# Part IV Other Systems: II

Ada Tasking: A Brief Review

Programs must be written for people to read, and only incidentally for machines to execute.

# The Development of Ada: 1/2

- A DoD study in the early and middle 1970s indicated that enormous saving in software costs (about \$24 billion between 1983 and 1999) might be achieved if the DoD used one common programming language for all its applications instead of 450 programming languages and incompatible dialects used by its programmers.
- An international competition was held to design a language based on DoD's requirements.
- Seventeen proposals were submitted and four were selected as semifinalists.

# The Development of Ada: 2/2

- All semifinalists chose to base their languages on Pascal.
- The final winner was the team lead by Jean Ichibiah of CII Honeywell Bull.
- With some minor modifications, this language referred to as Ada was adopted as an ANSI standard in February 1983 (i.e., Ada 83).
- Ada was overhauled in 1995 (i.e., Ada 95) and then in 2005 with less changes (i.e., Ada 2005).

# Ada Task Type and Body: 1/2

 A task requires two components: a task type (definition) and a task body (implementation).

```
task type myTask is
entry put(data: integer);
entry get(result: integer);
end myTask;

end myTask;

- other statement
accept put(x: integer) do
- other statements
end put;
- other statements
end put;
- other statements
end;
```

# Ada Task Type and Body: 2/2

Static tasks can be declared as follows:

```
agent: myTask;
philosophers: array (1..5) of myTask;
```

Or, tasks can be dynamically allocated:

```
type access_to_myTask is access myTask;
to_myTask : access_to_myTask;
-- other statements
to_myTask := new myTask;
```

## Task Execution: 1/3

- Tasks run independently until
  - \*an **ACCEPT** statement
    - ✓ wait for someone to call this entry, then proceed to the rendezvous section. After this, both tasks execute their ways.
  - an **ENTRY** call
    - ✓ wait for the corresponding task reaches it **ACCEPT** statement, then proceed to the rendezvous section. After this, both tasks execute their ways.

# Task Execution: 2/3

- Multiple ACCEPTs may be used in a task body.
- Communication between tasks takes place, when they rendezvous, through the actual parameters of the ENTRY call and the formal parameters in the corresponding ACCEPT statement.
- The task that accepts the entry call causes suspension of the calling task, retrieves information from parameters, processes them, and passes the results back through parameters.
- The call resumes once the ACCEPT completes.

# Task Execution: 3/3

- Thus, the ENTRY-ACCEPT pair looks like a synchronous channel communication.
- The task executes the **ENTRY** call is the sender and the task executes the corresponding **ACCEPT** statement is the receiver.
- If the task executing the **ACCEPT** statement only saves the information in the parameters and ends the rendezvous, this is a simple one-direction message passing.

# **Terminate and Delay**

- The **terminate** statement terminates the task that executes this **terminate** statement.
- The **delay** statement has the following syntax: **delay** exp;
  - \*The **delay** statement suspends the task for at least *exp* seconds.
  - ❖ If *exp* is zero or negative, the *delay* statement has no effect.

# A Simple Example

```
task PRODUCER;
-- if nothing is exported,
-- a task declaration is simple

task type CONSUMER is entry REC(C: in character);
end CONSUMER;

task body PRODUCER is
C: character;
begin
while not END_OF_FILE(STANDARD_INPUT) loop
GET(C); -- read a character from standard input
CONSUMER.REC(C); -- send it to CONSUMER
end loop;
end PRODUCER;

task body CONSUMER is
```

X : character;

begin

**W**loop

accept REC(C: in character) do

**X** := **C**; -- retrieve the input character

end REC;

**PUT(UPPER(X))**; -- convert to upper case and print

end loop;

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end CONSUMER;

# A Mutex Lock

task type Mutex is entry Lock; entry Unlock; end Mutex;

task body Mutex is begin loop accept Lock; accept Unlock; end loop; end Mutex;

MyLock: Mutex;

MyLock.Lock;
-- critical section
MyLock.Unlock;

Mutex is a task

# Selective Wait: 1/4

- The **select** statement has the following purposes:
  - 1. Wait for more than a single rendezvous at any one time;
  - 2. Time out if no rendezvous is forthcoming within a specified period;
  - 3. Withdraw its offer to communicate if no rendezvous is immediately available;
  - 4. Terminate if no other tasks can possibly call its entries.

