

Name:

Student Number:

Section: (RE-25, ET 26)

Equations of motion for constant acceleration:

$$v = v_0 + at; \quad (x - x_0) = v_0 t + \frac{1}{2} at^2; \quad v^2 = v_0^2 + 2a(x - x_0);$$

$$(x - x_0) = \frac{1}{2}(v_0 + v)t; \quad (x - x_0) = vt - \frac{1}{2} at^2$$

Questions

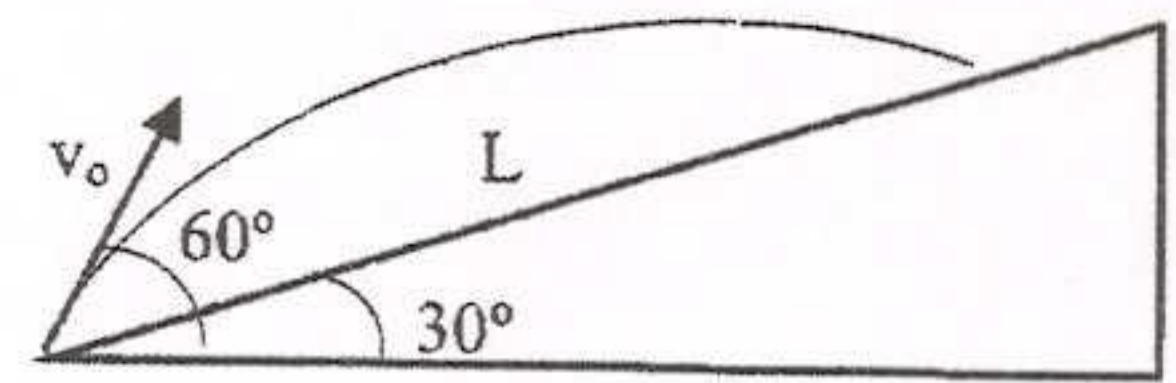
1. Some of the physical laws belonging to alternative universes/computer games are listed below where $\alpha, \beta, \gamma, \delta, \epsilon$ are constants. Analyze each of them and derive the units of the constants in the equations in order to have in principle correct equations. (4 points each)

[F: Force; K: Kinetic Energy; U: Potential Energy; ρ : density; μ_k : Kinetic friction coefficient; P: Power]

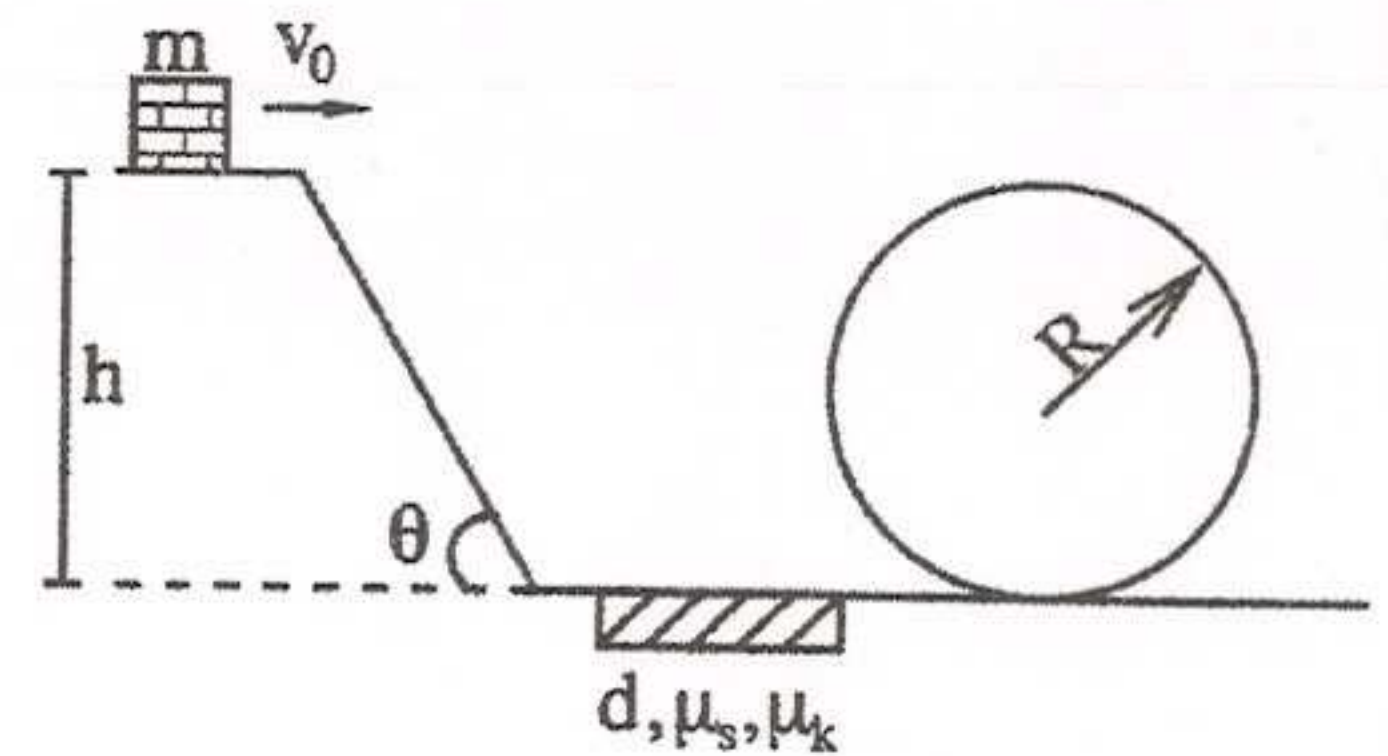
$$K = \alpha mv \quad P = \beta \frac{ma}{t^2} \quad F = \gamma mv^2 \quad v = \sqrt{v_0^2 + \delta \frac{F}{m}} \quad \mu_k = \epsilon \frac{F \rho x}{ma^2}$$

