

Chapter3: HSV color space conversion (RGB-HSV)

1.1 Introduction to color space

RGB is also known as the three primary color space. Any color can be a mixture of these three colors. However, the effective processing of the image in the color space is generally performed in the HSV space. HSV (Humidity, Saturation, Brightness Value) is a color space created according to the intuitive characteristics of the color, also called the hexagonal cone model.

Detail: https://blog.csdn.net/taily_duan/article/details/51506776

HSV space is wider and more convenient than RGB space recognition.

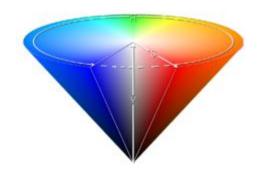


Figure 1-1 HSV color space model

1.2 Three color spaces conversion (gray BGR HSV)

The common two color conversion methods: BGR->Gray and BGR->HSV.

!!!Note: Gray and HSV cannot be converted to each other.

Color space conversion function:

cv2.cvtColor(input image, flag)

BGR->Gray: flag is cv2.COLOR_BGR2GRAY BGR->HSV: flag is cv2.COLOR BGR2HSV

The value range of the HSV color space in OpenCV: H [0, 179] S [0, 255] V [0, 255]

hmin	black 0	gray 0	white 0	red		orange yellov		green	verdant	blue	purple
				0	156	11	26	35	78	100	125
hmax	180	180	180	10	180	25	341	77	99	124	155
smin	0	0	0	43		43	43	43	43	43	43
smax	255	43	30	255		255	255	255	255	255	255
vmin	0	46	221	46		46	46	46	46	46	46
vmax	46	220	255	255		255	255	255	255	255	255

Figure 1-2 Range of commonly used colors



The source code of the program is located

/home/pi/yahboom/colorBlock/colorBlock.py

The program is shown below:

```
* @par Copyright (C): 2010-2019, Shenzhen Yahboom Tech
* @file
                colorBlock
* @version
                V1.0
* @details
* @par History
* @author
                LongfuSun
import cv2
import numpy as np
#Create picture and Color block
img=np.ones((240,320,3),dtype=np.uint8)*255
img[100:140,140:180]=[0,0,255]
img[60:100,60:100]=[0,255,255]
img[60:100,220:260]=[255,0,0]
img[140:180,60:100]=[255,0,0]
img[140:180,220:260]=[0,255,255]
#Hsv threshold of yellow and red
yellow_lower=np.array([26,43,46])
yellow_upper=np.array([34,255,255])
red_lower=np.array([0,43,46])
red_upper=np.array([10,255,255])
#Color space conversionbgr->hsv
hsv=cv2.cvtColor(img,cv2.COLOR_BGR2HSV)
#Build a mask and use a mask
mask_yellow=cv2.inRange(hsv,yellow_lower,yellow_upper)
mask_red=cv2.inRange(hsv,red_lower,red_upper)
mask=cv2.bitwise_or(mask_yellow,mask_red)
res=cv2.bitwise_and(img,img,mask=mask)
cv2.imshow('image',img)
cv2.imshow('mask',mask)
cv2.imshow('res',res)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

The phenomenon is shown below:

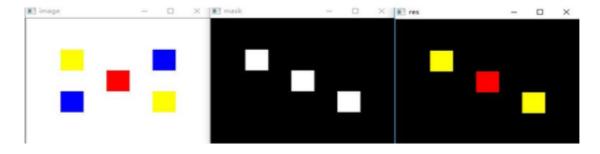


Figure 1-3 Color space conversion identifies the yellow and

red parts of the image

About mask: mask may be used in extracting regions of interest, masking certain regions of the image, extracting structural features, and making special images.