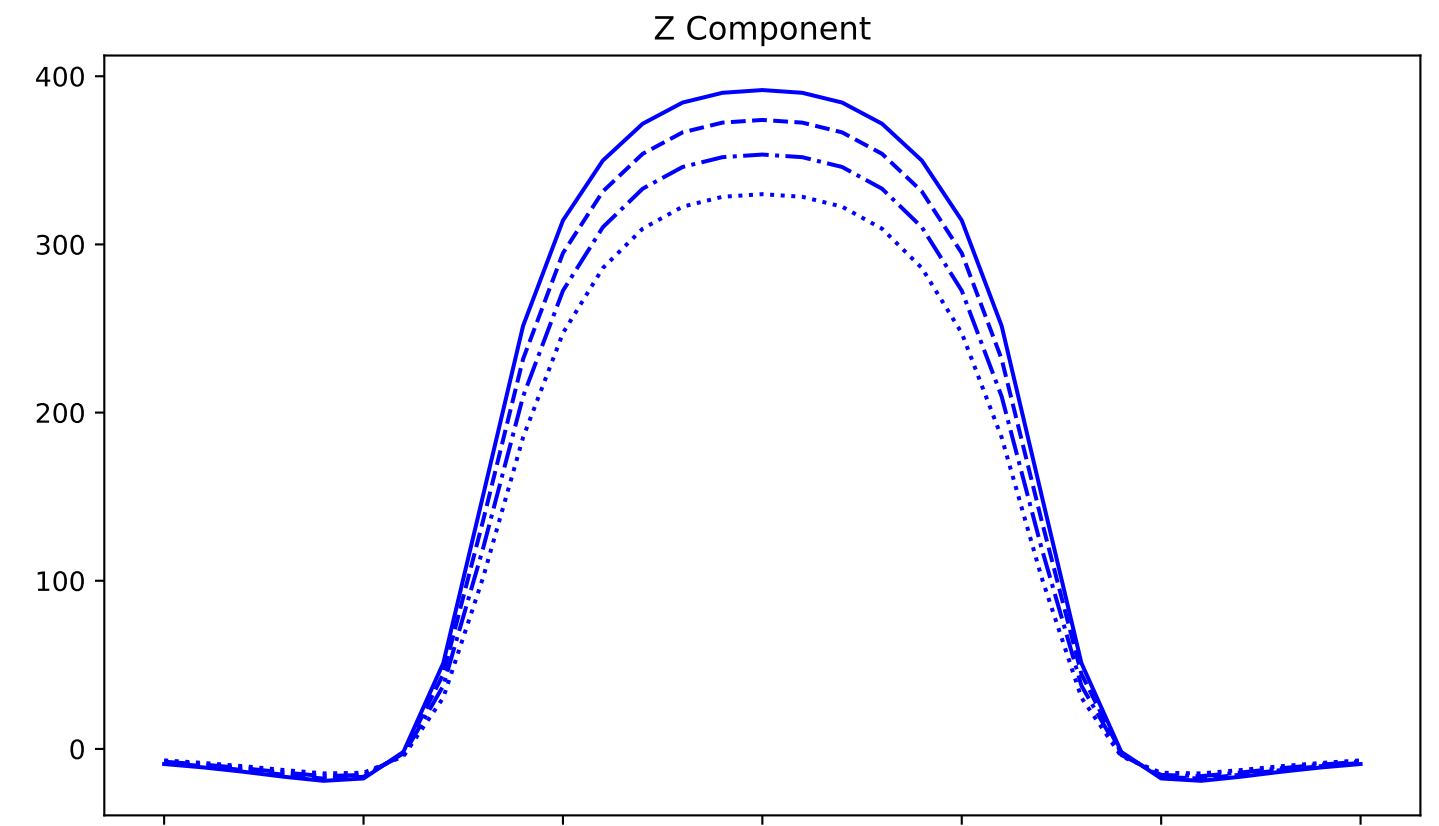
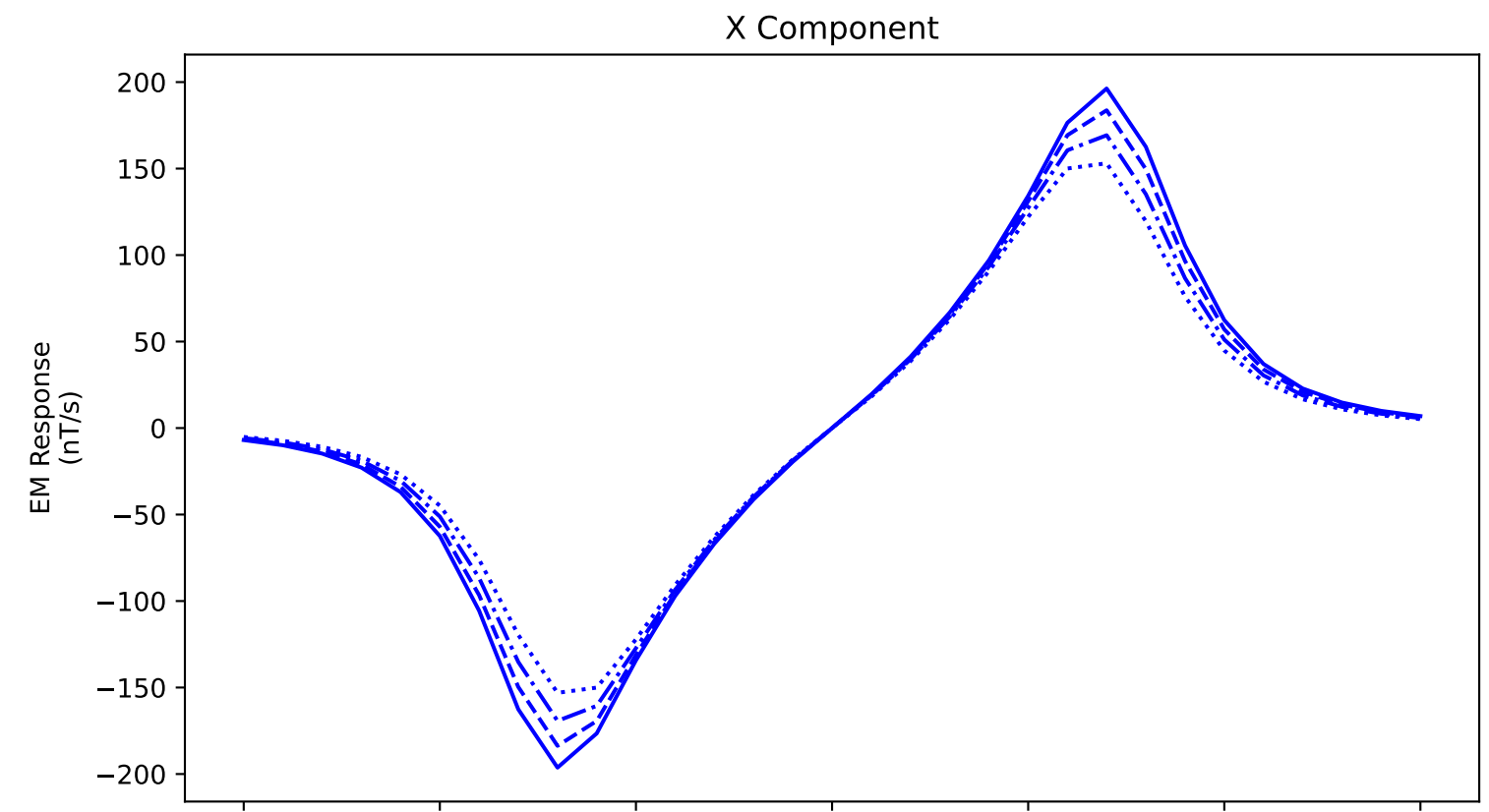
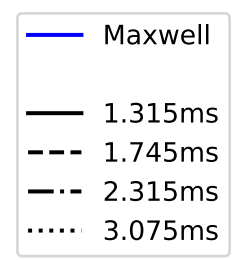
Two-Way Induction
300x100m, 1000S
LOOP=-50
0.235ms to 0.56ms



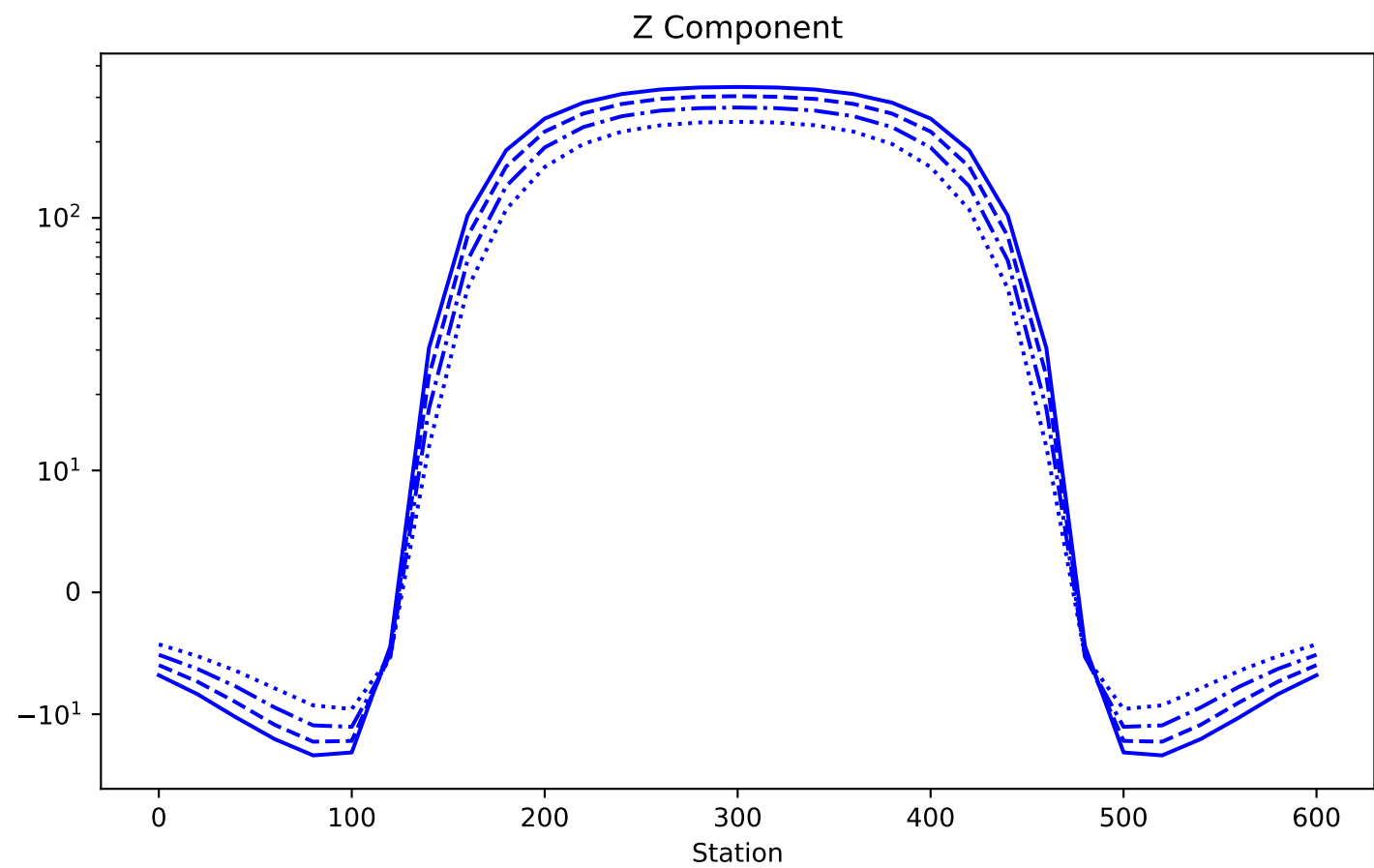
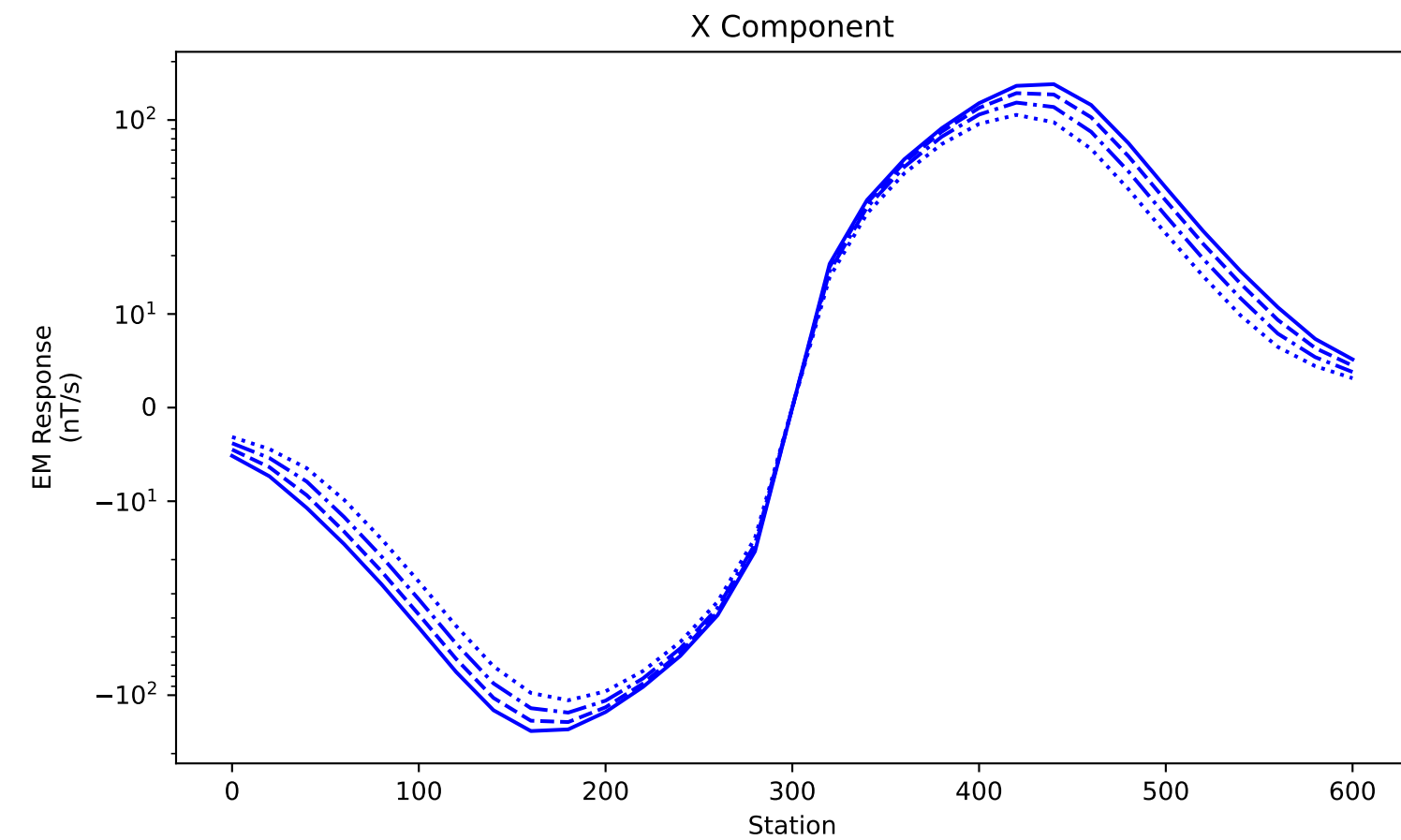
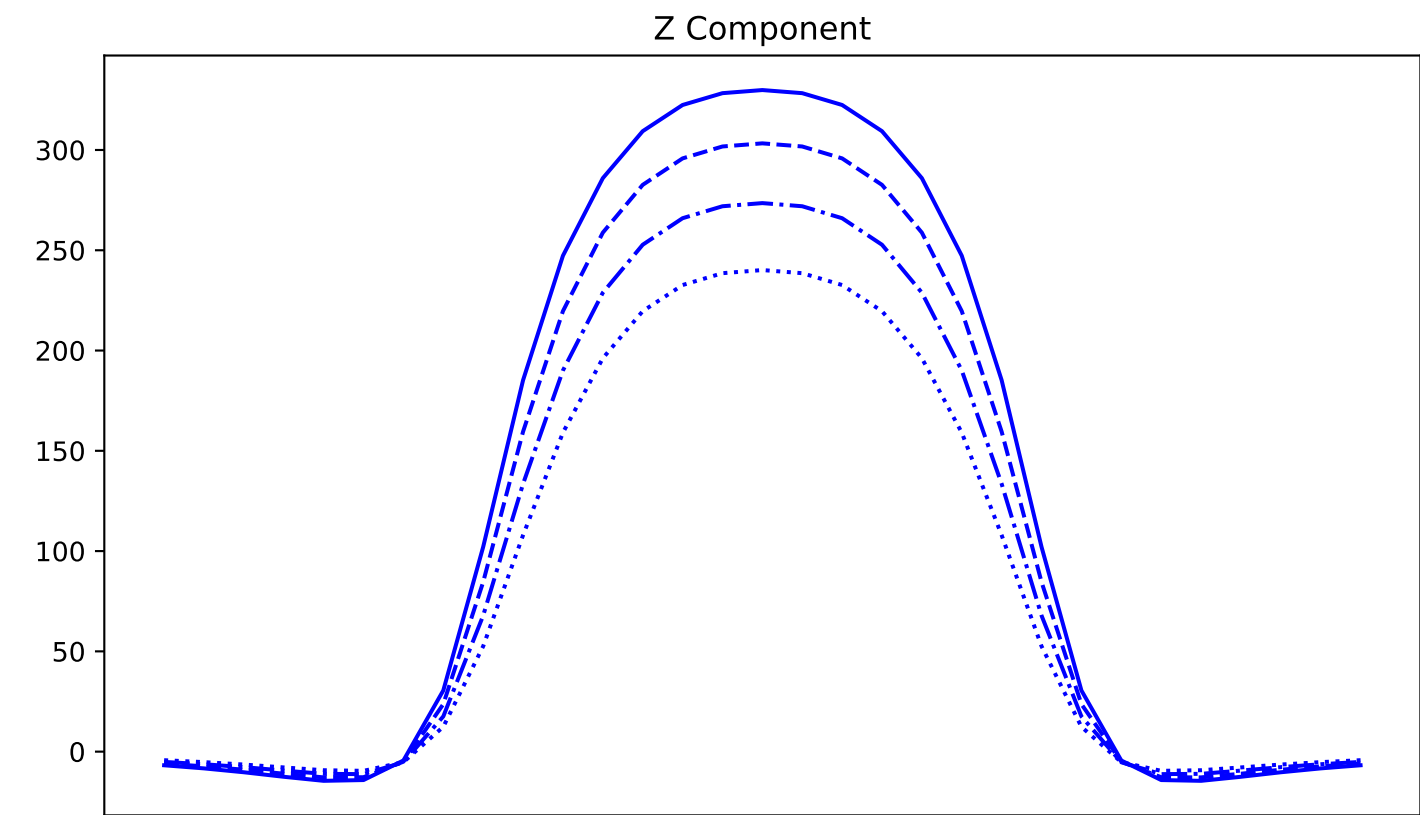
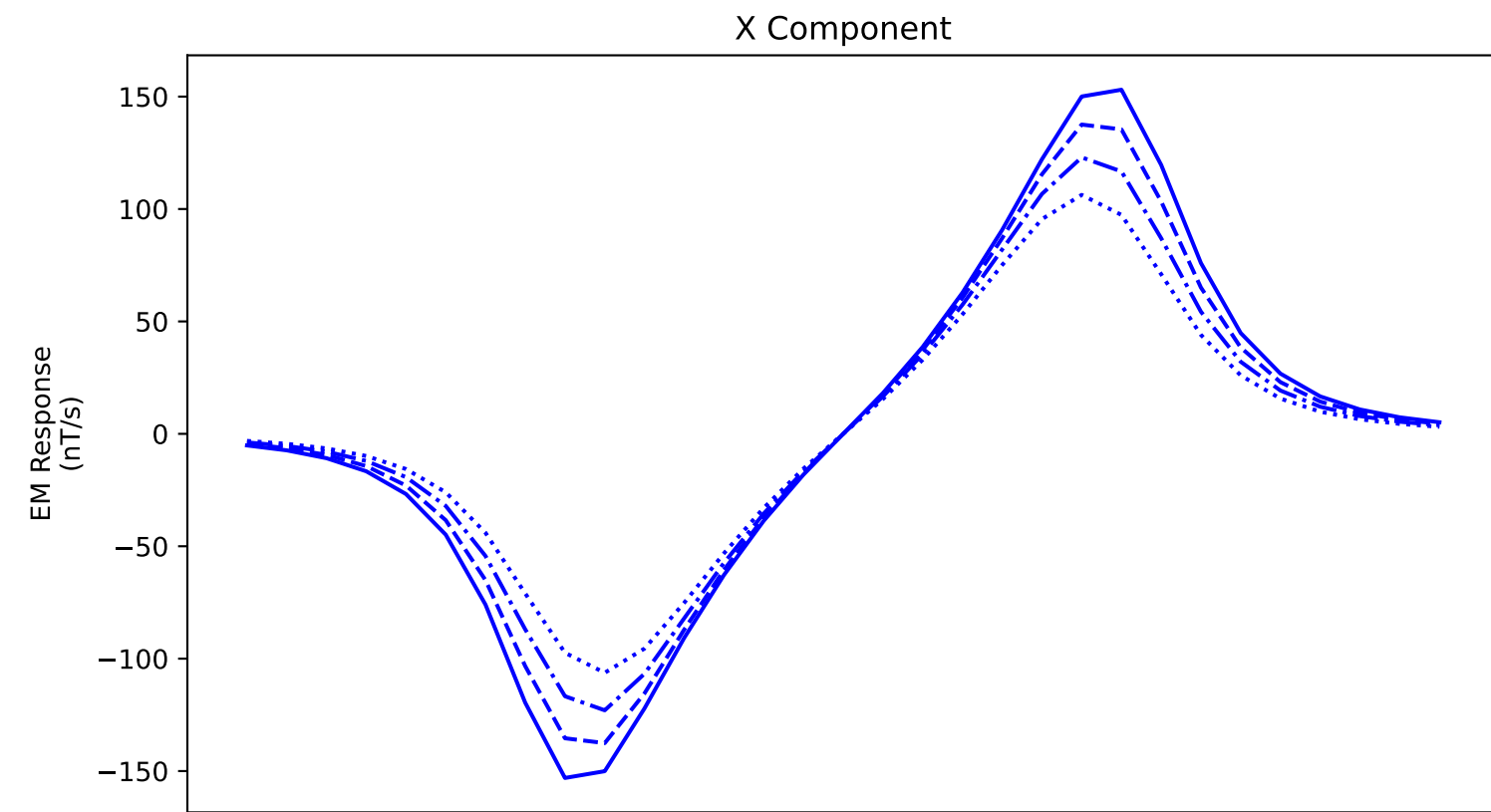
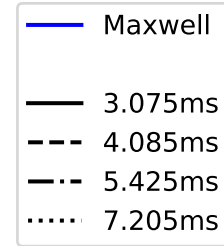
Two-Way Induction
300x100m, 1000S
LOOP=-50
0.56ms to 1.315ms



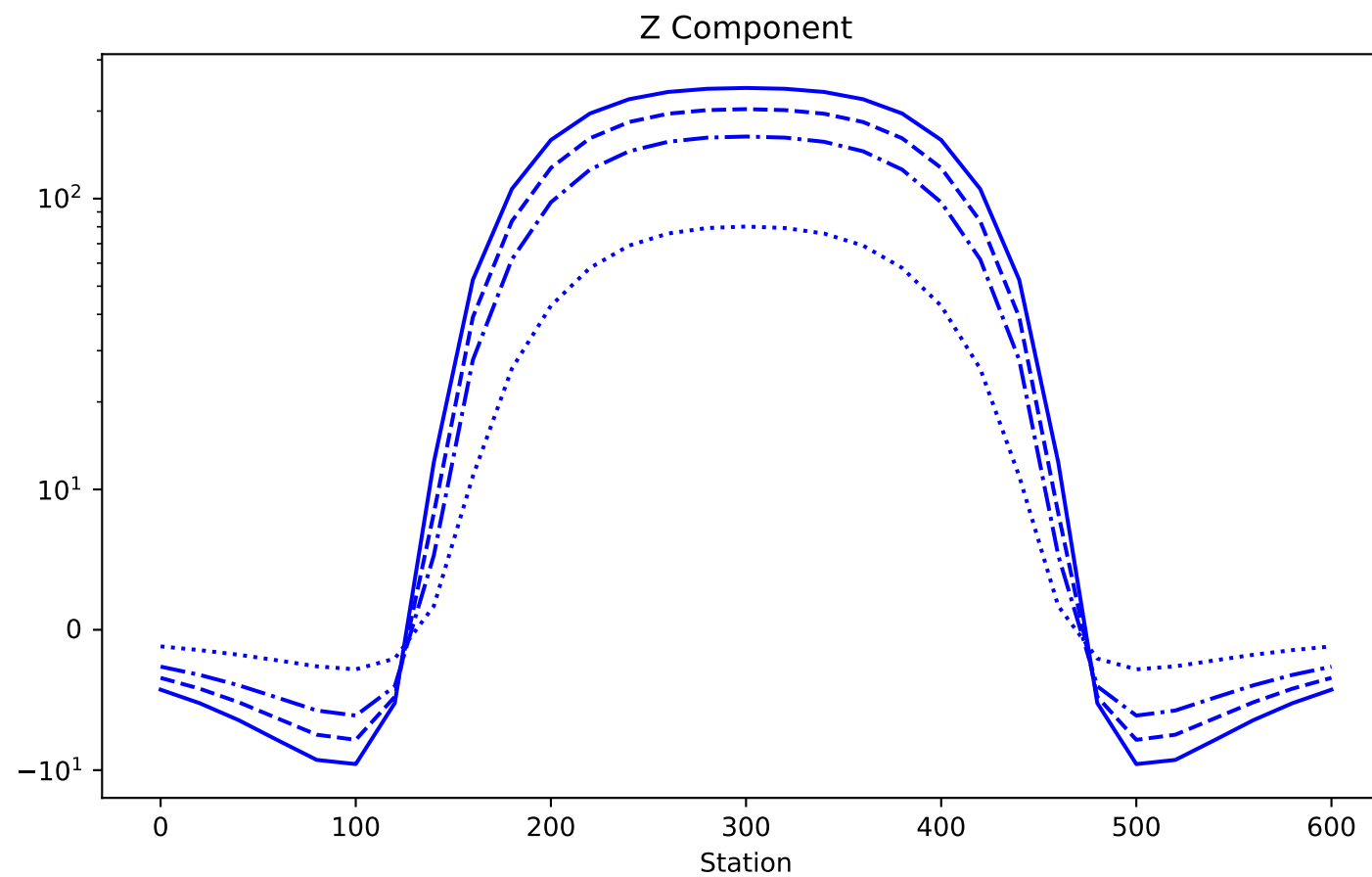
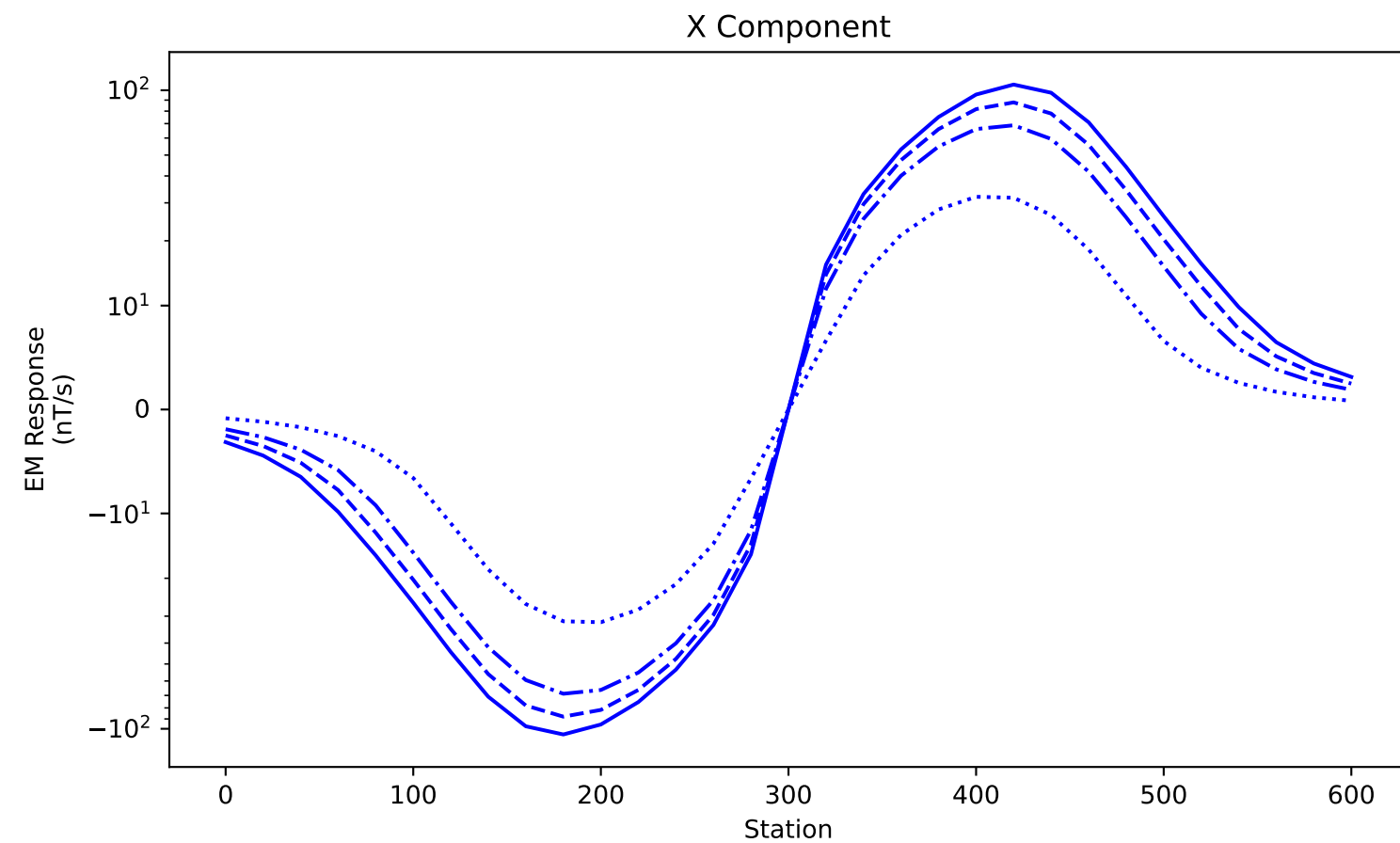
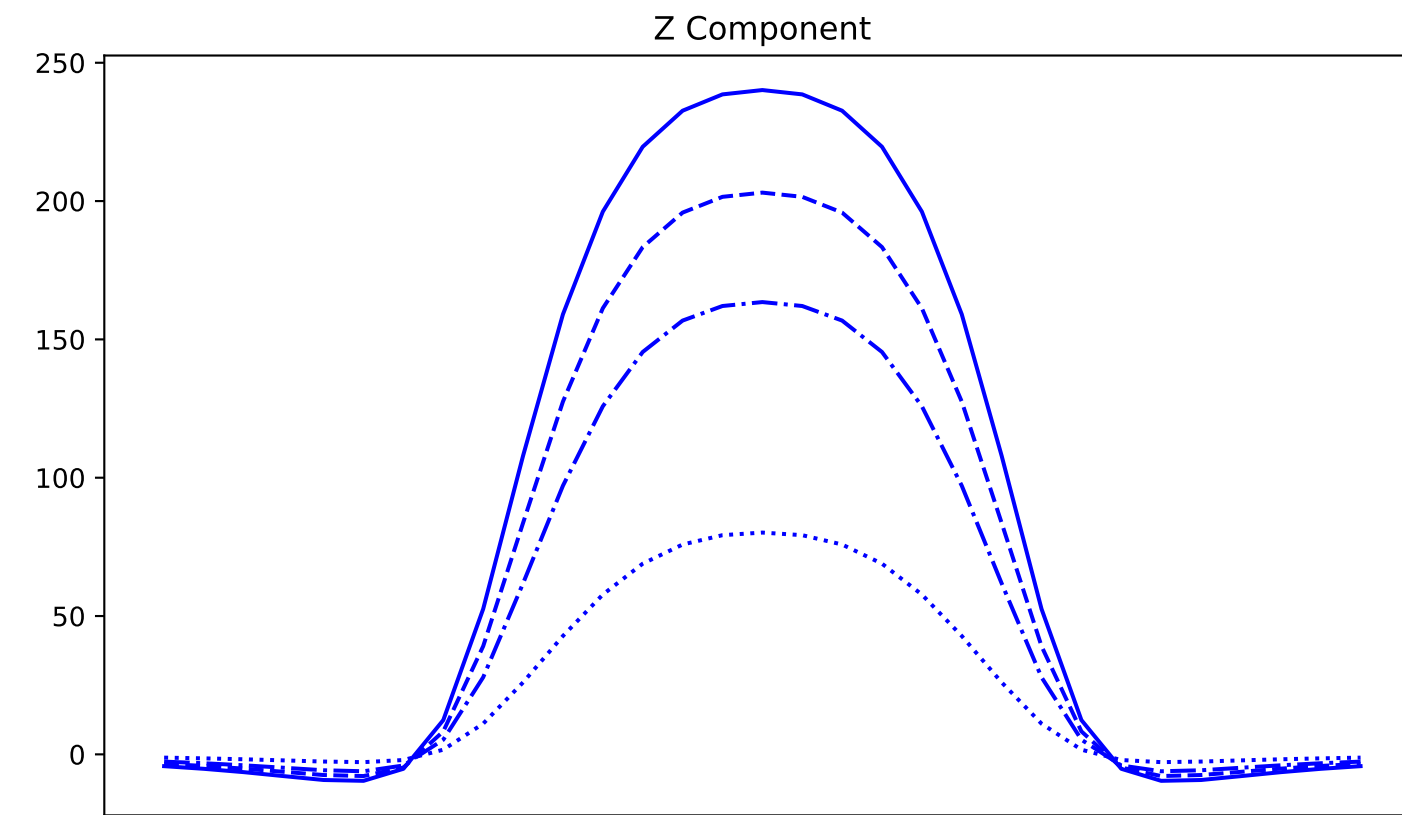
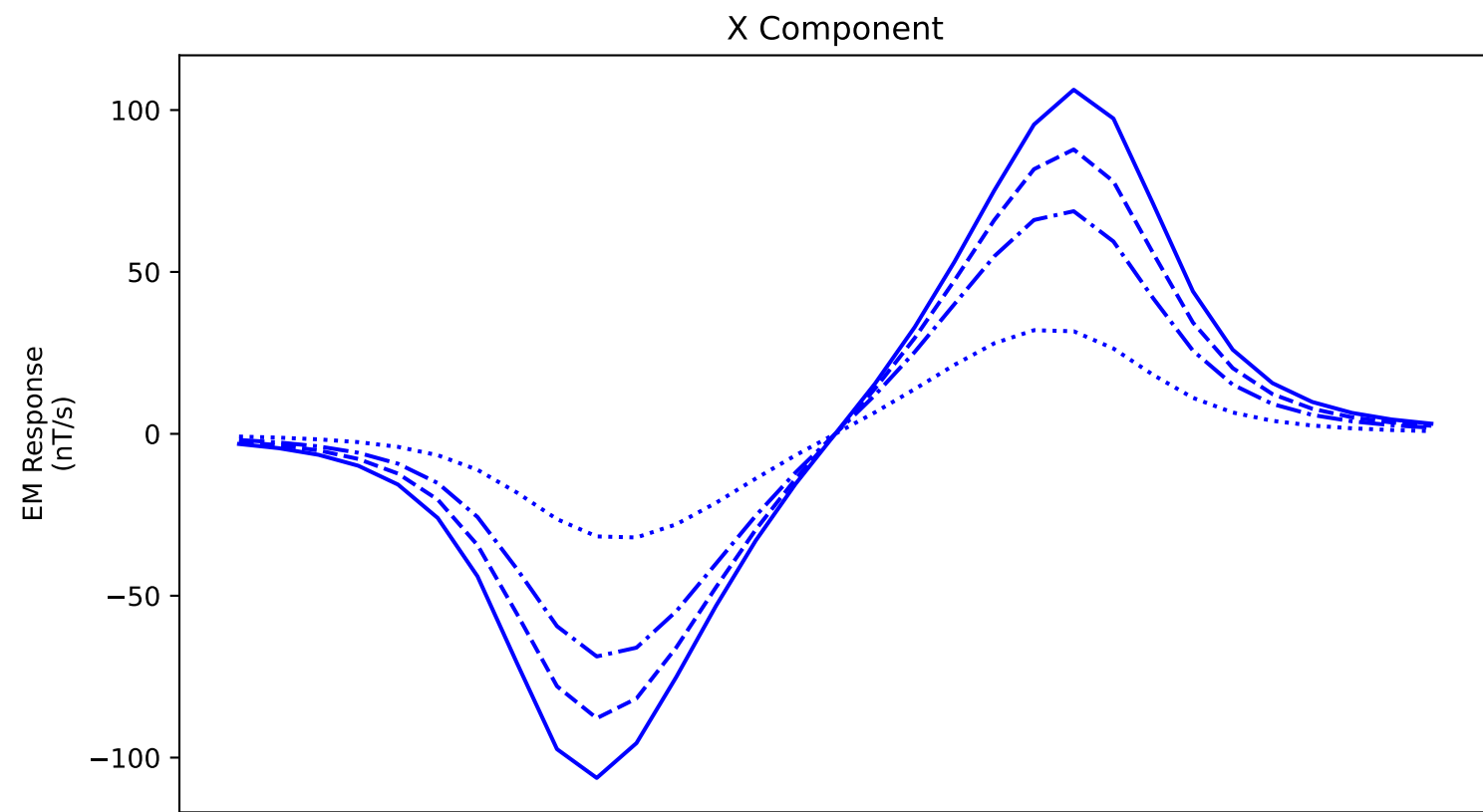
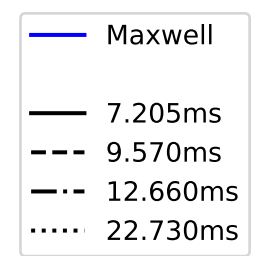
Two-Way Induction
300x100m, 1000S
LOOP=-50
1.315ms to 3.075ms



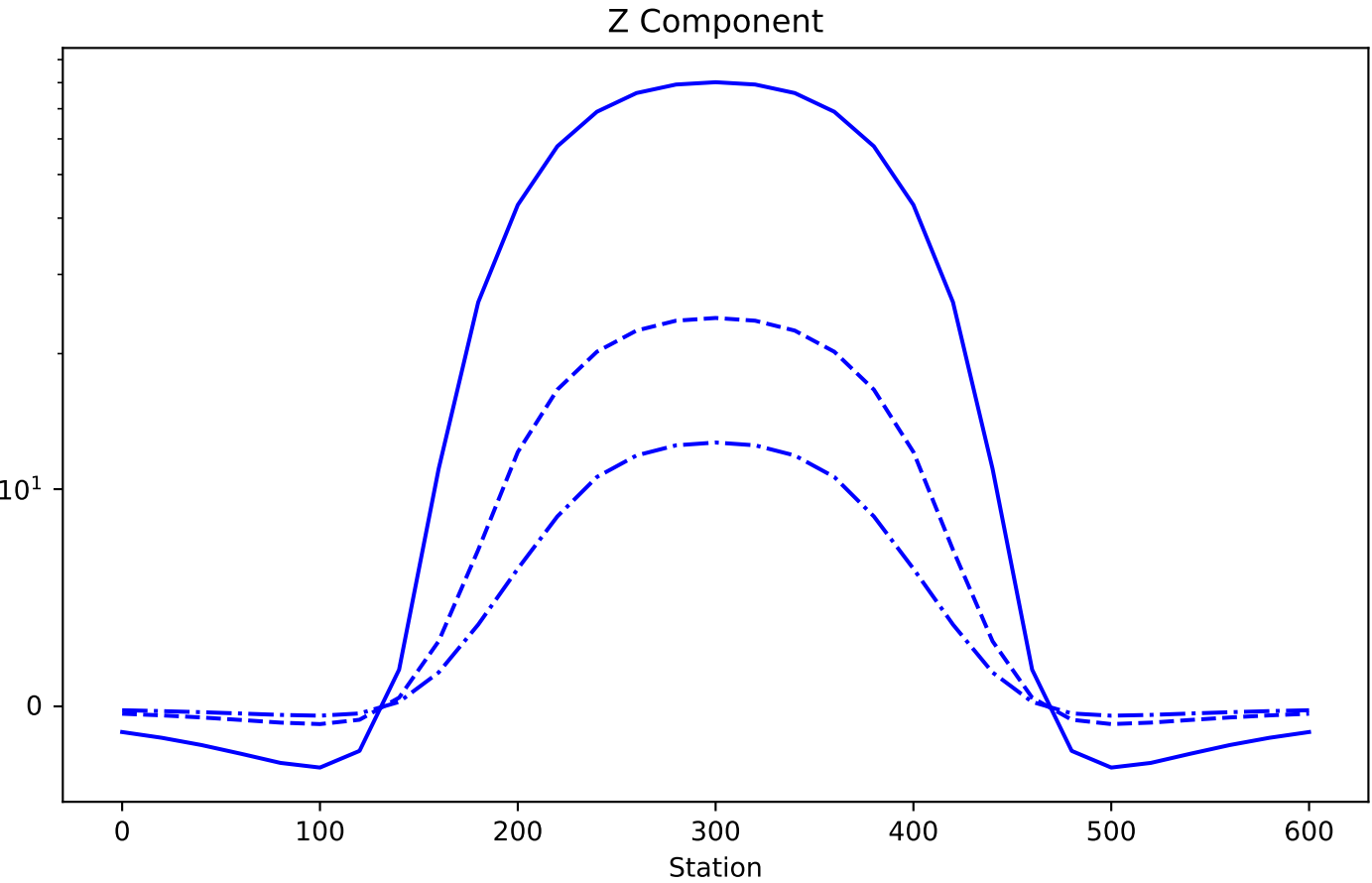
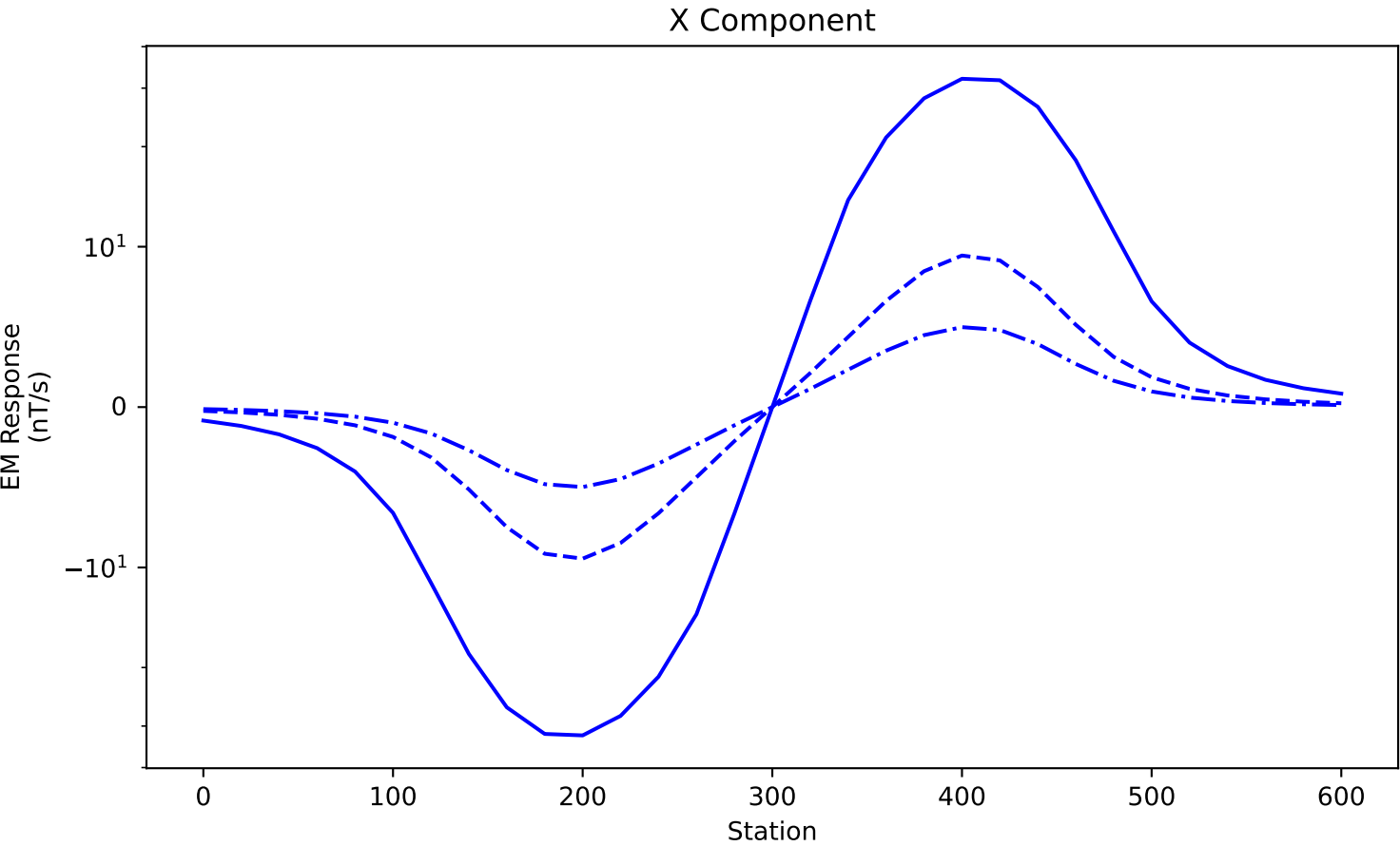
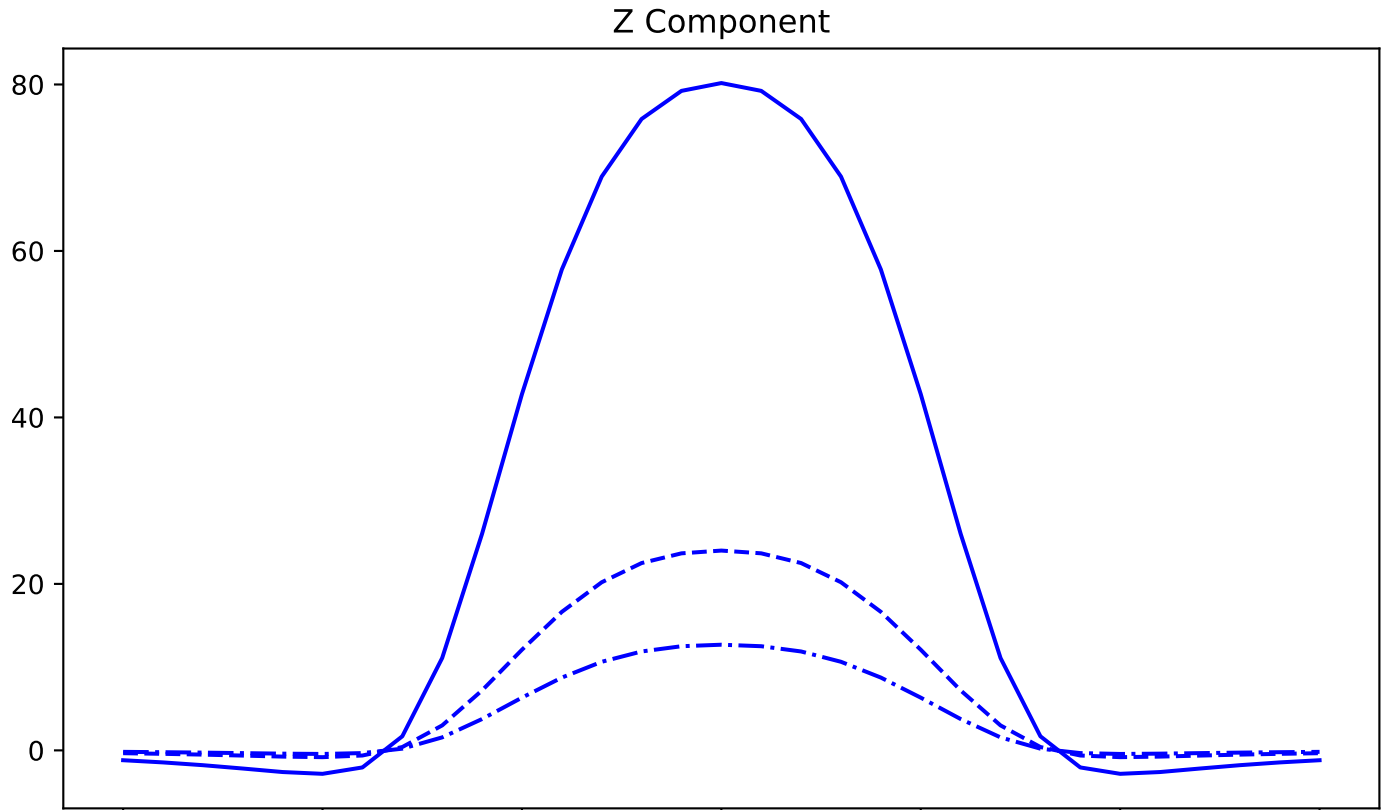
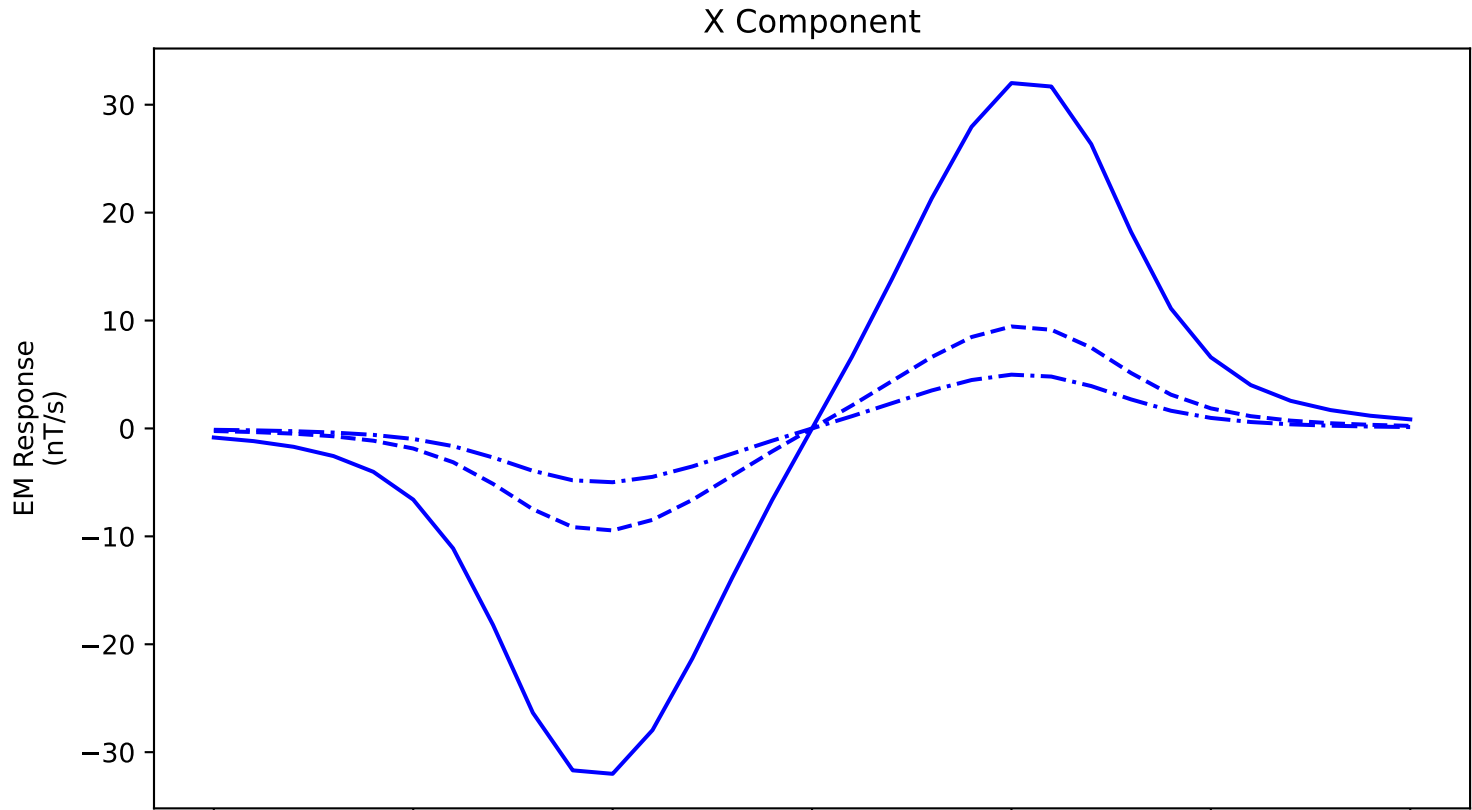
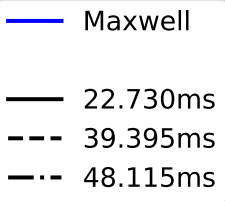
Two-Way Induction
300x100m, 1000S
LOOP=-50
3.075ms to 7.205ms



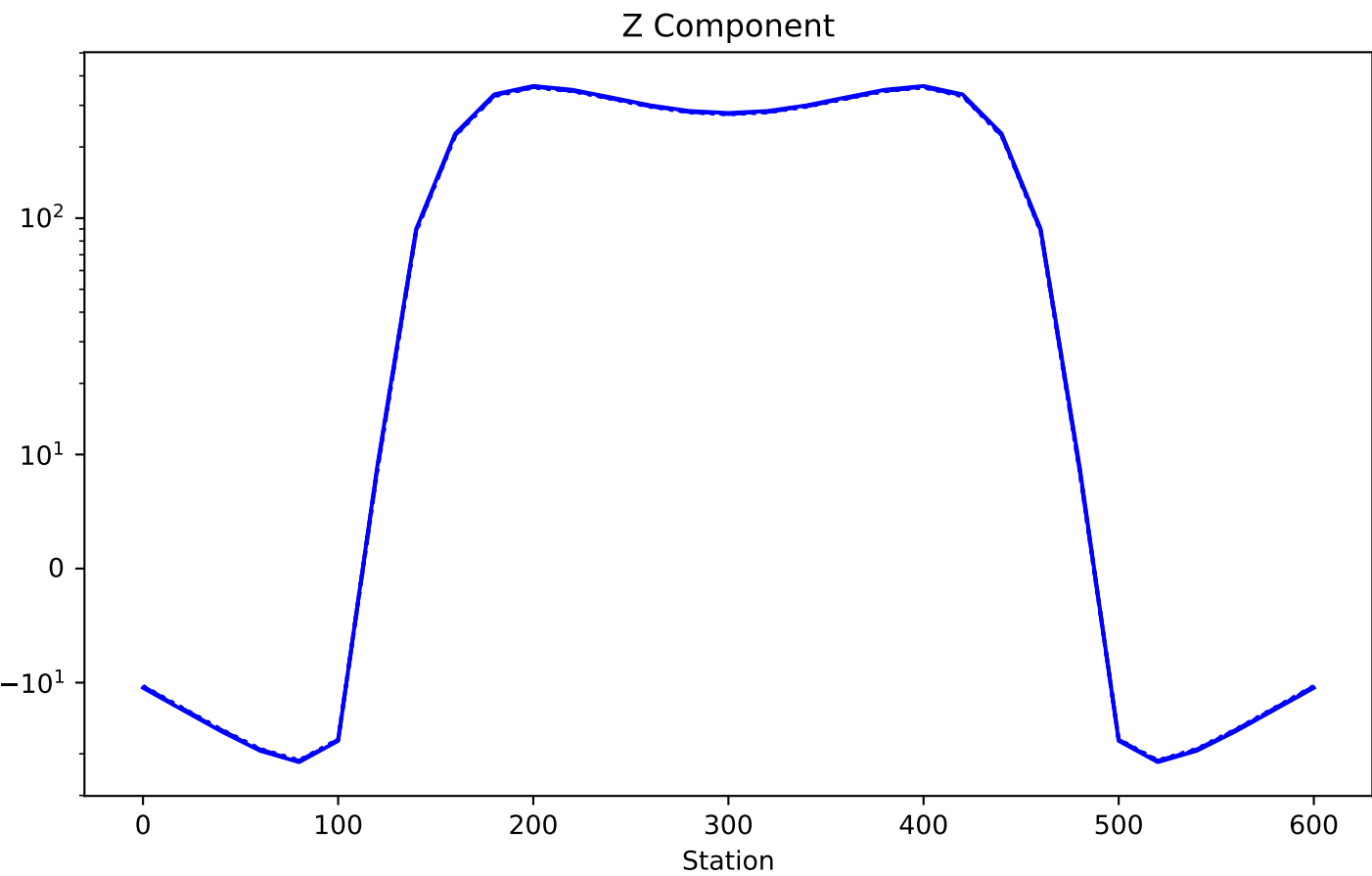
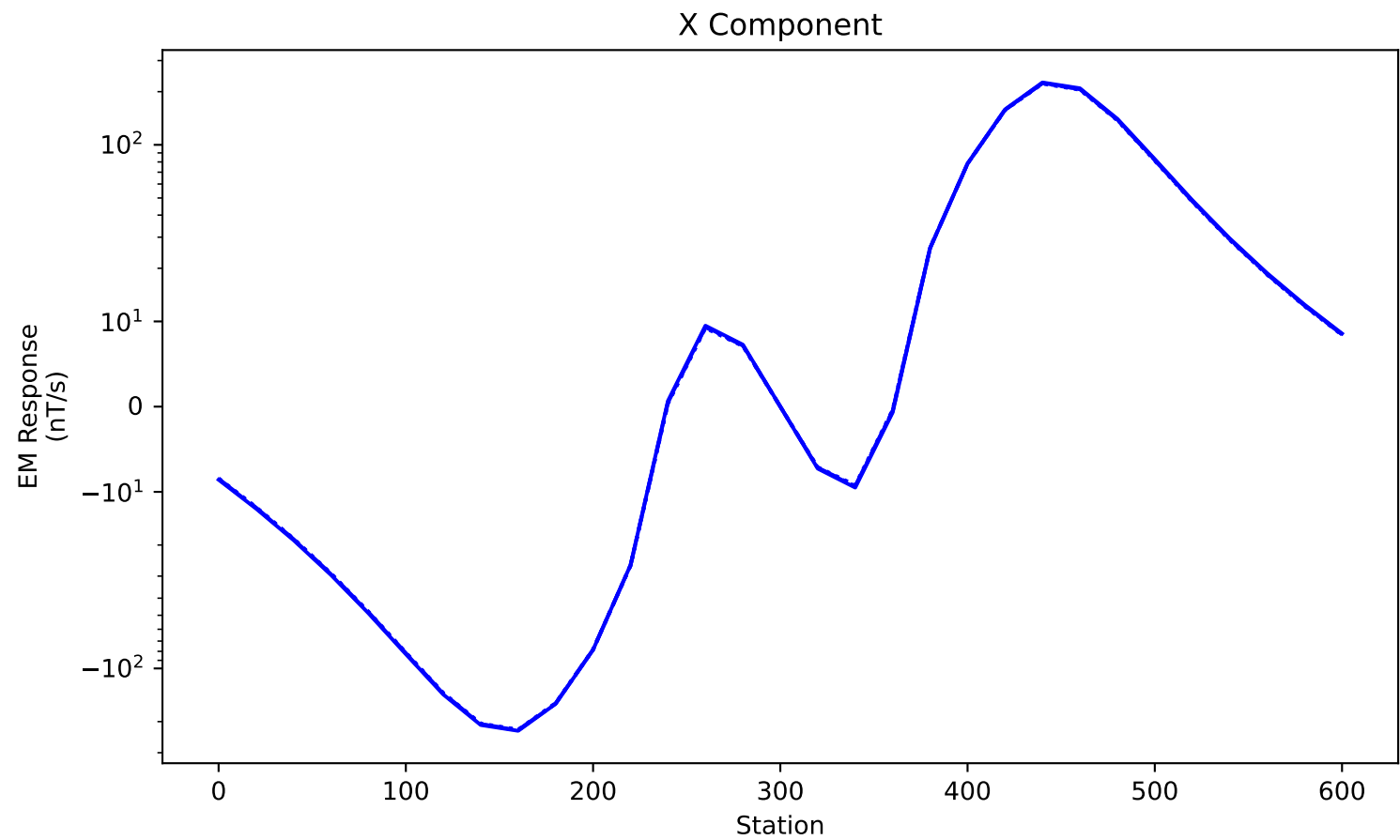
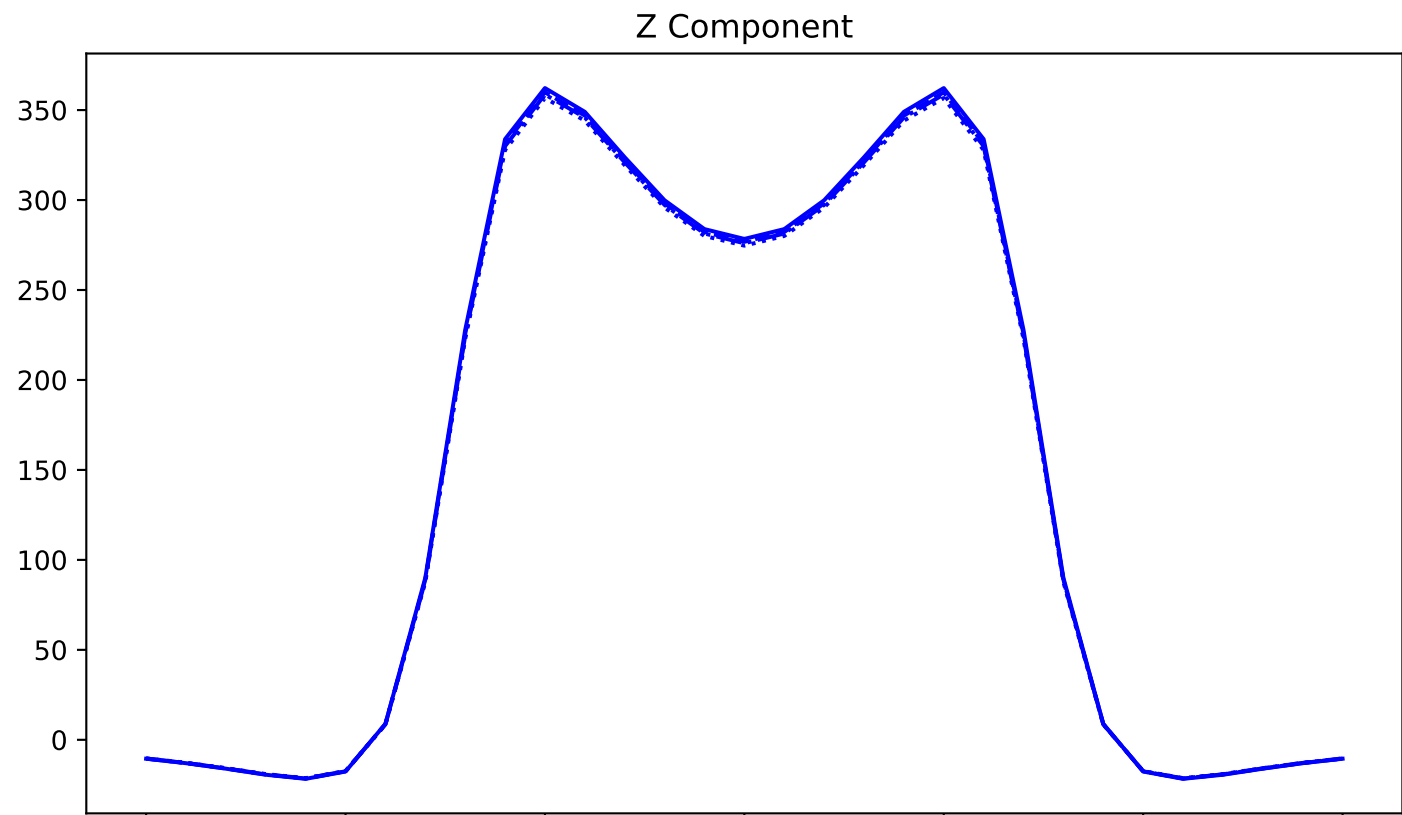
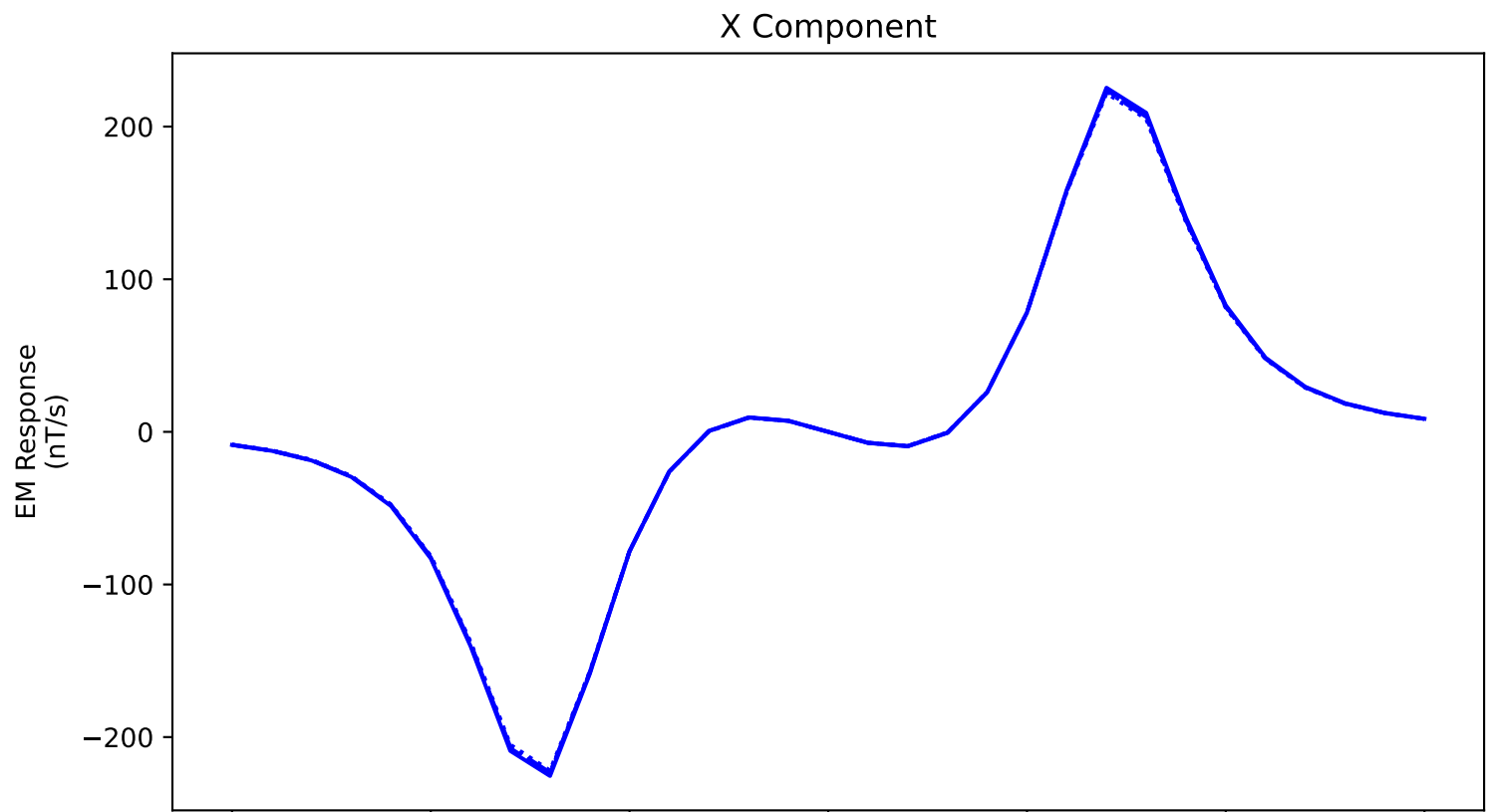
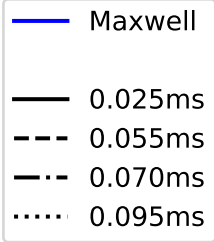
Two-Way Induction
300x100m, 1000S
LOOP=-50
7.205ms to 22.73ms



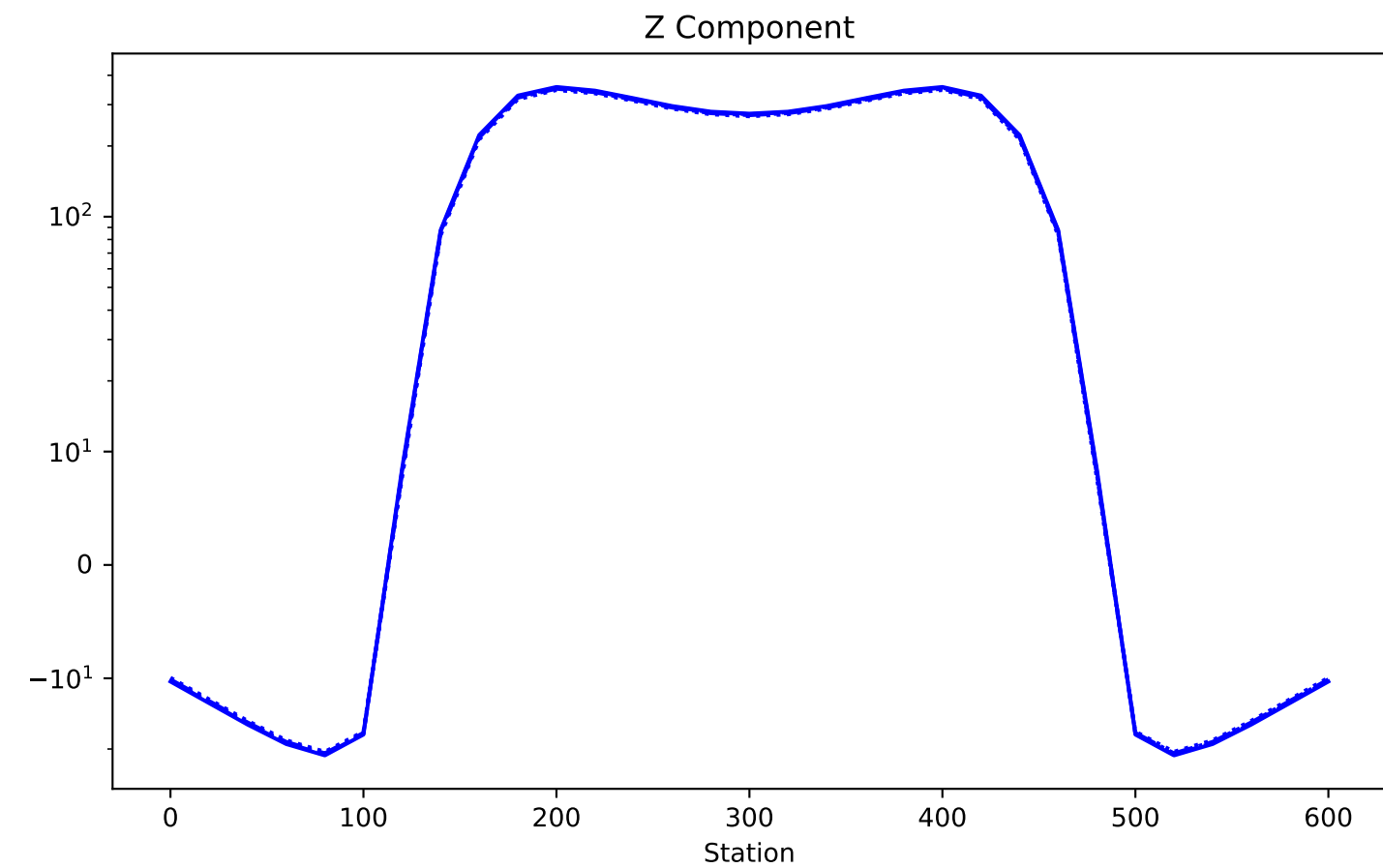
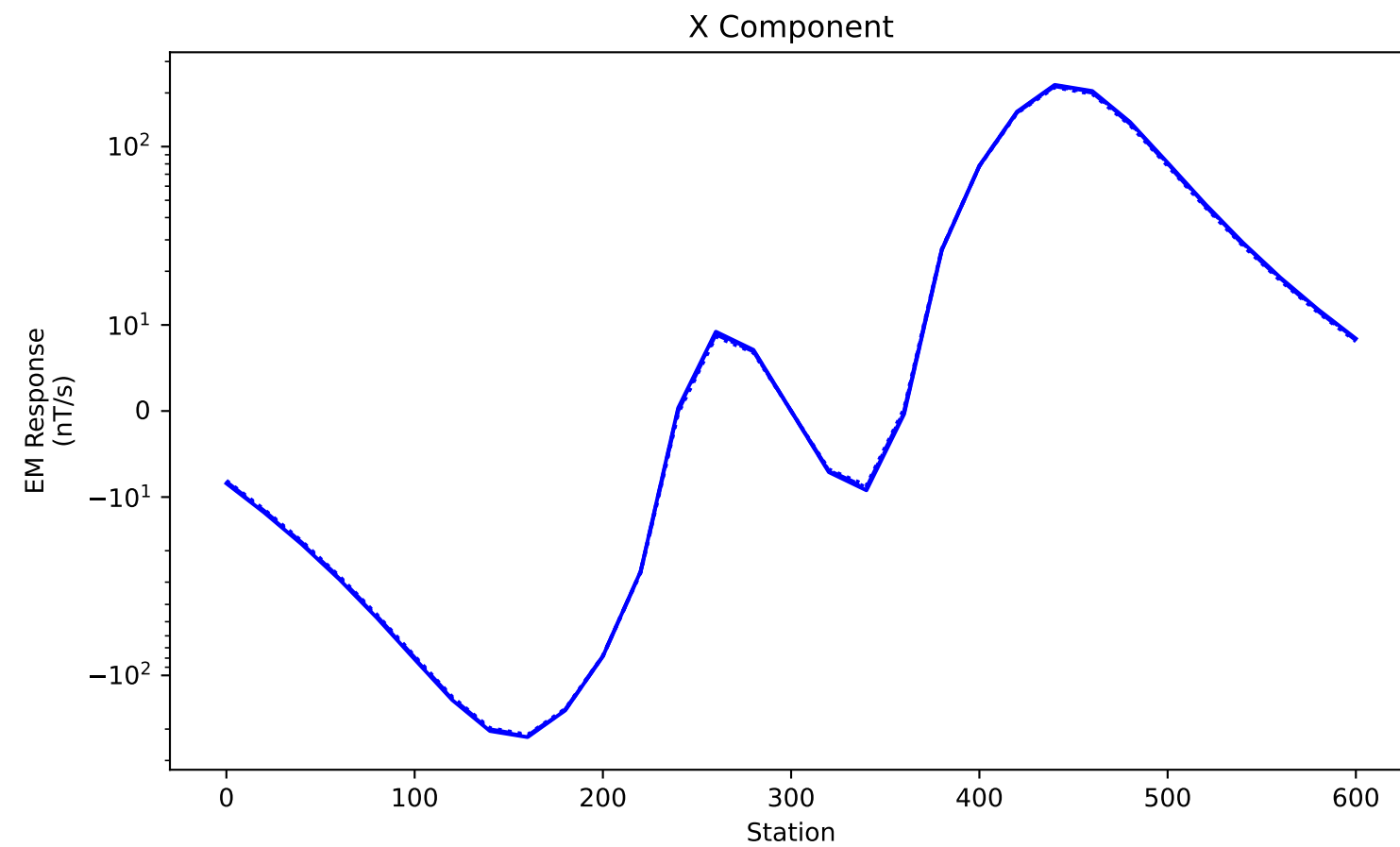
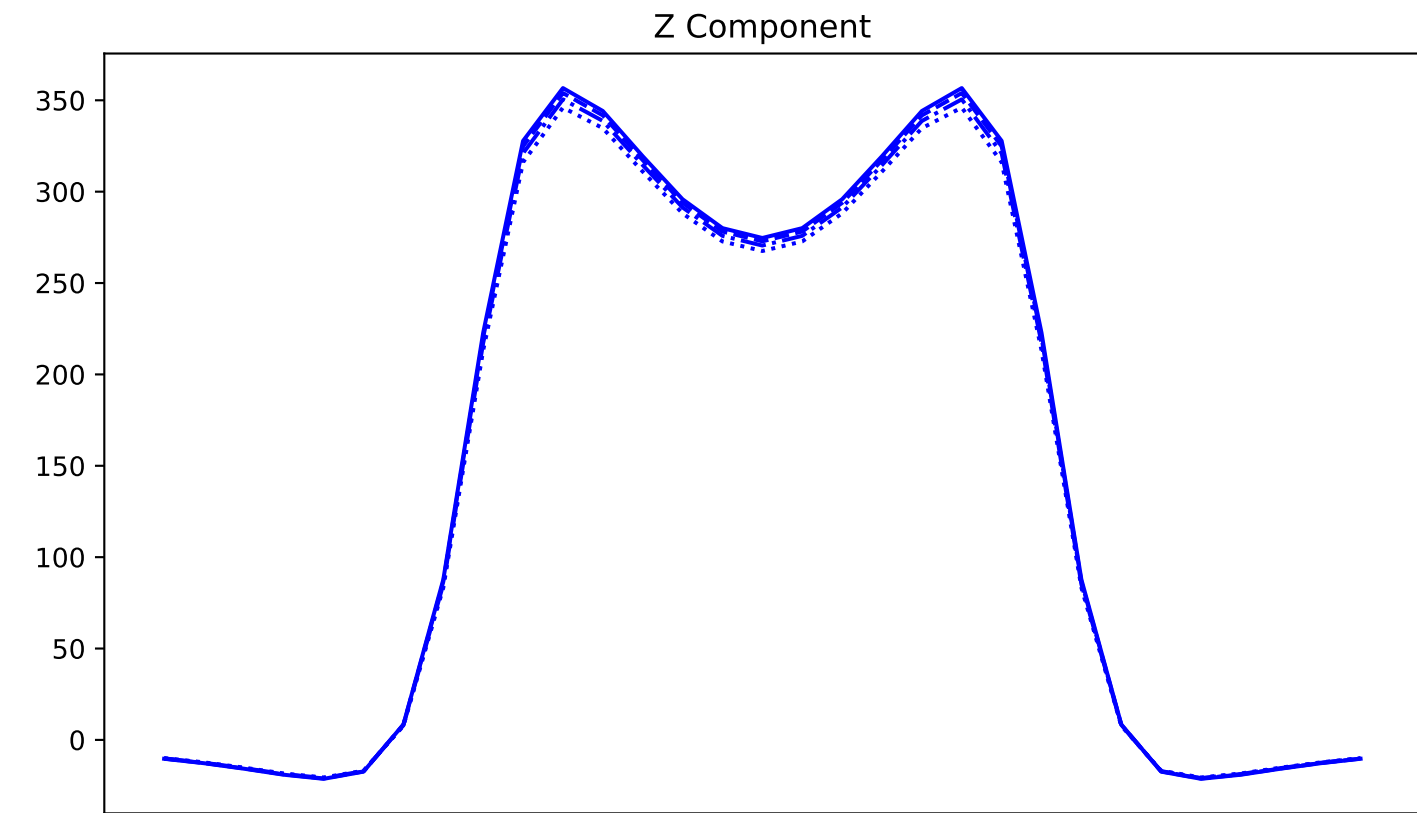
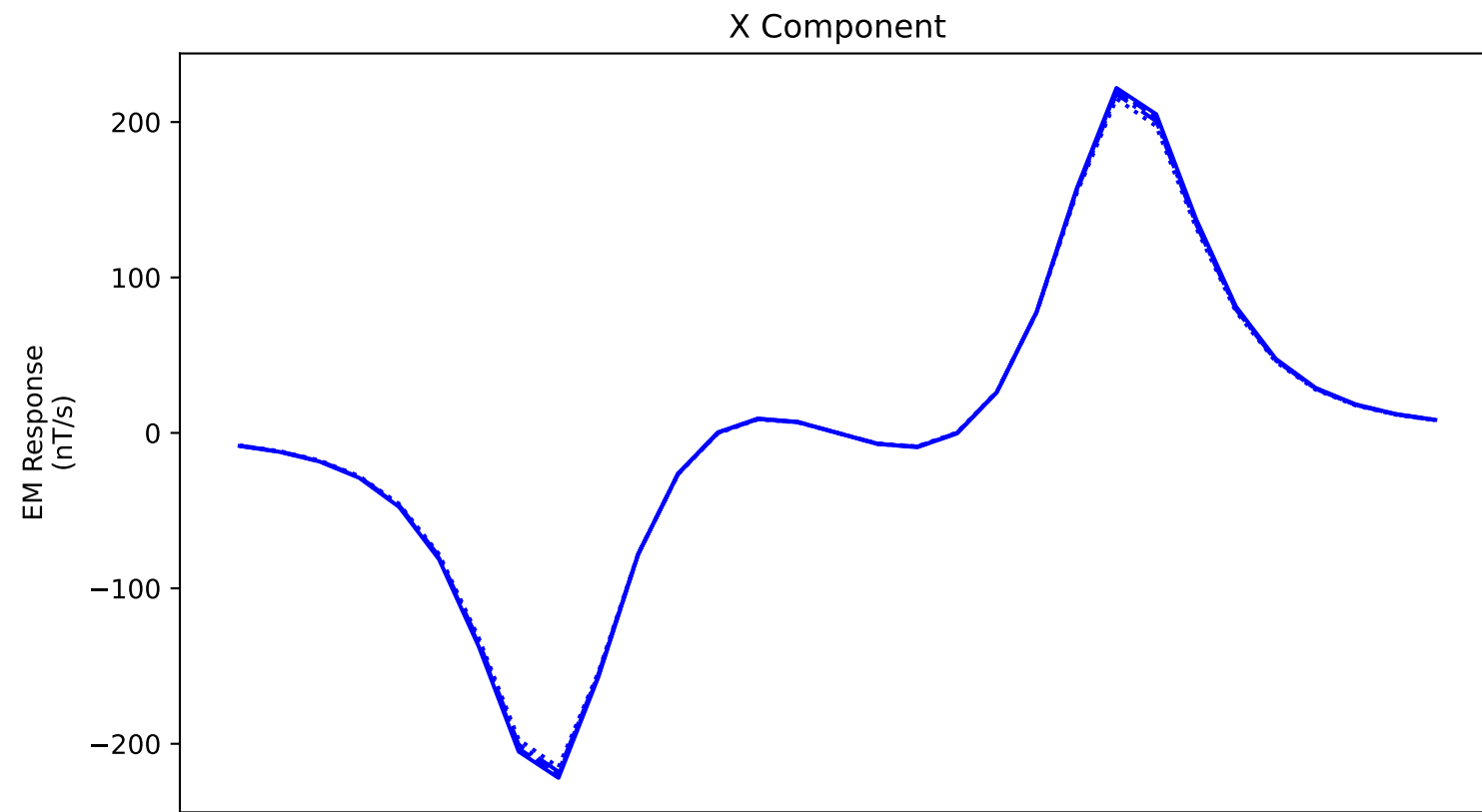
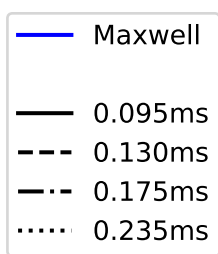
Two-Way Induction
300x100m, 1000S
LOOP=-50
22.73ms to 48.115ms



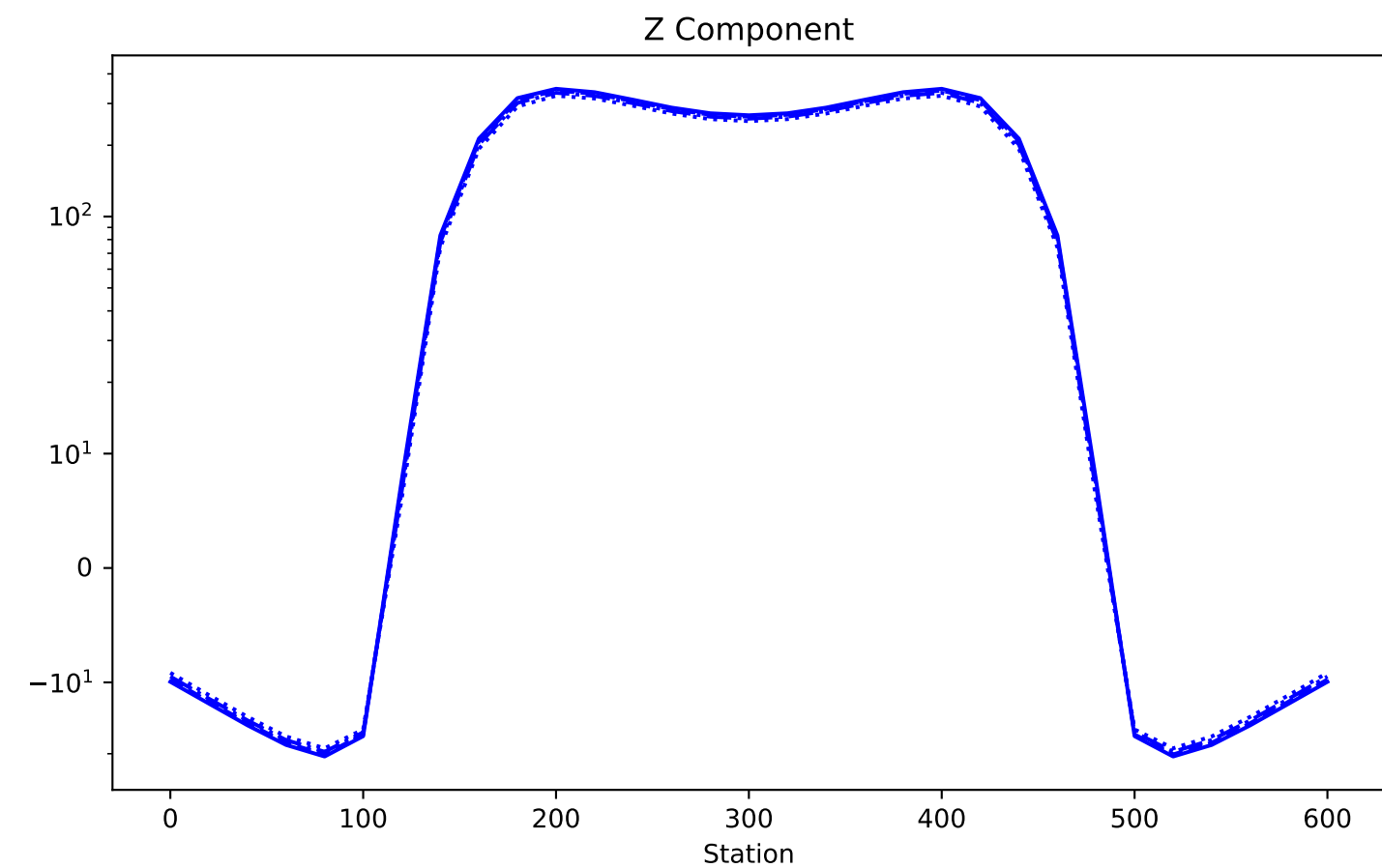
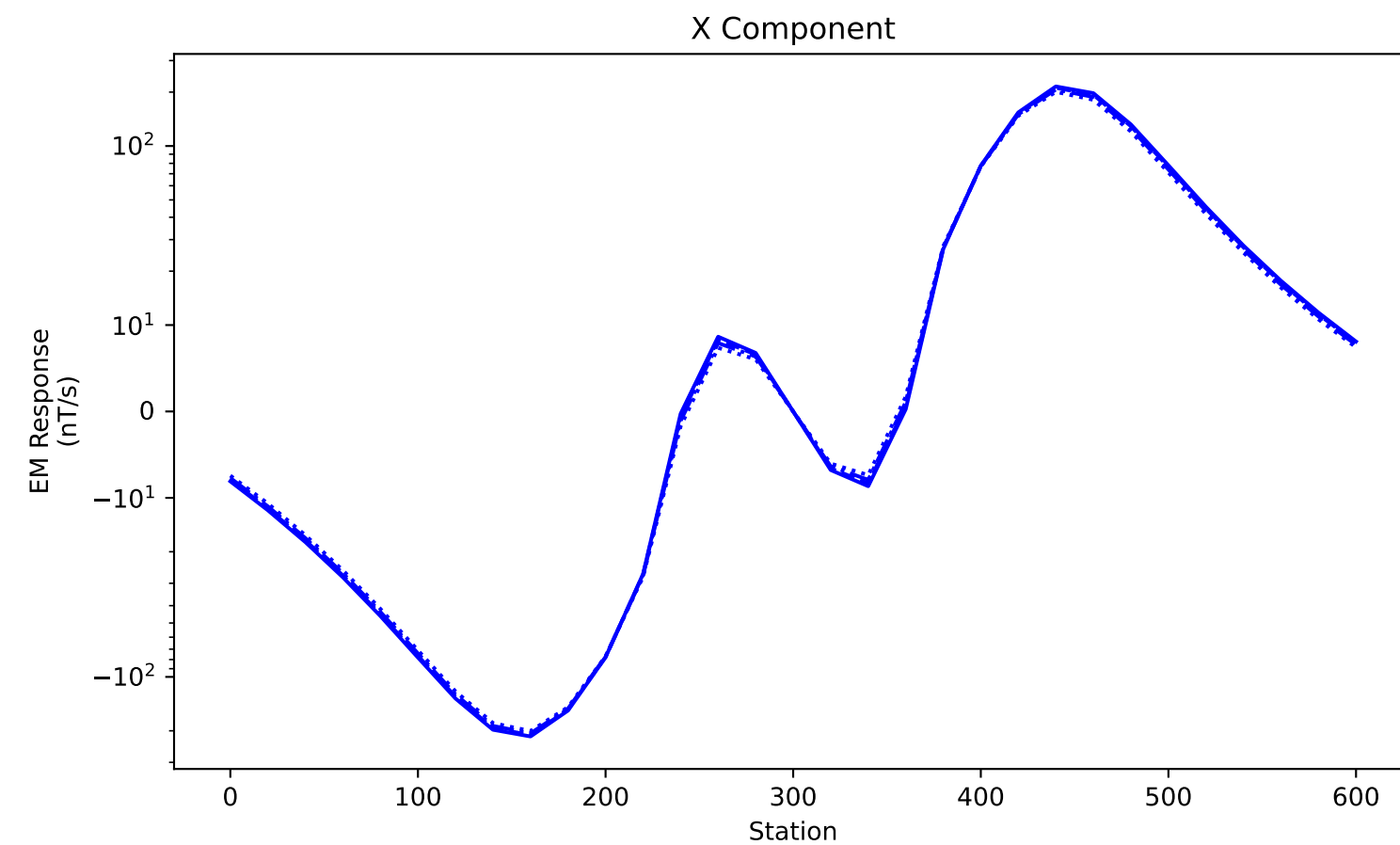
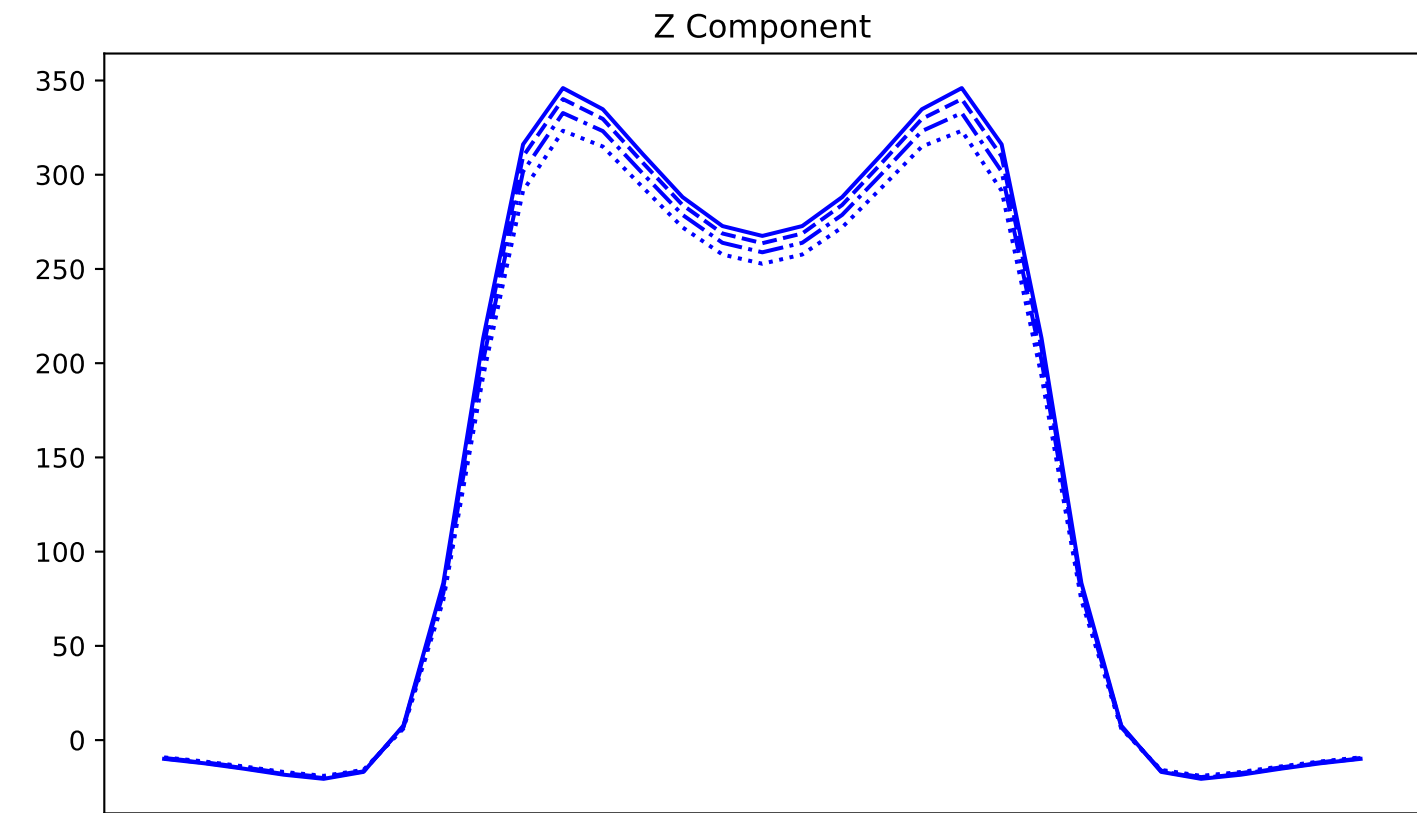
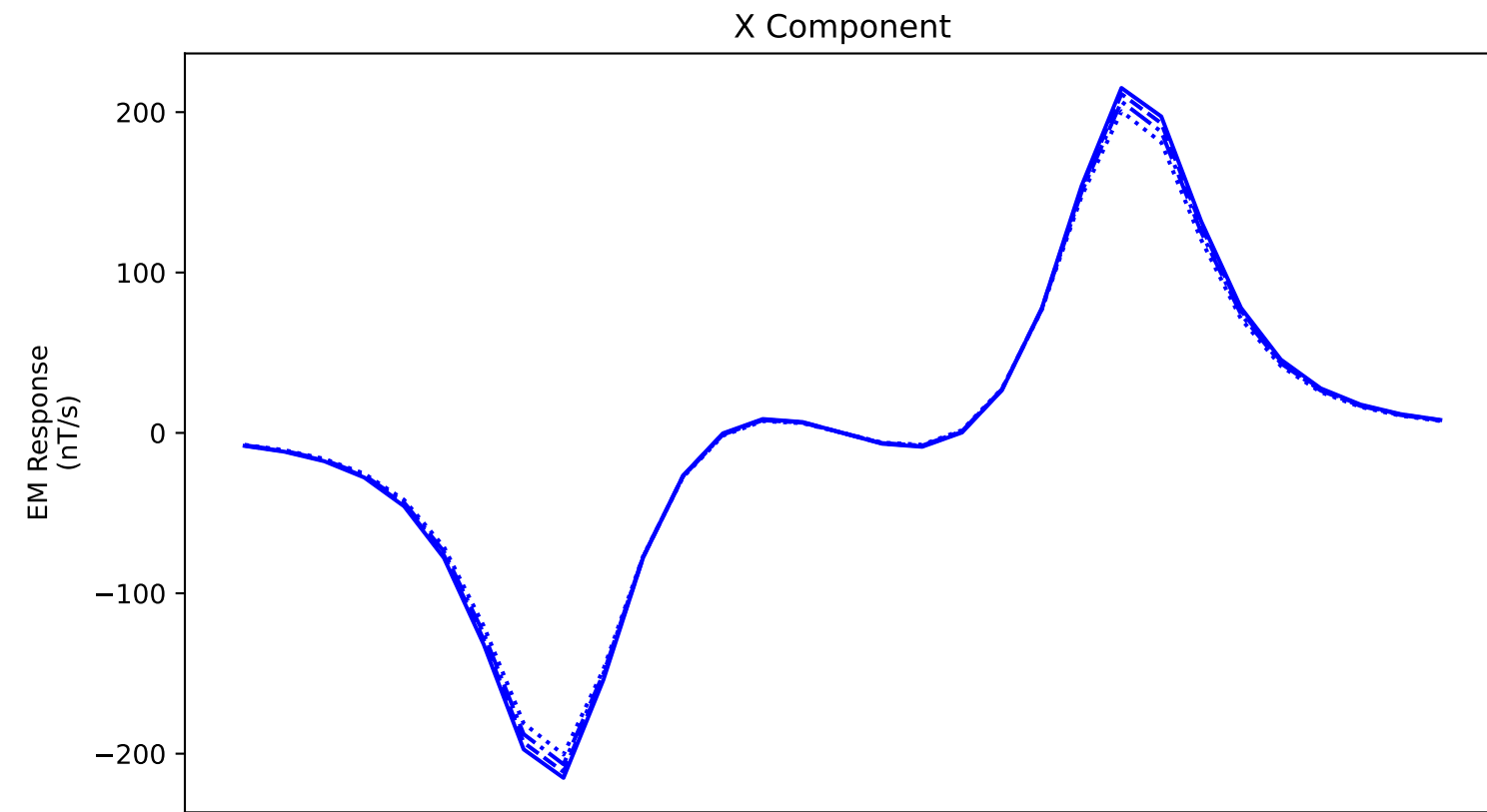
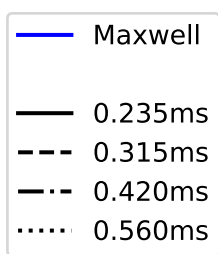
Two-Way Induction
300x100m, 1000S
LOOP=-100
0.0255ms to 0.095ms