2. At a certain instant, a 2 kg object is acted on by a force $\mathbf{F} = 4\mathbf{i} - 2\mathbf{j} + 5\mathbf{k}$ [N] while having a velocity $\mathbf{v} = -2\mathbf{i} + 3\mathbf{k}$ [m/s]. What is the instantaneous rate at which the force does work on the object? At a later time, the velocity consists of only a y component and the instantaneous power is -8 W. If the force is unchanged, what is the kinetic energy of the object just then? (20 points)

3. A ball is thrown with an initial velocity of magnitude $v_0 = 10$ m/s, which makes an angle 60° with the horizontal, from the lowest point of a 30° incline plane. Find the distance L travelled by the ball on the incline. ($\cos 30^\circ = \sin 60^\circ = \sqrt{3}/2$; $\sin 30^\circ = \cos 60^\circ = 1/2$; $g = 10$ m/s²). (20 points)



4. A block of bricks, mass m is released from a height of h with an initial horizontal speed of v_0 . Shortly after it slides down an inclined plane of angle θ and enters a region of d length where there is a friction characterized by static and kinetic frictional coefficients of μ_s and μ_k , respectively, present between the block and the floor. This region is followed by a circular loop of radius R . (Other than the shaded d region, there is no friction present)



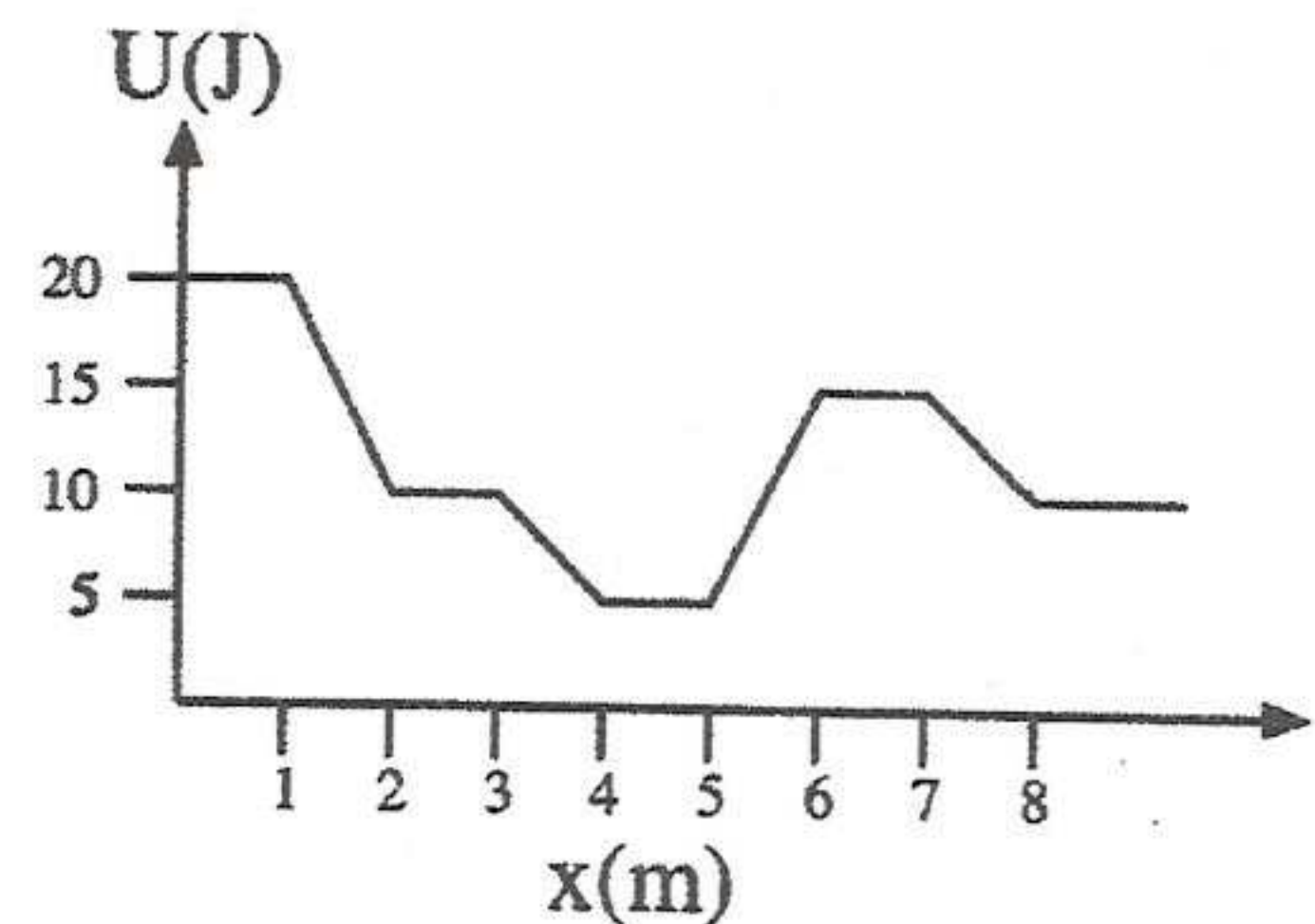
For the particle to be able to complete the loop just without falling down, derive an equation between R and other relevant quantities. Indicate the unrelated quantities among the given ones, if there are any. (20 points)

5. Regarding the given Potential Energy vs. Position graph:

a) Plot the corresponding Force vs. Position graph (7 points)

b) Calculate the work done on the particle by the given interactions to move it from $x = 0$ m to $x = 8$ m (6 points)