# Selective Wait: 2/4

### select

select\_alternative

or

select\_alternative

or

select\_alternative

-- other **or** select\_alternatives

else

-- sequence\_of\_statements

end select;

Each select\_alternative is an **accept**, or a **delay** statement followed by other statements, or a **terminate** statement.

At most one **terminate** can be used in a selective wait.

One and only one **accept** in **select** or **or** will be executed.

or and else are optional

# Selective Wait: 3/4

```
task body CONSUMER is
 X : character;
begin
 loop
   select
      accept REC(C: in character) do
        X := C;
                      -- retrieve the input character
      end REC;
      PUT(UPPER(X)); -- convert to upper case and print
      terminate;..
                   now the task can terminate
    end select;
 end loop;
end CONSUMER;
```

# Selective Wait: 4/4

Each select\_alternative can have a guard:

"**when** condition =>" loop select when condition | => accept xyz(....) do These are the guards ::: -- statements in accept end xyz; . or when condition, =>. It is a program error accept abc(...) do if all guards are FALSE. -- statements in accept One and only one guards **end** abc: whose conditions are -- other alternatives true will be selected. or terminate: end select:

end loop;

# Dining Philosophers: 1/2

```
procedure DiningPhilosophers is
 subtype ID is integer range 1..5;
task type Philosopher is
  entry Get_ID(k: in ID);
end Philosopher;
task type Chopstick is
  entry Pick_Up;
  entry Put_Down;
end Chopstick;
Chop: array(ID) of Chopstick;
   -- the 5 chopsticks
```

Philo: **array**(ID) **of** Philosopher;

-- the 5 philosophers

```
task body Chopstick is
begin
 loop
   select
                  mutex
     accept Pick_Up;
     accept Put_Down;
   or
     terminate;
   end select;
 end loop;
end Chopstick;
    to next slide
```

# Dining Philosophers: 2/2

```
task body Philosopher is
i: ID;
limit:: constant:= 100_100;
count: integer := 0;
left, right: ID;
begin
accept Get_ID(k: in ID) do
i:= k;
end Get_ID;
left:= i; right:= i mod 5 + 1;
```

```
Chop(left).Pick_Up;
    Chop(right).Pick_Up;
      -- eating
    Chop(right).Put_Down;
    Chop(left).Put_Down;
    count := count + 1;
  end loop;
end Philosopher;
begin -- the main
 for k in ID loop
   Philo(k).Get_ID(k); -- assign ID
 end loop;
end DiningPhilosophers;
```

**while** count /= limit **loop** 

# Dining Philosophers – 4 Chairs

```
task type GetChair is
entry Enter;
entry Exit;
end GetChair;
```

this is a counting semaphore

```
task body GetChair is
 i: integer := 0;
begin
  loop
    select
      when i < 4 \Rightarrow
         accept Enter;
        i := i + 1;
      or
         accept Exit;
        i := i - 1;
      or
        terminate;
      end select:
   end loop;
end GetChair:
```

# **Counting Semaphores**

```
entry Initialize(N: in Natural);
 entry Wait;
 entry Signal;
end CountingSemaphore;
```

```
task type CountingSemaphore is task body CountingSemaphore is
                                    Count : Natural; -- non-negative integer
                                   begin
                                     accept Initialize(N : in Natural) do
                                       Count := N;
                                     end Initialize;
                                     loop
                                       select
                                         when Count > 0 = >
                                           accept Wait do
                                              Count := Count - 1;
                                           end Wait:
                                         or
                                           accept Signal;
                                              Count := Count + 1;
                                        end select:
                                     end loop;
                                                                    19
                                   end CountingSemaphore;
```

# **Conditional Entry: 1/2**

A conditional entry has the following syntax:

# entry\_call other statements else statements

end select;

- When execution reaches the select statement and the other party is not ready for a rendezvous, the else part is executed.
- In other words, there is no waiting at the entry call if the other party is not ready.

# **Conditional Entry: 2/2**

- The following does
  - **Loops** until a character can be read from the buffer
  - ❖ If a character can be read, process it and break the loop
  - **❖** If a character cannot be read, do some local thing and try again.

```
loop
    select
    BUFFER.GET(C);
    -- process the retrieved character
    exit;
    else
        -- do some other local computation
    end select;
end loop;
```

# The End