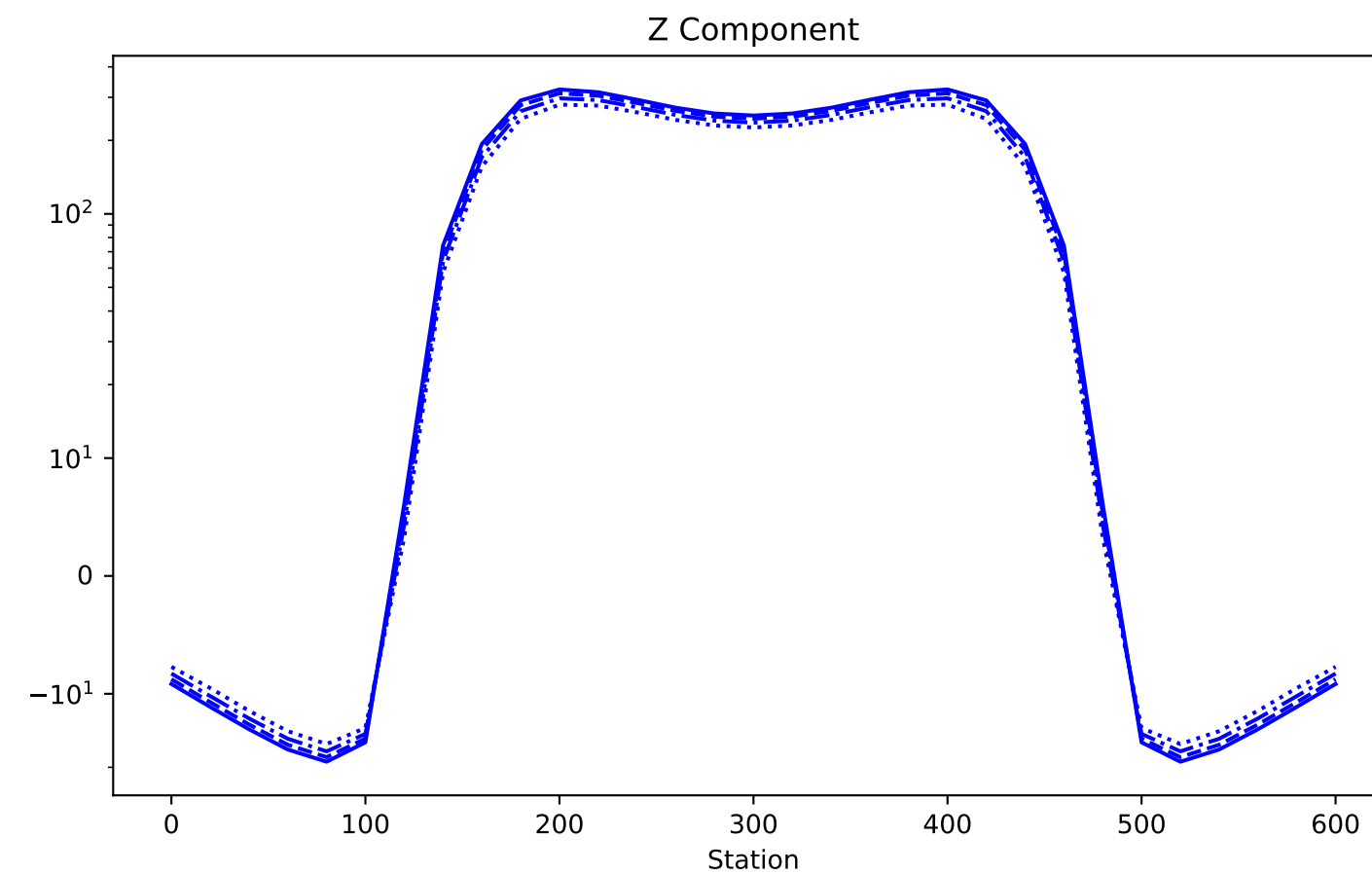
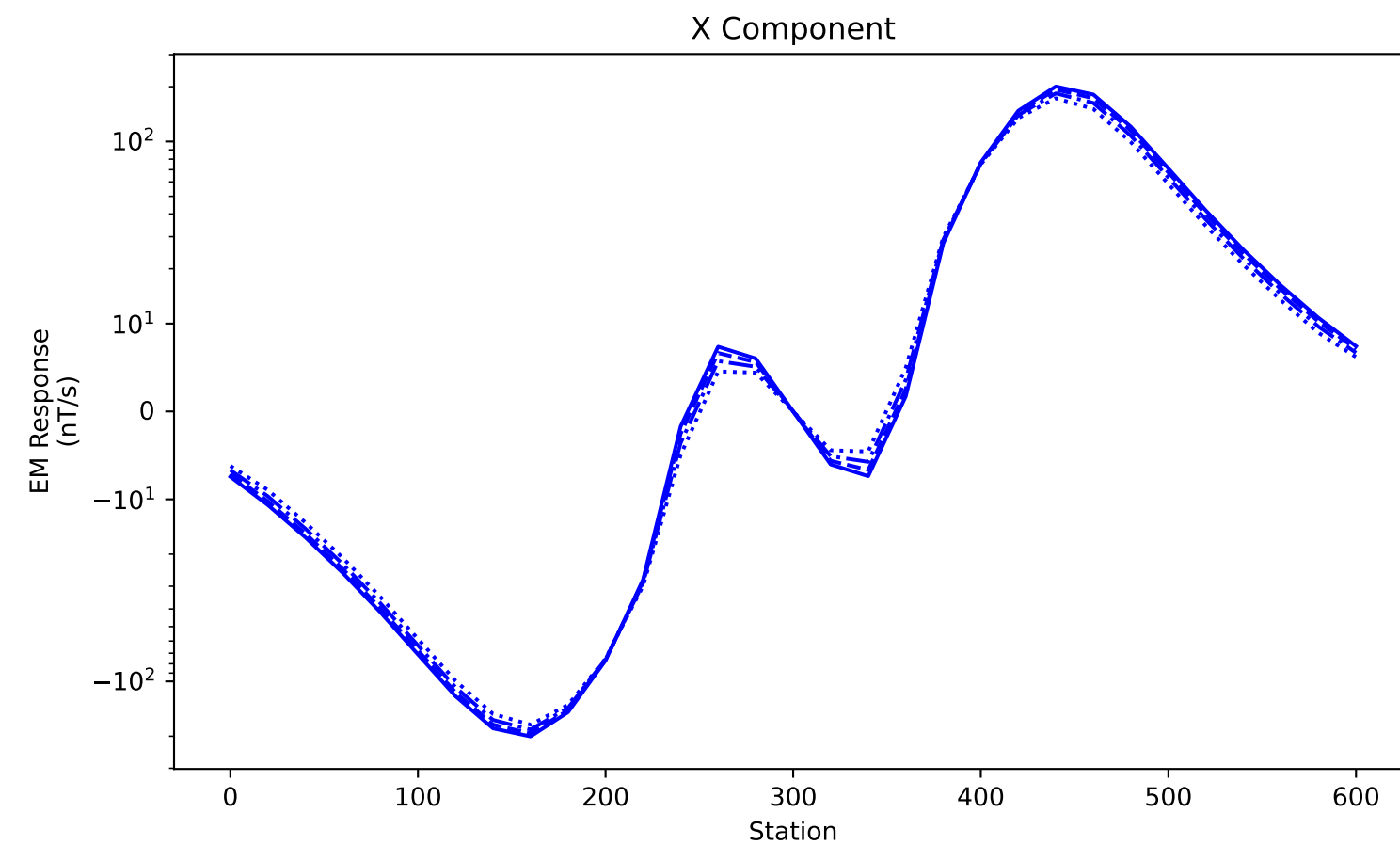
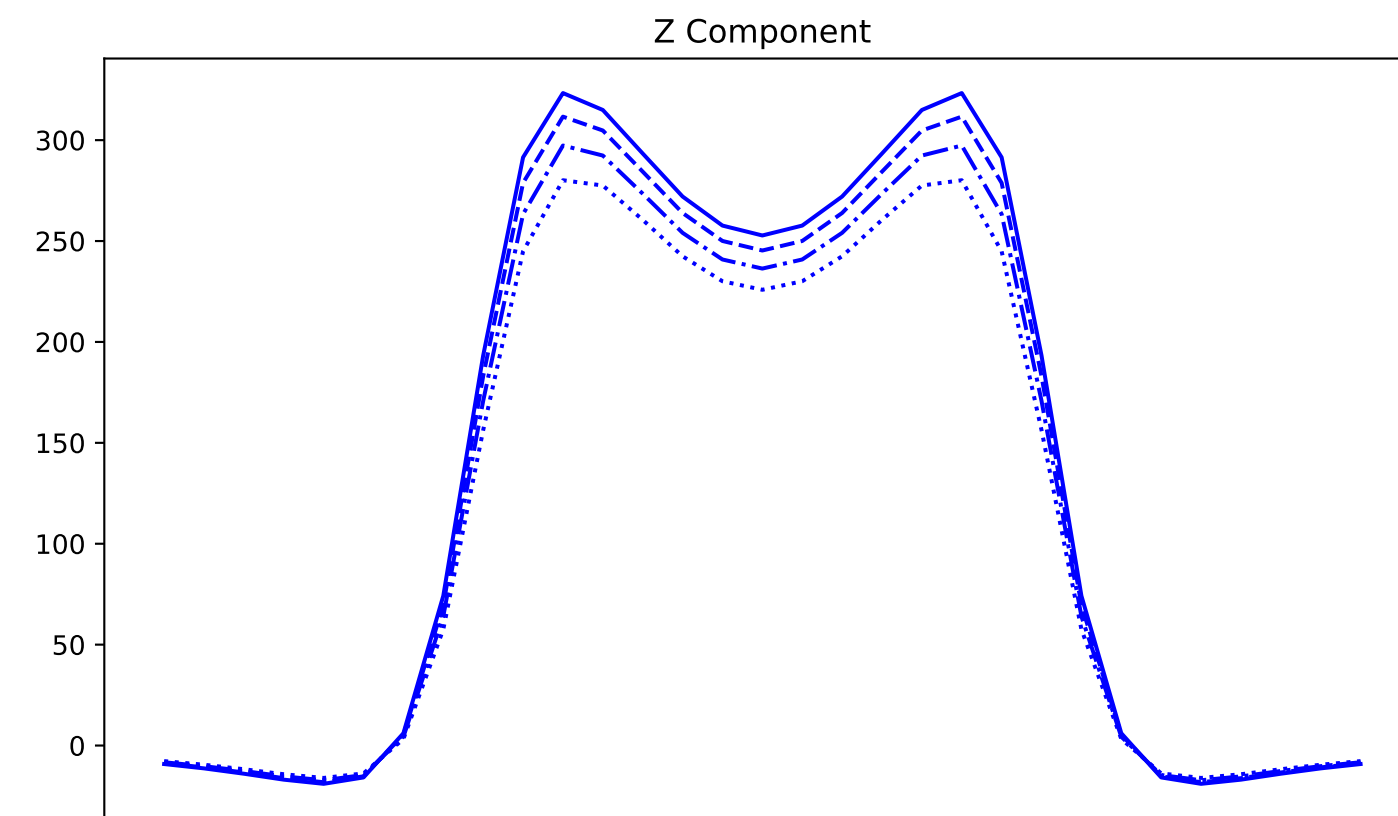
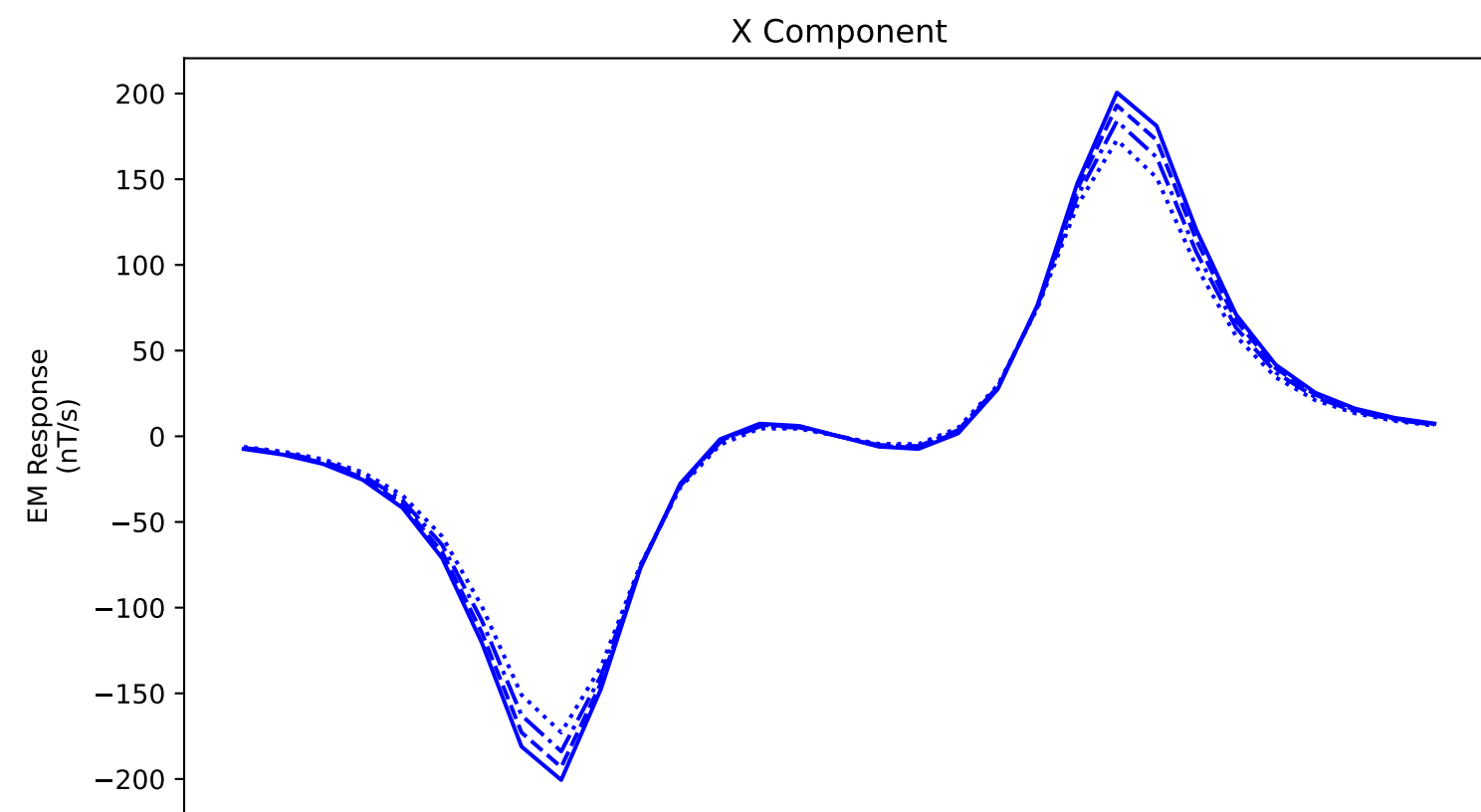
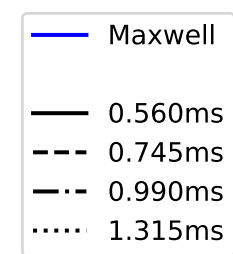
Two-Way Induction
300x100m, 1000S
LOOP=-100
0.095ms to 0.235ms



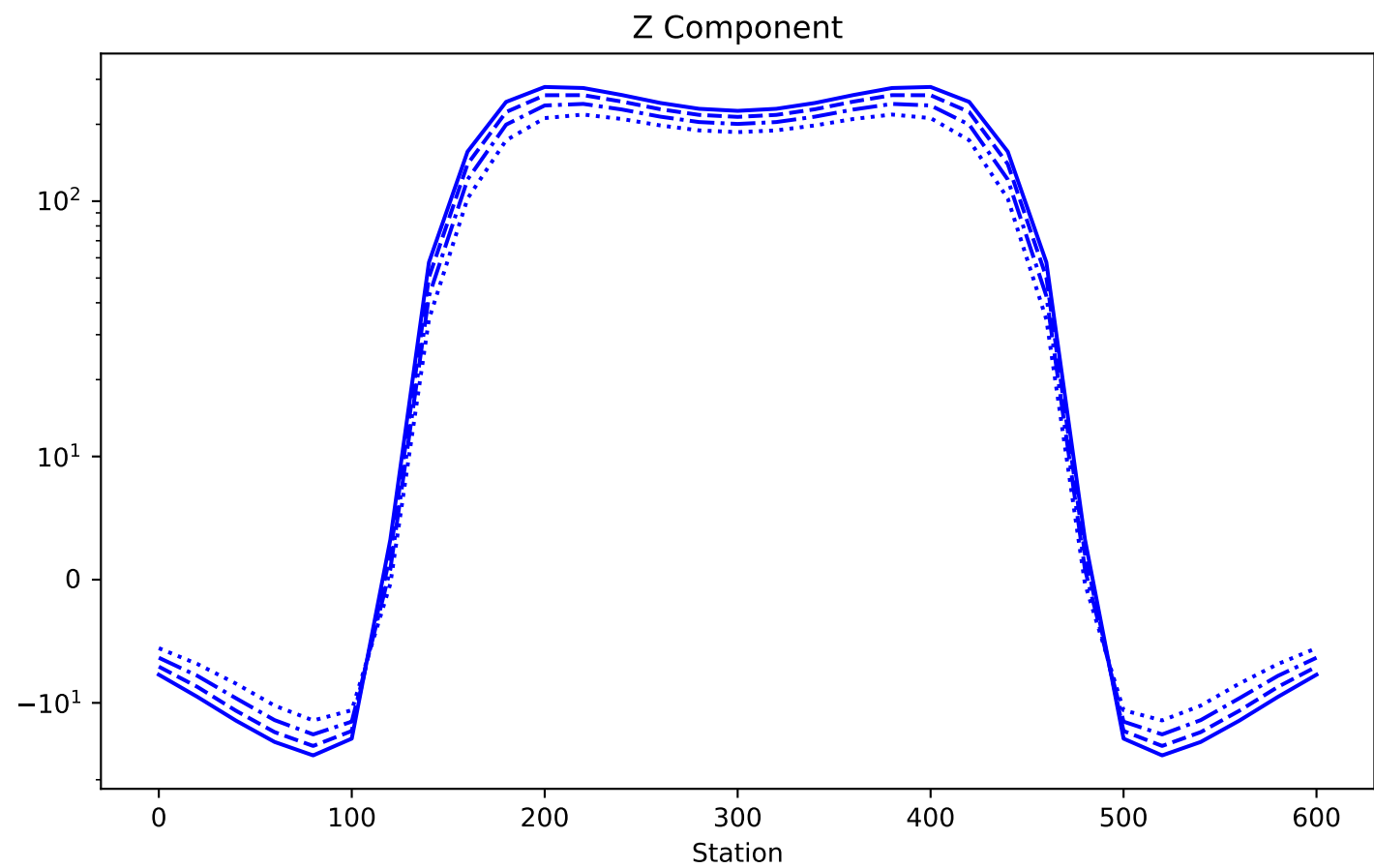
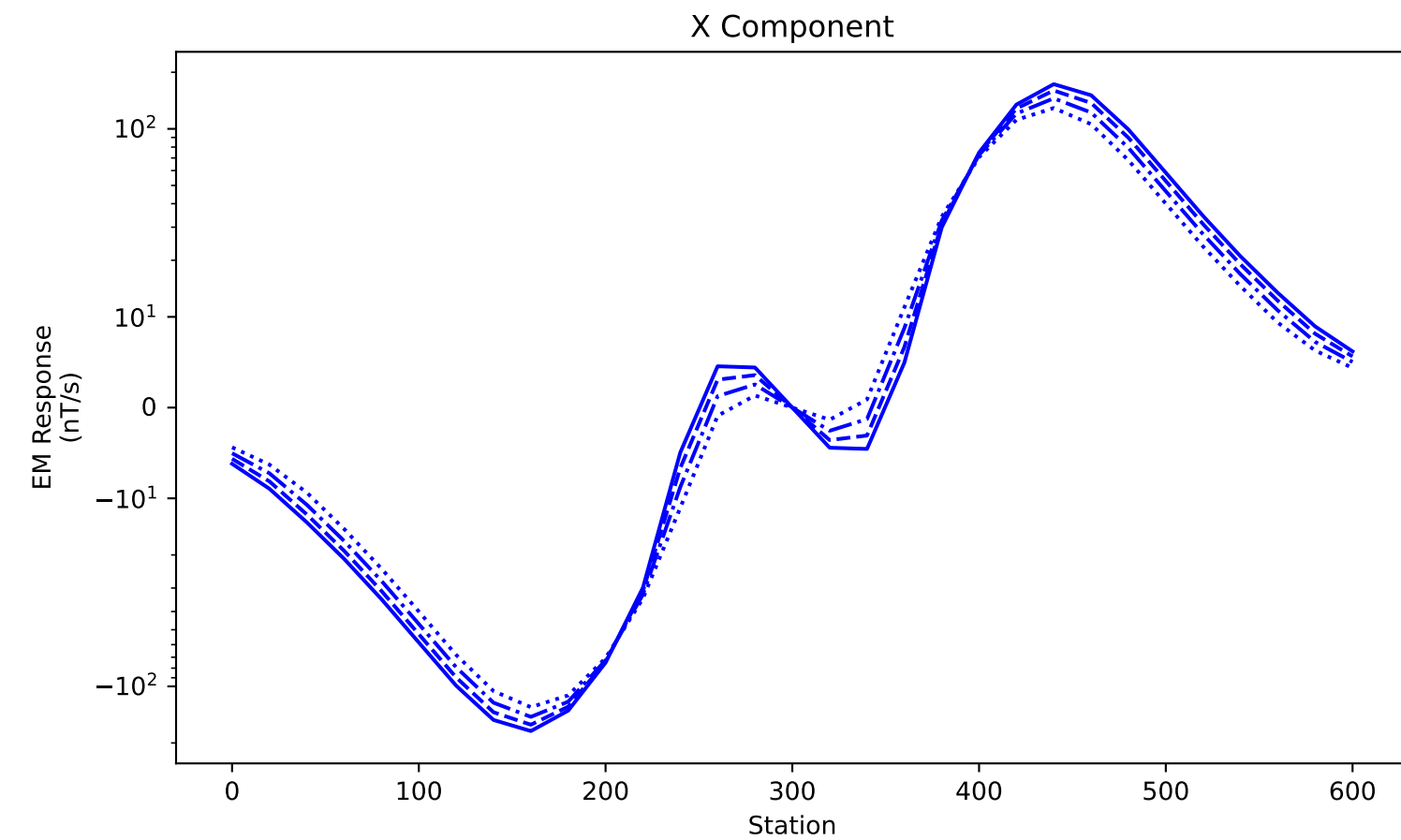
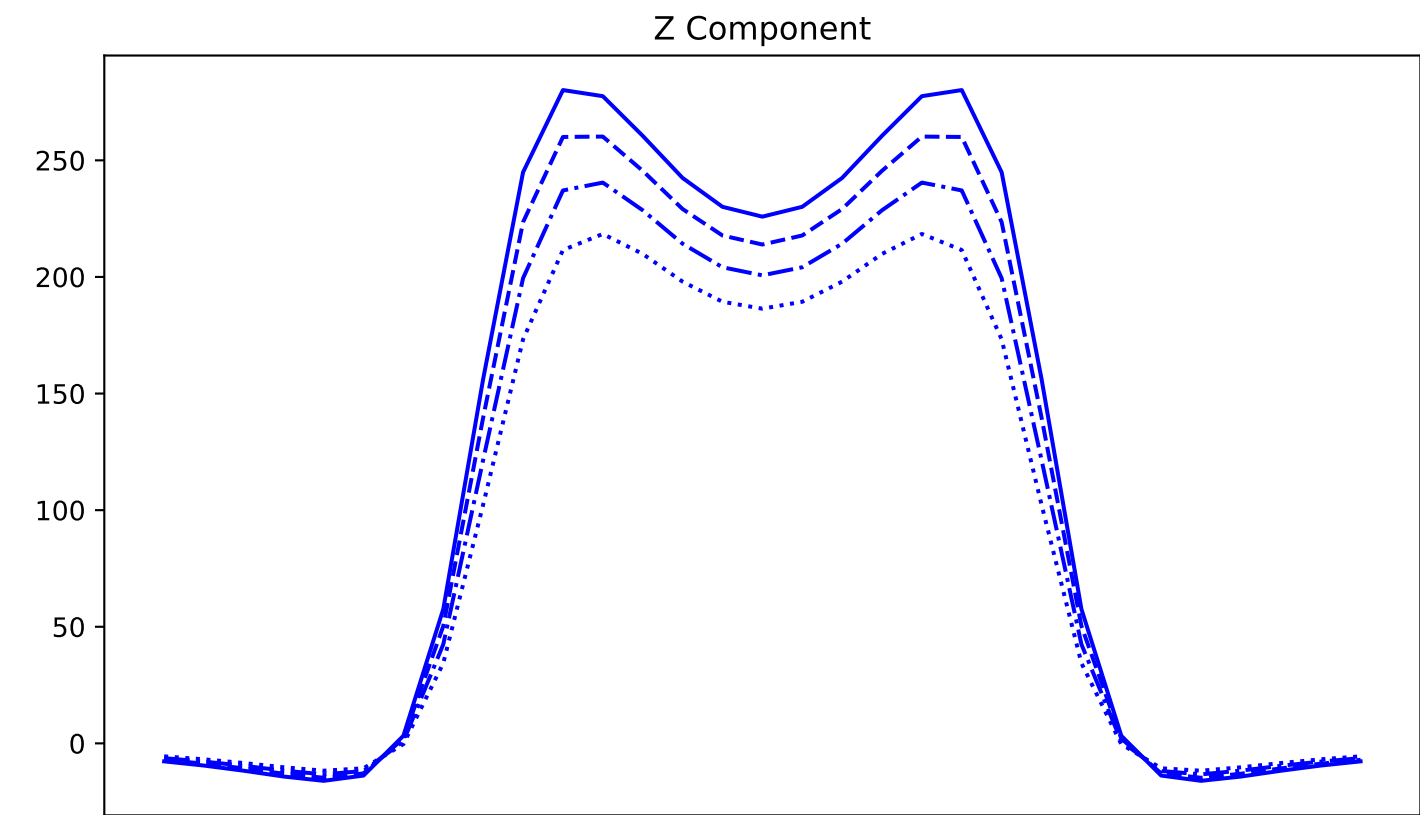
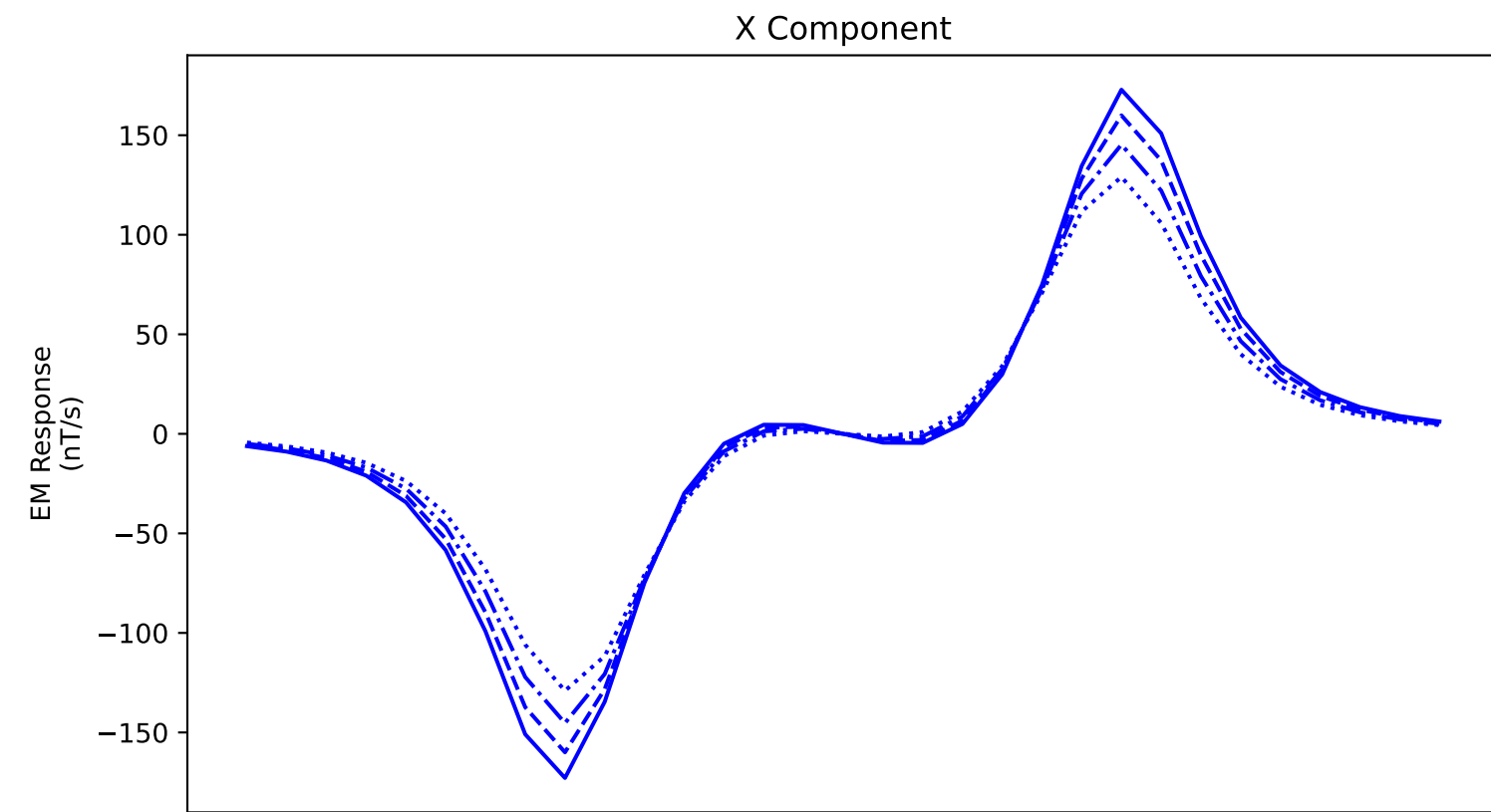
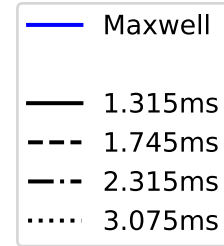
Two-Way Induction
300x100m, 1000S
LOOP=-100
0.235ms to 0.56ms



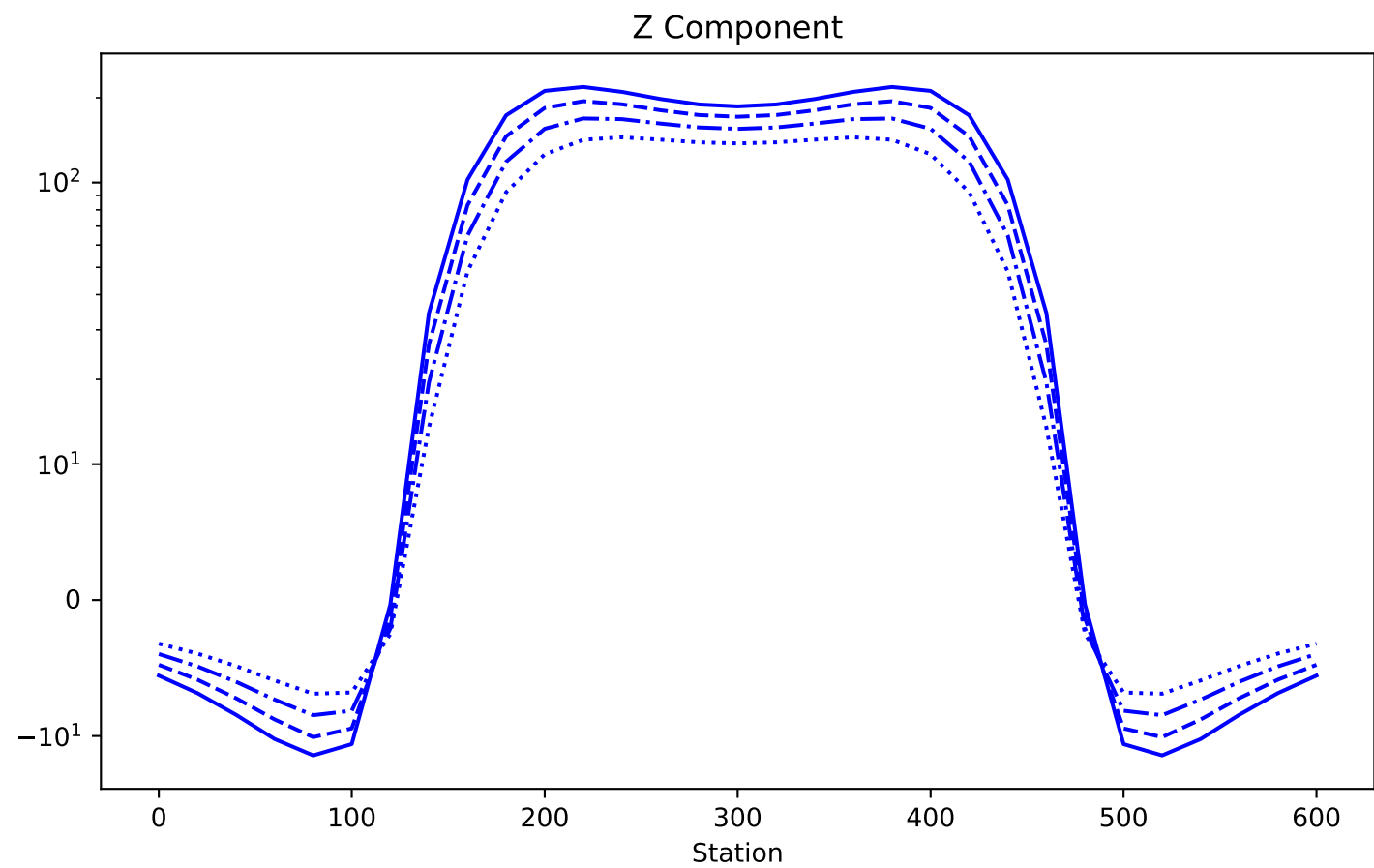
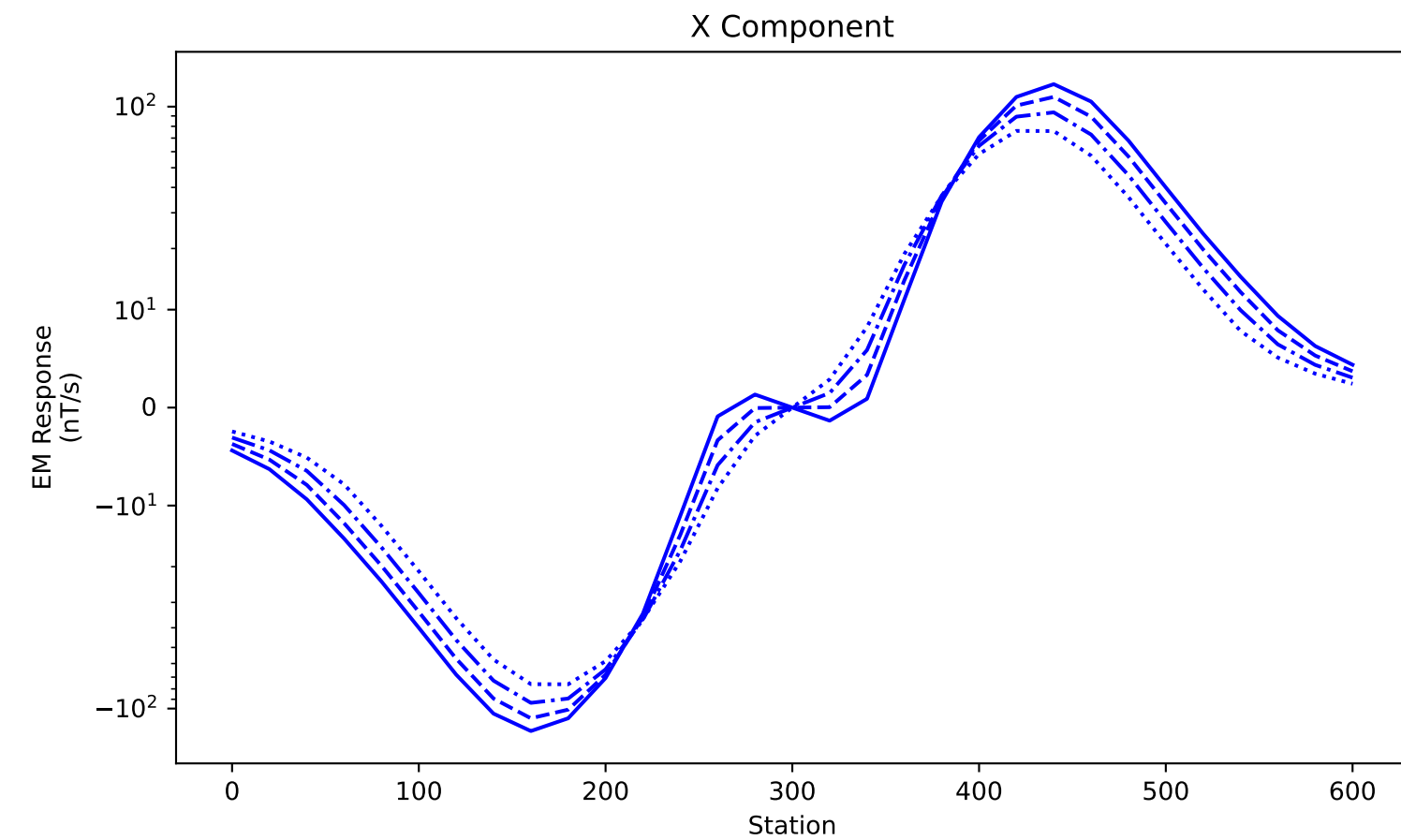
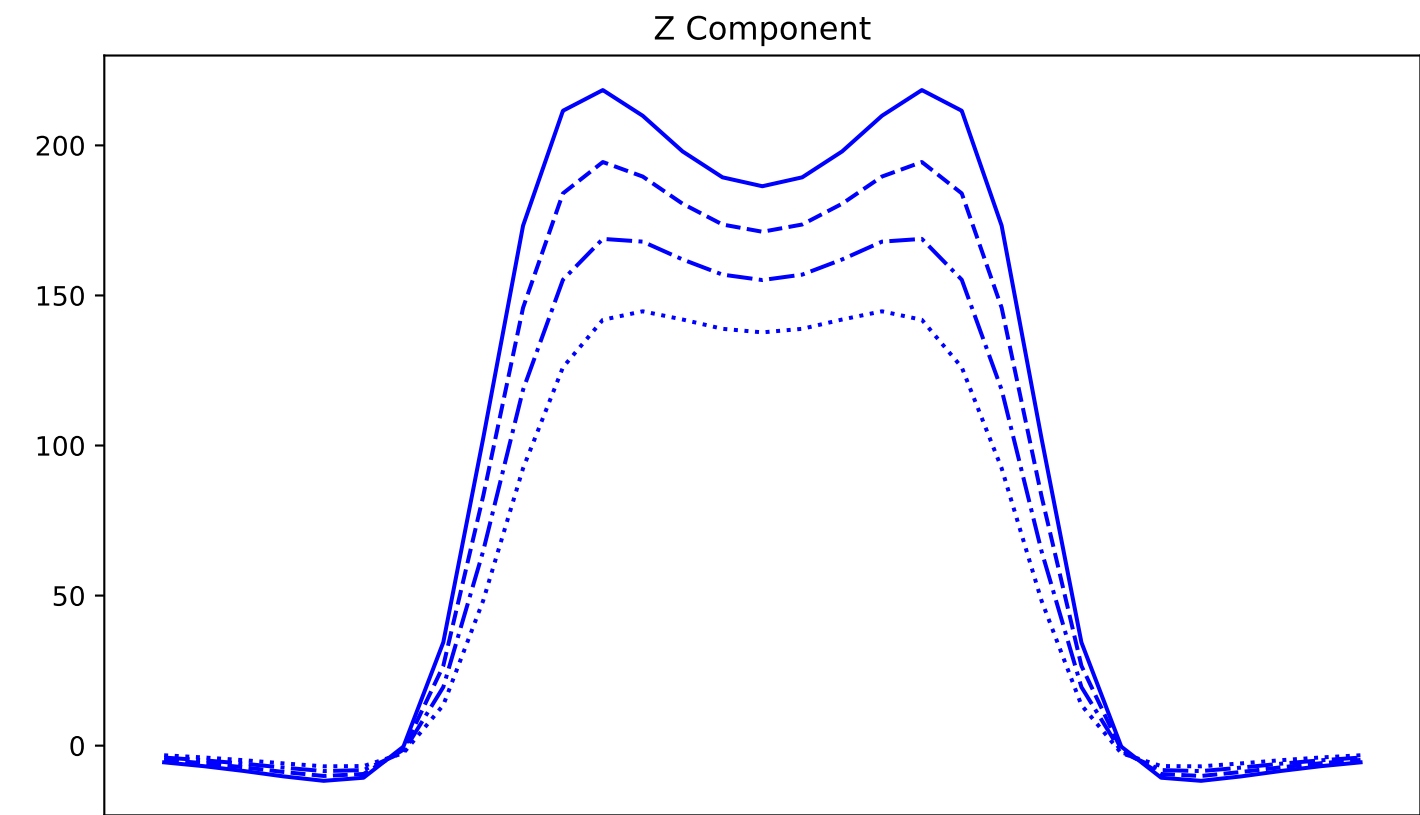
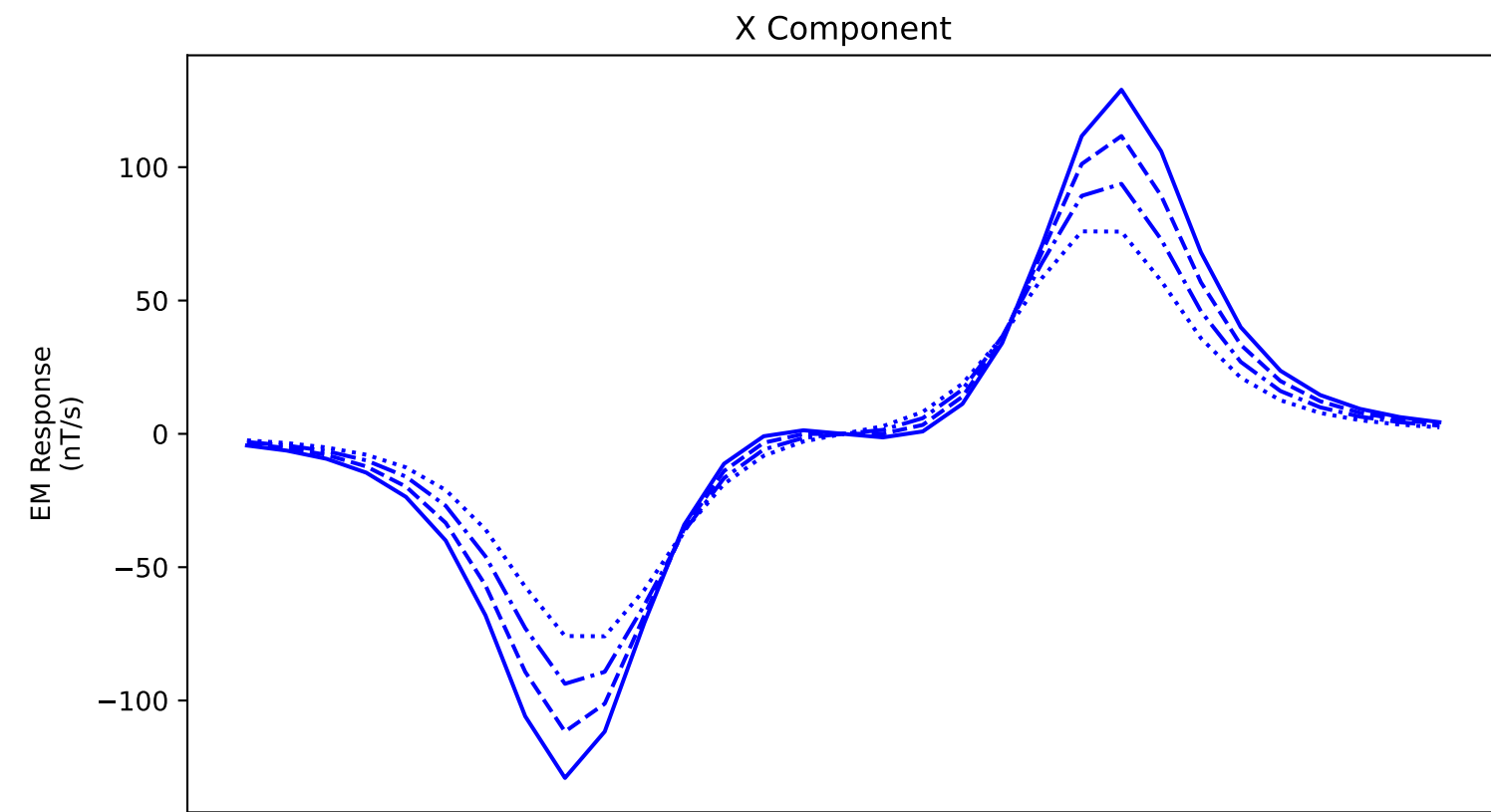
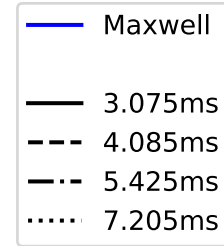
Two-Way Induction
300x100m, 1000S
LOOP=-100
0.56ms to 1.315ms



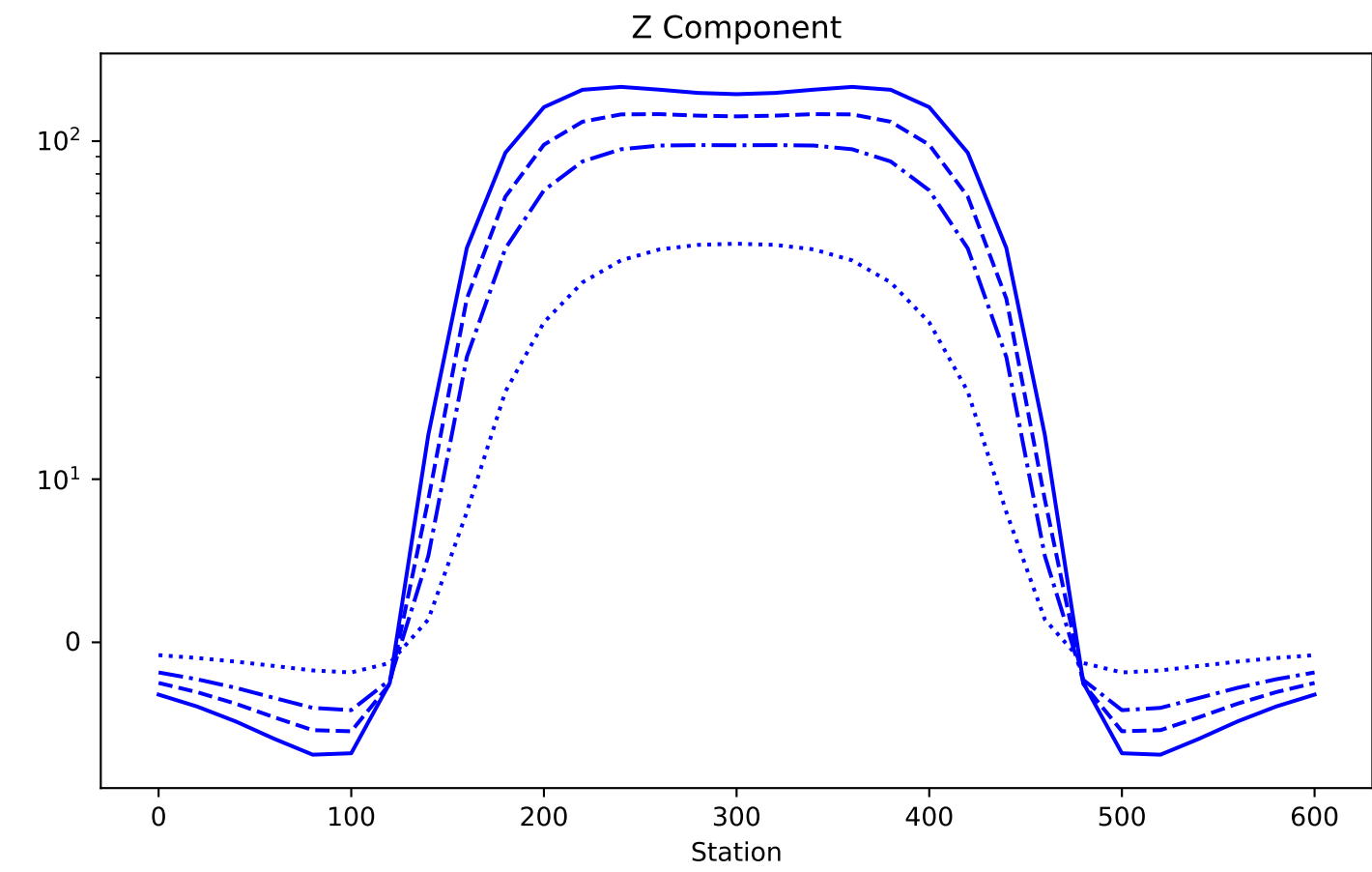
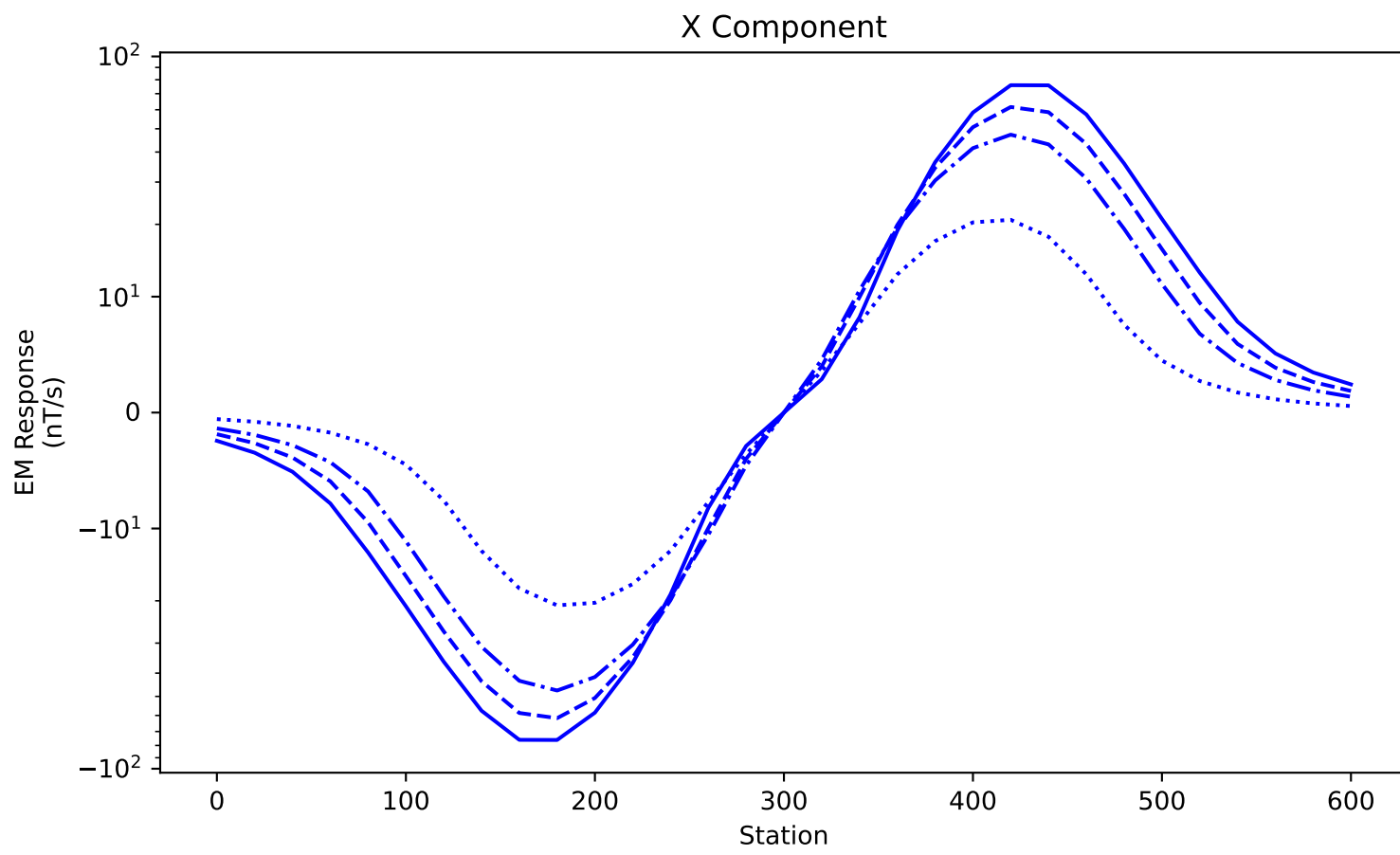
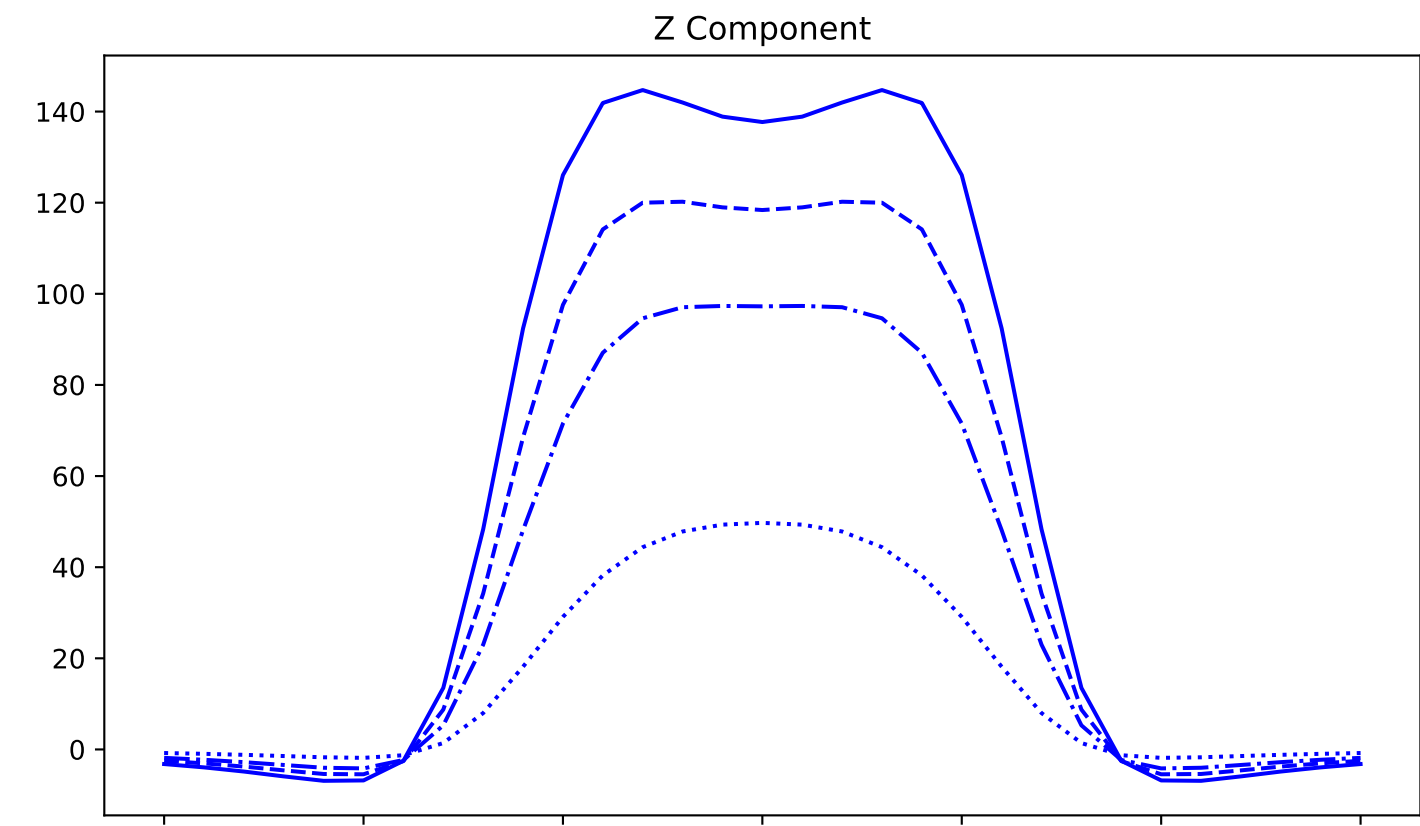
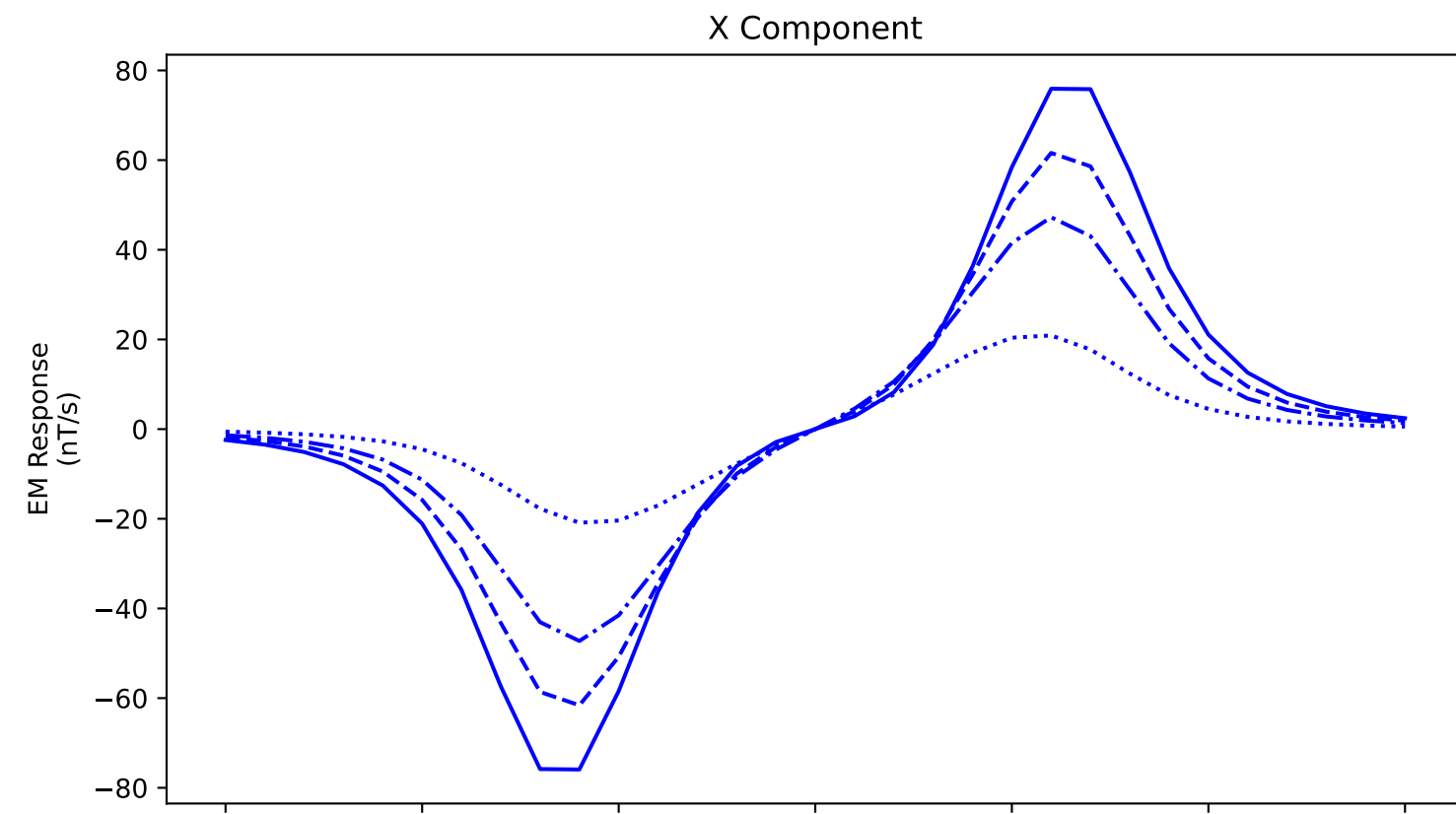
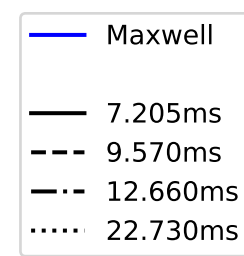
Two-Way Induction
300x100m, 1000S
LOOP=-100
1.315ms to 3.075ms



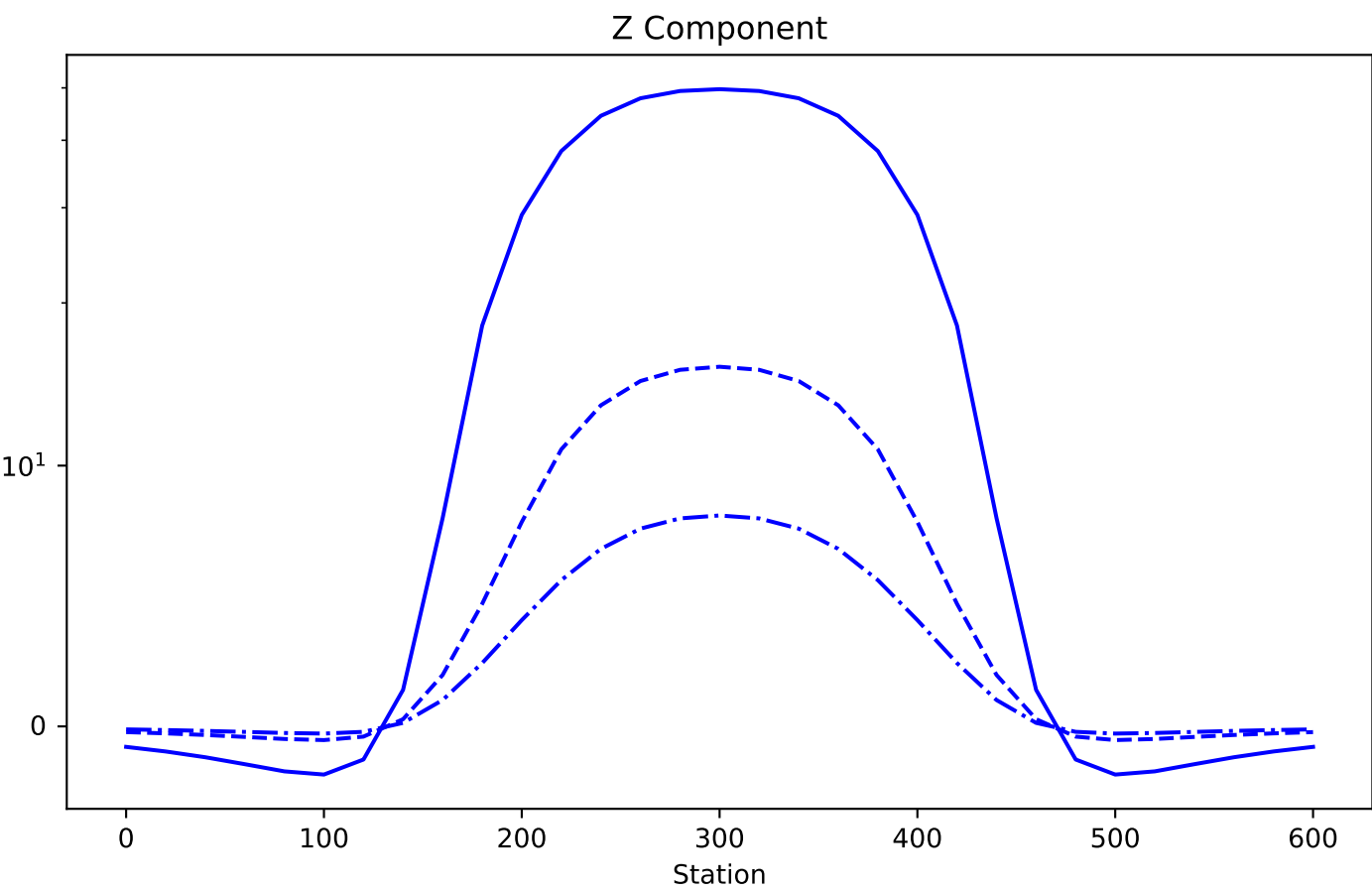
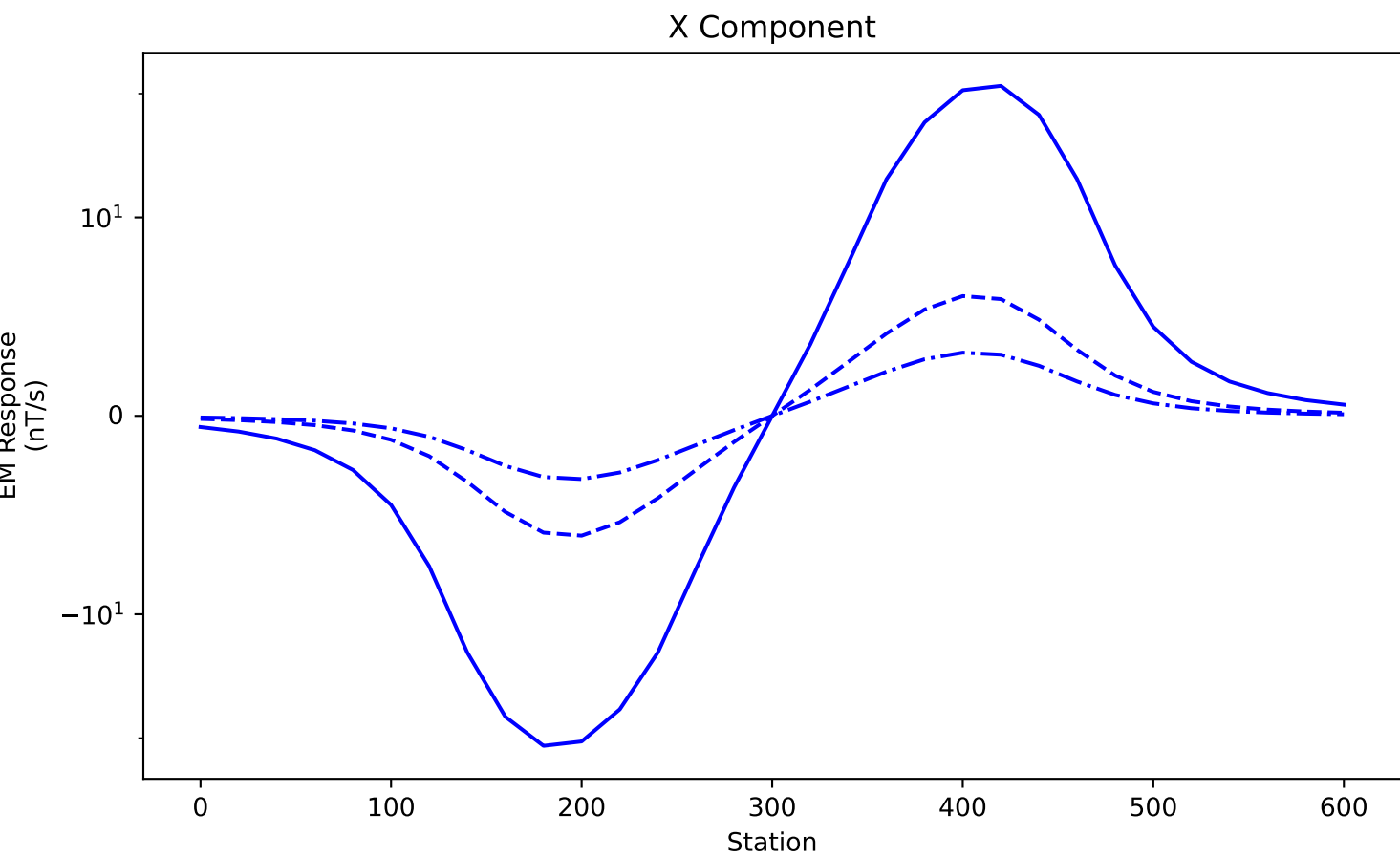
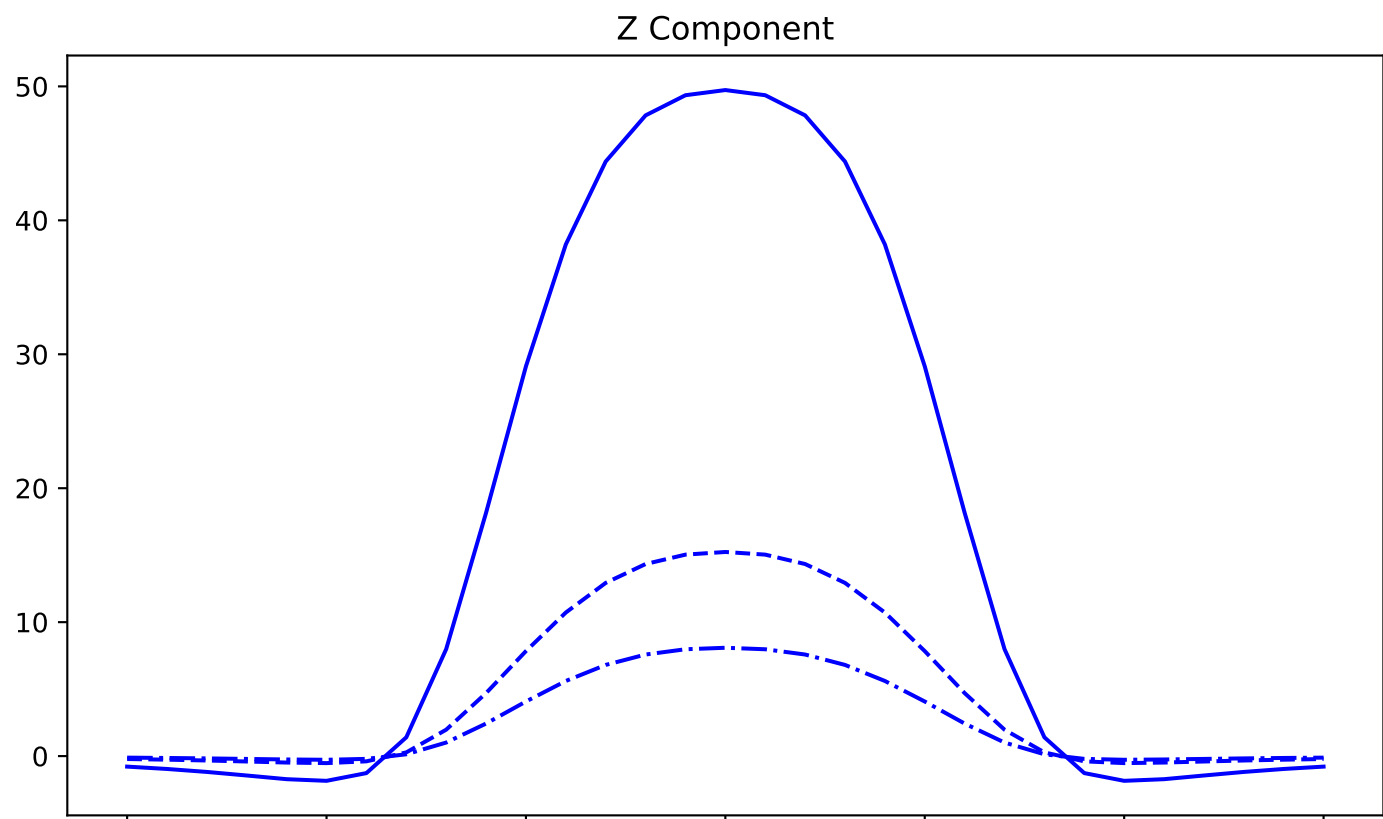
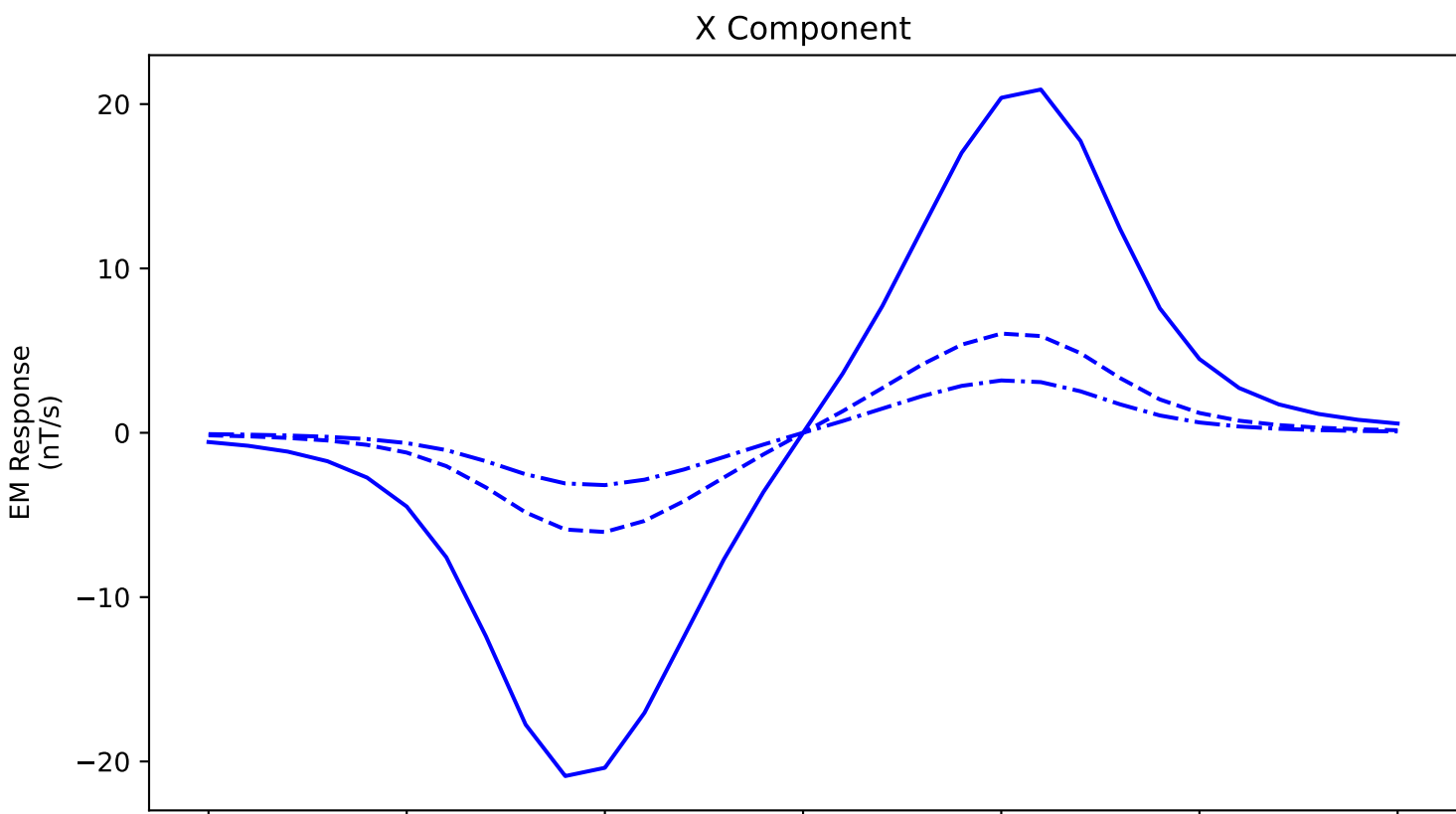
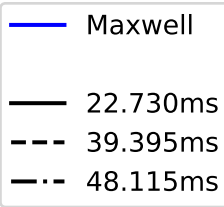
Two-Way Induction
300x100m, 1000S
LOOP=-100
3.075ms to 7.205ms



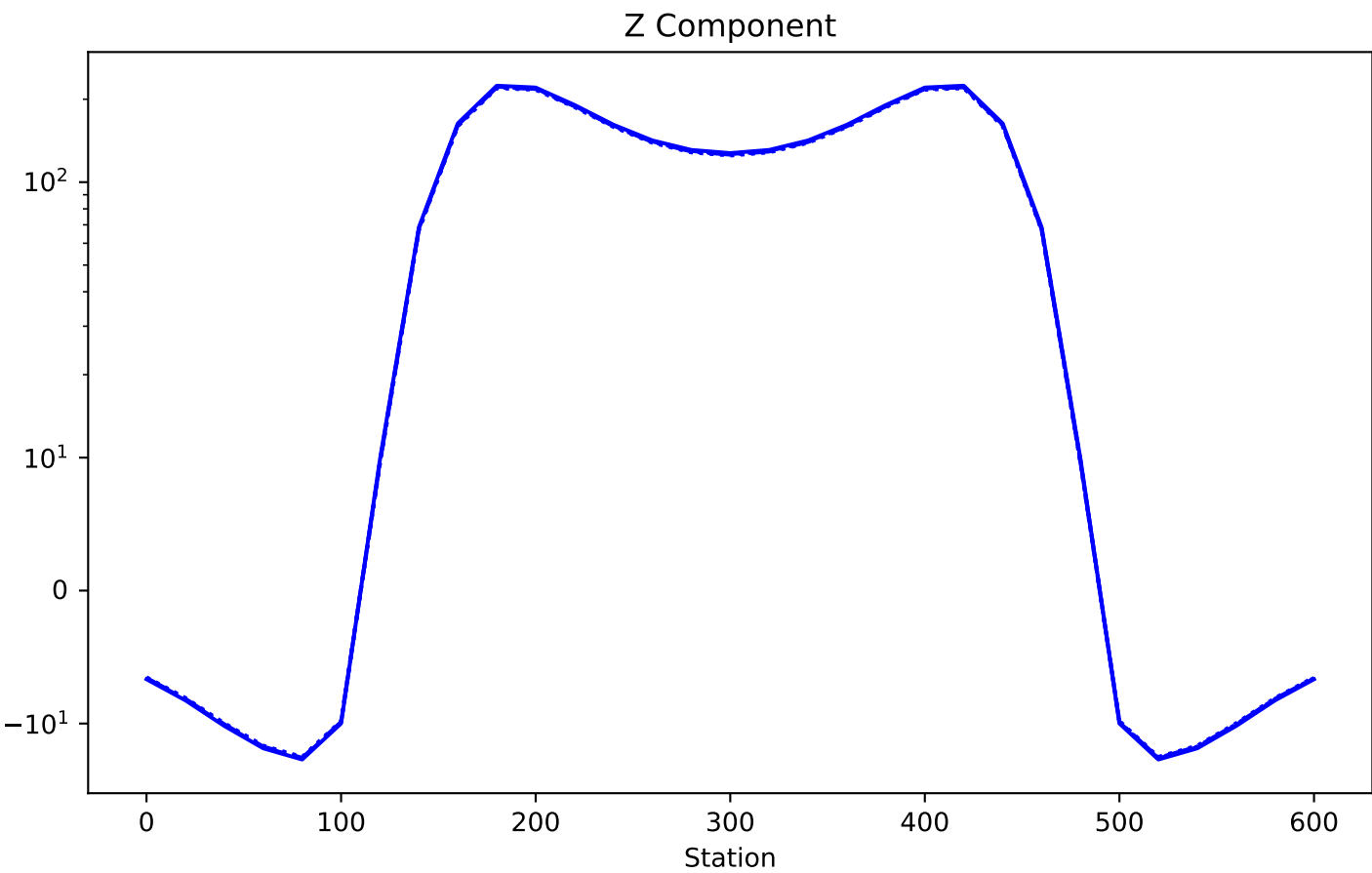
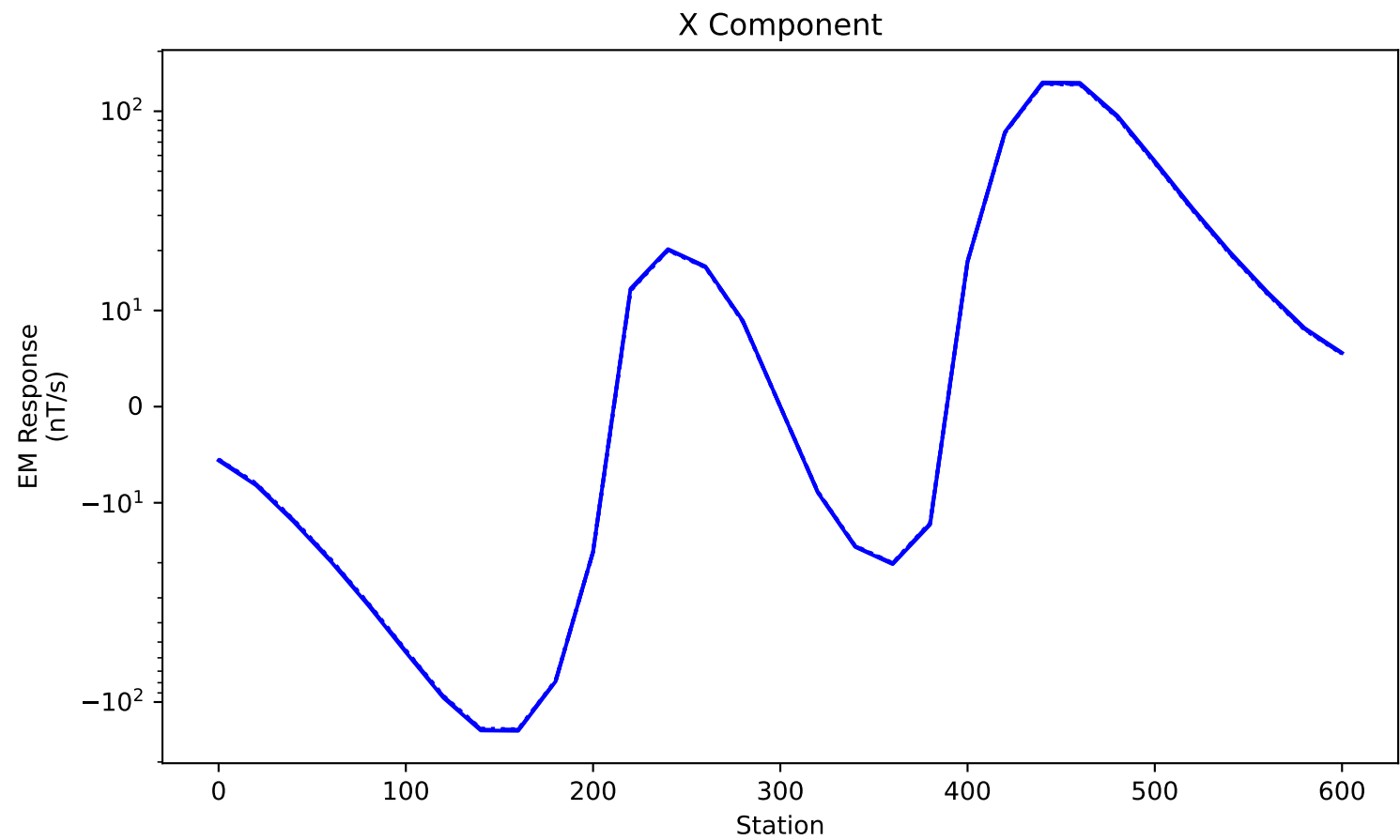
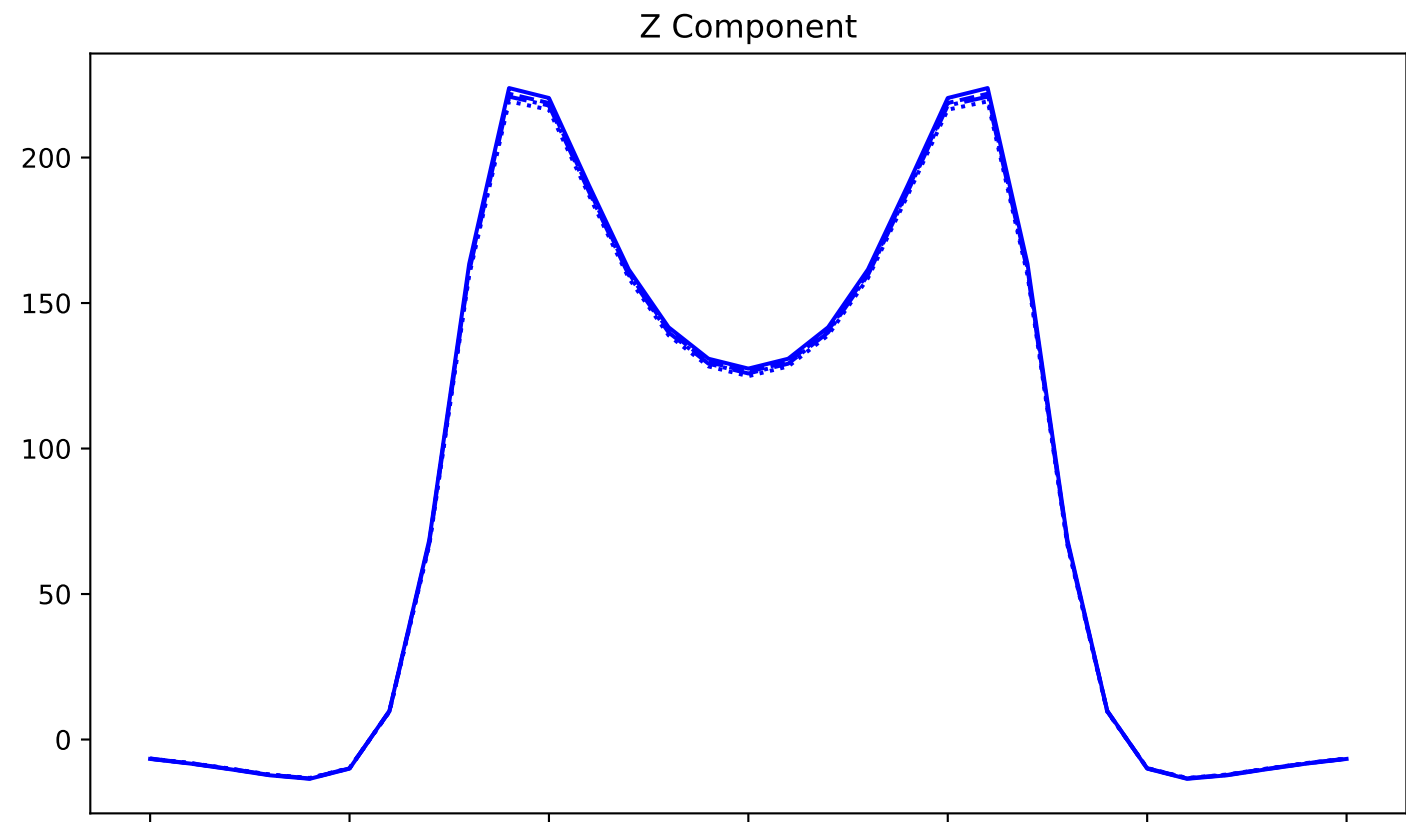
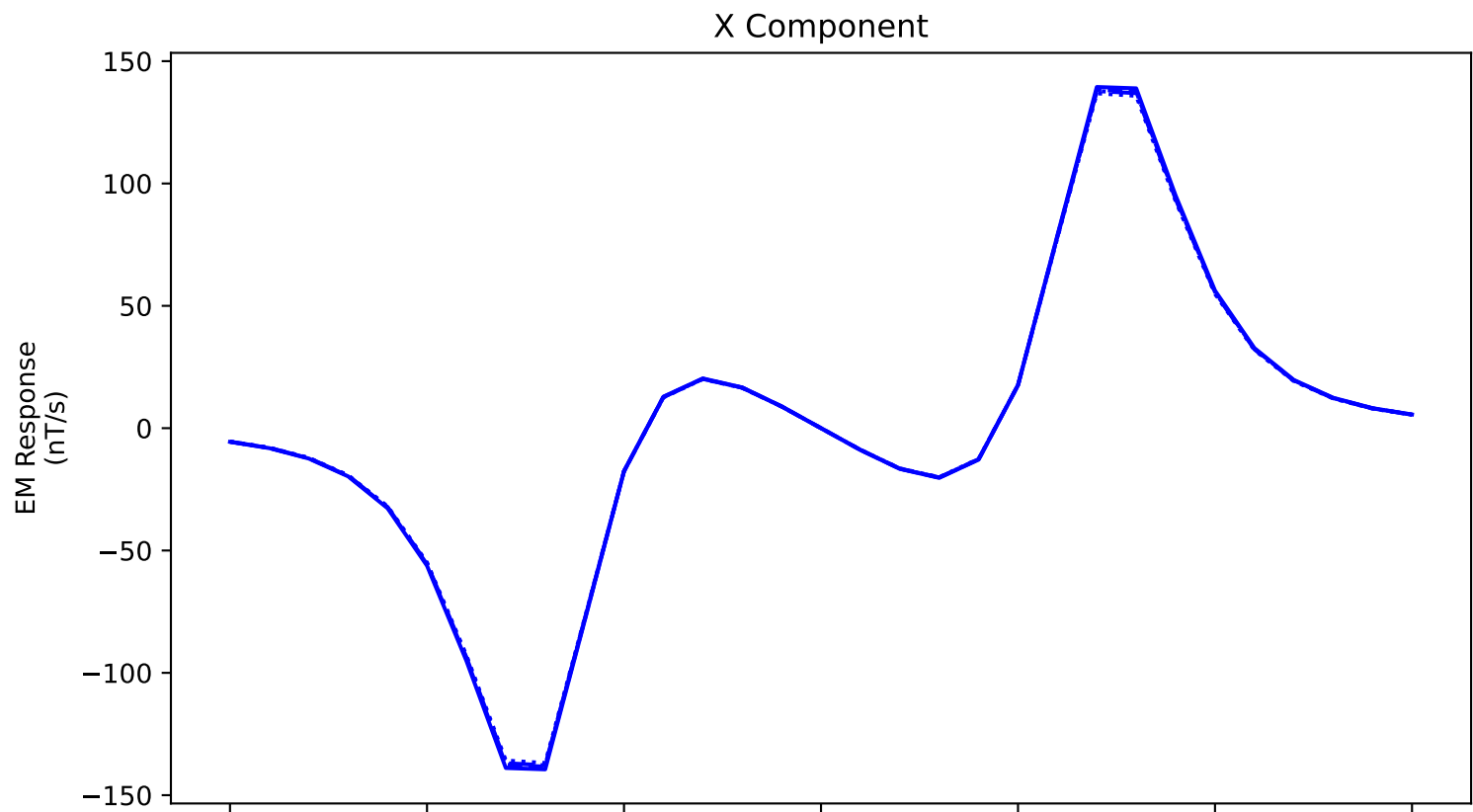
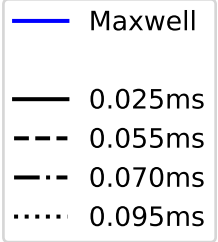
Two-Way Induction
300x100m, 1000S
LOOP=-100
7.205ms to 22.73ms