c) For a particle with mechanical energy $E_{mec} = 13$ J, released from $x = 4$ m and initially moving in the positive x-direction, identify the turning and equilibrium points, if there are any. (7 points)



$$1) a \neq k = \alpha m v$$

$$\eta \equiv \frac{\text{kg} \cdot \text{m}}{\text{s}^2} = [\alpha] \frac{\text{kg} \cdot \text{m}}{\text{s}}$$

$$[\alpha] = \frac{\text{m}}{\text{s}} \Rightarrow [\alpha] = \frac{[L]}{[T]}$$

$$c) F = \gamma m v^2$$

$$N \equiv \text{kg} \frac{\text{m}}{\text{s}^2} = [\gamma] \text{kg} \frac{\text{m}^2}{\text{s}^2}$$

$$\Rightarrow [\gamma] = \frac{1}{[L]}$$

$$b) P = \beta \frac{m a}{t^2}$$

$$W \equiv \frac{J}{s} = \frac{\text{kg} \frac{\text{m}^2}{\text{s}^2}}{s} = [\beta] \frac{\text{kg} \frac{\text{m}^2}{\text{s}^2}}{\text{s}^2}$$

$$[\beta] = \text{m} \cdot \text{s} \Rightarrow [\beta] = [L][T]$$

$$d) \left[\delta \frac{F}{m} \right] = [v^2]$$

$$[\delta] \frac{\text{kg} \frac{\text{m}}{\text{s}^2}}{\text{kg}} = \frac{\text{m}^2}{\text{s}^2} \Rightarrow [\delta] = \text{m} \Rightarrow [\delta] = [L]$$

$$e) M_k = \epsilon \frac{F \Delta x}{m a^2}$$

$$1 = [\epsilon] \frac{\text{kg} \frac{\text{m}}{\text{s}^2} \text{kg} \frac{\text{m}}{\text{s}^2} \cdot \text{m}}{\text{kg} \frac{\text{m}^2}{\text{s}^2}} = [\epsilon] \frac{\text{kg} \frac{\text{m}^3}{\text{s}^2}}{\text{m}^3}$$

$$\Rightarrow [\epsilon] = \frac{\text{m}^3}{\text{kg} \text{s}^2} \Rightarrow [\epsilon] = \frac{[L]^3}{[M][T]^2}$$

$$2) P = \frac{W}{\Delta t} = \frac{\Delta K}{\Delta t}$$

$$\Delta K = -\Delta U$$

$$F = -\frac{\Delta U}{\Delta x} \Rightarrow -\Delta U = F \Delta x$$

$$\Rightarrow P = \frac{F \Delta x}{\Delta t}, \Delta t \rightarrow 0: P = \vec{F} \frac{d\vec{x}}{dt} = \vec{F} \cdot \vec{v}$$

