Math 45 - Section — HW 2 Tuesday, March 8, 2016

## 1, 2, 3

1 Complex numbers are helpful when expressing oscillatory behavior using trigonometric functions. Euler's formula helps us to convert from complex exponentials like  $e^{i\theta}$  to trigonometric functions like cosine and sine:

$$e^{i\theta} = \cos\theta + i\sin\theta.$$

How do we convert from cosine and sine into complex exponentials? Consider that

$$e^{-i\theta} = \cos(-\theta) + i\sin(-\theta) = \cos\theta - i\sin\theta.$$

Add the two equations above and solve for  $\cos \theta$ . Subtract to solve for  $\sin \theta$ .

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**2** Simplify each of the following expressions, assuming that a, t,  $\omega$  are real numbers.

Example:  $\Re\left(e^{i\omega t}\right) = \Re\left[\cos(\omega t) + i\sin(\omega t)\right] = \boxed{\cos(\omega t)}$ 

- (a)  $\Im\left(e^{i\omega t}\right) =$
- (b)  $\Im\left(e^{-i\omega t}\right) =$
- (c)  $\Re\left(e^{(a+i\omega)t}\right) = \Re\left(e^{at}e^{i\omega t}\right) = \Re\left[e^{at}\cos(\omega t) + ie^{at}\sin(\omega t)\right] =$ (d)  $\Im\left(e^{(a+i\omega)t}\right) =$

3 For each of the following ordinary differential equations, indicate its order, whether it is linear or nonlinear, whether it is autonomous or non-autonomous, and whether it is driven or undriven.

(a) 
$$\frac{dg}{dx} + g^3 = 0$$

(b) 
$$\ddot{y}(t) + e^{ty(t)} = \cosh t$$
 Note:  $\ddot{y}(t)$  is the same as  $y''(t) = \frac{d^2y}{dt^2}$ .

(c) 
$$r^2R''(r) + rR'(r) - 5R(r) = 0$$

(d) 
$$\ddot{\theta} + \sin \theta = 0$$

(e) 
$$f''' = f' + x f + 4 \sin(x)$$

(c) 
$$r^2R''(r) + rR'(r) - 5R(r) = 0$$
  
(d)  $\ddot{\theta} + \sin \theta = 0$   
(e)  $f''' = f' + x f + 4\sin(x)$   
(f)  $\frac{y'}{y} = 7$  Note: If possible, rewrite this DE so that it is linear. If not, explain why.