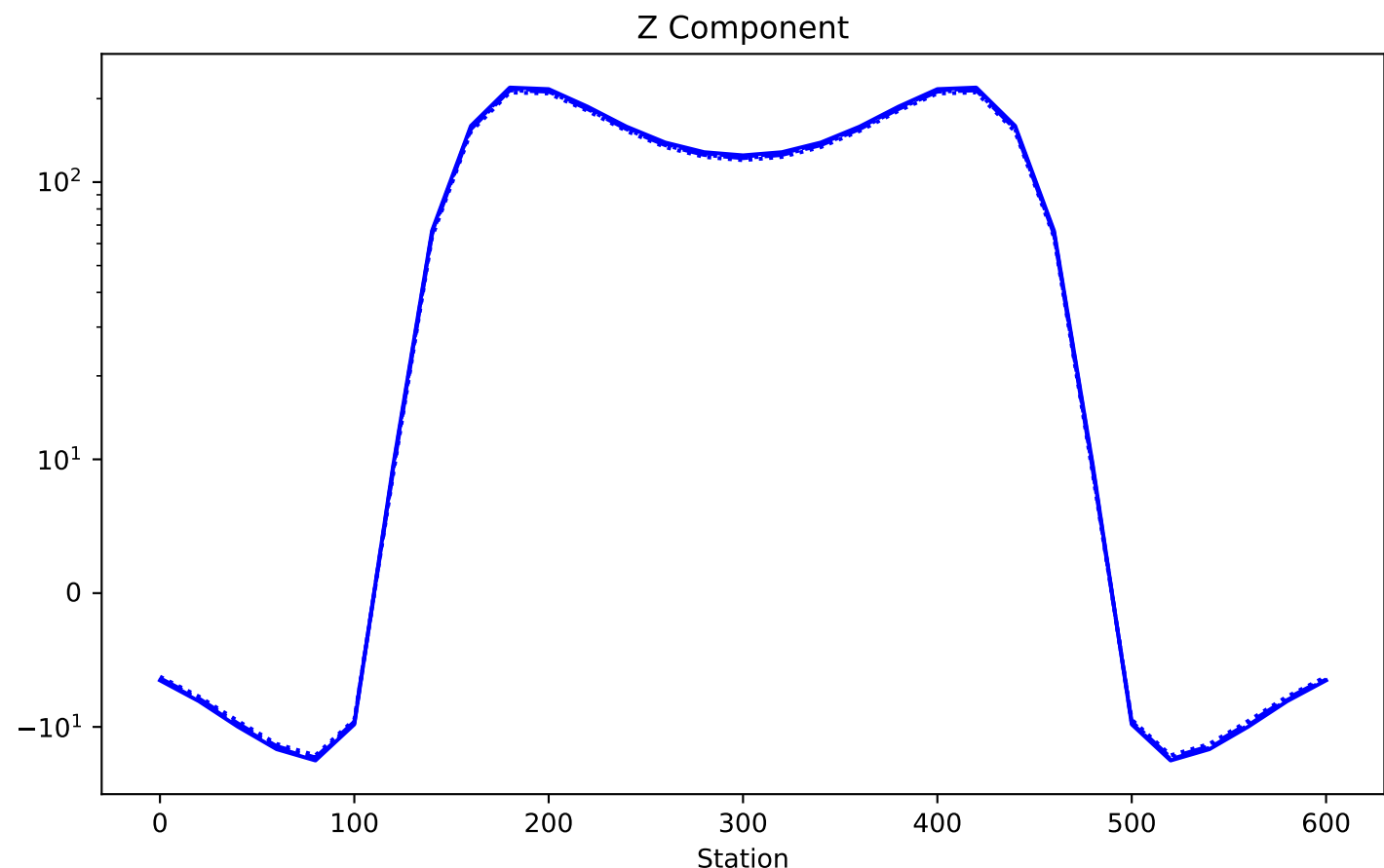
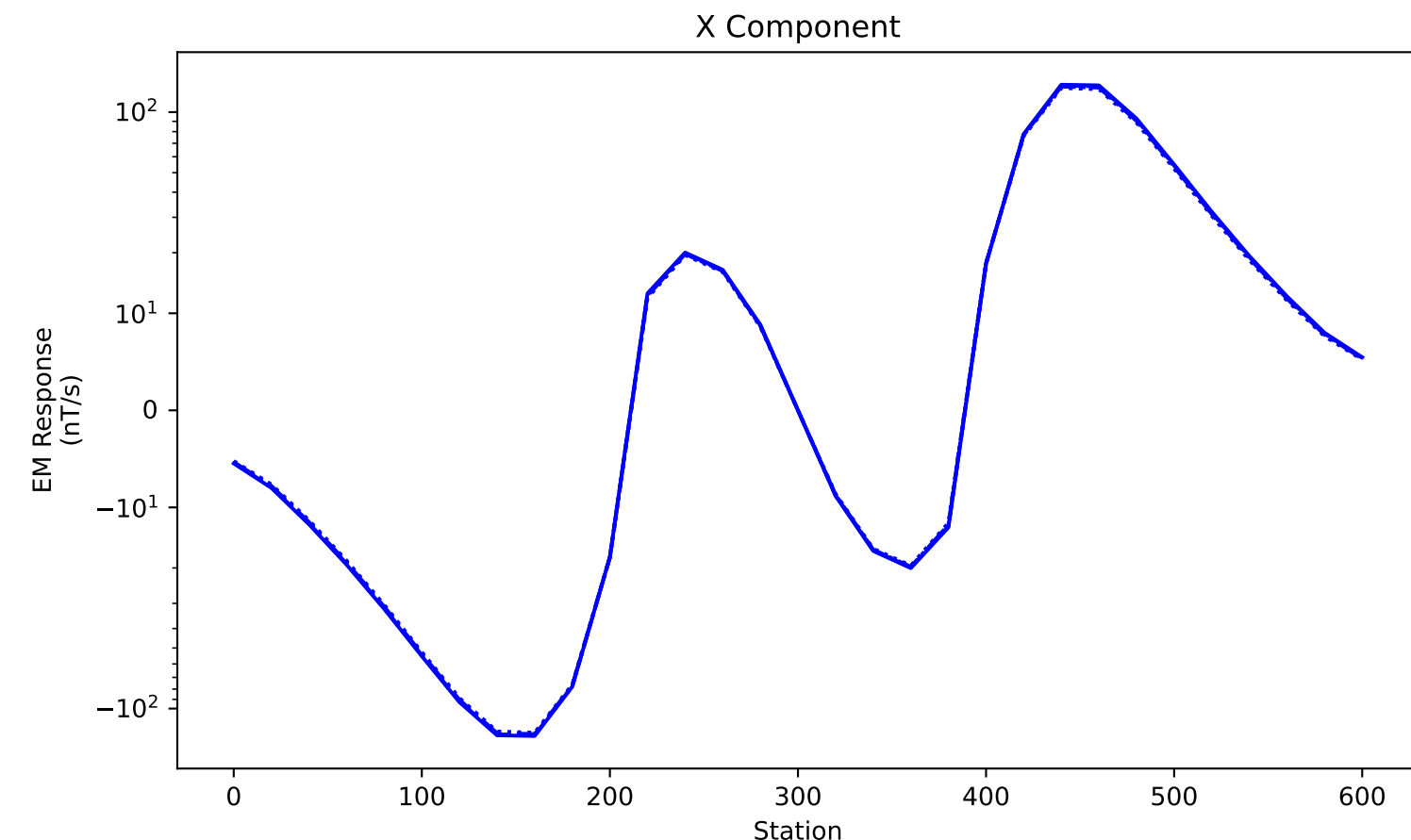
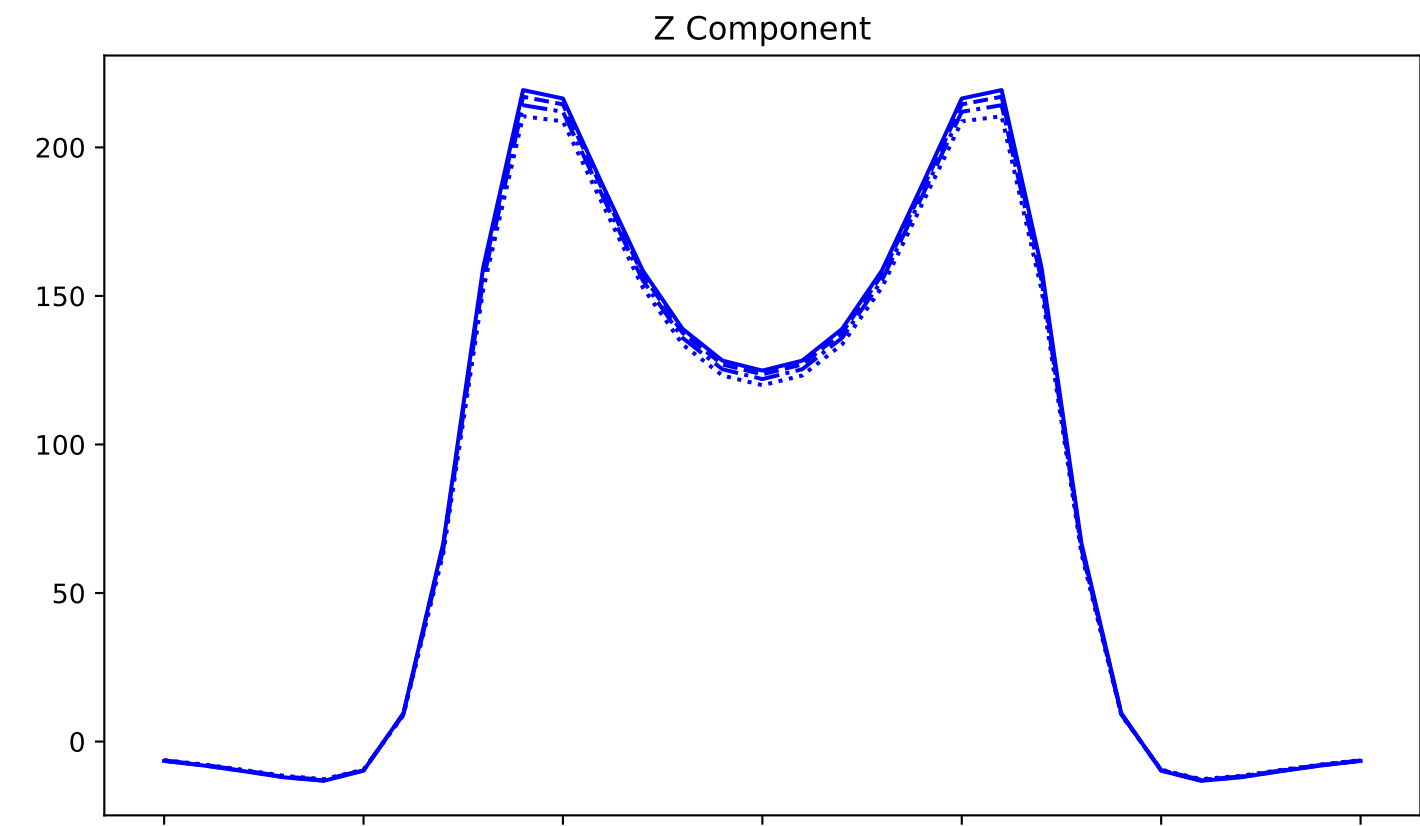
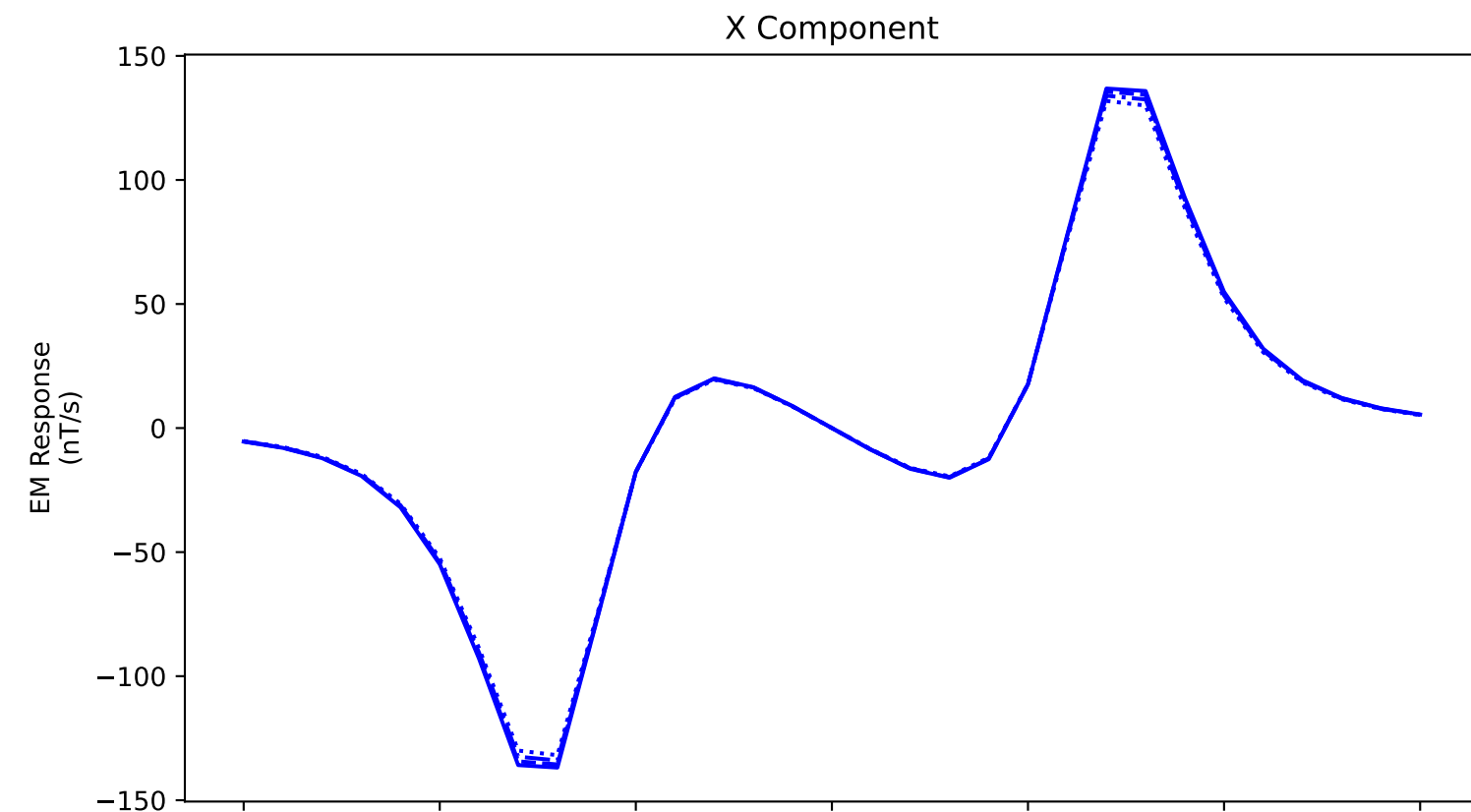
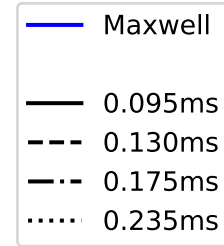
Two-Way Induction
300x100m, 1000S
LOOP=-100
22.73ms to 48.115ms



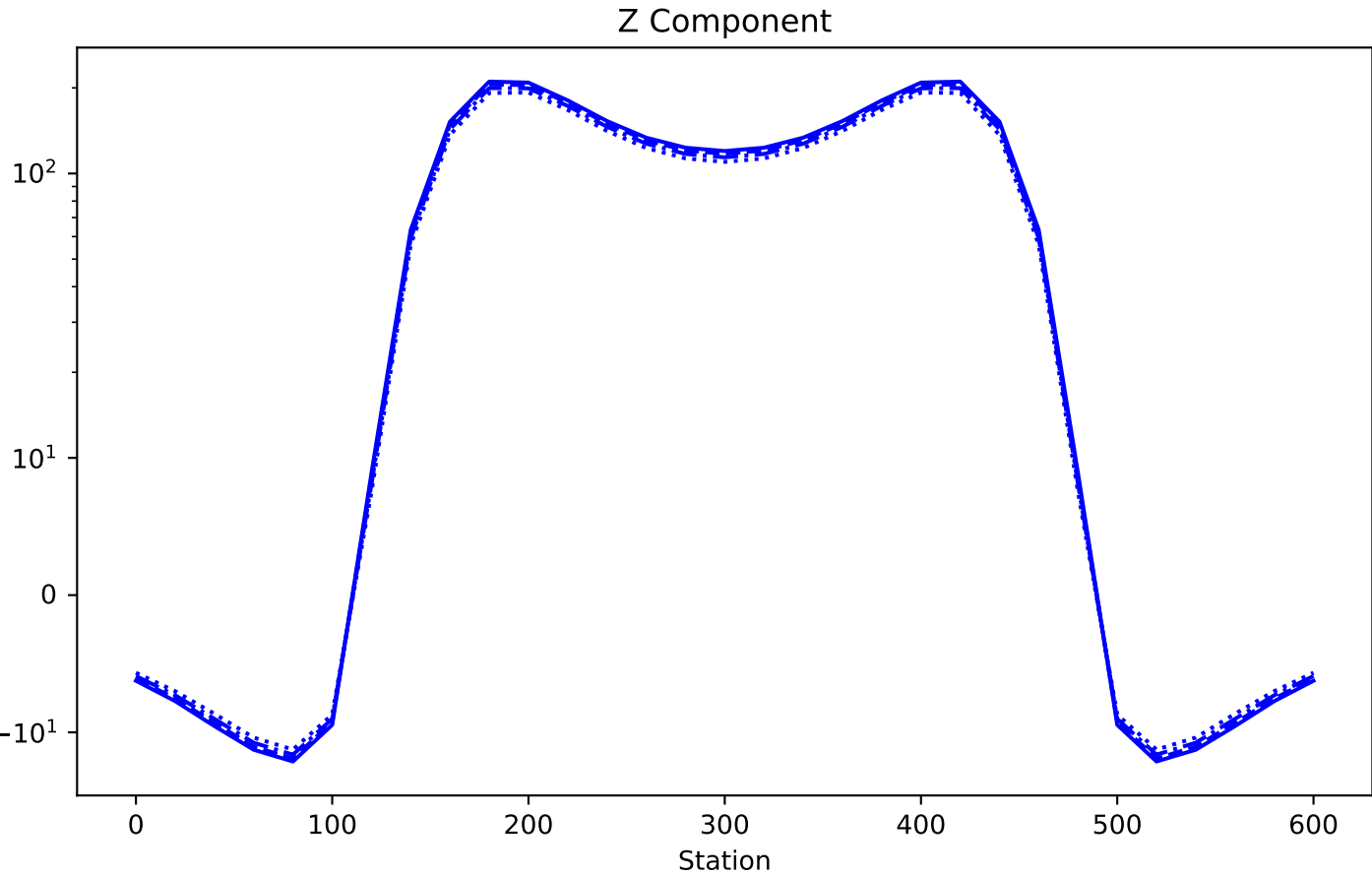
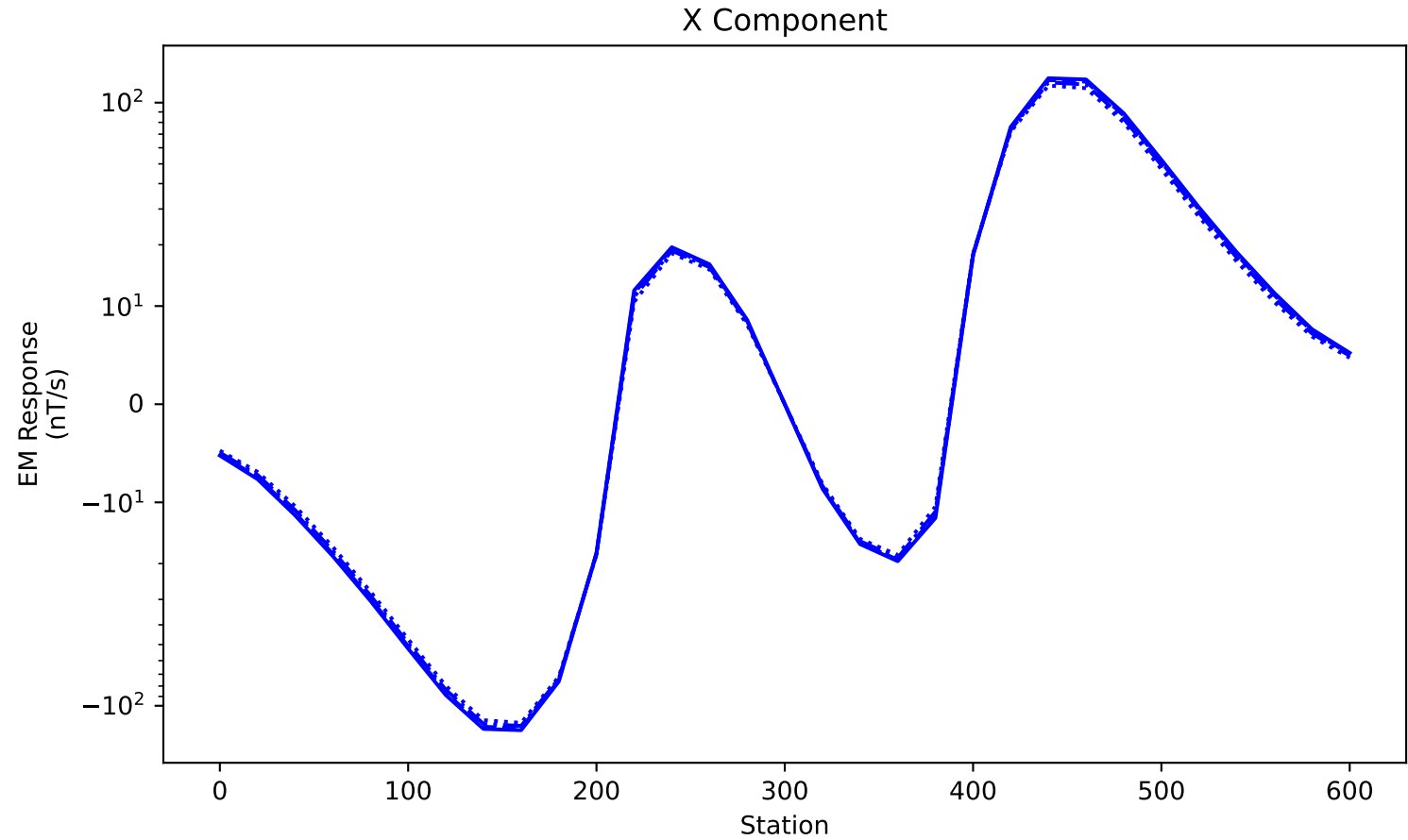
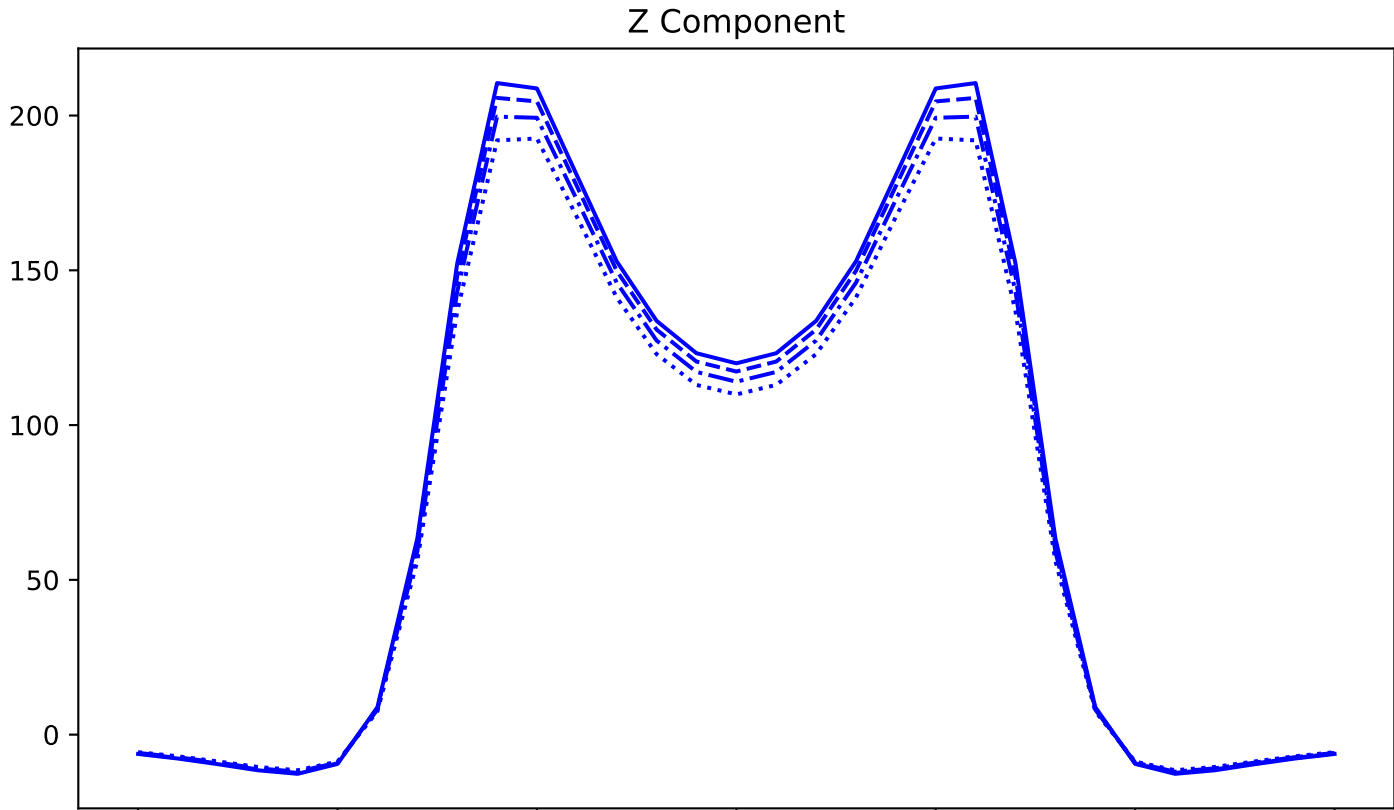
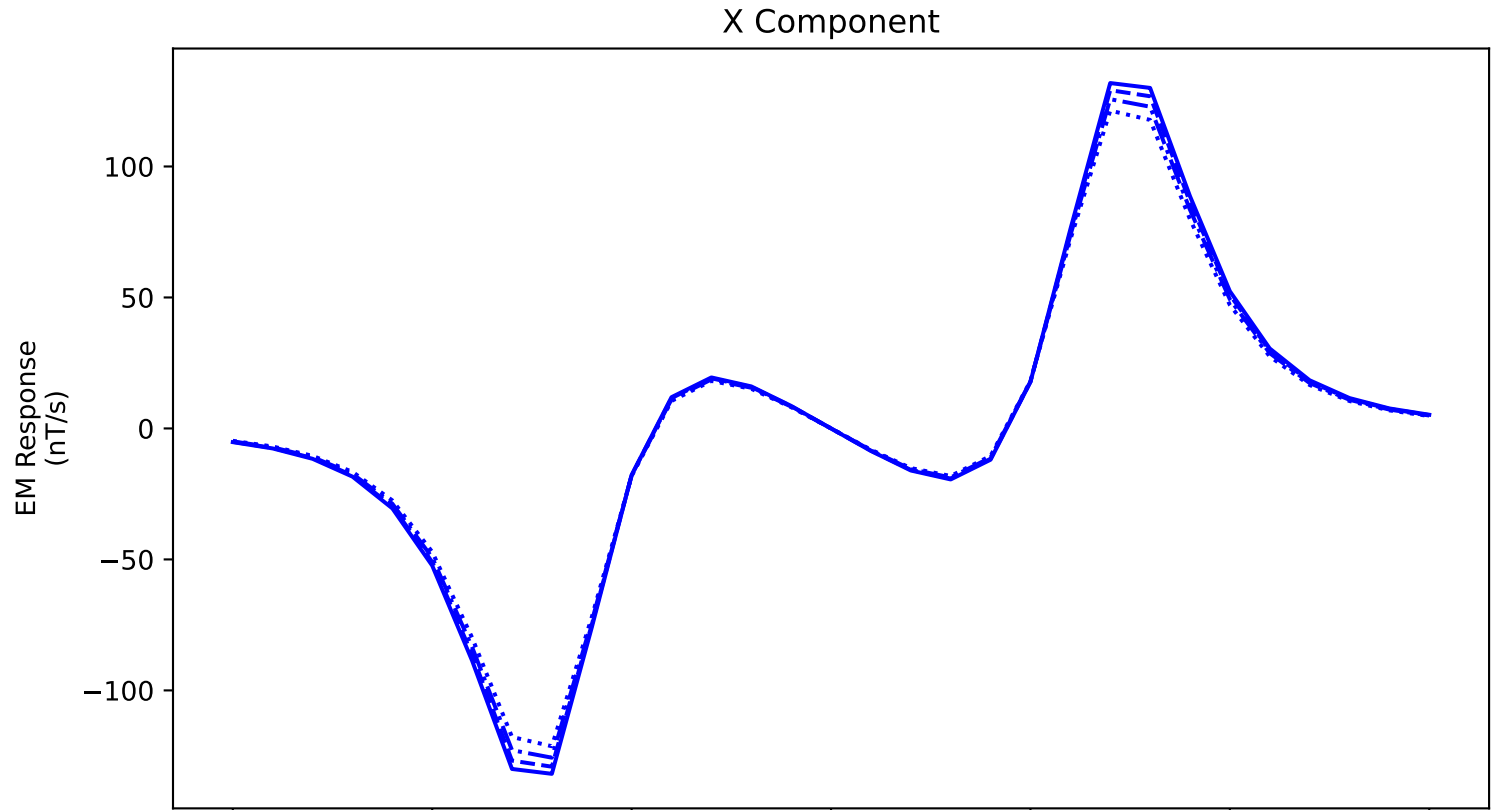
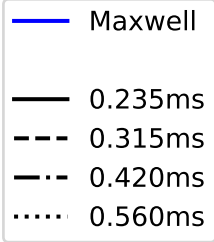
Two-Way Induction
300x100m, 1000S
LOOP=-150
0.0255ms to 0.095ms



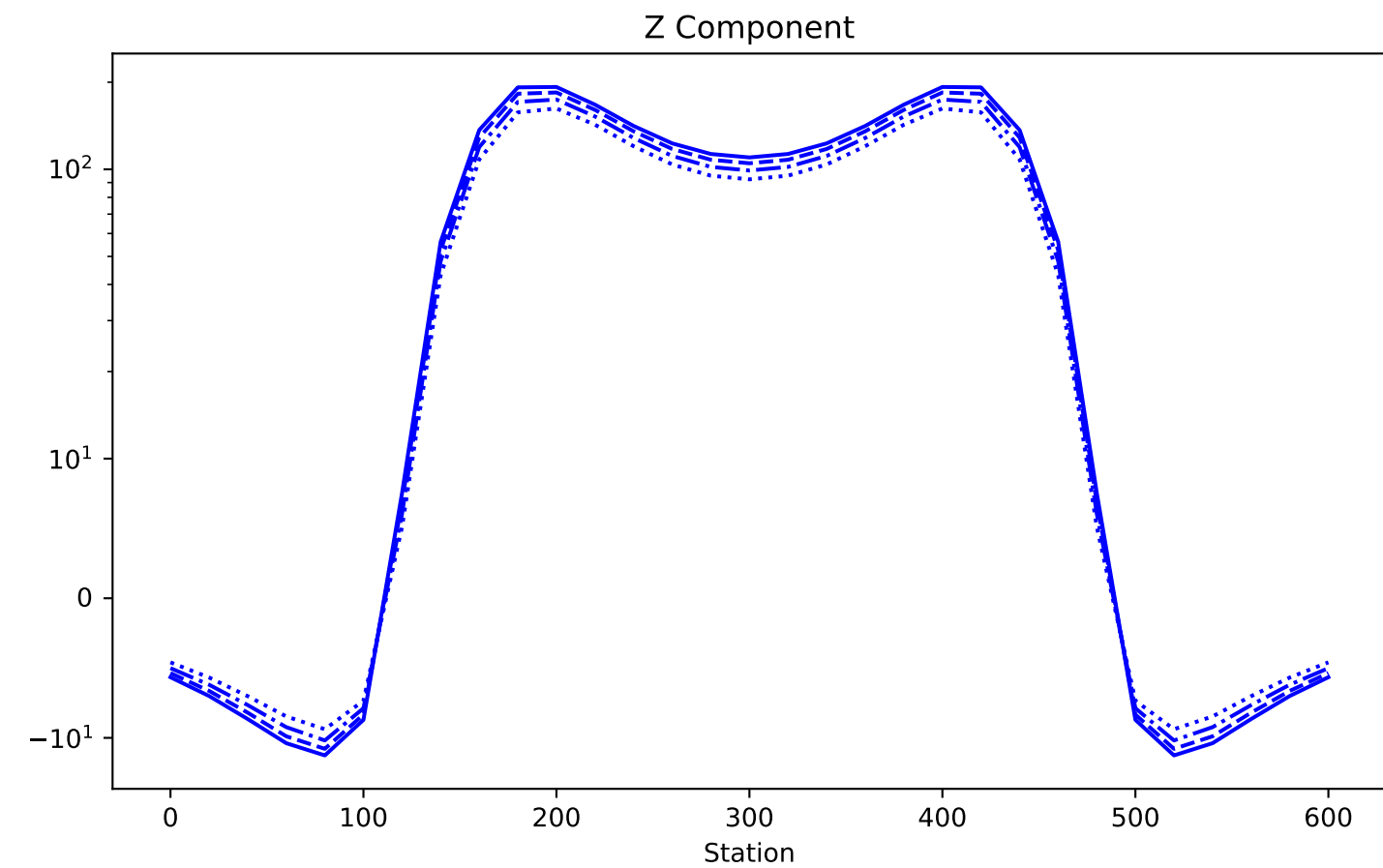
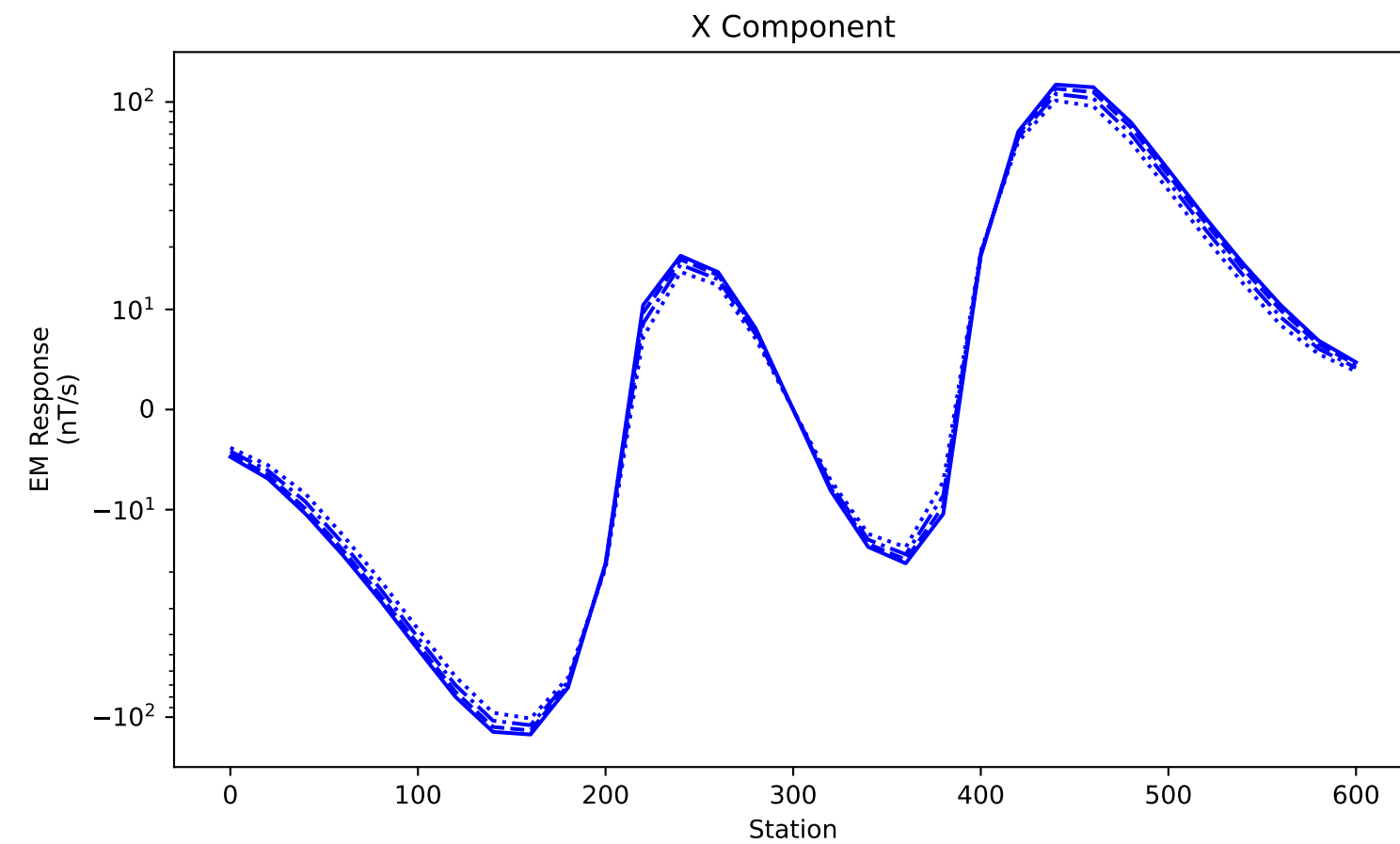
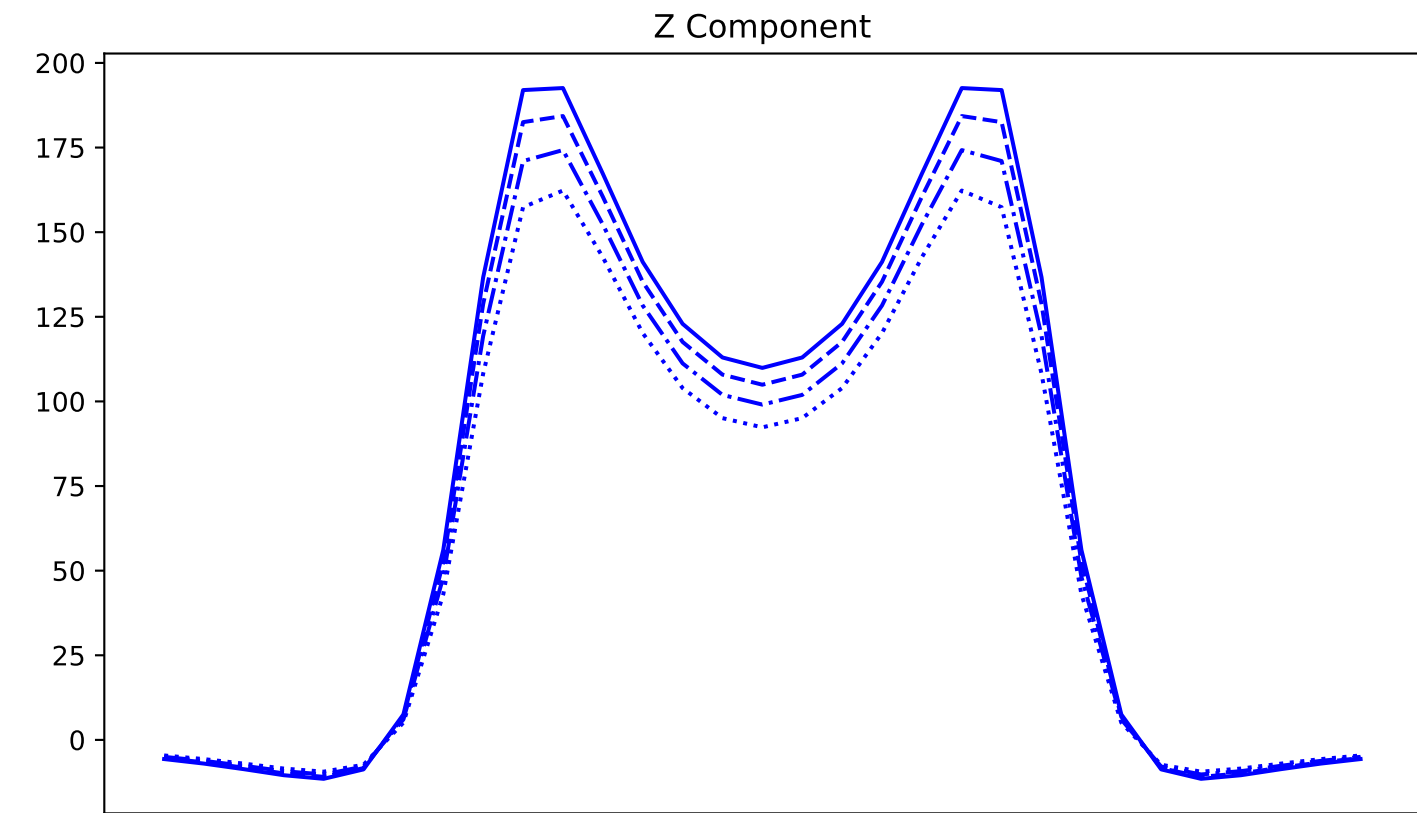
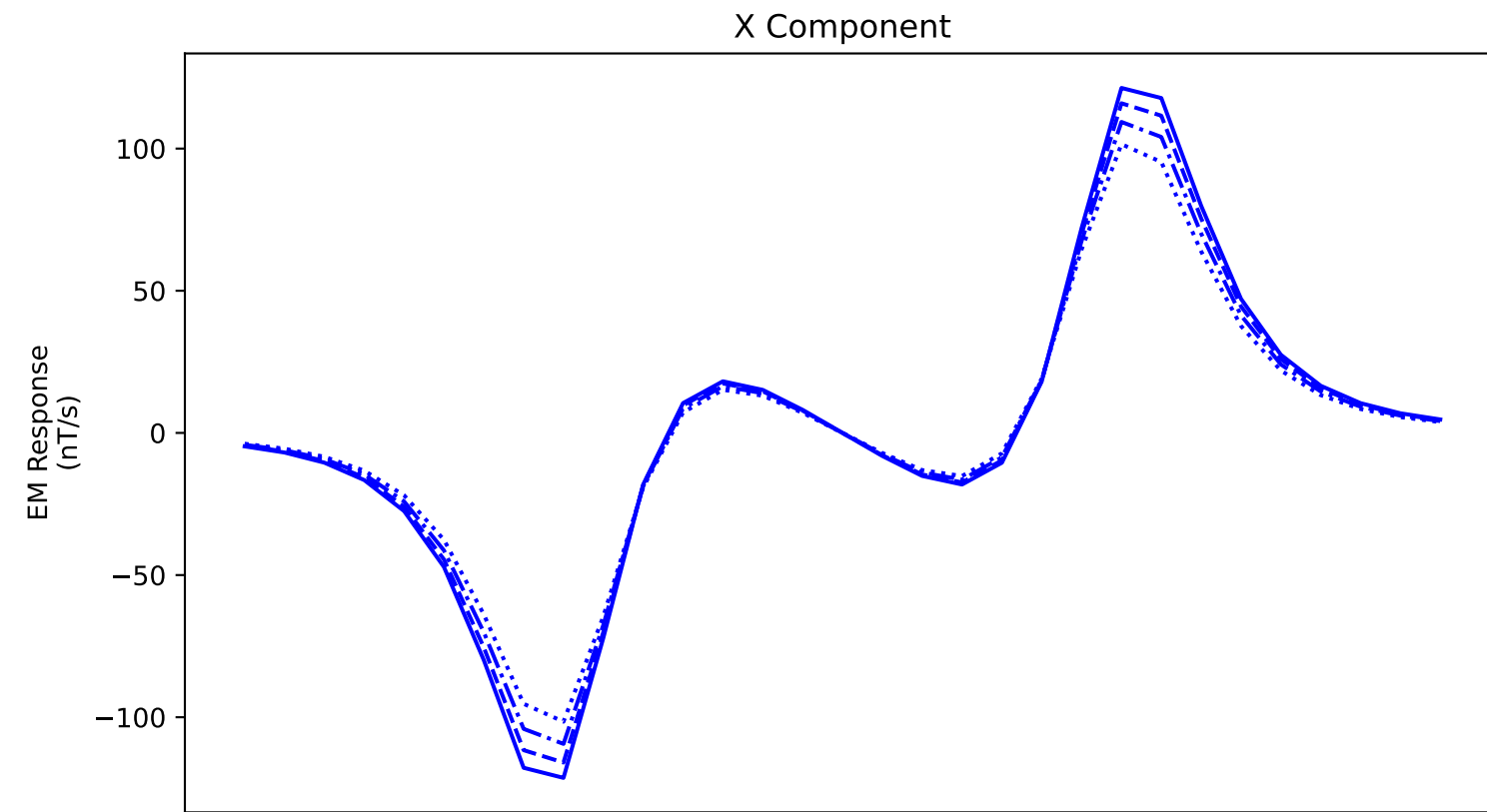
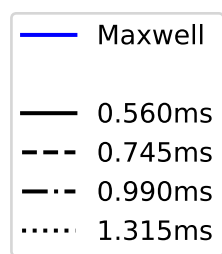
Two-Way Induction
300x100m, 1000S
LOOP=-150
0.095ms to 0.235ms



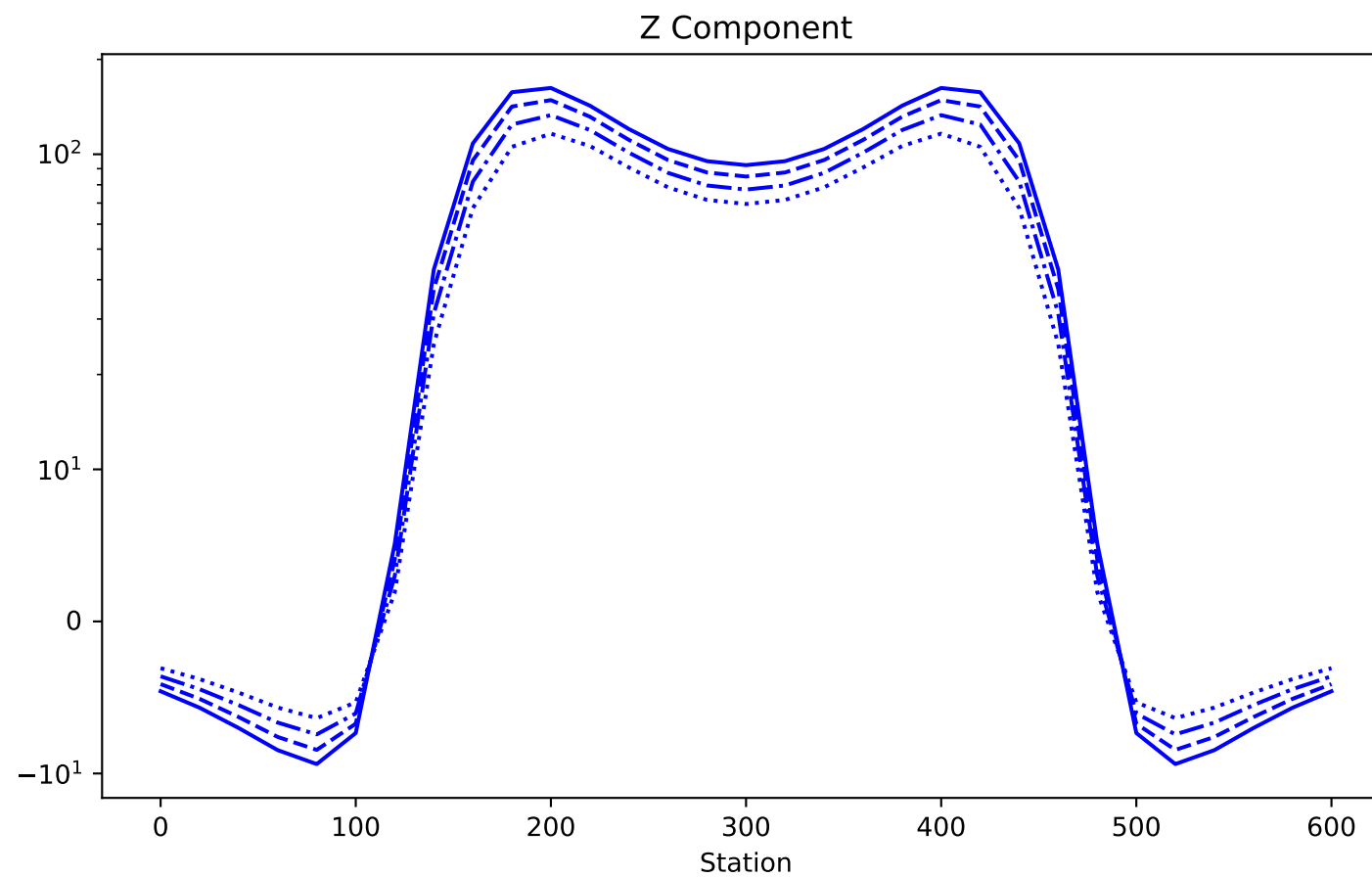
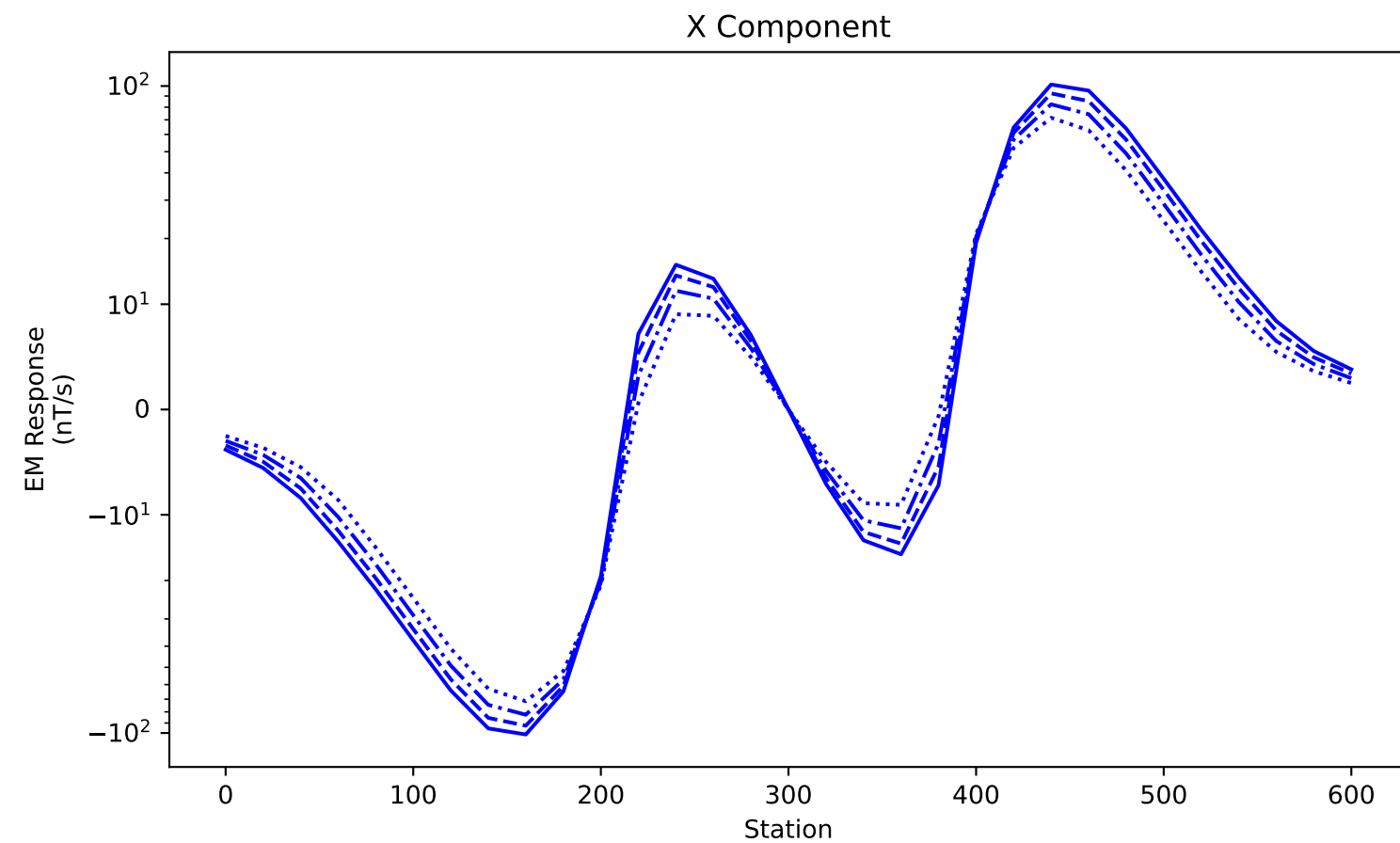
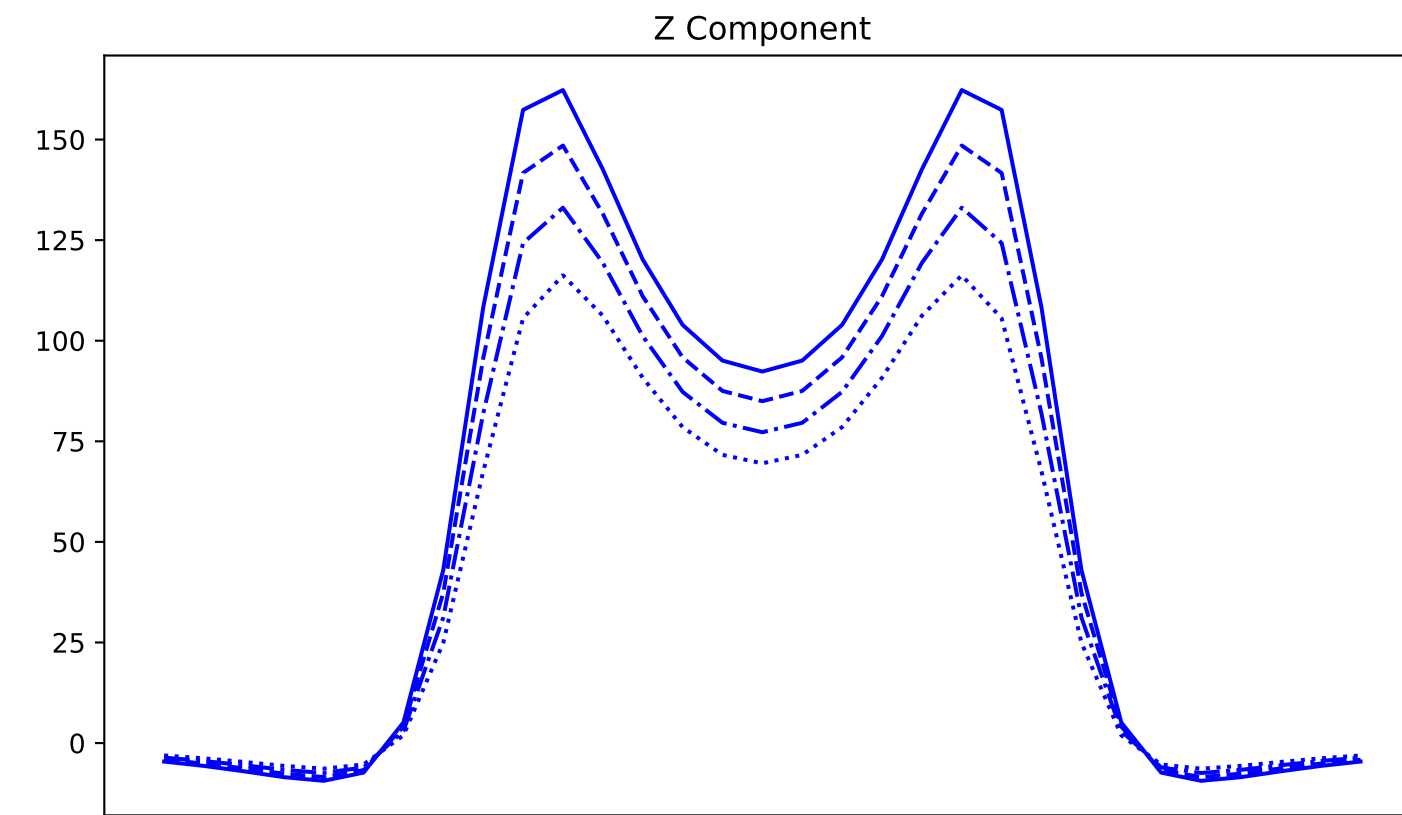
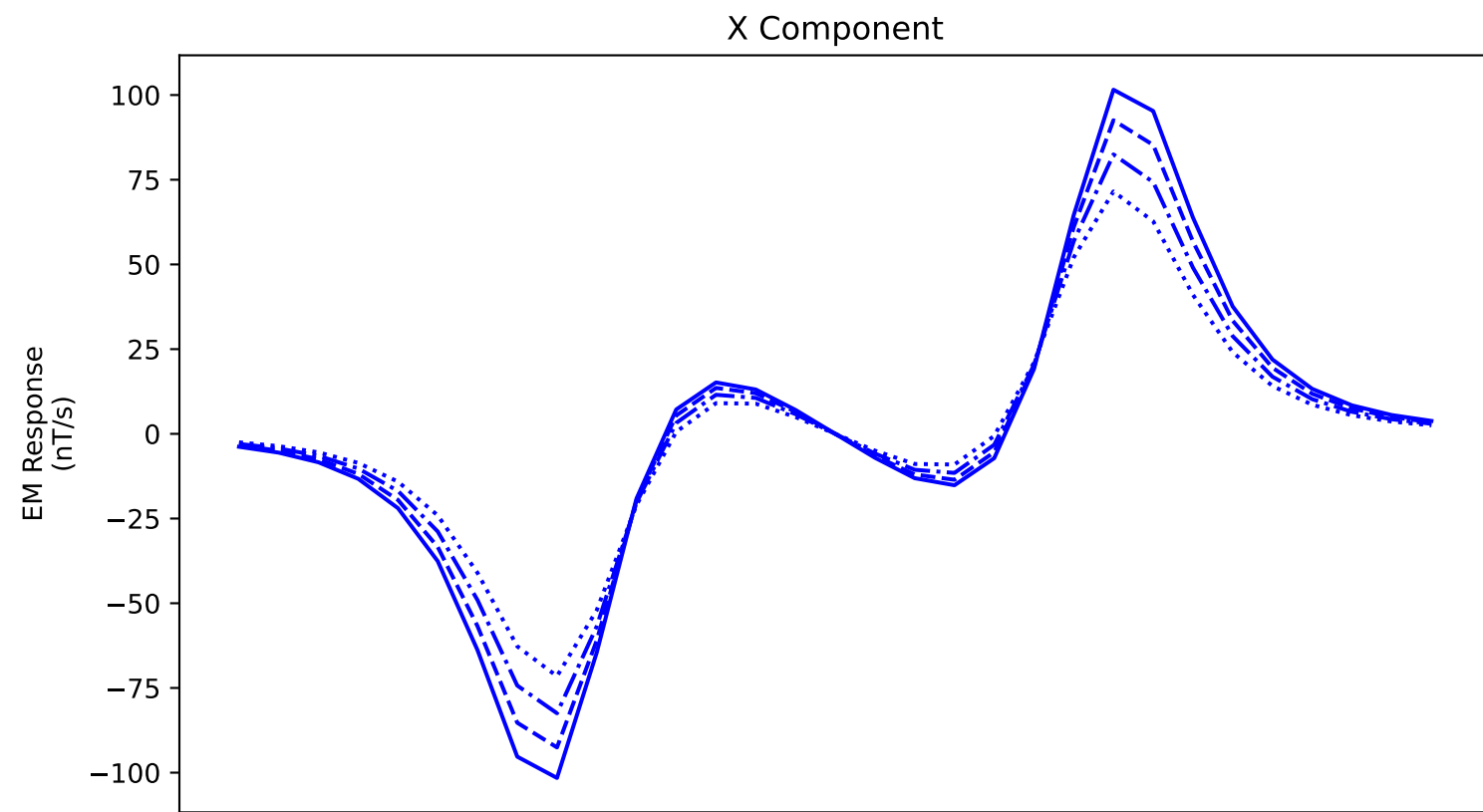
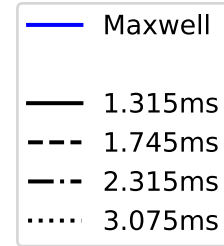
Two-Way Induction
300x100m, 1000S
LOOP=-150
0.235ms to 0.56ms



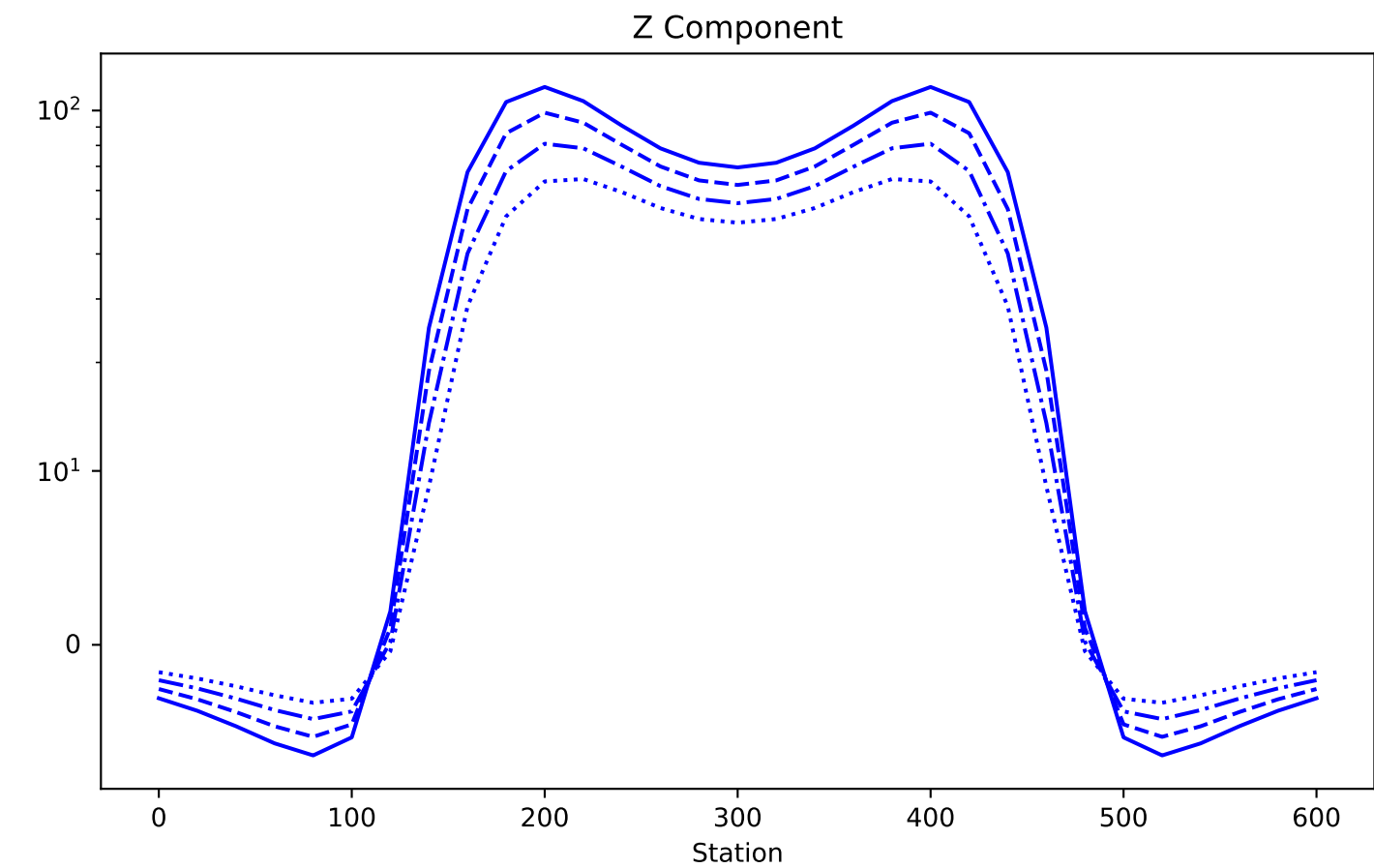
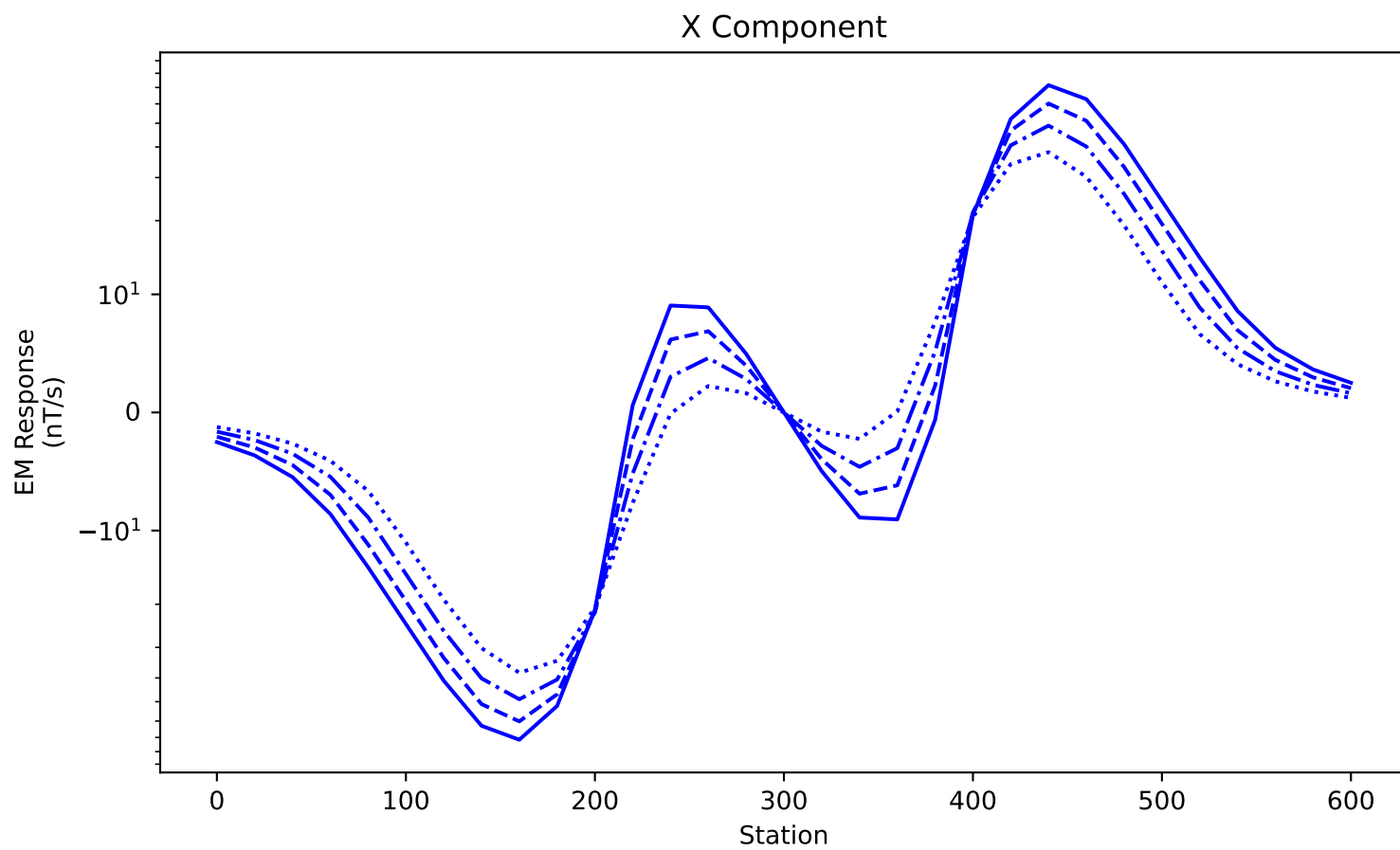
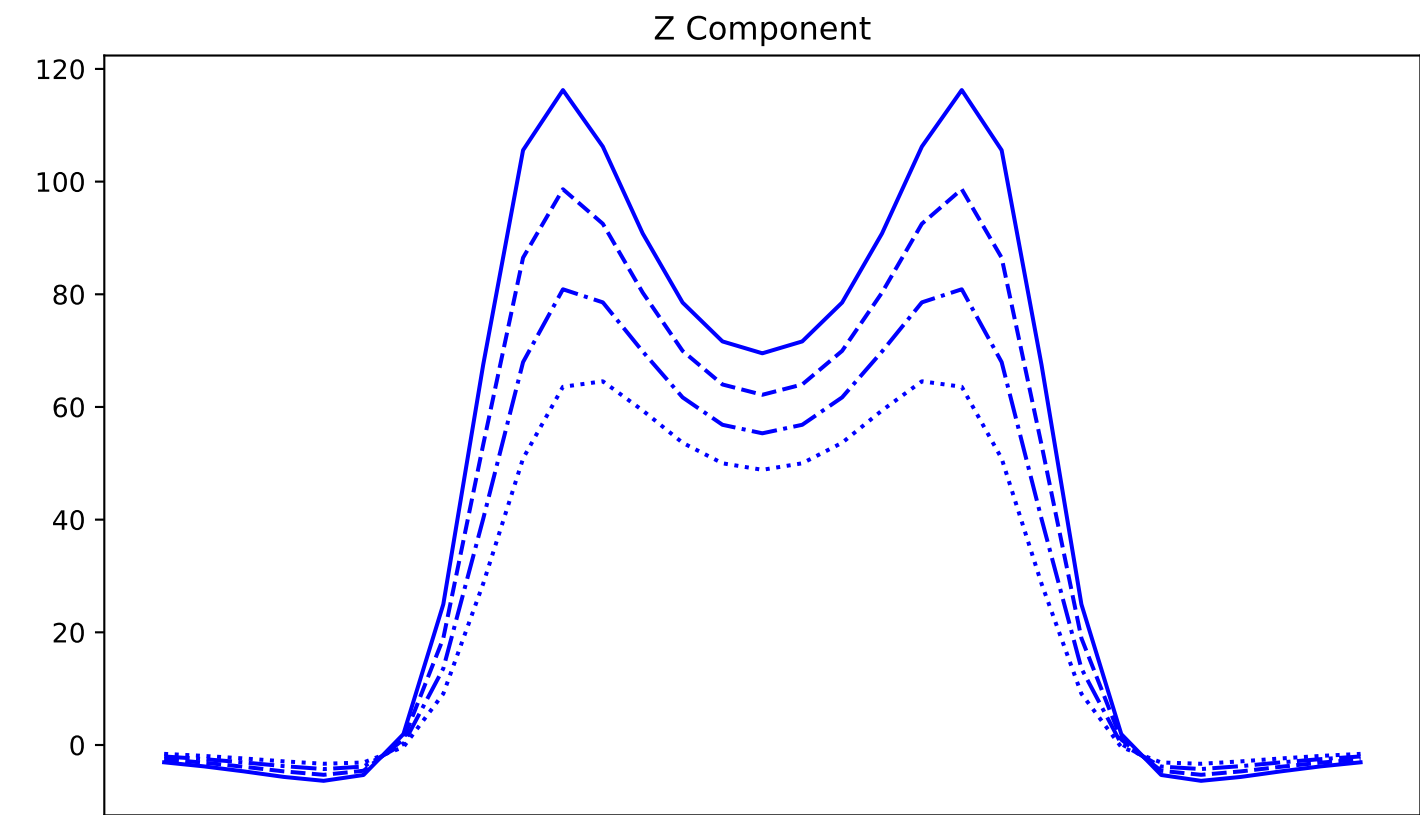
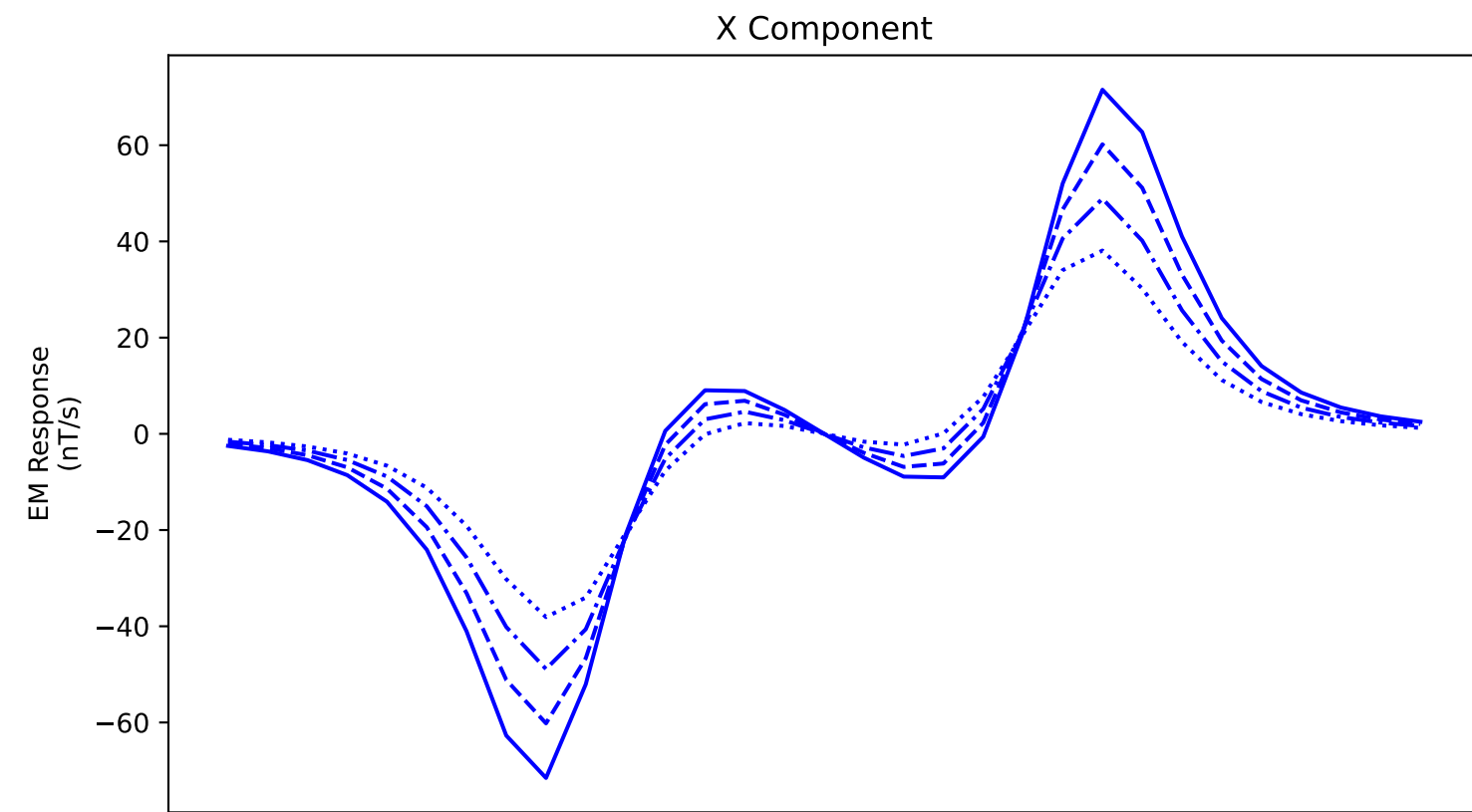
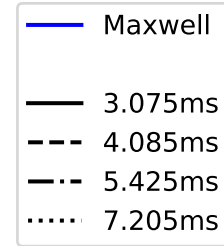
Two-Way Induction
300x100m, 1000S
LOOP=-150
0.56ms to 1.315ms



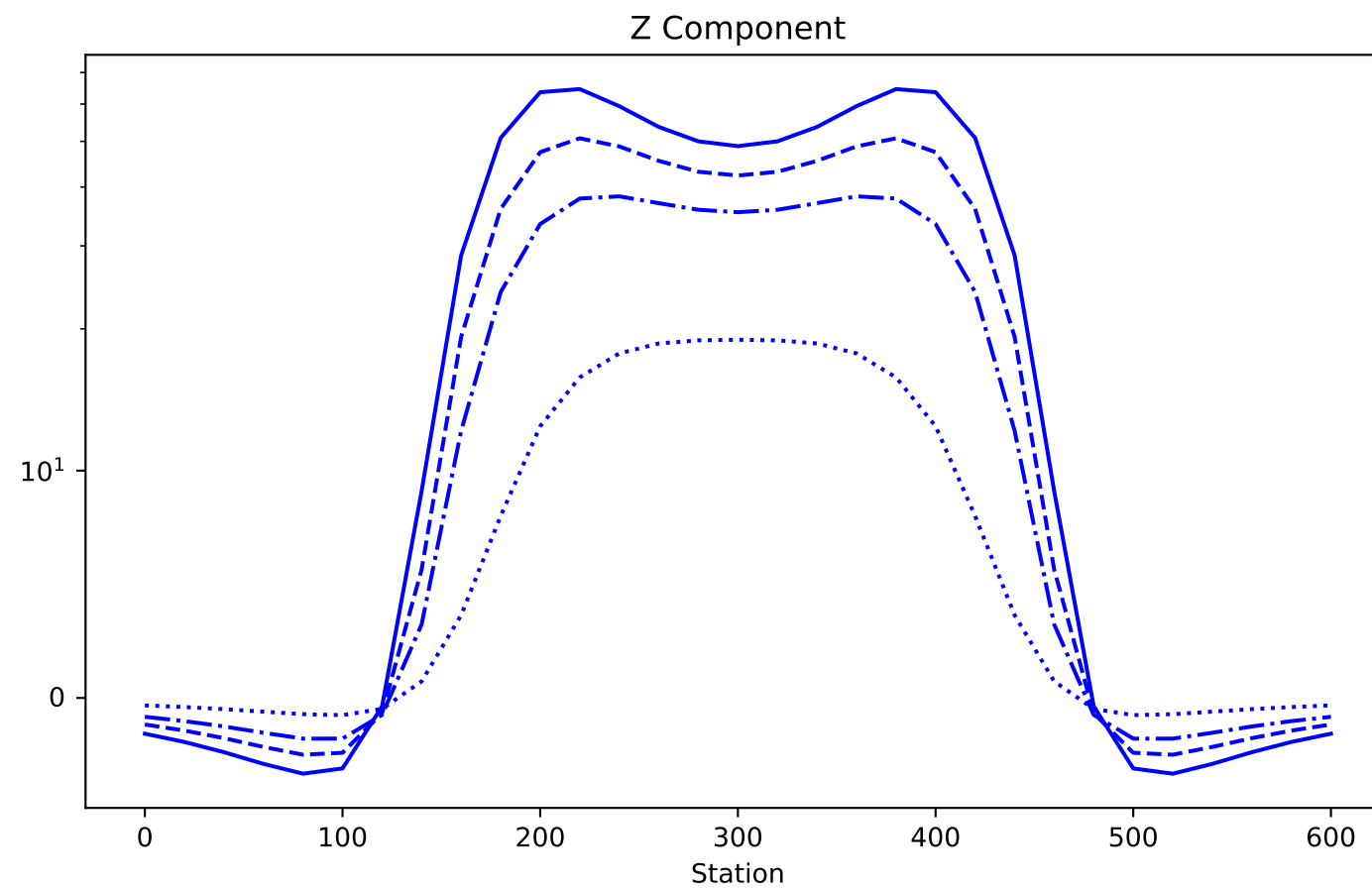
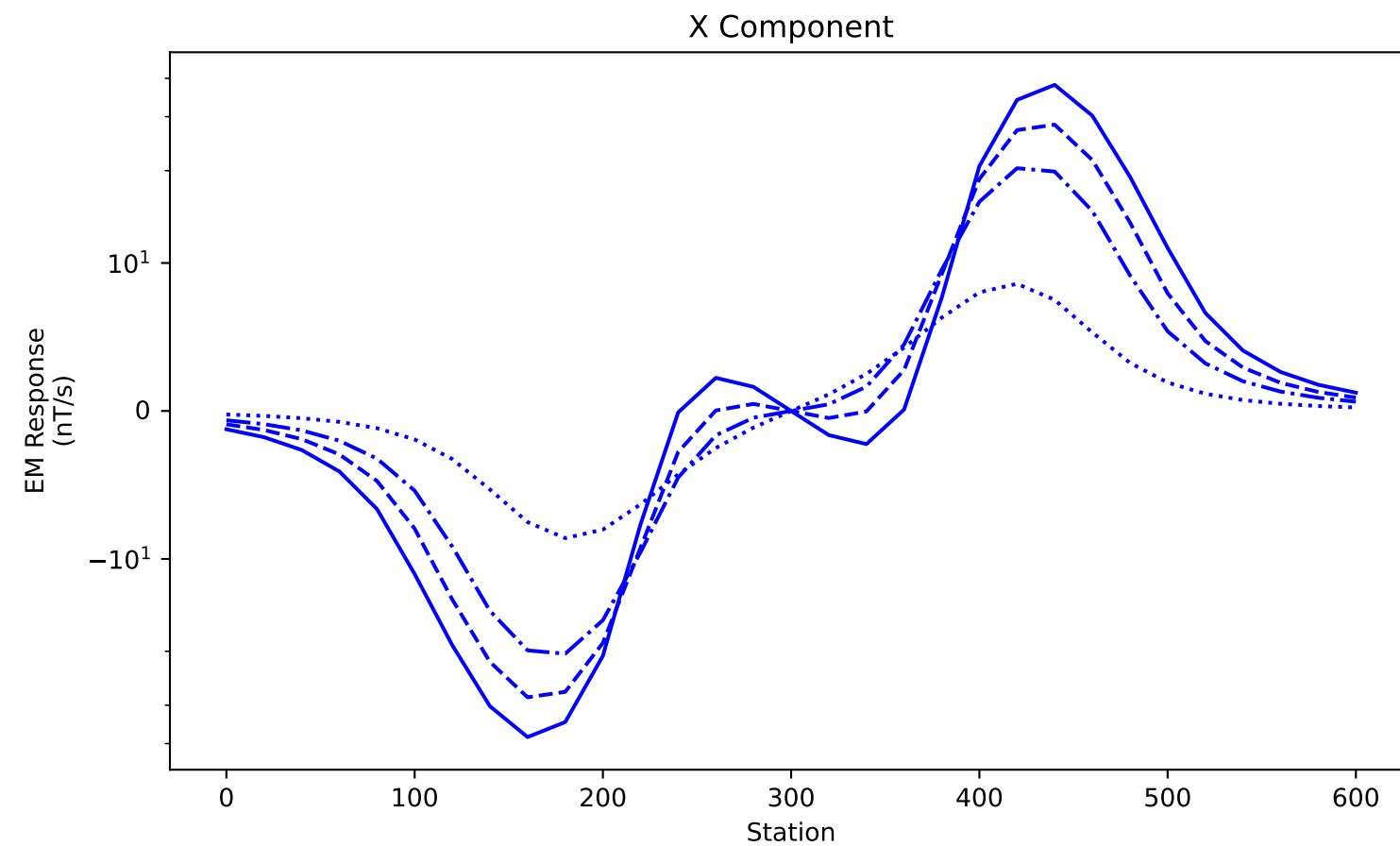
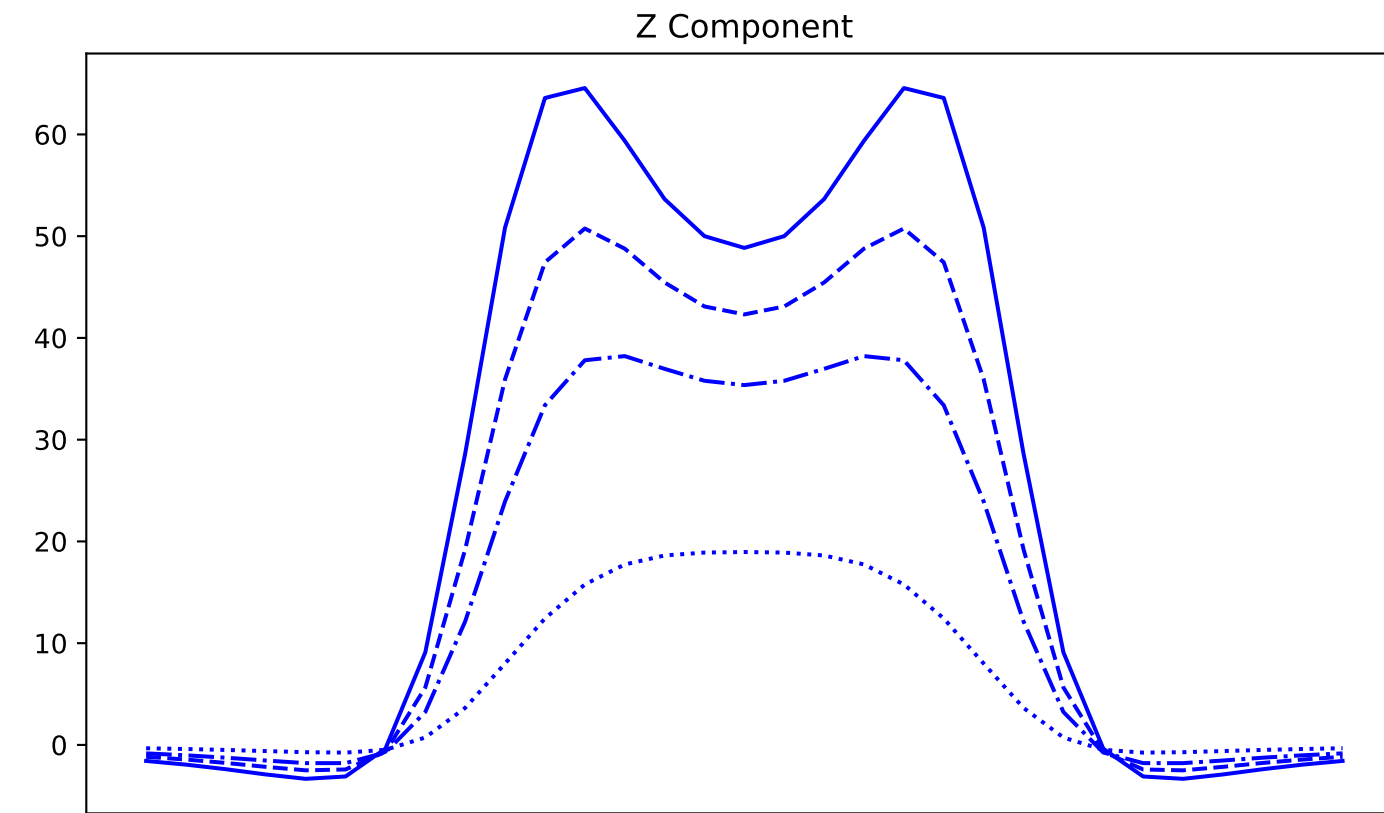
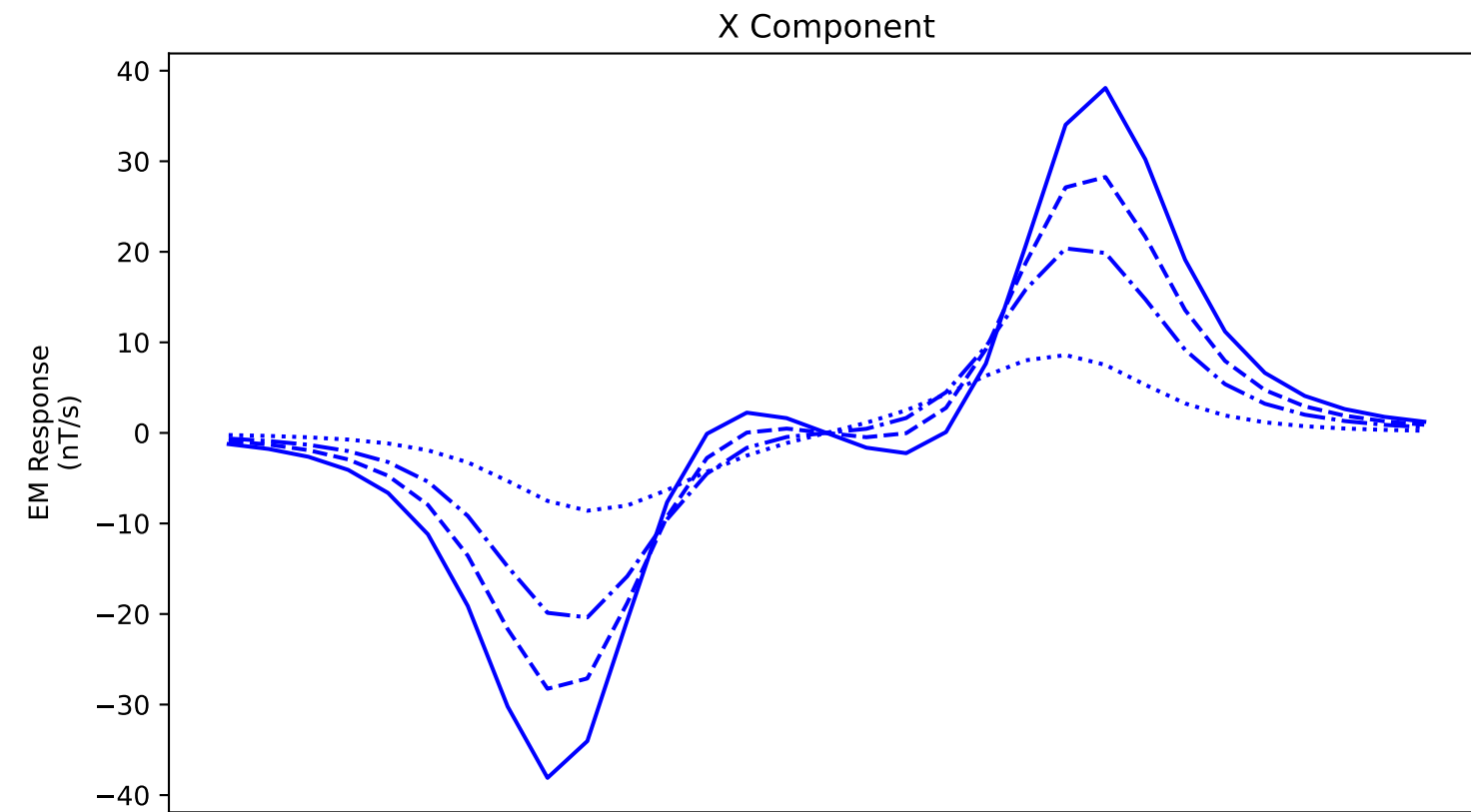
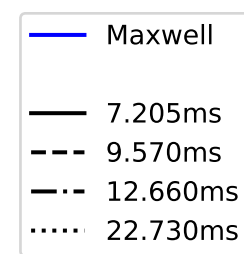
Two-Way Induction
300x100m, 1000S
LOOP=-150
1.315ms to 3.075ms