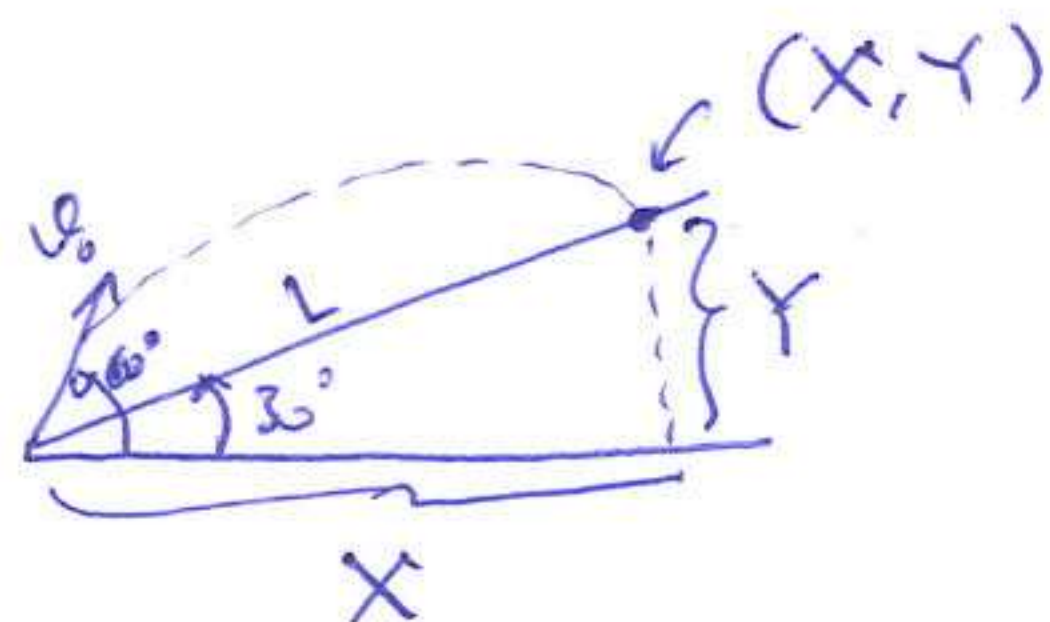
$$a) \vec{F} = (4\hat{i} - 2\hat{j} + 5\hat{k}) \text{ N} \quad \vec{v} = (-2\hat{i} + 3\hat{k}) \text{ m/s} \quad \rightarrow P = \vec{F} \cdot \vec{v} = (-8 + 15) \text{ W} = \underline{7 \text{ W}}$$

$$b) \vec{v} = v_y \hat{j} \Rightarrow -8 \text{ W} = (4\hat{i} - 2\hat{j} + 5\hat{k}) \text{ N} (v_y \hat{j})$$

$$-8 \text{ W} = -2 v_y \text{ N} \Rightarrow v_y = \frac{-8 \text{ W}}{-2 \text{ N}} = 4 \text{ m/s}$$

$$\Rightarrow K = \frac{1}{2} m v^2 = \frac{1}{2} (2 \text{ kg}) (4 \text{ m/s})^2 = \underline{16 \text{ J}}$$

3)



$$X = L \cos 30^\circ$$

$$Y = L \sin 30^\circ$$

$$v_x = v_0 \cos 60^\circ$$

$$v_y = v_0 \sin 60^\circ$$

$$X = v_x t = v_0 \cos 60^\circ t \rightarrow L \cos 30^\circ = v_0 \cos 60^\circ t$$

$$\Rightarrow t = \frac{L \cos 30^\circ}{v_0 \cos 60^\circ} \quad (1)$$

$$Y = v_y t - \frac{1}{2} g t^2 = L \sin 30^\circ$$

$$(1) \Rightarrow v_0 \sin 60^\circ \left(\frac{L \cos 30^\circ}{v_0 \cos 60^\circ} \right) - \frac{1}{2} g \left(\frac{L^2 \cos^2 30^\circ}{v_0^2 \cos^2 60^\circ} \right) = L \sin 30^\circ$$

