

For beginners, it is recommend using our image, which already contains all the libraries and tools required by the development environment below.

For Yahboom image

```
user name: pi Password: yahboom
```

The source code is stored in the Raspberry Pi system /home/pi/yahboom and /home/pi/Adafruit Python PCA9685 folders.

Temporary method:

This method will start the program after power-on again.

Enter the following command to view the process:

ps -ef | grep Pi-motion

Find this process as shown below:

End the large program process through the kill command:

sudo kill -9 708 723

```
pi@raspberrypi:~ $ sudo kill -9 708 723
pi@raspberrypi:~ $ sudo kill -9 708 723
kill: (708): 没有那个进程
kill: (723): 没有那个进程
pi@raspberrypi:~ $ ps -ef|grep Pi-motion
pi 1163 1098 0 13:05 pts/0 00:00:00 grep --color=auto Pi-motion
pi@raspberrypi:~ $
```

! Note: Everyone's process ID is different, please operate according to your actual process ID.

Permanent method:

This method will not start the program after power-on again.

Enter the following command:

sudo nano etc/rc.local

```
pi@raspberrypi:~ $ sudo nano /etc/rc.local
```

Add # sign before the following command:

```
#su pi -c "exec /home/pi/boot.sh"
```



```
## By default this script does nothing.

# Print the IP address
_IP=$(hostname -I) || true
if [ "$_IP" ]; then
    printf "My IP address is %s\n" "$_IP"
fi

#su pi -c "exec /home/pi/boot.sh"

exit 0
```