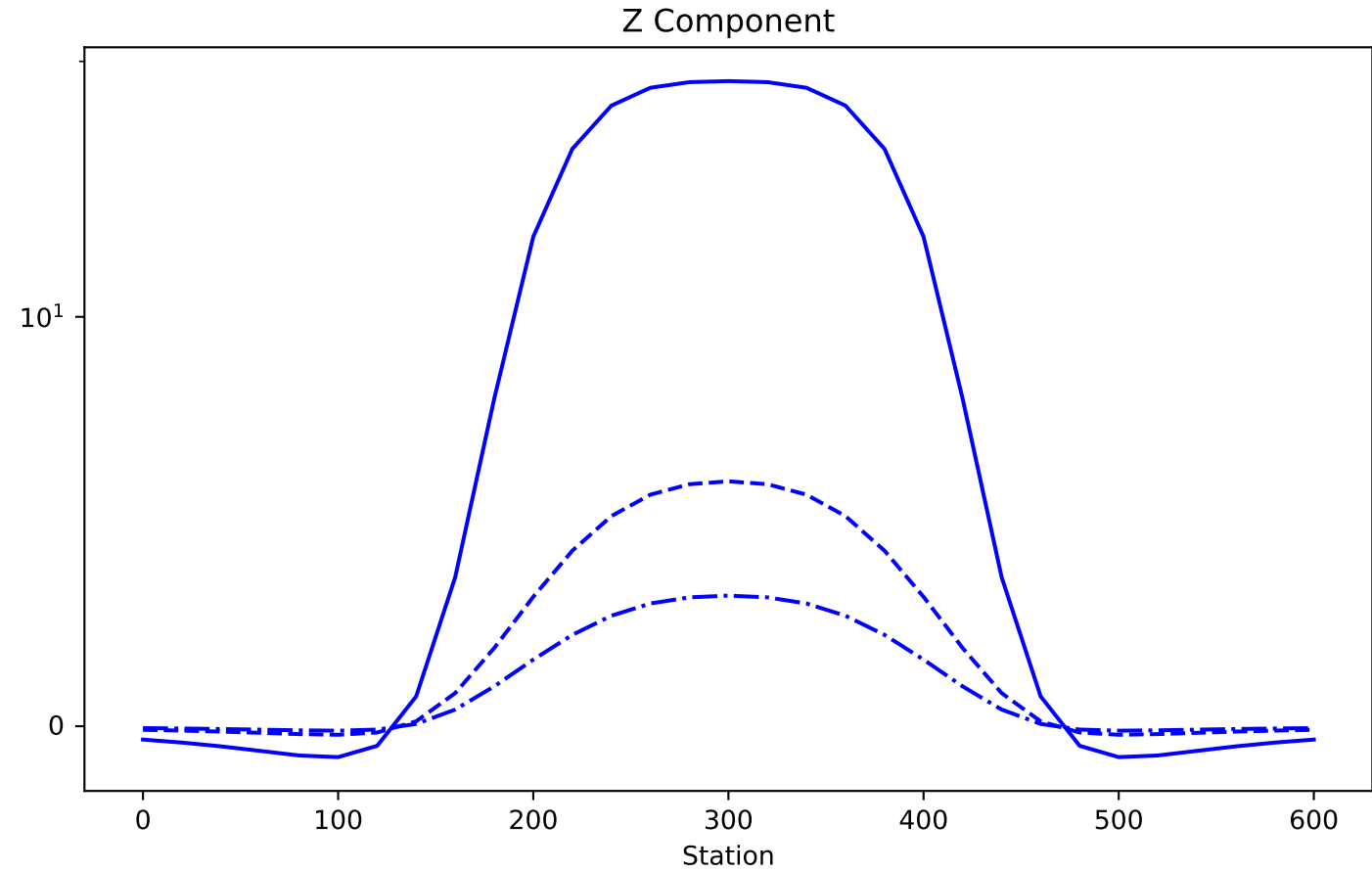
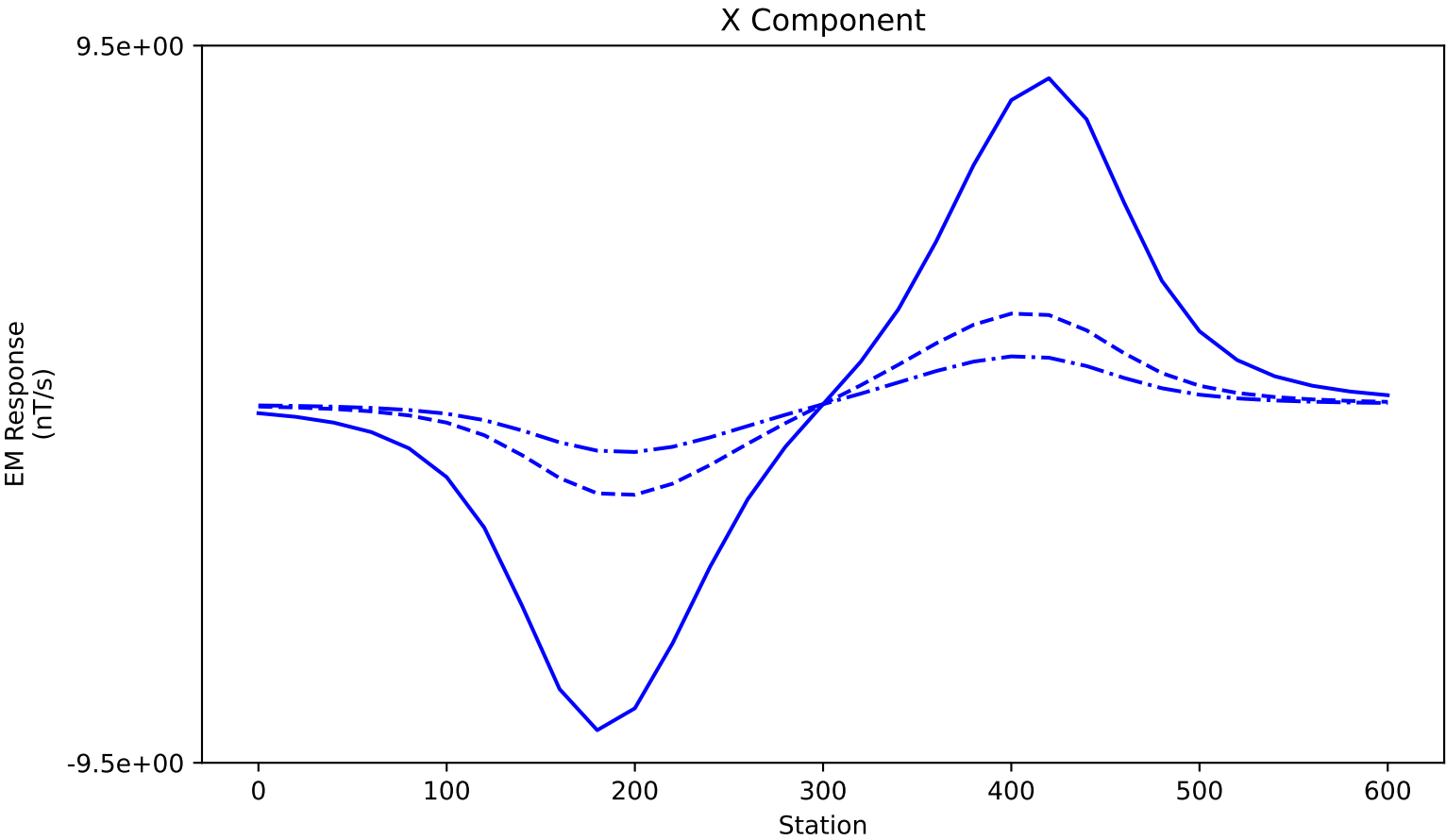
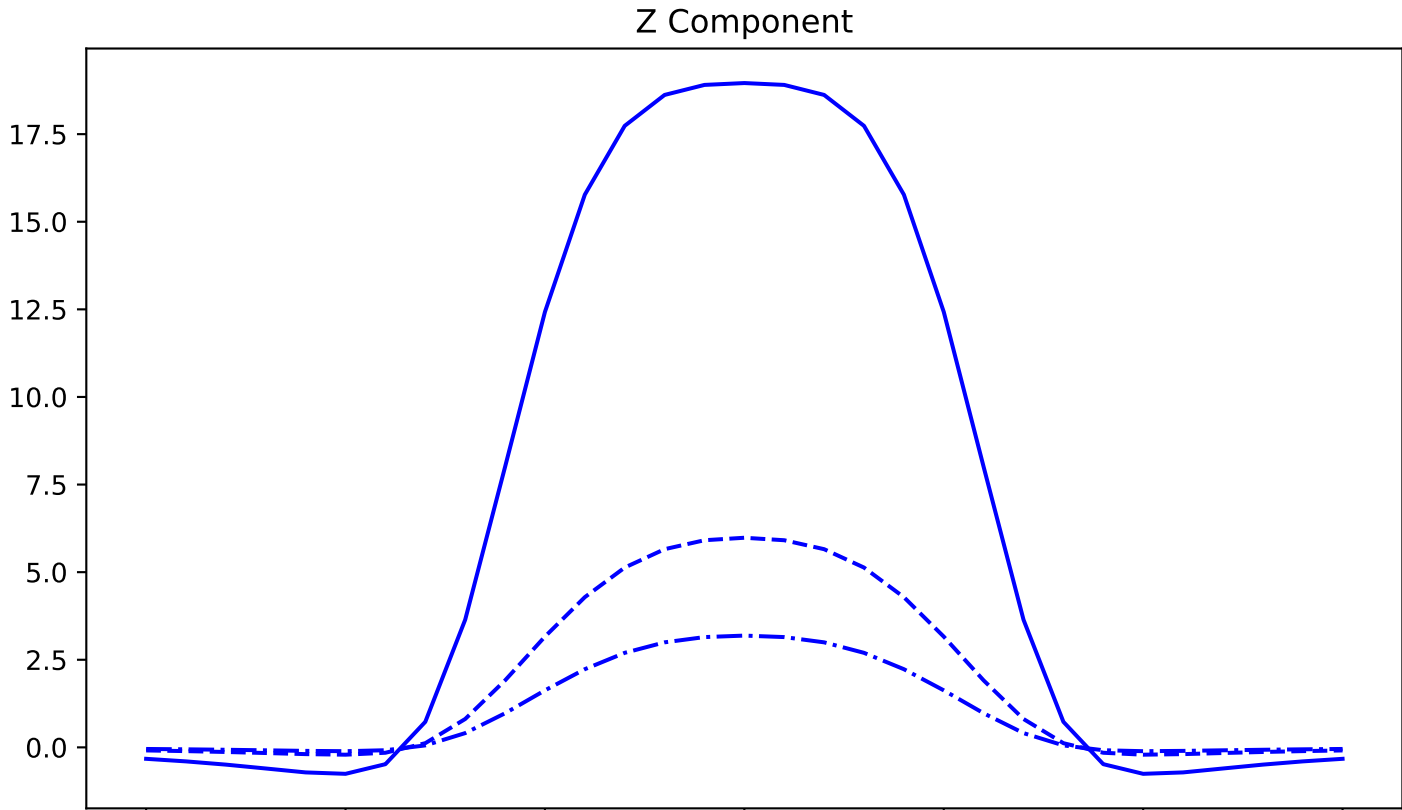
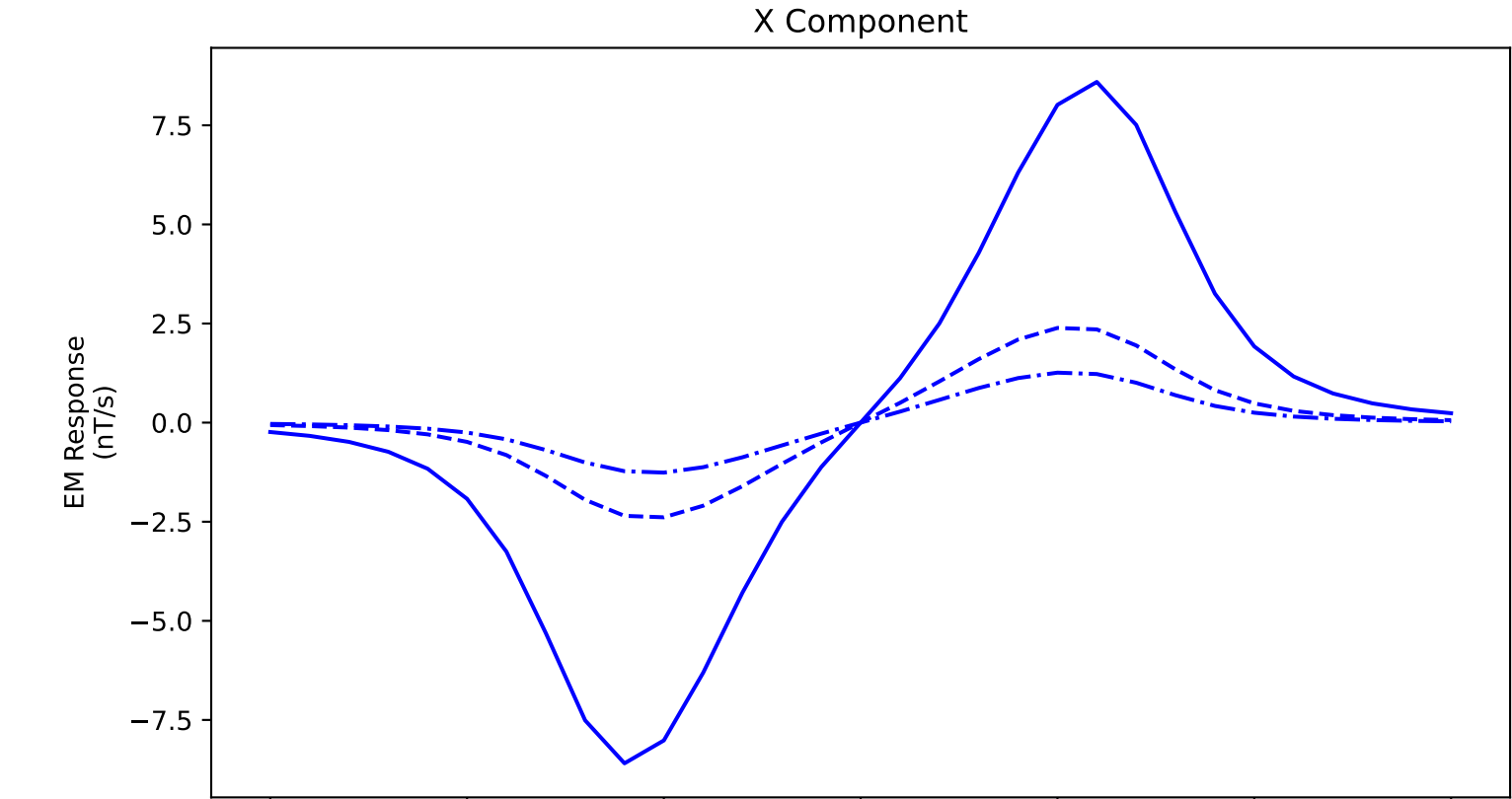
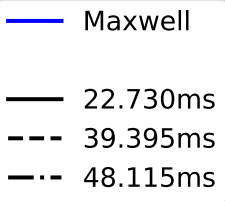
Two-Way Induction
300x100m, 1000S
LOOP=-150
3.075ms to 7.205ms



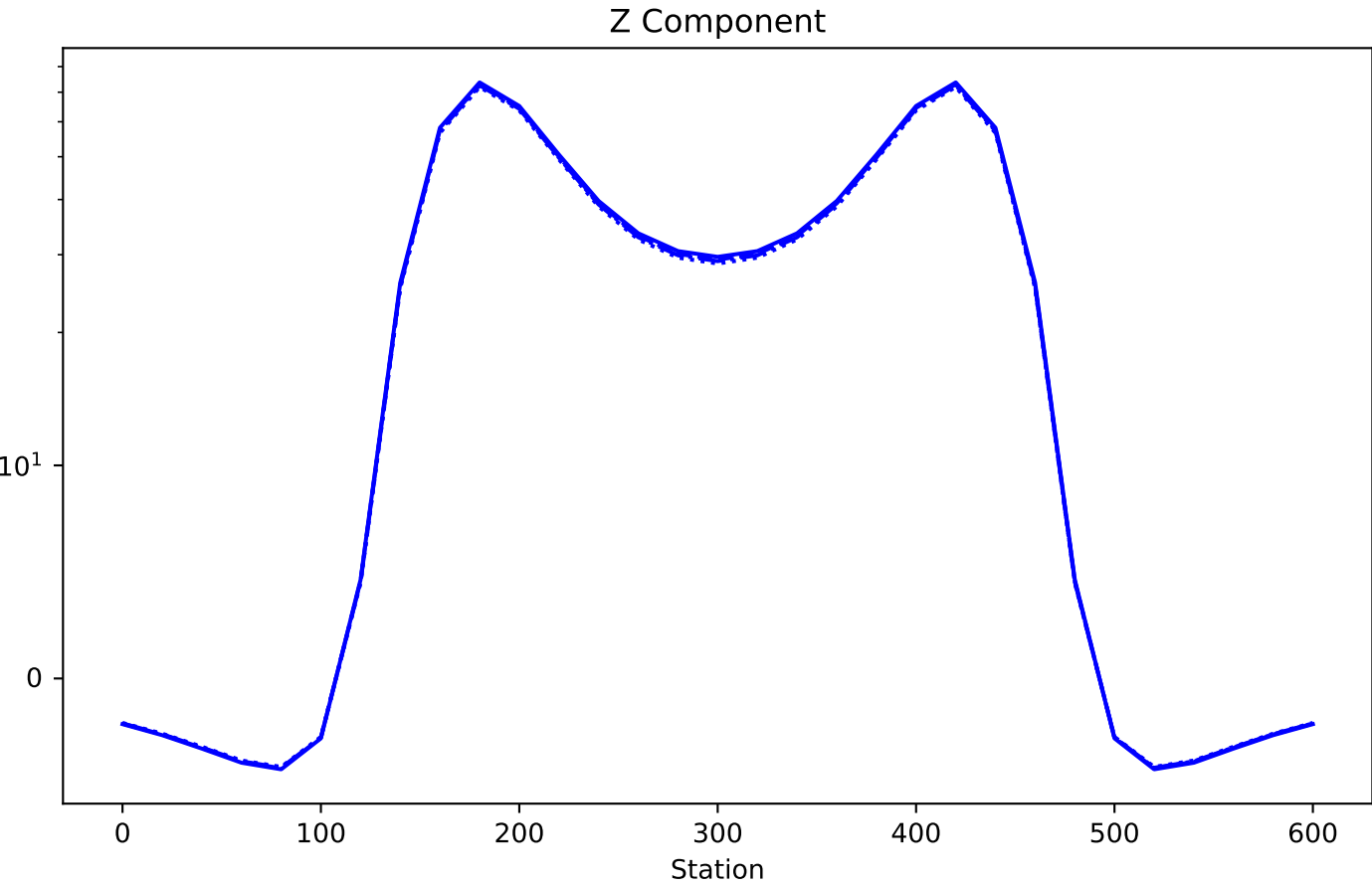
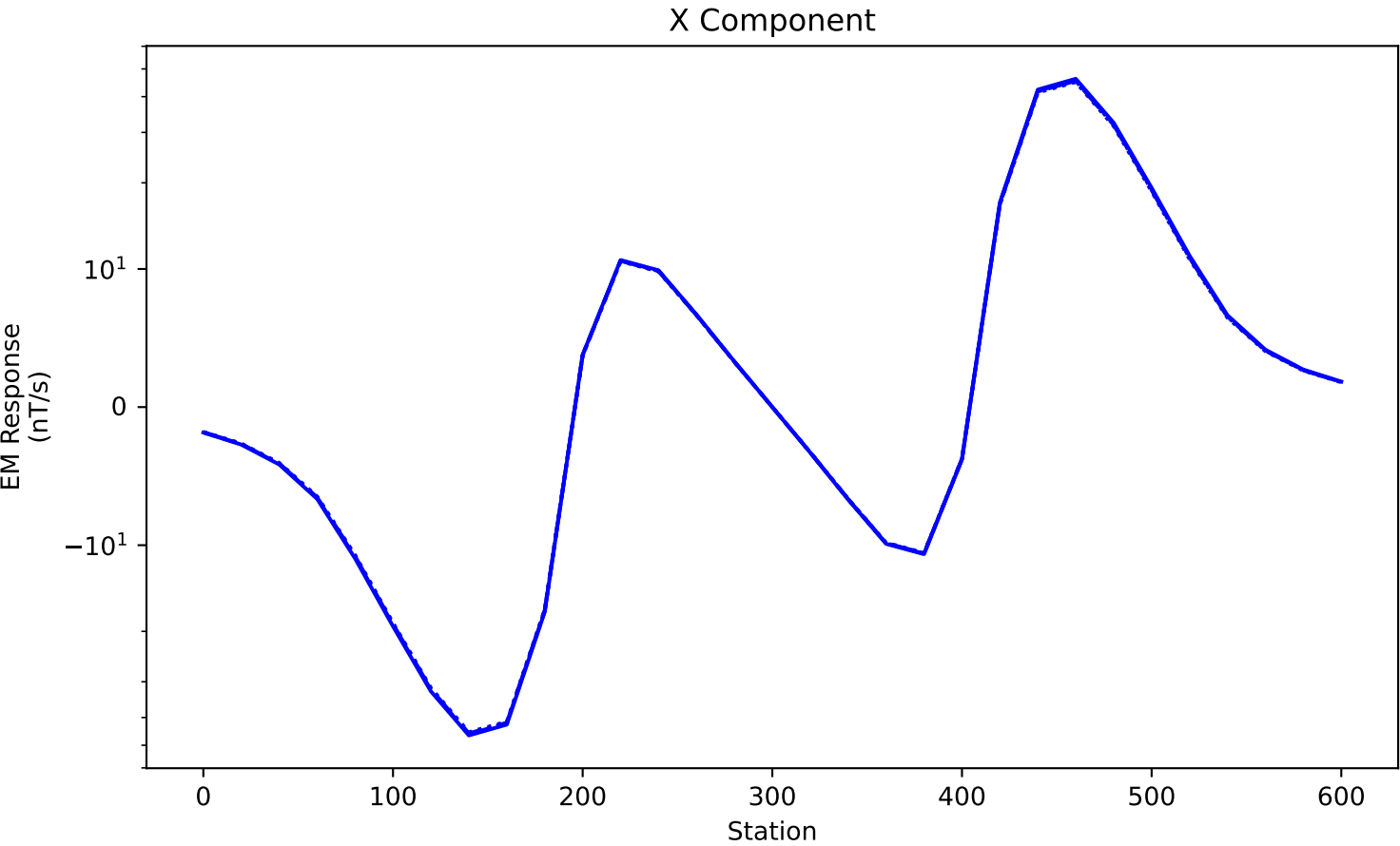
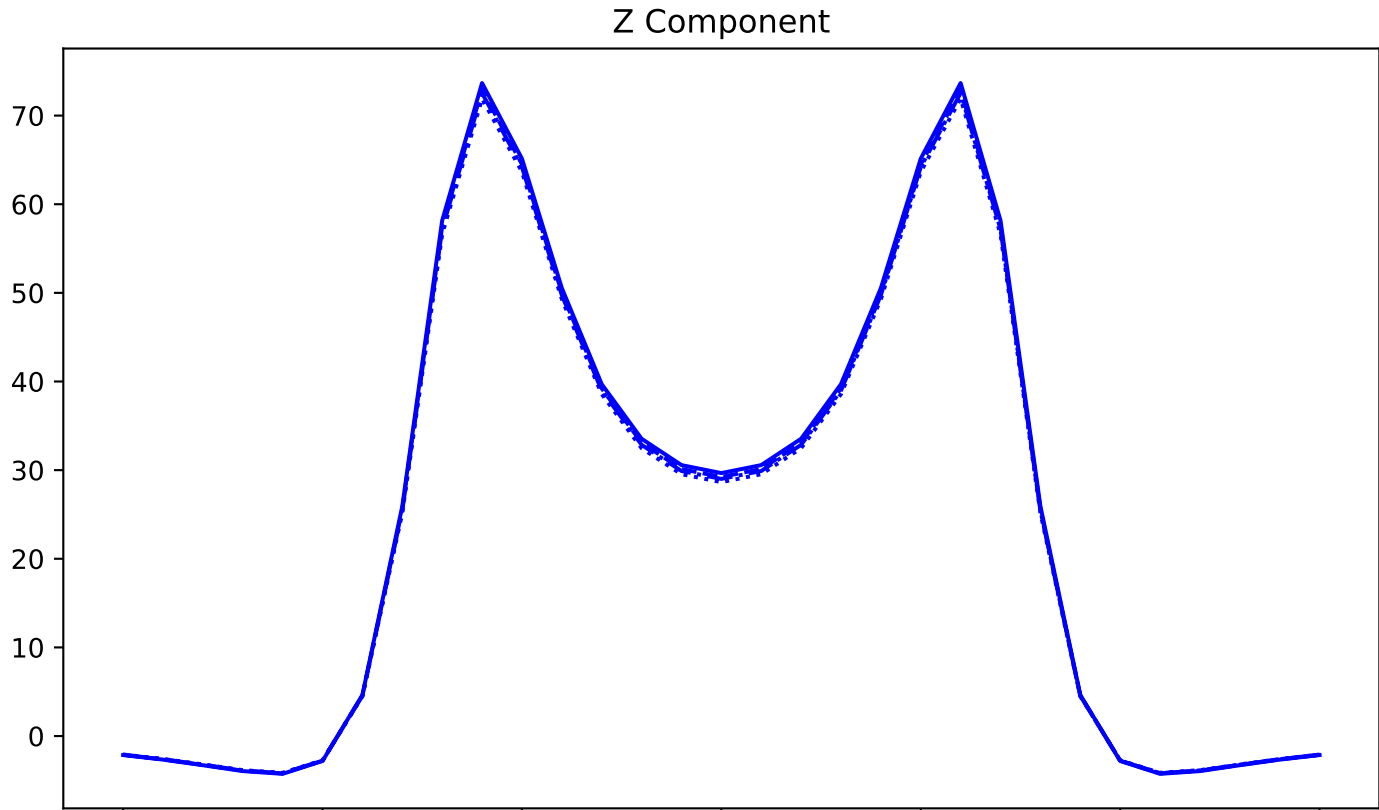
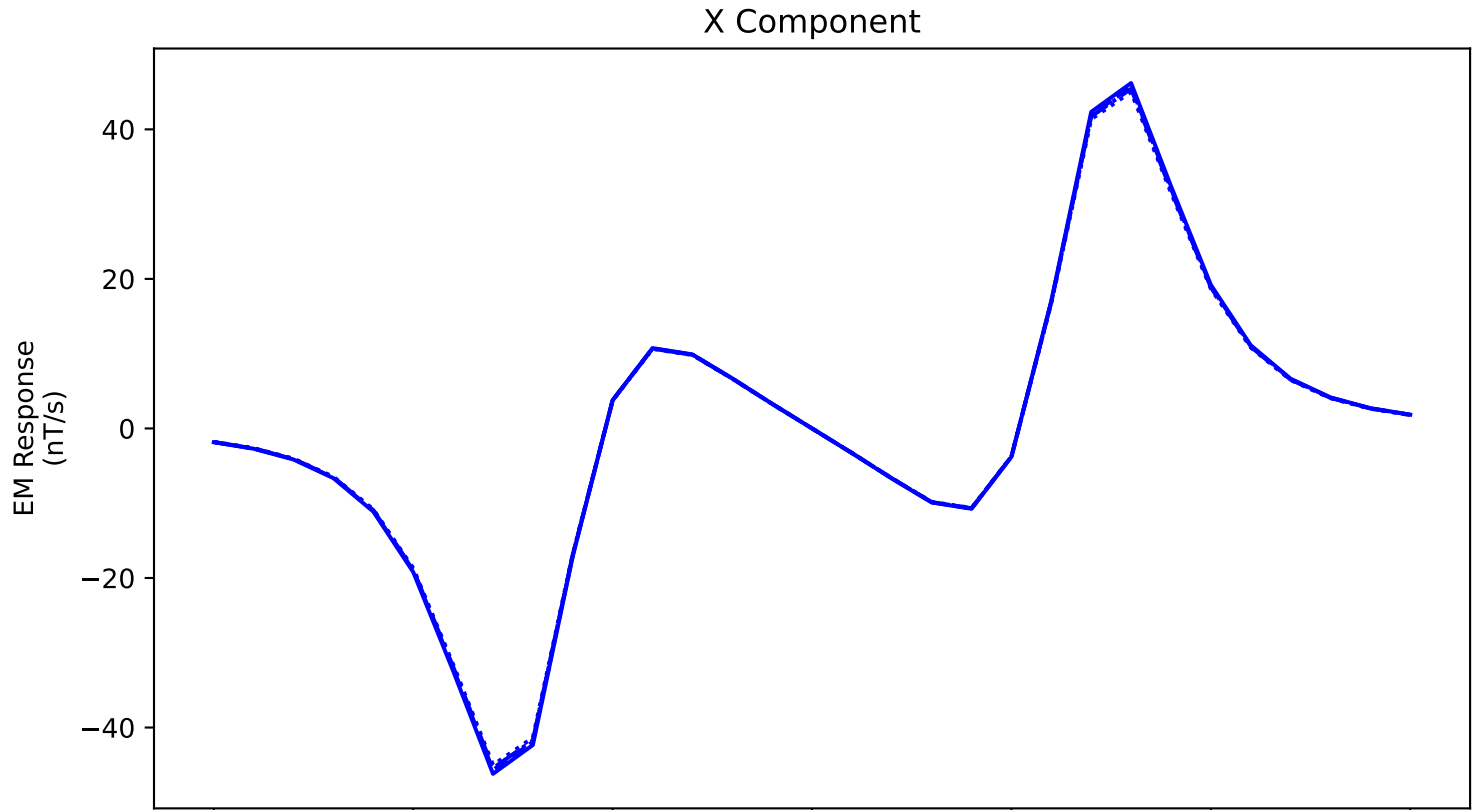
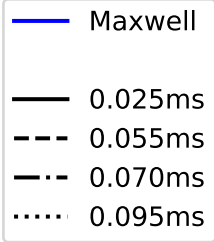
Two-Way Induction
300x100m, 1000S
LOOP=-150
7.205ms to 22.73ms



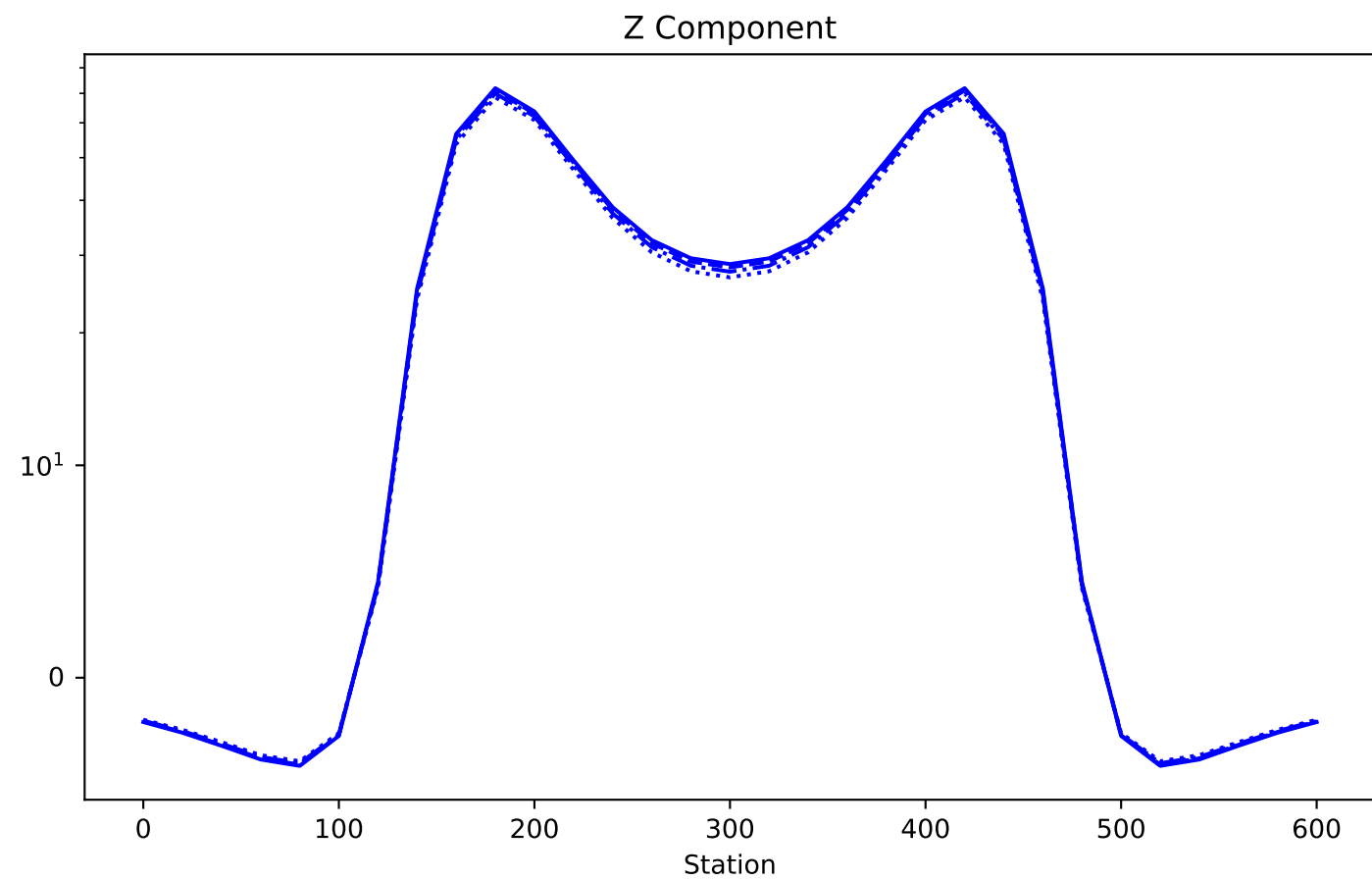
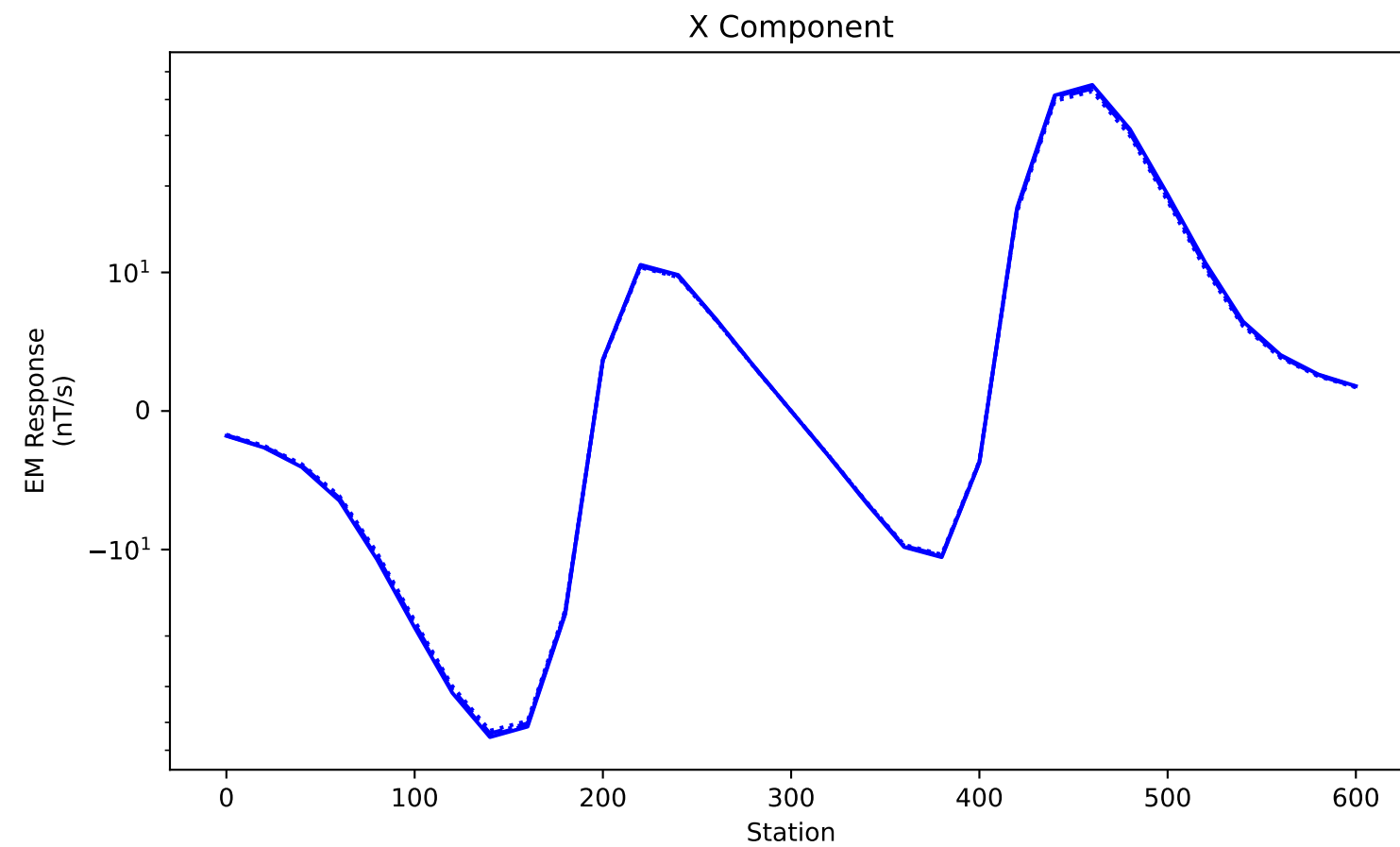
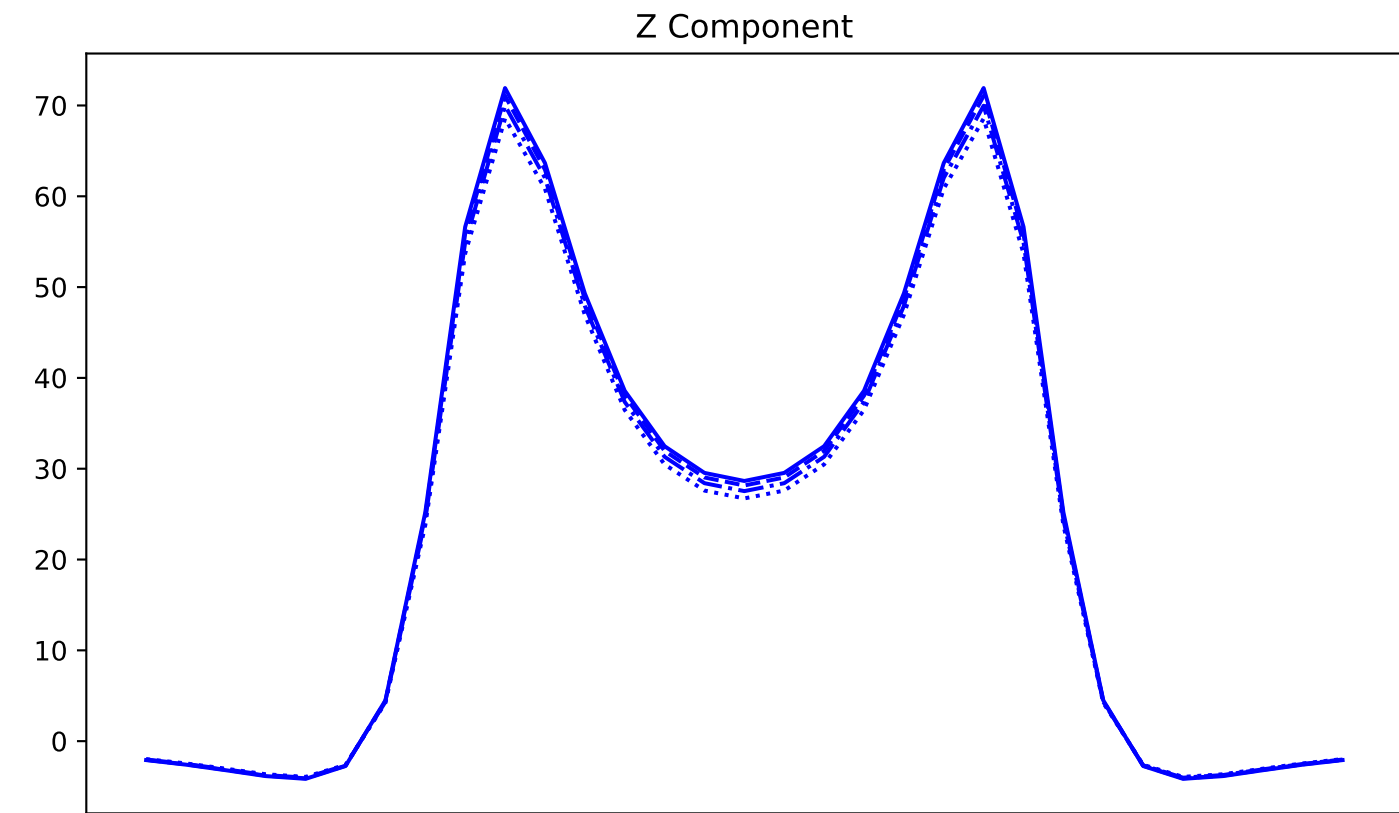
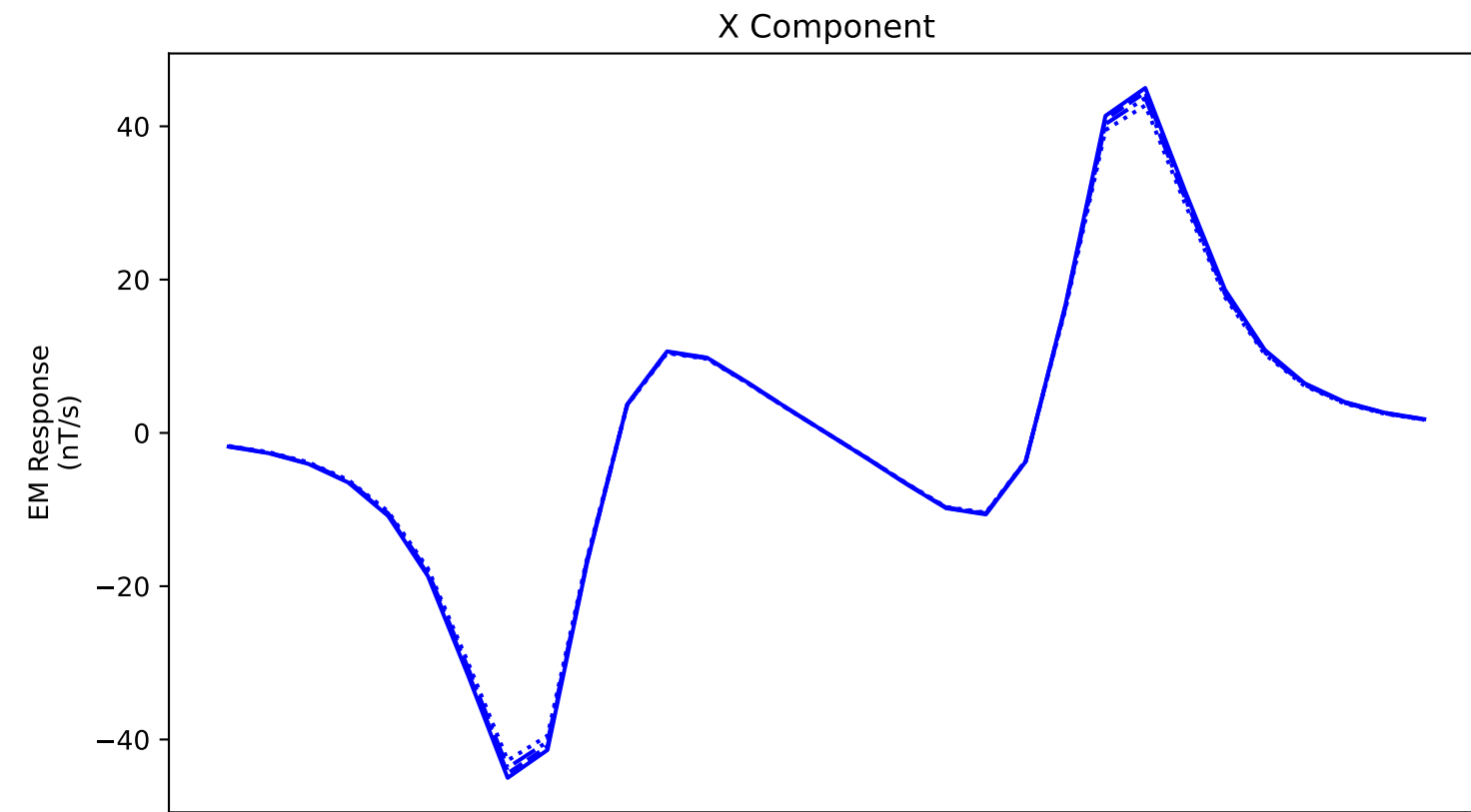
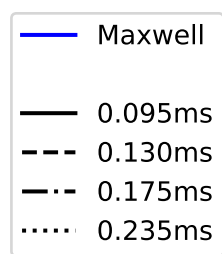
Two-Way Induction
300x100m, 1000S
LOOP=-150
22.73ms to 48.115ms



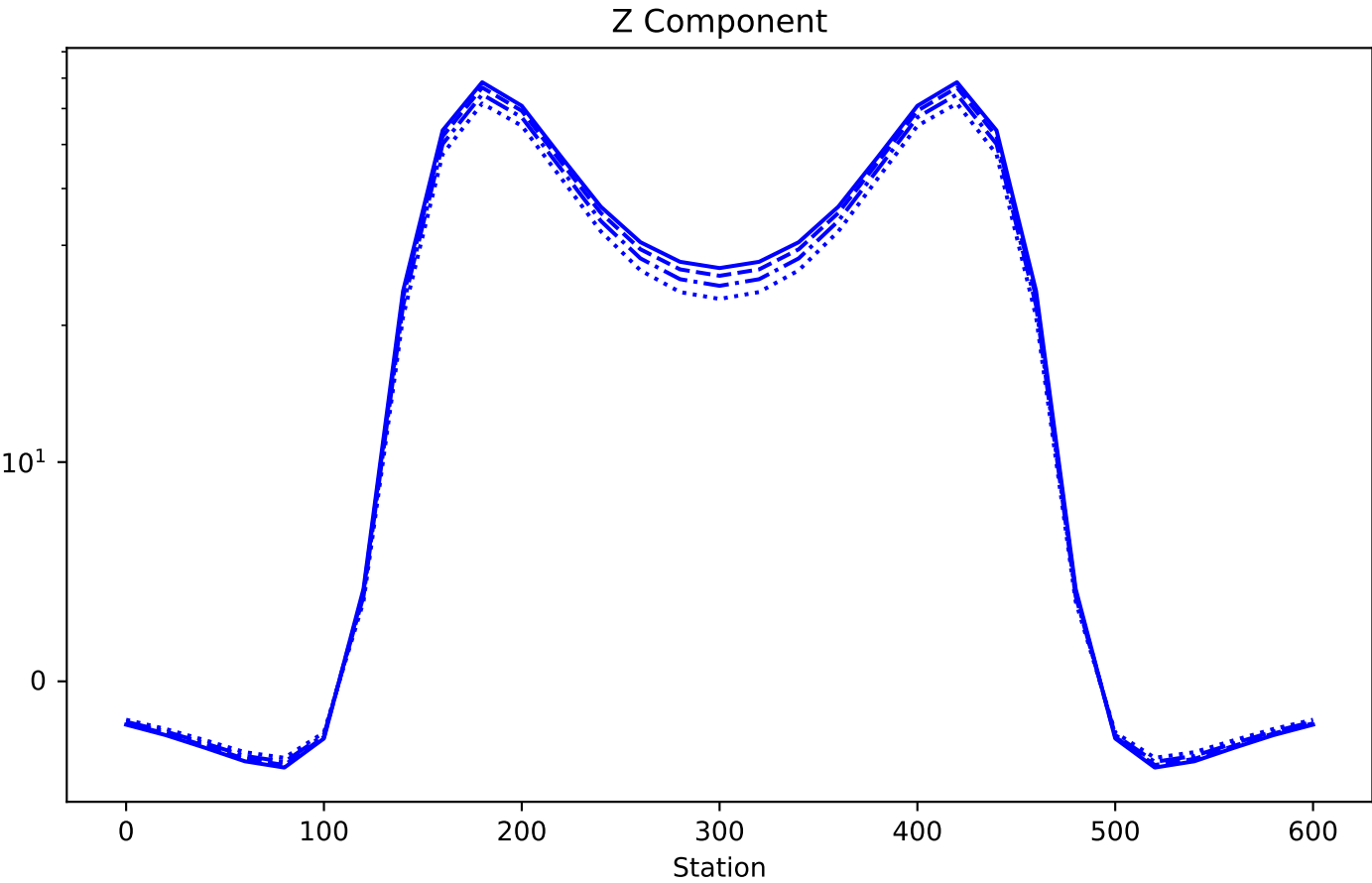
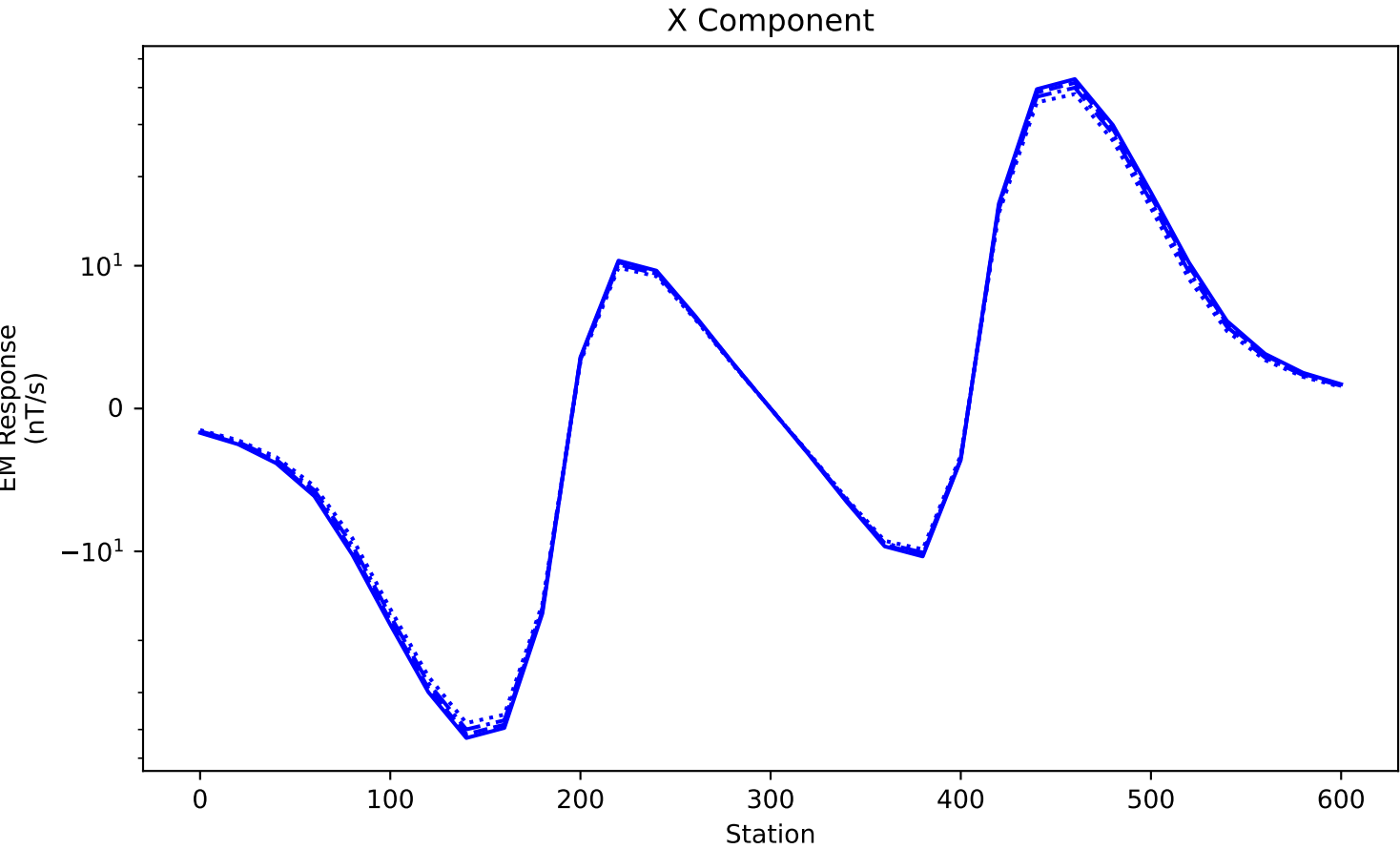
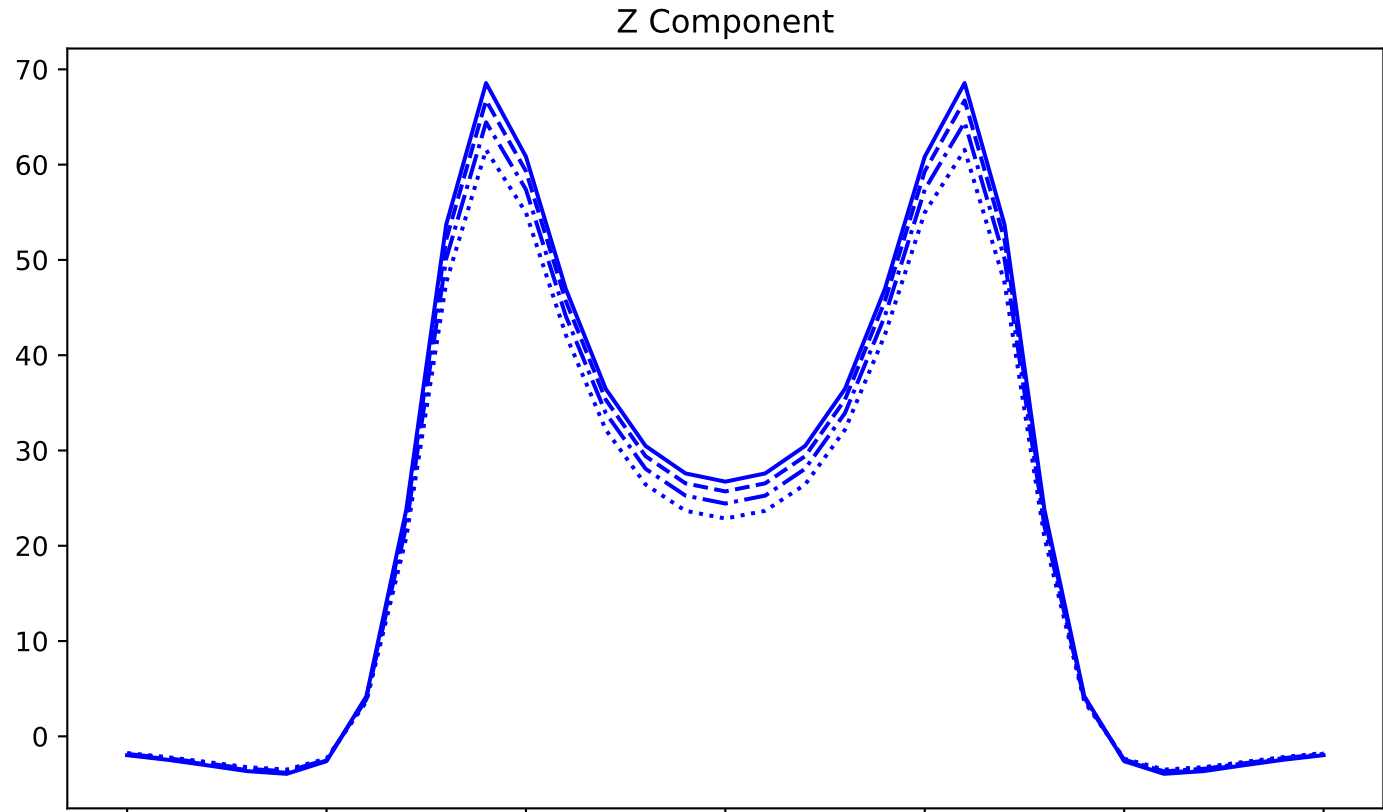
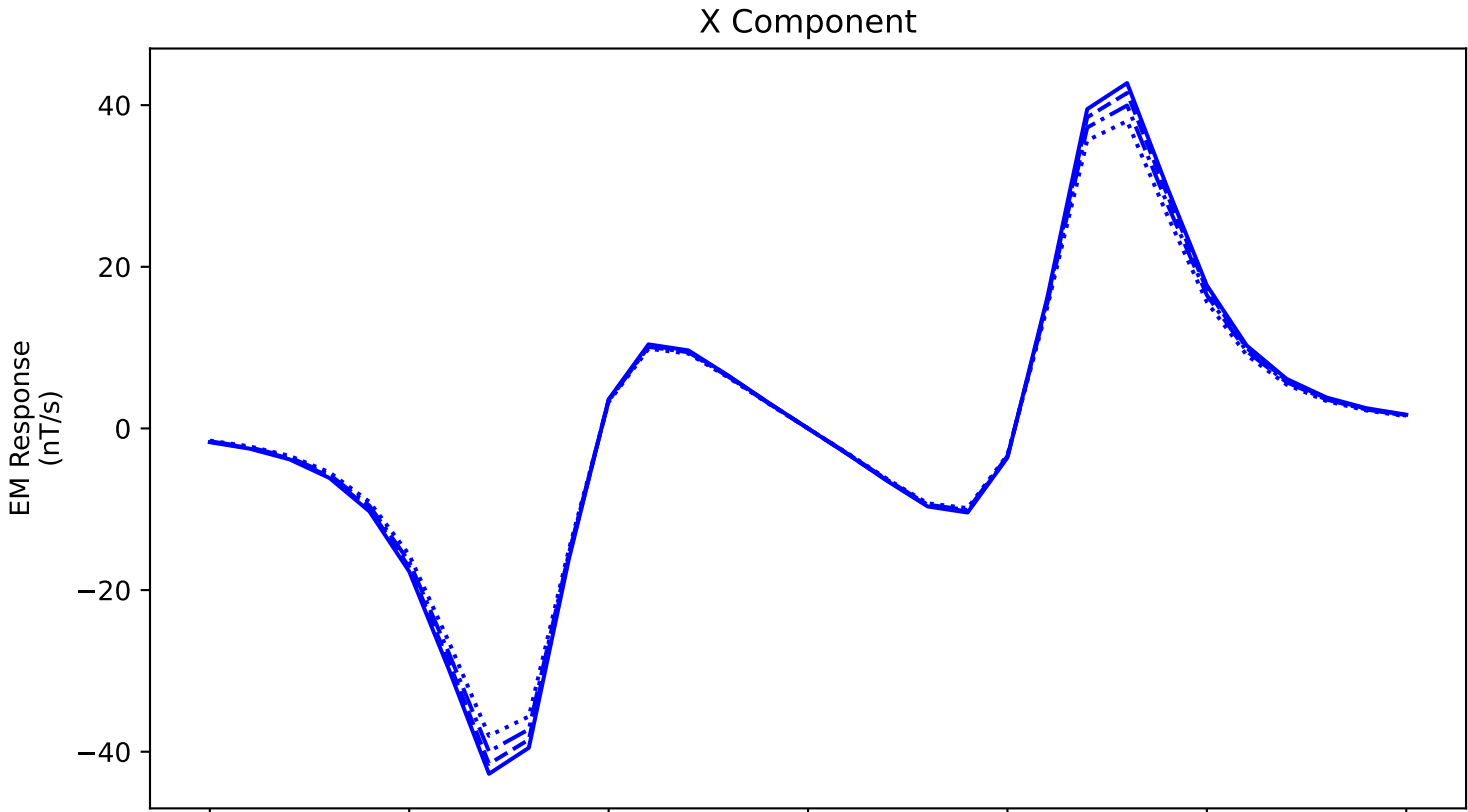
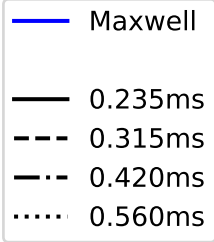
Two-Way Induction
300x100m, 1000S
LOOP=-200
0.0255ms to 0.095ms



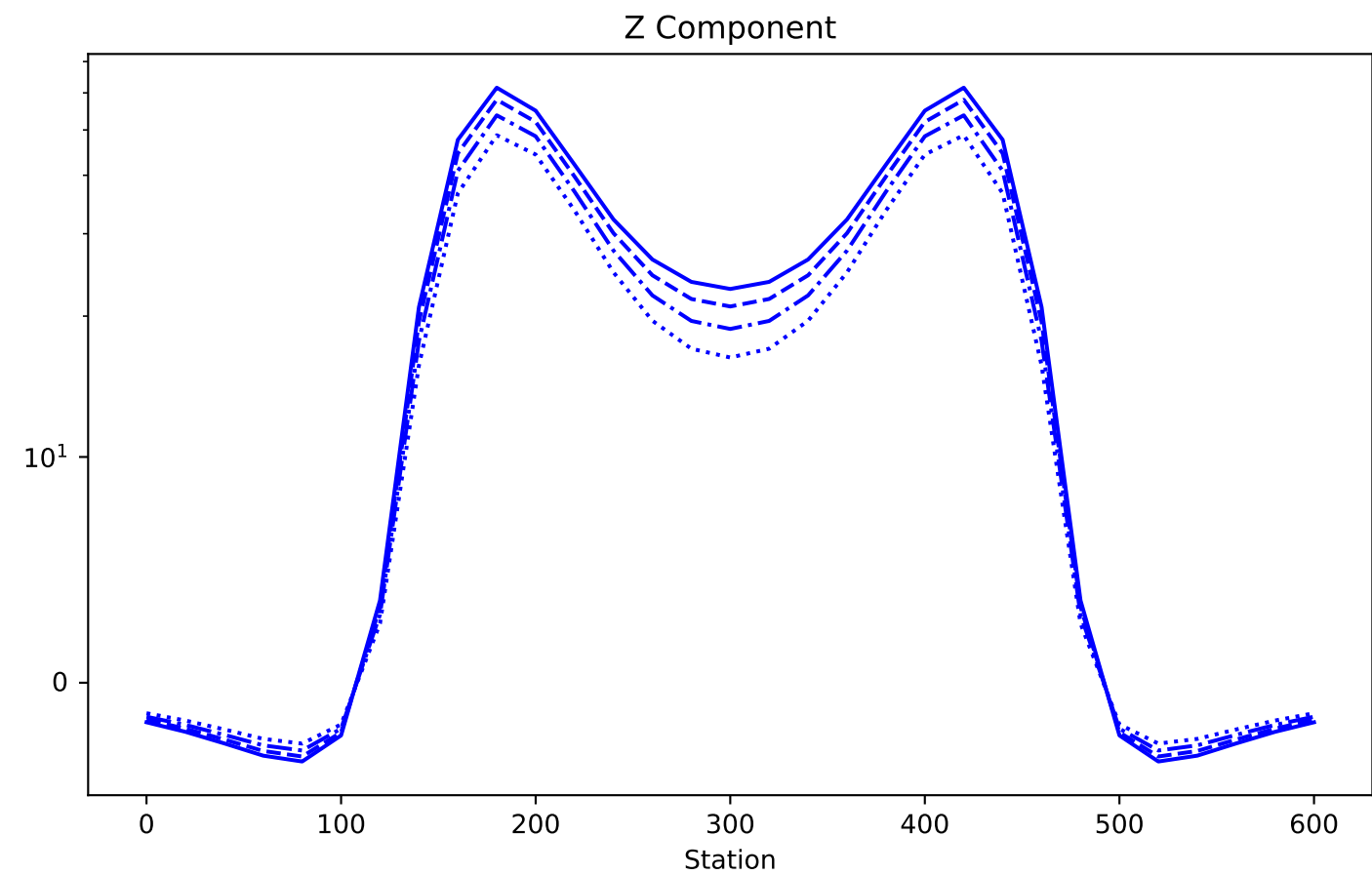
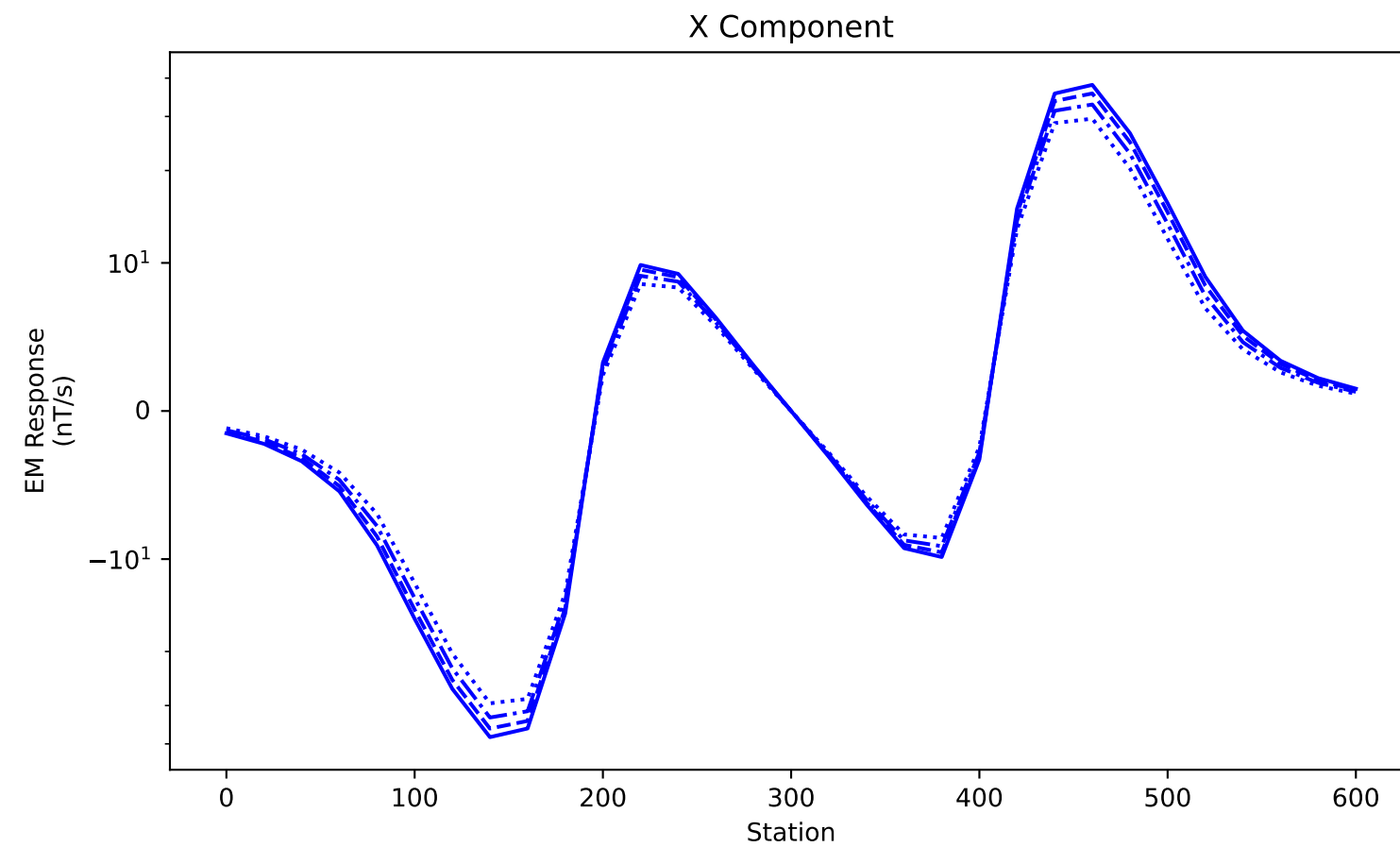
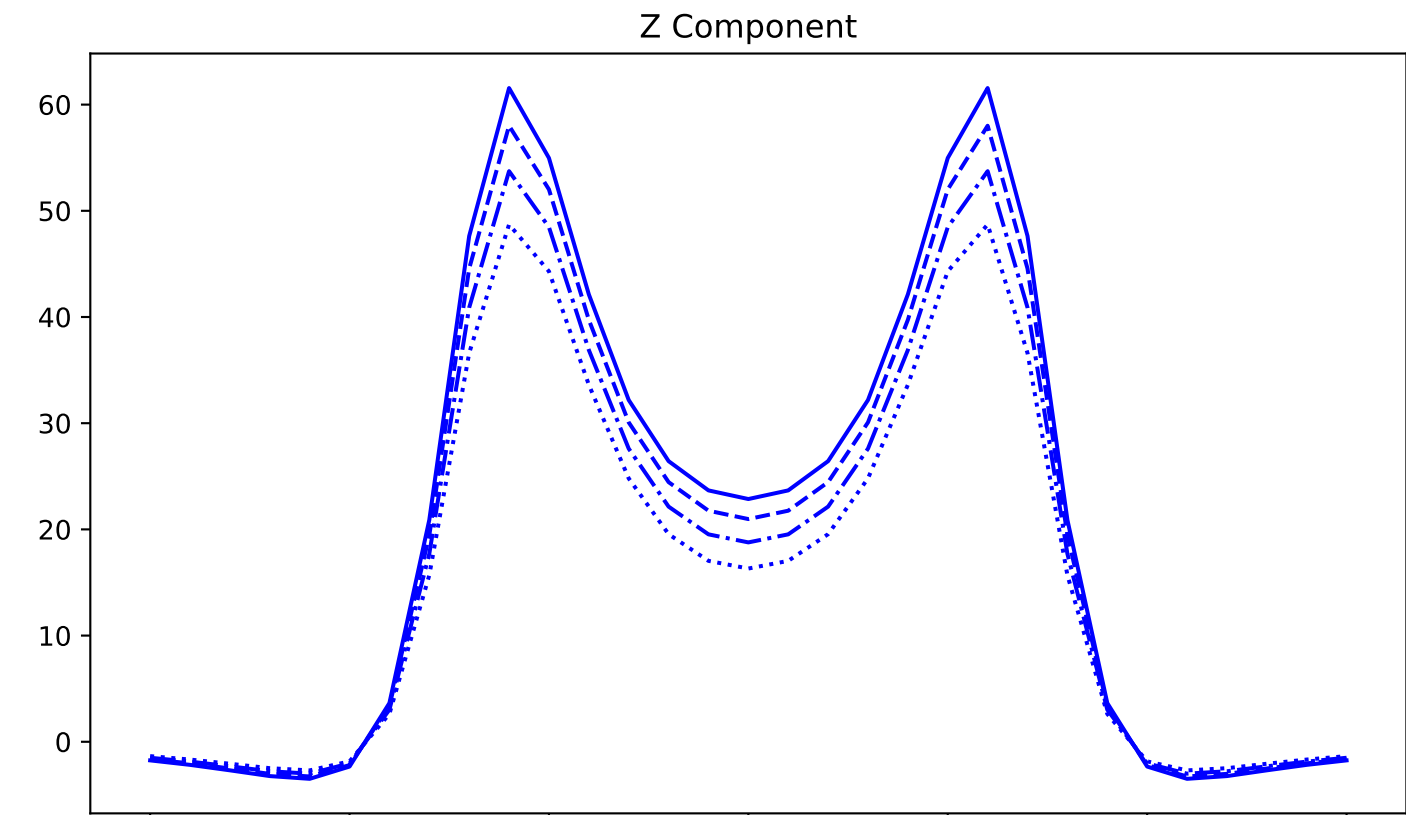
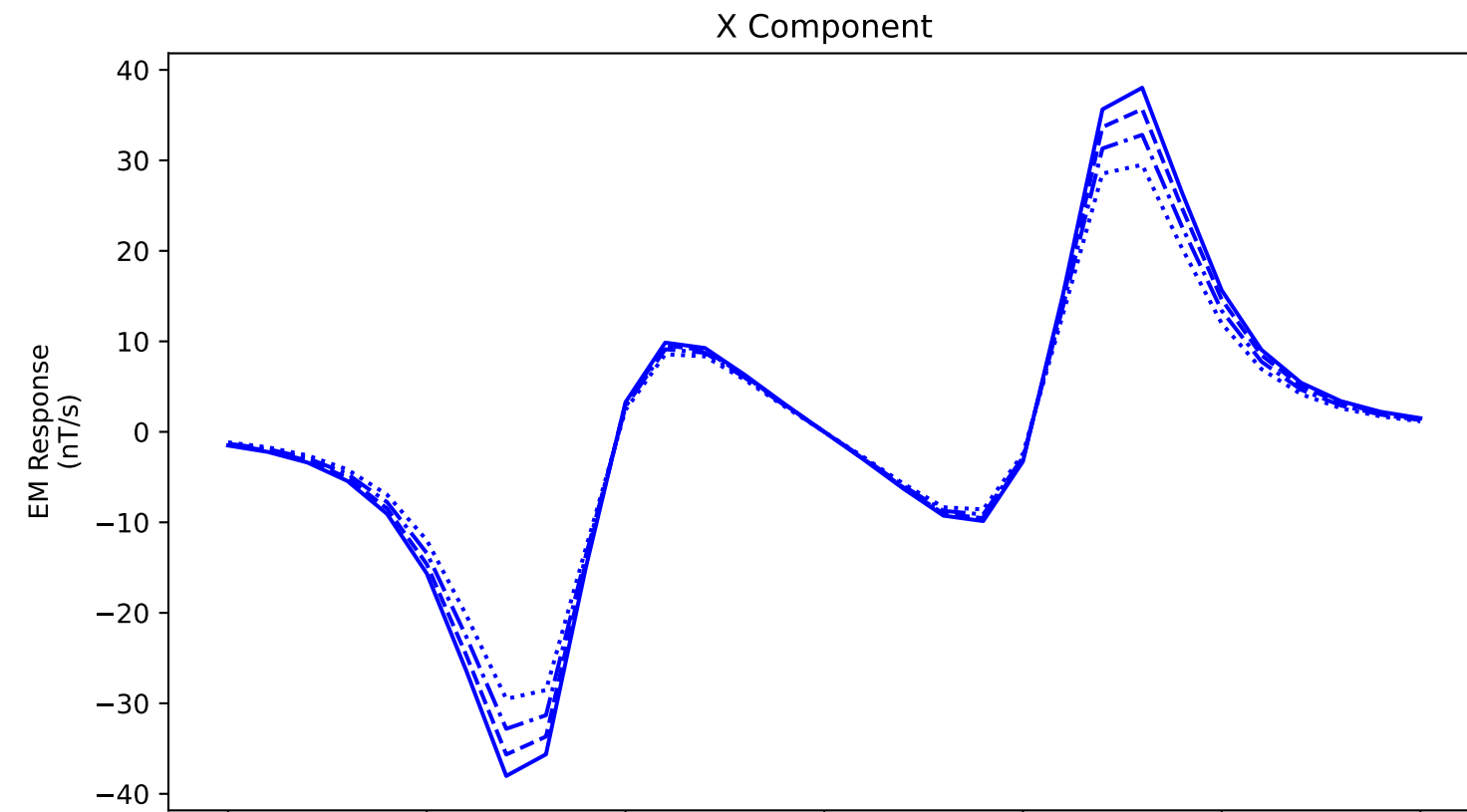
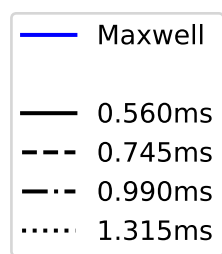
Two-Way Induction
300x100m, 1000S
LOOP=-200
0.095ms to 0.235ms



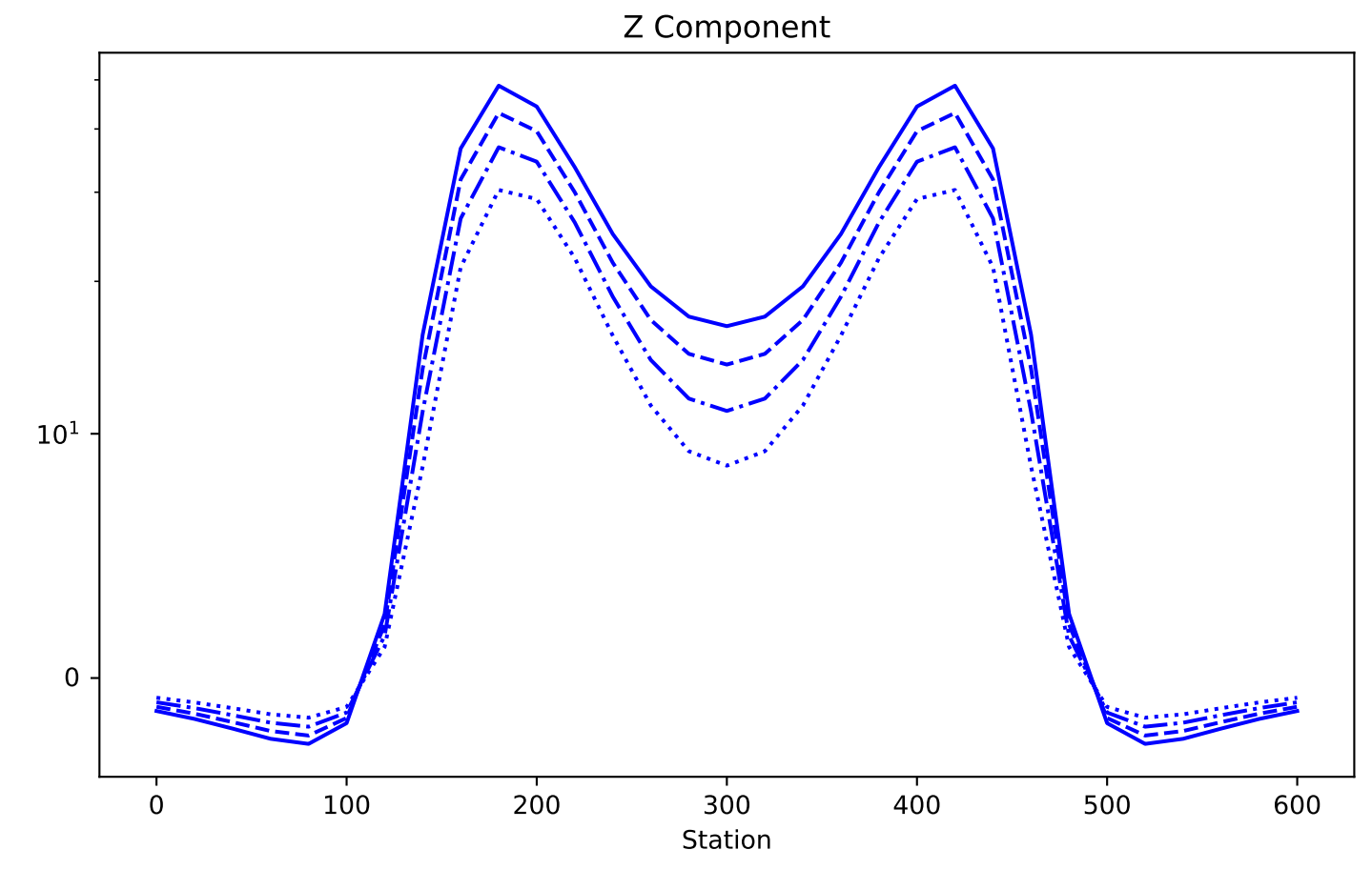
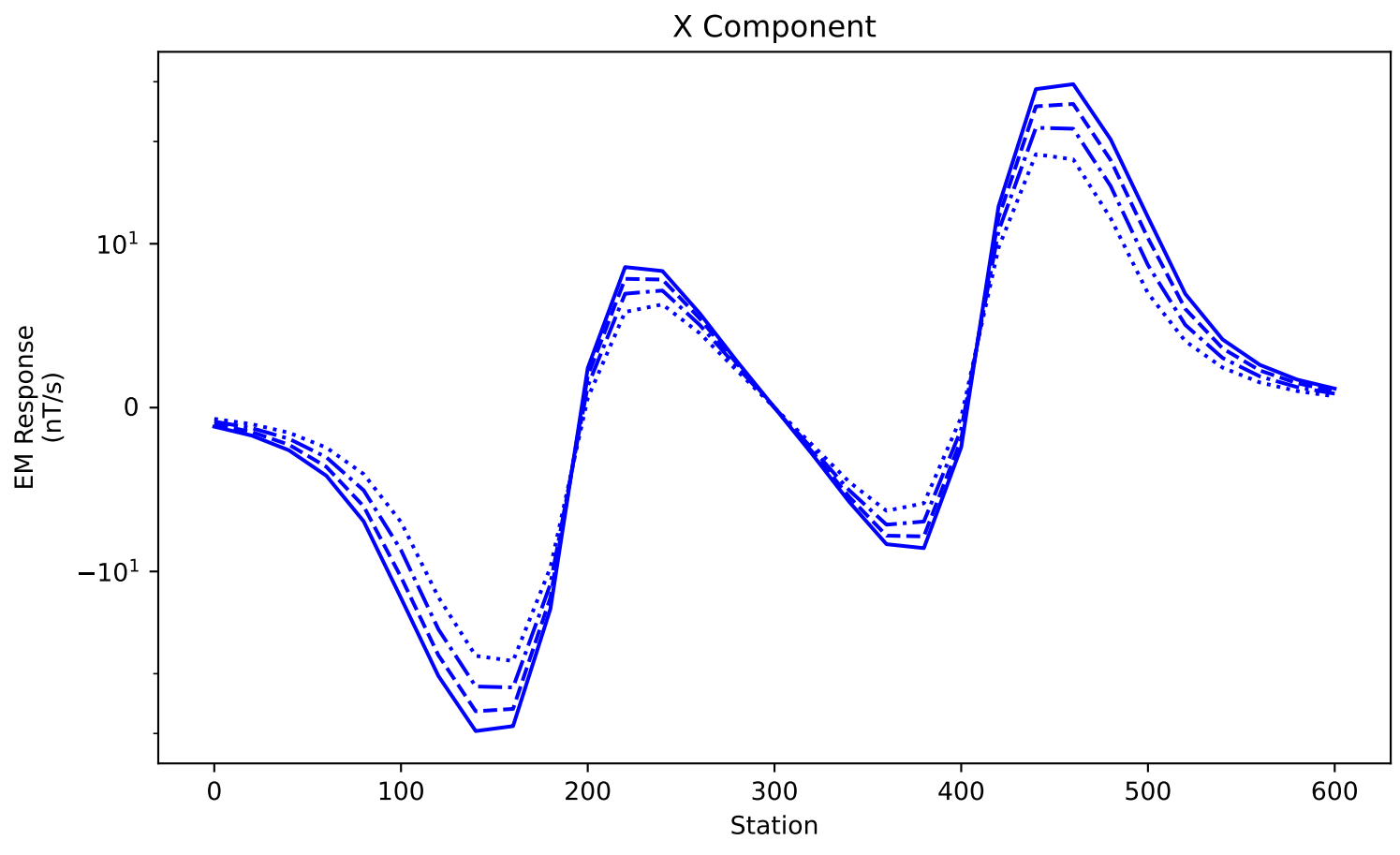
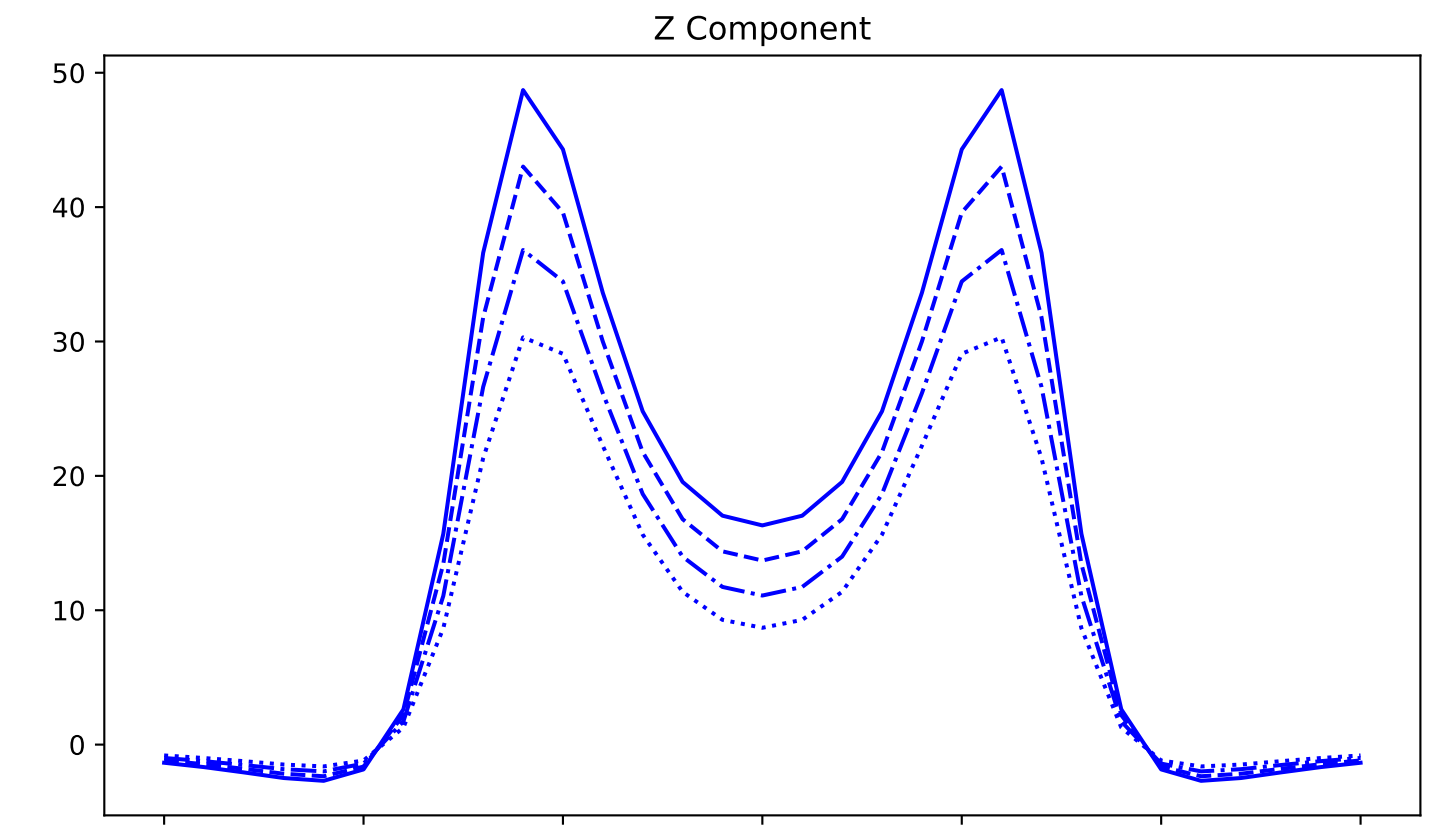
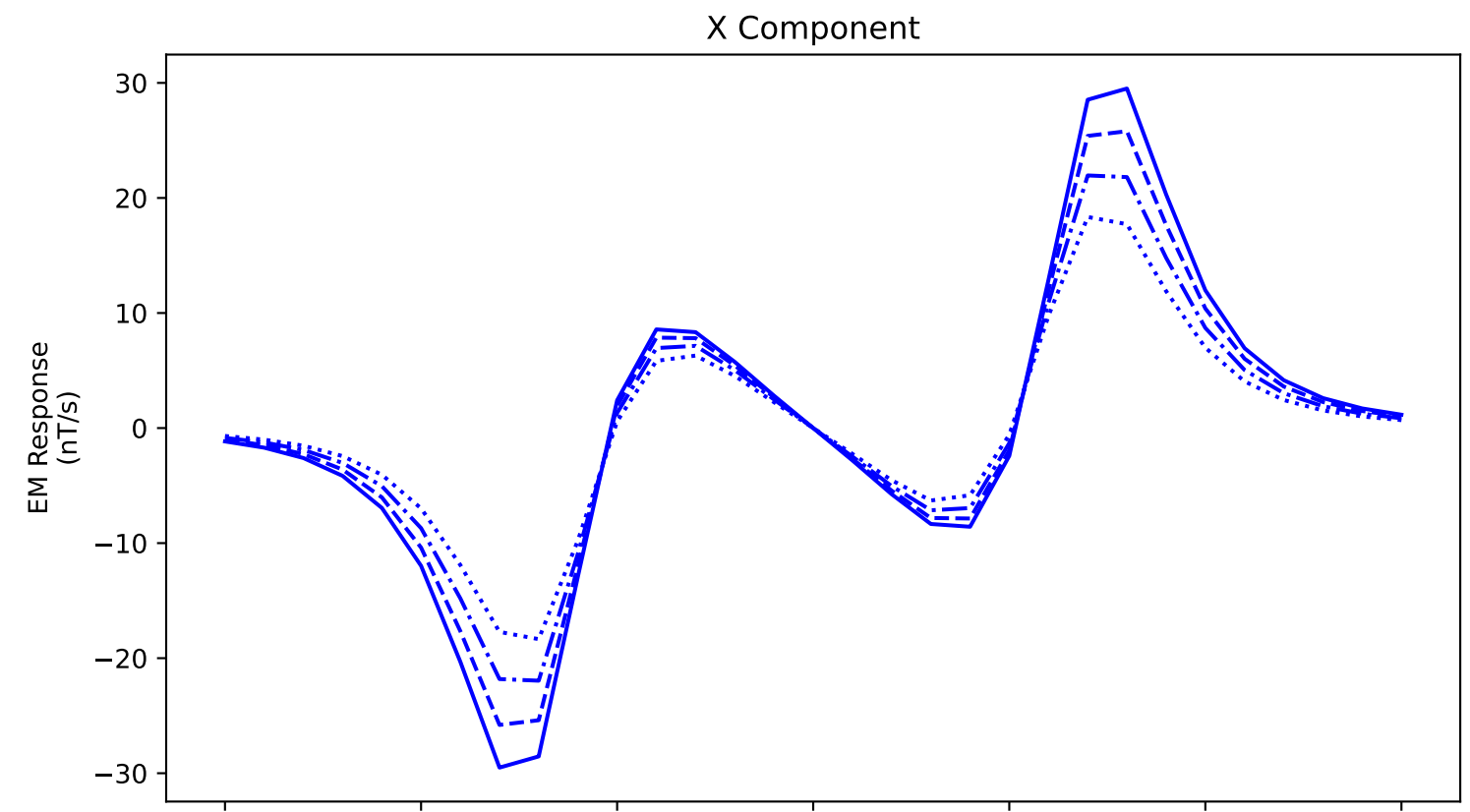
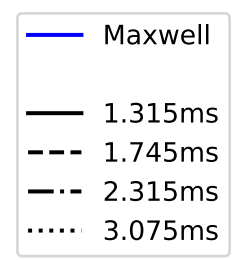
Two-Way Induction
300x100m, 1000S
LOOP=-200
0.235ms to 0.56ms



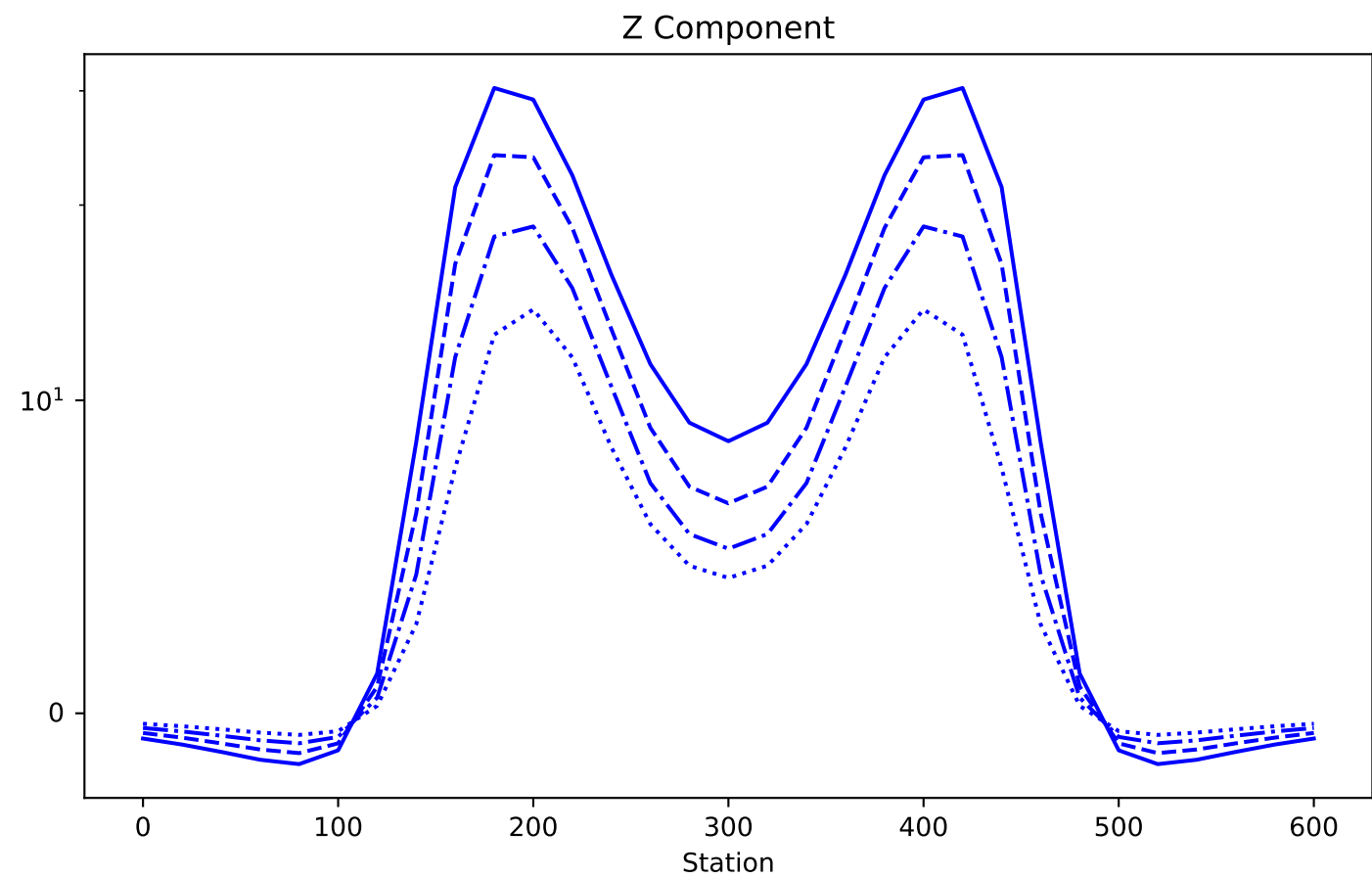
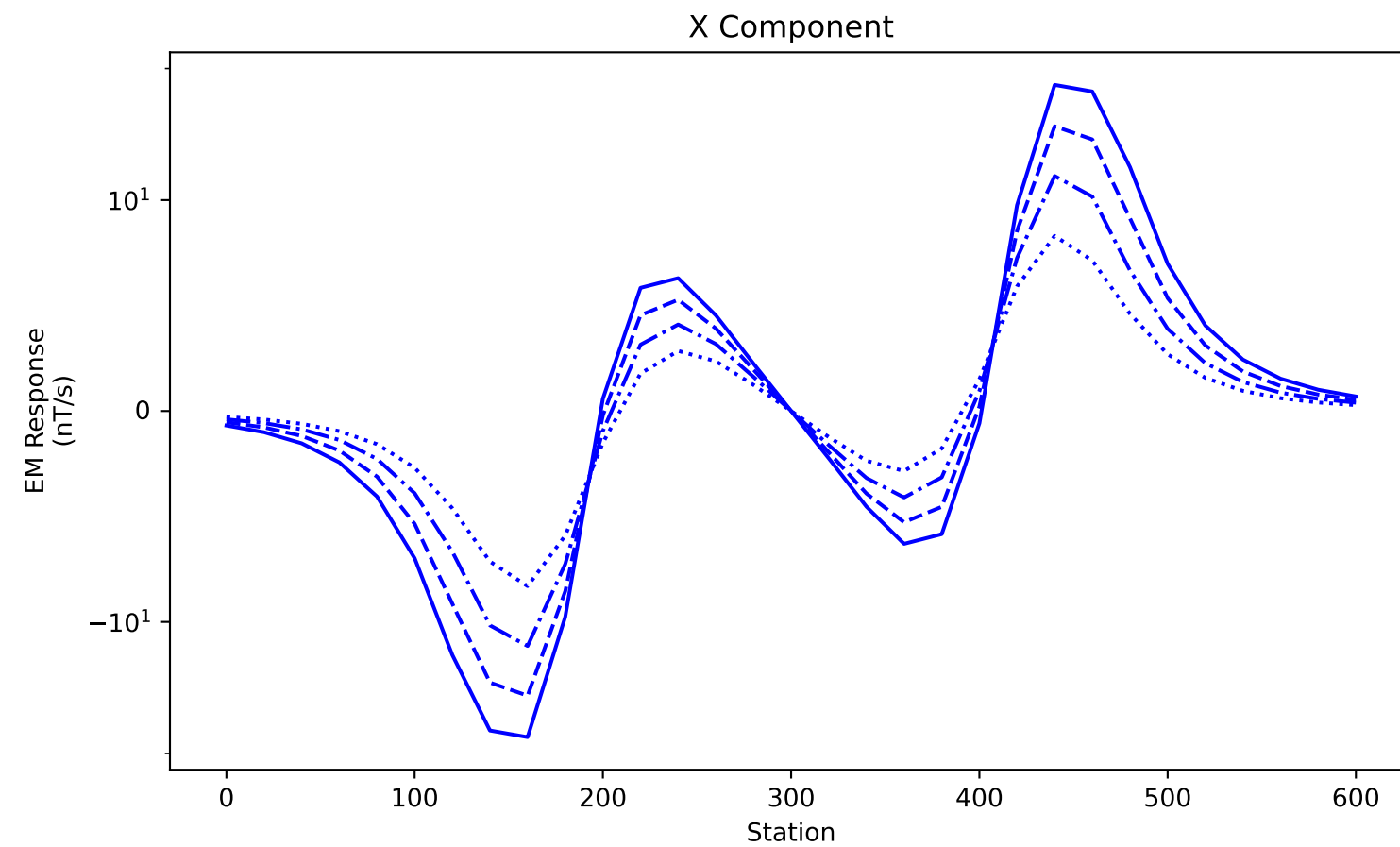
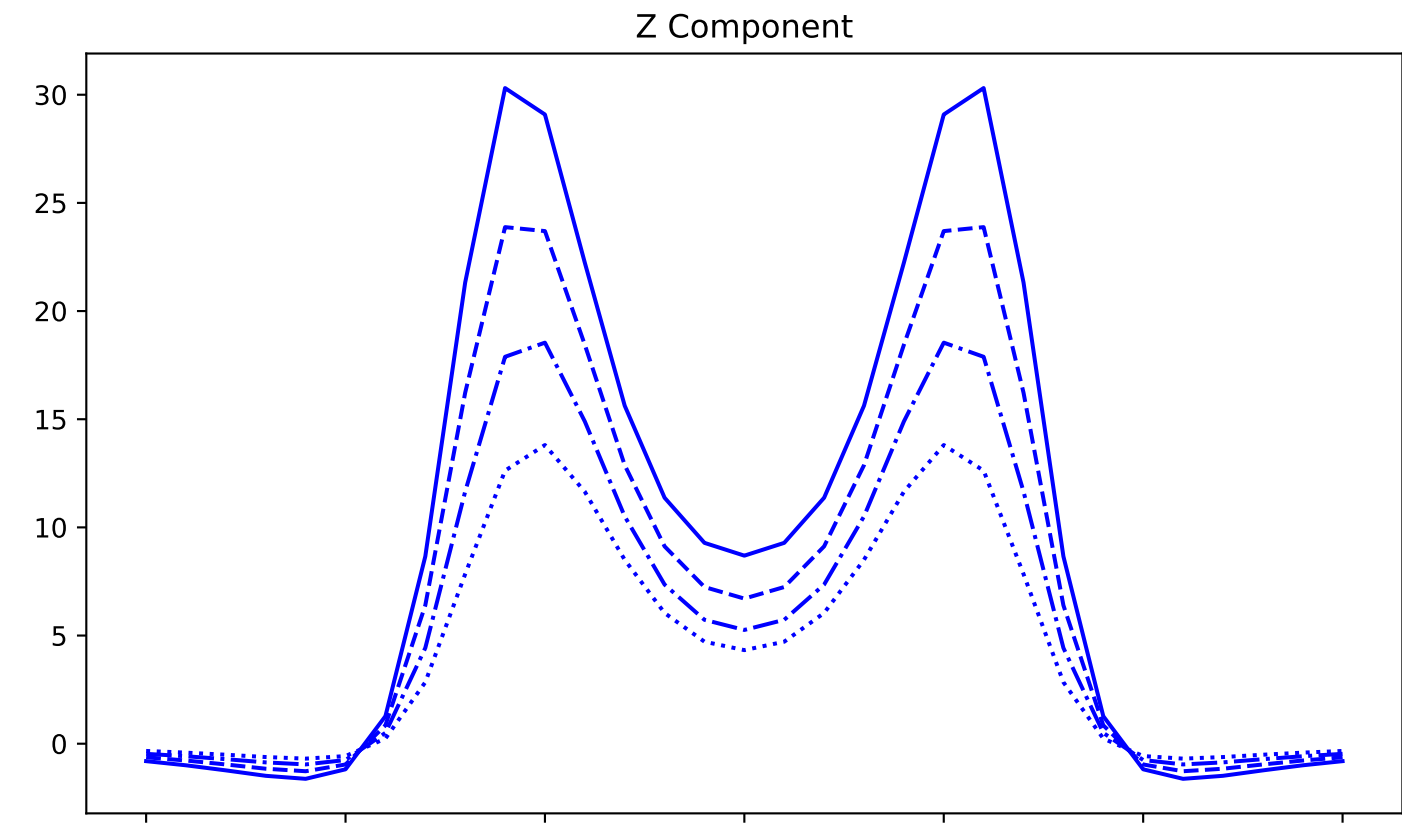
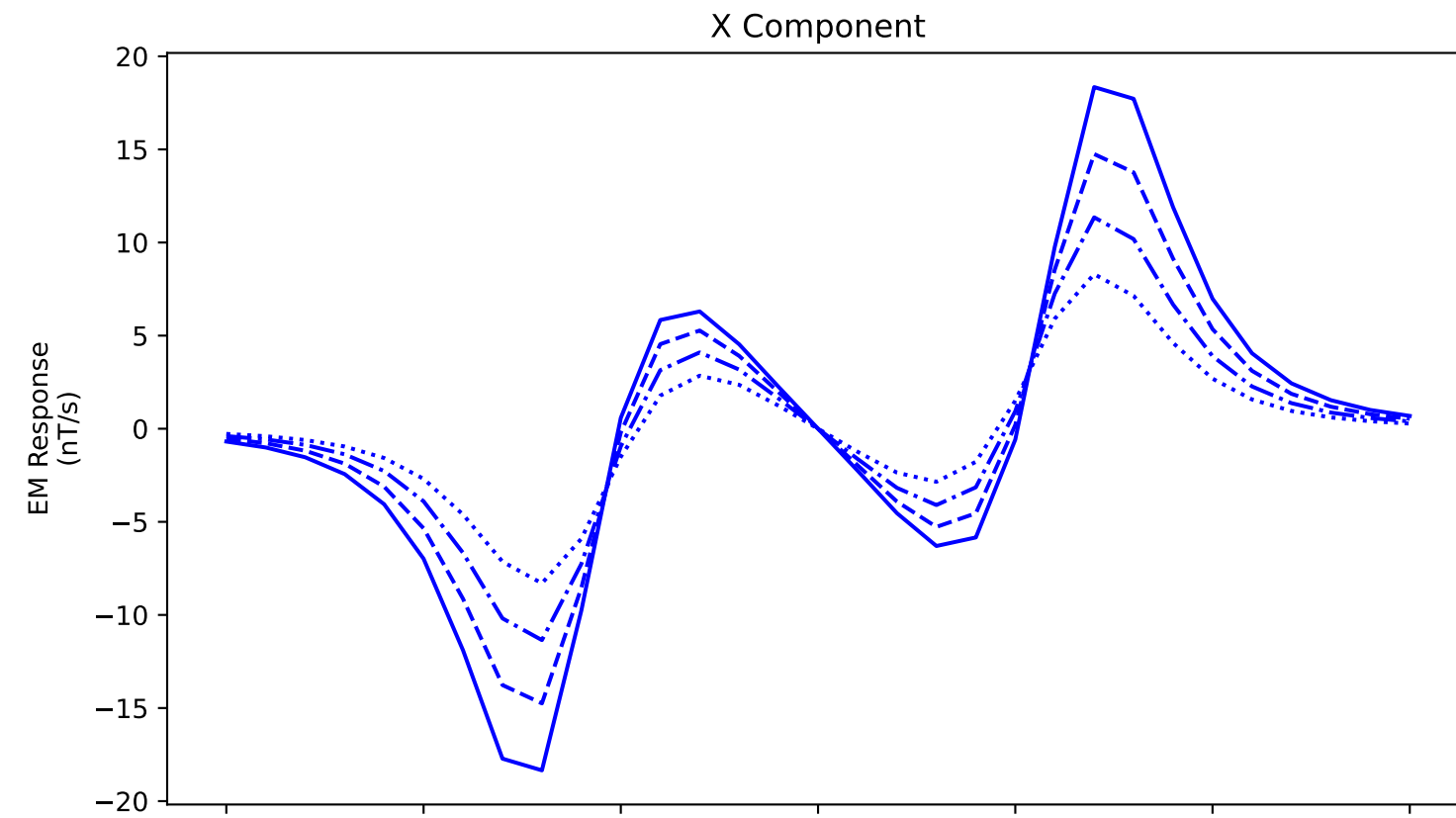
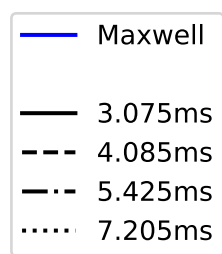
Two-Way Induction
300x100m, 1000S
LOOP=-200
0.56ms to 1.315ms