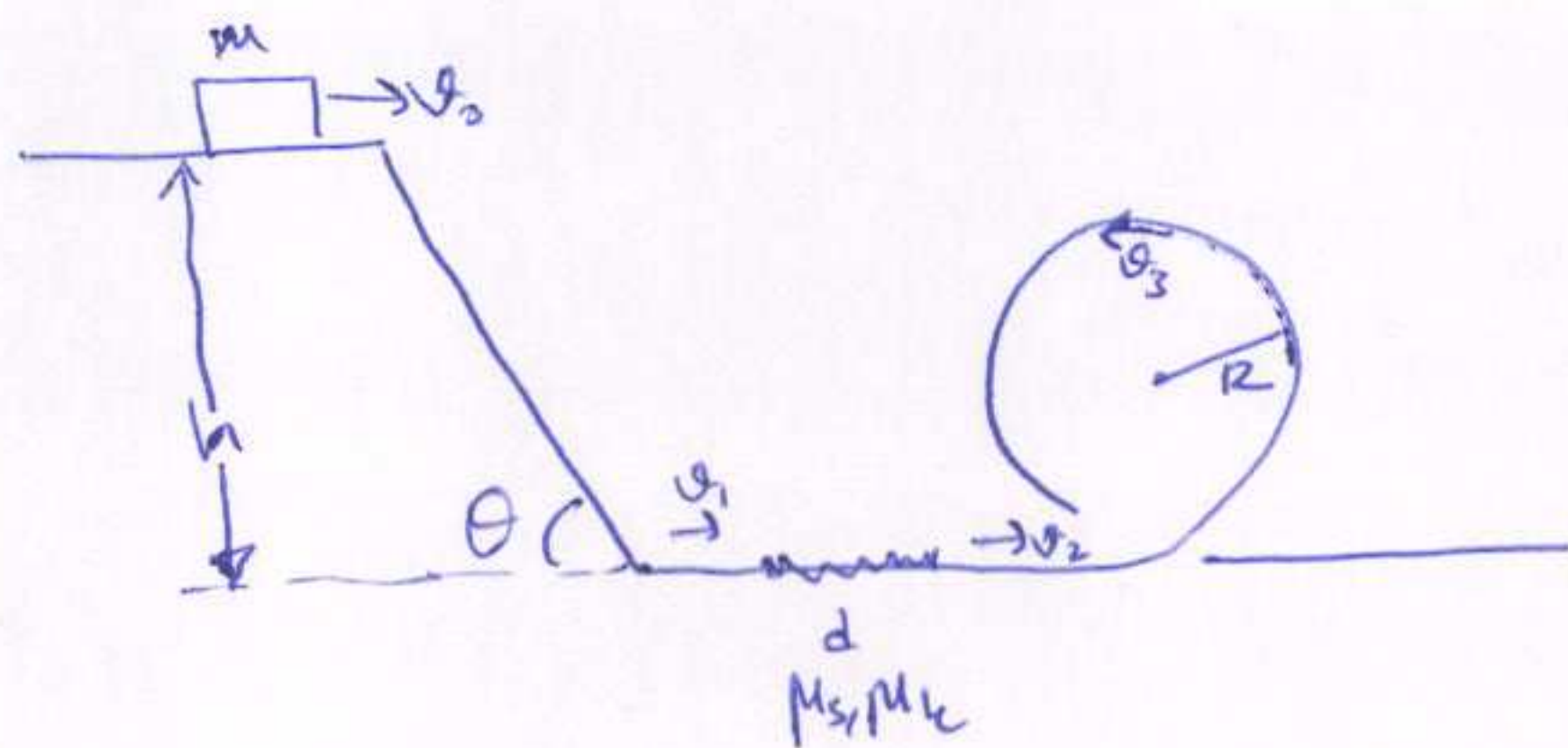
$$\frac{\sin 60^\circ \cos 30^\circ}{\cos 60^\circ} - \frac{1}{2} g \frac{L \cos^2 30^\circ}{v_0^2 \cos^2 60^\circ} = \sin 30^\circ$$

$$\frac{\sqrt{3}/2 \cdot \sqrt{3}/2}{1/2} - \frac{1}{2} (10 \text{ m/s}^2) \frac{L (\sqrt{3}/2)^2}{(10 \text{ m/s})^2 (1/2)^2} = \frac{1}{2} \rightarrow \frac{3}{2} - \frac{L^{3/4}}{(10 \text{ m})^{1/2}} = \frac{1}{2}$$

$$\frac{3}{20 \text{ m}} L = \frac{3}{2} - \frac{1}{2} = 1$$

$$\Rightarrow L = \frac{20 \text{ m}}{3} = 6.6 \text{ m} \quad (1)$$

A)



