## 1 Attribute growth

Consider an initial graph  $G_0 = (V_0, E_0)$  have vertex set  $V_0$  and edge set  $E_0$ . We will have a set of variable length vectors A where  $A_v$  represents the vector of attributes of vertex v. We will additionally define a threshold S representing the proportion of attributes that two vertices must share in order for an edge to exist. To determine whether an edge exists between u and v where possibly  $|A_u| \neq |A_v|$  we will compare only the first  $\min(|A_u|, |A_v|)$  attributes. Next we define C, a vector of the count of attributes at added as well as B a vector of possible attributes. Then we define  $I_i$ , the number of new vertices introduced at step i. Finally we define L, the length of the random walk new vertices take when added to the graph.

In order to track how long vertices have existed in the network we will denote the time they have existed as  $T_v$  for some vector v.

To create the initial  $E_0$  we assign first each  $v \in V_0$  an attribute in  $\{1, ..., B_0\}$ . Next we add edges for pairs that meet threshold S. In this initial case for any non-zero S we only have edges between vertices u, v where  $A_u[0] = A_v[0]$ 

In all subsequent iterations k we first add  $C_{T_v}$  attributes to all  $v \in V_{k-1}$ . We then add  $I_k$  vertices and assign them each one attribute with value in  $\{1, ..., B_0\}$ . Next for each new vertex u we randomly select a vertex  $v \in V_{k-1}$  s.t.  $A_u[0] = A_v[0]$  and take a random walk of length L. At each step in the walk we determine if the edge existance threshold is met and if so add an edge. If there is no suitable initial vertex we add this new vertex as an isolated component in the graph. After all new vertices have been added we check all existing edges and remove them if they no longer meet the threshold. Denote this new total set of vertices as  $V_k$  and new total set of edges as  $E_k$ .

Note that it is possible for an edge that was removed for not meeting the threshold can meet it in a future iteration.

A more formal definition follows below:

## Algorithm 1: Network formation by attribute growth

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let E_0 = \emptyset and an initial vertex set V_0;
let G_0 = (V_0, E_0);
let S denote the threshold for edge preservation;
let B define the sequence of possible attributes;
let I be the sequence defining the number of new vertices at each iteration;
let C be the sequence defining the number of new attributes gained by each vertex in each iteration of it's
 existance:
let T be the vector of how many iterations a vertex has existed;
for v \in V_0 do
 IID assign C_0 elements to A_v from \{1,...,B_0\};
end
for u, v \in V_0 do
    if A_u[0] = A_v[0] then
         E_0 = E_0 \cup \{uv\};
     \mathbf{end}
end
let i = 1 denoting the iteration number;
while Network grows do
     create a set of new vertices V_{i'} of size I_i;
     let E_i = \emptyset for v' \in V_{i'} do
       IID assign A_{v'}[0] \in \{1, ..., B_0\};
     \mathbf{end}
     for v \in V_i do
      | IID assign C_{T_v} elements to A_v from \{1,...,B_{T_v}\}
     for v' \in V_{i'} do
          Select L vertices via a random walk seeded at a random vertex u' s.t. \frac{|\{A_{u'}[j]|A_{u'}[j]=A_{v'}[j]forj\in\min(|A_{u'}|,|A_{v'}|)\}}{\min(|A_{u'}|,|A_{u'}|,|A_{v'}|)\}} \geq S;
          \frac{\|\{A_{u'}[j]\}\|^2 \|u'\|_{J^{1}}\|_{J^{1}}\|_{J^{1}}\|_{J^{1}}}{\min(|A_{v'}|,|A_{v'}|)} \leq \varnothing,
let E_{i} = E_{i} \cup \{v'w'|\frac{v'w'|A_{v'}[j]=A_{w'}[j]forj\in\min(|A_{v'}|,|A_{w'}|)}{\min(|A_{v'}|,|A_{w'}|)} \geq S\};
     \mathbf{end}
     V_i = V_i \cup V_{i'};
     for u, v \in V_i do
          \text{if } \frac{|\{A_u[j]|A_u[j]=A_v[j]forj\in\min(|A_u|,|A_v|)\}}{\min(|A_u|,|A_v|)} \geq S \text{ then } 
 | E_i = E_i \cup \{uv\}; 
          end
    \mathbf{end}
end
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