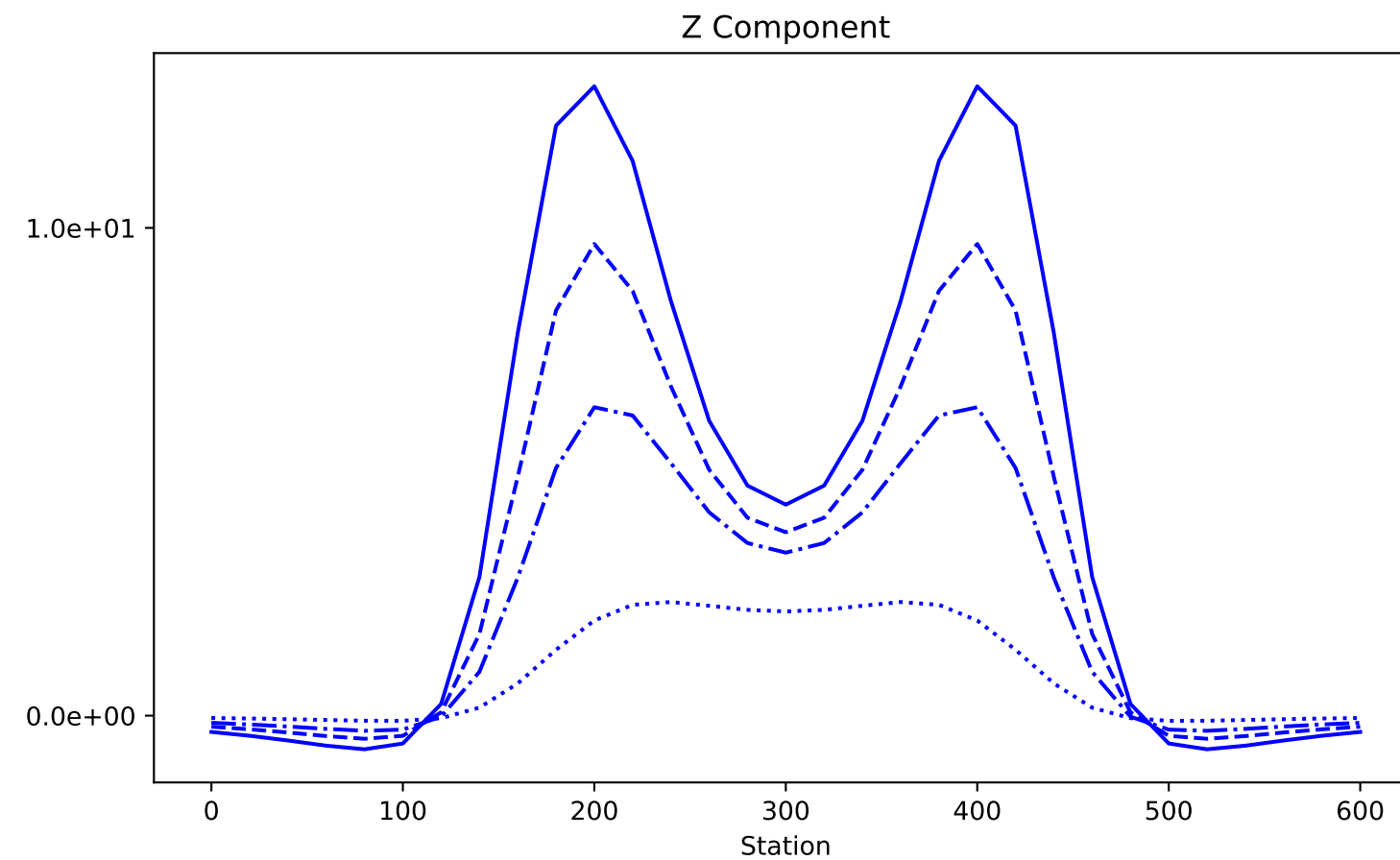
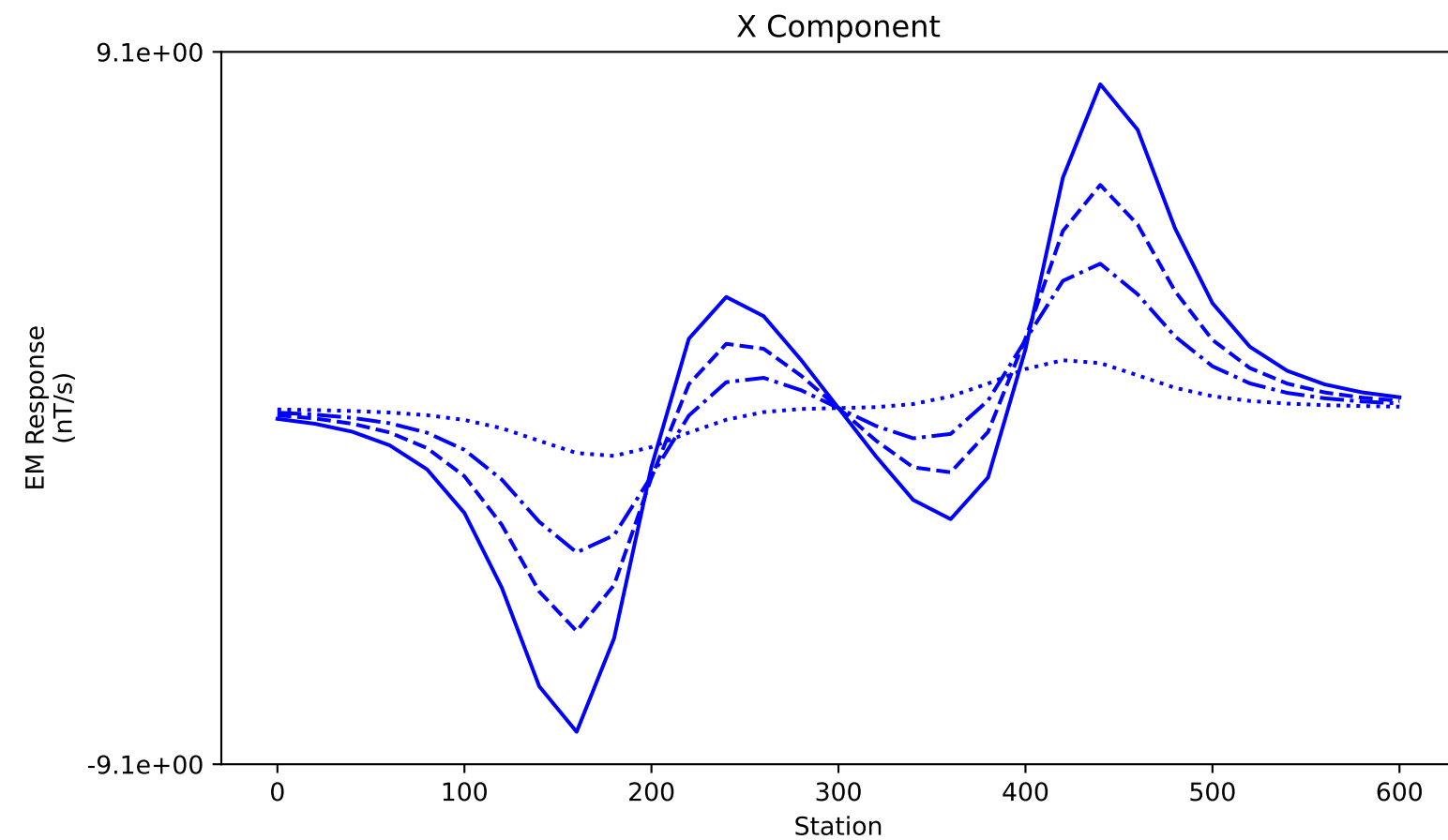
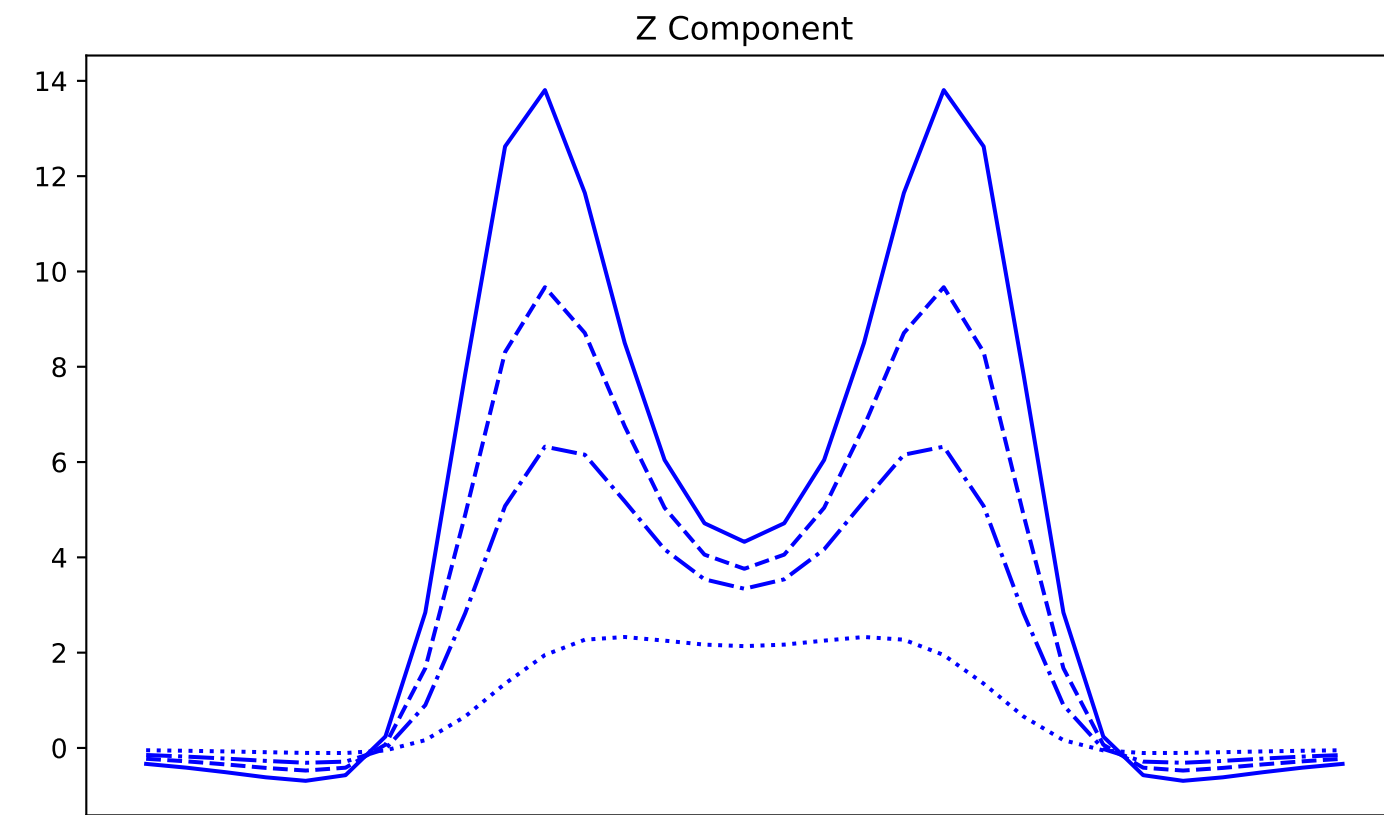
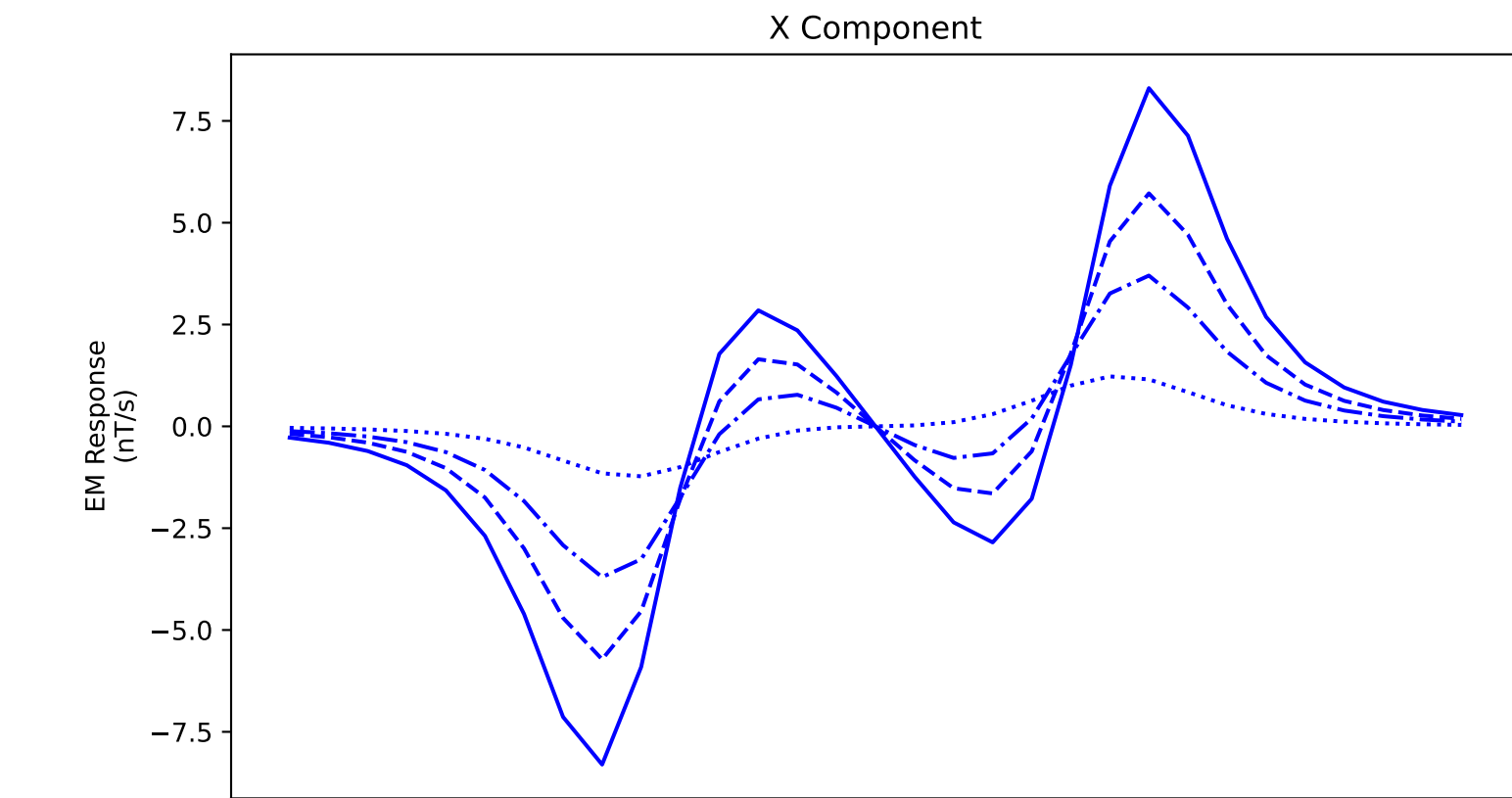
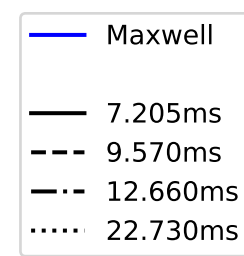
Two-Way Induction
300x100m, 1000S
LOOP=-200
1.315ms to 3.075ms



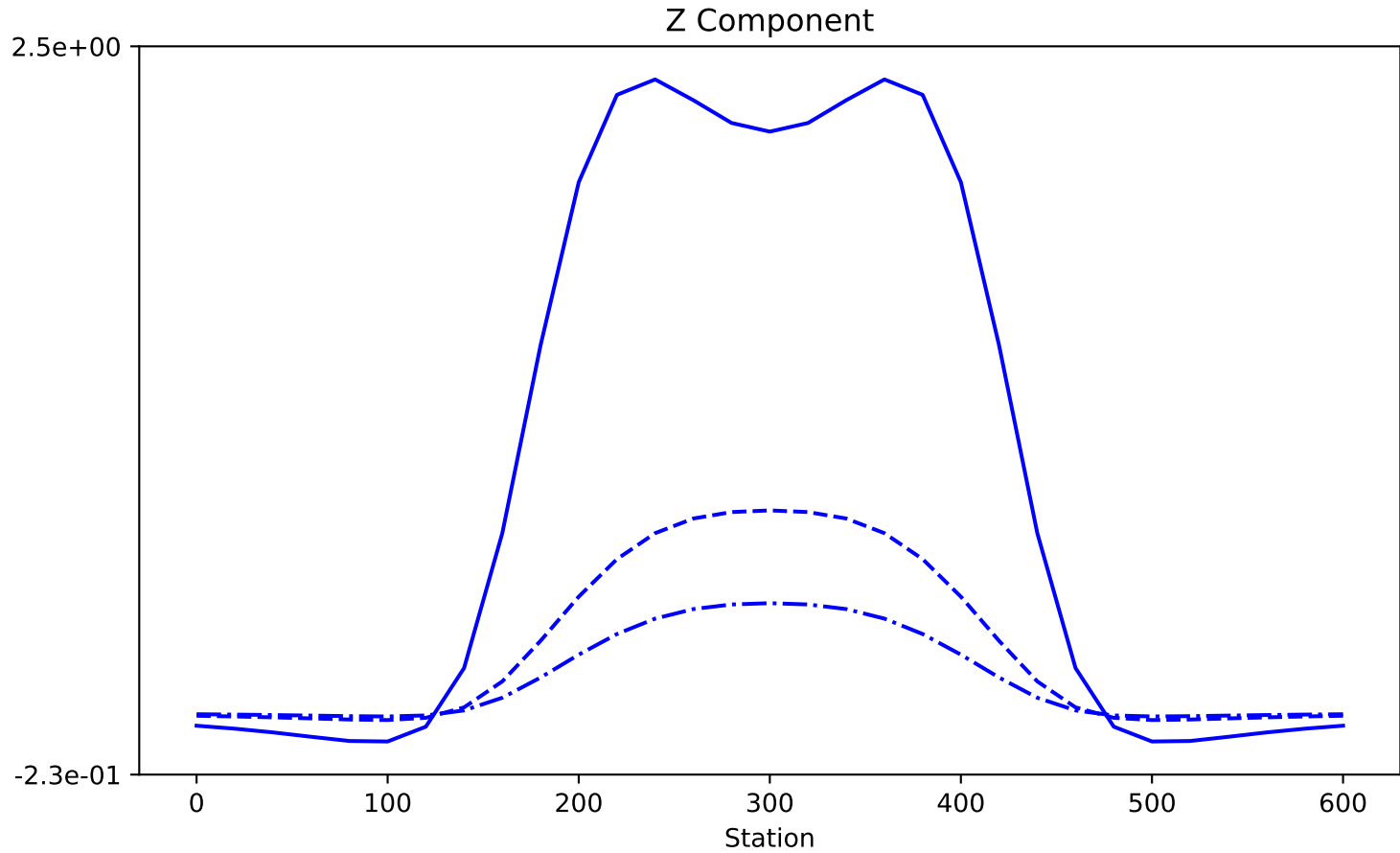
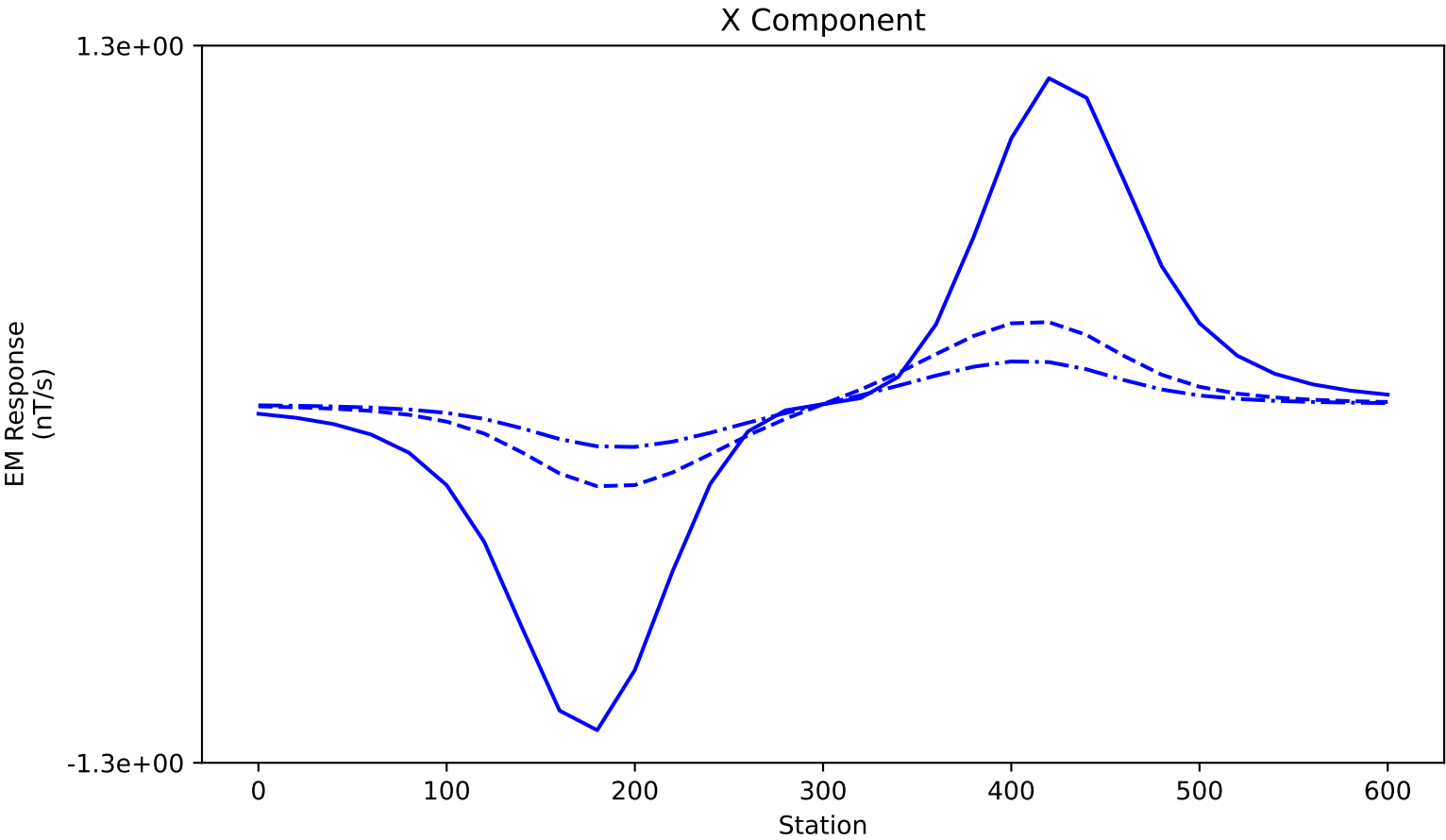
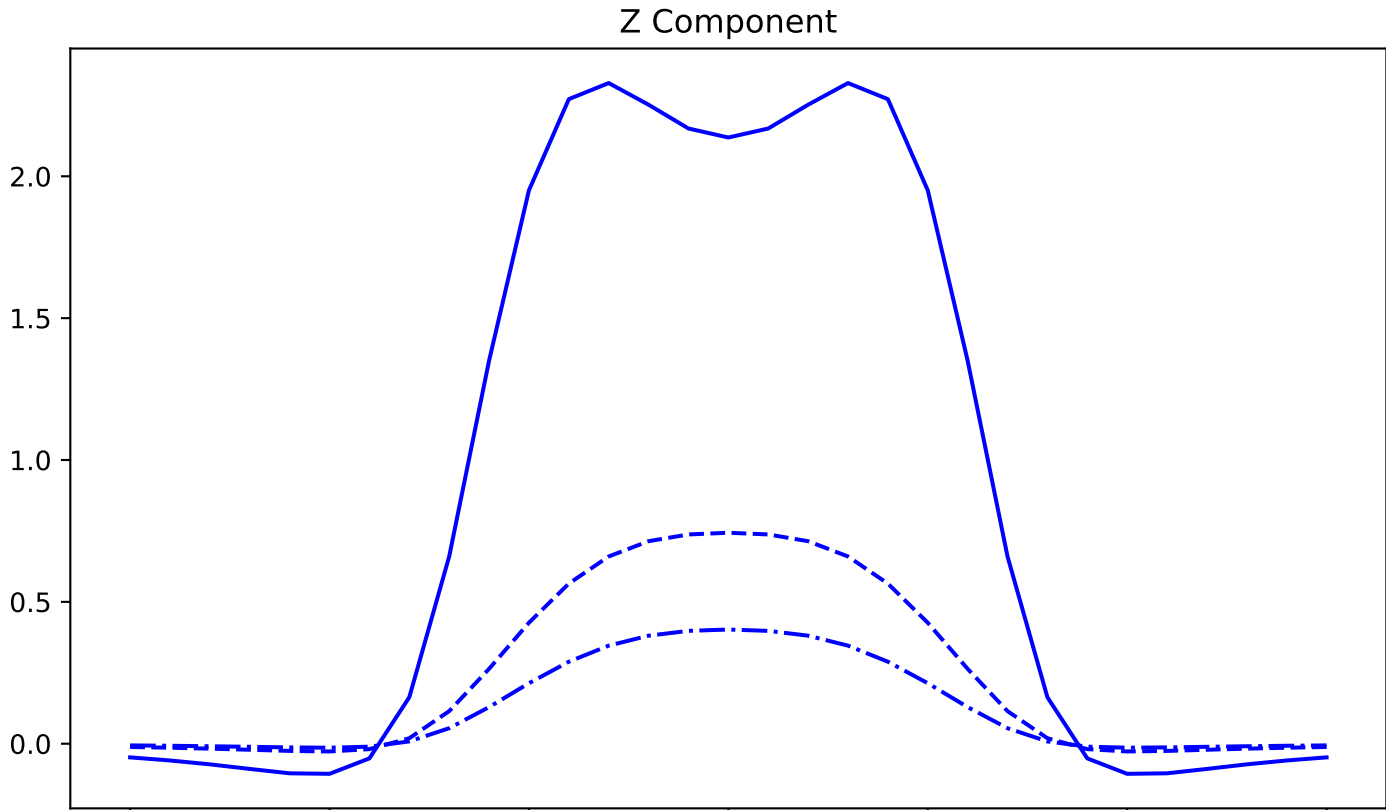
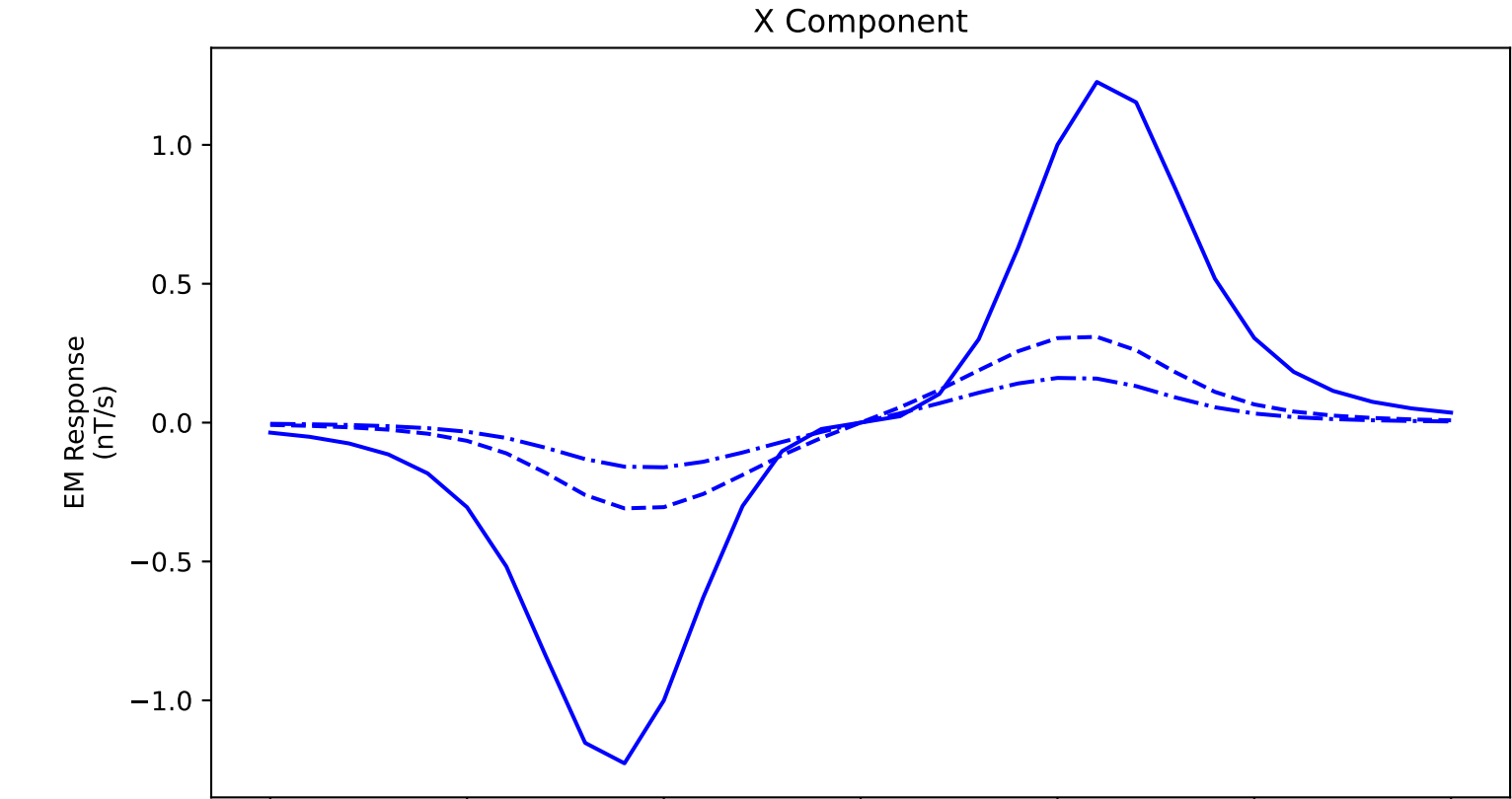
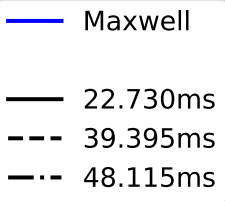
Two-Way Induction
300x100m, 1000S
LOOP=-200
3.075ms to 7.205ms



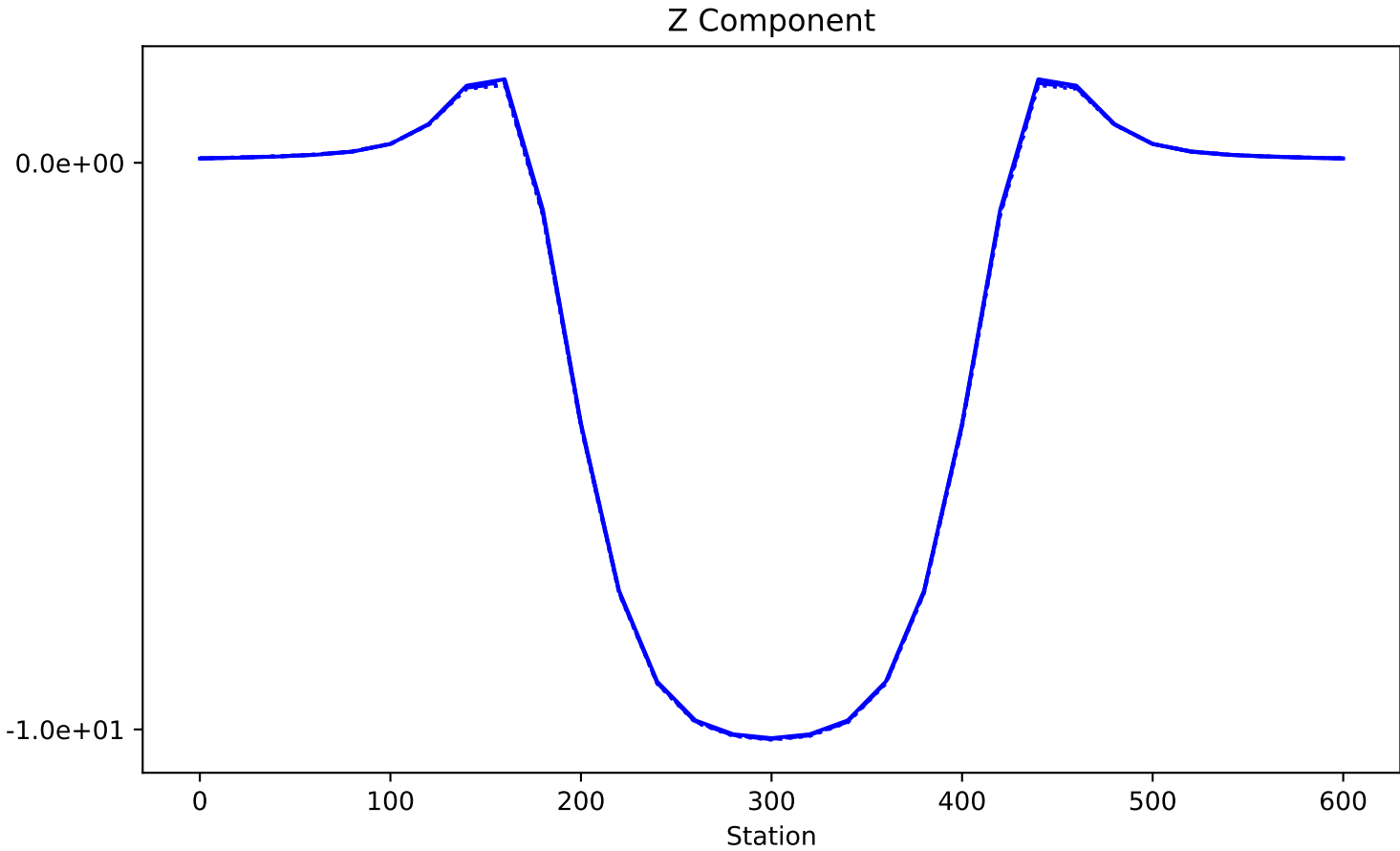
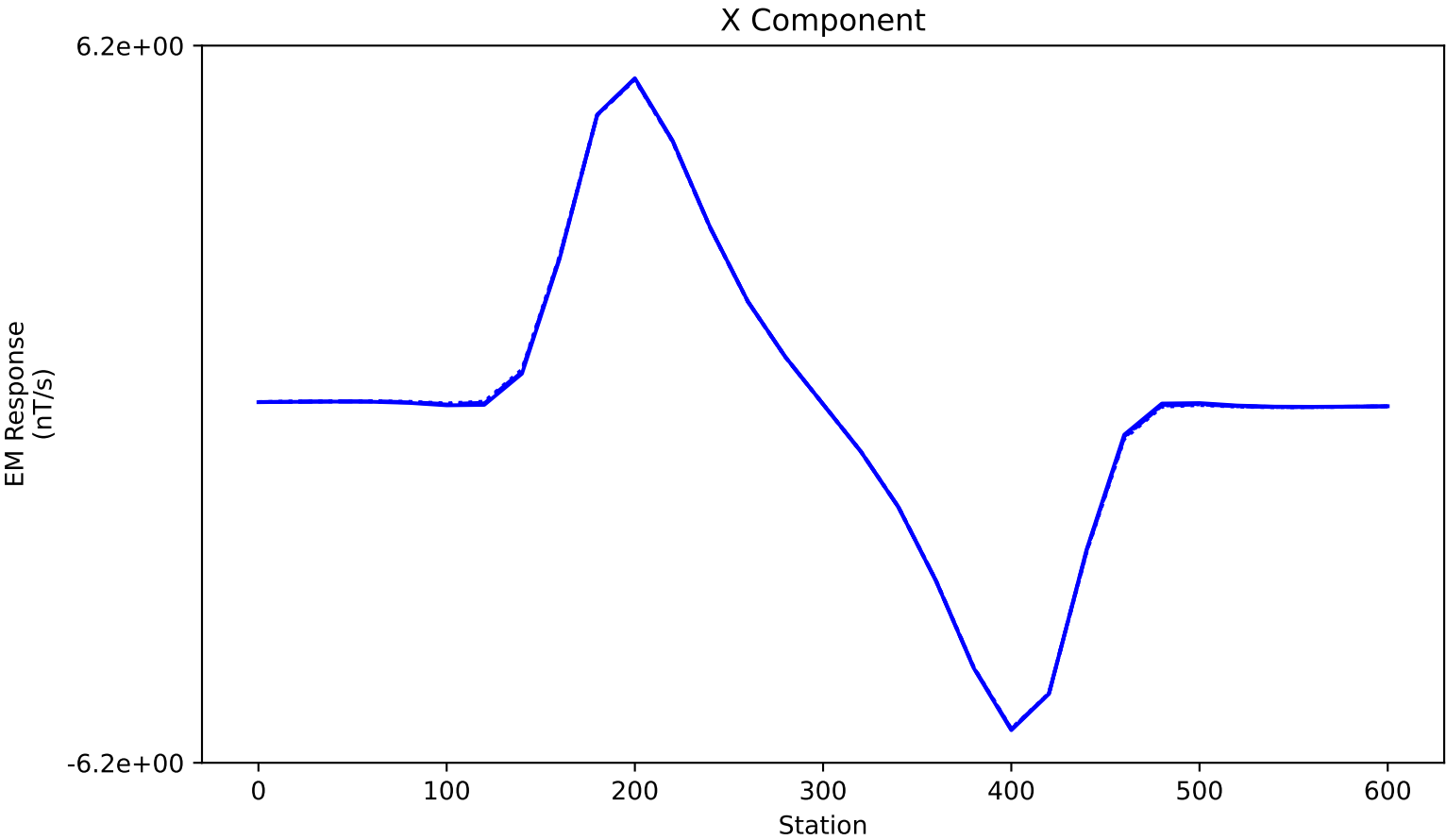
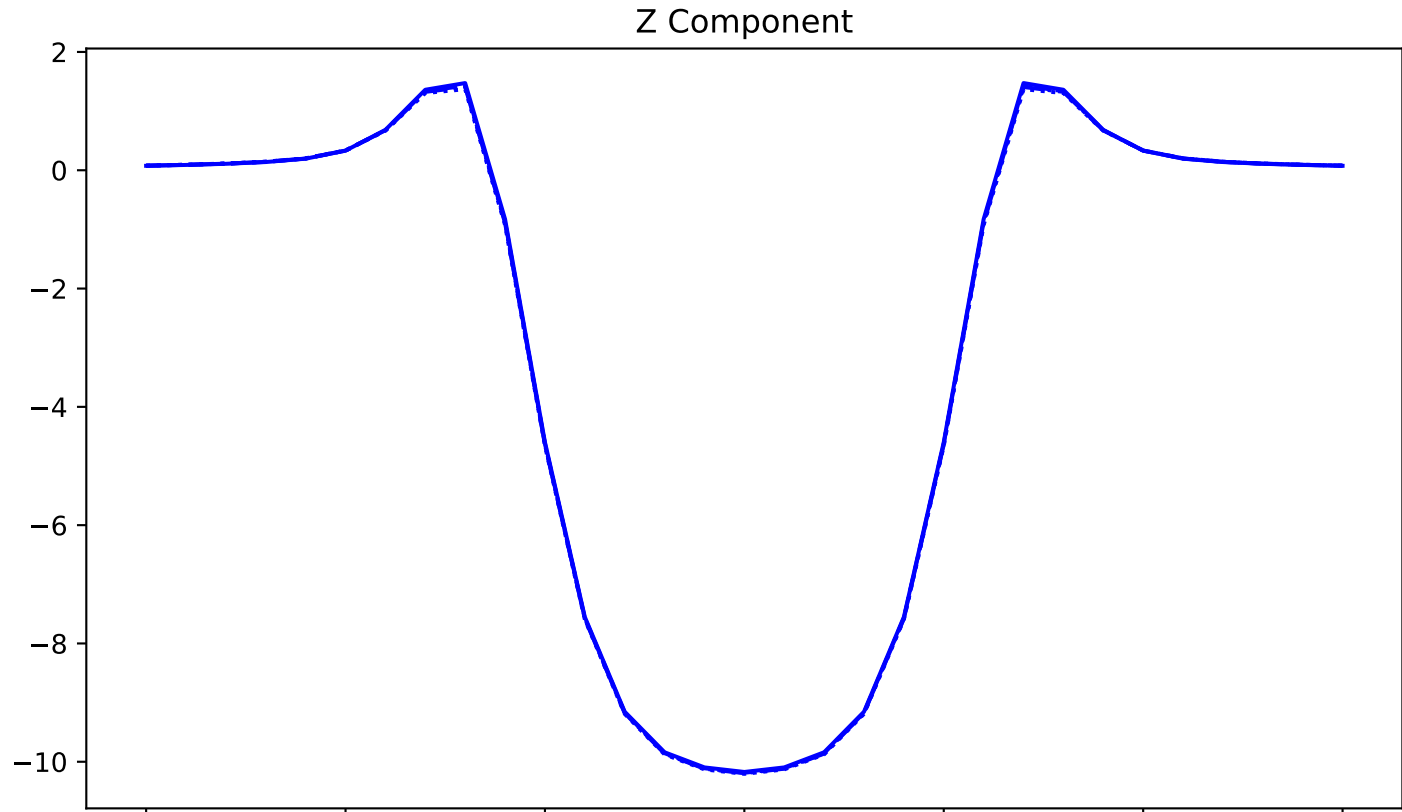
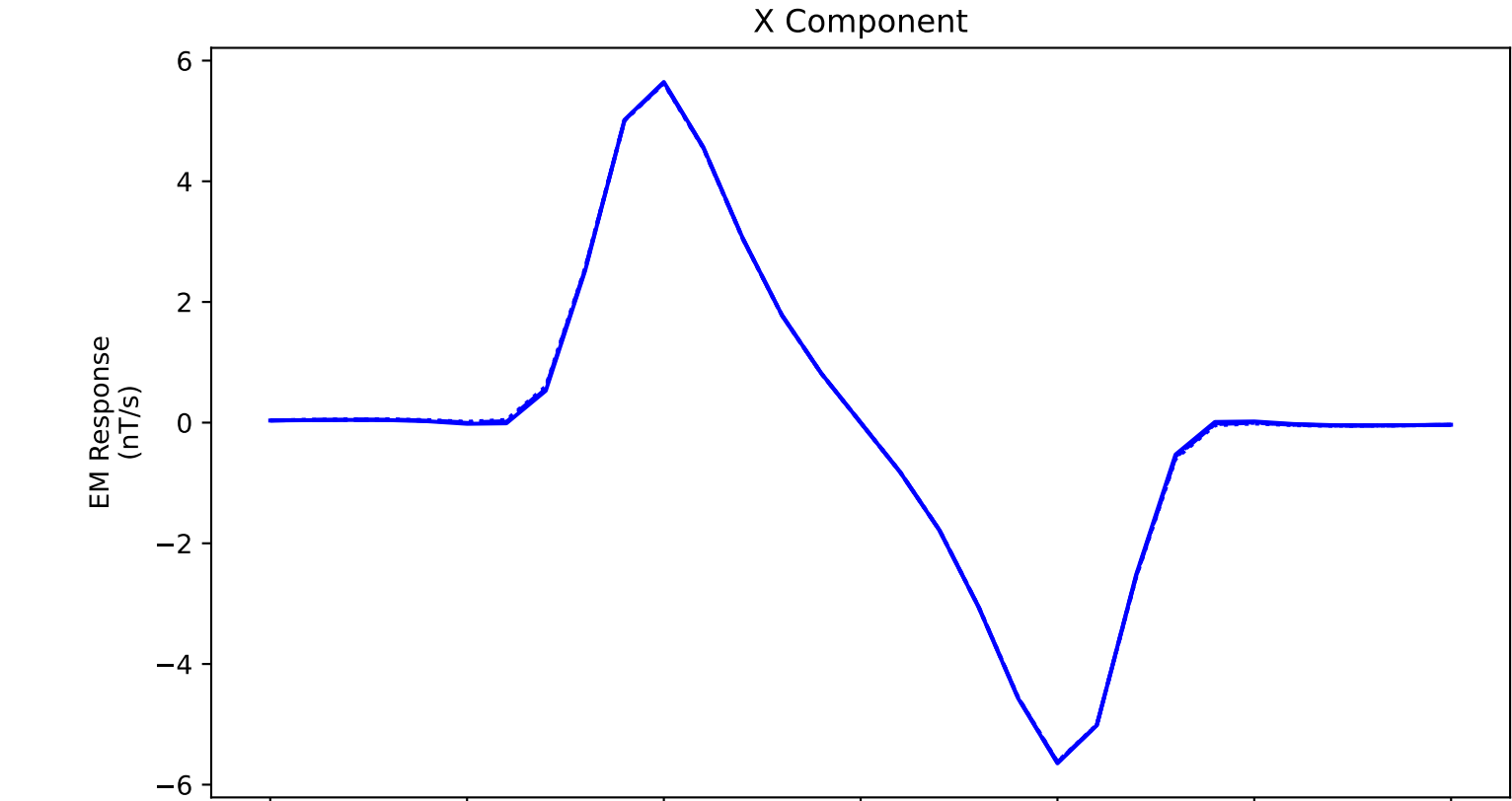
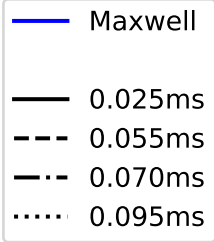
Two-Way Induction
300x100m, 1000S
LOOP=-200
7.205ms to 22.73ms



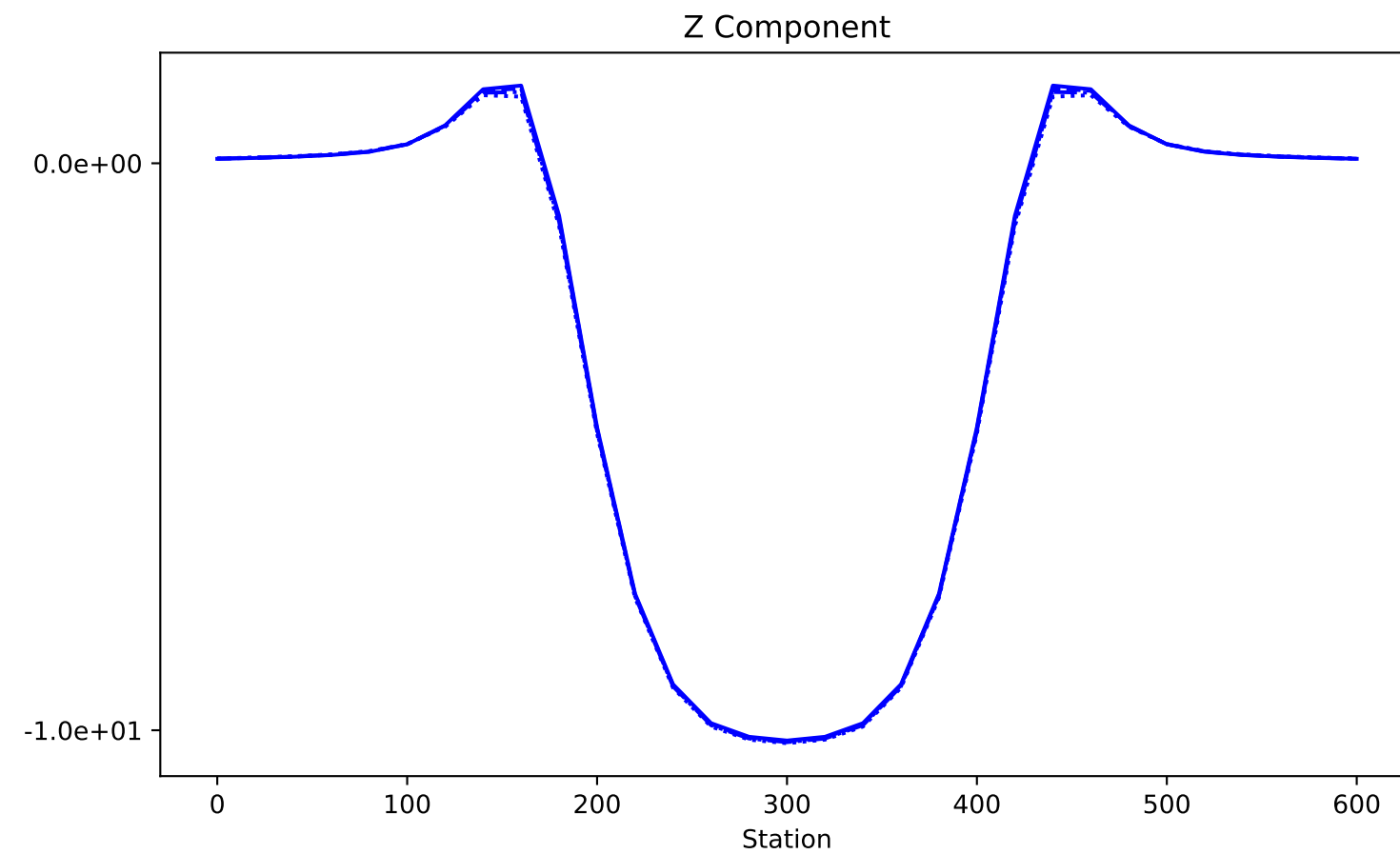
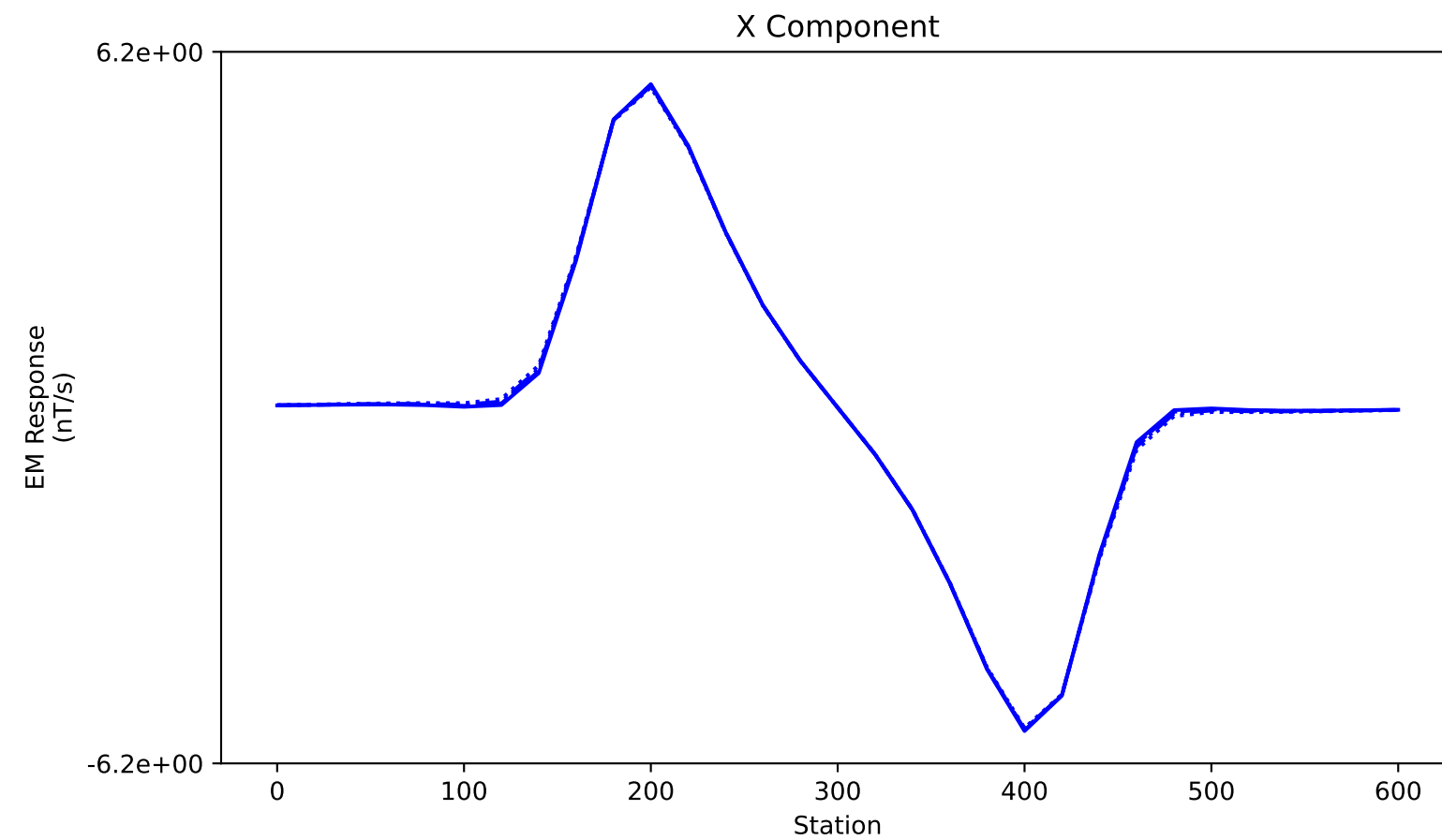
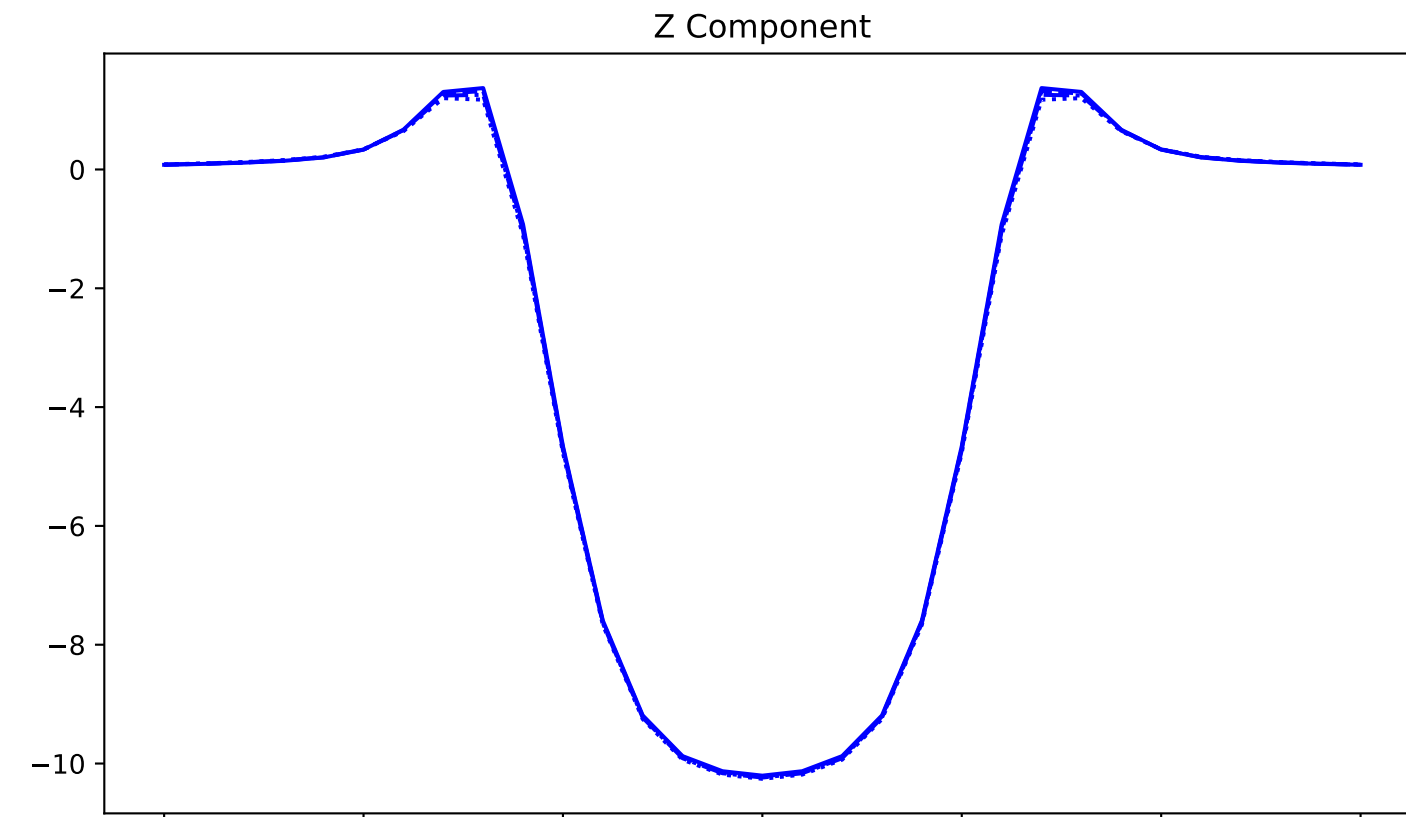
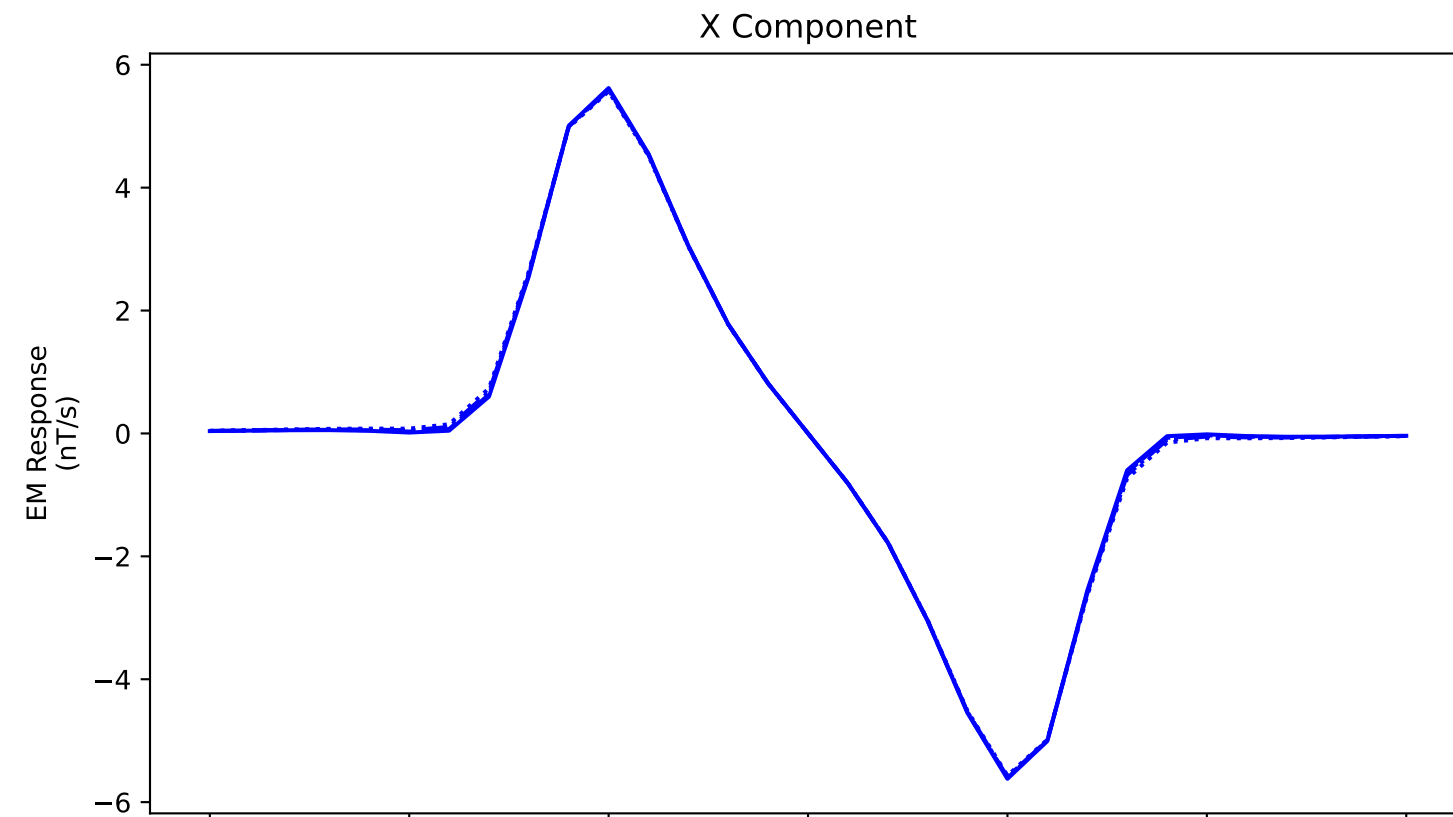
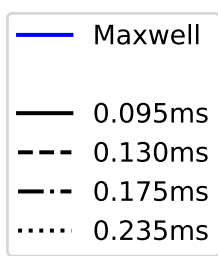
Two-Way Induction
300x100m, 1000S
LOOP=-200
22.73ms to 48.115ms



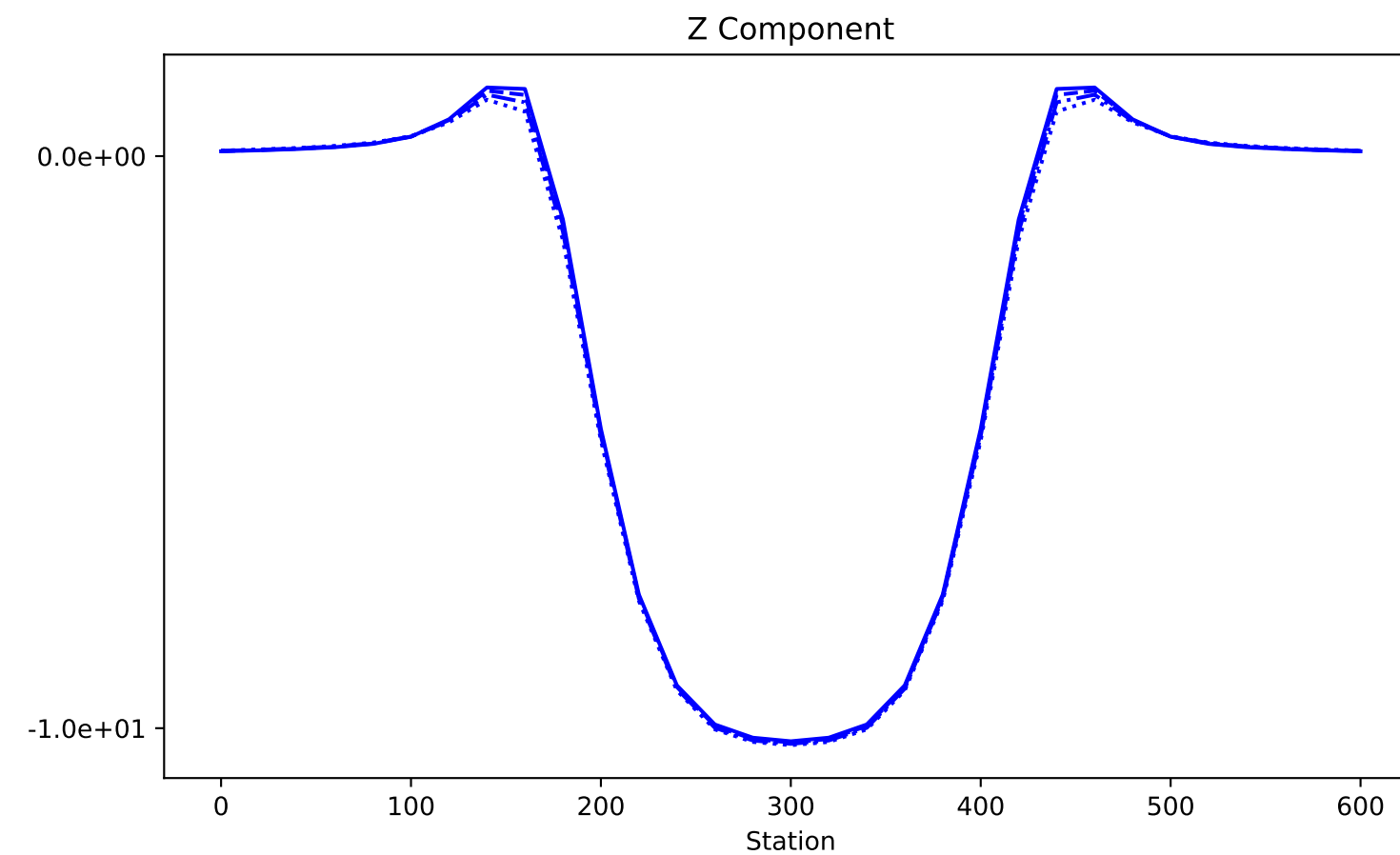
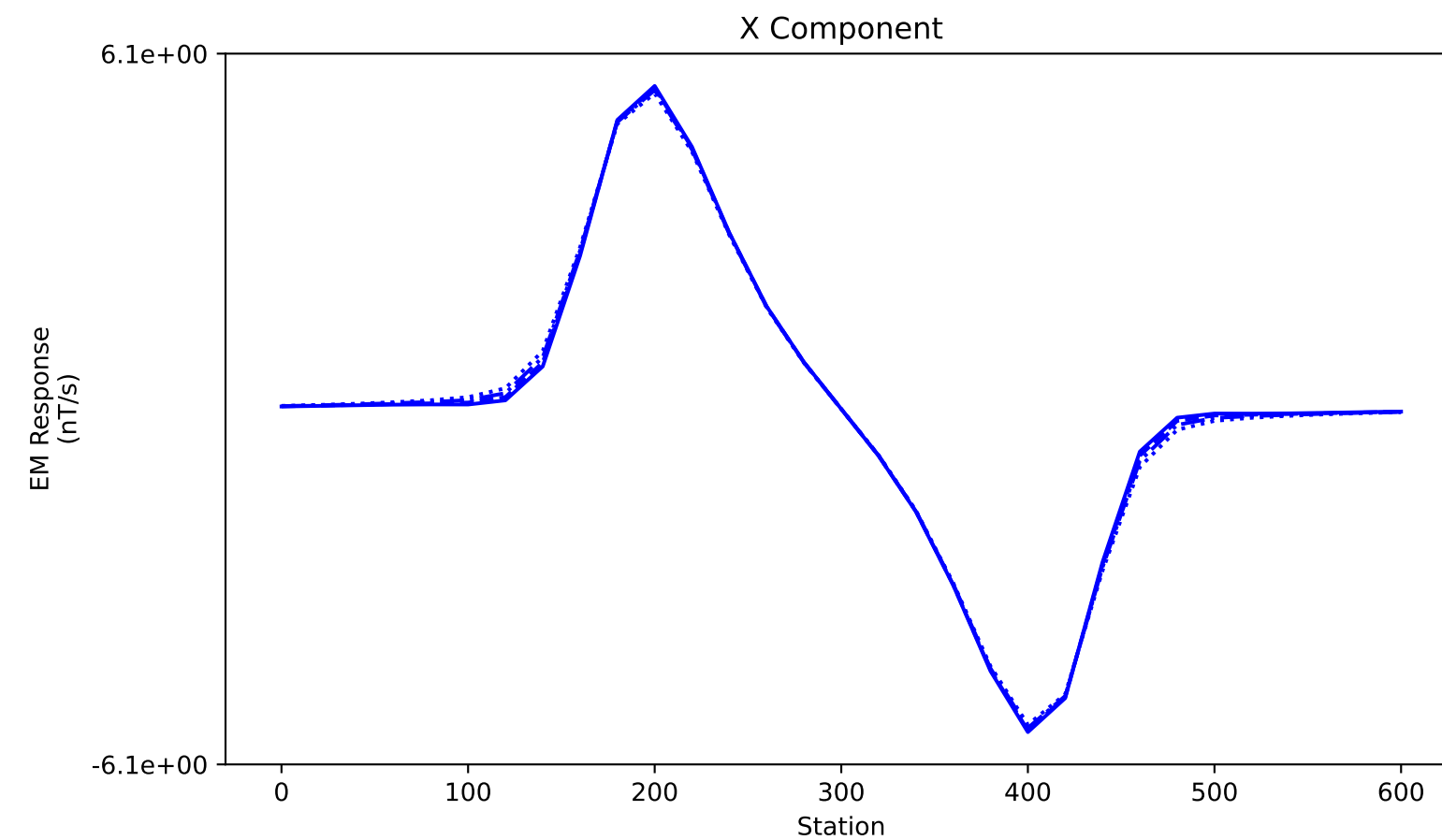
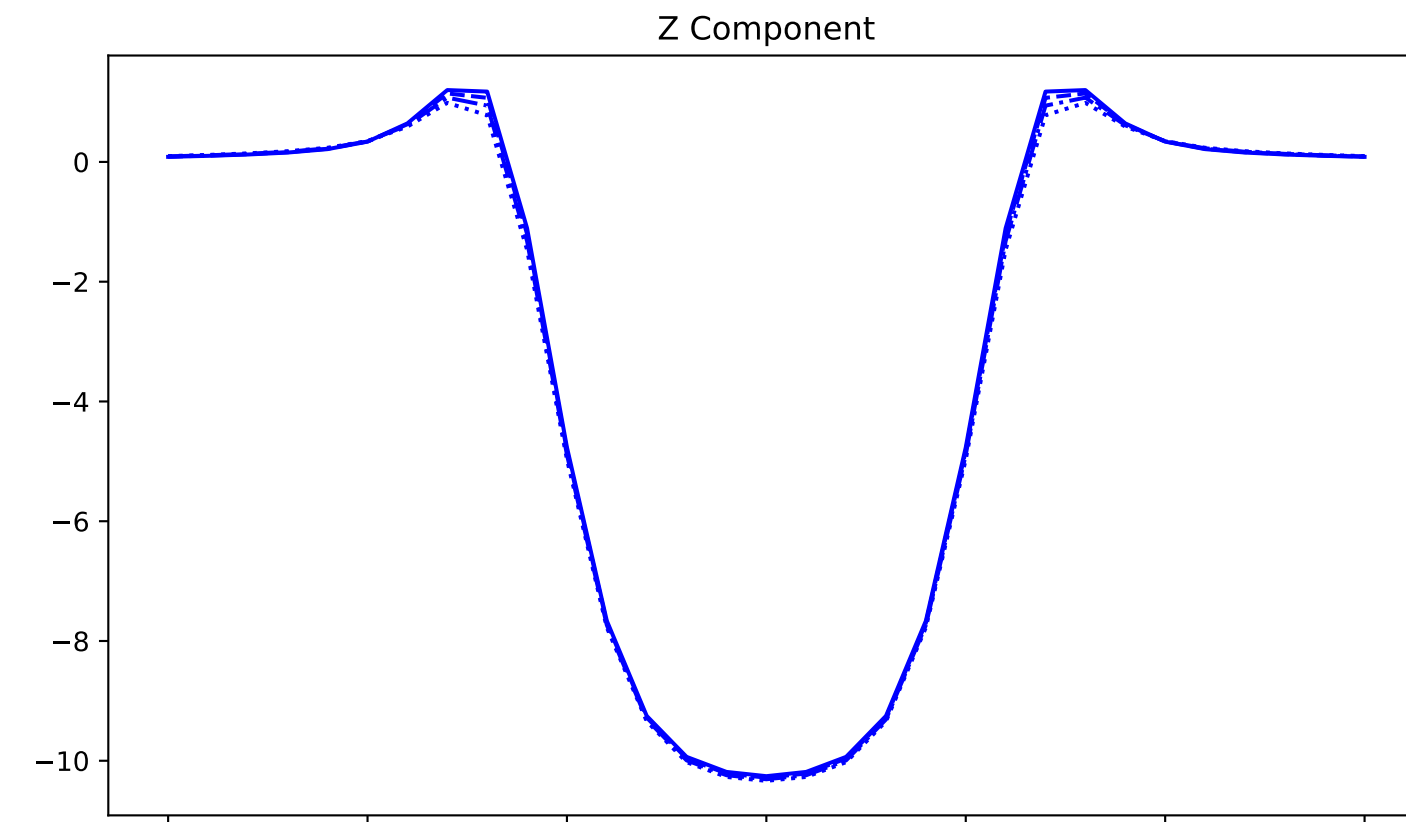
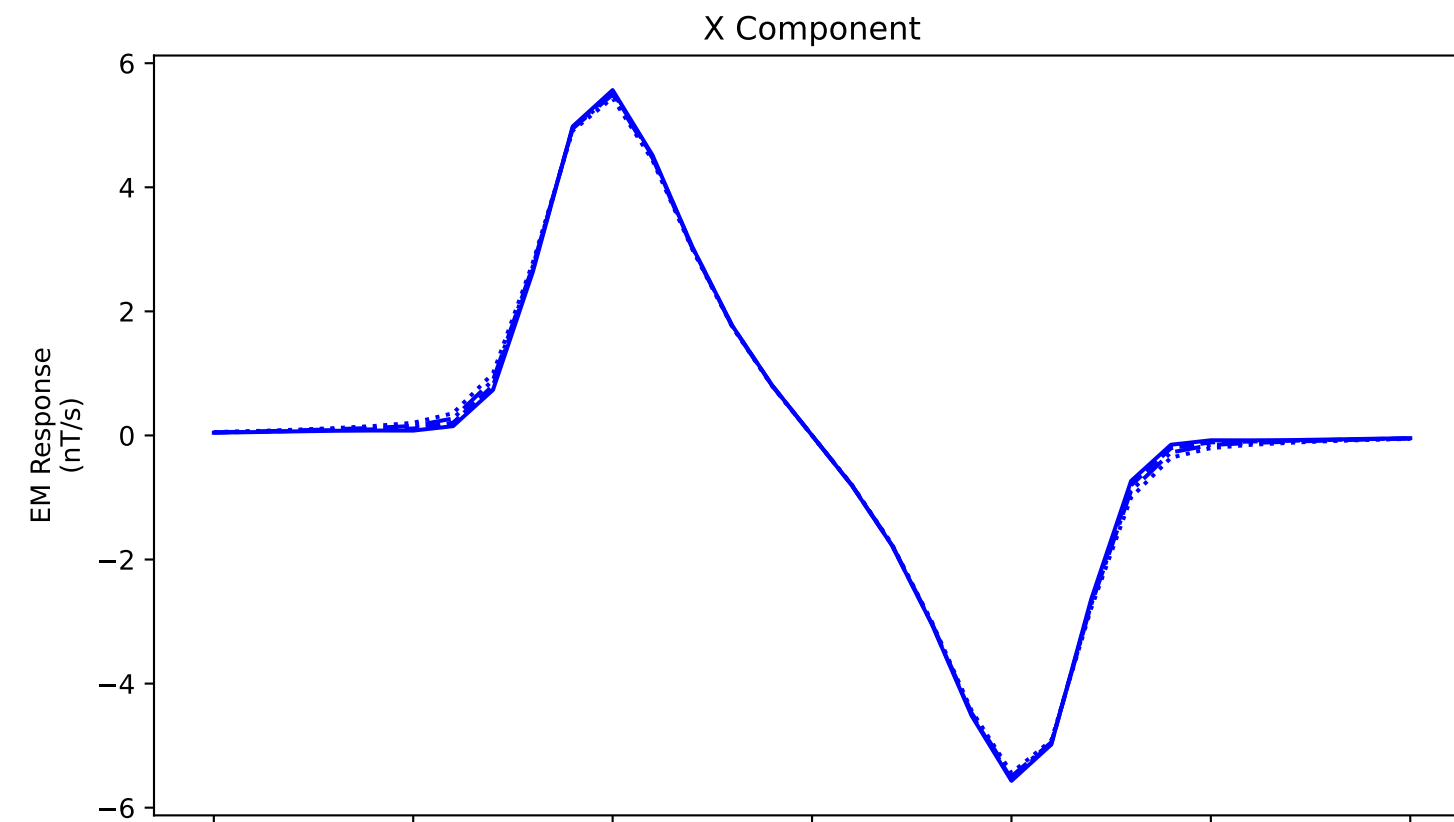
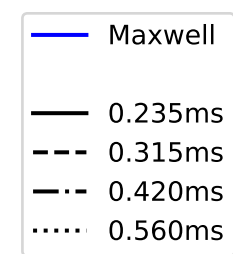
Two-Way Induction
300x100m, 1000S
LOOP=-250
0.0255ms to 0.095ms



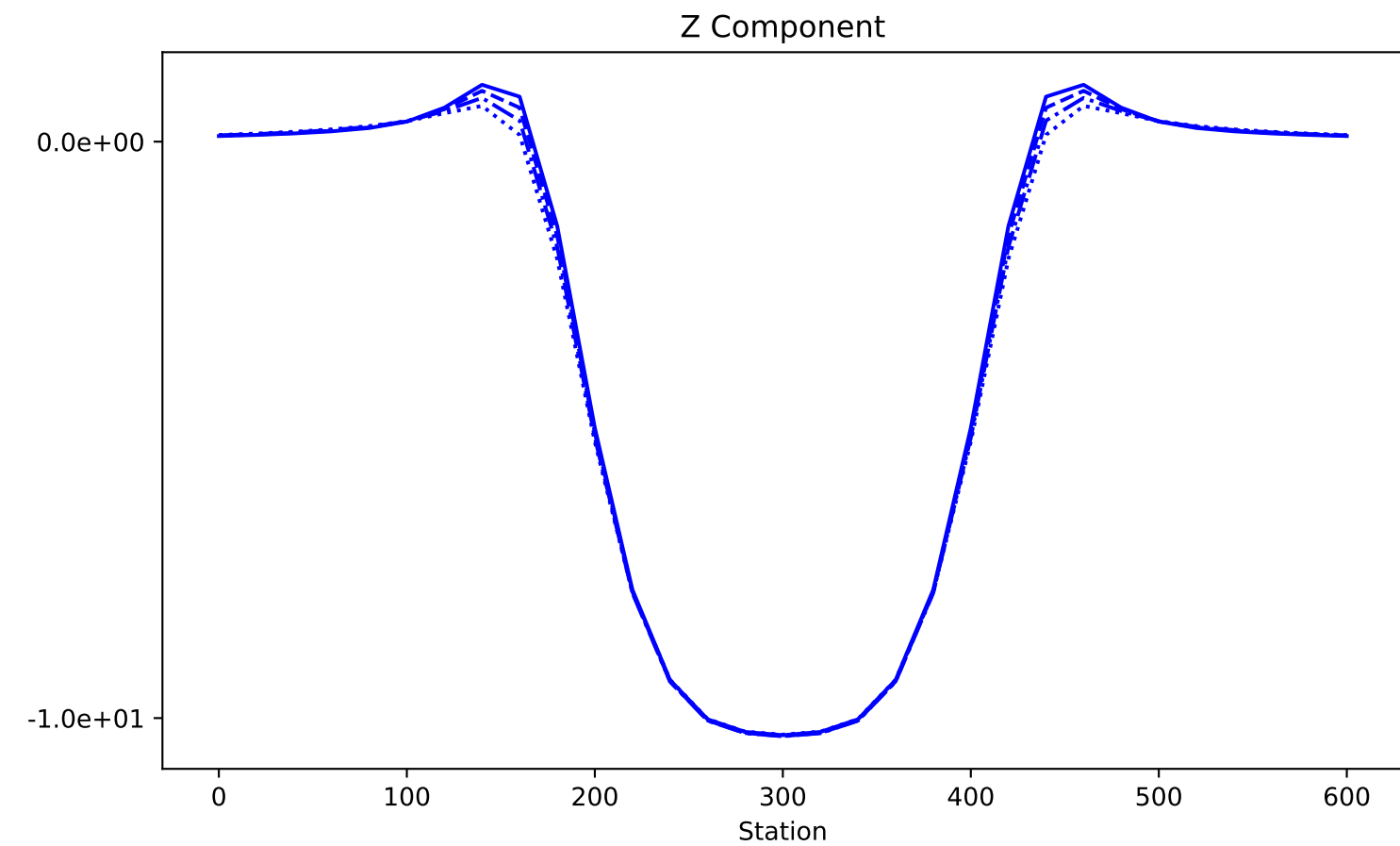
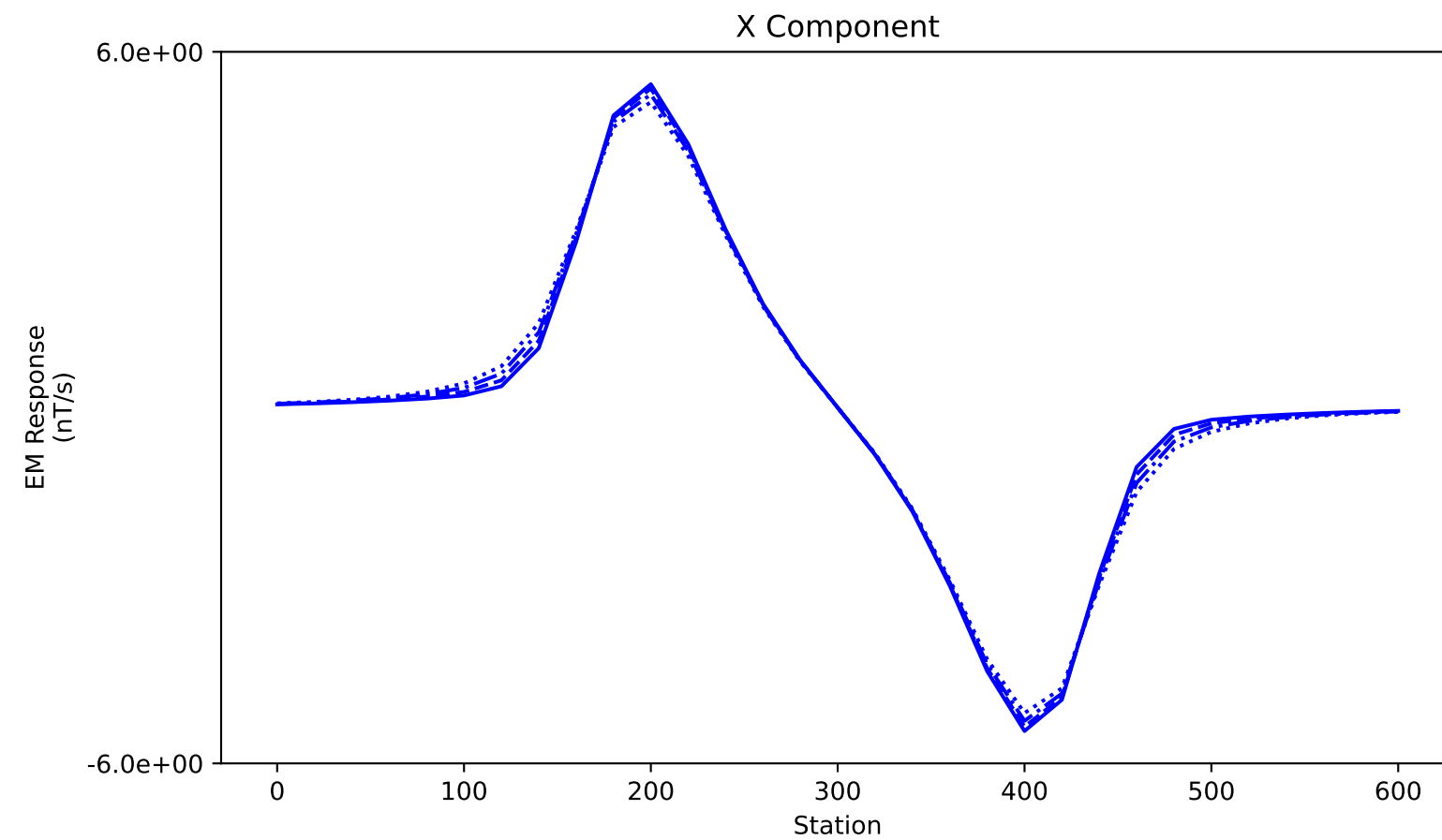
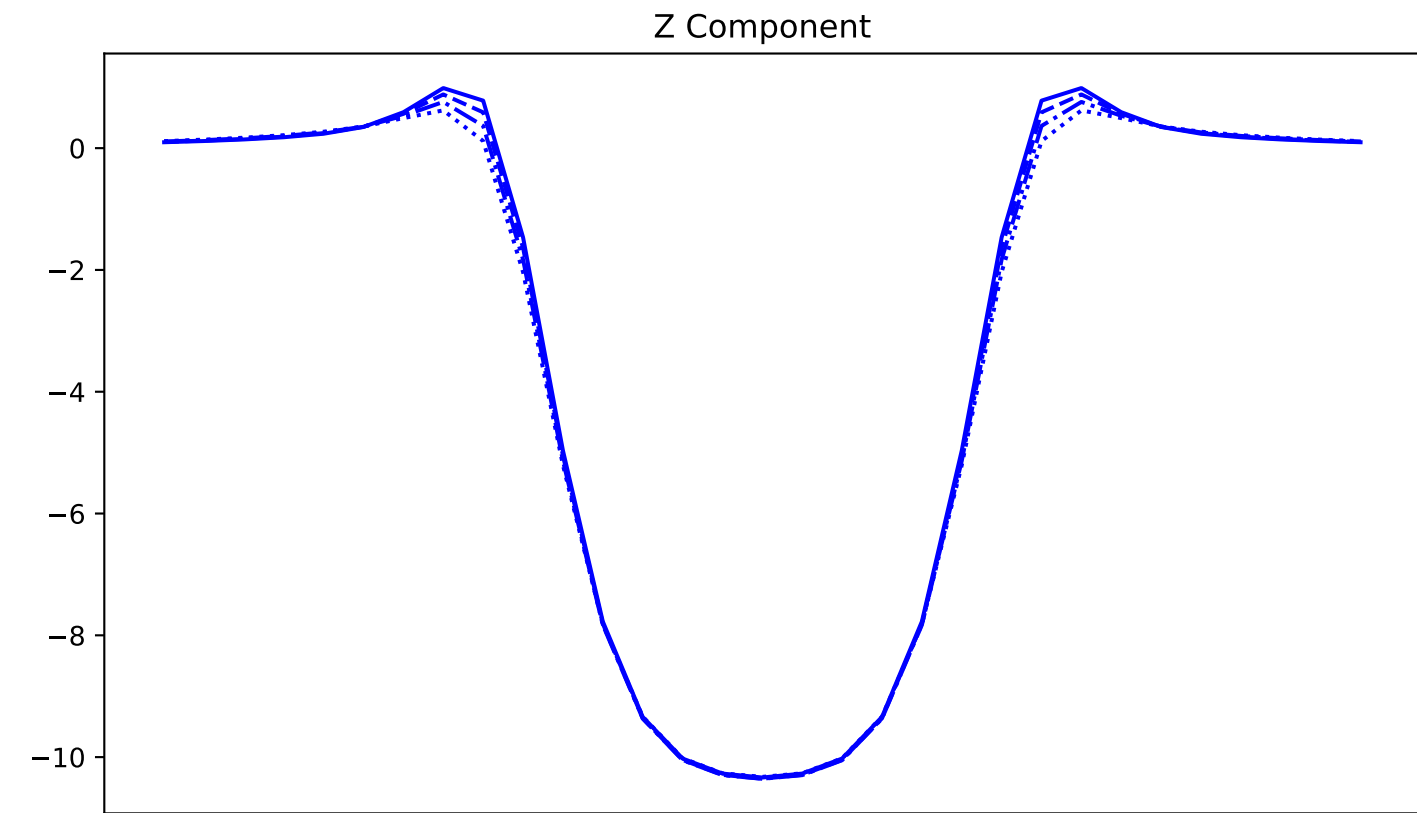
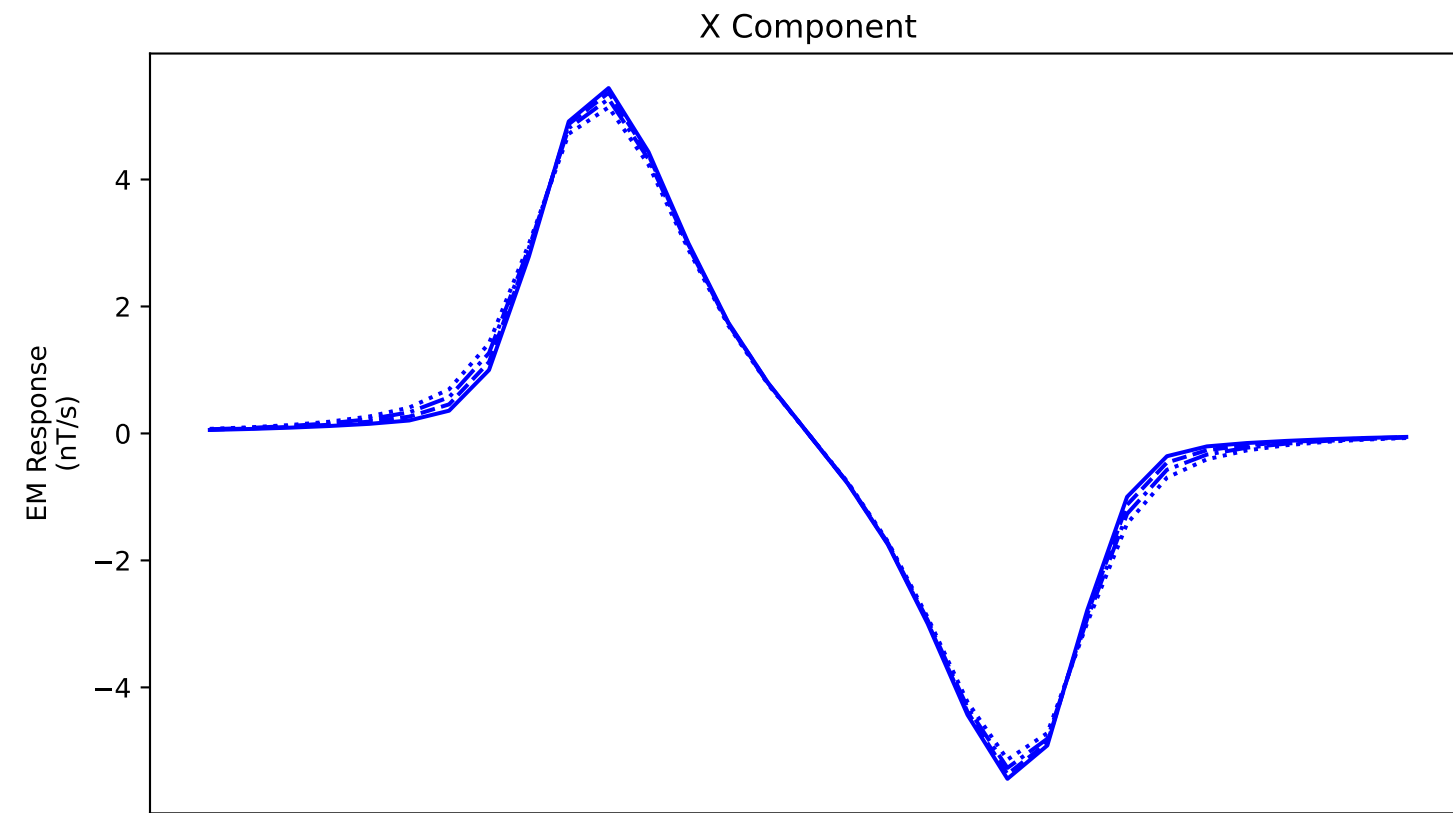
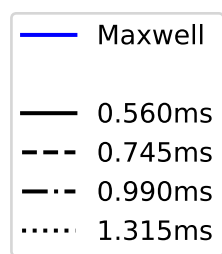
Two-Way Induction
300x100m, 1000S
LOOP=-250
0.095ms to 0.235ms