$$mgh + \frac{1}{2}mv_0^2 = \frac{1}{2}mv_1^2 \quad (v_1 > v_0)$$

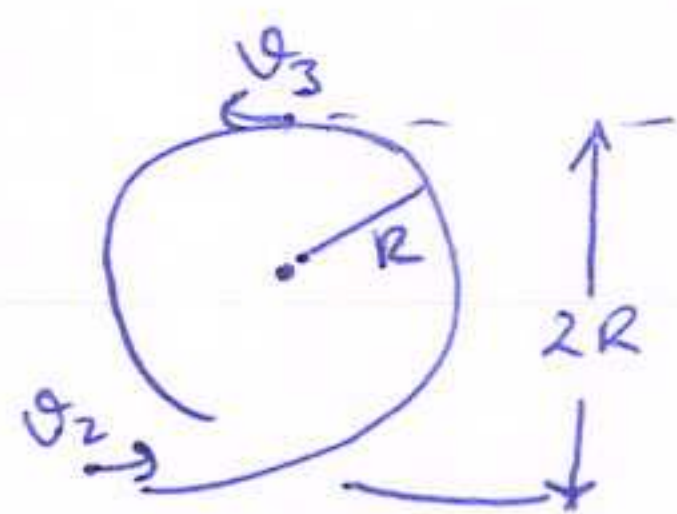
$$2gh + v_0^2 = v_1^2 \quad (1)$$

$\Delta K = W_f$, $W_f < 0$ (Energy is transferred from the block by the friction force)
($v_2 < v_1$)

