A Heuristic Search Agent based on Markov Bayesian Probability Inference for Recon Blind Multi-Chess Agent

CS 4649: Robot Intelligence: Planning

Zhangqi Liu, Ruoyang Xu

Last Edited: April 20, 2019

1 Executive Summary

2 Contributions

References

[1] Author "place holder". SIAM News, Volume 23, Number 5, September 1990, pp 1 & 18.