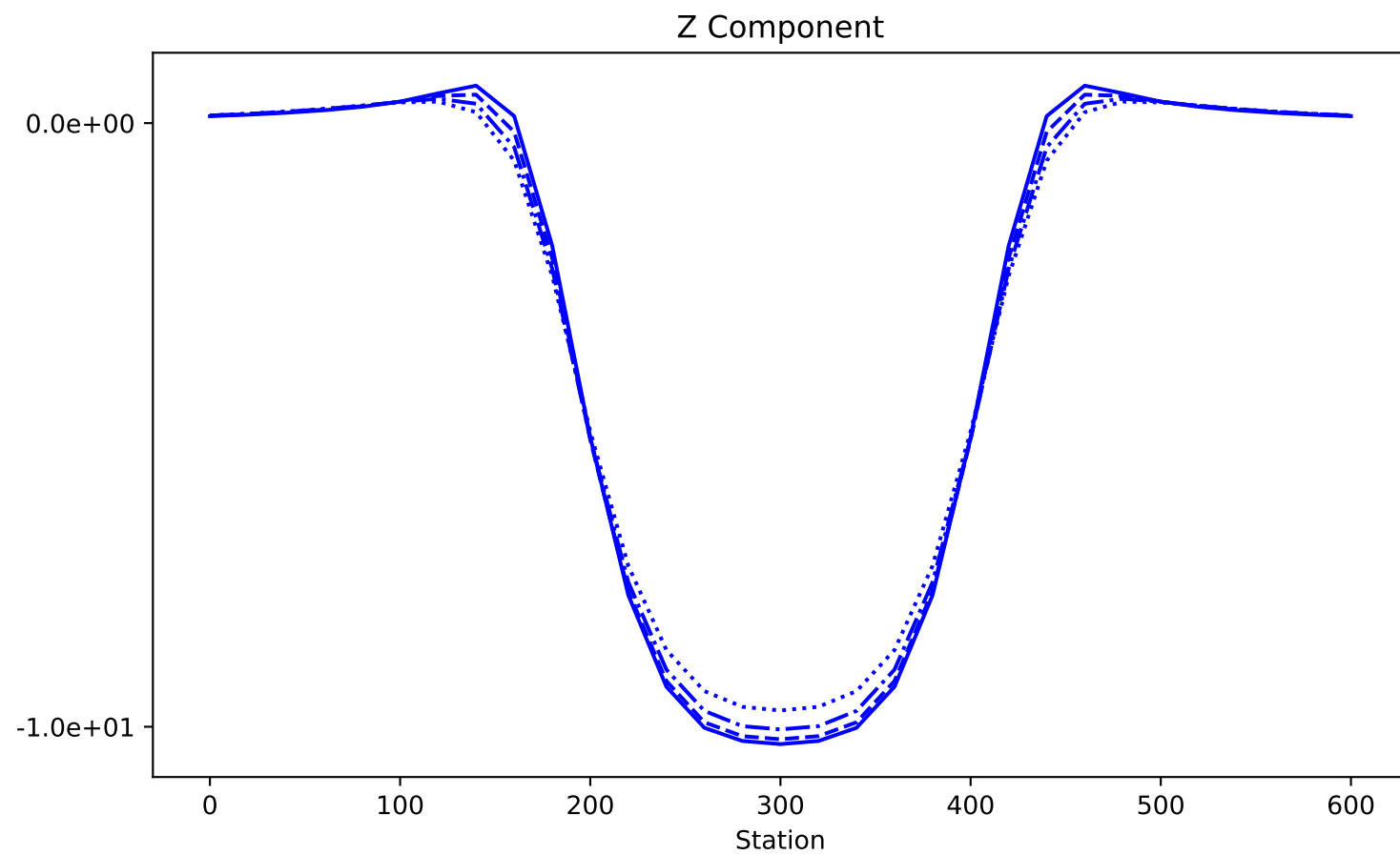
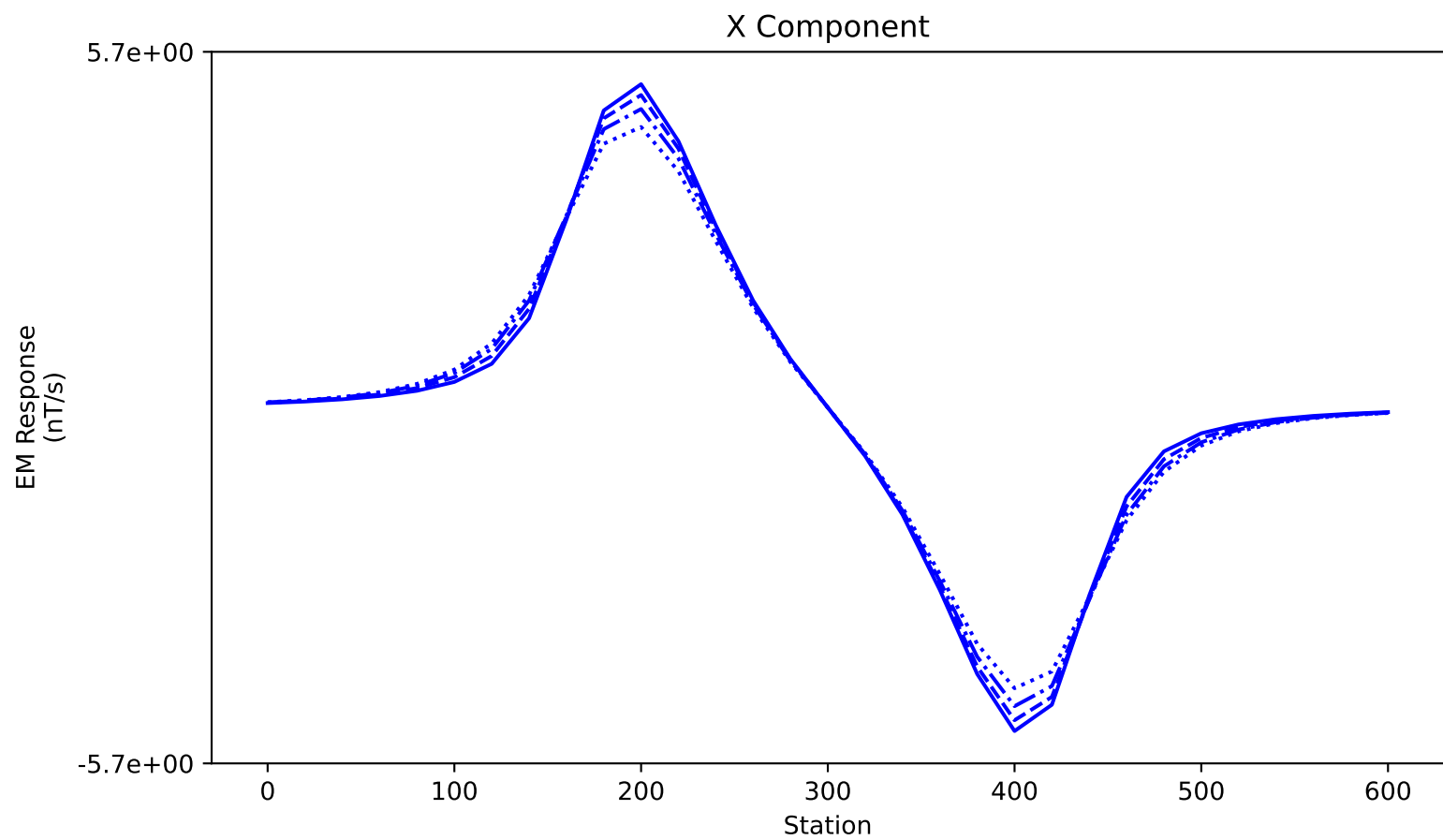
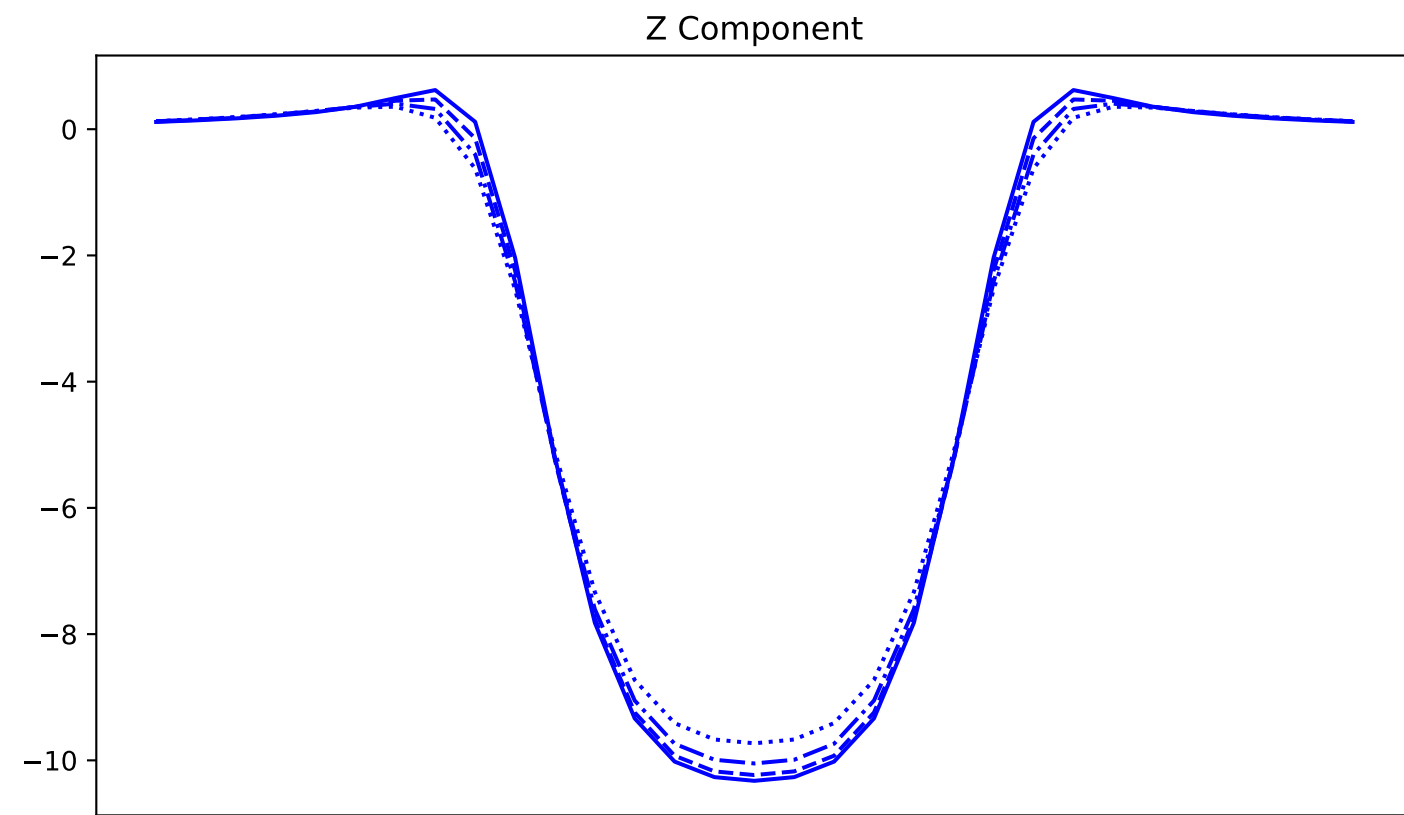
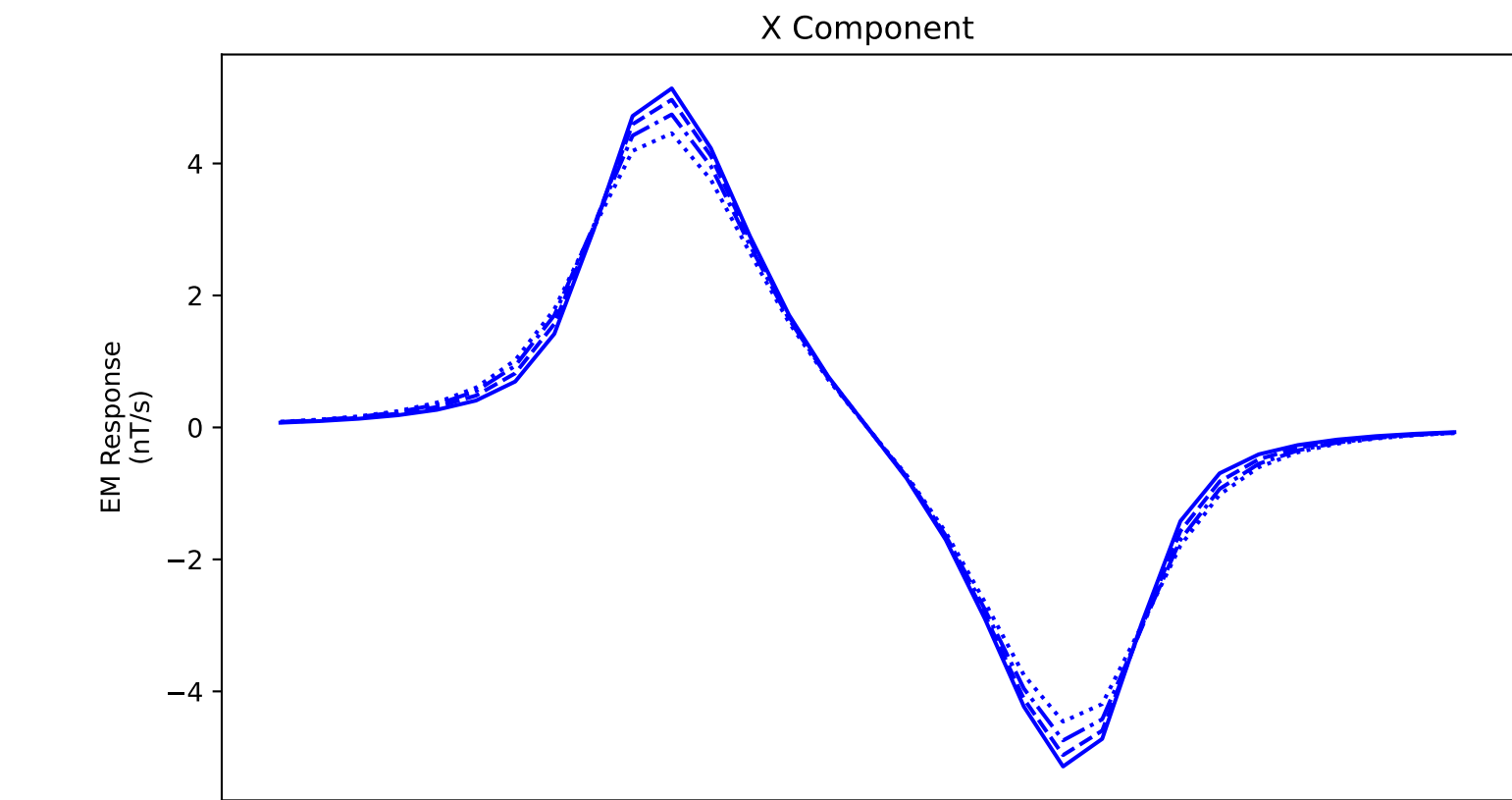
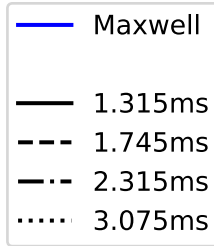
Two-Way Induction
300x100m, 1000S
LOOP=-250
0.235ms to 0.56ms



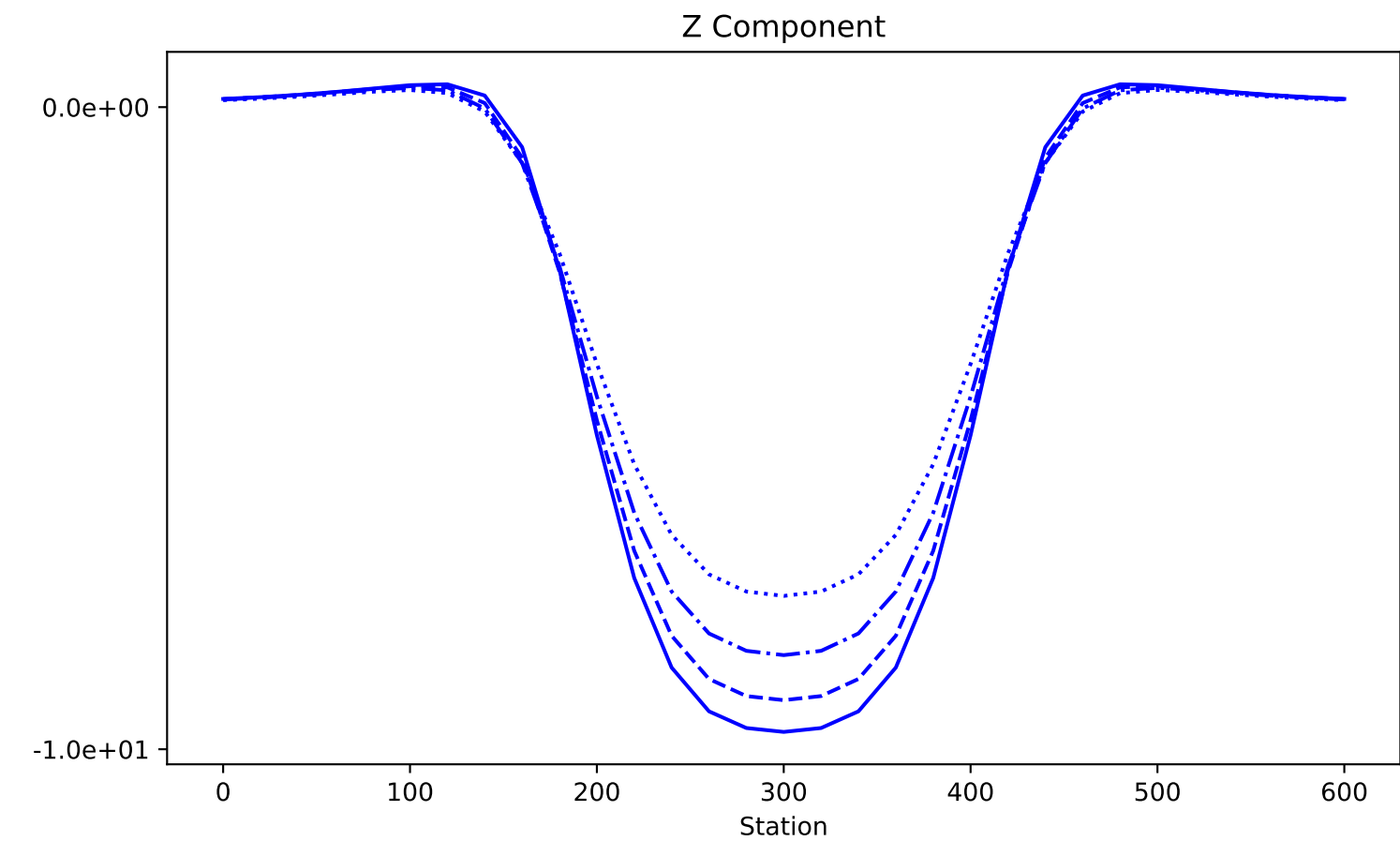
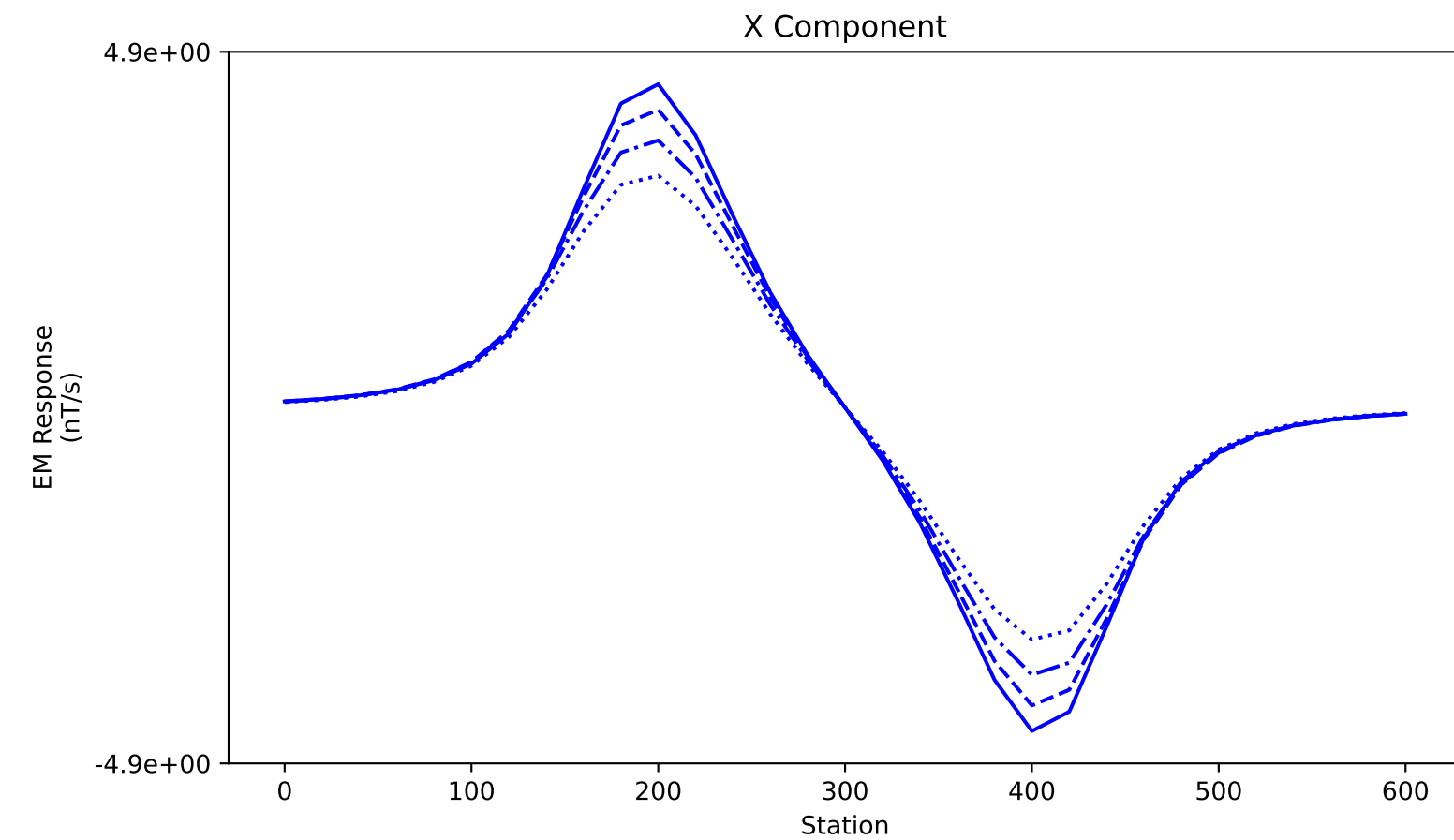
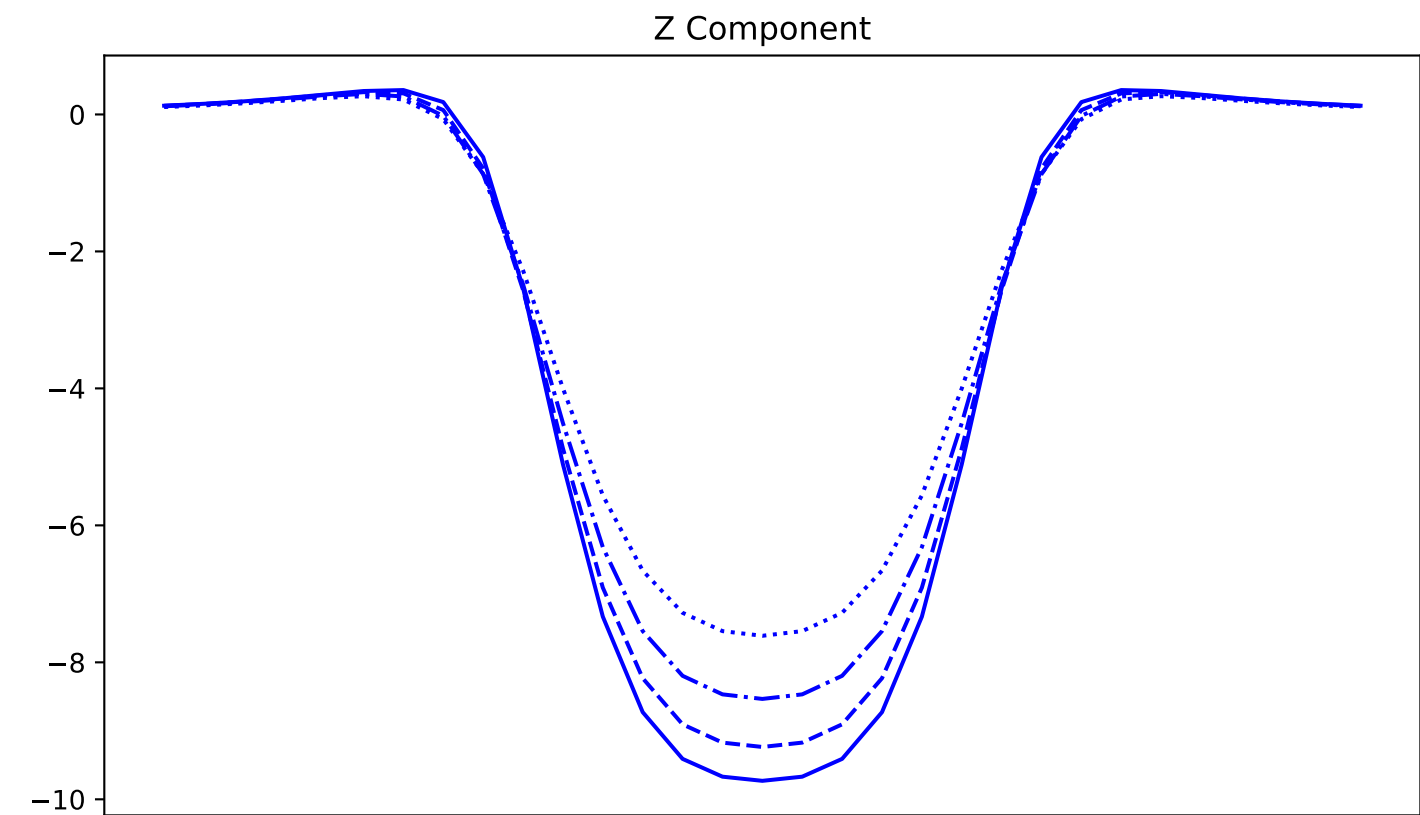
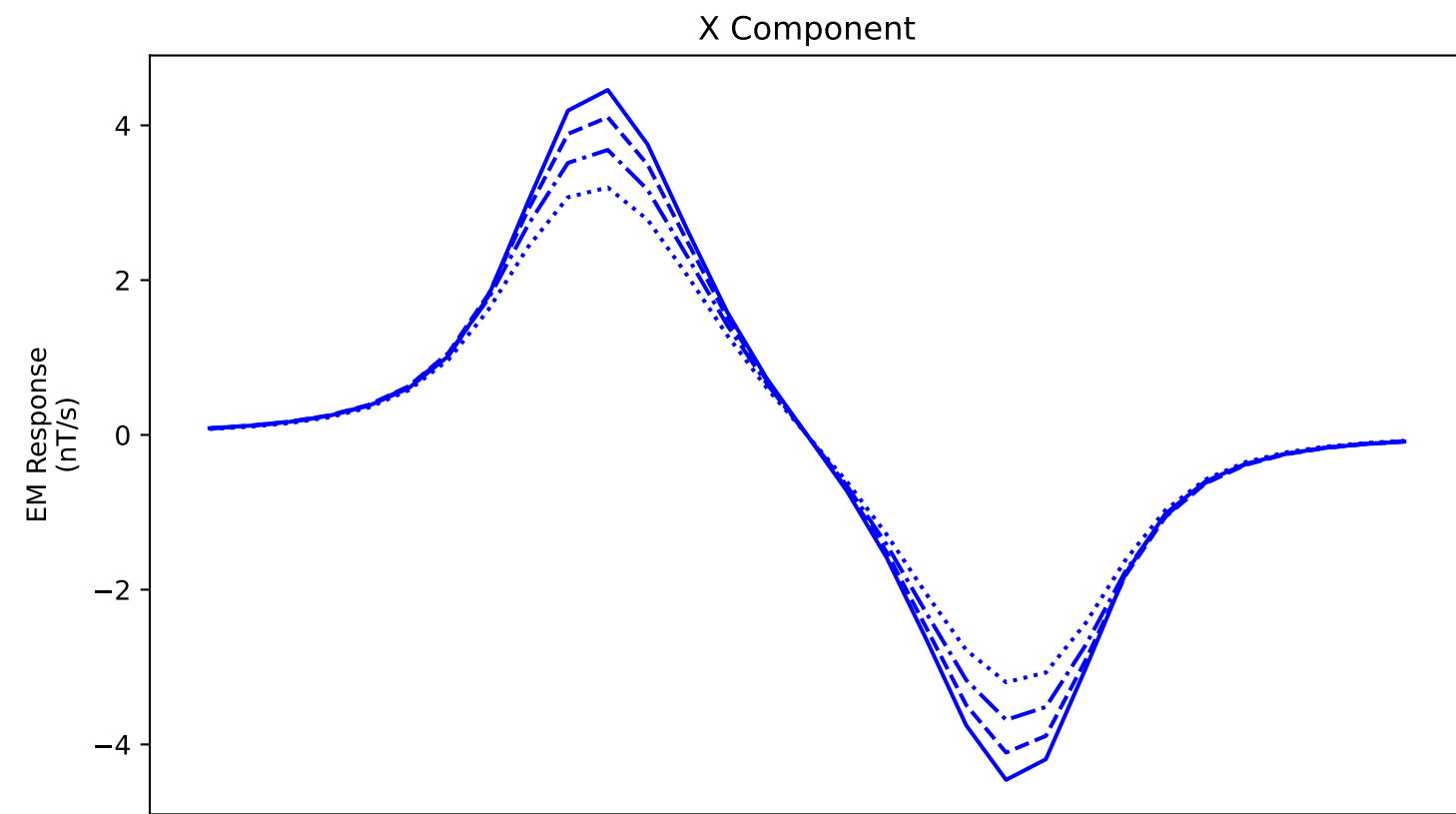
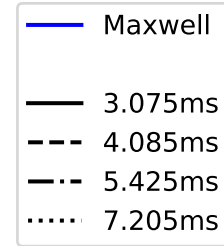
Two-Way Induction
300x100m, 1000S
LOOP=-250
0.56ms to 1.315ms



Two-Way Induction
300x100m, 1000S
LOOP=-250
1.315ms to 3.075ms

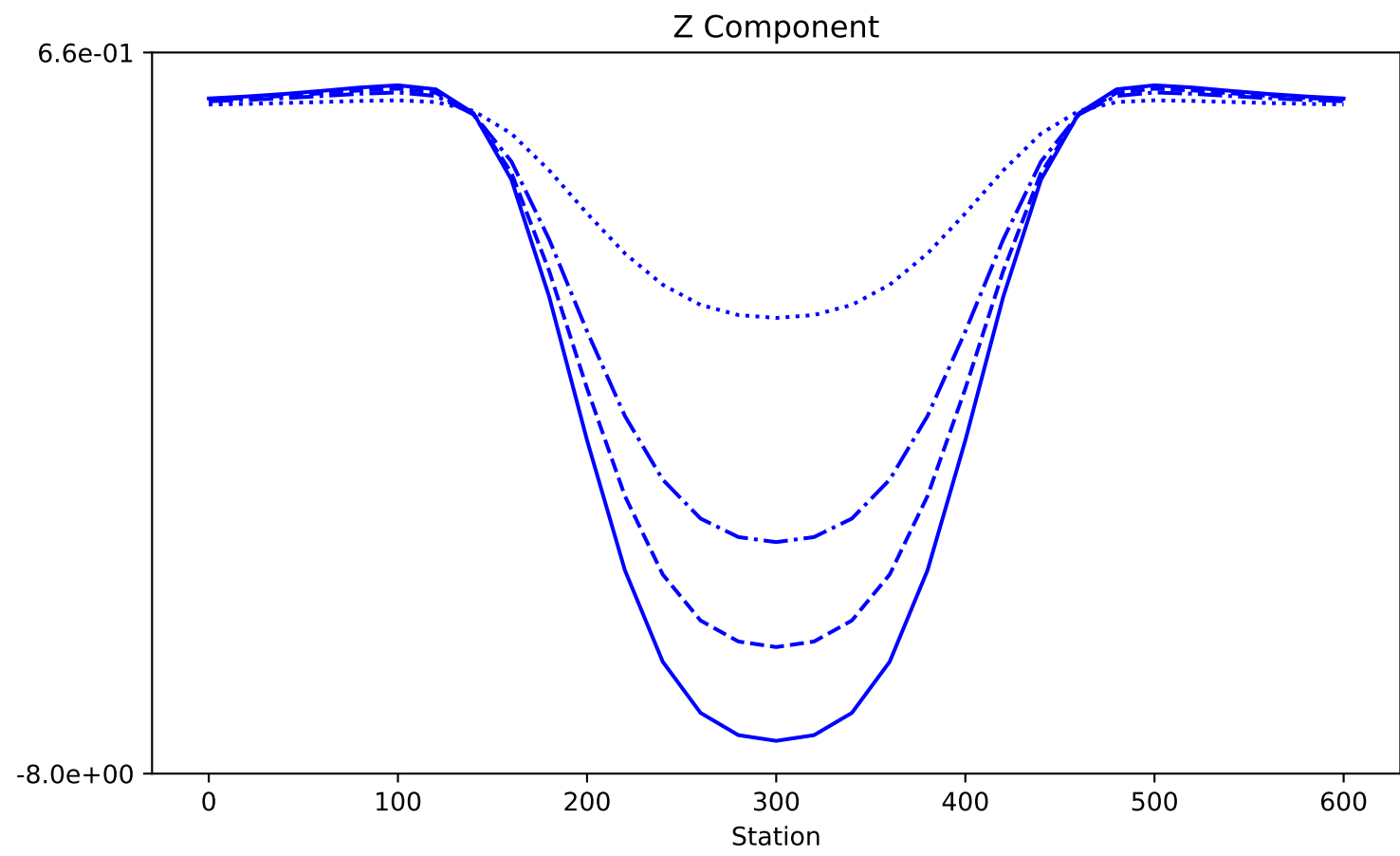
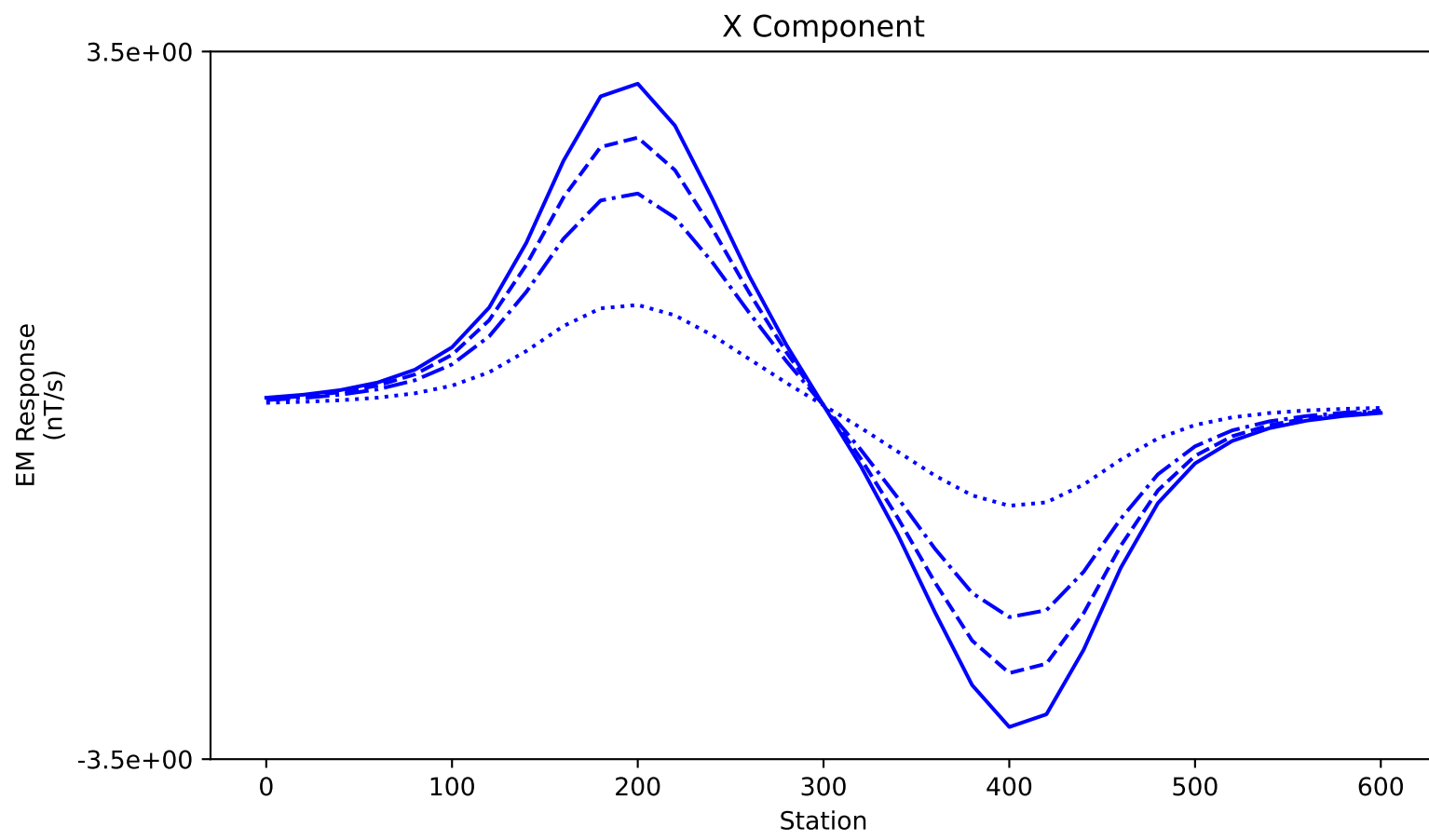
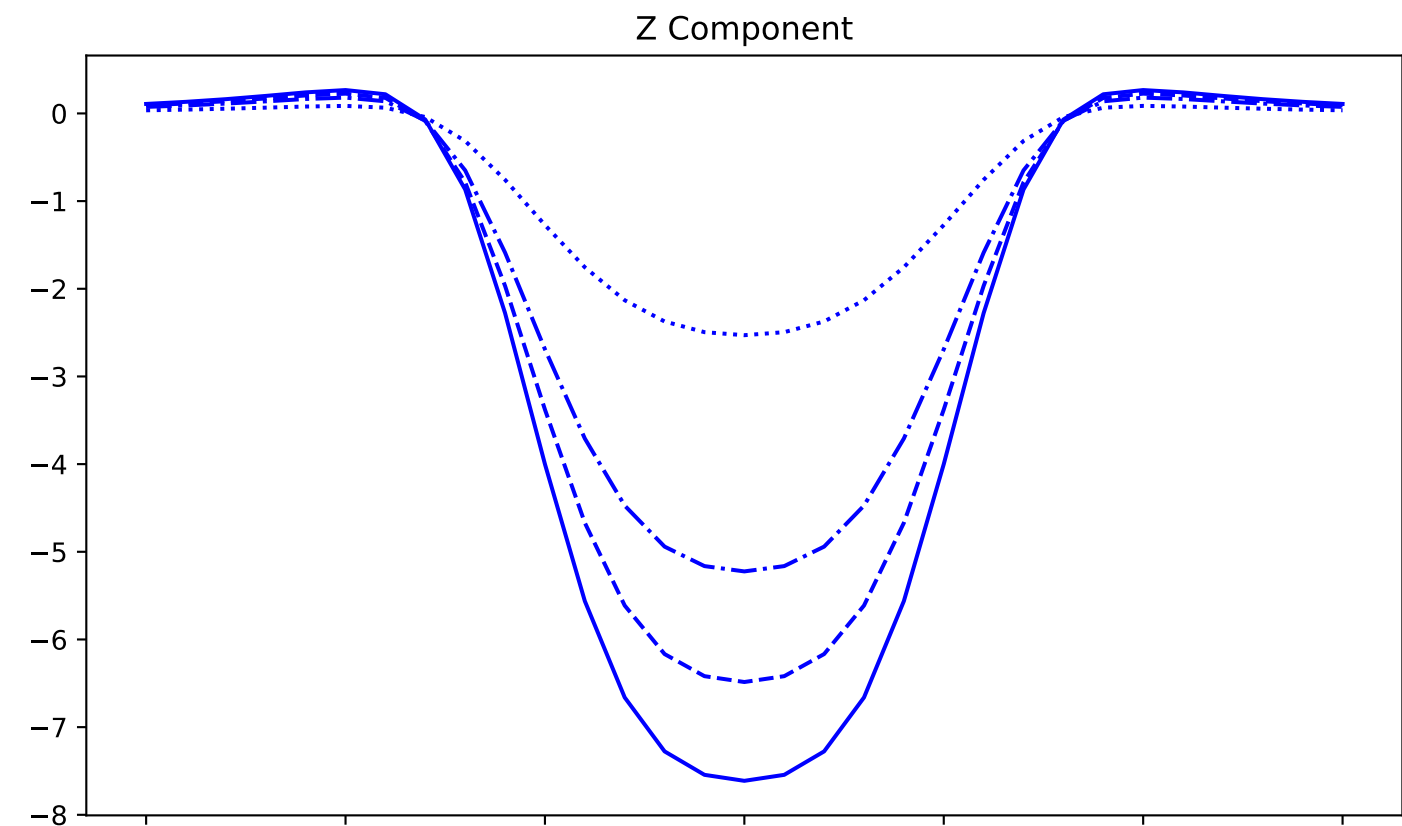
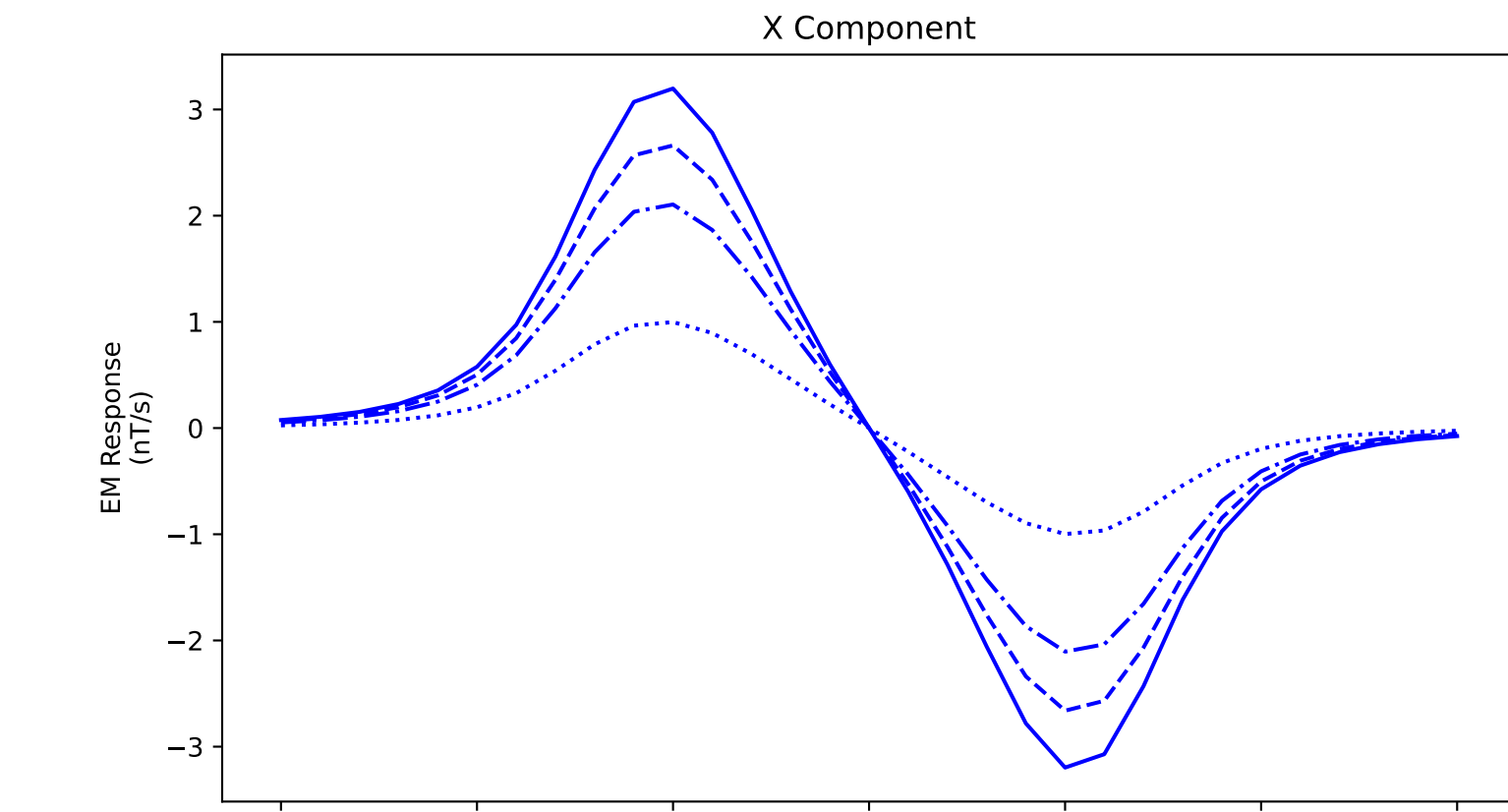


Two-Way Induction
300x100m, 1000S
LOOP=-250
3.075ms to 7.205ms

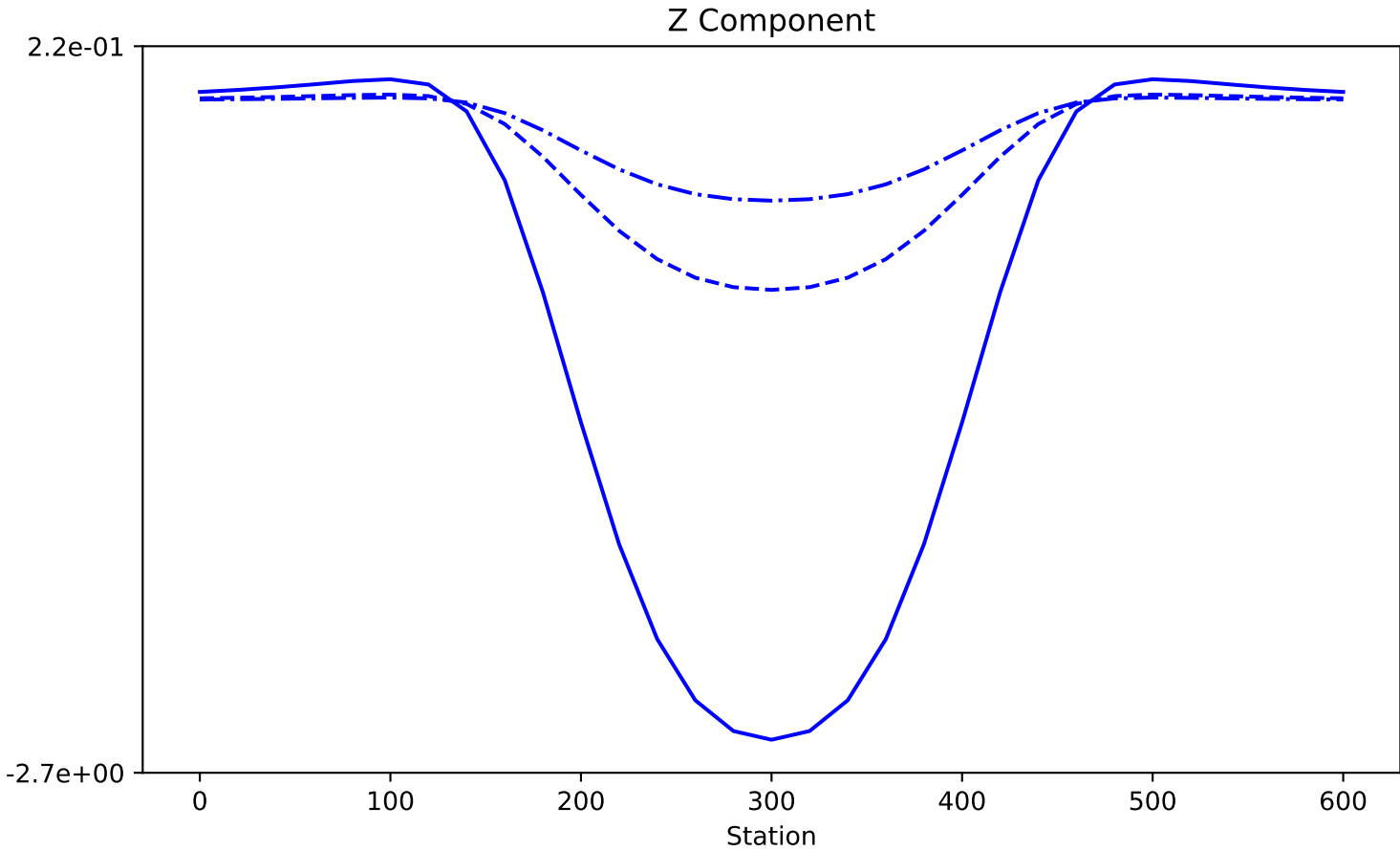
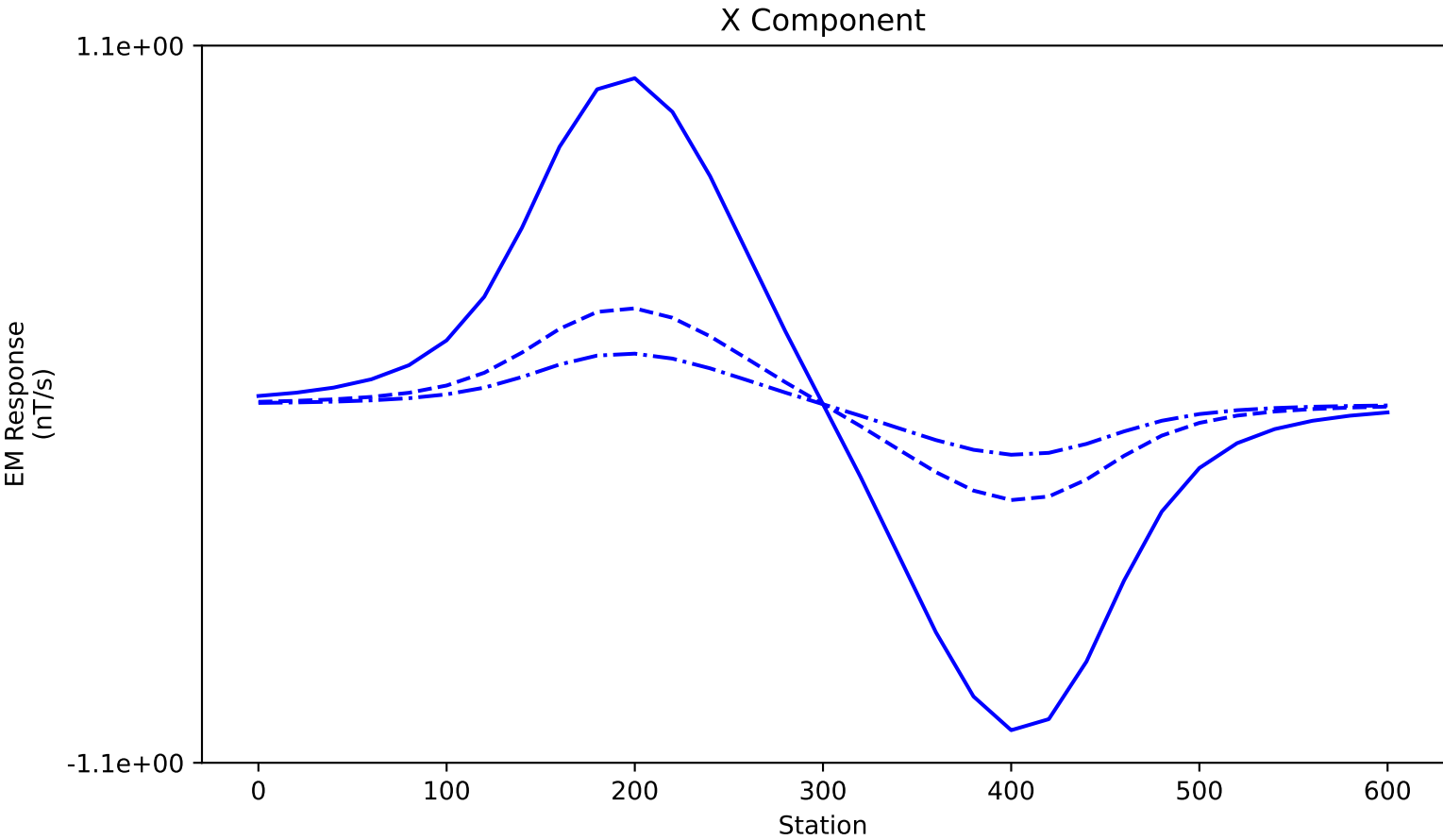
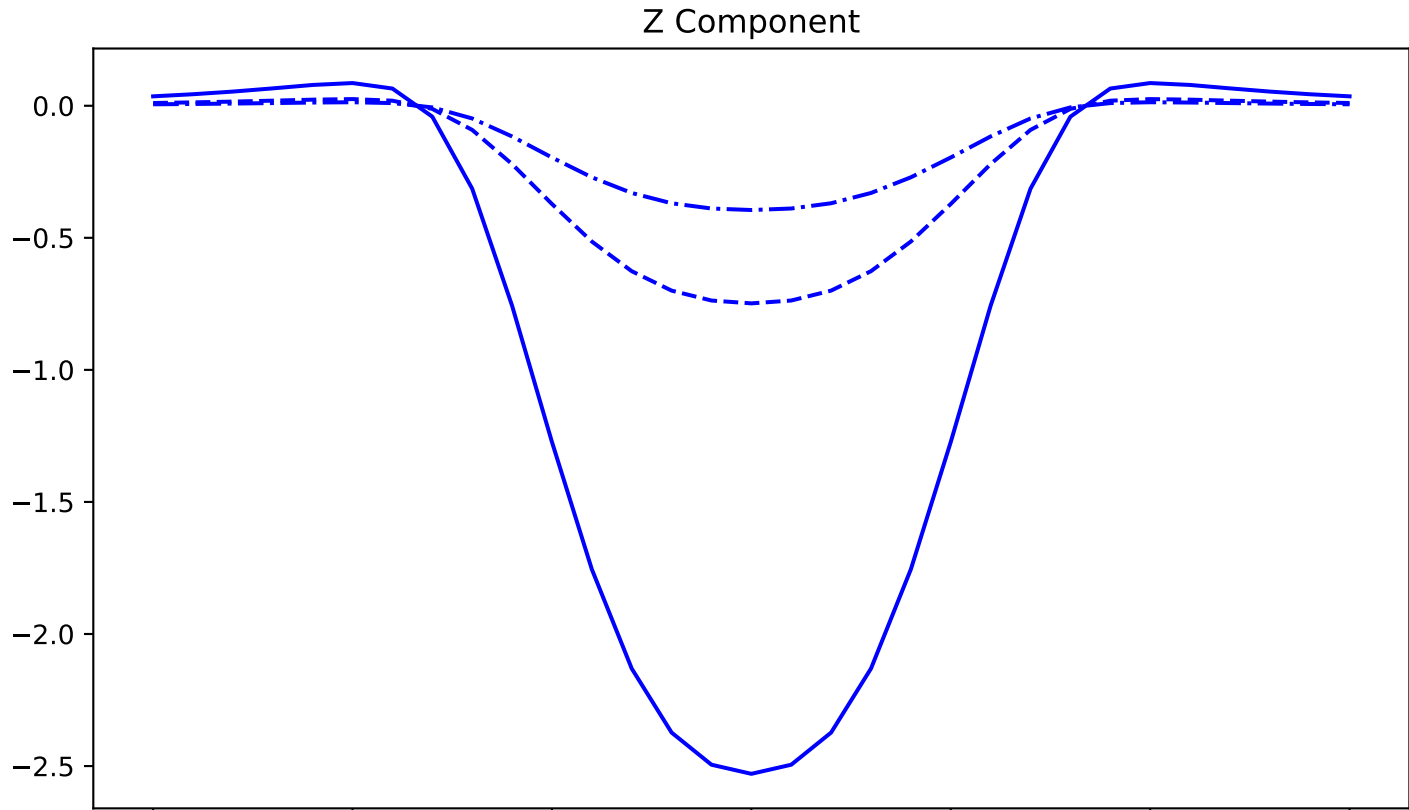
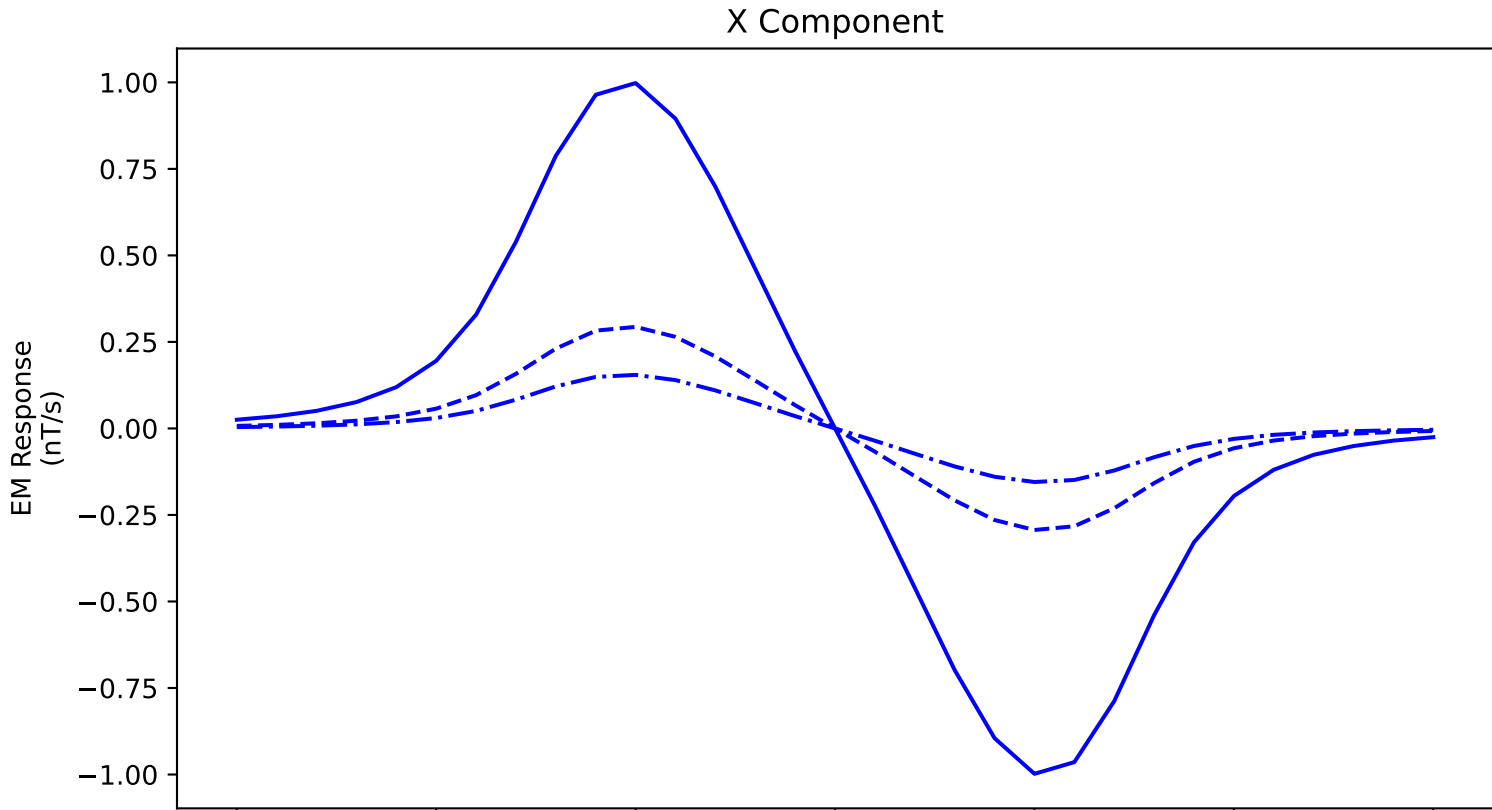
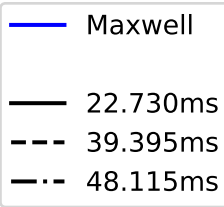


Two-Way Induction
300x100m, 1000S
LOOP=-250
7.205ms to 22.73ms

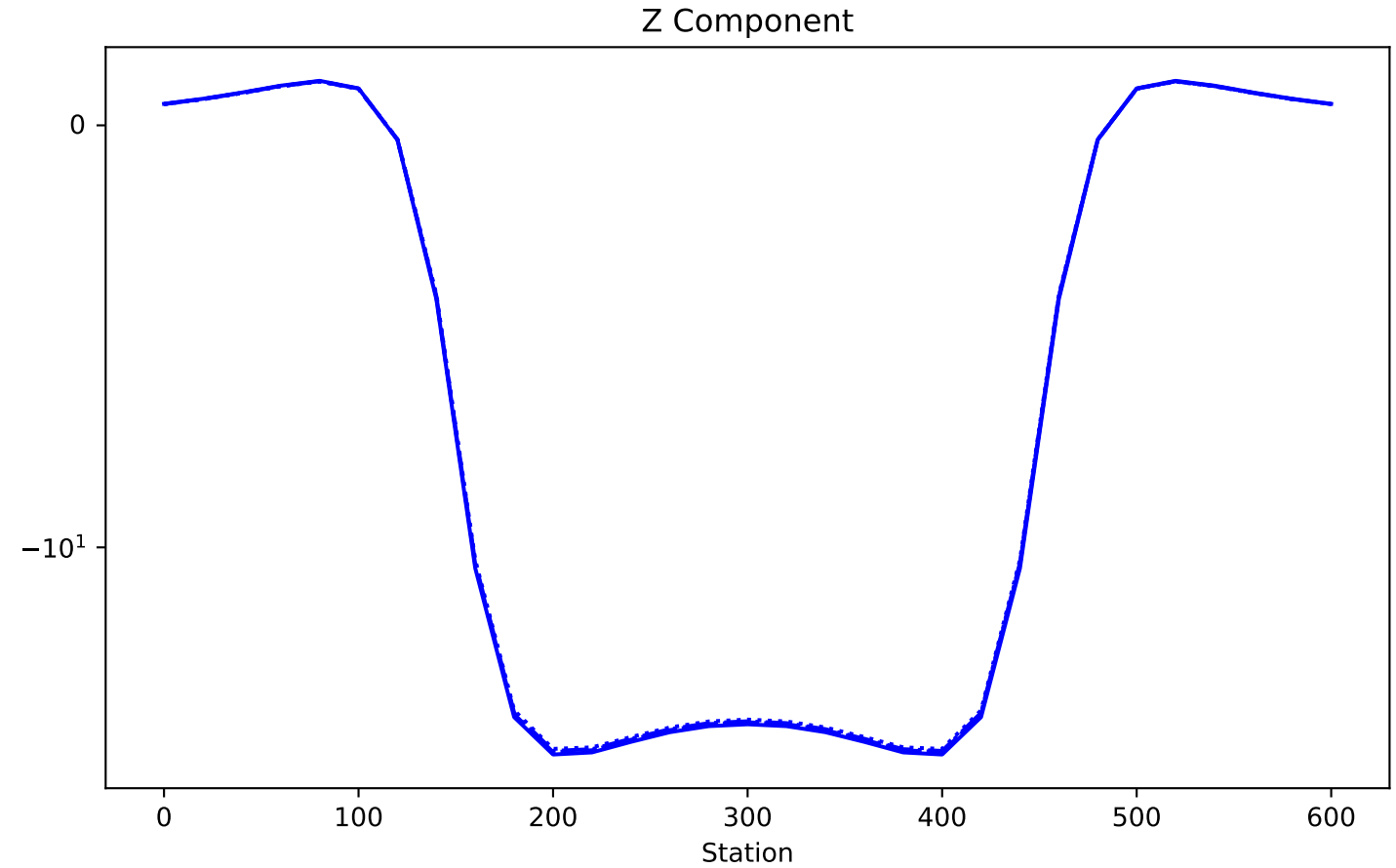
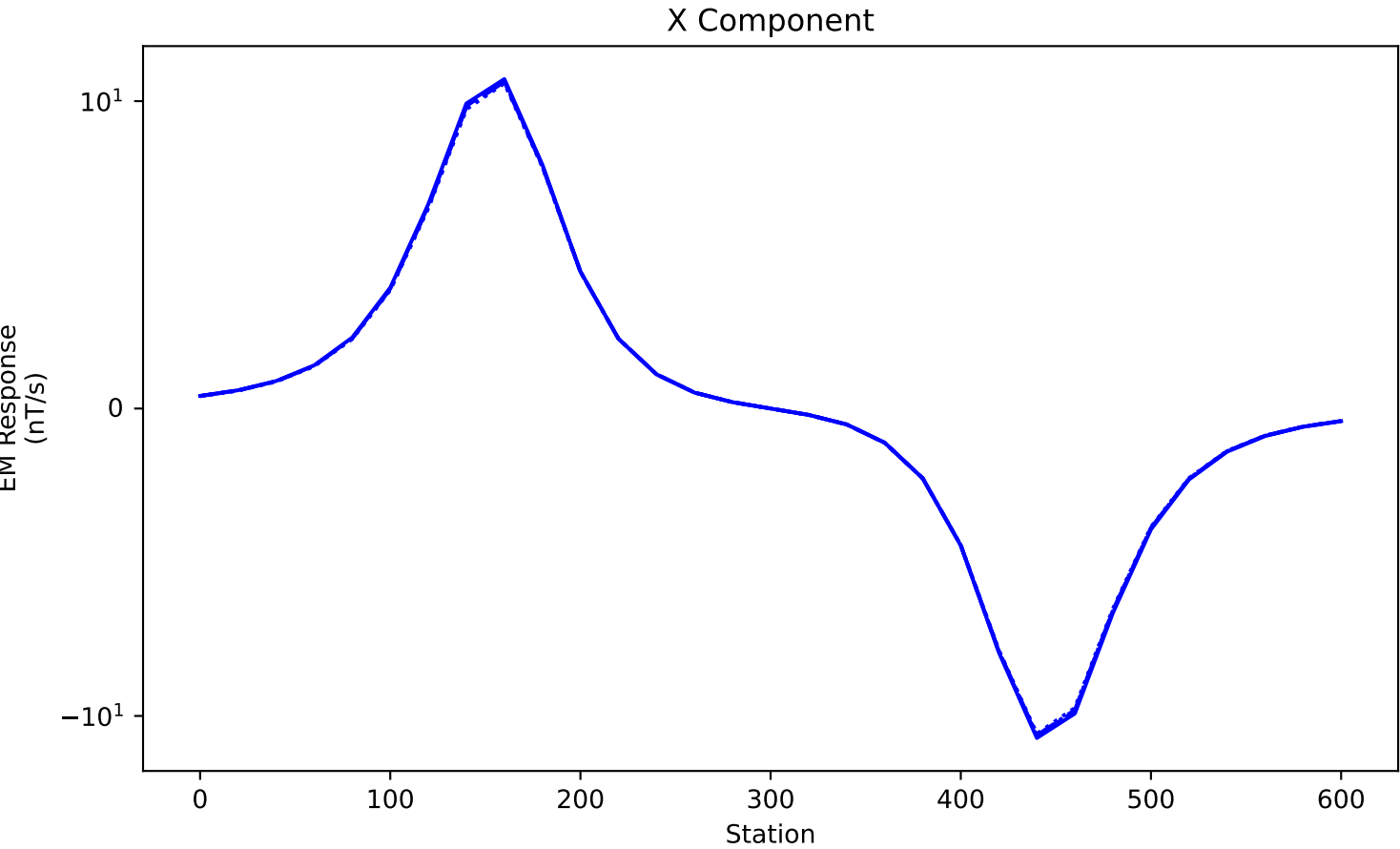
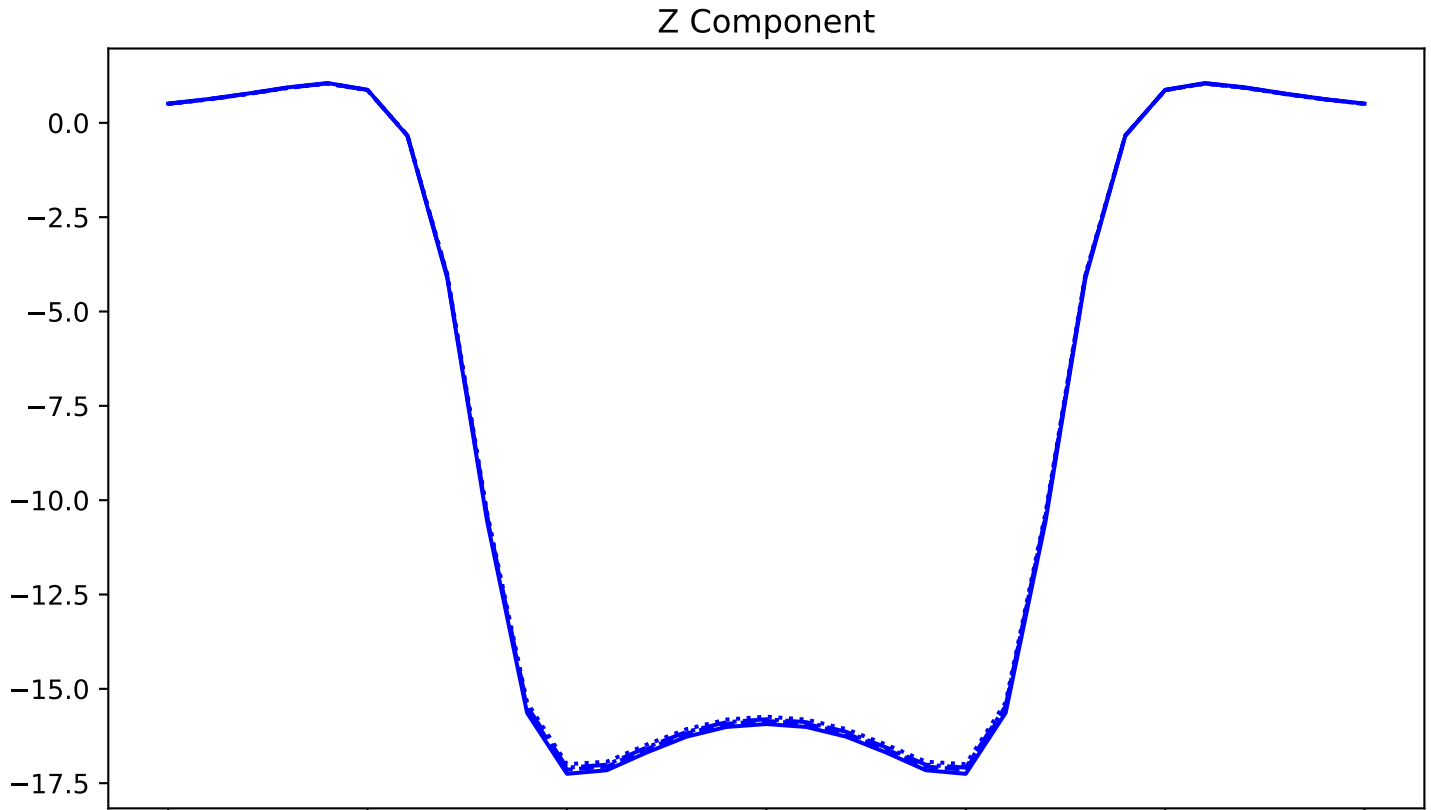
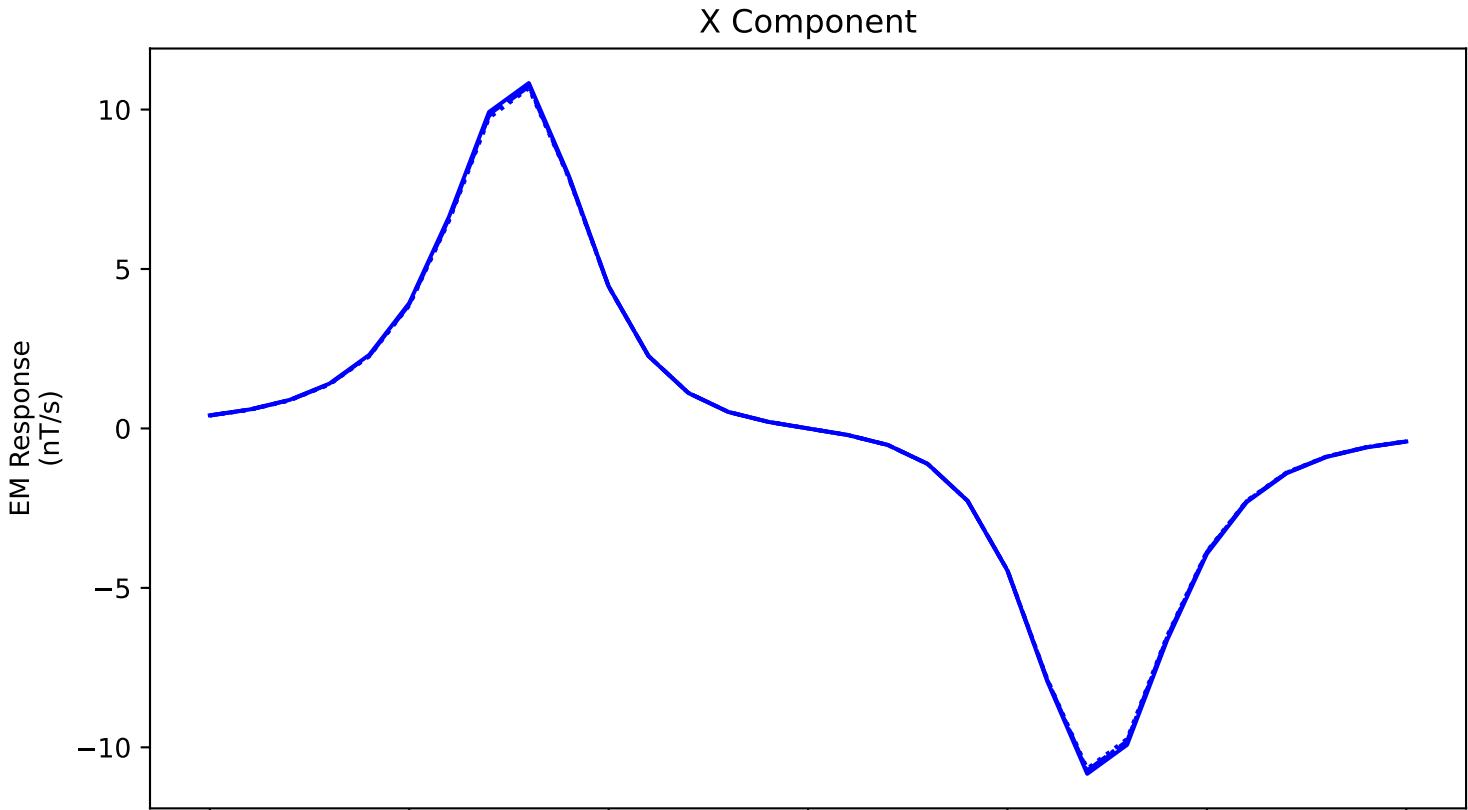
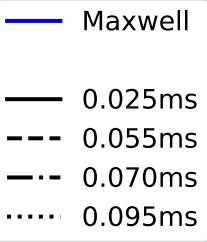
- Maxwell
- 7.205ms
- 9.570ms
- 12.660ms
- 22.730ms



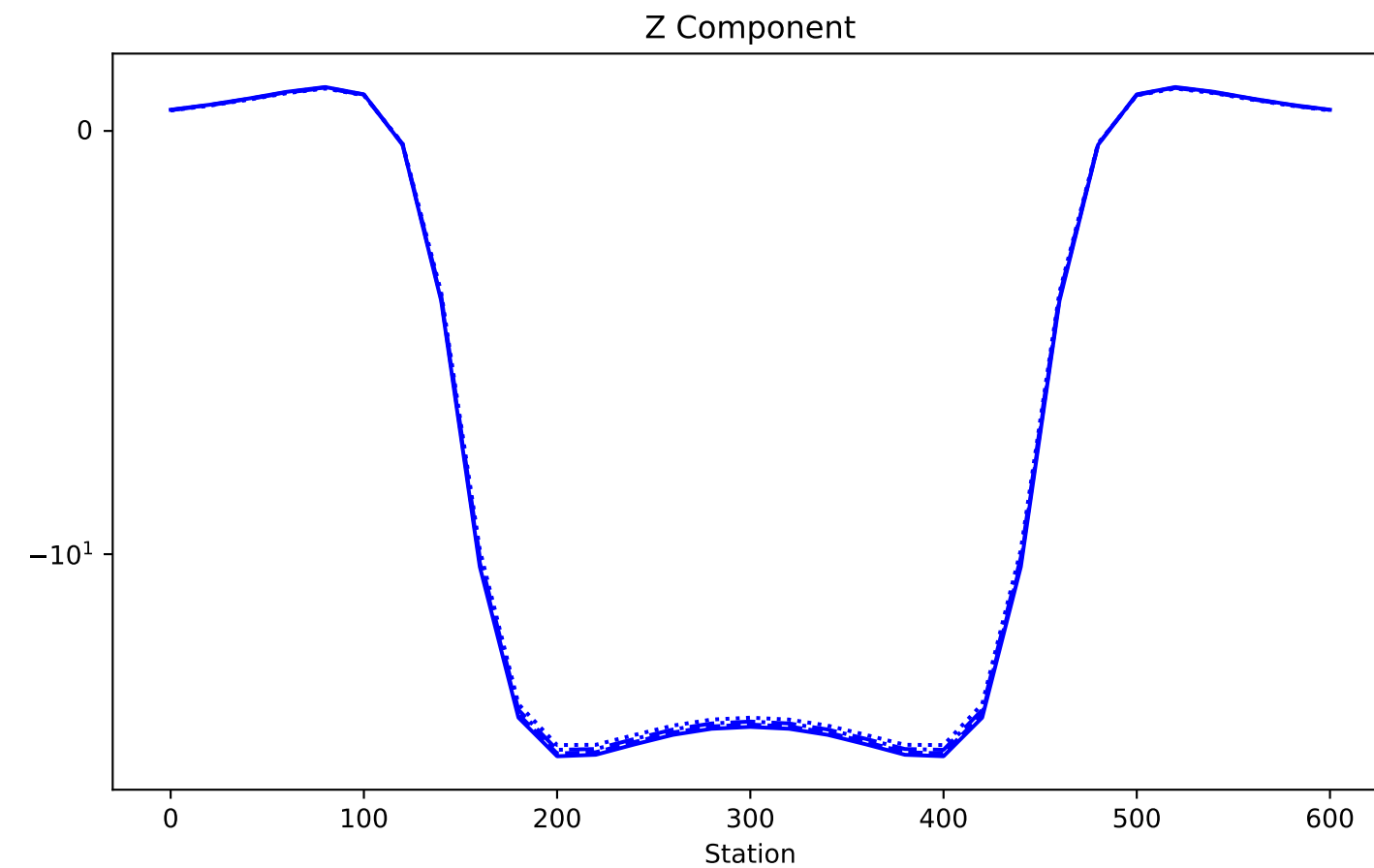
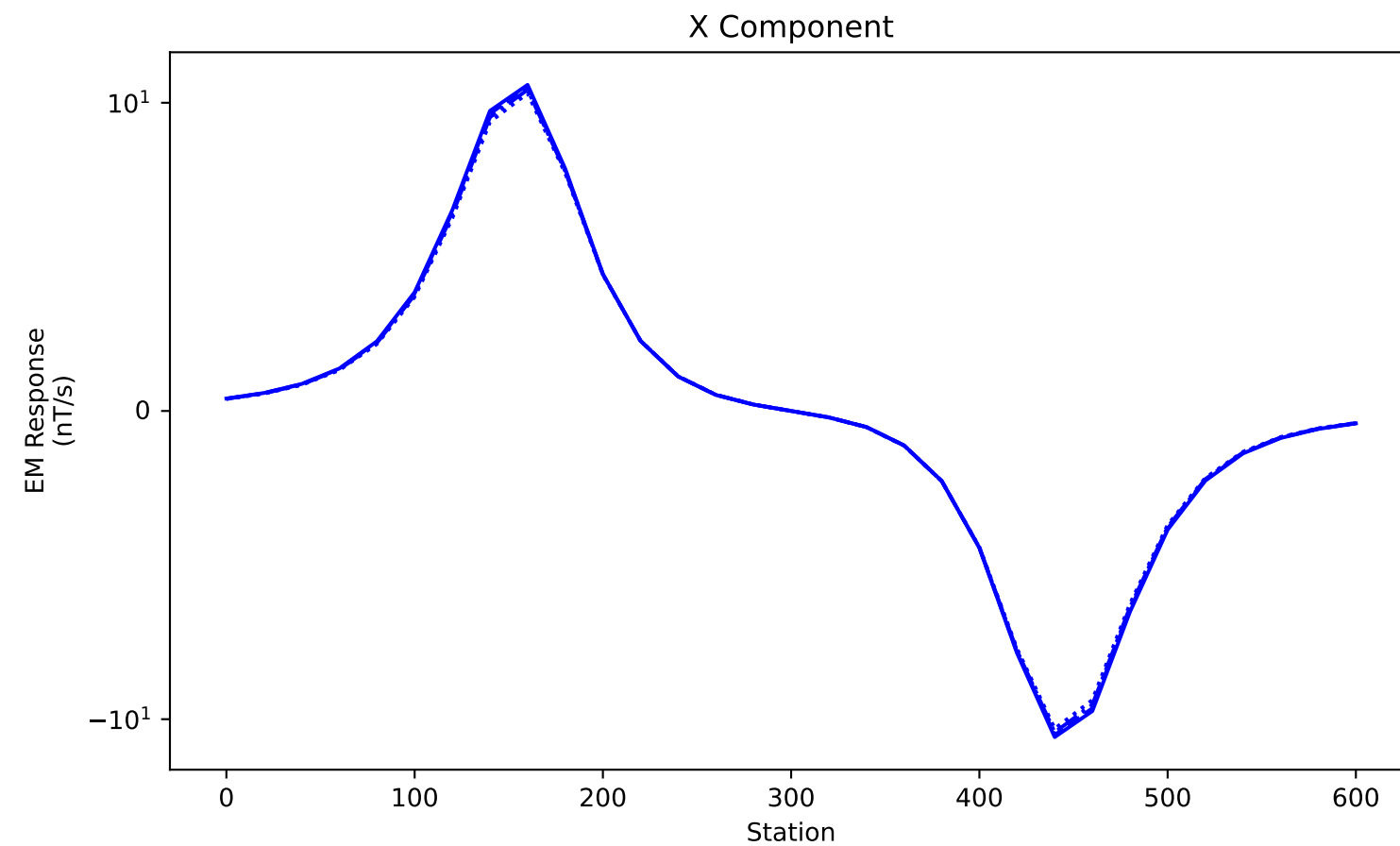
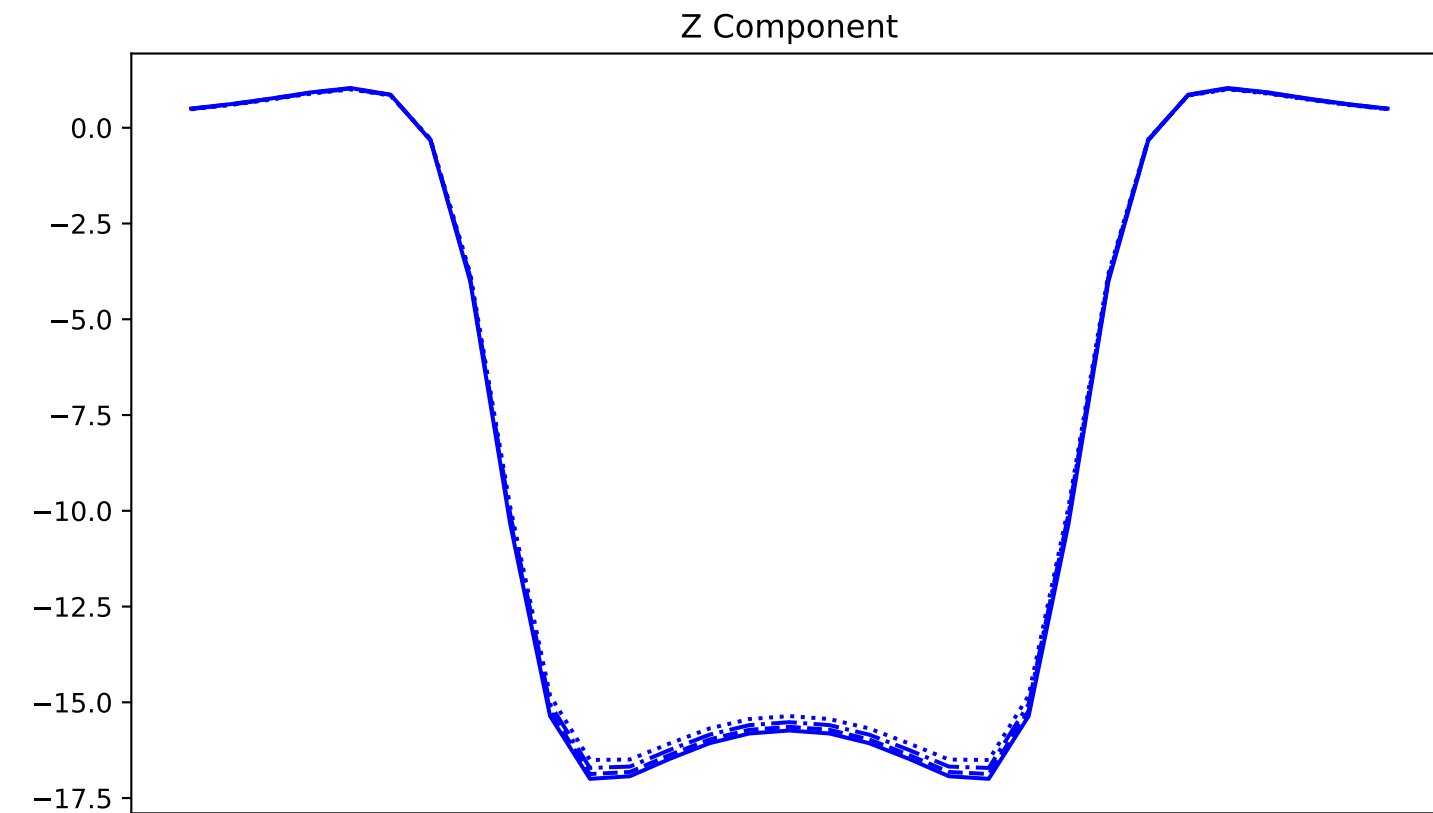
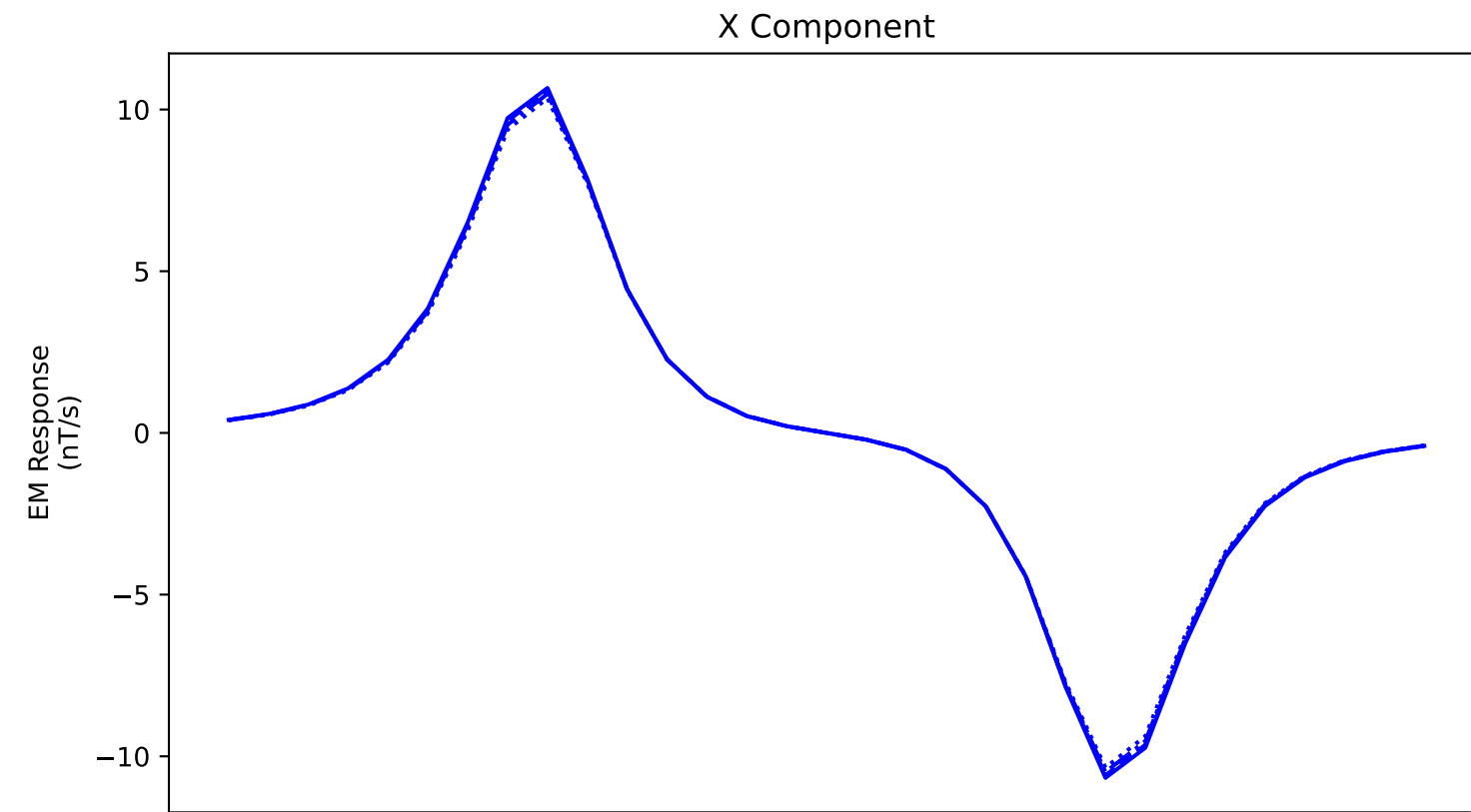
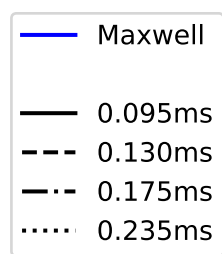
Two-Way Induction
300x100m, 1000S
LOOP=-250
22.73ms to 48.115ms