$$\frac{1}{2}mv_2^2 - \frac{1}{2}mv_1^2 = -f_k d = -\mu_k mg d$$

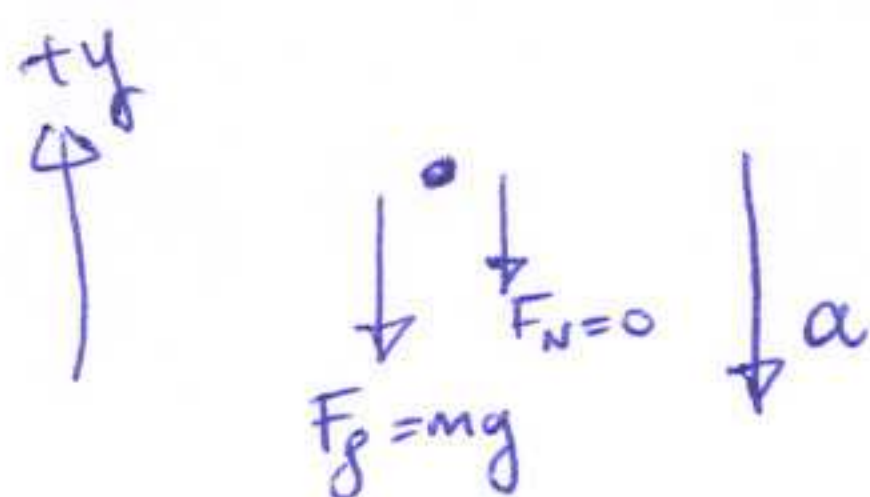
$$v_2^2 = -2\mu_k g d + v_1^2$$

$$(1) \Rightarrow v_2^2 = -2\mu_k g d + 2gh + v_0^2 \quad (2)$$



$$\frac{1}{2}mv_2^2 = mg(2R) + \frac{1}{2}mv_3^2$$

$$v_3^2 = v_2^2 - 4gR \quad (3)$$



$$0 - mg = m(-a) = m\left(-\frac{v_3^2}{R}\right)$$

$$g = \frac{v_3^2}{R} \Rightarrow v_3^2 = gR$$

$$(3) \Rightarrow v_2^2 - 4gR = gR$$

$$v_2^2 = 5gR \quad (4)$$

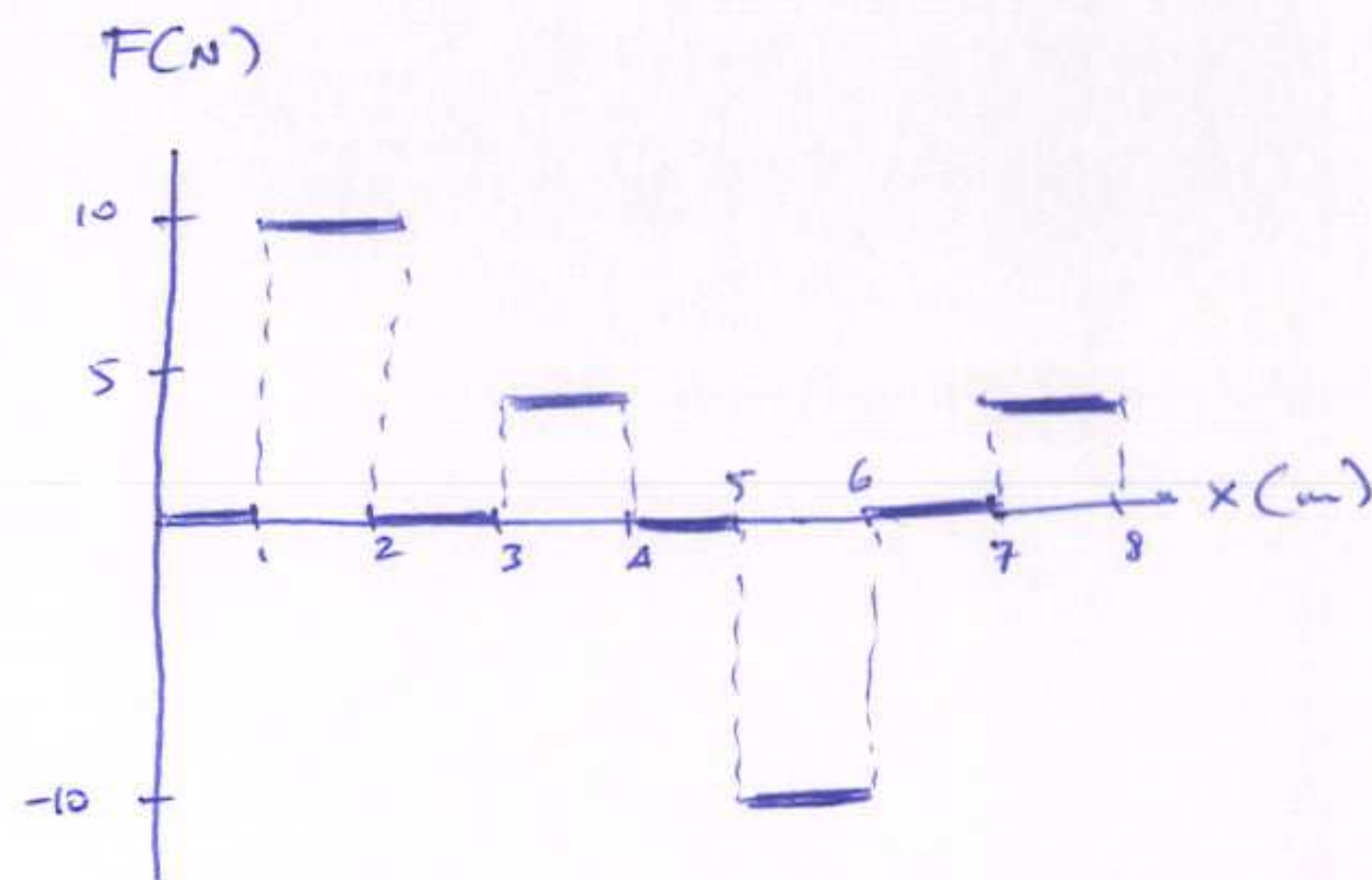
$$(2) + (4) : 5gR = v_0^2 + 2gh - 2\mu_k g d$$

$$R = \frac{v_0^2}{5g} + \frac{2}{5}(h - \mu_k d)$$

$\rightarrow R$ is independent of m , θ and μ_s .

5) a) $F = -\frac{dU}{dx}$, U linear $\Rightarrow F = -\frac{\Delta U}{\Delta x}$

