

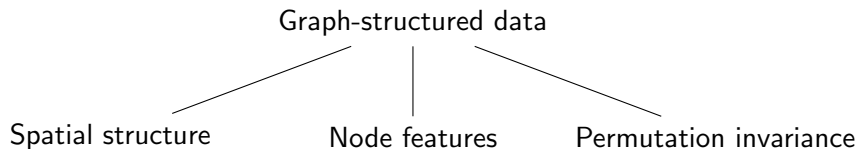
# Message Passing Graph Neural Networks

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# Motivation



## Intuition

1	1	0	0	0	0	0	0
1	1	1	0	0	0	0	0
0	1	1	1	0	0	0	1
0	0	1	1	1	1	1	0
0	0	0	1	1	0	0	0
0	0	0	1	0	1	0	0
0	0	0	1	0	0	1	0
0	0	1	0	0	0	0	1

**I + A**

X

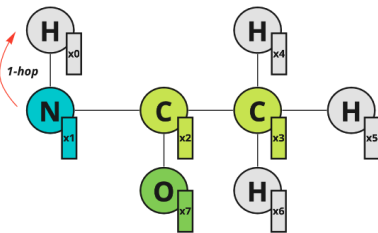
x0
x1
x2
x3
x4
x5
x6
x7

**X**

==

$x_0 + x_1$
$x_0 + x_1 + x_2$
$x_1 + x_2 + x_3 + x_7$
$x_2 + x_3 + x_4 + x_5 + x_6$
$x_3 + x_4$
$x_3 + x_5$
$x_3 + x_6$
$x_2 + x_7$

**X'**



$$x'_i = \text{update}(x_i, \text{aggregate}([x_j, j \in N(i)]))$$

<https://towardsdatascience.com>

# Problem statement

Given a graph  $G = (V, E)$  with node features  $x_v, v \in V$  and edge features  $e_{vw}, (v, w) \in E$ , there are two types of tasks

- Predict label or value for graph classification or regression
- Predict label or value for each node or edge in structured prediction

## Message passing neural networks (MPNN)

Let  $h_v^t$  represent the node embedding for some vertex  $v$  at iteration  $t$ .

### 1. Initialization

$$h^{(0)}_v = x_v \quad \forall v \in V$$

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### 2. Message passing phase For $1 \leq t < T$

$$m_v^{t+1} = \sum_{w \in N(v)} M_t(h_v^t, h_w^t, e_{vw})$$

$$h_v^{t+1} = U_t(h_v^t, m_v^{t+1})$$

where  $N(v)$  denotes the neighbors of  $v$  in  $G$ .

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### 3. Readout phase

$$\hat{y} = R(\{h_v^T | v \in G\})$$

# Message passing function

- **Concatenation**

$$M_t(h_v^t, h_w^t, e_{vw}) = (h_w^t, e_{vw})$$

- **Matrix Multiplication**

$$M_t(h_v^t, h_w^t, e_{vw}) = A_{e_{vw}} h_w^t$$

(for discrete edge types)

- **Edge Network**

$$M_t(h_v^t, h_w^t, e_{vw}) = A(e_{vw}) h_w^t,$$

where  $A(e_{vw})$  is a neural network which maps the edge vector to a  $d \times d$  matrix

- **Pair Message**

$$M_t(h_v^t, h_w^t, e_{vw}) = f(h_v^t, h_w^t, e_{vw}),$$

where  $f$  is a neural network



# Update function

- **Sum**

$$U_t(h_v^t, m_v^{t+1}) = h_v^t + m_v^{t+1}$$

- **MLP**

$$U_t(h_v^t, m_v^{t+1}) = \sigma(H_t^{deg(v)} m_v^{t+1})$$

- **RNN**

$$U_t(h_v^t, m_v^{t+1}) = GRU(h_v^t, m_v^{t+1})$$

the same update function at each time step  $t$

- **Neural Network**

$$R = f\left(\sum_{v \in G} h_v^T\right)$$

$$R = \sum_{v \in G} f(h_v^T)$$

- **Neural Network with skip connections**

$$R = f\left(\sum_{v,t} \text{softmax}(W_t h_v^t)\right)$$

- **Two Neural Networks**

$$R = \sum_{v \in G} \sigma\left(f_1(h_v^T, h_v^0)\right) \odot \left(f_2(h_v^T)\right),$$

where  $\odot$  denotes elementwise multiplication

# Virtual graph elements

Allow information to travel long distances during the propagation phase

- **Virtual edge** for pairs of nodes that are not connected
- **Master node** which is connected to every input node in the graph with a special edge type. Master is allowed to have a separate node dimension

## Molecular property prediction

### Experiments

- Any  $T \geq 3$  works
- Complete edge feature vector (bond type, spatial distance) and explicit hydrogen work better
- Common weights and a large hidden dimension are beneficial
- The pair message function performs worse than the edge network function

- [1] Justin Gilmer et al. *Neural Message Passing for Quantum Chemistry*. 2017. DOI: 10.48550/ARXIV.1704.01212. URL: <https://arxiv.org/abs/1704.01212>.

# Questions

1. What function do virtual elements perform?
2. Describe the three stages of MPNN