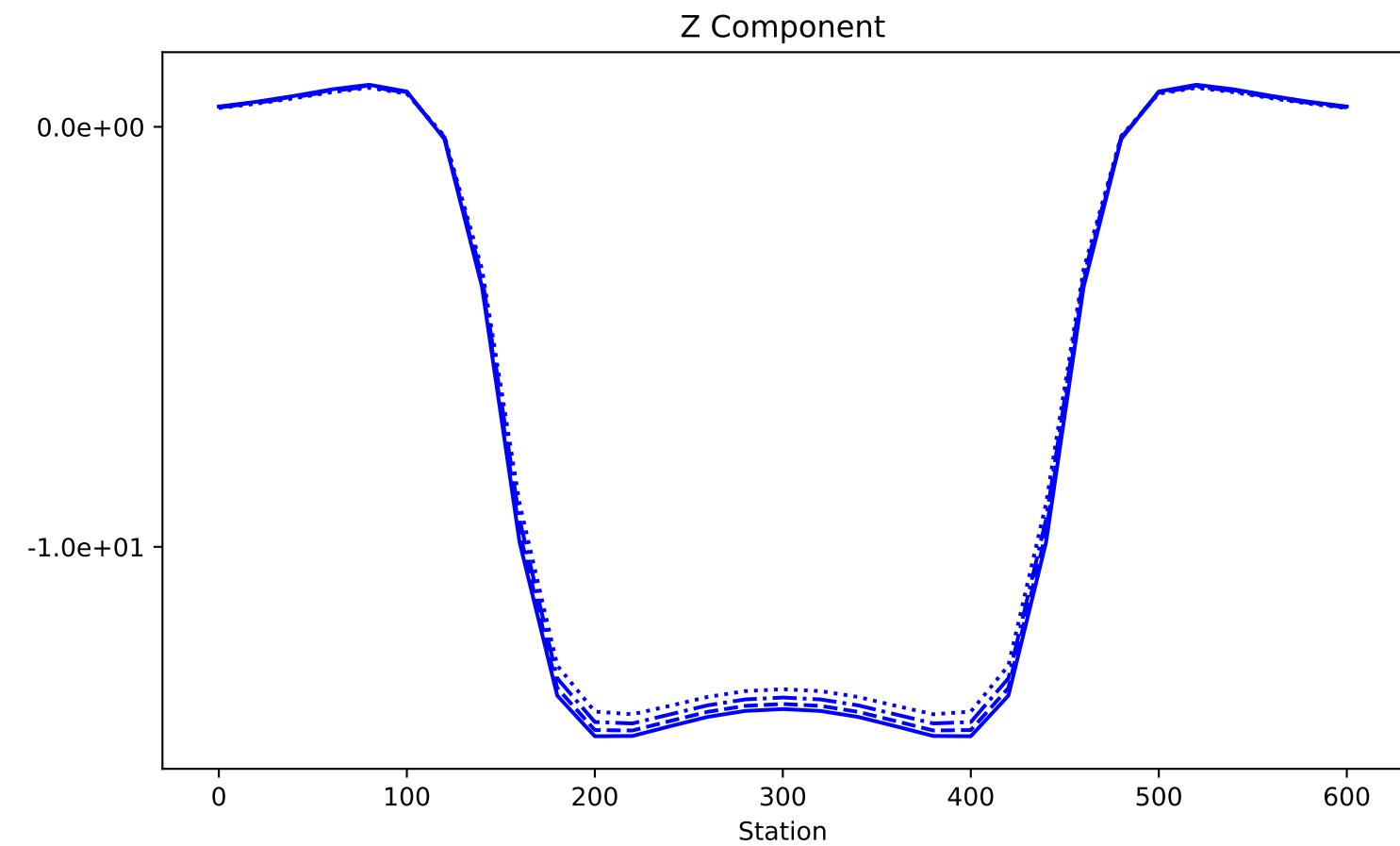
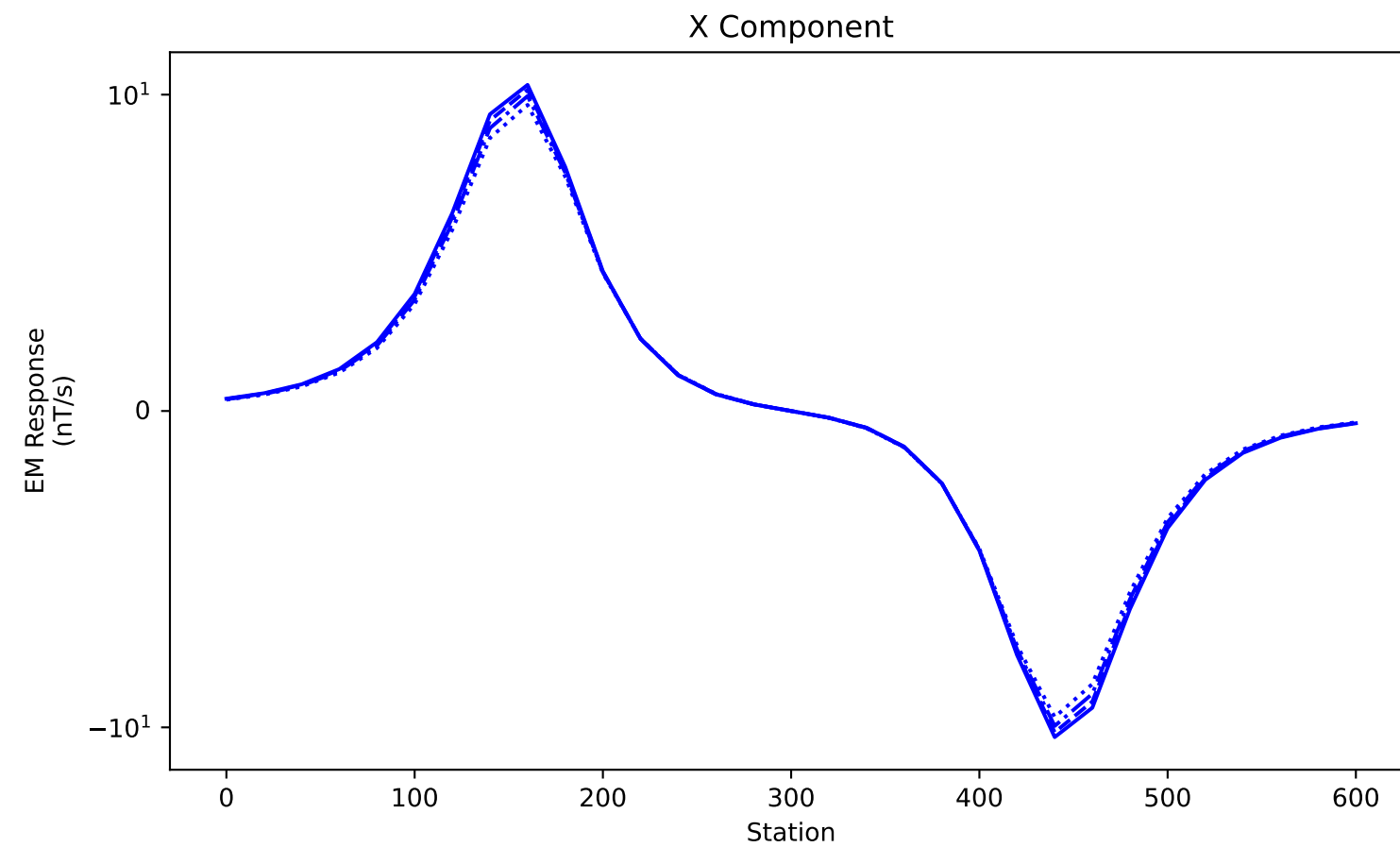
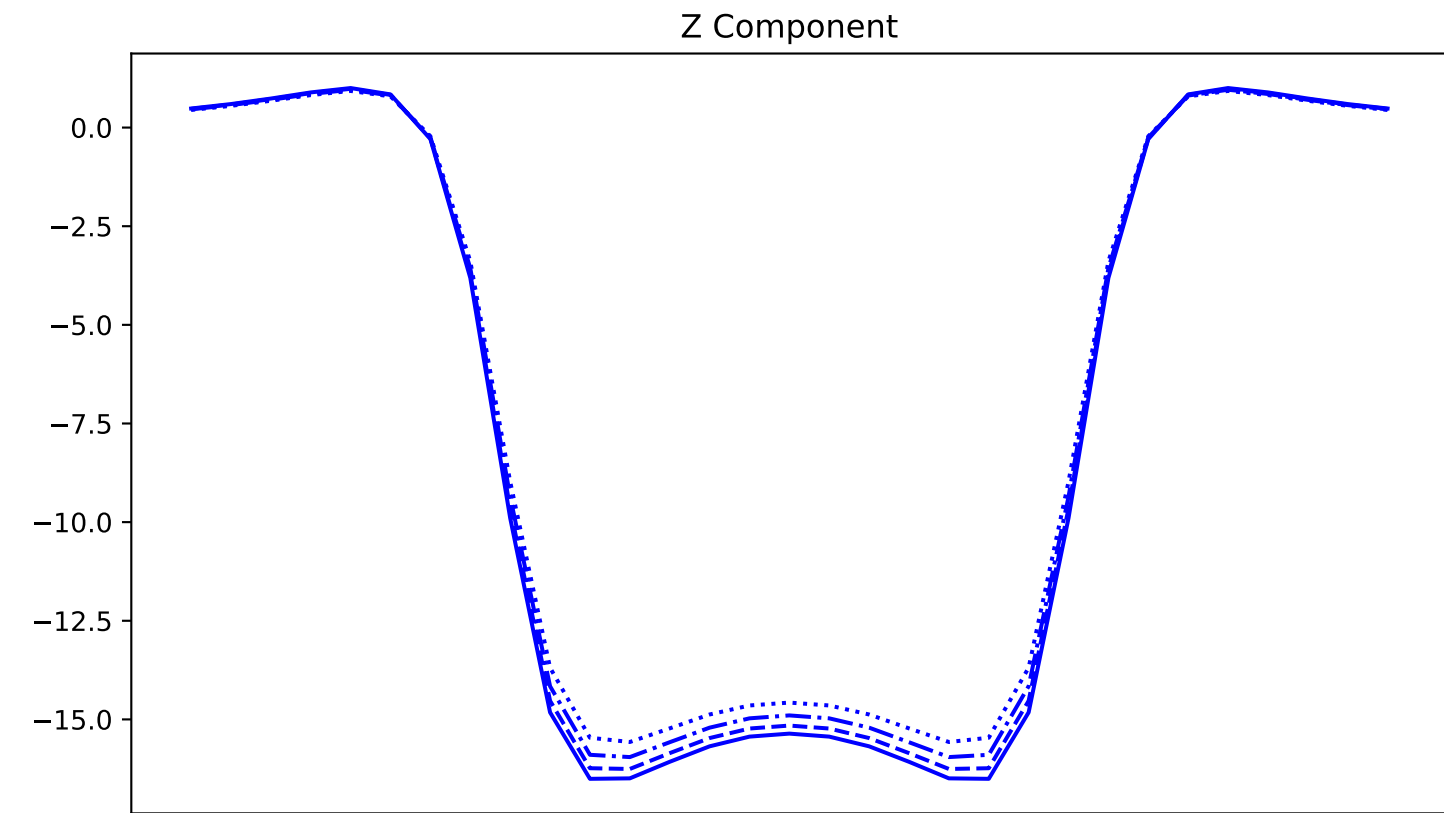
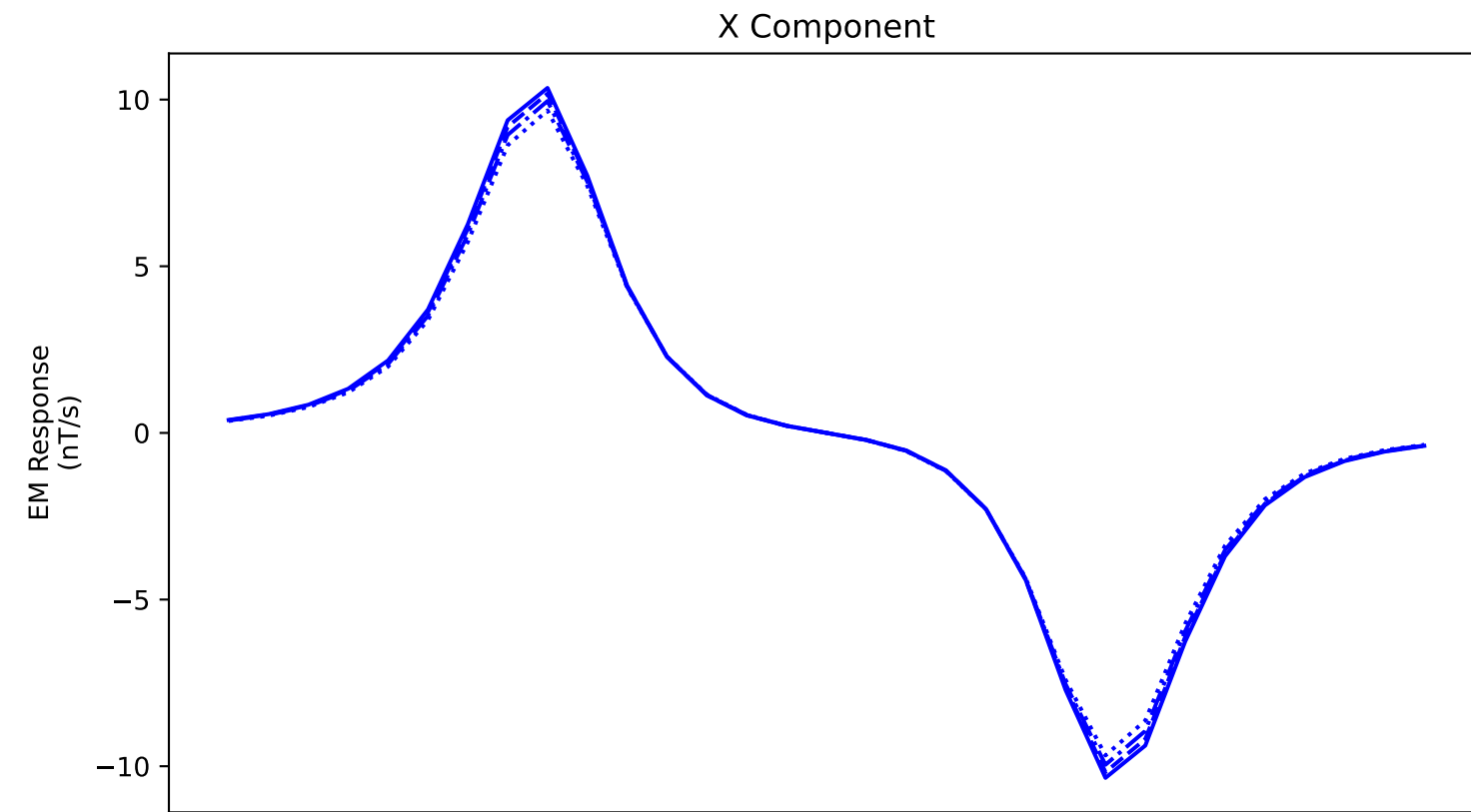
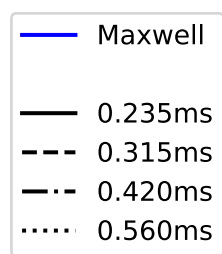
Two-Way Induction
300x100m, 1000S
LOOP=-300
0.0255ms to 0.095ms



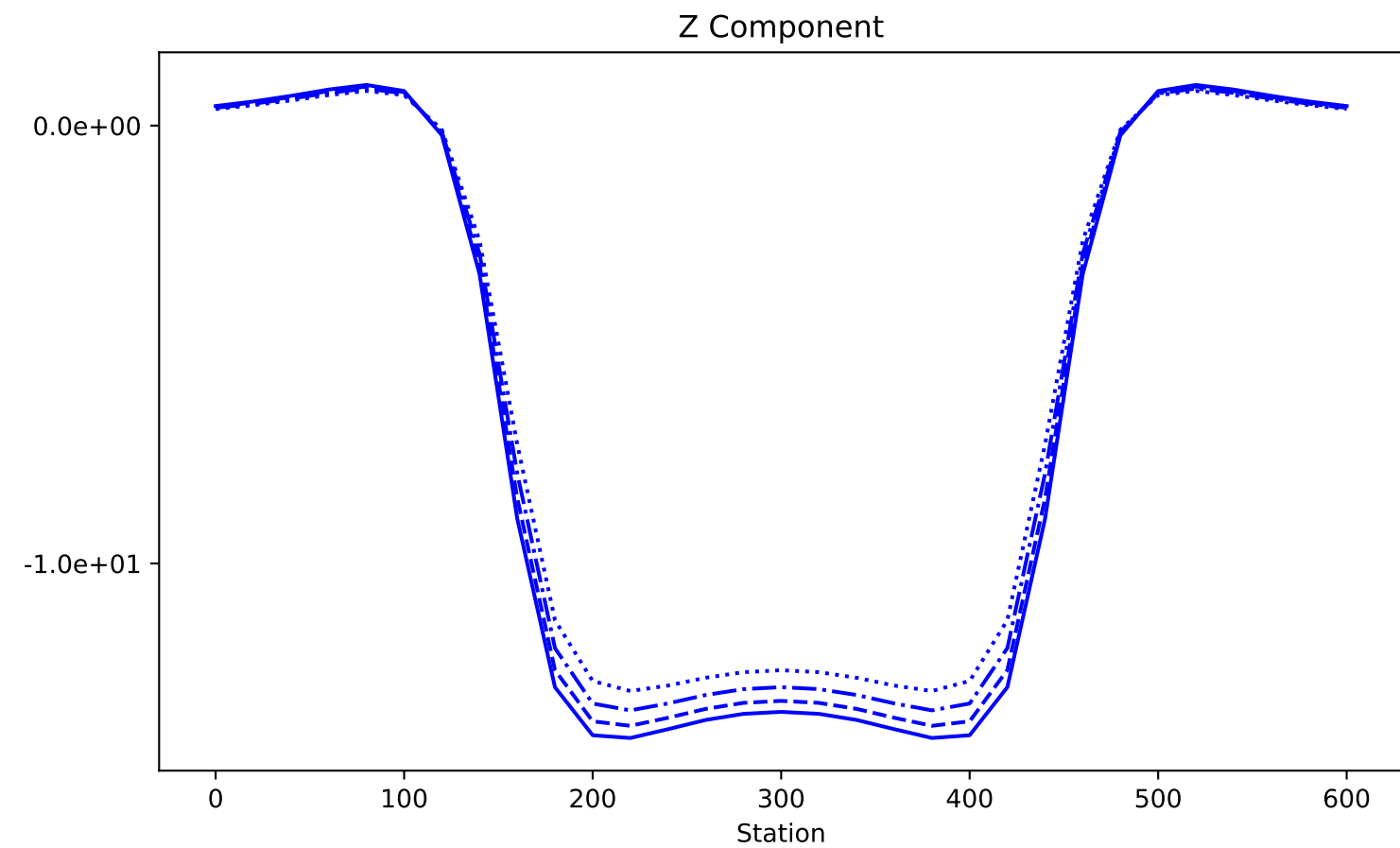
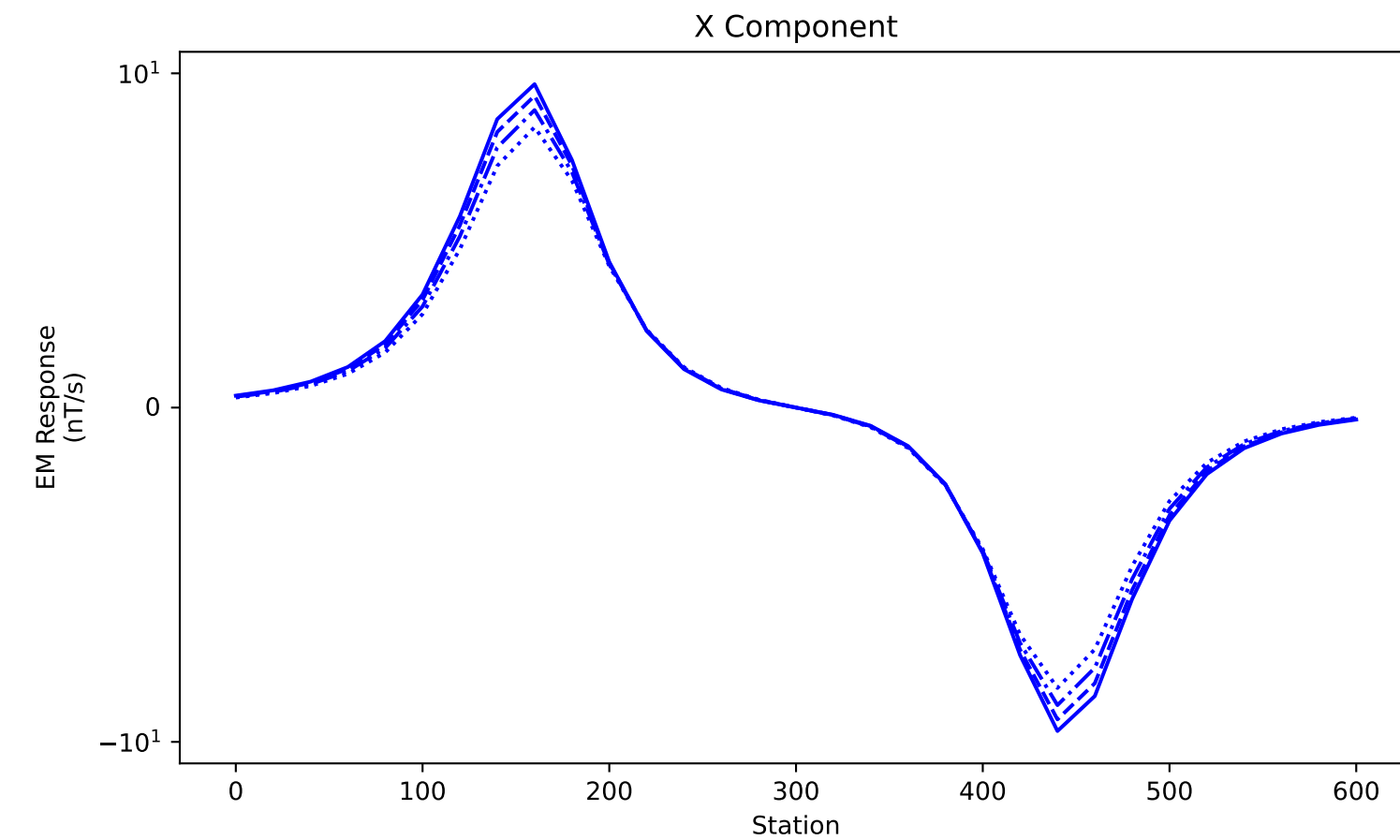
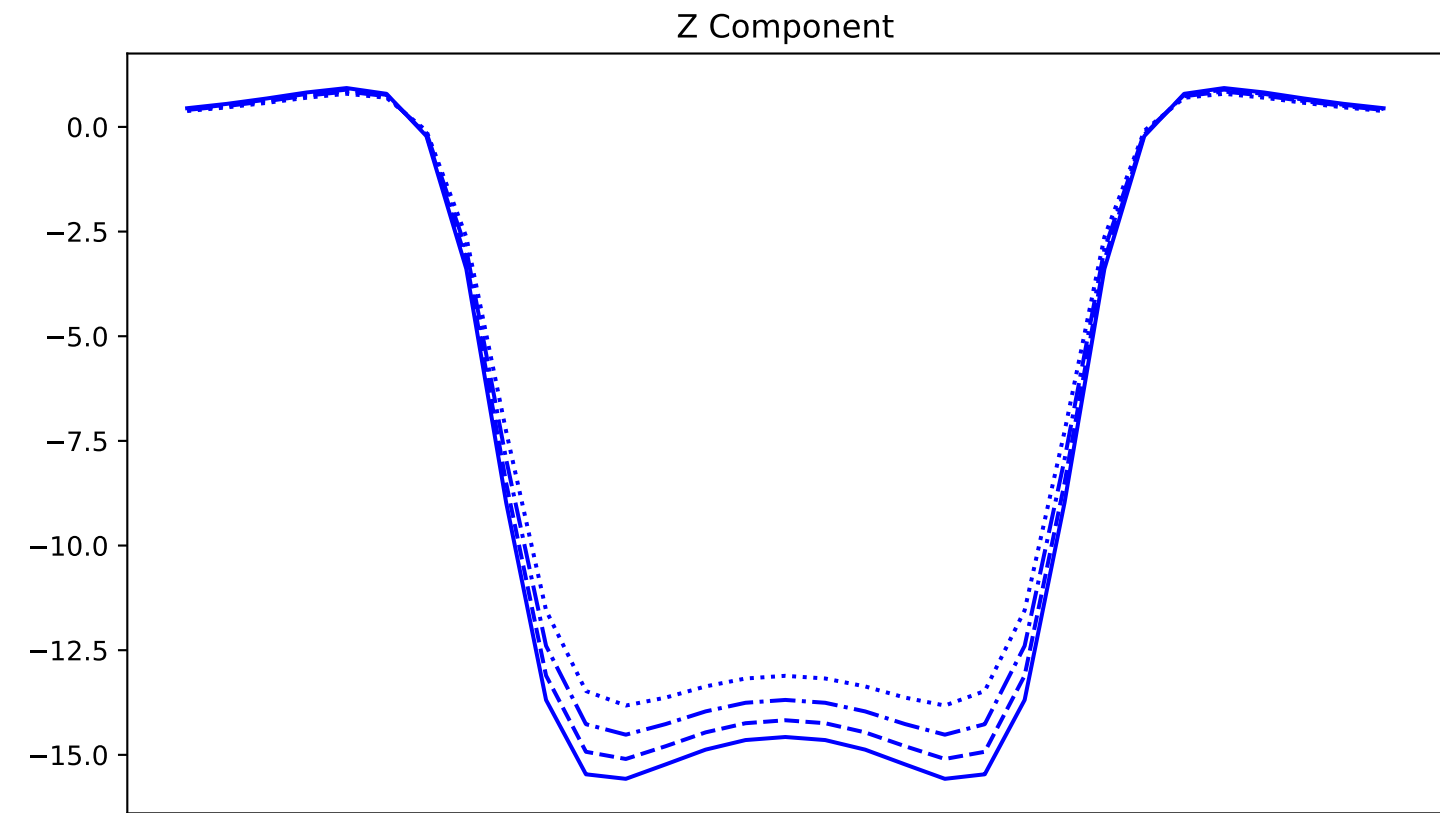
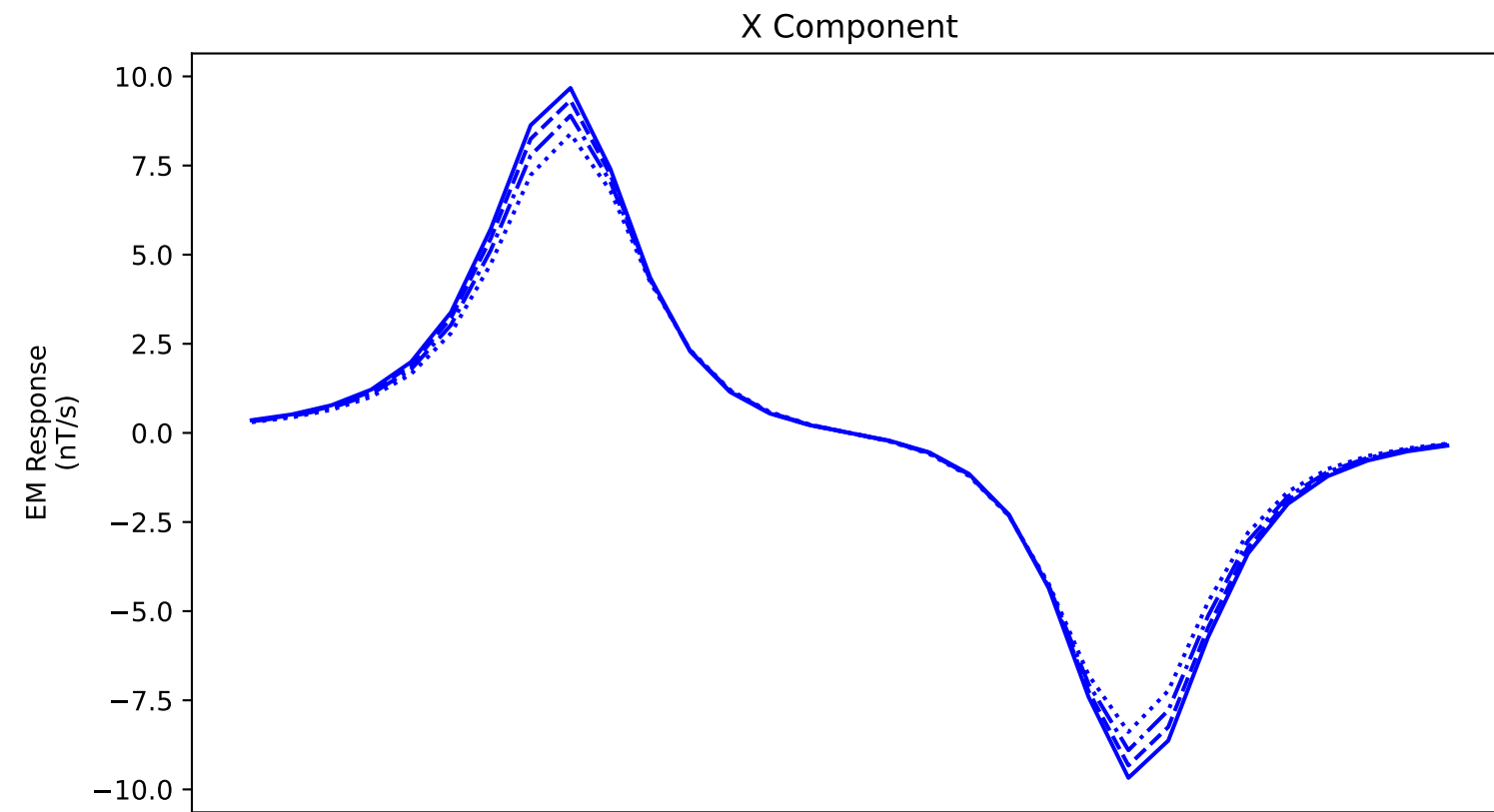
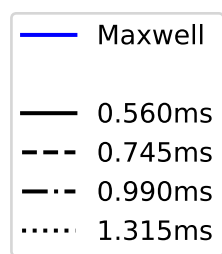
Two-Way Induction
300x100m, 1000S
LOOP=-300
0.095ms to 0.235ms



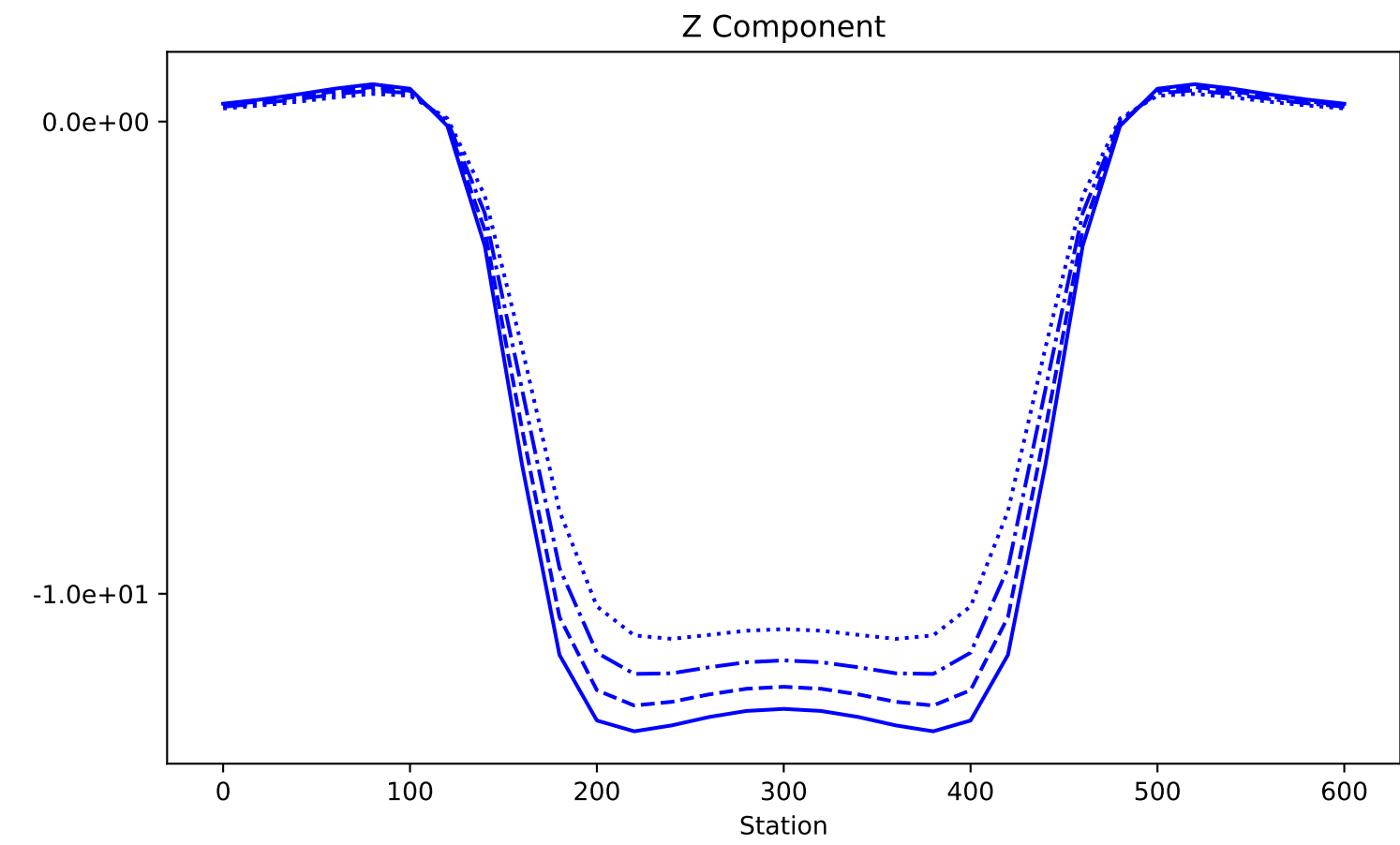
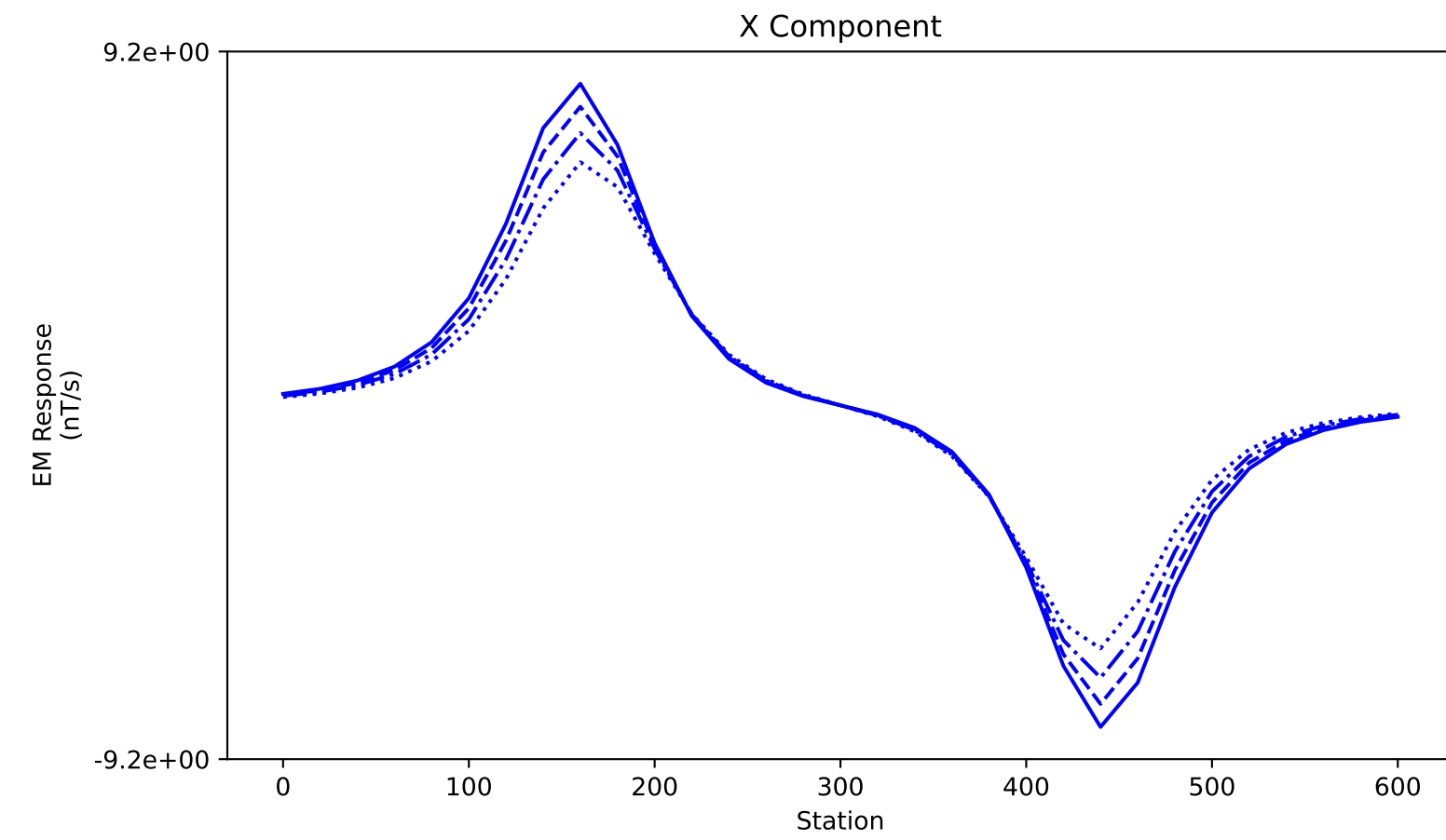
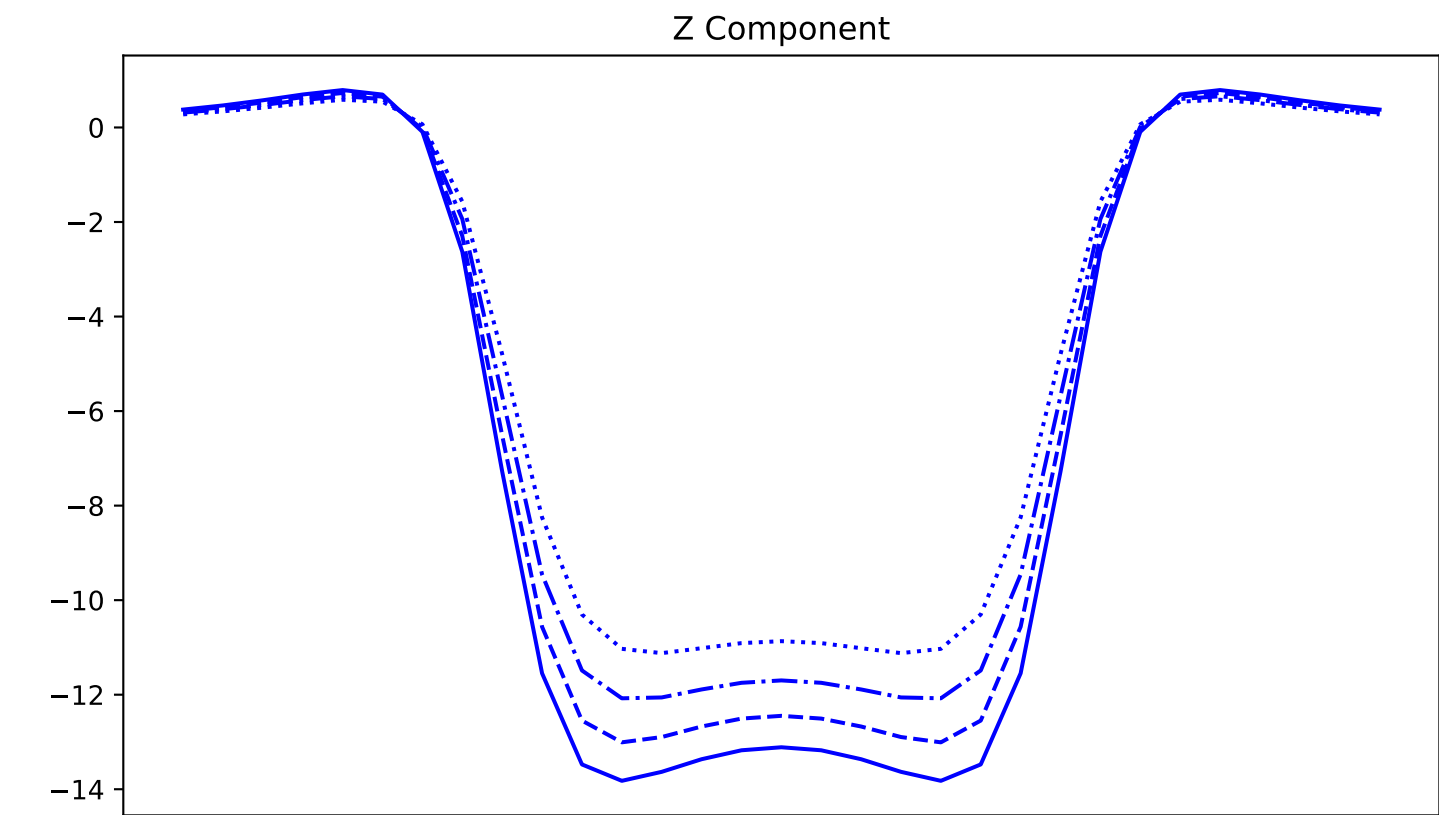
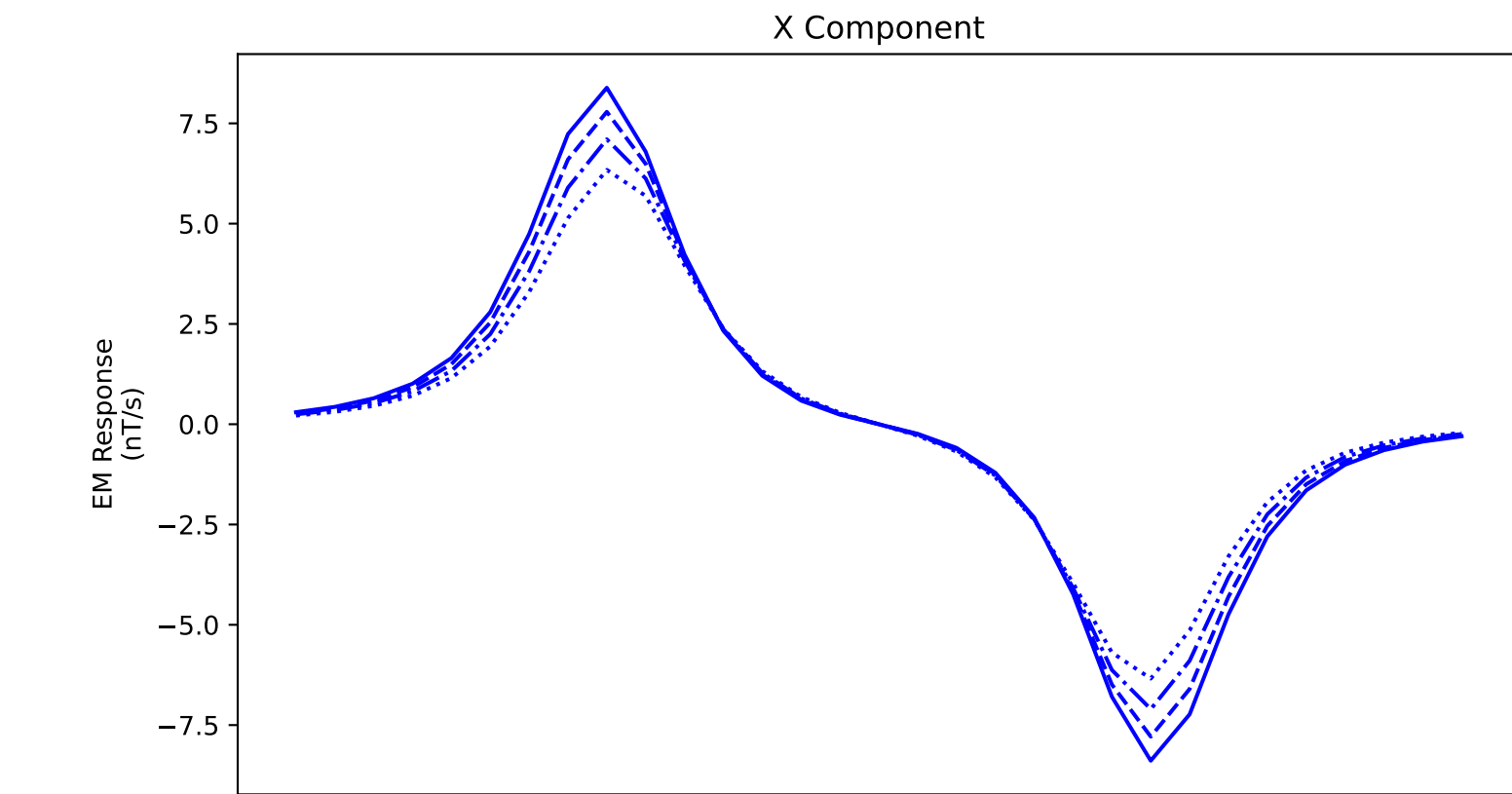
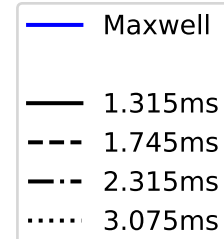
Two-Way Induction
300x100m, 1000S
LOOP=-300
0.235ms to 0.56ms



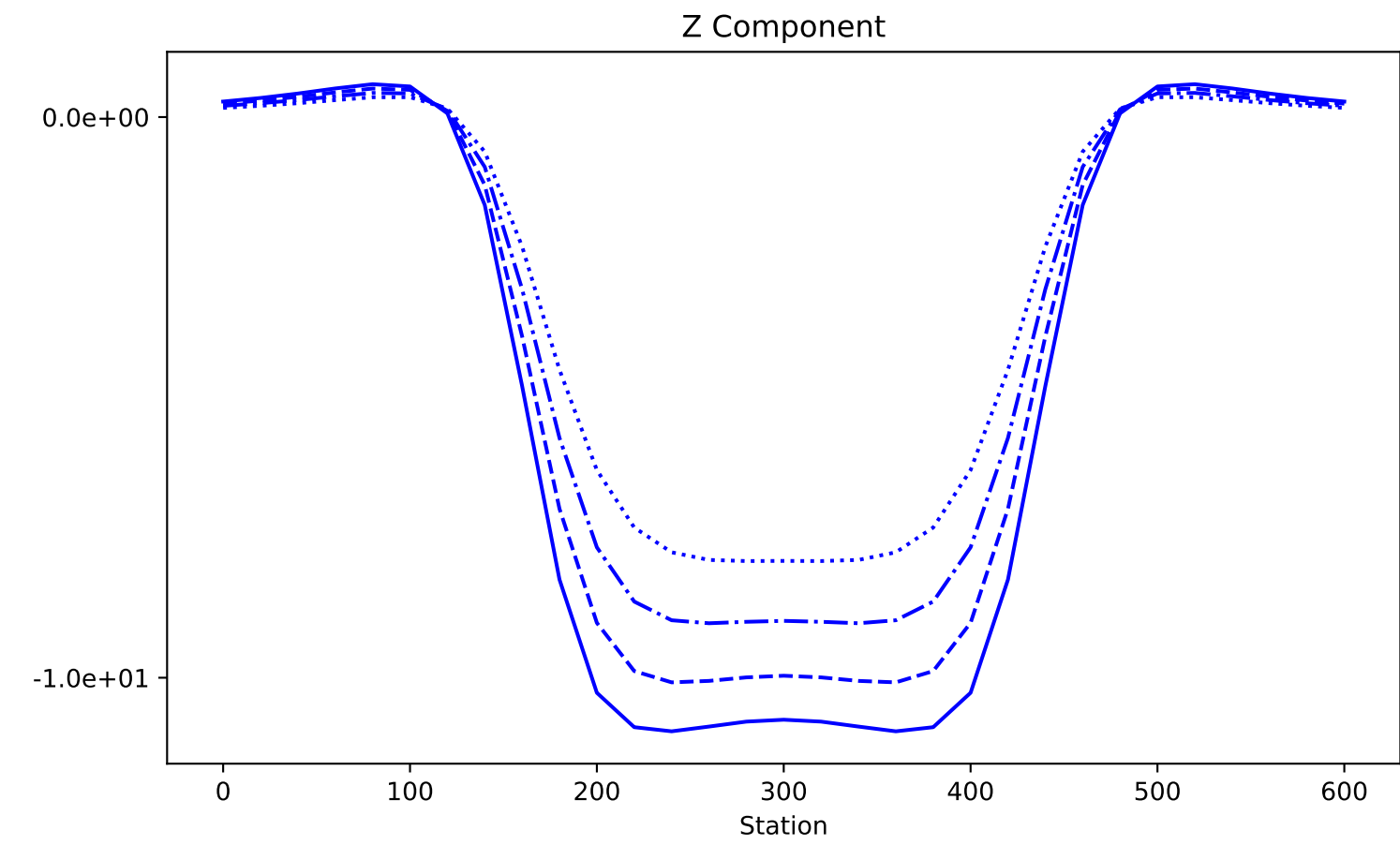
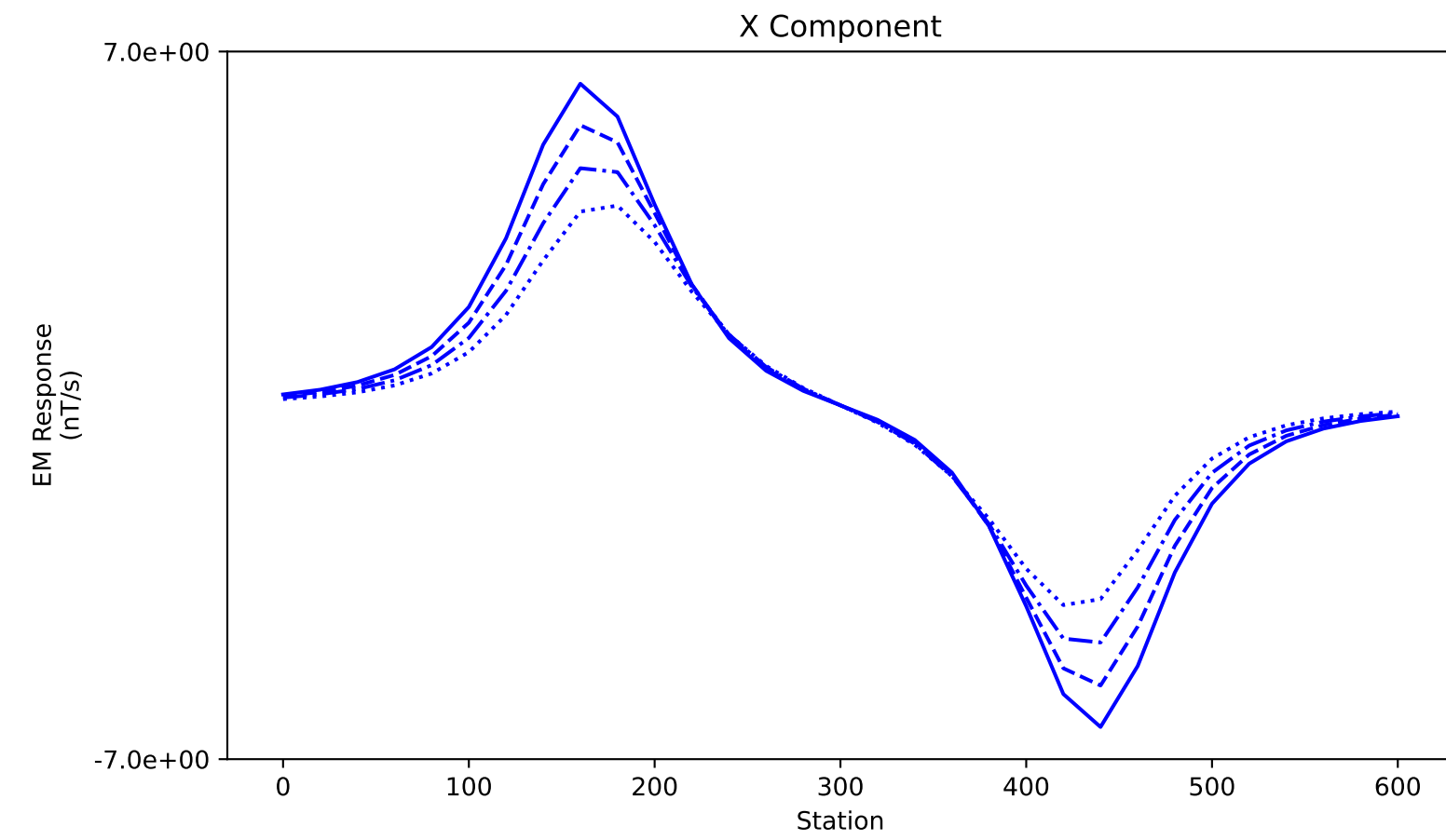
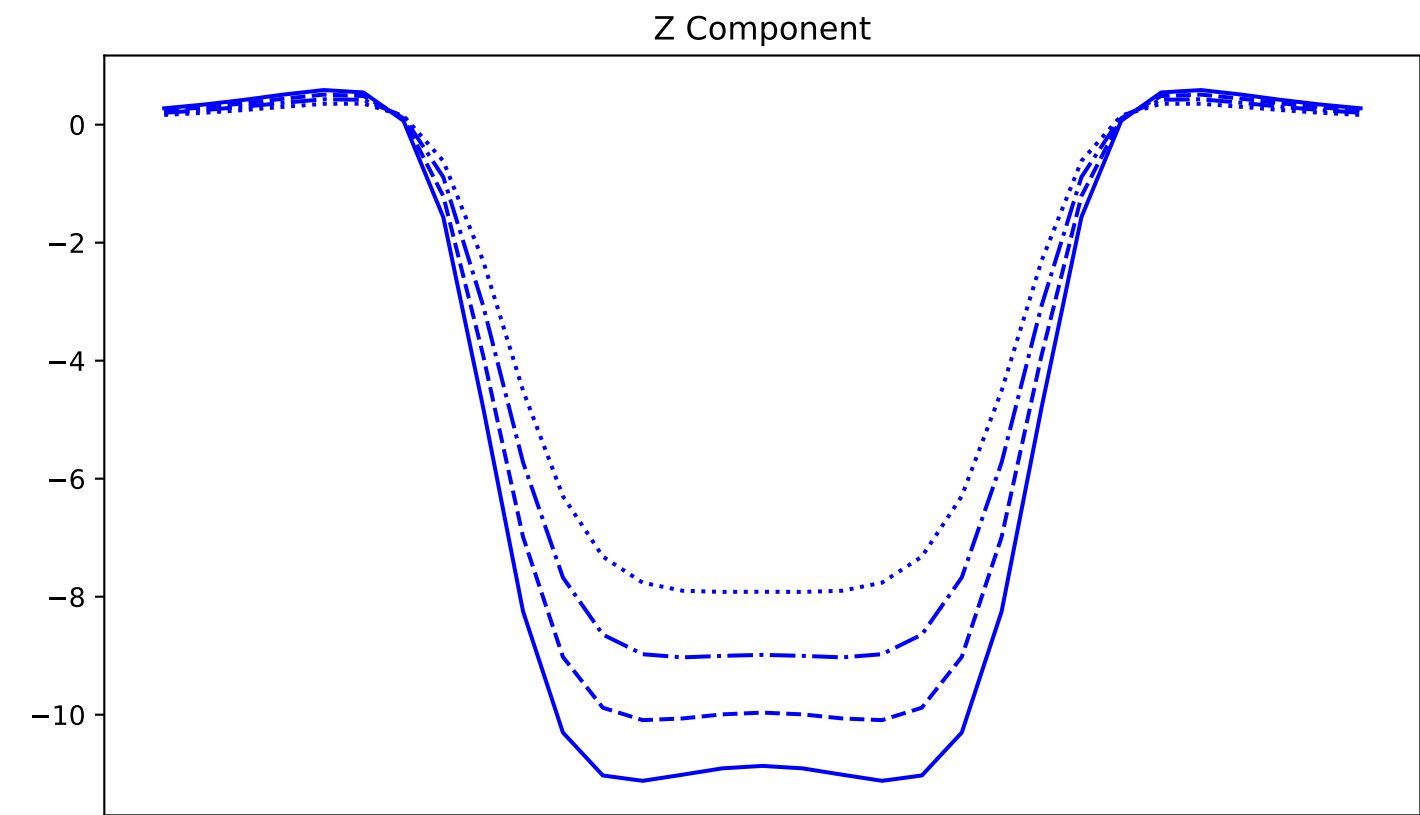
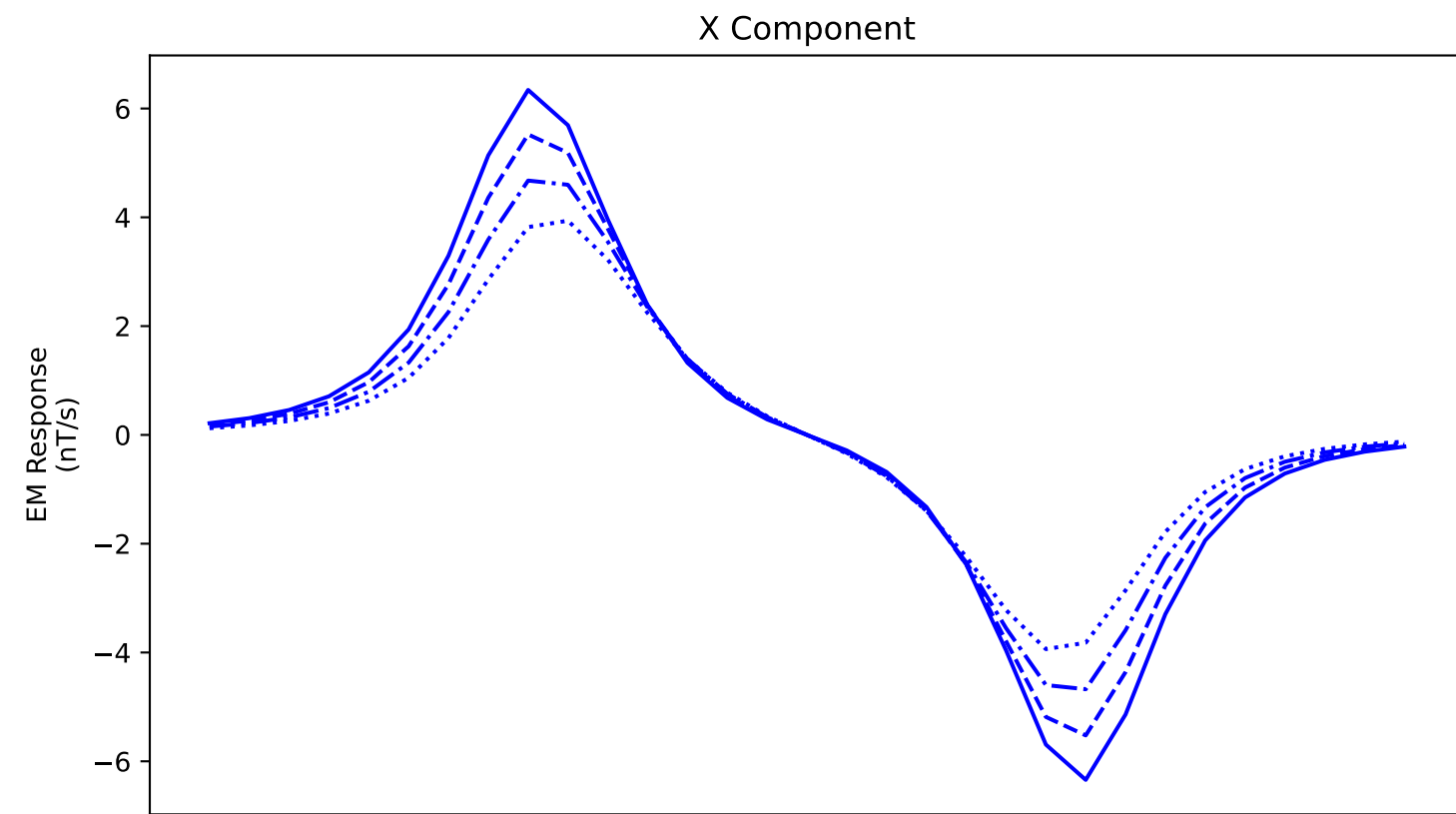
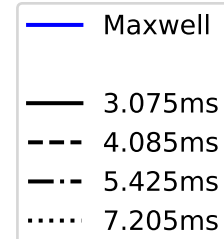
Two-Way Induction
300x100m, 1000S
LOOP=-300
0.56ms to 1.315ms



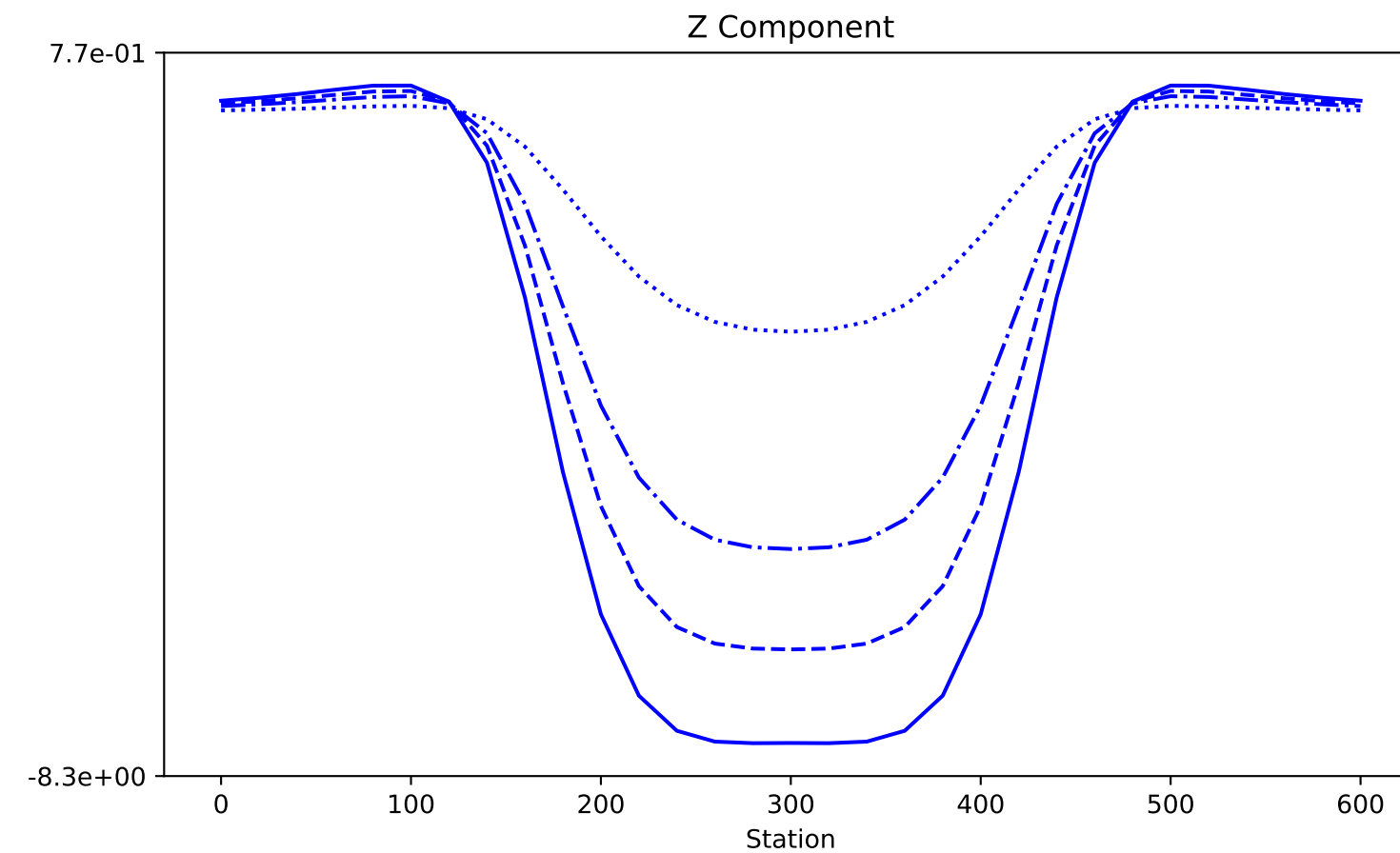
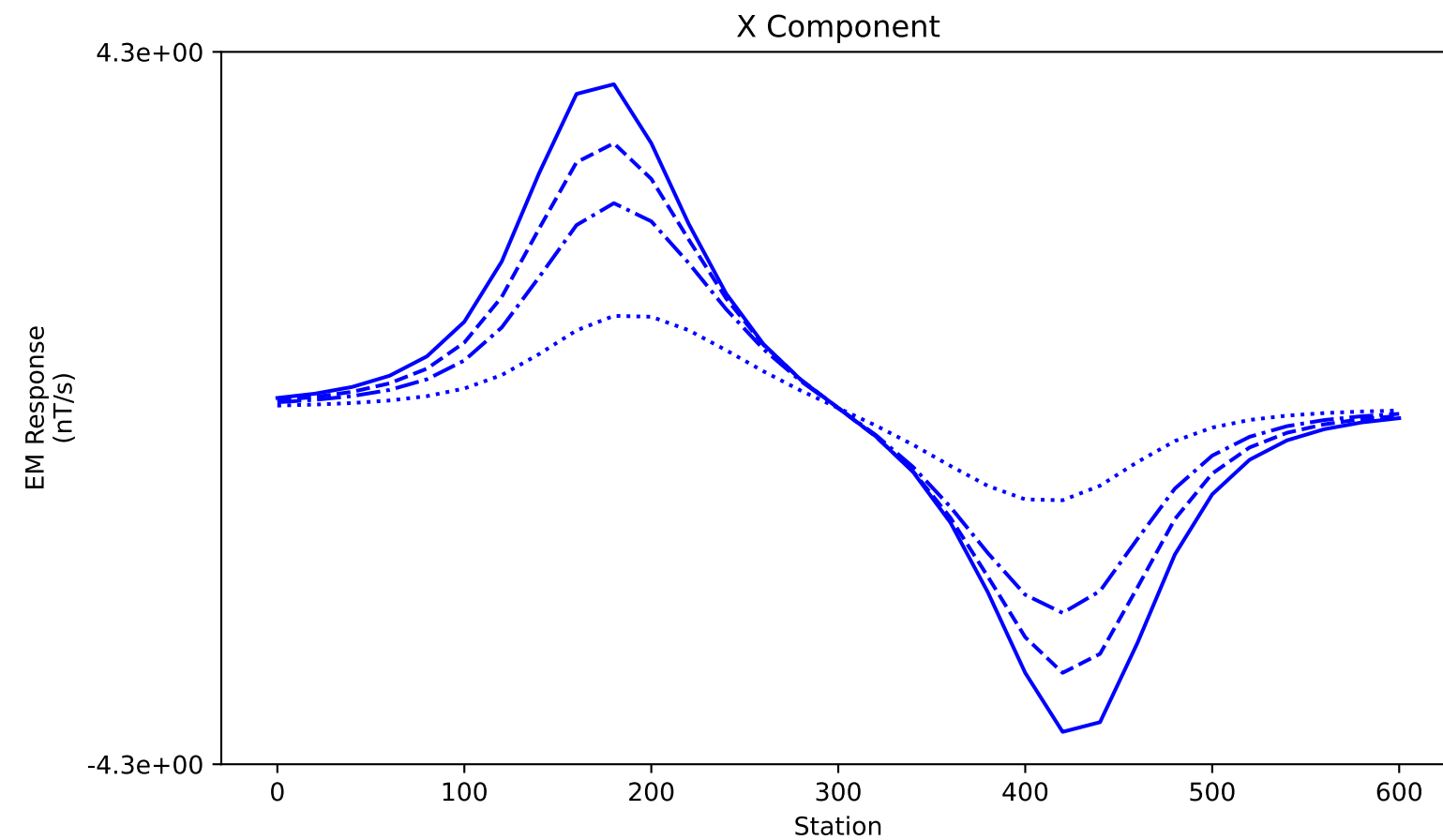
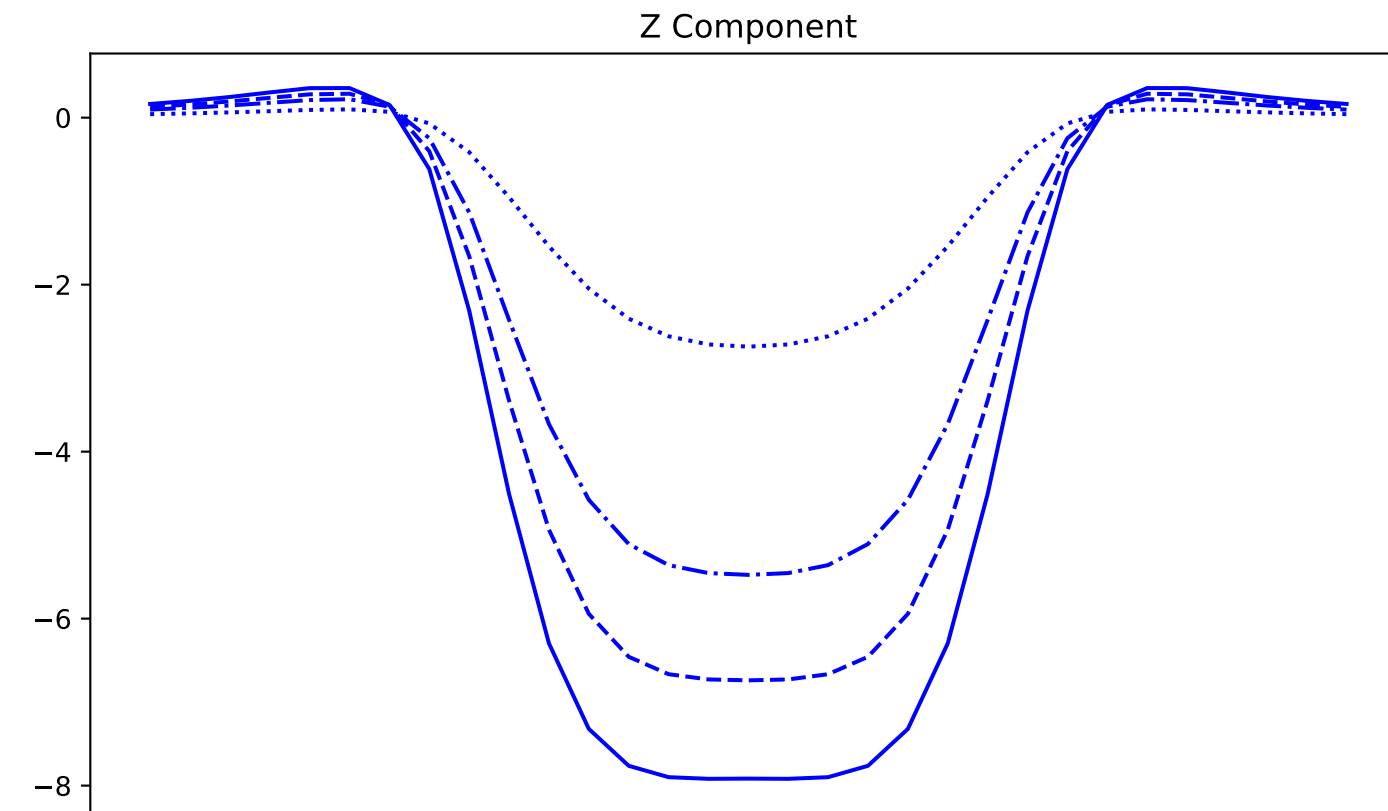
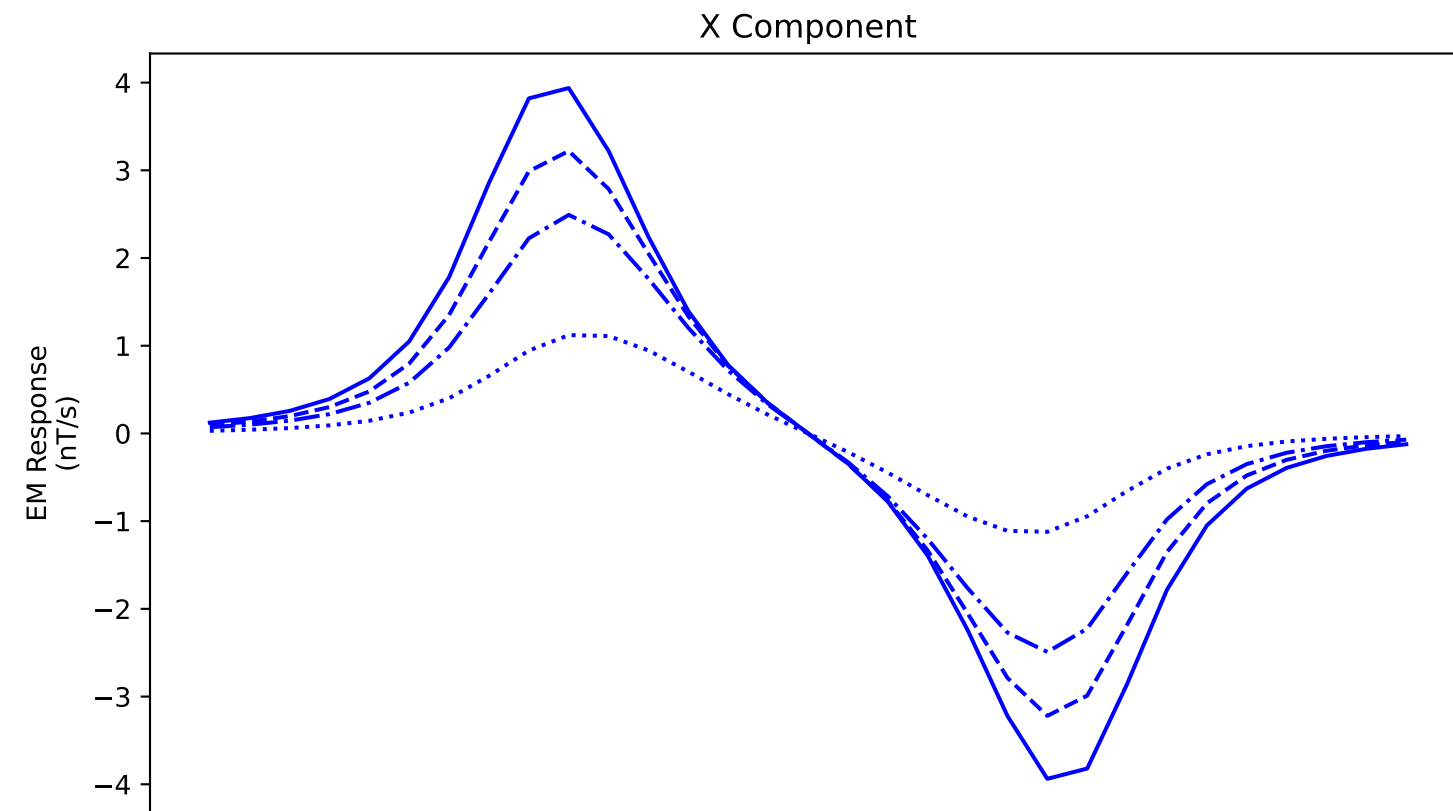
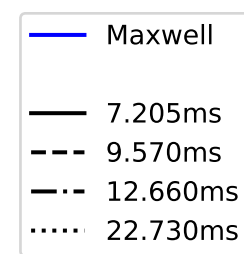
Two-Way Induction
300x100m, 1000S
LOOP=-300
1.315ms to 3.075ms



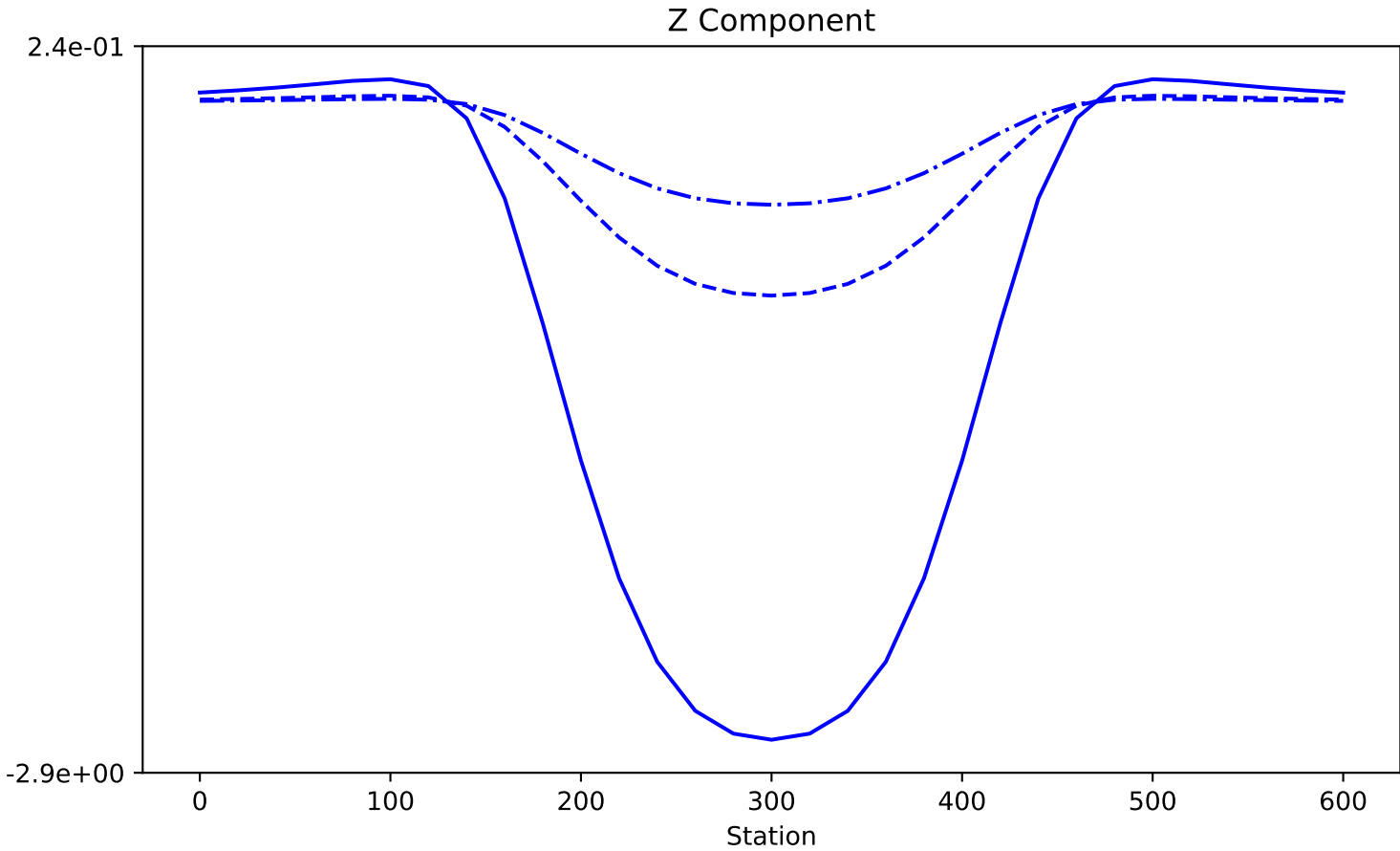
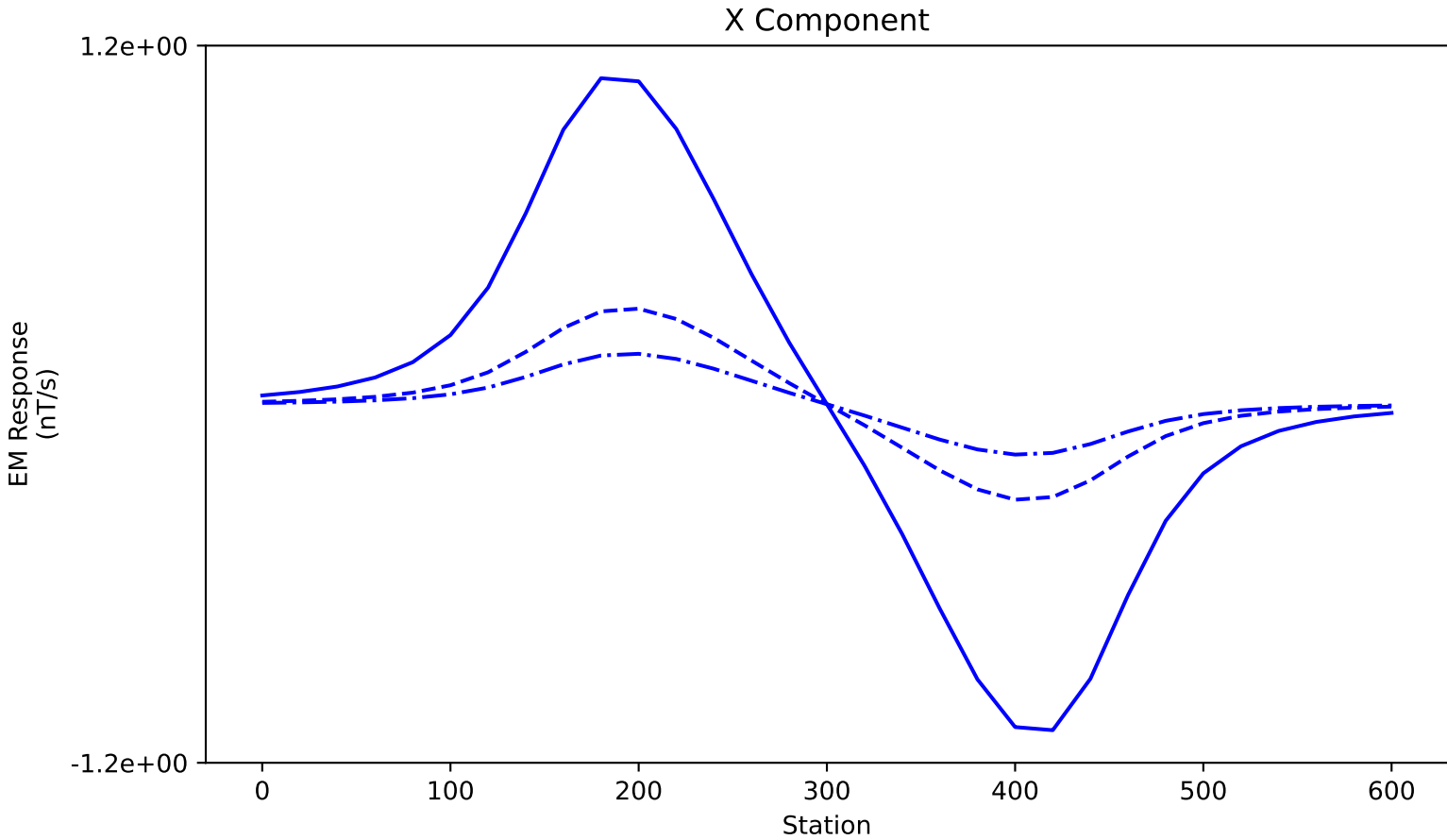
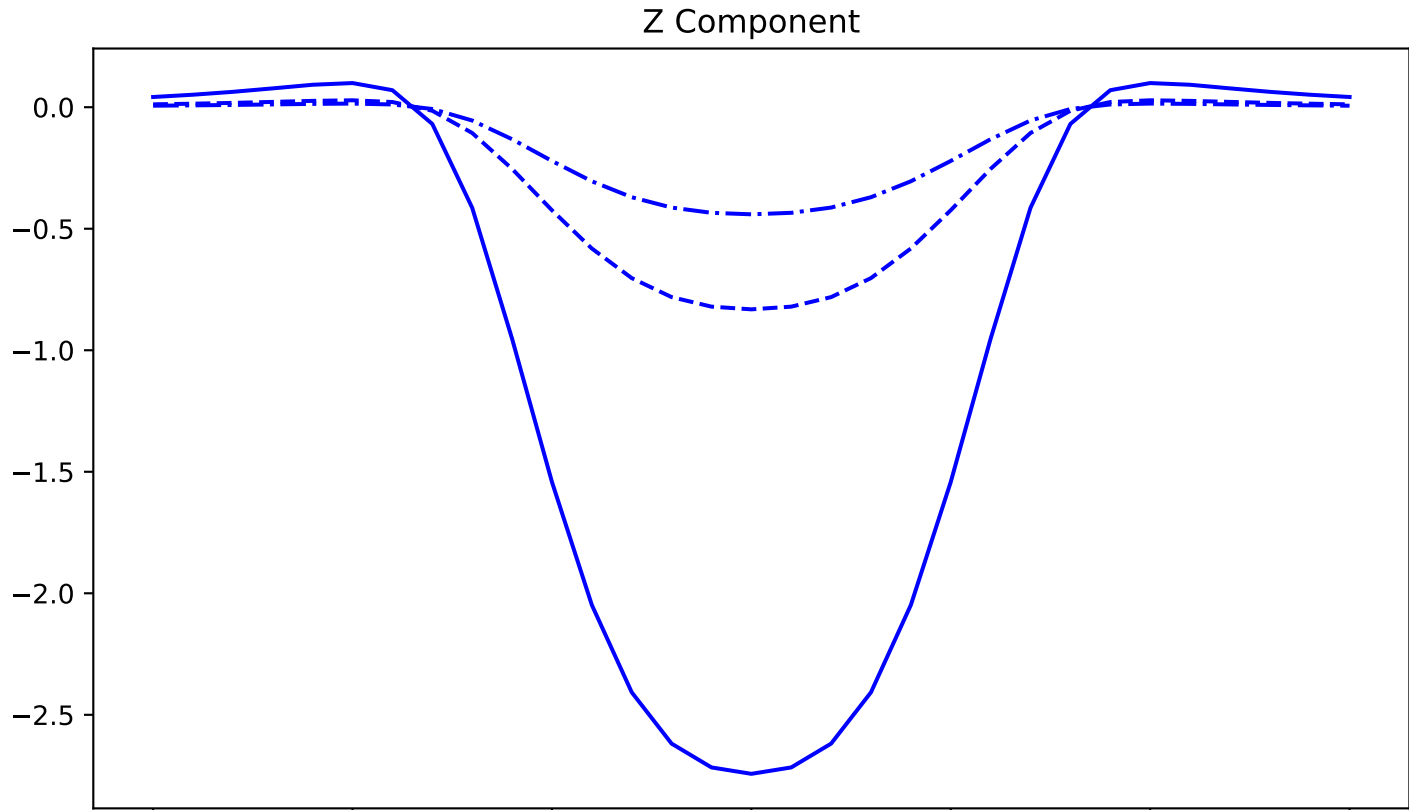
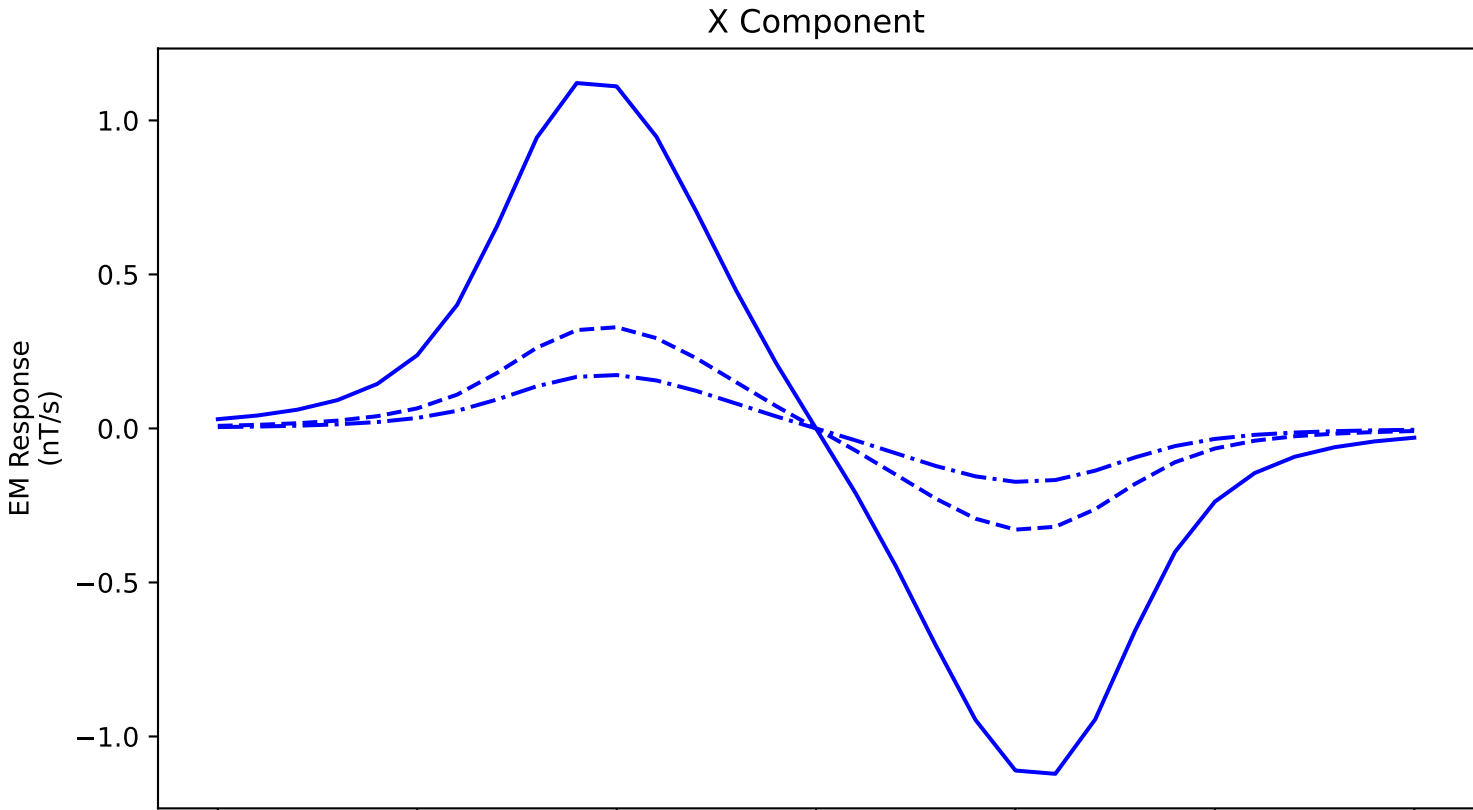
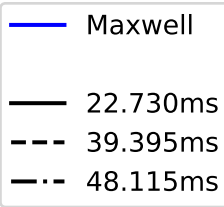
Two-Way Induction
300x100m, 1000S
LOOP=-300
3.075ms to 7.205ms



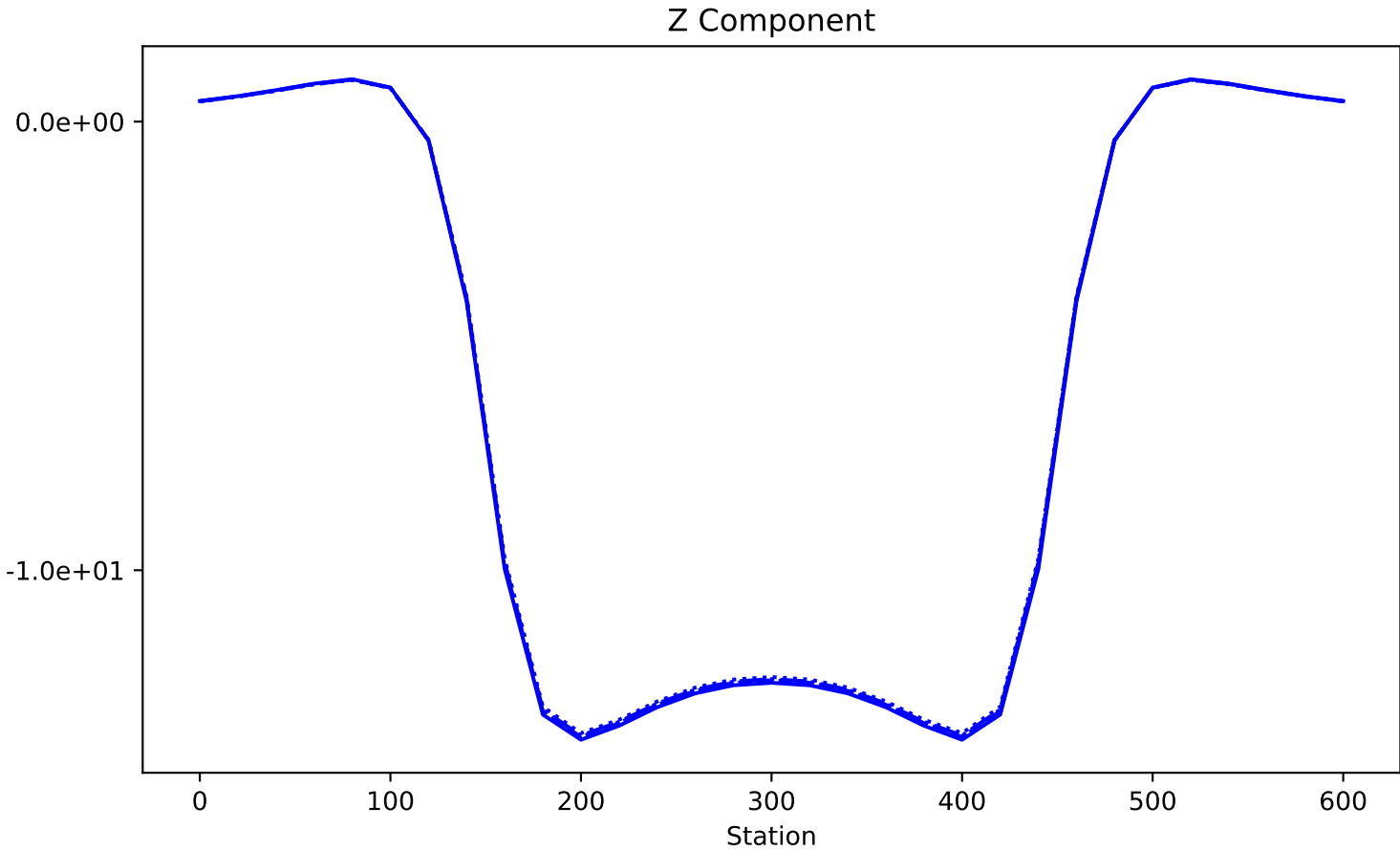
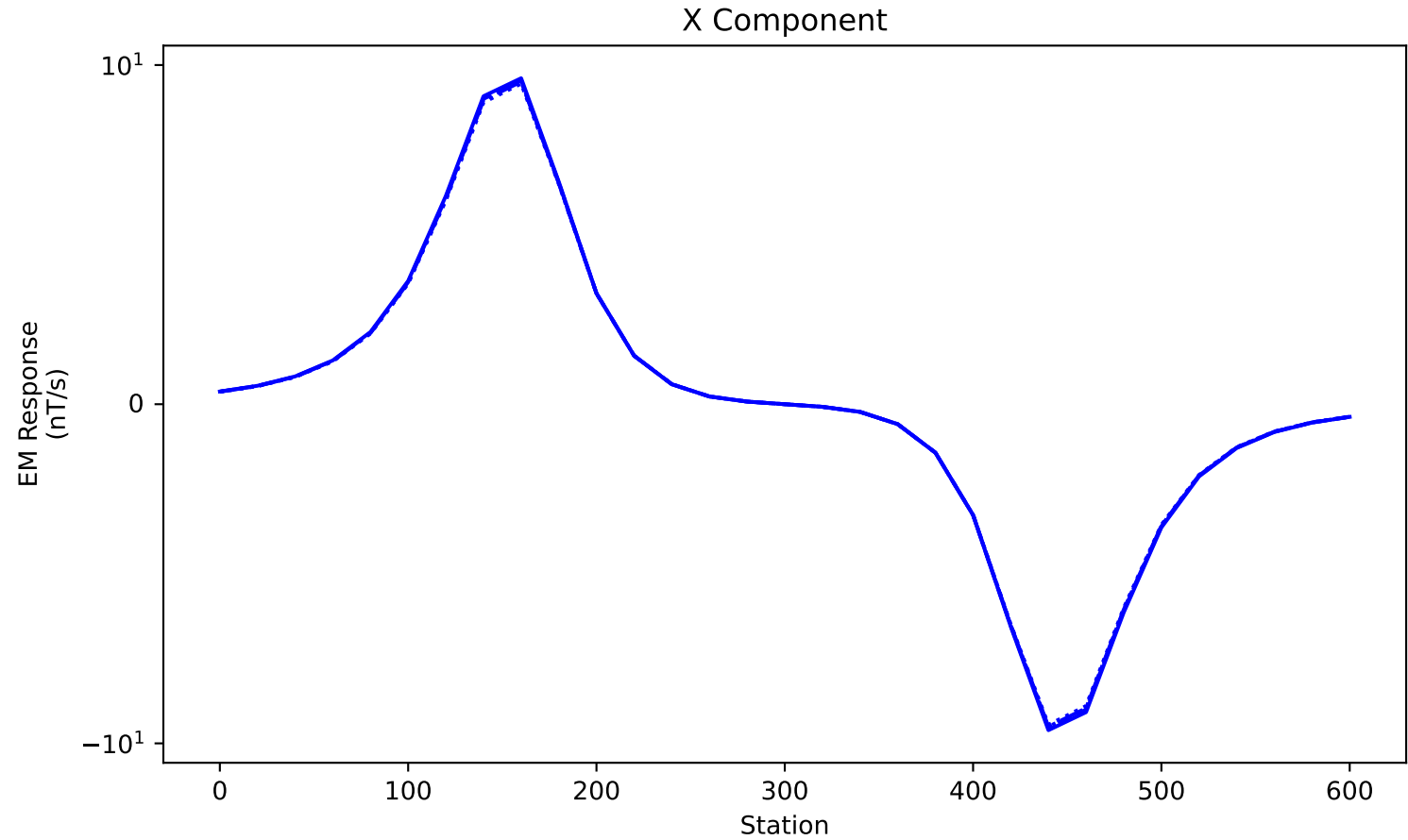
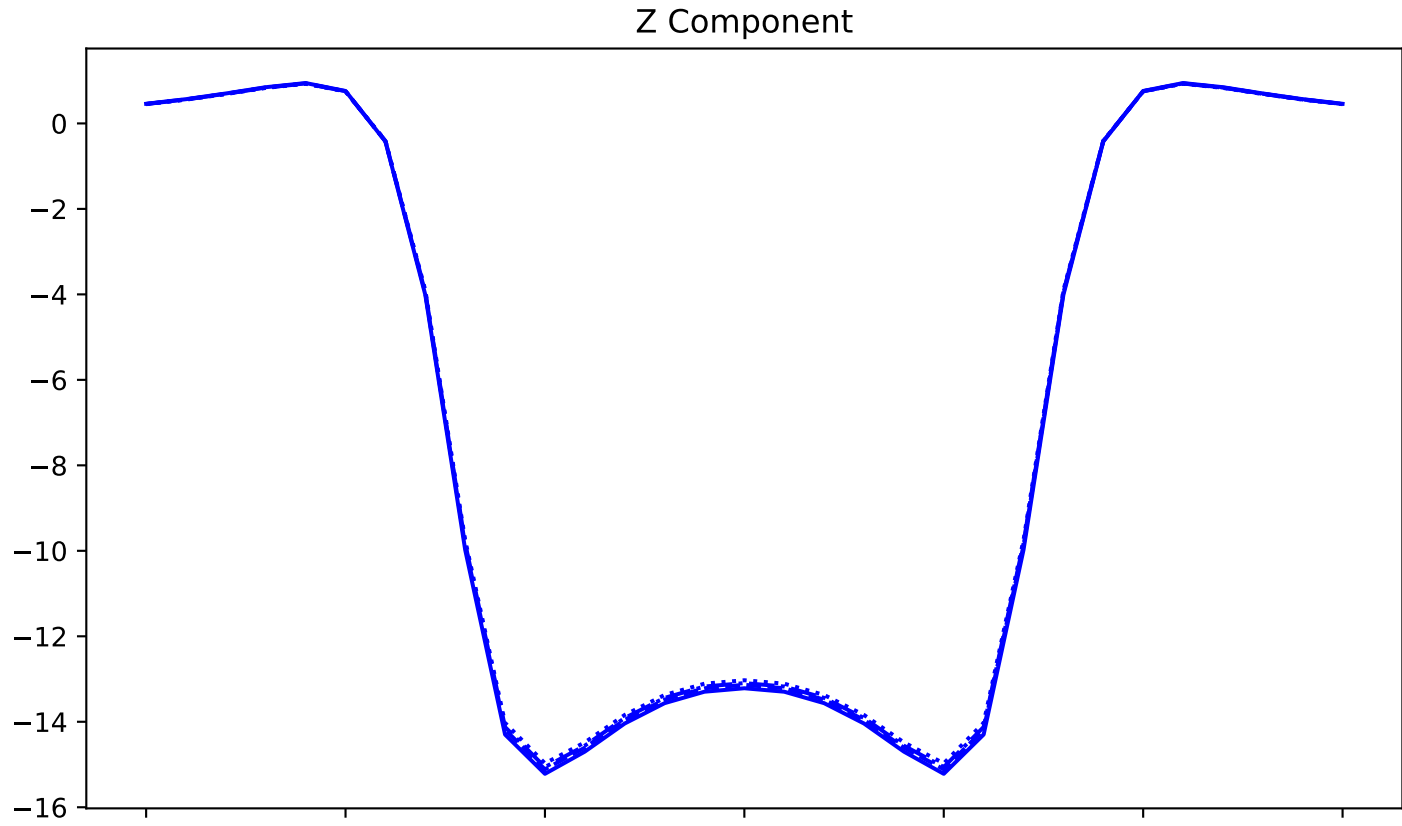
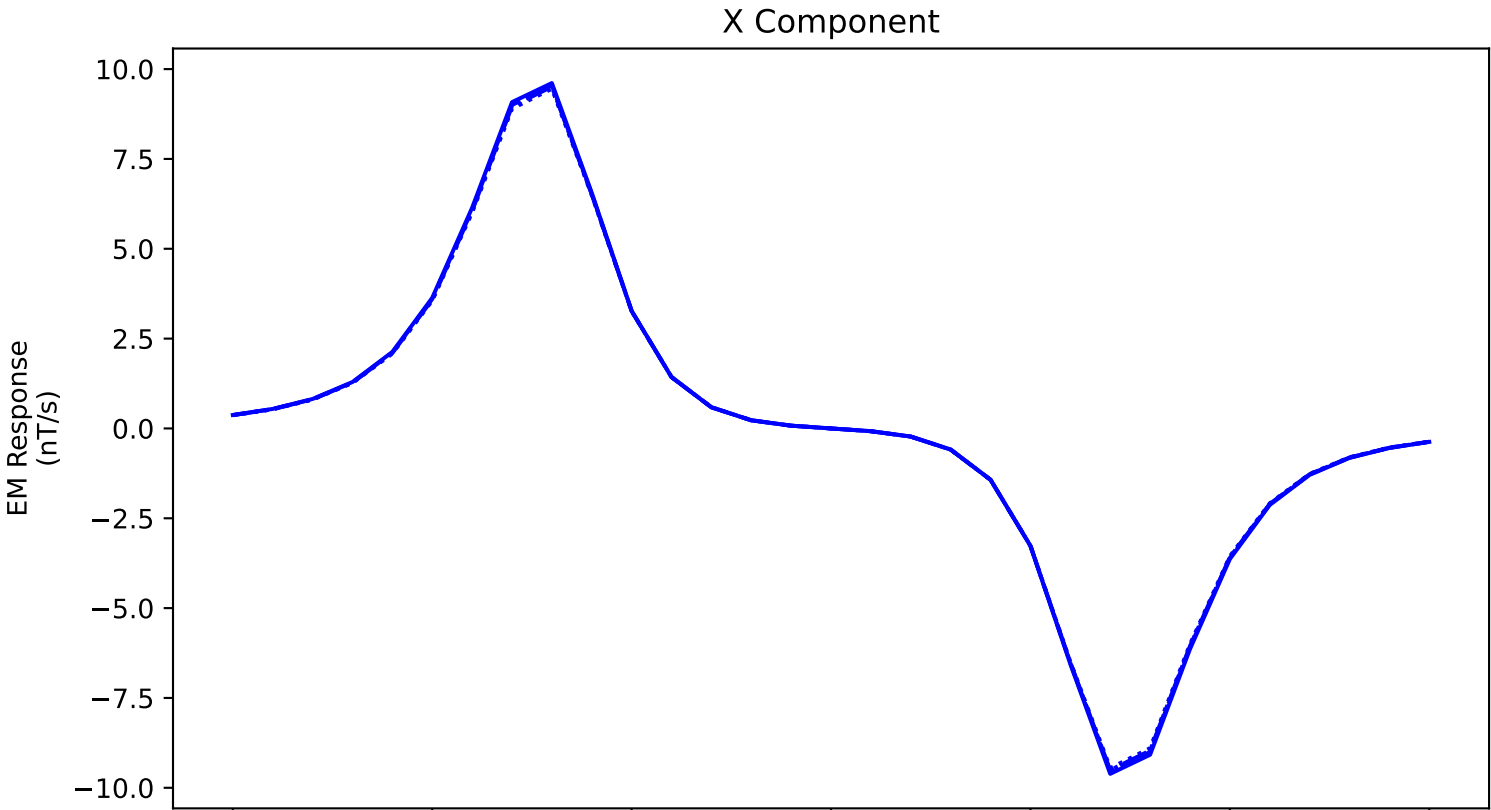
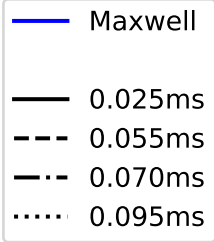
Two-Way Induction
300x100m, 1000S
LOOP=-300
7.205ms to 22.73ms