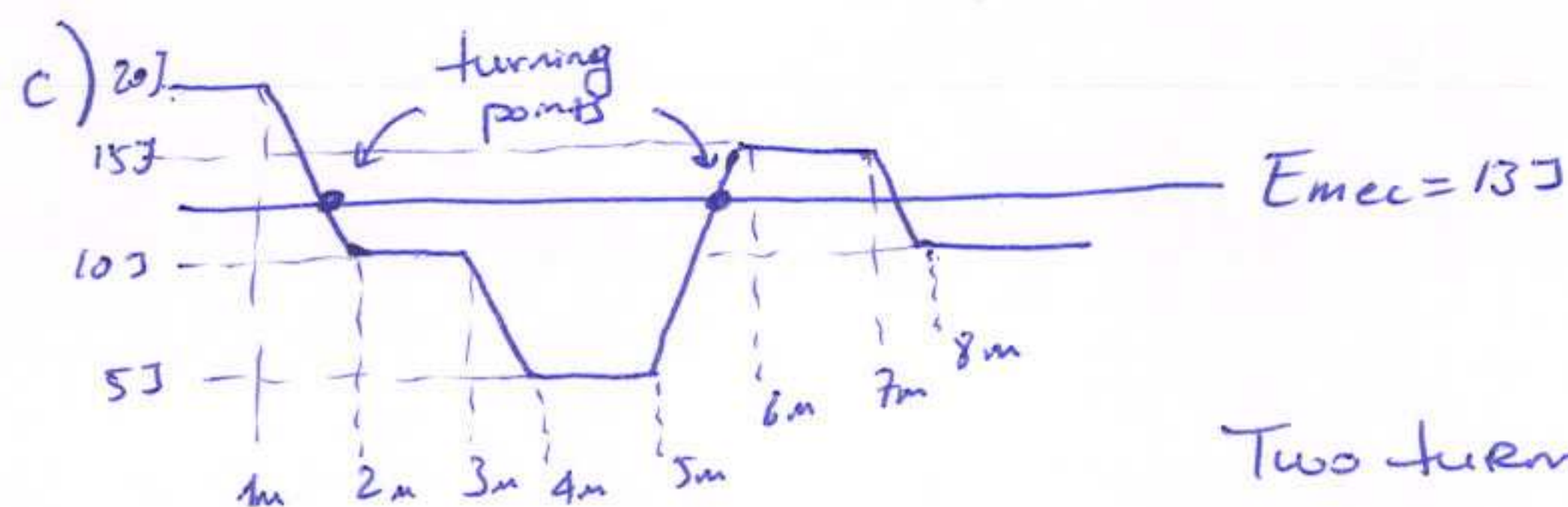
- i) $x: 0 \text{ to } 1\text{m} : U = \text{const.} \rightarrow F_{01} = 0$
- ii) $x: 1\text{m to } 2\text{m} : F_{12} = -\frac{(20-10)\text{J}}{(1-2)\text{m}} = 10\text{N}$
- iii) $x: 2\text{m to } 3\text{m} : U = \text{const.} \rightarrow F_{23} = 0$
- iv) $x: 3\text{m to } 4\text{m} : F_{34} = -\frac{(10-5)\text{J}}{(3-4)\text{m}} = 5\text{N}$
- v) $x: 4\text{m to } 5\text{m} : U = \text{const.} \rightarrow F_{45} = 0$
- vi) $x: 5\text{m to } 6\text{m} : F_{56} = -\frac{(5-15)\text{J}}{(5-6)\text{m}} = -10\text{N}$
- vii) $x: 6\text{m to } 7\text{m} : U = \text{const.} \rightarrow F_{67} = 0$
- viii) $x: 7\text{m to } 8\text{m} : F_{78} = -\frac{(15-10)\text{J}}{(7-8)\text{m}} = 5\text{N}$



b) $W = \sum F(x) \Delta x = (10 \cdot 1 + 5 \cdot 1 - 10 \cdot 1 + 5 \cdot 1)\text{J} = 10\text{J}$

-or-

$$W = -\Delta U = -(U(x=8\text{m}) - U(x=0\text{m})) = -(10\text{J} - 20\text{J}) = 10\text{J}$$



Two turning points:

- i) x_{t1-2} : between $x=1\text{m}$ and $x=2\text{m}$
- ii) x_{t5-6} : between $x=5$ and $x=6\text{m}$

No equilibrium point in between

$$K(x) + U(x) = E_{\text{mec}}$$

at turning point, $K=0$ ($v=0$), $F \neq 0$

$$x_{t1-2} : \frac{y_{t1-2} - 20\text{J}}{x_{t1-2} - 1\text{m}} = \frac{(20-10)\text{J}}{(1-2)\text{m}} \rightarrow \frac{-7\text{J}}{x_{t1-2} - 1\text{m}} = \frac{10\text{J}}{-1\text{m}}$$

$$\Rightarrow x_{t1-2} - 1\text{m} = \frac{7\text{m}}{10} \rightarrow x_{t1-2} = \frac{17\text{m}}{10} = 1.7\text{m}$$

$$x_{t5-6} : \frac{y_{t5-6} - 15\text{J}}{x_{t5-6} - 6\text{m}} = \frac{(5-15)\text{J}}{(5-6)\text{m}} \rightarrow \frac{-2\text{J}}{x_{t5-6} - 6\text{m}} = \frac{-10\text{J}}{-1\text{m}}$$

$$\Rightarrow x_{t5-6} - 6\text{m} = -\frac{2\text{m}}{10}$$

$$x_{t5-6} = \frac{58\text{m}}{10} = 5.8\text{m}$$