

# Combining online and offline Reinforcement learning techniques

Thorben Klamt - 10.04.2024

Advanced Topics in Reinforcement Learning, , Gottfried Wilhelm Leibniz University Hannover





## Combining online and offline-RL

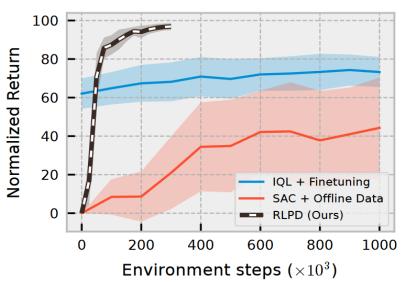
- Online RL with offline pretraining datasets
  - Pretrain on offline dataset and finetune online
  - Improved sample efficiency
  - Extract behavior primitives from offline data, then learn to compose them online
- Dynamic combination of online and offline Reinforcement Learning



## Combining online and offline-RL

- Efficient online reinforcement learning with offline data (paper from 2023)
  - RLPD (Reinforcement Learning with Prior Data)
    - Clipped Double Q-Learning
    - Previous policies or human expert
    - Remarkable performance over 30 different tasks

#### All D4RL AntMaze Tasks



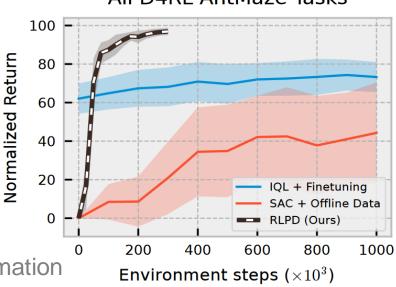
Ball, PhilipJ., et al. "Efficient online reinforcement learning with offline data." *International Conference on Machine Learning*. PMLR, 2023



## Combining online and offline-RL

- Efficient online reinforcement learning with offline data (paper from 2023)
  - RLPD (Reinforcement Learning with Prior Data)
    - Clipped Double Q-Learning
    - Previous policies or human expert
    - Remarkable performance over 30 different tasks
  - No pre-training or explicit imitation terms that privilege the prior offline Data
  - Balanced sampling strategies, Augmentation
  - LayerNorm to reduce OOD overestimation

#### All D4RL AntMaze Tasks



Ball, Philip J., et al. "Efficient online reinforcement learning with offline data." *International Conference on Machine Learning*. PMLR, 2023



### References

- Schrittwieser, Julian, et al. "Online and offline reinforcement learning by planning with a learned model." Advances in Neural Information Processing Systems 34 (2021): 27580-27591
- Xie, Tengyang, et al. "Policy finetuning: Bridging sample-efficient offline and online reinforcement learning." Advances in neural information processing systems 34 (2021): 27395-27407
- Lee, Seunghyun, et al. "Offline-to-online reinforcement learning via balanced replay and pessimistic q-ensemble." Conference on Robot Learning. PMLR, 2022
- Ball, Philip J., et al. "Efficient online reinforcement learning with offline data."
  International Conference on Machine Learning. PMLR, 2023
- Schrittwieser, Julian, et al. "Online and offline reinforcement learning by planning with a learned model." Advances in Neural Information Processing Systems 34 (2021): 27580-27591
- Wagenmaker, Andrew, and Aldo Pacchiano. "Leveraging offline data in online reinforcement learning." International Conference on Machine Learning. PMLR, 2023
- Ball, Philip J., et al. "Efficient online reinforcement learning with offline data."
  International Conference on Machine Learning. PMLR, 2023