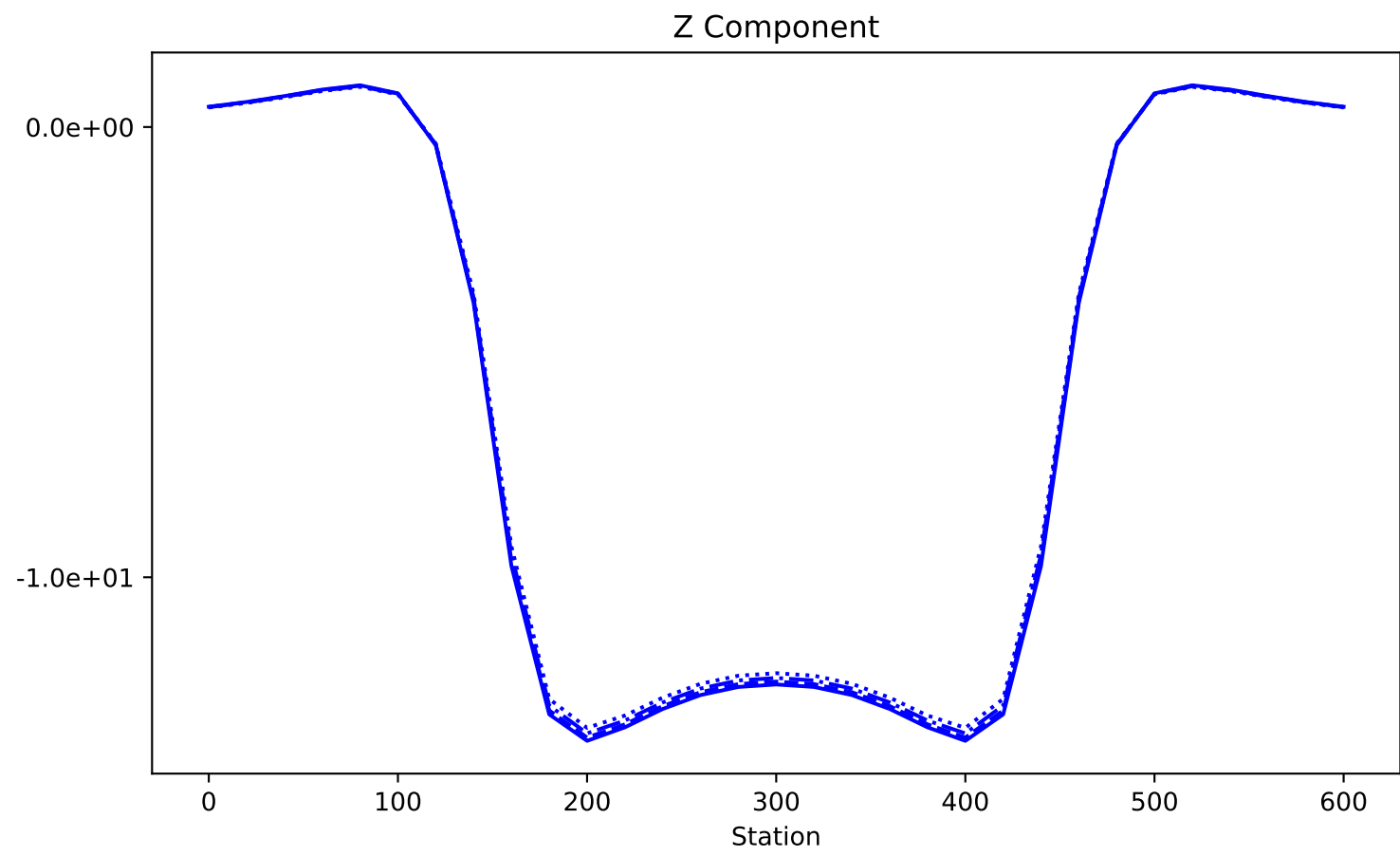
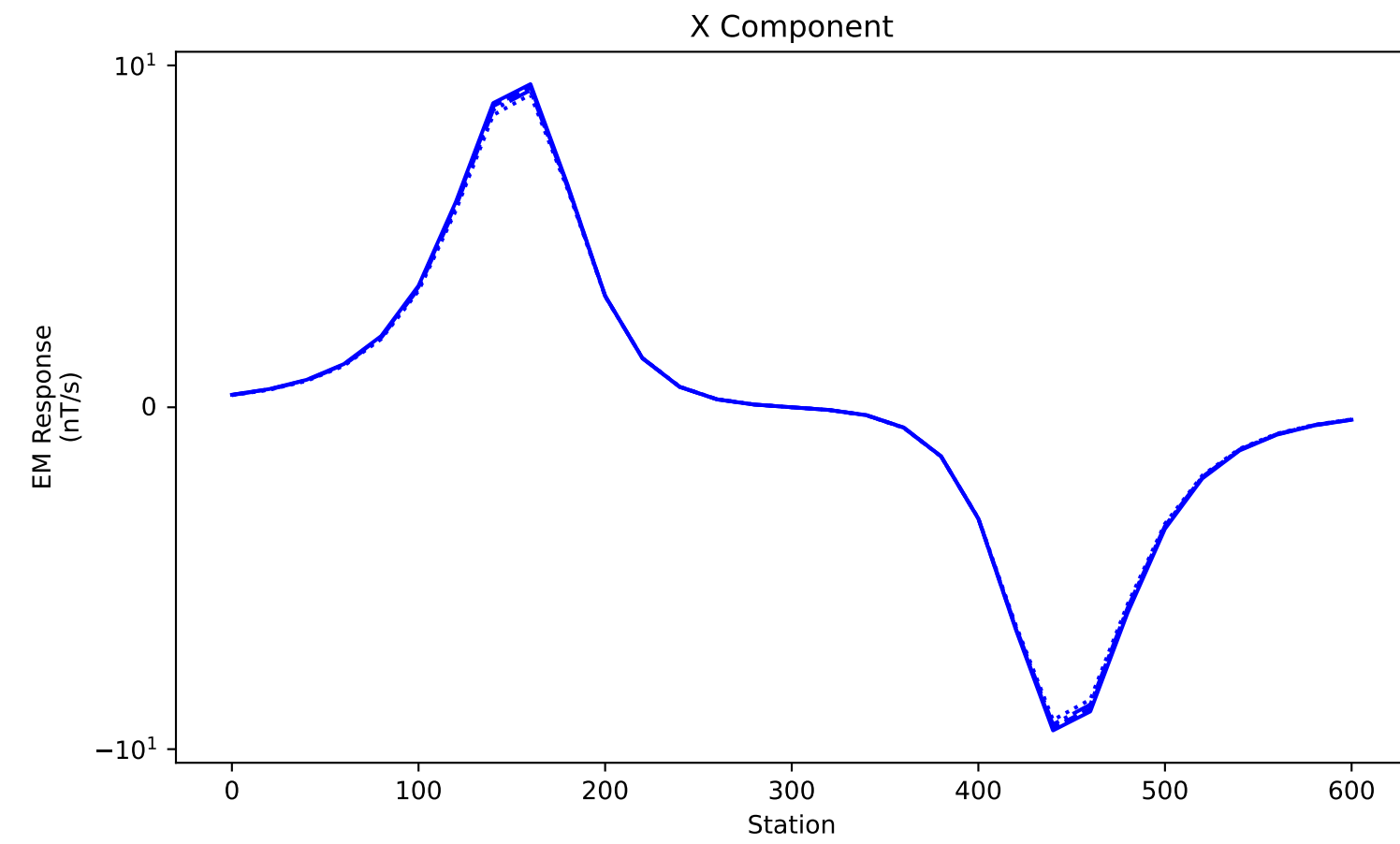
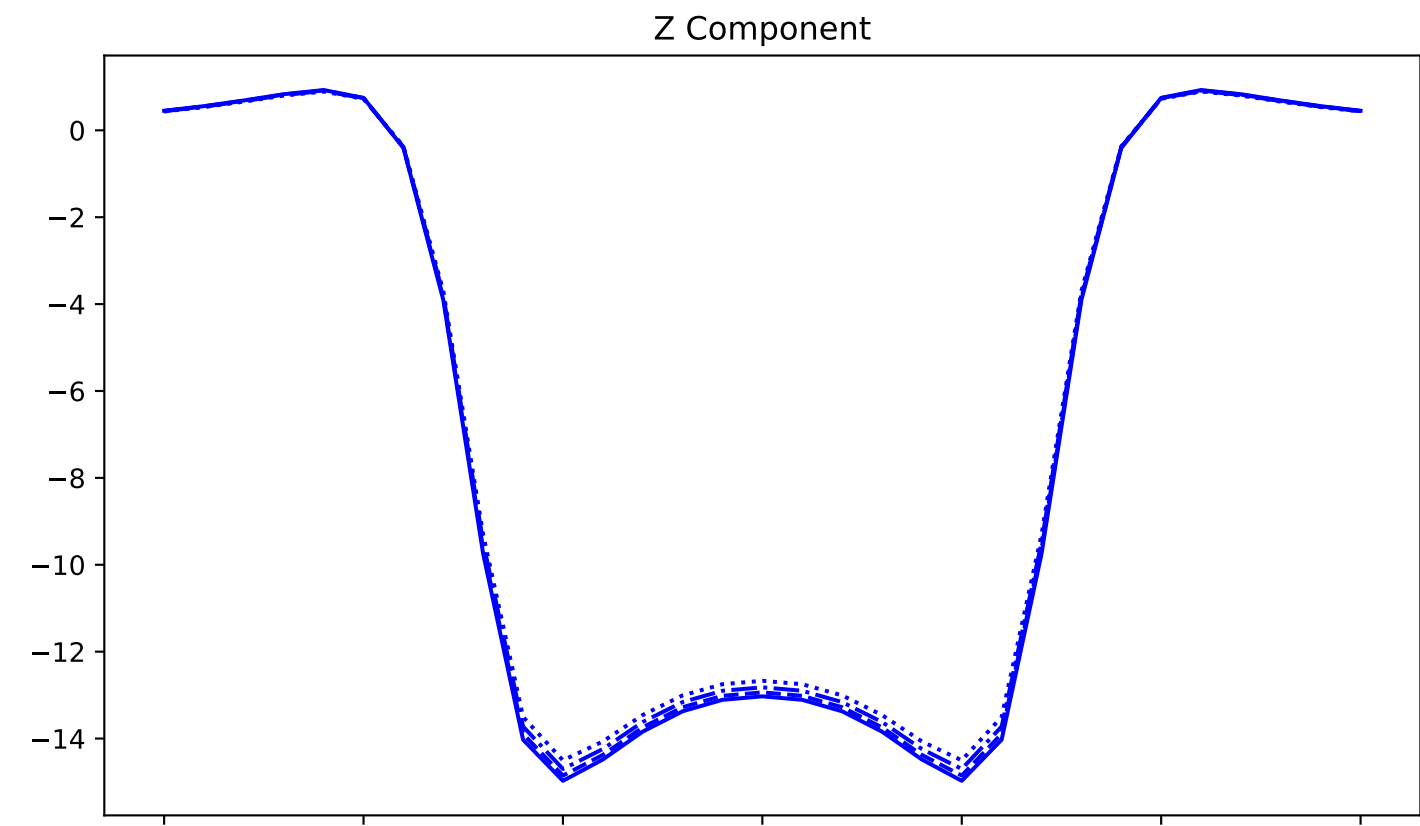
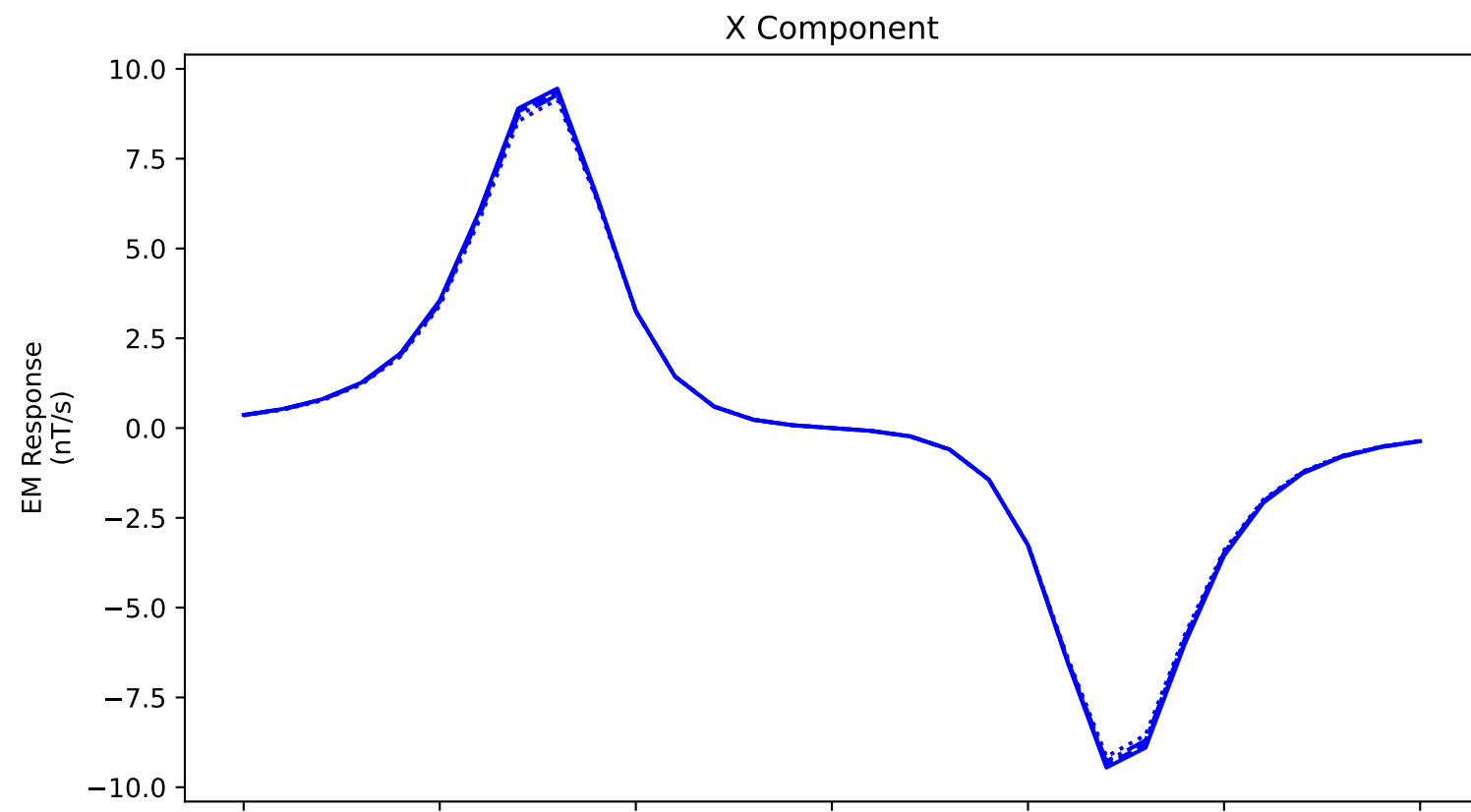
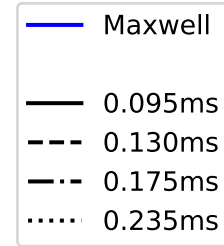
Two-Way Induction
300x100m, 1000S
LOOP=-300
22.73ms to 48.115ms



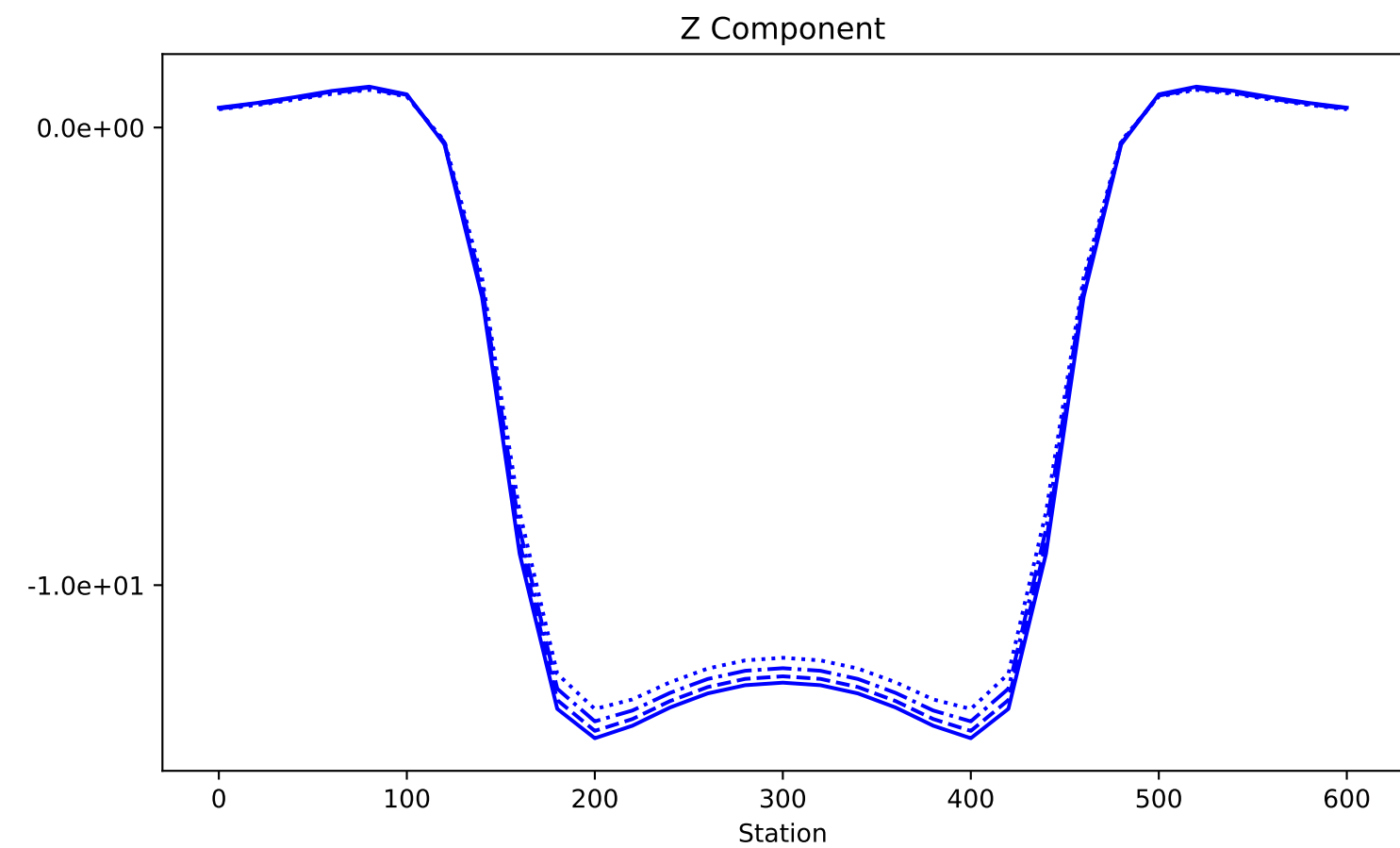
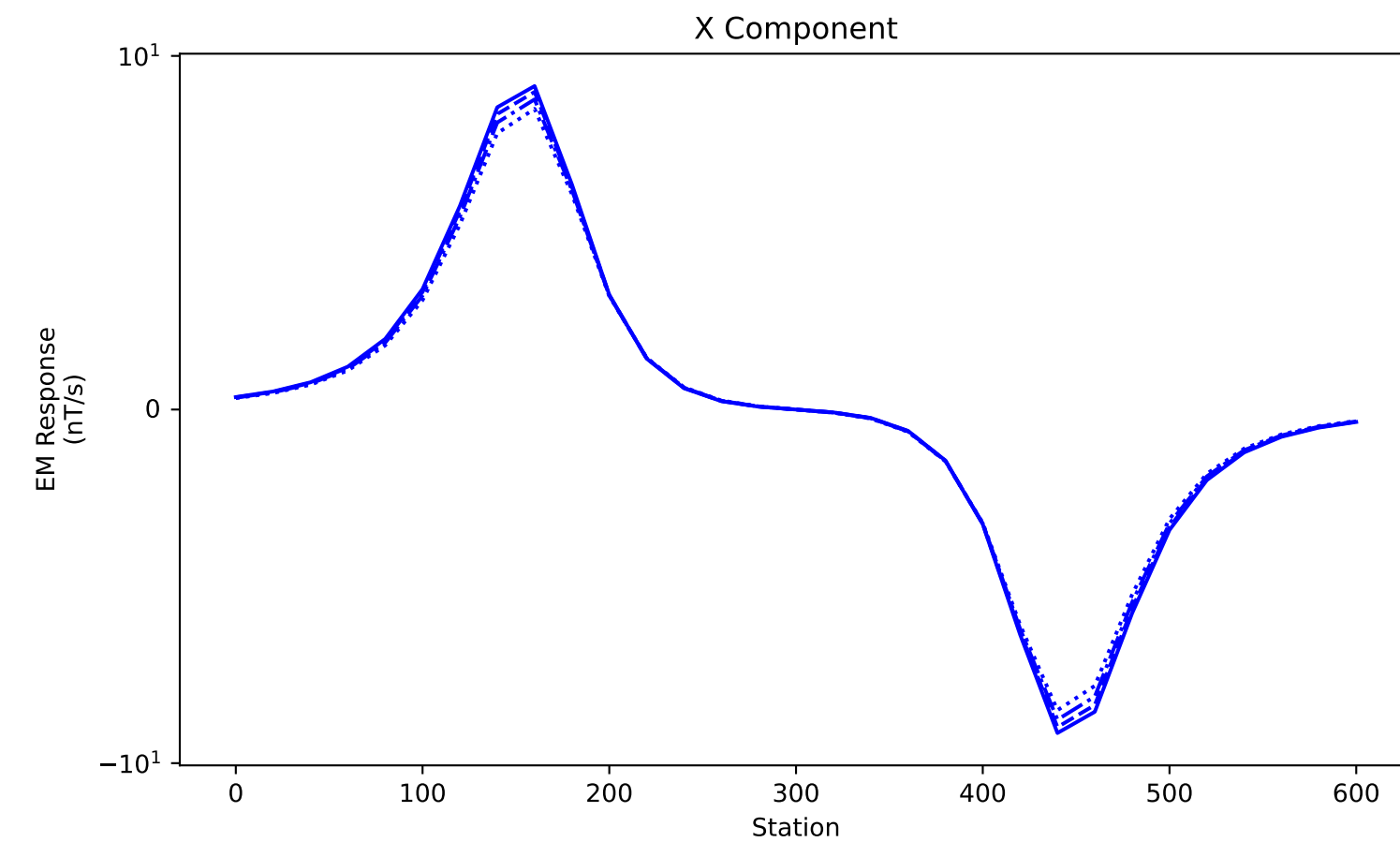
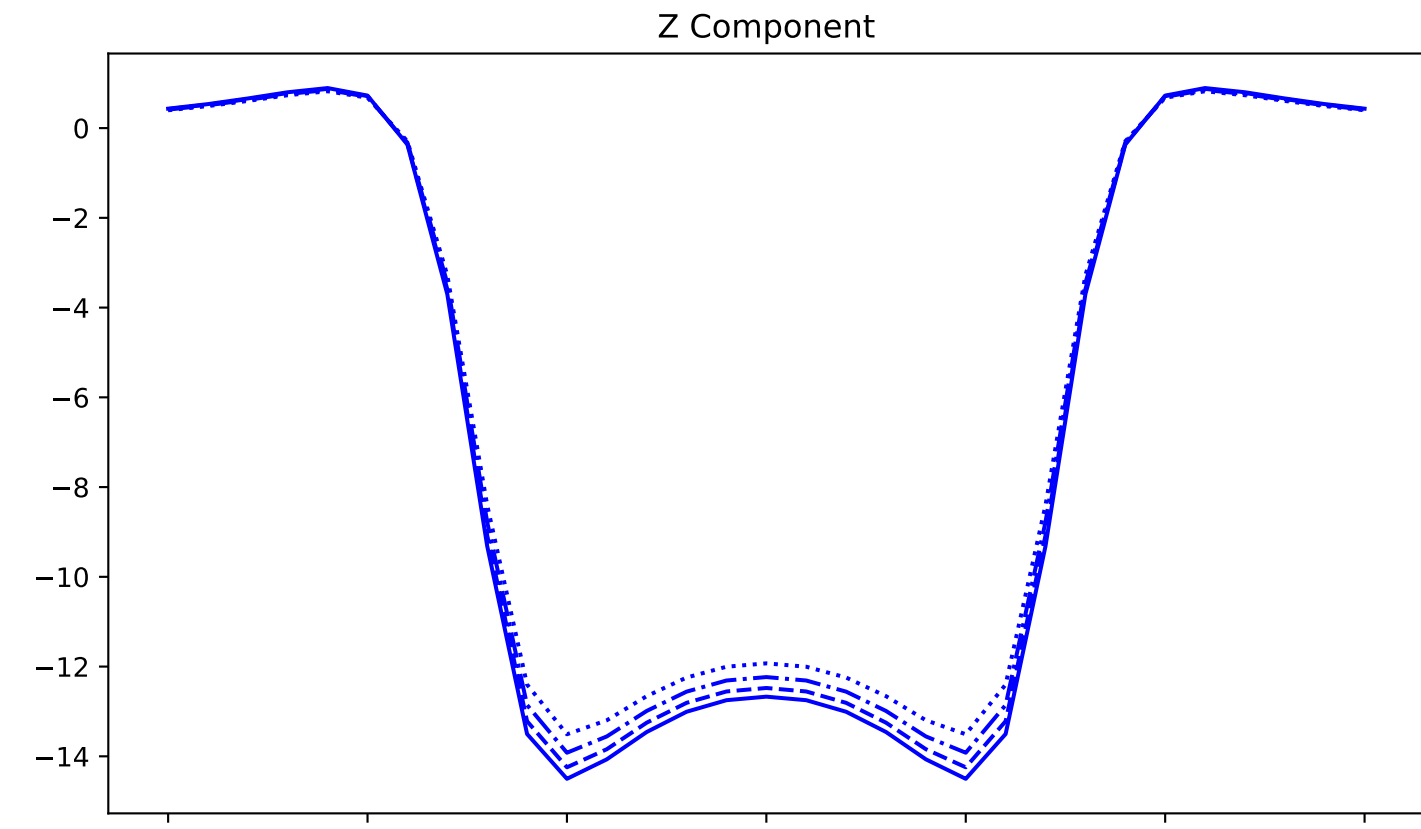
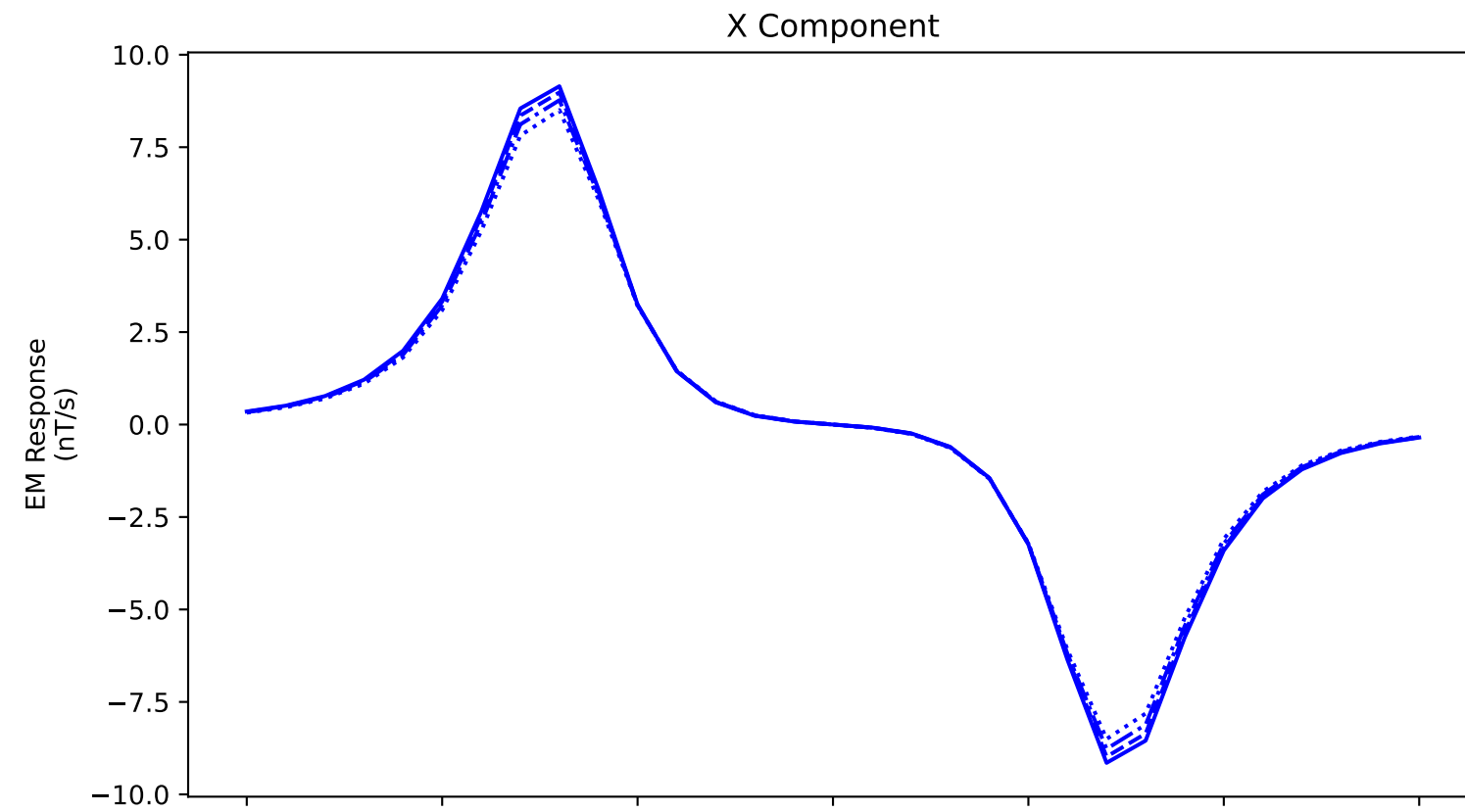
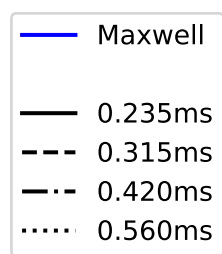
Two-Way Induction
300x100m, 1000S
LOOP=-350
0.0255ms to 0.095ms



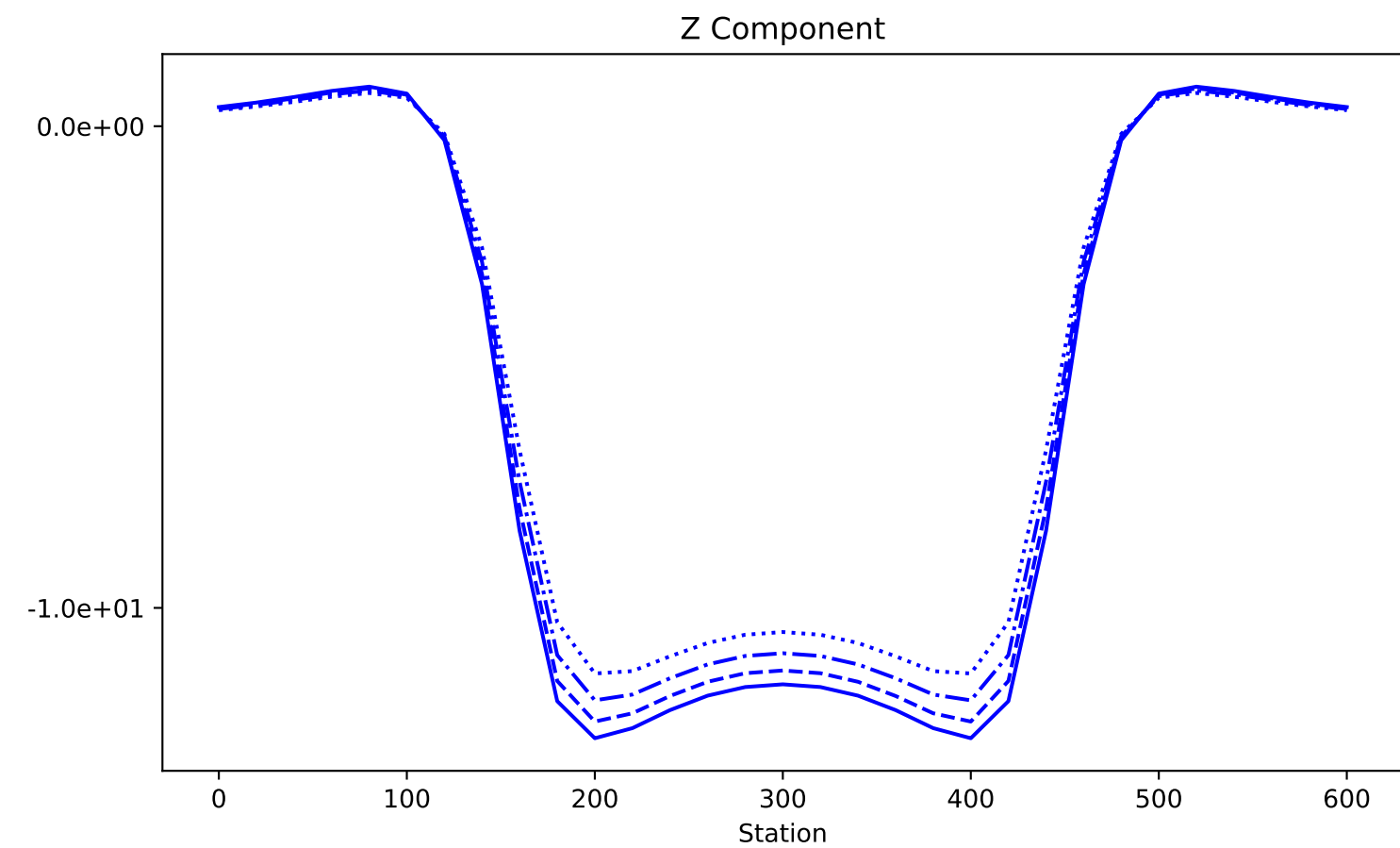
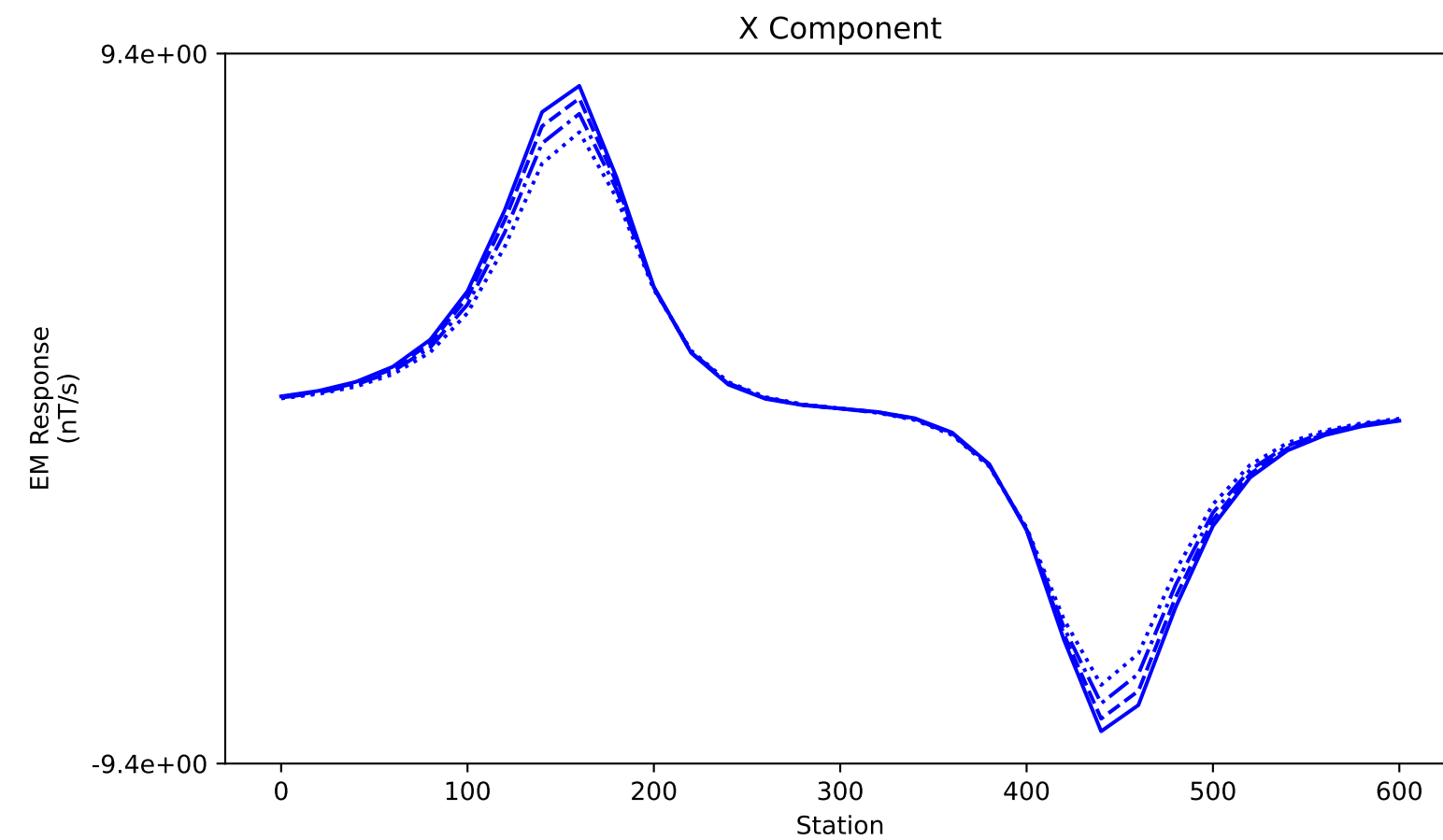
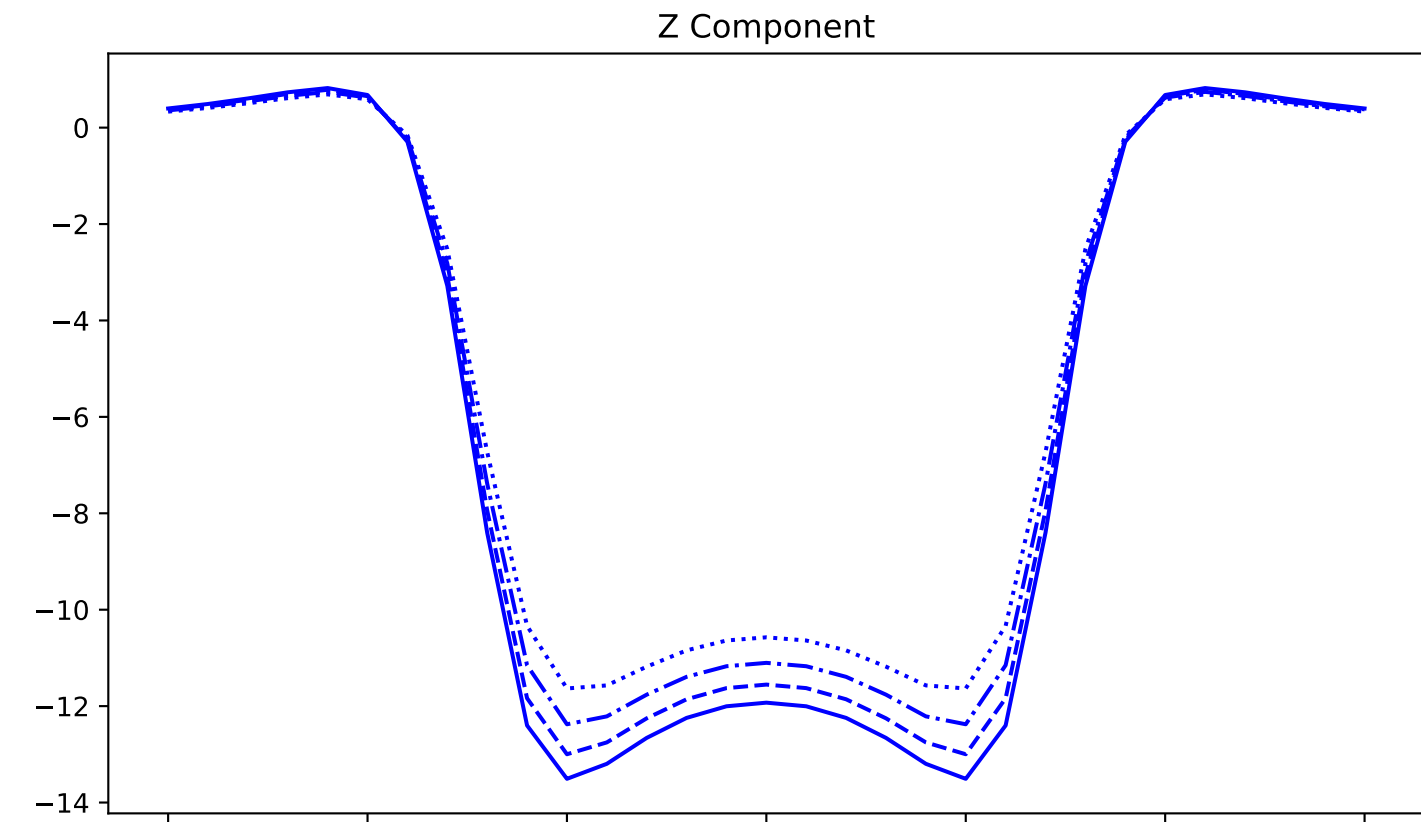
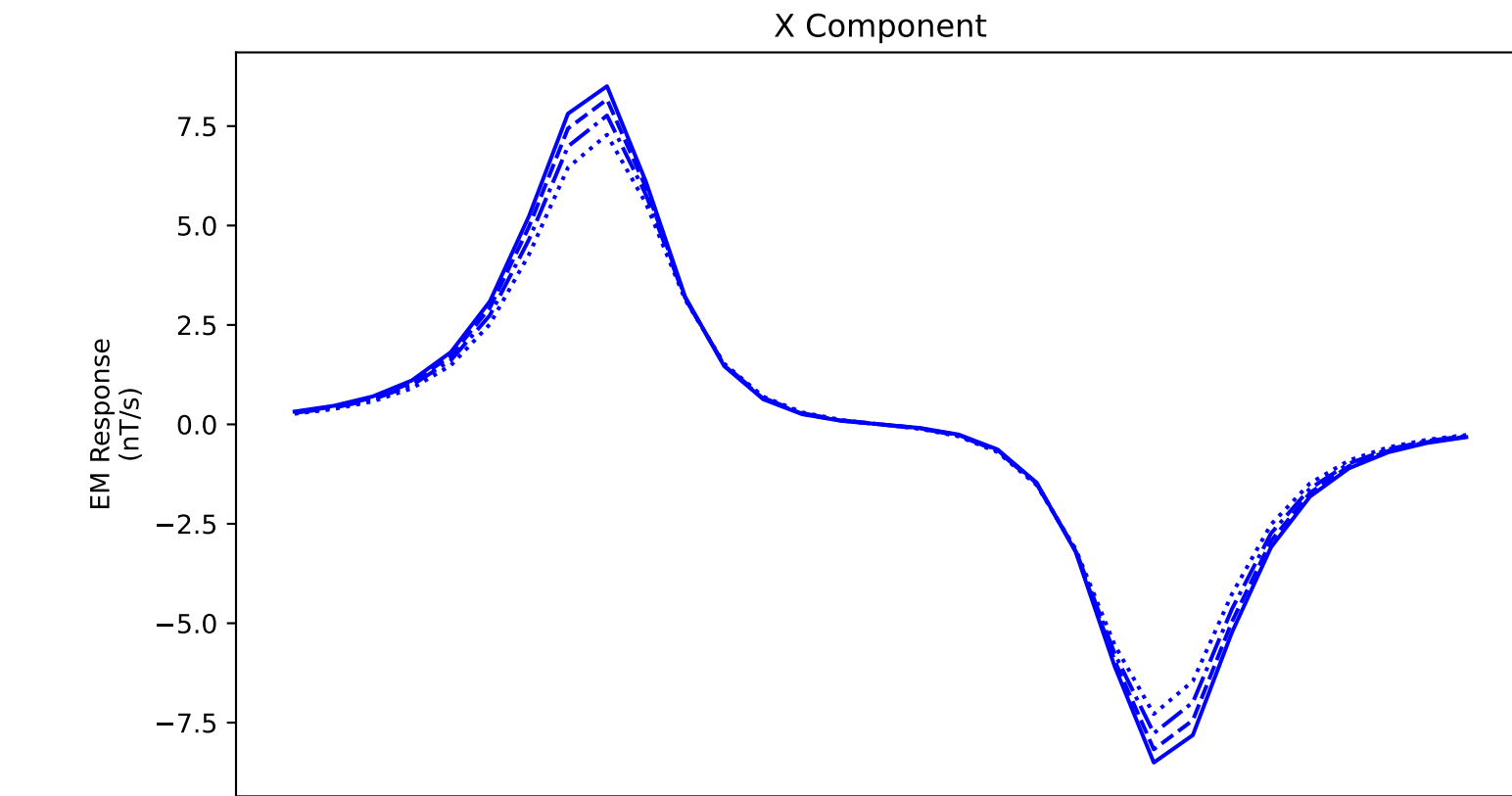
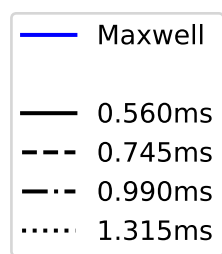
Two-Way Induction
300x100m, 1000S
LOOP=-350
0.095ms to 0.235ms



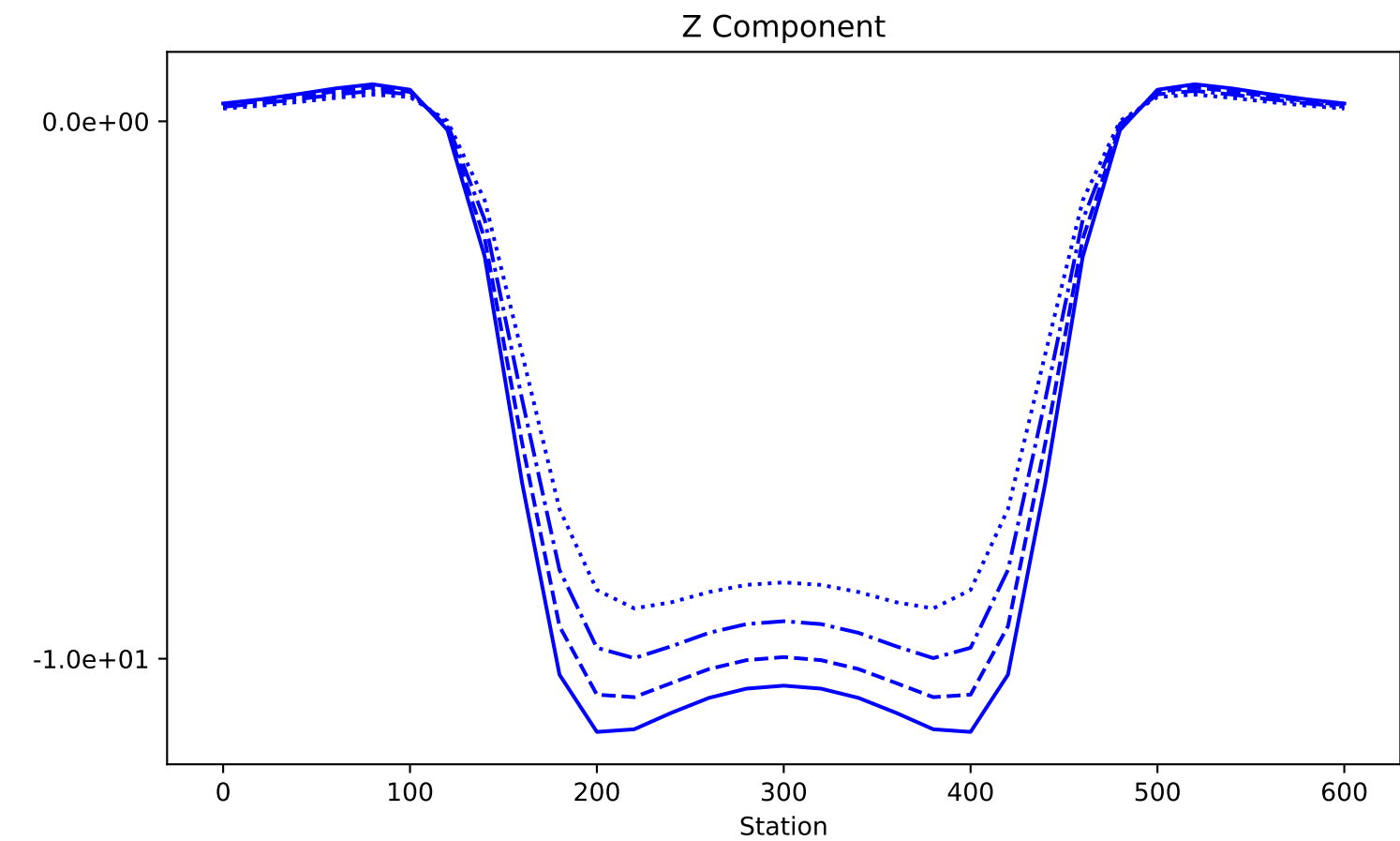
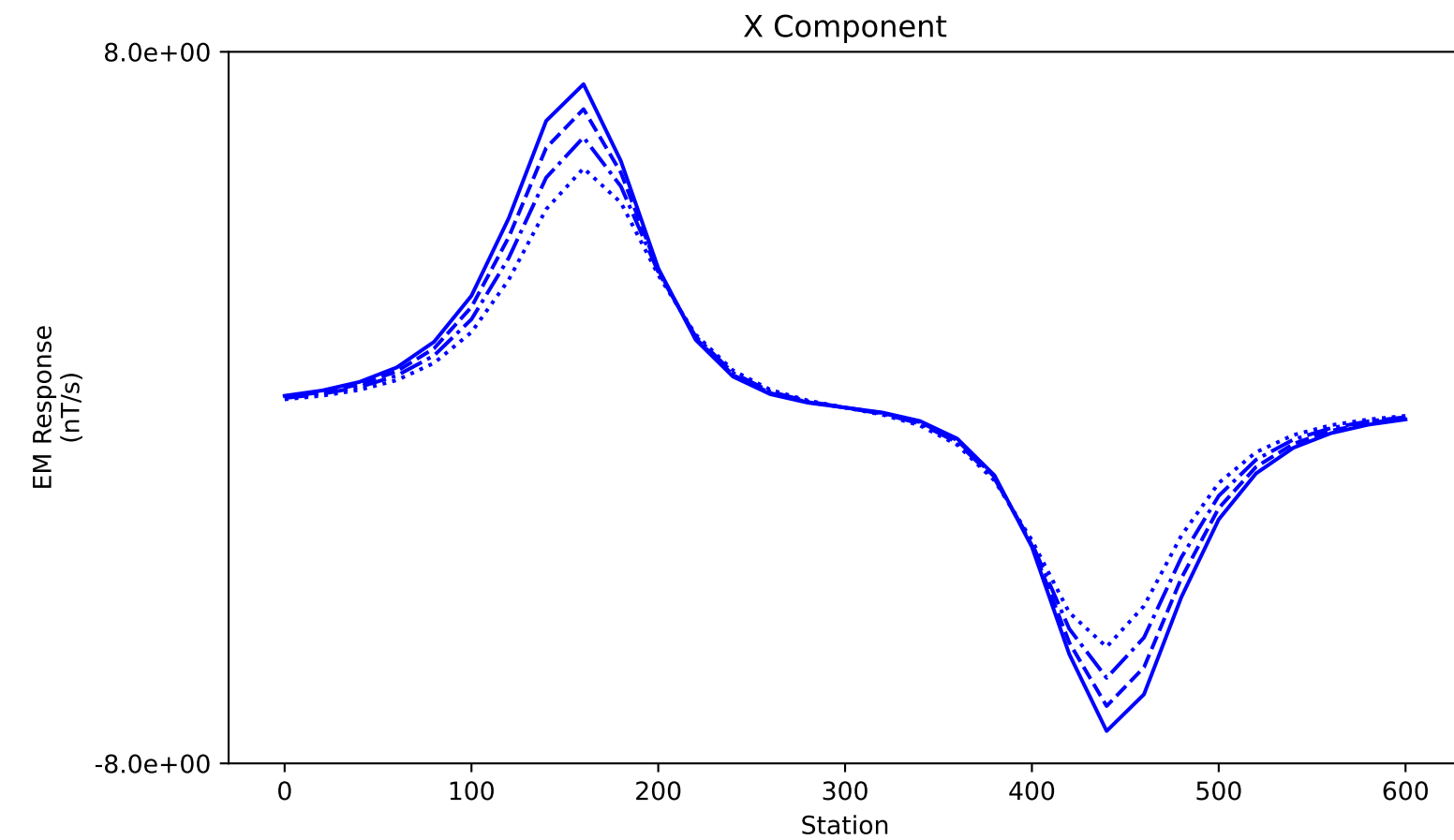
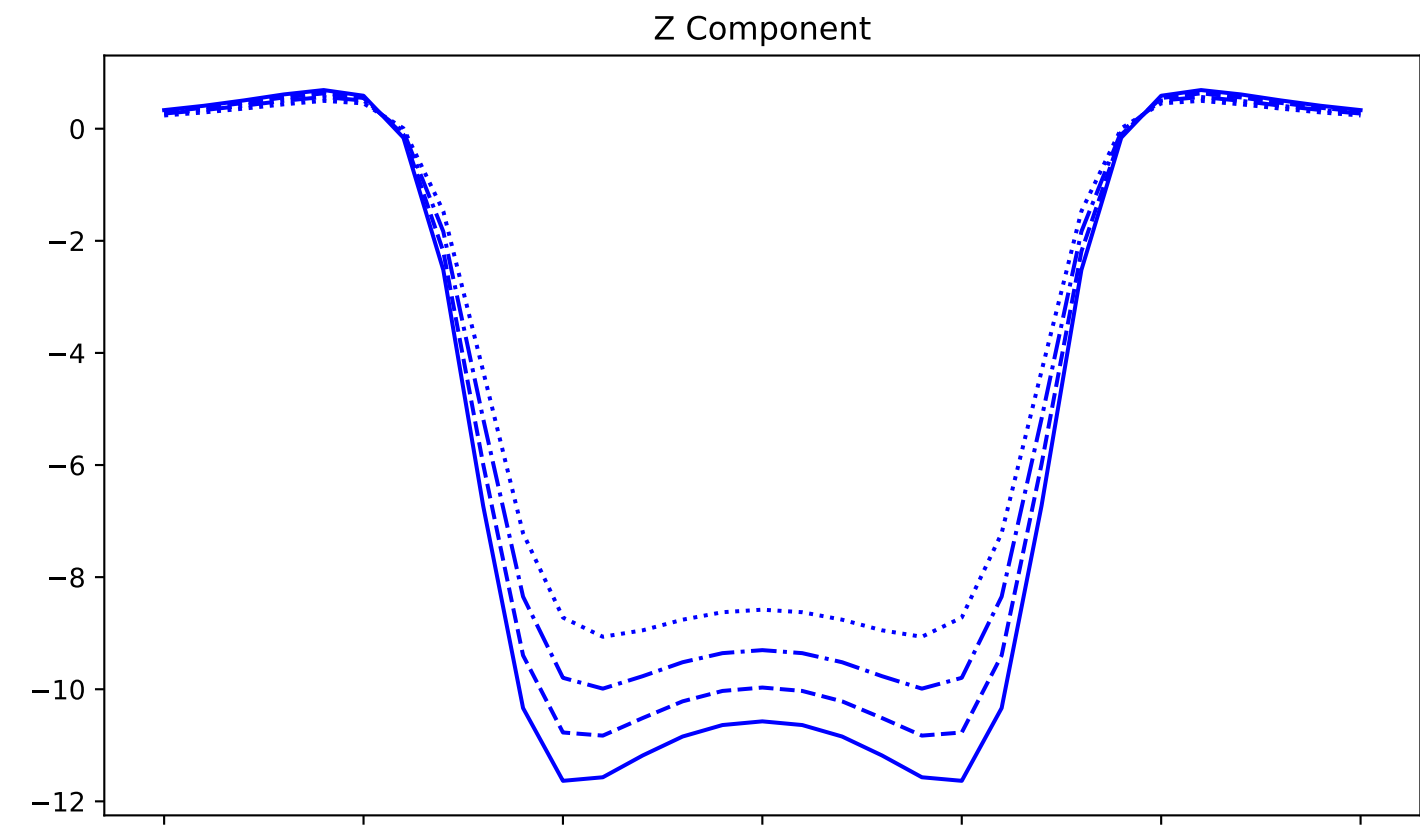
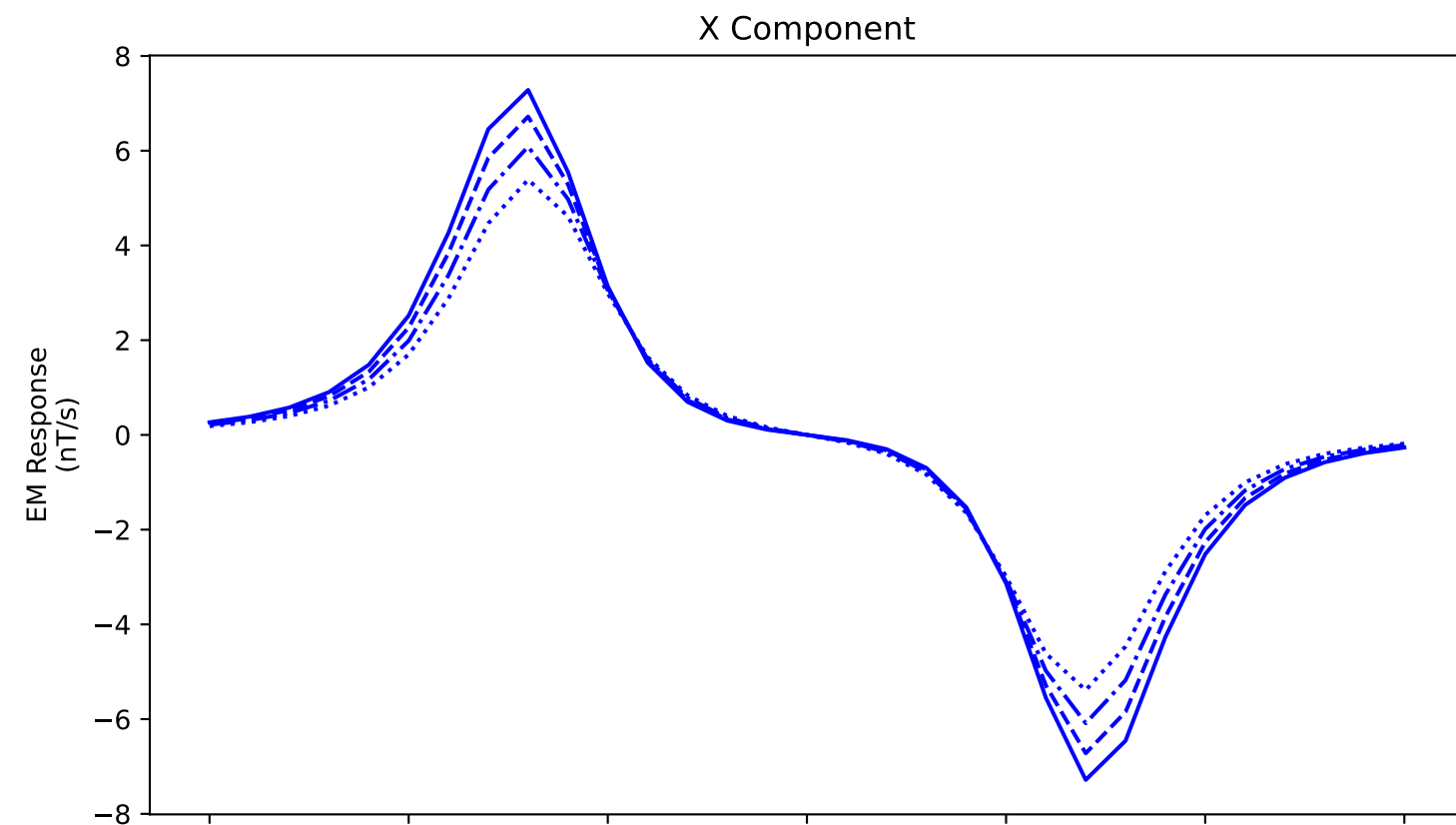
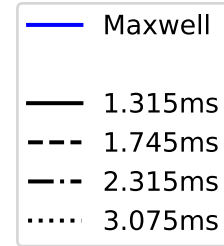
Two-Way Induction
300x100m, 1000S
LOOP=-350
0.235ms to 0.56ms



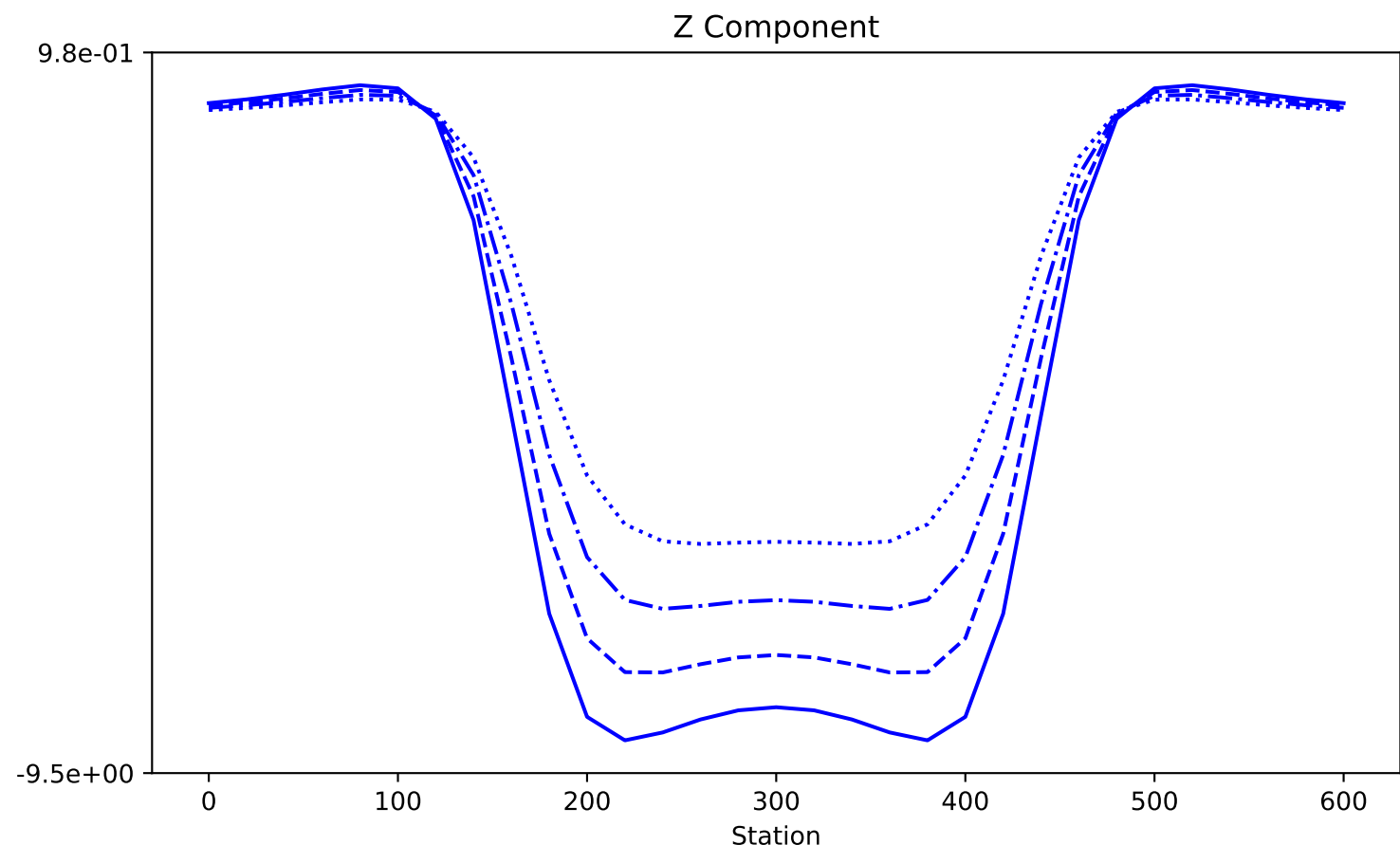
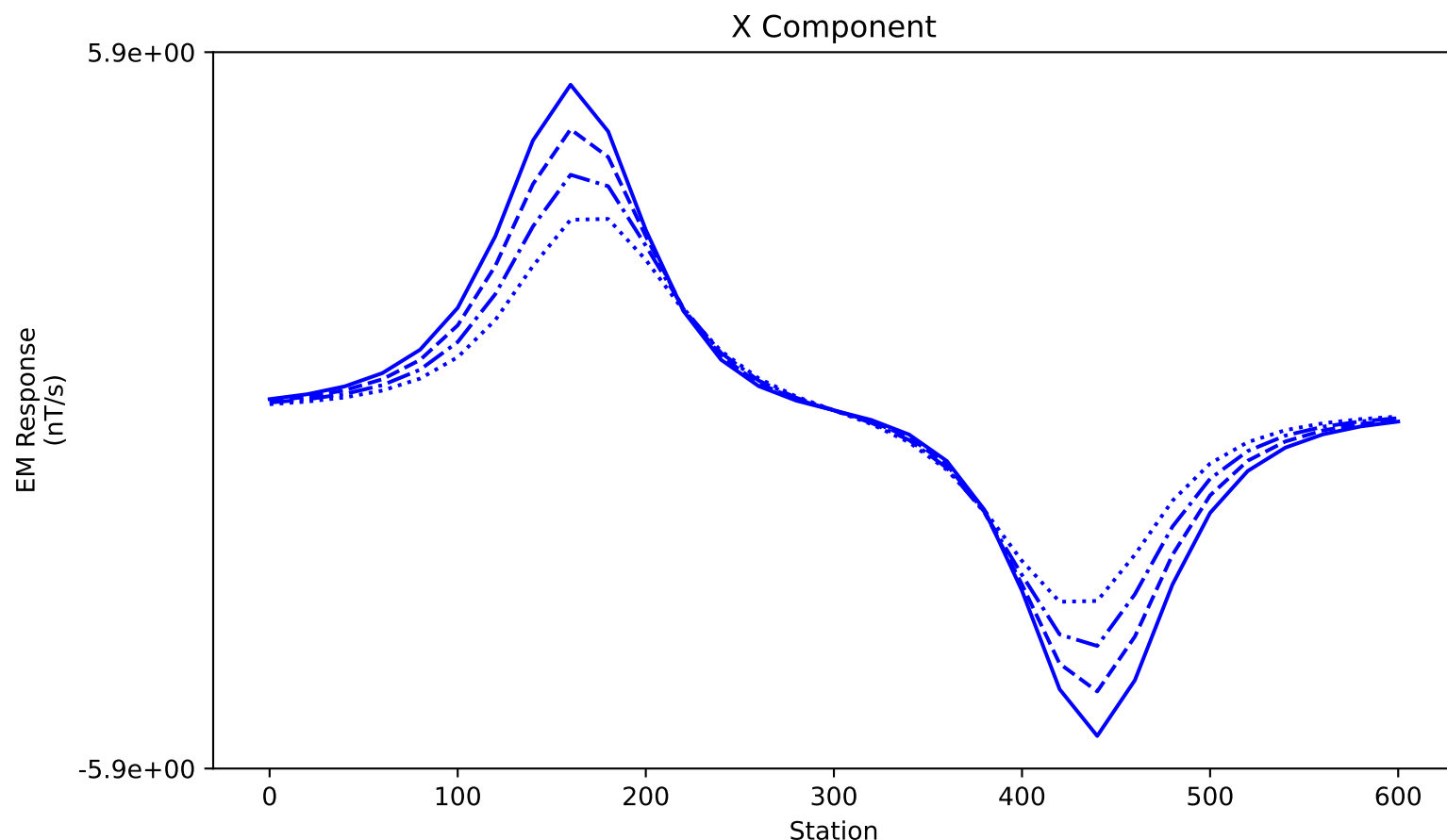
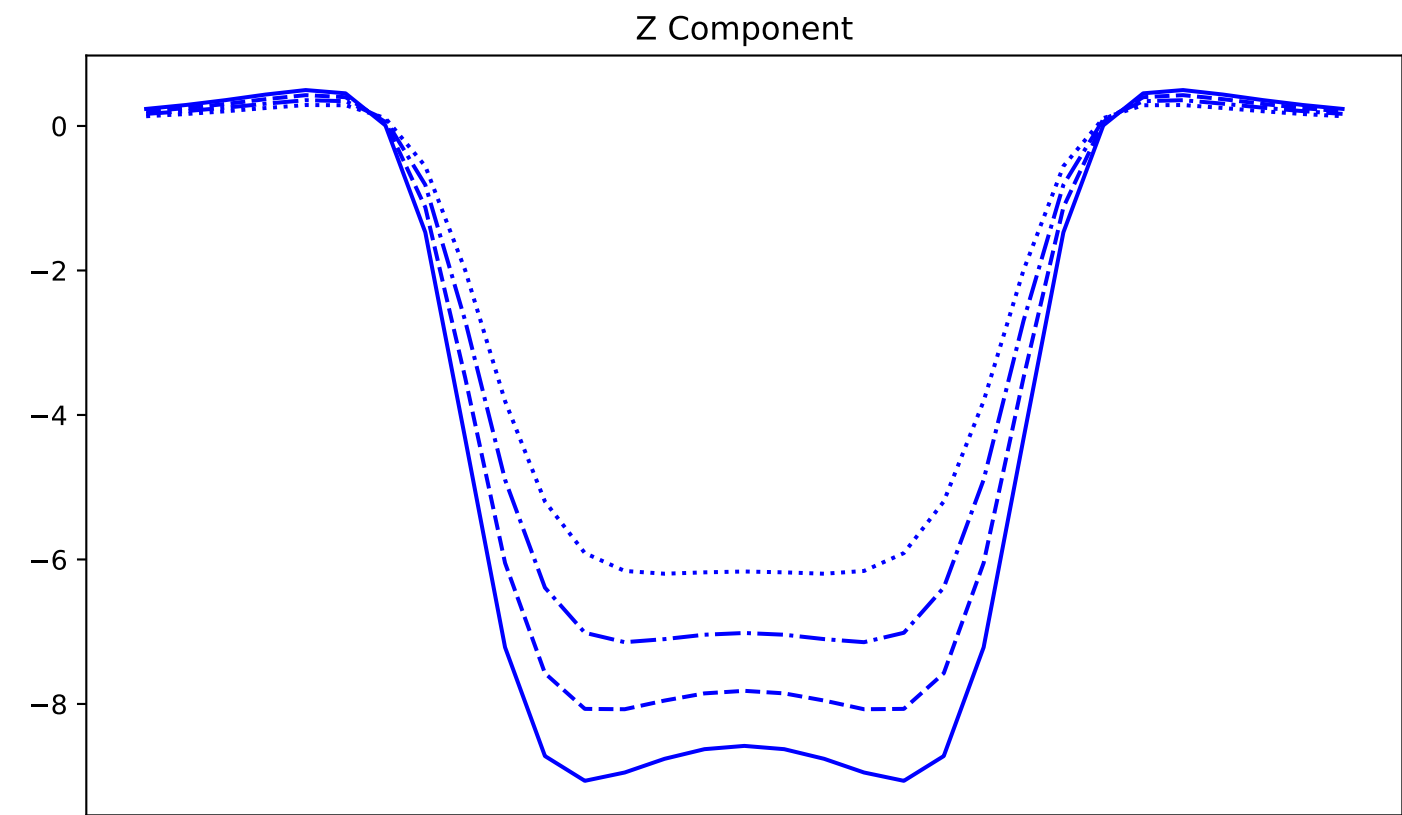
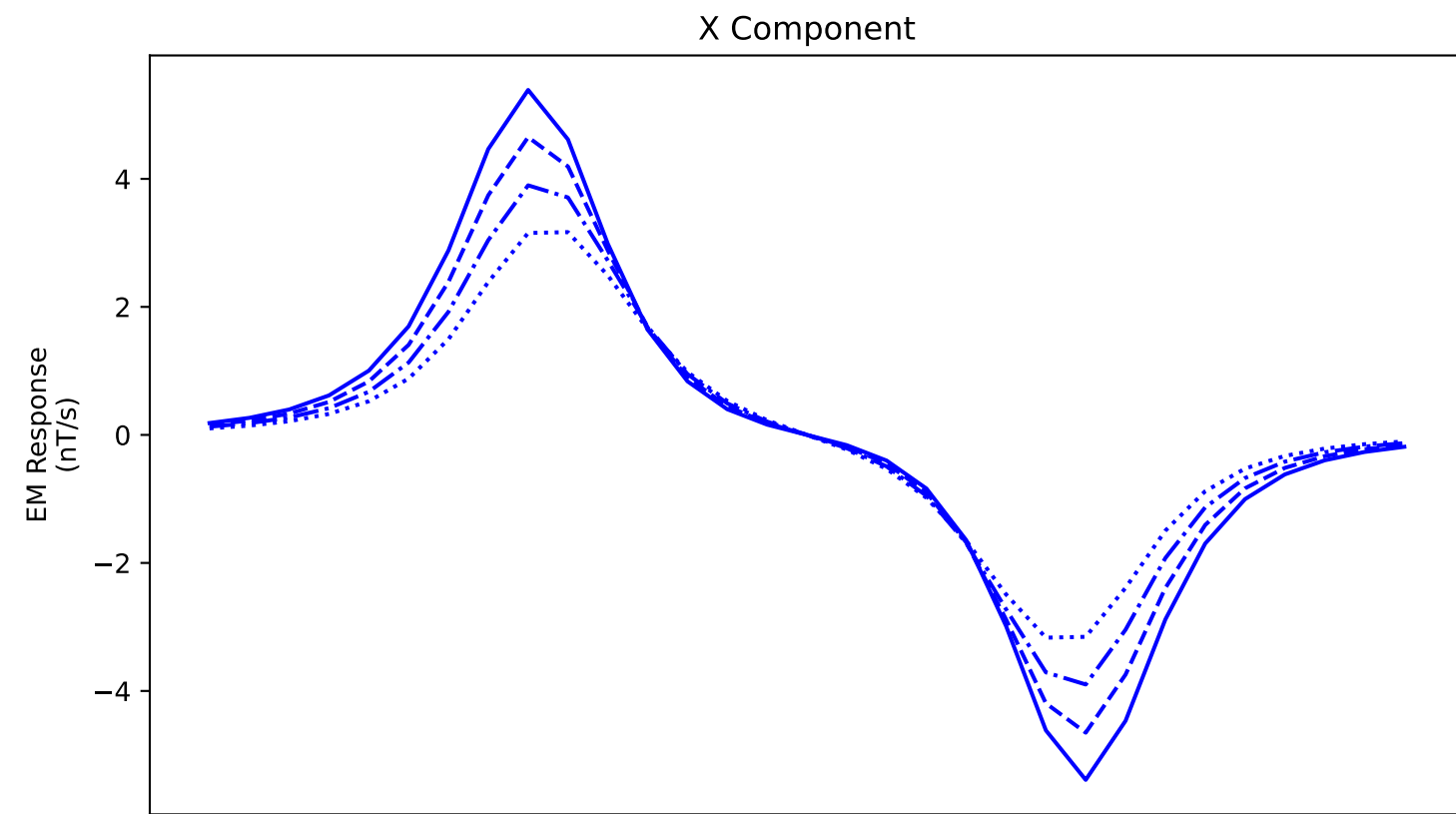
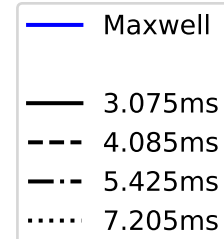
Two-Way Induction
300x100m, 1000S
LOOP=-350
0.56ms to 1.315ms



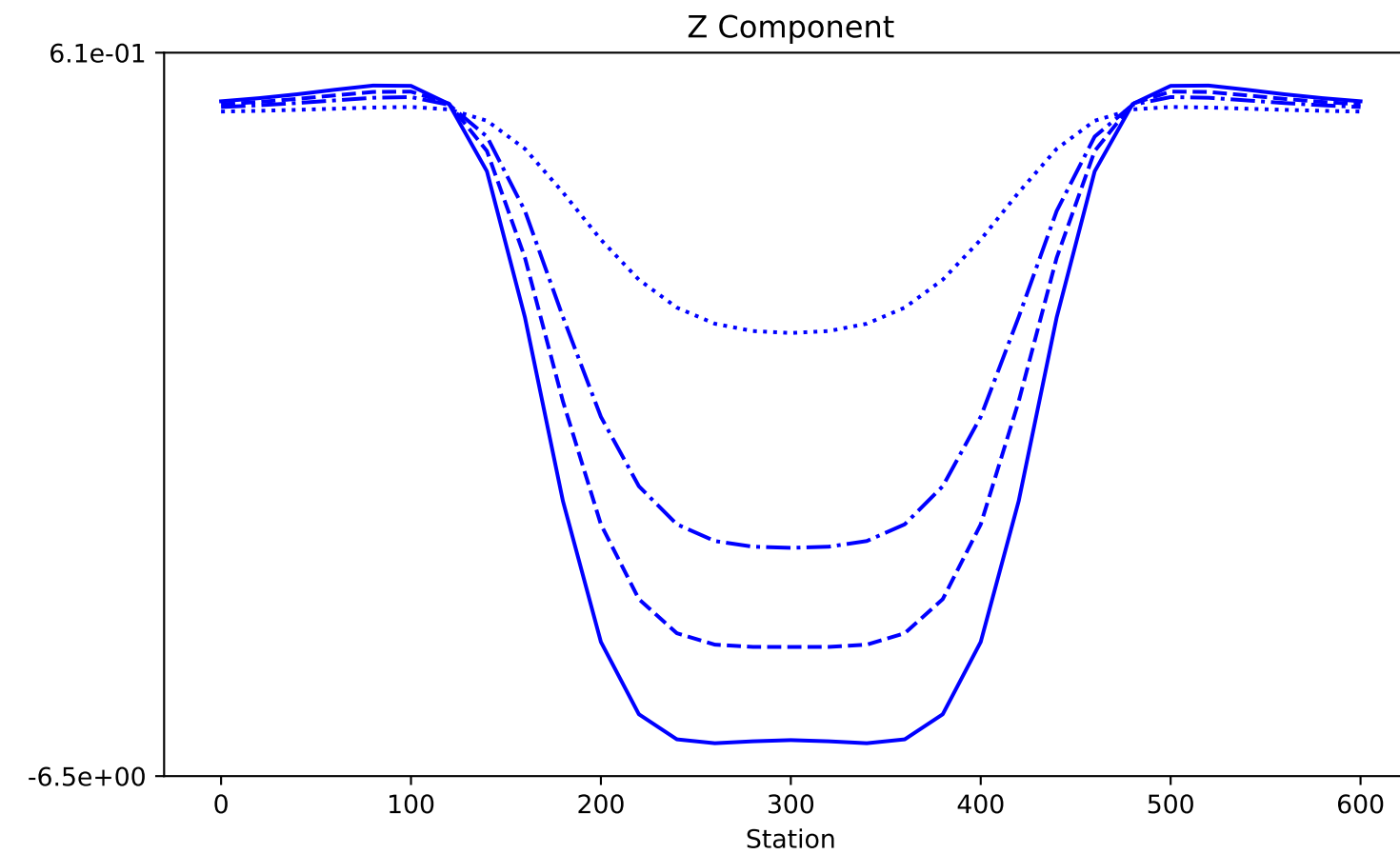
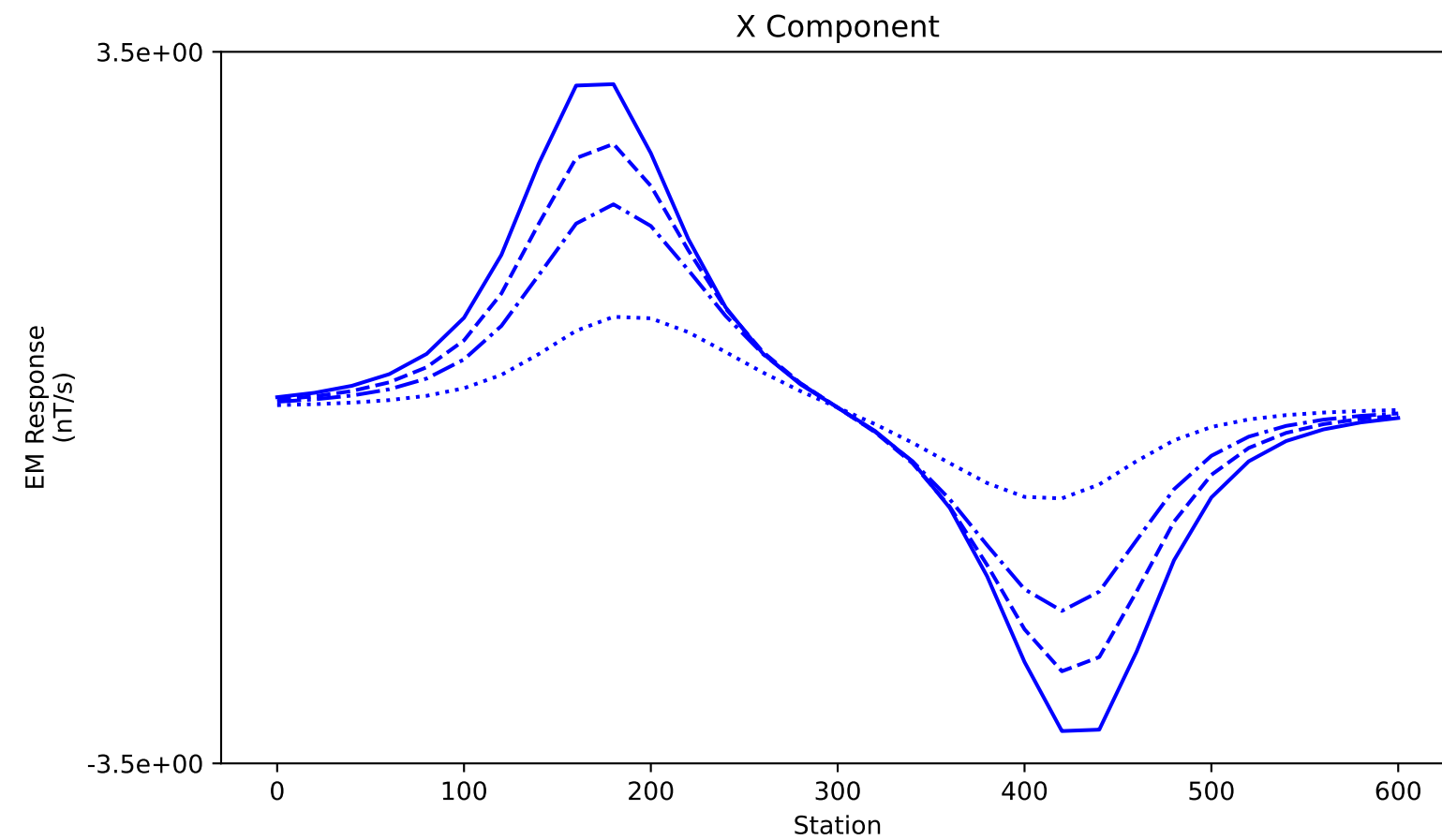
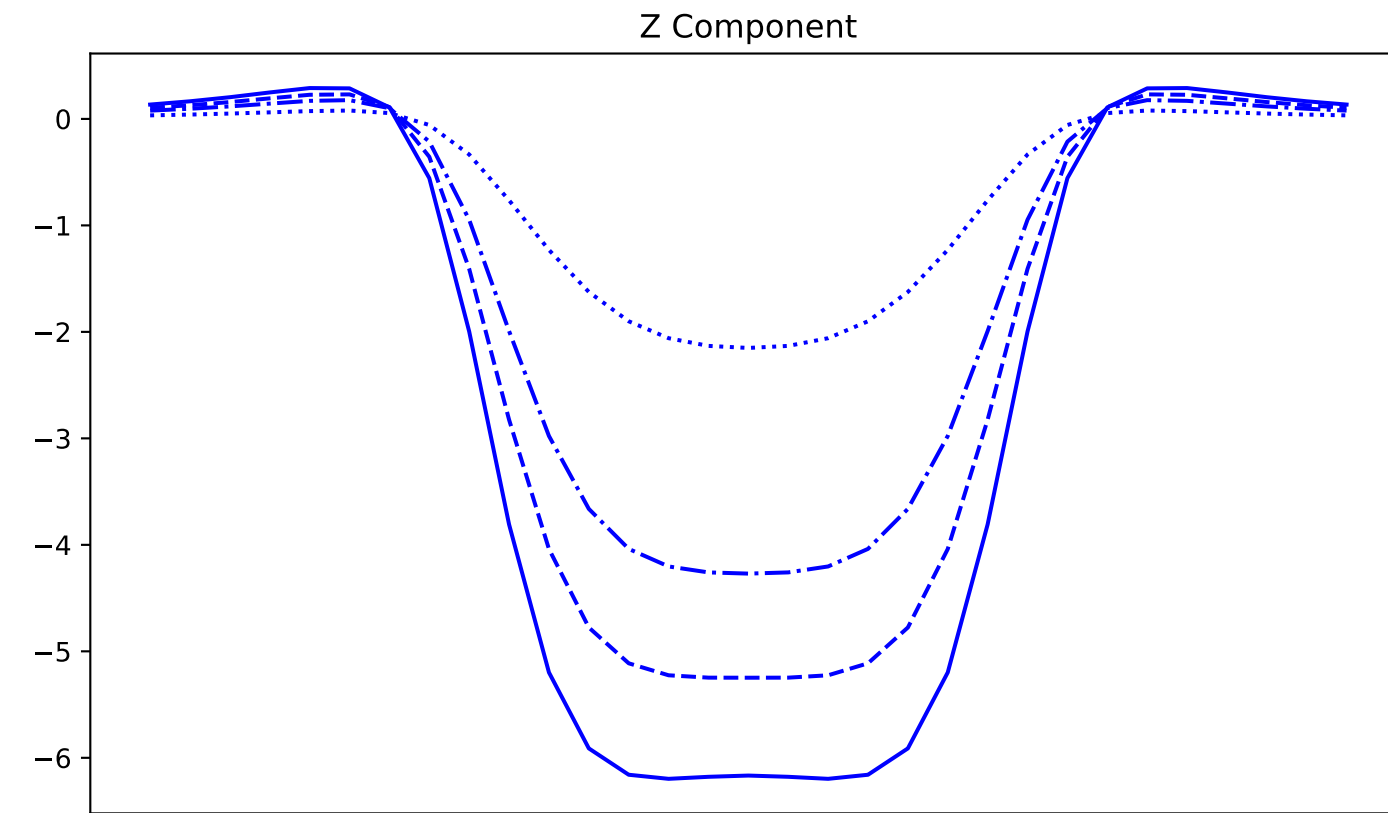
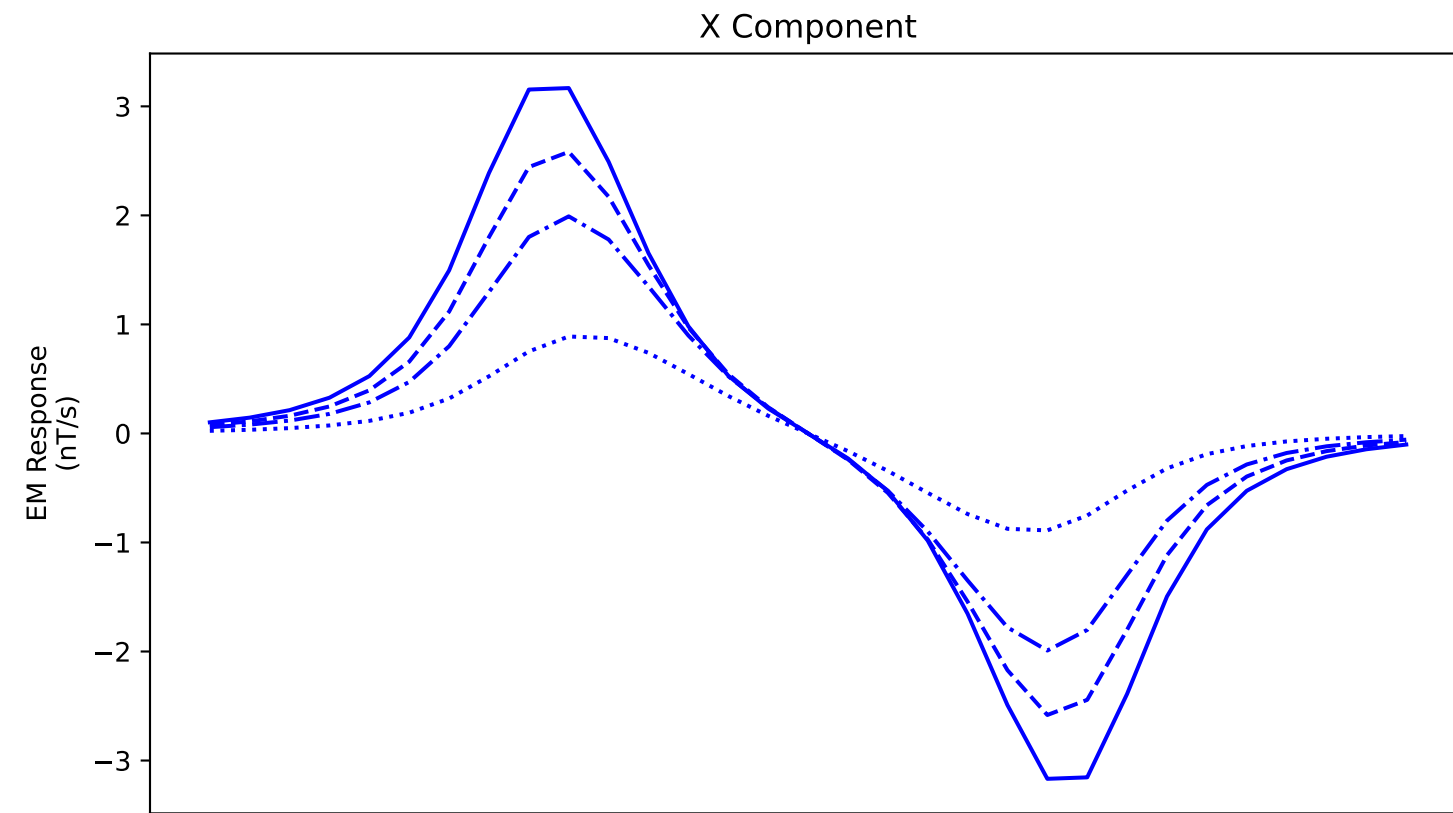
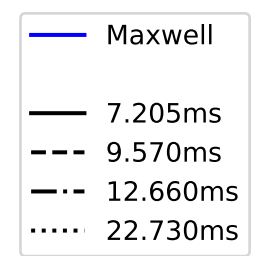
Two-Way Induction
300x100m, 1000S
LOOP=-350
1.315ms to 3.075ms



Two-Way Induction
300x100m, 1000S
LOOP=-350
3.075ms to 7.205ms



Two-Way Induction
300x100m, 1000S
LOOP=-350
7.205ms to 22.73ms



Two-Way Induction
300x100m, 1000S
LOOP=-350
22.73ms to 48.115ms

